

Preprocessing Fix

Tuesday, August 2, 2022 11:29 AM

Calc Raw (Clipped) Velocity

< old version, as written >

$$\omega = \sqrt{[a^2 - g^2] / [r + (b)(\sqrt{1 - (g/a)^2})]}$$

Snuly: $A_r = r(\omega^2) \rightarrow$ Acc relative to earth

$$a_{\text{earth}} = A_r + g$$

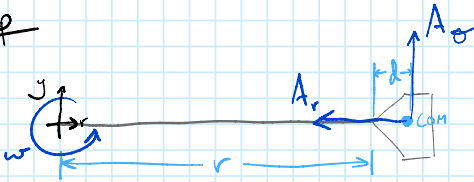
$$a_{\text{earth}} = r(\omega^2) + g$$

$$a - g = r(\omega^2)$$

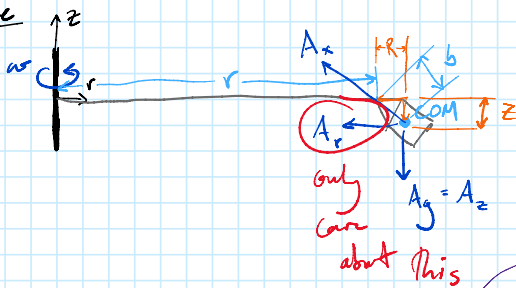
$$\omega = \sqrt{\frac{a - g}{r}}$$

```
154 %% ----- Velocity Profile Conversion ----- %%
155 %% Calculate Raw (Clipped) Velocity
156
157 omega_raw = [];
158 for i = 1:length(ax_clip)
159     omega_raw(i) = sqrt((ax_clip(i)^2 - g^2)/(r + b*sqrt(1 - (g/ax_clip(i))^2)));
160 end
161
162 %% Calculate Processed Velocity
163
164 omega_proc = [];
165 for i = 1:length(ax_proc)
166     omega_proc(i) = sqrt((ax_proc(i)^2 - g^2)/(r + b*sqrt(1 - (g/ax_proc(i))^2)));
167 end
168
169
```

Top



Side



$$A_x^2 = A_r^2 + A_g^2$$

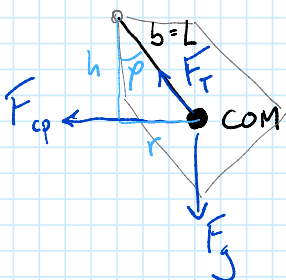
only
care
about this

what makes C low A_r?

$$\omega_{\text{new}} = \sqrt{A_r / [r + (b)(\sqrt{1 - (g/A_r)^2})]}$$

got how? = R

Got to
r + R



$$\left. \begin{aligned} \sin(\phi) &= \frac{F_{cp}}{F_T} \\ \cos(\phi) &= \frac{F_g}{F_T} \end{aligned} \right\} \begin{aligned} F_T \sin(\phi) &= F_{cp} = m \vec{a}_r = m[r(\omega^2)] \\ F_T \cos(\phi) &= F_g = m \vec{a}_g \end{aligned}$$

$$\left. \begin{aligned} \sin(\phi) &= \frac{r}{L} \\ \cos(\phi) &= \frac{z}{L} \end{aligned} \right\} \begin{aligned} F_T &= m[r(\omega^2)] \left(\frac{L}{r}\right) \\ F_T &= \frac{m(\vec{a}_g)L}{\omega} \end{aligned}$$

$$\cos(\gamma) = \frac{z}{L}$$

$$F_T = \frac{m(\vec{a}_g)L}{z}$$

make equal

$$mL(\omega^2) = \frac{mL(\vec{a}_g)}{z}$$

$$\omega^2 = \frac{\vec{a}_g}{z} \therefore z = \frac{\vec{a}_g}{\omega^2} \rightarrow \frac{A_g}{\frac{A_r}{r}} = \frac{r g}{A_r}$$

$$\text{from } A_r = r(\omega^2)$$

$$b^2 = R^2 + z^2$$

plug in z

$$b^2 = R^2 + \left(\frac{r g}{A_r}\right)^2$$

$$r = R$$

$$b^2 = R^2 + R^2 \left(\frac{g}{A_r}\right)^2$$

$$b^2 = R^2 \left[1 + \left(\frac{g}{A_r}\right)^2\right]$$

$$b = R \sqrt{1 + \left(\frac{g}{A_r}\right)^2}$$

$$R = \frac{b}{\sqrt{1 + \left(\frac{g}{A_r}\right)^2}}$$

Numerical testing shows these to be the same

Though the bottom expression currently in the code is confusing, as my intuition says that if $a < g$, where a is the input/desired acceleration, the last term becomes nonreal/imaginary

$$\omega = \sqrt{\left[\frac{a^2 - g^2}{r + (b)(\sqrt{1 - (g/a)^2})}\right]}$$

$$\text{From: } A_x^2 = A_r^2 + A_g^2 \rightarrow A_r^2 = A_x^2 - A_g^2$$

However, this is saying we want ω where A_x experiences target Accel (via Data.csv)

If we wanted A_r to be representative of target Accel, then:

$$\omega_{\text{new}} = \sqrt{(A_r - A_g) / [r + (b)(\sqrt{1 - (g/A_r)^2})]}$$

Where the A_g term is kept to account for the steady-state presence of gravity. Though it is normal to the radial acceleration, it is still present to the system and compounds to create the overall acceleration vector.