

Today



Last Lecture

Hashing

Today

- Introduction to Trees
- Recursion Review



Warm-up: Open Addressing

Perform the following operations for Table 1:

```
add(10.1)
add(4.6)
add(9.3)
add(2.5)
add(0.1)
remove(10.1)
rehash(10) //rehash to Table 2 (size 10)
```

Both Tables:

Open Addressing with Quadradic Probing

Hash Function: h(x) = |x|

Remember to indicate any special states!

Table 1:

0	1	2	3	4

Summary (with words):

- 1. Hash all numbers into Table 1 (5 slots) using open addressing with quadradic probing and h(x) = [x].
- 2. Remove the first inserted value.
- 3. Rehash remaining numbers into Table 2 (10 slots).

Table 2:

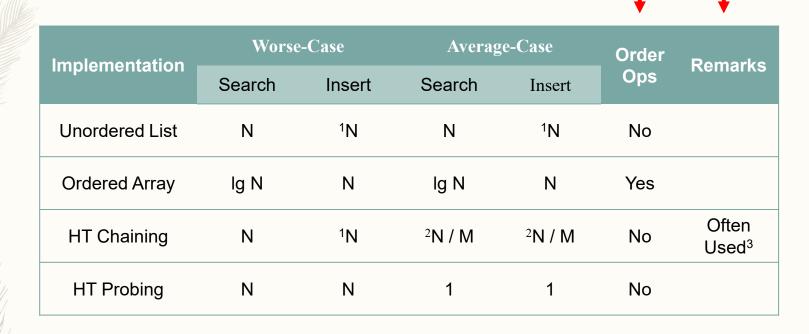
0	1	2	3	4	5	6	7	8	9

Sets and Maps So Far



Implementation	Worse-Case		Average-Case		Order	Remarks
	Search	Insert	Search	Insert	Ops	Remarks
Unordered List	N	¹ N	N	¹ N	No	
Ordered Array	lg N	N	lg N	N	Yes	
HT Chaining	?	?	?	?	No	
HT Probing	?	?	?	?	No	

Sets and Maps So Far

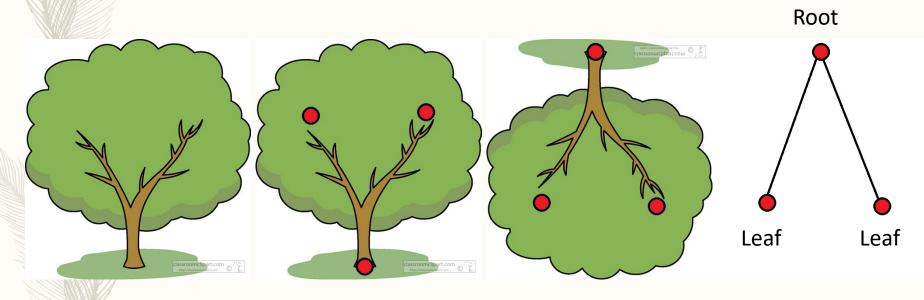


- 1. O(n) to check for duplicates, O(1) if this is not needed for some reason
- 2. M is the size of the table. If N/M (load) is < a constant, then O(1)
- 3. Good constants and relatively easy to implement, used in many libraries



Trees

- Data structure which looks like an upside down tree (or the root system of a tree)
 - Nodes have parents and children
 - No loops







- Collection of nodes
 - Any shape, but can't have a loop
 - acyclic = "no cycles" = no loops
- Nodes have:
 - data
 - (possibly) a "key" to sort/search by
 - (possibly) pointer to children
 - (possibly) pointer to parent

- Common tree operations
 - Searching for an item
 - Adding items
 - Deleting items (synonymous with removing)
 - Balancing
 - Iterating = mention thingsone by one
 - all the items (in some order)
 - a section of a tree

Tree Definitions

Note: Unfortunately, due to the manner in which the field of computer science grew out of many other fields (math, engineering, etc.)... there are no completely-agreed-upon definitions of some of these terms.

We will use the definitions given in these slides for CS310.

Tree Definitions 1/3

- The root node is the top most node in the tree
- The descendants of a node are all the nodes below it (and sometimes includes the node itself)
- The ancestors of a node are the nodes on the path from the node to the root (and sometimes includes the node itself)
- Nodes are siblings if they have the same parent

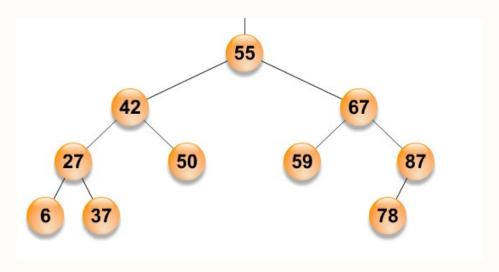


Tree Definitions Practice 1/3



- What is the root?
- What is the parent of 27?
- What are the children of 67?
- What are the ancestors of 59?
- What are the descendants of 55?





Tree Definitions 2/3



- An inner node has at least one child (i.e. not a leaf)
- A null link describes an empty link, typically child link
- The depth of a node is the length (number of edges) of the path from the node to the root
- The node height is the length of the path from the node to the deepest leaf.
- The tree height is the maximum depth of any node in the tree

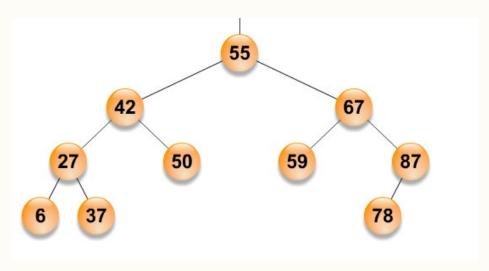


Tree Definitions Practice 2/3



- Which nodes are leaf nodes?
- Which nodes are inner nodes?
- Where are the null links?
- What is the tree height?
- What is the depth of node 59?









Full tree

- every node other than the leaves has the max number of children
- Perfect tree (sometimes called "complete")
 - all leaves have the same depth
 - every node other than the leaves has the max number of children
- Nearly complete tree (sometimes called "complete")
 - last level is not completely filled

Balanced tree

 height of the left and right sub trees of every node differ by 1 or less (as used by AVL tree)

Degenerate tree

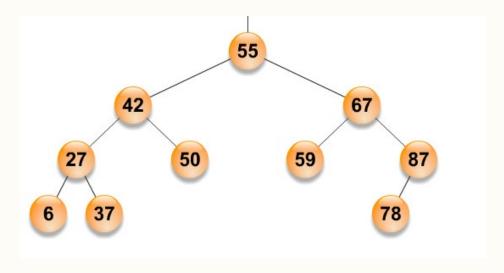
- each parent node has only one associated child node
- equiv. to linked list, maximum height?

Tree Definitions Practice 3/3



- Is this tree full?
- Is this tree perfect or nearly complete?
- Is this tree balanced?
- Is this tree degenerate?
 - what nodes could we remove to make it degenerate?







k-ary Trees



- aka. n-ary and m-ary trees
- each parent can have only k children
 - k is the "branching factor"
- number of nodes in a perfect k-ary tree
 - $(k^{h+1}-1)/(k-1)$
 - h is the height of the tree
- number of leaves in a perfect k-ary tree
 - first level k⁰, second k¹, third k²... k^h
- height of a perfect k-ary tree of with n nodes
 - $-\log_k((k-1)^*(n)+1)-1$



- each parent can have only two children
- number of nodes in a perfect binary tree
 - min: $2^{h}+1$ max: $2^{h+1}-1$
 - $max\ from\ k$ - $ary\ tree\ formula: <math>(k^{h+1}-1)/(k-1),\ k=2$ $\therefore 2^{h+1}-1/(2-1)=2^{h+1}-1$
- number of leaves in perfect binary tree
 - first level 2⁰, second 2¹, third 2²... 2^h
- number of internal nodes in perfect binary tree of n nodes
 - [n/2]
- height of a balanced binary tree of n nodes
 - [lg(n+1)]



Binary Tree Storage: Arrays



- Children at index:
 - parentIndex*2+1
 - parentIndex*2+2
 - e.g. root at 0, children of root at index 1 and 2
- Parent at index
 - [(childIndex-1)/2]
 - e.g. parent of item at index $2 = \lfloor 1/2 \rfloor = 0$
- Common variant is to start root at index 1

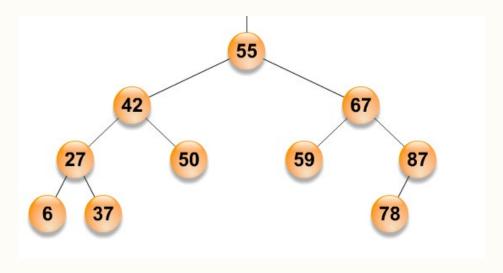




– Draw the binary tree for:

[55, 42, 67, 27, 50, 59, 87, 6, 37, null, null, null, null, 78]





Binary Tree Storage: Links



- (optional) key
- value
- link to child 1
- link to child 2

– Do we need a link from child to the parent?

```
class Node<V> {
     V value;
     Node<V> left;
     Node<V> right;
class Node {
     int value;
     Node[] children;
class Node<K,V> {
     K key;
     V value;
     Node<K,V> left;
     Node<K,V> right;
```

Other Tree Storage



K-ary Tree Storage

- node structure
 - array/list of children

- array structure
 - root, children of root, grandchildren of root, etc.
 - same as binary tree, but different math

Arbitrary Tree Storage

- node structure
 - list of children (dynamic or linked)

- array structure
 - first-child-next-sibling storage(see textbook 18.1.2)







- Need to know where each item is
- How? Need to limit number of children and/or use other methods of storage (see first-child-next-sibling storage)
- Most common for balanced trees (very little wasted space)
- Not good for degenerate trees (lots of wasted space)
- Fast memory access (compared to linked list)

Linked Data Structures

easy to add, delete, and swap around parts of the tree

