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import datetime
from PIL import ImageGrab
import numpy as np
import cv2
from win32api import GetSystemMetrics
width = GetSystemMetrics(0)
height = GetSystemMetrics(1)
time stamp = datetime.datetime.now().strftime('%Y-%m-%d %H-%M-%S')
file name = f'{time stamp}.mp4'
fourcc = cv2.VideoWriter fourcc('m', 'p', '4', 'v')
captured_video = cv2.VideoWriter(file_name, fourcc, 20.0, (width, height))
# webcam = cv2.VideoCapture(1)
while True:
  img = ImageGrab.grab(bbox=(0, 0, width, height))
  img np = np.array(img)
  img final = cv2.cvtColor(img np, cv2.COLOR BGR2RGB)
  # _, frame = webcam.read()
  # fr height, fr width, = frame.shape
  # img_final[0:fr_height, 0: fr_width,:] = frame[0: fr_height, 0: fr_width, :]
  cv2.imshow('Secret Capture', img_final)
  # cv2.imshow('webcam', frame)
```

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captured_video.write(img_final)
if cv2.waitKey(1) == ord('q'):
    break
```