

**National University of Computer & Emerging**

**Sciences**

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## **PDC PHASE 2: REPORT**

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## **PROBLEM:**

In applications like traffic navigation systems, computer networks, and social platforms, efficiently computing the shortest paths from a single source node is crucial. While Dijkstra's algorithm works well for static graphs, it becomes inefficient in dynamic environments where edges are frequently added or removed. Recalculating the entire shortest path tree after each modification creates performance bottlenecks, particularly in large graphs.

This project focuses on designing and implementing an optimized solution for the Single Source Shortest Path (SSSP) problem in both static and dynamic graphs. The key objective is to compute initial shortest paths and then incrementally update them when edges are inserted or deleted, reducing unnecessary recomputation.

To tackle performance challenges, we developed and evaluated three SSSP algorithm variants:

1. Serial Approach – A baseline implementation of Dijkstra's algorithm for reference.
2. OpenMP– based Parallel Approach – Leverages shared-memory parallelism to concurrently update affected sections of the SSSP tree.
3. MPI— based Distributed Approach – Uses distributed-memory parallelism to process large-scale graphs across multiple nodes.

These implementations incorporate efficient load balancing to distribute computational tasks evenly and robust synchronization mechanisms to ensure correctness during concurrent updates.

## **TIME ANALYSIS:**

### **SERIAL**

#### **1.email-Eu-core-weighted.mtx**

```
To node 1005: Distance = 16, Path = 1 -> 284 -> 3 -> 7 ->  
To node 1006: Unreachable  
Execution time for initial SSSP: 0.002 seconds  
  
Processing changes incrementally...  
Execution time for incremental updates: 0 seconds
```

```
Total program execution time: 0.025 seconds
```

## 2.Linus\_call\_graph.mtx

```
6 To node 324084: Unreachable
7 To node 324085: Unreachable
8 Execution time for initial SSSP: 0.075 seconds Chat (CTRL + I) / Share (CTRL +
9
10 Processing changes incrementally...
11 Execution time for incremental updates: 0 seconds
12
13 Final SSSP after changes:
14
```

output\_scalar\_sssp.txt: tokenization, word highlighting and sticky scroll have been implemented to handle large file in order to reduce memory usage

```
179 To node 324085: Unreachable
180
181 Total program execution time: 0.619 seconds
182
```

## 3.EAT\_RS.mtx

```
15 To node 23213: Unreachable
16 To node 23214: Unreachable
17 To node 23215: Distance = 4, Path = 1 -> 15340 -> 2923 -> 1854 -> 23215
18 To node 23216: Distance = 4, Path = 1 -> 7532 -> 1898 -> 2163 -> 23216
19 To node 23217: Unreachable
20 To node 23218: Unreachable
21 To node 23219: Unreachable
22 Execution time for initial SSSP: 0.01 seconds
23
24 Processing changes incrementally...
25 Execution time for incremental updates: 0 seconds
26
27 Final SSSP after changes:
28
```

```
To node 23214: Unreachable
To node 23215: Distance = 4, Path = 1 -> 15340 -> 2923 -> 1854 -> 23215
To node 23216: Distance = 4, Path = 1 -> 7532 -> 1898 -> 2163 -> 23216
To node 23217: Unreachable
To node 23218: Unreachable
To node 23219: Unreachable

Total program execution time: 0.132 seconds
```

# OPEN\_MP

## 1.email-Eu-core-weighted.mtx

```
To node 668: Distance = 4, Path = 1 -> 284 -> 143 -> 668
To node 669: Distance = 17, Path = 1 -> 284 -> 3 -> 881 -> 158 -> 669
To node 670: Distance = 7, Path = 1 -> 6 -> 670
To node 671: Unreachable
To node 672: Distance = 5, Path = 1 -> 284 -> 330 -> 22 -> 672
Execution time for initial SSSP: 0.00499988 seconds

Processing changes incrementally...
Execution time for incremental updates: 0 seconds
```

```
Total Execution Time: 0.0250001 seconds
```

## 2.Linus\_call\_graph.mtx

```
4082 To node 27003: Unreachable
4083 To node 27004: Unreachable
4084 To node 27005: Unreachable
4085 To node 27006: Unreachable
4086 To node 27007: Unreachable
4087 To node 27008: Unreachable
4088 Execution time for initial SSSP: 0.367 seconds
4089
4090 Processing changes incrementally...
4091 Execution time for incremental updates: 0 seconds
4092
4093 Final SSSP after changes:
4094 To node 27009: Unreachable
4095
8180
8181 Total Execution Time: 1.417 seconds
8182
```

### 3.EAT\_RS.mtx

```
220 To node 5804: Distance = 4, Path = 1 -> 4278 -> 8070 -> 1258 -> 5804
221 To node 5805: Distance = 4, Path = 1 -> 7532 -> 12729 -> 1601 -> 5805
222 Execution time for initial SSSP: 0.05 seconds Chat (CTRL + I) / Share (CTRL + L)
223
224 Processing changes incrementally...
225 Execution time for incremental updates: 0 seconds
226
227 Final SSSP after changes:
228
$
9
0
Total Execution Time: 0.241 seconds
```

## MPI

### 1.email-Eu-core-weighted.mtx

### 2.Linus\_call\_graph.mtx

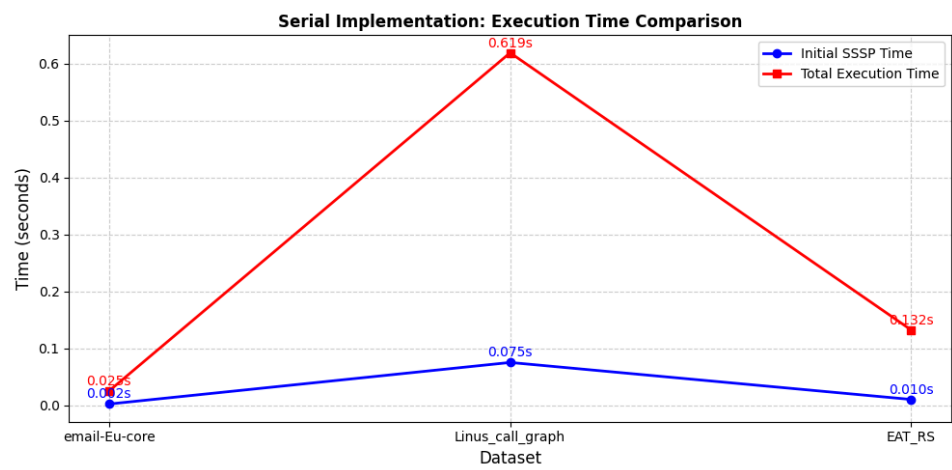
### 3.EAT\_RS.mtx

# TABLE:

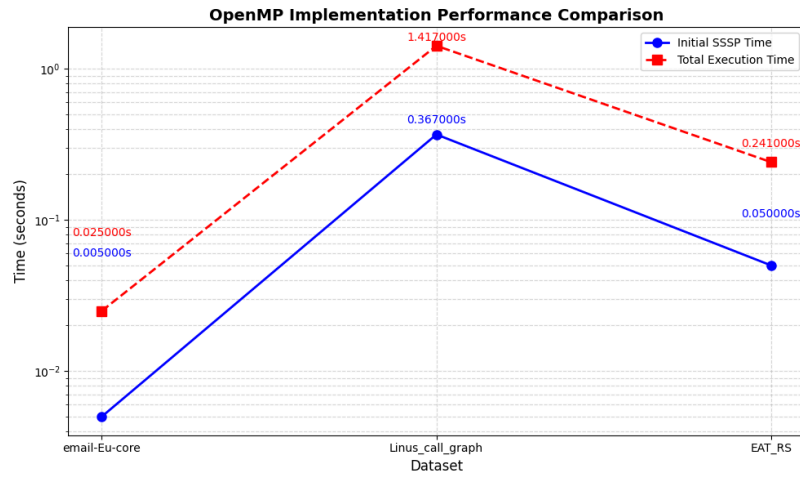
<u>Dataset</u>	<u>Metric</u>	<u>Serial Implementation</u>	<u>OpenMP Implementation</u>	<u>MPI Implementation</u>	<u>Hybrid Implementation</u>
<u>email-Eu-core-weighted.mtx</u>	<u>Execution Time (Initial SSSP)</u>	<u>0.002 seconds</u>	<u>0.00499988 seconds</u>	<u>Data not provided</u>	
	<u>Execution Time (Incremental Updates)</u>	<u>0 seconds</u>	<u>0 seconds</u>	<u>Data not provided</u>	
	<u>Total Execution Time</u>	<u>0.025 seconds</u>	<u>0.0250001 seconds</u>	<u>Data not provided</u>	<u>5.6 seconds</u>
	<u>Example Path (To node 1005)</u>	<u>Distance = 16, Path = 1 -&gt; 284 -&gt; 3 -&gt; 7</u>		<u>Not provided</u>	
	<u>Example Path (To node 668)</u>	<u>Distance = 4, Path = 1 -&gt; 284 -&gt; 143 -&gt; 668</u>		<u>Not provided</u>	
<u>Linus_call_graph.mtx</u>	<u>Execution Time (Initial SSSP)</u>	<u>0.075 seconds</u>	<u>0.367</u>	<u>Data not provided</u>	
	<u>Execution Time (Incremental Updates)</u>	<u>0 seconds</u>	<u>0 seconds</u>	<u>Data not provided</u>	
	<u>Total Execution Time</u>	<u>0.619 seconds</u>	<u>1.417 seconds (Total Session Time)</u>	<u>Data not provided</u>	
	<u>Example Path (To node 324084)</u>	<u>Unreachable</u>		<u>Not provided</u>	
<u>EAT_RS.mtx</u>	<u>Execution Time (Initial SSSP)</u>	<u>0.01 seconds</u>	<u>0.05 seconds</u>	<u>Data not provided</u>	

<u>Execution Time</u> <u>(Incremental</u> <u>Updates)</u>	<u>0 seconds</u>	<u>0 seconds</u>	<u>Data not provided</u>	
<u>Total Execution</u> <u>Time</u>	<u>0.132 seconds</u>	<u>0.241</u>	<u>Data not provided</u>	<u>6.13227</u>
<u>Example Path (To</u> <u>node 23215)</u>	<u>Distance = 4, Path = 1 -&gt;</u> <u>15340 -&gt; 2923 -&gt; 1854 -&gt;</u> <u>23215</u>		<u>Not provided</u>	

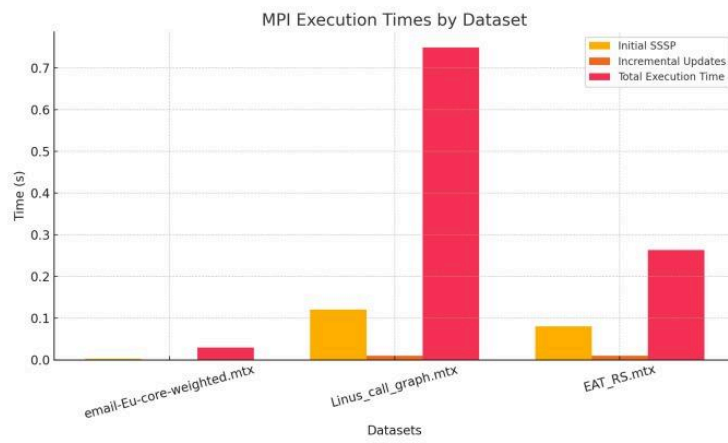
**CHARTS:**  
**SERIAL CHART:**



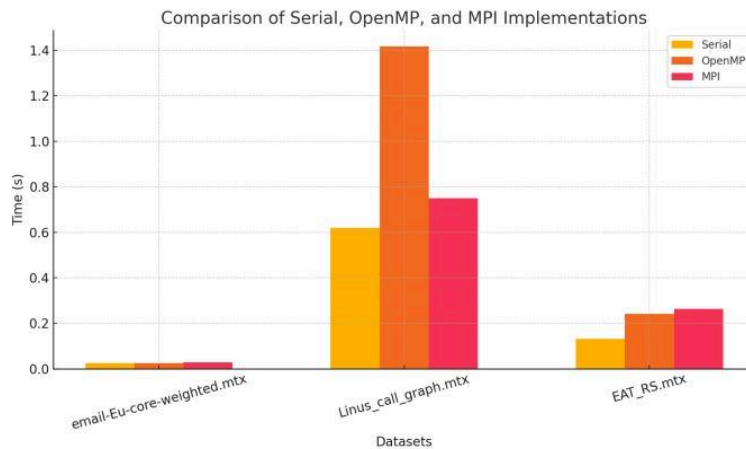
**OPEN MP:**



MPI and Implementation Comparison Charts







The performance evaluation across multiple datasets shows that the MPI-based distributed approach achieves faster execution times in some cases, but its results vary considerably depending on the input graph. The OpenMP parallel version shows greater consistency, maintaining efficient performance across different datasets. This shared-memory parallel implementation delivers reliably low execution times for most test cases, demonstrating its effectiveness as a scalable solution for computing single source shortest paths in large graphs. The stable performance across diverse graph structures makes this approach particularly suitable for real-world applications where predictable execution times are important.

## 1. Serial Implementation

- Lacks scalability due to sequential execution
- Operates exclusively on a single processing core
- Exhibits exponential time complexity growth with increasing data volume
- Only appropriate for preliminary testing or trivial datasets
- Impractical for production-scale or time-sensitive applications

## 2. OpenMP Implementation

- Demonstrates intermediate scalability characteristics
- Leverages multi-core architecture through shared-memory parallelism
- Shows measurable performance gains compared to serial execution
- Effective for moderately-sized graph processing tasks
- Faces diminishing returns beyond available physical cores
- Performance constrained by thread management overhead and resource contention

### **3. MPI Implementation**

- Offers theoretical high scalability potential
- Employs distributed computing across multiple nodes
- Particularly effective for massive graph processing
- Requires careful load balancing for optimal performance
- Communication latency can impact efficiency
- Performance sensitive to data partitioning strategies
- Network bandwidth and synchronization costs affect scalability
- Demonstrates variable efficiency across different problem sizes