

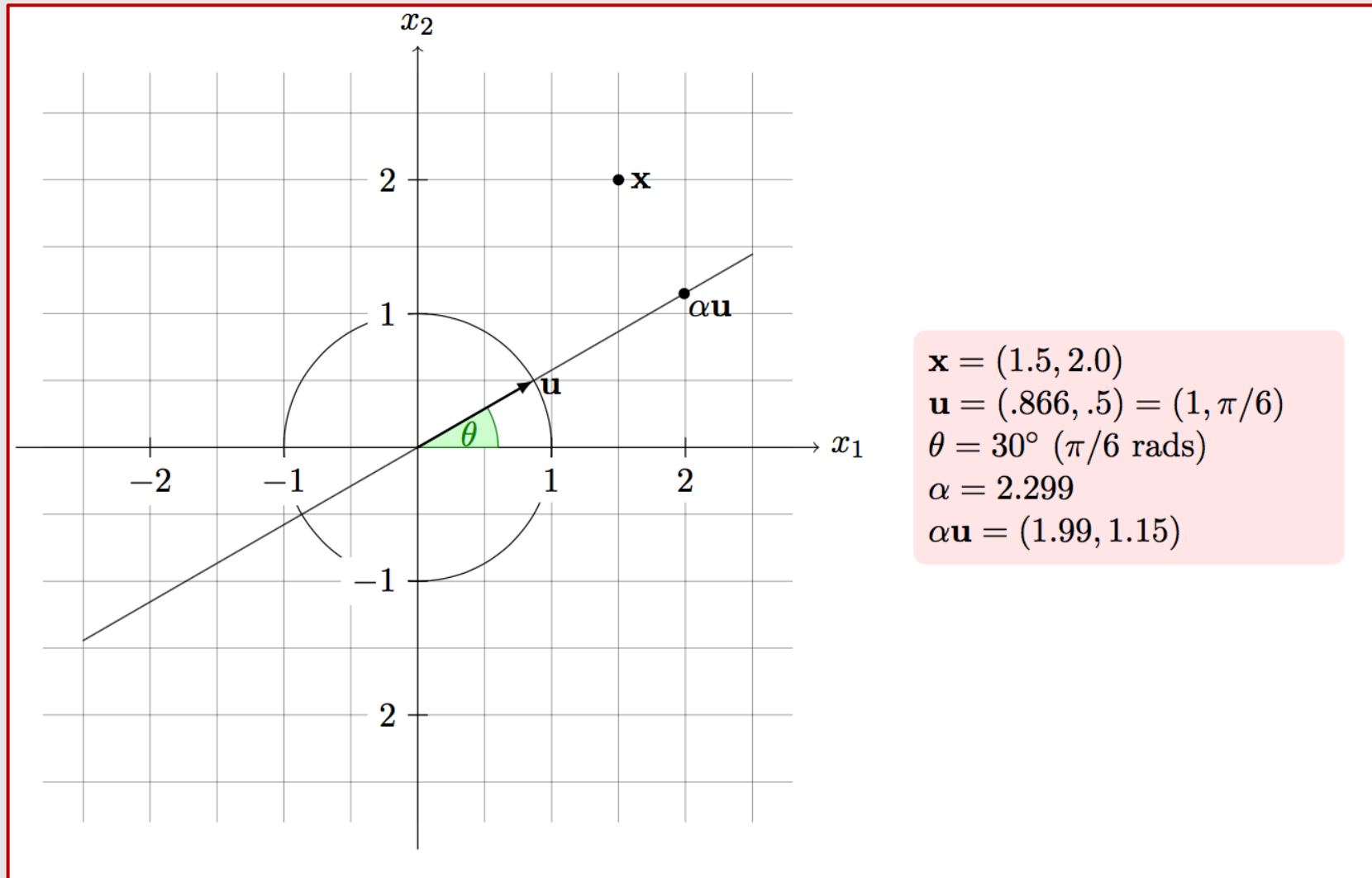
Exercise from Goodfellow et al Book Web Page

Slides by Anthony Maida

The expression $\alpha \mathbf{u}$ for $\alpha \in \mathbb{R}$ and unit vector $\mathbf{u} \in \mathbb{R}^n$ defines a line of points that may be obtained by varying the value of α . Derive an expression for the point \mathbf{y} that lies on this line that is as close as possible to an arbitrary point $\mathbf{x} \in \mathbb{R}^n$. This operation of replacing a point by its nearest member within some set is called *projection*.

Possible application in data science: If you do an eigendecomposition on a dataset sampled from a bivariate distribution and want to project all data points onto the principle axis, this is a way to do it.

Diagram in 2D to Visualize the Problem



Steps in Solution

Minimize

$$\|\mathbf{x} - \mathbf{y}\|^2.$$

$$\|\mathbf{x} - \alpha \mathbf{u}\|^2.$$

$$\mathbf{x} - \alpha \mathbf{u} = \begin{bmatrix} x_1 - \alpha u_1 \\ x_2 - \alpha u_2 \\ \vdots \\ x_n - \alpha u_n \end{bmatrix}$$

$$\begin{aligned} & \|\mathbf{x} - \alpha \mathbf{u}\|^2 \\ &= (\mathbf{x} - \alpha \mathbf{u})^\top (\mathbf{x} - \alpha \mathbf{u}) \\ &= \mathbf{x}^\top \mathbf{x} - 2\alpha \mathbf{x}^\top \mathbf{u} + \alpha^2 \mathbf{u}^\top \mathbf{u} \\ &= \mathbf{x}^\top \mathbf{x} - 2\alpha \mathbf{x}^\top \mathbf{u} + \alpha^2. \end{aligned}$$

This step explained on next slide.

Euclidean Distance of Point or Vector from Origin

$$||\mathbf{v}||$$

$$\sqrt{\sum_{i=1}^n (v_i - 0)^2} = \sqrt{\sum_{i=1}^n v_i^2}$$

$$||\mathbf{x} - \alpha\mathbf{u}||^2 = (\mathbf{x} - \alpha\mathbf{u})^T (\mathbf{x} - \alpha\mathbf{u})$$



Move transpose inward.

$$(\mathbf{x} - \alpha\mathbf{u})^T = \mathbf{x}^T - \alpha\mathbf{u}^T$$

$$||\mathbf{x} - \alpha\mathbf{u}||^2 = (\mathbf{x}^T - \alpha\mathbf{u}^T)(\mathbf{x} - \alpha\mathbf{u})$$

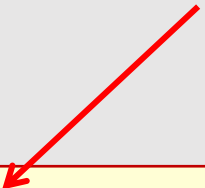
1. Multiplication is associative for matrices.
2. Addition and multiplication are distributive for matrices.
3. Multiplication is **not** commutative for matrices. For instance, if a and b were matrices then ab would not necessarily equal ba . There are exceptions. For instance, since \mathbf{x} and \mathbf{u} are vectors, $\mathbf{u}^T \mathbf{x} = \mathbf{x}^T \mathbf{u}$.

$$(\mathbf{x}^T - \alpha \mathbf{u}^T)(\mathbf{x} - \alpha \mathbf{u}) = \mathbf{x}^T \mathbf{x} - \alpha \mathbf{u}^T \mathbf{x} - \alpha \mathbf{u}^T \mathbf{x} + \alpha^2 \mathbf{u}^T \mathbf{u}$$

Formula for Distance as a Function of Alpha

$$f(\alpha) = \mathbf{x}^T \mathbf{x} - 2\alpha \mathbf{u}^T \mathbf{x} + \alpha^2$$

Notice how transpose creates a row vector.


$$f(\alpha) = [x_1, x_2] \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} - 2\alpha [u_1, u_2] \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \alpha^2$$

$$f(\alpha) = x_1^2 + x_2^2 - 2\alpha(x_1 u_1 + x_2 u_2) + \alpha^2$$

Take Derivative and Set to Zero

$$f(\alpha) = x_1^2 + x_2^2 - 2\alpha(x_1u_1 + x_2u_2) + \alpha^2$$

From previous slide

Derivative wrt alpha

$$f'(\alpha) = -2(x_1u_1 + x_2u_2) + 2\alpha$$

$$f'(\alpha) = -2\mathbf{x}^T \mathbf{u} + 2\alpha = 0$$

$$f'(\alpha) = -2\mathbf{x}^T \mathbf{u} + 2\alpha$$

Set to
zero

$$\alpha = \mathbf{x}^T \mathbf{u} = [x_1, x_2] \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}$$

Solve for alpha