## National University of Computer and Emerging Sciences, Lahore Campus



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**Course Code:** 

EE2003 Fall 2022 90 11

Exam: Final Your Section:

Instruction/Notes:

This is an open notes/book exam. Sharing notes and calculators is NOT ALLOWED. All the answers should be written in provided space on this paper. Rough sheets can be used but will not be collected and checked. In case of any ambiguity, make reasonable assumptions. Questions during exams are not allowed.

Question 1 [Pipelining] [CLO 6] [10 Marks]:

# Important Instruction: Following question is ONLY for section BSCS-A, BSCS-B, BSCS-F and BSCS-G

For the code segment given below, fill-in the following pipeline diagram. Clearly show the stall AND/OR forwarding where required. In case of forwarding, clearly draw the arrow and mention the name of operand that needs forwarding. Assume you have optimized pipelined MIPS Architecture (with all the hazards control implementation) as we have studied in class.

sub \$1, \$2, \$3 or \$4, \$5, \$6 lw \$6, 100 (\$4) and \$7, \$6, \$8

# Important Instruction: Following question is for ALL THE SECTIONS EXCEPT section BSCS-A, BSCS-B, BSCS-F and BSCS-G

Let us consider the following decomposition of the instruction | Set of instructions processing

Fetch Instruction (FI): Read the next expected instruction into a

Decode Instruction (DI): Determine the opcode and the operand specifiers.

Fetch Operands (FO): Calculate the effective address of each source operand and fetch each operand from the memory. Operand in registers need not to be fetched.

Execute Instruction (EI): Perform the indicated operation and store the result if any, in the specified destination operand location.

Write Operand (WO): Store the result in memory.

Following is a set of instructions. Their implementation through pipelining has some data hazards. You have to solve those hazards by using stalling method.

**I1:** mov bx, 0

I2: mov word [n1], ax

I3: add word [n1], bx

**I4:** add word [n1], 01

**I5:** mov cx, 0

I6: mov word [n2], cx

I7: add bx, [n1]

I8: add bx, word[n2]

Do it with Stalling Method (without Data Forwarding)

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20
I1	FI	DI	F0	ΕI	WO															
12		FI	DI	FO	ΕI	WO														
13			FI	DI	ST	ST	FO	EI	WO											
14				FI	DI	ST	ST	ST	ST	F0	ΕI	WO								
15					FI	DI	ST	F0	ΕI	WO										
16						FI	DI	ST	ST	ST	F0	ΕI	WO							
17							FI	DI	ST	ST	ST	ST	F0	ΕI	WO					
18								FI	DI	ST	ST	ST	ST	ST	ST	FO	ΕI	WO		

### Question 2 [Cache] [CLO 6] [5+5 = 10 Marks]:

Consider a sequence of memory address references given below. In the sequence, each word address is provided in both the decimal and binary formats. Below each address, the relative time at which these references occur is also listed. Memory contents and addresses are shown in the second table.

Memory						
Decimal Address	Binary Address	Data				
0	00 00 00 00	2				
120	01 11 10 00	100				
248	11 11 10 00	7				
170	10 10 10 10	50				
187	10 11 10 11	52				
51	00 11 00 11	80				
15	00 00 11 11	41				
174	10 10 11 10	32				
150	10 01 01 10	77				
9	00 00 10 01	5				
4	00 00 01 00	9				
253	11 11 11 01	2				
1	00 00 00 01	3				
7	00 00 01 11	65				
6	00 00 0 1 10	90				
2	00 00 00 10	55				

Memory Access Sequence							
Time	Address Decimal	Address Binary					
1	6	00 00 0 1 10					
2	0	00 00 00 00					
3	15	00 00 11 11					
4	120	01 11 10 00					
5	253	11 11 11 01					
6	1	00 00 00 01					
7	248	11 11 10 00					
8	9	00 00 10 01					
9	4	00 00 01 00					
10	51	00 11 00 11					
11	2	00 00 00 10					
12	1	00 00 00 01					

Now consider two different 8-word caches shown below. Assume that each of the caches was used independently to facilitate memory access for the sequence above. For each cache type, assume that the cache is initially empty. Assume that the least-recently used (LRU) scheme is used where appropriate. Also, when inserting an element into the cache, if there are multiple empty slots for one index, you should insert the new element into the left-most slot (first available slot)

Part (A) [5 Marks]: Use the <u>direct-mapped cache</u> to facilitate memory access for the memory sequence above. You should fill in the binary form of the Tag values. Show the final contents of the cache in the table below.

Note: V means Valid OR Value Bit.

Index	Cache						
	TAG	DATA	VALUE BIT				
0	11111	7	0				
1	00000	3	0				
2	00000	55	0				
3	00110	80	0				
4	00000	9	0				
5	11111	2	0				
6	00000	90	0				
7	00001	41	0				

Hit I	Rate:	0	
Miss	Rate:	1	

Part (B) [5 Marks]: Use the <u>2-way set associative cache</u> to facilitate memory access for the memory sequence above. You should fill in the binary form of the Tag values. Show the final contents of the cache in the table below.

Index		2-way set associative Cache							
	TAG	DATA	VALUE BIT	TAG	Data	Value Bit			
0	111110	7	0	000001	9	0			
1	000010	5	0	000000	3	0			
2	000001	90	0	000000	55	0			
3	000011	41	0	001100	80	0			

TIL RALE. 1/12	Hit Rat	e: 1/12	
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Miss Rate: \_\_\_\_\_11/12\_\_\_\_\_

Question 3 [Performance] [CLO 6] [10 Marks]: It takes  $15\mu s$  to complete one instruction in a non-pipelined processor. We were able to convert the circuit to a 6 stage pipeline processor. Stage 1 to 6 take  $2\mu s$ ,  $1.5\mu s$ ,  $3\mu s$ ,  $4\mu s$ ,  $1.5\mu s$ ,  $3\mu s$  resp. Time to move from one pipe stage to another is  $2\mu s$ . (Note for Section BSCS-A, BSCS-B, BSCS-F and BSCS-G: Assume the transition time, to move from one pipe stage to another, is zero.)

Calculate the following values for pipeline and non-pipelined processor (Write the answer inthe given table)

Value	Non-Pipeline	Pipeline
Clock Cycle	15μs	6μs
Clock Speed	1/15 x 10 <sup>-6</sup> Hz = 0.067 x 10 <sup>6</sup> Hz	1/6 x 10 <sup>-6</sup> Hz = 0.17 x 10 <sup>6</sup> Hz
Latency	15μs	36μs
Throughput for 46 instructions	46/46x15 x 10 <sup>-6</sup> instructions/s = 0.067 x 10 <sup>6</sup>	46/51 x 6 x 10 <sup>-6</sup>

		Instructions/s = 0.15 x 10 <sup>6</sup>
Throughput for 1 instruction	1/15 x 10 <sup>-6</sup> instructions/s	1/36 x 10 <sup>-6</sup> instructions/s
	0.067 x 10 <sup>6</sup>	0.03 x10 <sup>6</sup>
Speedup of pipeline processor for 1 instruction	15/36 = 0.42	
Speedup of pipeline processor for 75 instructions	15x 75/80 x 6 = 2.34	

# Question 4 [Short Questions] [CLO 1,2,3,4,5] [5x6 = 30 Marks]:

a. The following program is trying to add the first three numbers in the array num1 and store the sum in the fourth index of the num1 array. However, after running the program, the final sum generated is incorrect. Identify mistakes in the program and write the correct code in the box on the right side.

; a program to add three numbers	; Write Correct Code here
[org 0x0100]	
mov ax, [num1]	[org 0x0100]
mov bx, [num1+1]	mov ax, [num1]
add ax, bx	inov ax, [itumi]
mov bx, [num1+2]	mov bx, [num1+2]
add ax, bx	add ax, bx
mov [num1+3], ax	
mov ax, 0x4c00	mov bx, [num1+4]
int 0x21	add ax, bx
num1: dw 5, 10, 15, 0	mov [num1+6], ax
	mov ax, 0x4c00
	int 0x21
	num1: dw 5, 10, 15, 0



b. Write a piece of code to check if a number 'num' is a power of two or not. If the number is power of two, set the PowerOfTwo flag to 1. You are only allowed to use shifting and logical instructions. You are not allowed to use DIV instruction.

```
[org 0x0100]
                           CheckPowerOfTwo:
jmp start
                           push bp
PowerOfTwo :db 0
                           mov bp,sp
num: dw 0
                           push ax
                           push bx
                           mov ax, [bp+4]
start:
mov ax, [num]
                           ;write your code here
push ax
call CheckPowerOfTwo
                           mov bx,ax
terminate:
                           sub bx,1
mov ax,0x4c00
                           AND ax,bx
int 0x21
                           inz 12
                           mov byte[PowerOfTwo],1
                           12:
                           pop bx
                           pop ax
                           pop bp
                           ret 2
```

c. Following program has a function add1 that takes 2 numbers from stack and if sum of these two numbers is greater than 0, it returns their sum through stack otherwise it returns 0 through stack. Code has some logical errors. Highlight the errors and correct those errors so that you can pop the correct answer in the dx register. You can add or modify existing lines but you cannot remove any line.

```
jmp start
                                               ; Write only updated or new lines. Don't
add1:
                                               re-write full code.
push bp
                                               add1:
mov bp, sp
                                               jmp start
sub sp,2
                                               push bp
push ax
                                               mov bp, sp
mov ax, [bp+2]
                                               sub sp,2
mov [bp-2], ax
                                               push ax
```

```
mov ax, [bp+4]
                                                    mov ax, [bp+4]
add [bp+8],ax
                                                    mov [bp+8], ax
cmp word [bp+8],0
                                                    mov ax, [bp+6]
ja end
                                                    add [bp+8],ax
mov [bp+8], 0
                                                    cmp word [bp+8],0
end:
                                                    jg end
pop bp
                                                    mov [bp+8], 0
ret 2
                                                    end:
start:
                                                    <mark>pop ax</mark>
sub sp, 2
                                                    mov sp, bp
push 8
                                                    pop bp
push 5
                                                    ret 4
call add1
                                                    start:
pop dx
                                                    sub sp, 2
                                                    push 8
                                                    push 5
                                                    call add1
                                                    pop dx
```

**d.** Answer the following questions:

(i) Which interrupt will be hooked after execution of following code?	0120
44h	0140
	0280
<pre>[org 0x100] ;;;; myISR is written here</pre>	123F
xor ax,ax mov es, ax	124A
mov [es: 0x110 ] , myISR mov [es: 0x112] , CS	A198
mov ax, 4c00h Int 21h	BCD6
	78D2
(ii) What is the total size (in bytes) of the interrupt vector table?	197B
1024 bytes	CD79
The first 22 words (in hex) of the 0th segment of the physical memory are shown in the following table (starting from data 0120).	E106
	56AB
(iii) What is the segment and offset of the interrupt service routine	9851
corresponding to interrupt 1?	0CDA
Offset:0x8002 Segment:0x3F12	6502
(iv) What is the segment and offset of the interrupt service routine	AB69

corresponding to interrupt 5?	F156
Offset: _0x06E1 Segment:0xAB56	49D8
	12E5
(v) What is the segment and offset of the interrupt service routine	9857
corresponding to interrupt 10h?	146B
Offset:not shown Segment:not shown	98A2

e. Write a piece of code that disables the timer interrupt in the PIC mask register.

```
[org 0x0100]
in al, 0x21
or al, 1
out 0x21, al
mov ax, 0x4c00
int 0x21
```

**Question 5** [CLO 1,2,3,4,5] [30 Marks]: You are required to implement Notepad Application according to the functionality as described below:

- 1- Notepad application will start/load with following specifications:
  - a. Notepad will have two partitions in the display memory. Upper half (1st 12 rows) will be editor window while 2nd half (last 12 rows) will be read-only window. 13th row will be boundary line like "=======". Both the editor and read-only windows will be space with white background initially. [4 marks]
  - b. A blinking cursor '|' (attribute: black on white background) will be on top-left cell of the Editor Window (1st half). For now, ignore the default cursor due to time constraint. [4 marks]
- 2- Editor window can be edited with following specifications (DO NOT take characters from user using software interrupts)
  - a. If user enters any key, that character or digit will be displayed at the position of cursor and cursor will move by one cell towards right. If cursor was at last cell of a row, it will move to 1st cell of next row within editor boundary. Due to time constraint, we assume that user will not write at bottom-right cell of Editor Window and beyond. You do not need to check this boundary condition. Assume that user will press only characters and numeric keys. Also assume that you are already given a function ScanCodeToAsciiConverter that reads scancode from AL and saves corresponding ascii in AH (You do not need to push or pop any parameter or return value and you do not need to re-write this converter, just use it wisely). [6 marks]
  - b. Make sure that your application doesn't write anything on Editor Window on key release. [2 marks]
  - c. Within Editor Window, user can move the cursor up, down, left or right by pressing Up, Down, Left, Right ARROW KEYS respectively. <u>Due to time constraint we will implement only DOWN ARROW KEY</u> (i.e. scancode 0x50). <u>If user presses DOWN ARROW key, the cursor moves to same column of next row.</u> Assume that user will not cross the Editor Window's boundary; you do not need to implement this

boundary check. <u>Make sure you properly handle previous position of cursor</u>. This cursor movement is allowed even if there is no text written in editor window.

[6 marks]

3- After every minute, Read-only window updates/refreshes itself with the latest content available on Editor Window i.e. after every minute, paste the content of Editor Window on Read-only Window (You do not need to remove cursor from read-only window). [8 marks]

### **Important Instructions:**

- Credit will be given on code efficiency, so use string instructions where required.
- You may use the functions given in book examples. Give proper reference and use them wisely. Function calls should exactly support the required functionality.

```
;Write Timer Code here (if required)
; Write your code here
                                                                       mkBoundary:
; Data Declarations (if required)
                                                                       push es
; and Start/Main Functionality here
                                                                       push ax
[org 0x100]
                                                                       push bx
jmp start
                                                                       push cx
                                                                       push di
offset: dw 0
count: dw 0
                                                                       mov ax, 0xB800
                                                                       mov es, ax
start:
                                                                       mov ax, 80
call clrscr
                                                                       mov bx, 12
call mkBoundary
                                                                       mul bx
mov ax, 0xB800
                                                                       shl ax, 1
mov es, ax
                                                                       mov di. ax
mov di, 0
                                                                       mov cx, 80
mov ah, 0xF0
                                                                       mov ah, 0x70
mov al, '|'
                                                                       mov al, '='; black = character on white
mov word [es:di], ax
                                                                       cld
xor ax. ax
                                                                       rep stosw
mov es, ax; point es to IVT base
                                                                       pop di
cli; disable interrupts
                                                                       рор сх
mov word [es:9*4], kbisr; store offset at n*4
                                                                       pop bx
mov [es:9*4+2], cs; store segment at n*4+2
                                                                       pop ax
mov word [es:8*4], timer; store offset at n*4
                                                                       pop es
mov [es:8*4+2], cs; store segment at n*4+
                                                                       ret
again: jmp again
                                                                       kbisr:
                                                                       push es
clrscr: push es
                                                                       push ax
push ax
                                                                       push di
push cx
                                                                       mov ax, 0xB800
push di
                                                                       mov es, ax
mov ax, 0xb800
mov es, ax; point es to video base
                                                                       in al, 0x60
xor di, di ; point di to top left column
                                                                       cmp al, 0x50; down arrow is pressed
mov ax, 0x7020; space char in black on white
                                                                       jne next
mov cx, 2000; number of screen locations
                                                                       add word [cs:offset], 160
cld; auto increment mode
                                                                       mov di, [cs:offset]
rep stosw; clear the whole screen
                                                                       mov ah, 0xF0
```

```
pop di
                                                                          mov al, '|'
pop cx
                                                                          mov [es:di], ax// blinking black | on white
pop ax
                                                                          jmp end
pop es
ret
                                                                          test al, 0x80
                                                                          jnz end
timer:
push ax
                                                                          call \, Scan Code To Ascii Converter \,
add word [cs:count], 1
                                                                          mov al, ah
cmp word [cs:count], 1080
                                                                          mov ah, 0x70
                                                                          mov di, [cs:offset]
jne end
mov word [cs:count], 0
                                                                          mov [es:di], ax
call copyToBottom
                                                                          add di, 2
end:
                                                                          add word [cs:offset], 2
pop ax
                                                                          mov ah, 0xF0
mov al, 0x20
                                                                          mov al, '|'
out 0x20, al
                                                                          mov [es:di], ax
iret
                                                                          end:
                                                                          pop di
                                                                          pop ax
copyTo Bottom:
                                                                          pop es
                                                                          mov al, 0x20
push es
                                                                          out 0x20, al
push ax
push bx
                                                                          iret
push ds
push si
push di
push cx
mov ax, 0xB800
mov es, ax
push es
pop ds
mov si, 0
mov ax, 80
mov bx, 13
mul bx
shl ax, 1
mov di, ax
mov cx, 960
cld
rep movsw
pop cx
pop di
pop si
pop ds
pop bx
pop ax
pop es
ret
```