



**Research
Design Lab**



GSM GPRS SIM800C Module

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1. Overview

GSM/GPRS Modem-RS232 is built with the Quad-Band GSM/GPRS engine-SIM800C, works on frequencies 850/900/1800/1900MHz. The module comes with RS232 interface, which allows you to connect PC as well as microcontroller with RS232 Chip(MAX232). The baud rate is configurable from 9600-115200 through AT command. The GSM/GPRS modem is having internal TCP/IP stack to enable you to connect with internet via GPRS. This module is suitable for SMS, Voice as well as DATA transfer application in M2M interface. The onboard Regulated Power supply allows you to connect wide range of unregulated power supply. Using this modem, you can make audio calls, SMS, Read SMS, attend the incoming calls and internet etc., through simple AT commands.

2. Features

- Quad-Band GSM/GPRS 850/900/1800/1900MHz.
- RS232 interface for the direct communication with computer or MCU kit.
- Configurable Baud Rate.
- Power controlled using 29302WU IC.
- ESD Compliance.
- Enable with MIC and Speaker socket.
- Enable with Audio Jack
- With push push sim card holder.
- With Stub antenna and SMA connector.
- Input Voltage: 12V DC.
- High quality PCB FR4 Grade with FPT certified

3. SIM800C General Features

- Quad-Band GSM/GPRS 850/900/1800/1900MHz.
- GPRS Multi-Slot Class 12/10
- GPRS Mobile Station Class B
- Compliant to GSM Phase 2/2+ : Class 4(2W @ 850/900MHz)
Class 1(1W @ 1800/1900MHz)
- Dimensions: 17.6*15.7*2.3mm
- Weight: 1.3g
- Control via AT Commands: (3GPP TS 27.007,27.006 and SIM Com enhanced AT Commands)
- Supply Voltage Range 3.4 ~ 4.4V
- Low Power Consumption.
- Operation Temperature: -40°C ~85°C.

4. Software Features

- 0710 MUX Protocol
- Embedded TCP/UDP Protocol
- FTP/HTTP
- MMS
- POP3/SMTP
- DTMF
- Jamming Detection
- Audio Record
- SSL
- Bluetooth 3.0(Optional)

5. Applications

- Industrial automation.
- GPRS based data logging.
- GPRS and GPS application.
- Home automation.
- Health monitoring.
- Agriculture automation
- Vehicle tracking.
- Remote monitoring and controlling.
- GPRS based Weather report logging
- GSM GPRS based Security alert.
- GPRS based remote terminal for file transfer.
- IVRS.
- Bulksms sending

6. Specification

6.1. Specifications for GPRS Data

- GPRS Class 12: max.85.6 kbps (downlink/uplink)
- PBCCH Support
- Coding Scheme CS 1,2,3,4
- PPP-Stack
- USSD

6.2. Specifications for SMS via GSM/GPRS

- Point to Point MO and MT
- SMS Cell Broad Cast
- Text and PDU Mode

6.3. Specifications for Voice

- Tricodec: Half Rate(HR)

Full Rate(FR)

Enhanced Full Rate(EFR)

- AMR: Half Rate(HR)

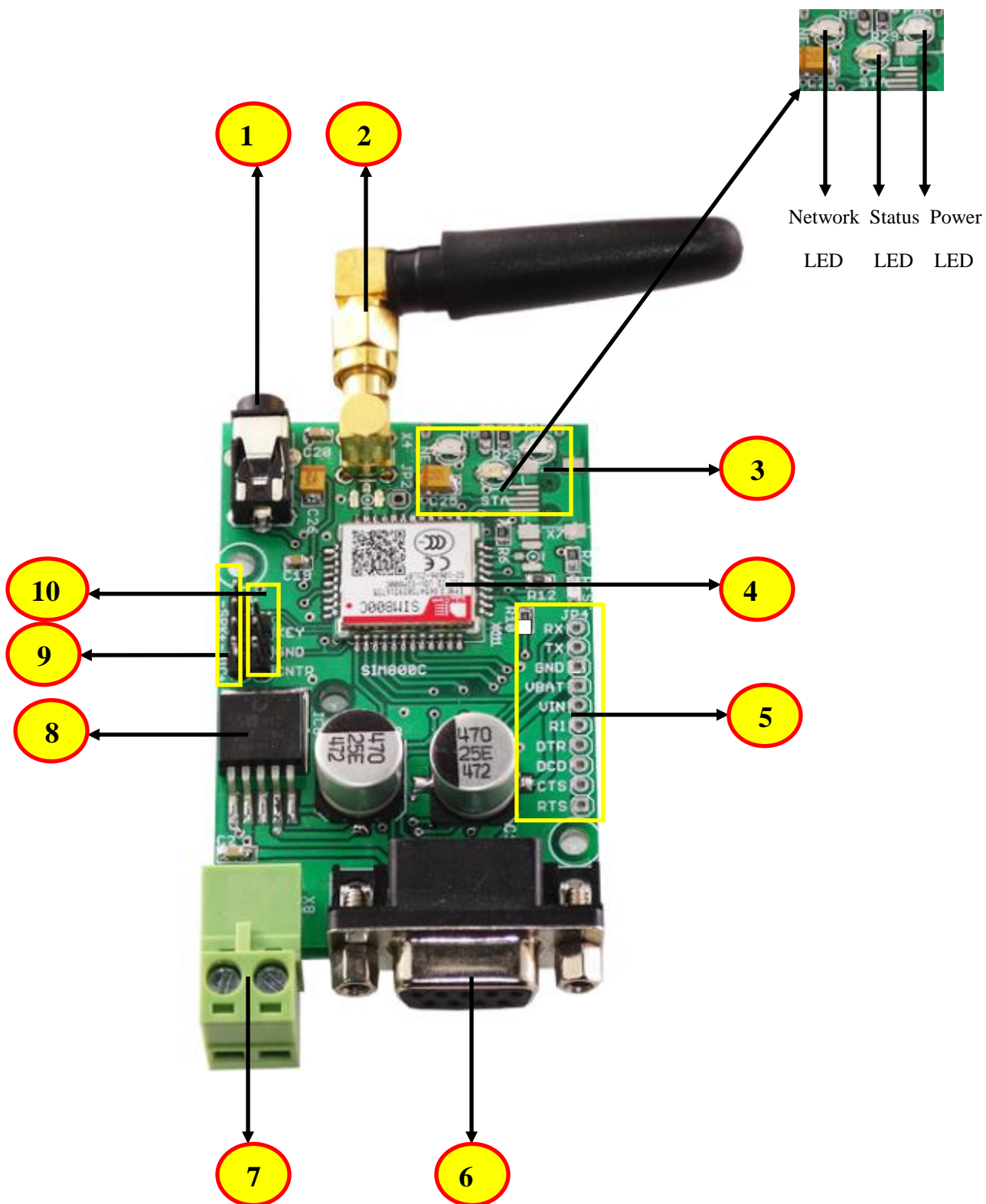
Full Rate(FR)

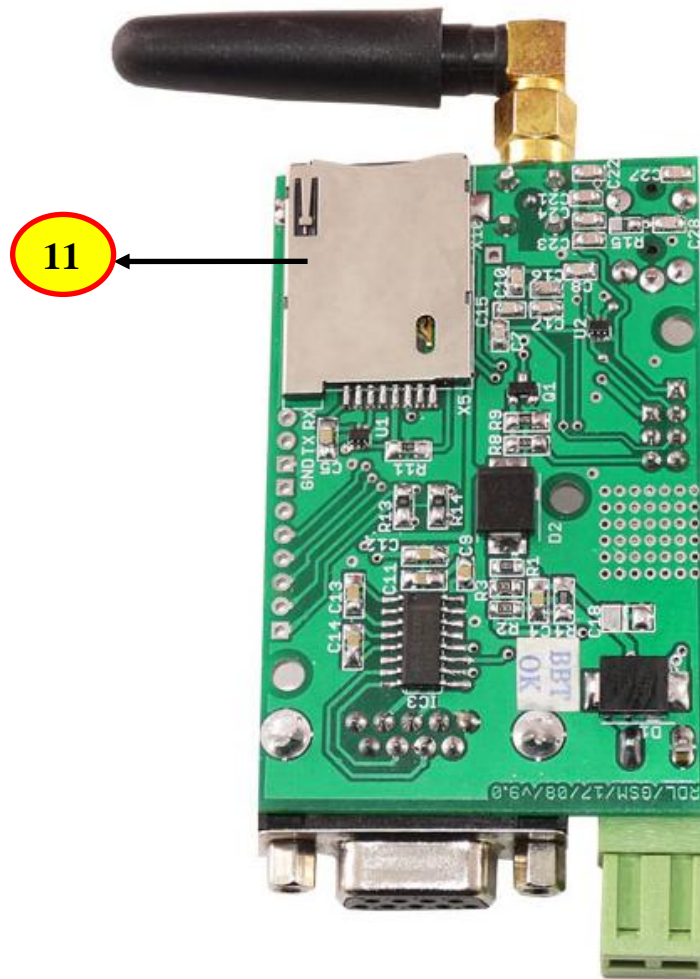
- Hands-Free Operation (Echo Suppression).

7. Interfaces

- 42 SMT Pins Including
- Analog Audio Interface
- RTC Backup
- USB Interface
- Serial Interface
- Interface to External SIM 3V/1.8V
- GPIO
- ADC
- GSM Antenna Pad
- Bluetooth Antenna Pad

8. Narration





1. Audio Jack
2. Stub antenna with SMA connector.
3. Network, Status and Power indicator.
4. SIM800C Module
5. General GPIO SIM800C
6. DB9 Connector
7. Power Supply 12V/2A
8. DC to DC Converter (29302WU IC)
9. Pins for Speaker and Mic
10. Power On Selection Pins
11. SIM Card Slot

9. Basic AT Commands for Testing

9.1. GSM AT Commands :

- [To Check Modem](#)

AT↓

OK

- [To Change SMS Sending Mode](#)

AT+CMGF=1↓

OK

- [To Send New SMS](#)

AT+CMGS="Mobile Number."↓

<Message

{CTRL+Z}

- [To Receive SMS](#)

AT+CMGD=1↓ {To delete the message in buffer}

AT+CMGR=1↓ {To receive the first message AT+CMGR=1}

{To receive the second message AT+CMGR=2 and so on}

+CMGL: 1,"REC READ","+85291234567","07/05/01,08:00:15+32"145,37

<Message

- [Preferred SMS Message Storage](#)

AT+CPMS=?↓

+CPMS: ("SM"),("SM"),("SM")

OK

AT+CPMS=?↓

+CPMS: "SM",19,30,"SM",19,30,"SM",19,30

- [To Make Voice Call](#)

ATD9876543210; ↓

- [To Redial Last Number](#)

ATDL ↓

- [To Receive Incoming Call](#)

ATA ↵

- [To Hangup Or Disconnect Call](#)

ATH ↵

- [To Set A Particular Baud Rate](#)

AT+IPR=?↵ {To view the baud rate value}

AT+IPR=0↵ {To set the modem to autobauding mode}

- [Operator Selection](#)

AT+COPS=?↵

OK

AT+COPS?↵

+COPS:0,0,"AirTel"

OK

- [To Set Cellular Result Codes For Incoming Call Indication](#)

AT+CRC=?↵

+CRC: (0-1)

OK

AT+CRC?↵

+CRC: 0

OK

AT+CRC=1↵

+CRC: 1

OK

+CRING: VOICE

- [Read Operator Names](#)

AT+COPN=? ↵

OK

AT+COPN ↵

+COPN: "472001","DHIMOBILE"

+COPN: "60500 +COPN: "502012","maxis mobile"

+COPN:

+COPN: "502013","TMTOUCH"

+COPN

+COPN: "502016","DiGi"

+COPN: "502017","TIMECel"

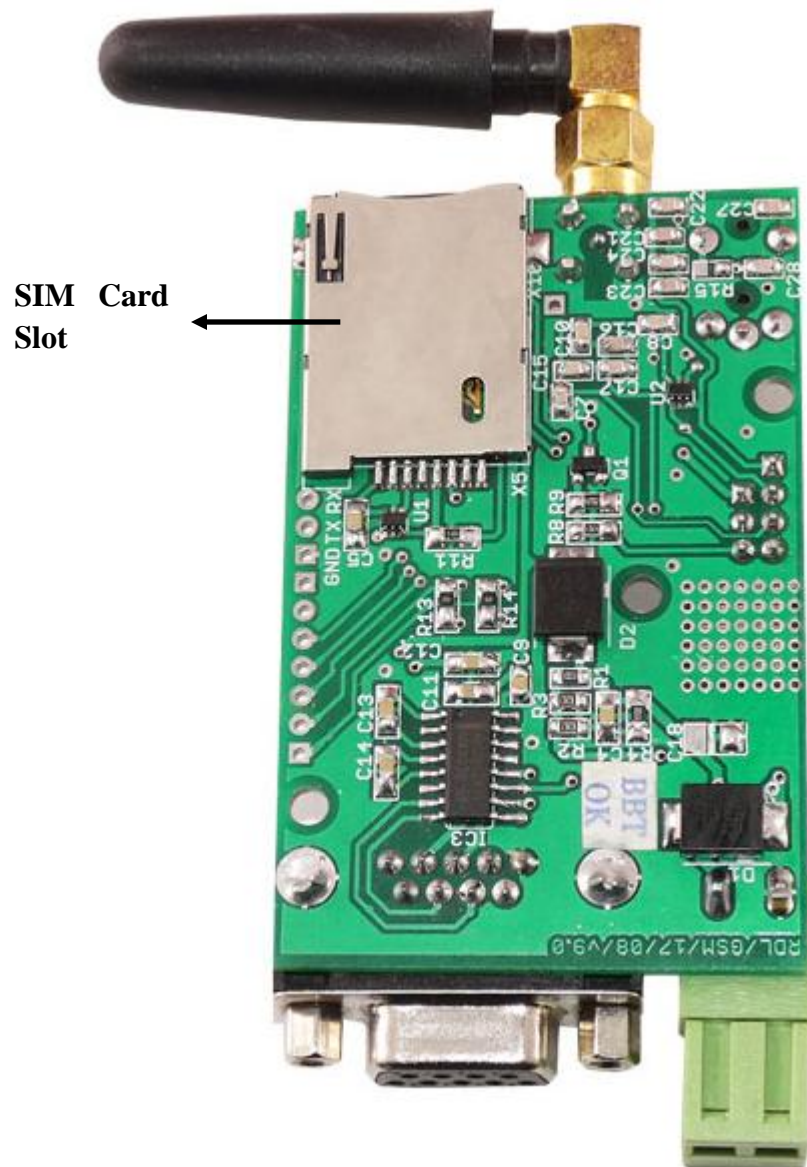
+COPN: "502019","CELCOM GSM"

9.2. GPRS AT Commands :

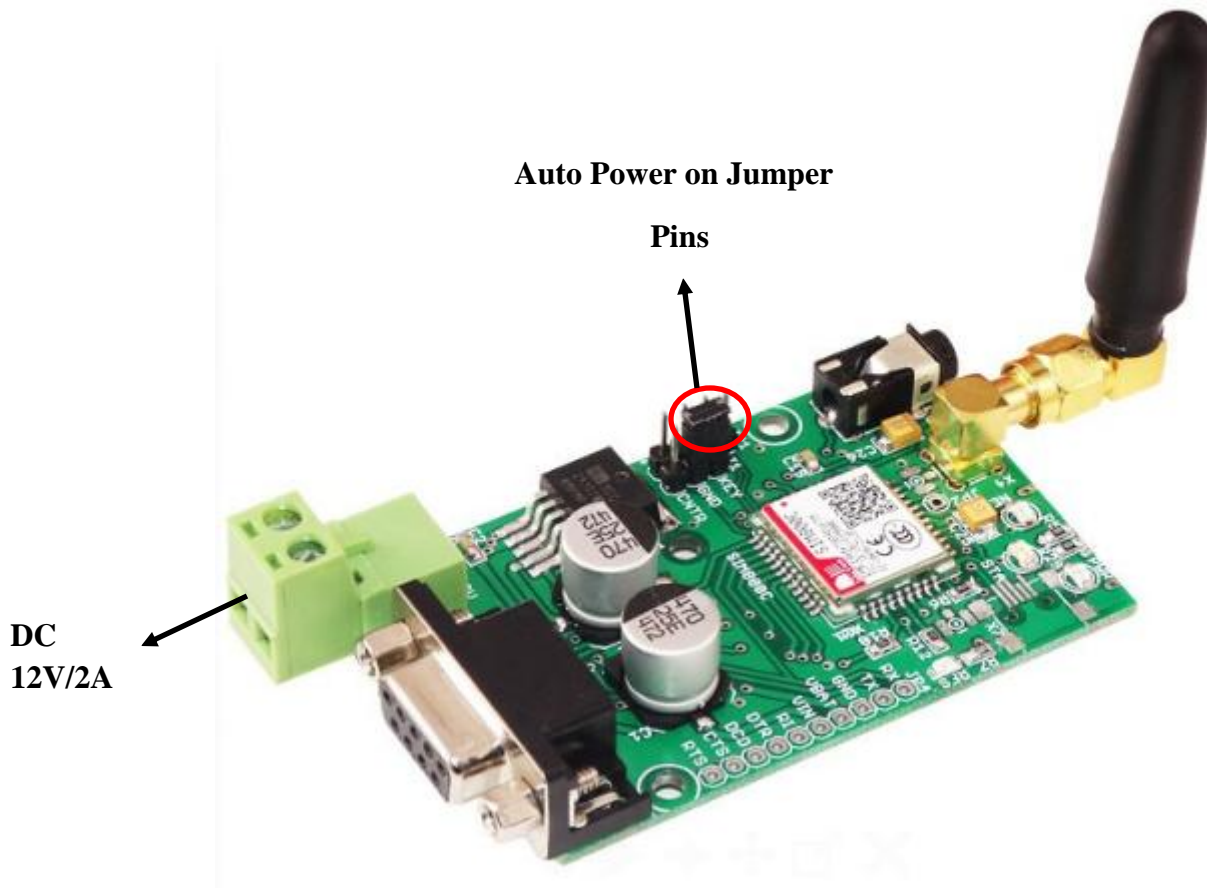
Commands	Description
AT+CGATT ↵	ATTACH/DETACH FROM GPRS SERVICE
AT+CGDCONT ↵	DEFINE PDP CONTEXT
AT+CGQMIN ↵	QUALITY OF SERVICE PROFILE (MINIMUM ACCEPTABLE)
AT+CGQREQ ↵	QUALITY OF SERVICE PROFILE (REQUESTED)
AT+CGACT ↵PDP	CONTEXT ACTIVATE OR DEACTIVATE
AT+CGDATA ↵	ENTER DATA STATE
AT+CGPADDR ↵	SHOW PDP ADDRESS
AT+CGCLASS ↵	GPRS MOBILE STATION CLASS
AT+CGEREP ↵	CONTROL UNSOLICITED GPRS EVENT REPORTING
AT+CGREG ↵	NETWORK REGISTRATION STATUS
AT+CGSMS ↵	SELECT SERVICE FOR MO SMS MESSAGES
AT+CGCOUNT ↵	GPRS PACKET COUNTERS

10. Module Setup

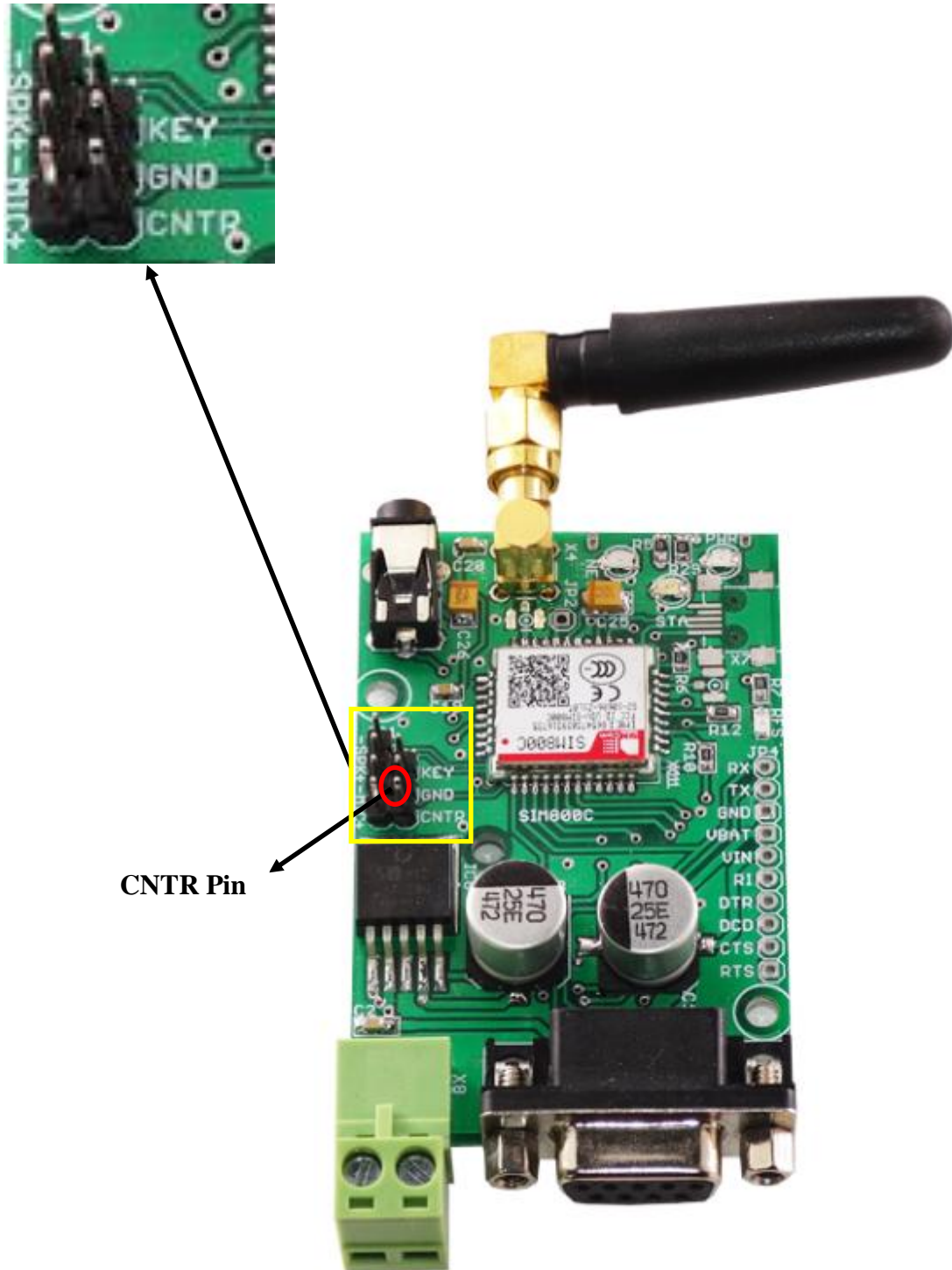
Step 1 : Insert SIM Card into the SIM Card Slot



Step2: Plug in 12V-2A DC power adapter, power led is lit(place jumper between KEY and GND pin for only to turn ON automatically).



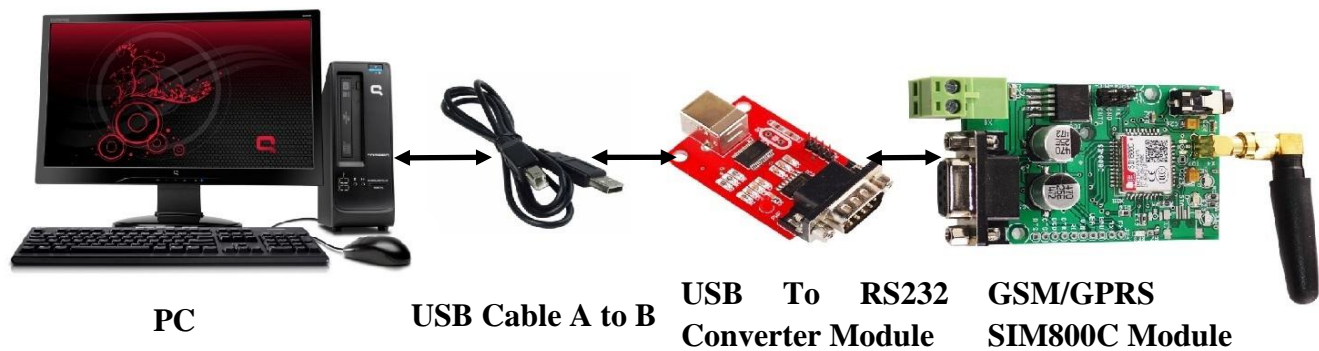
Step 3: Give Rising Edge Pulse to CNTR pin (External Power on Key) using any external controller (To turn on manually without jumper)



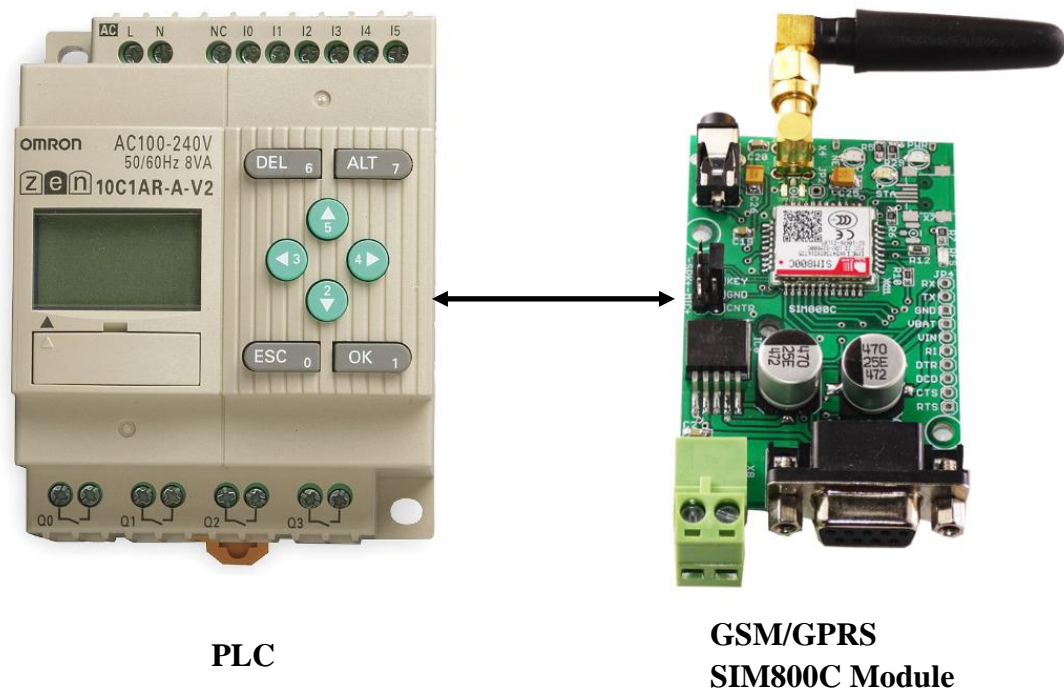
Step 4: Connect the PC to DB9 Connector of the GSM GPRS SIM800C Module via USB To RS232 Converter Module given in below link and USB Cable A to B.

<https://researchdesignlab.com/usb-to-rs232-converter.html>

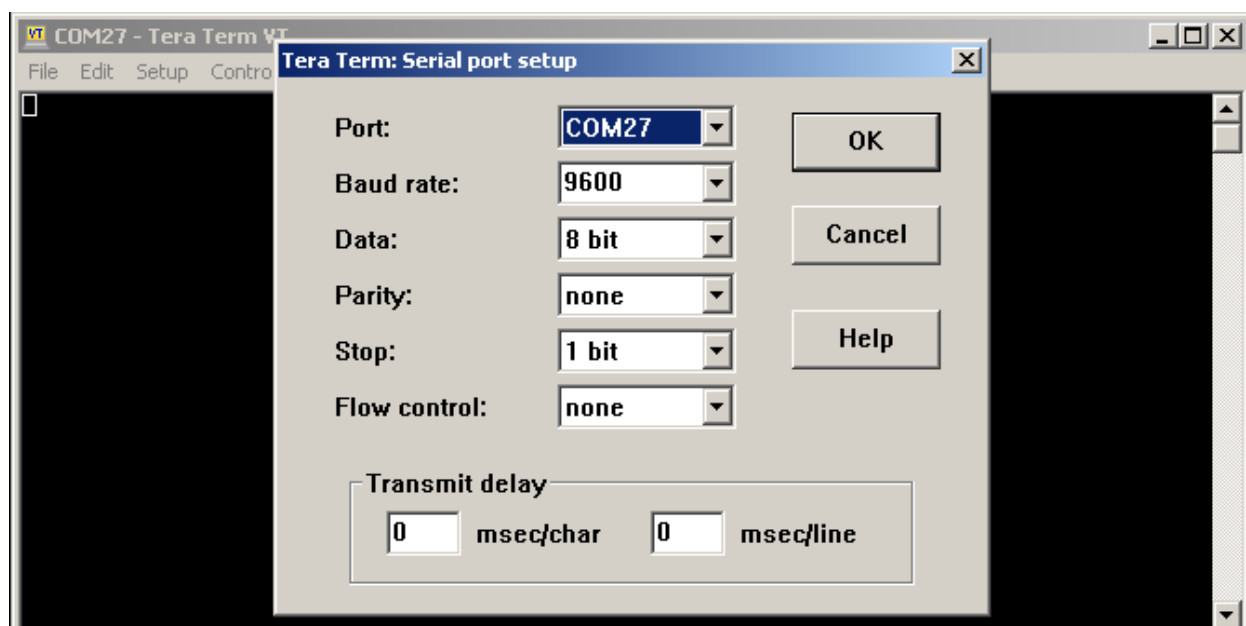
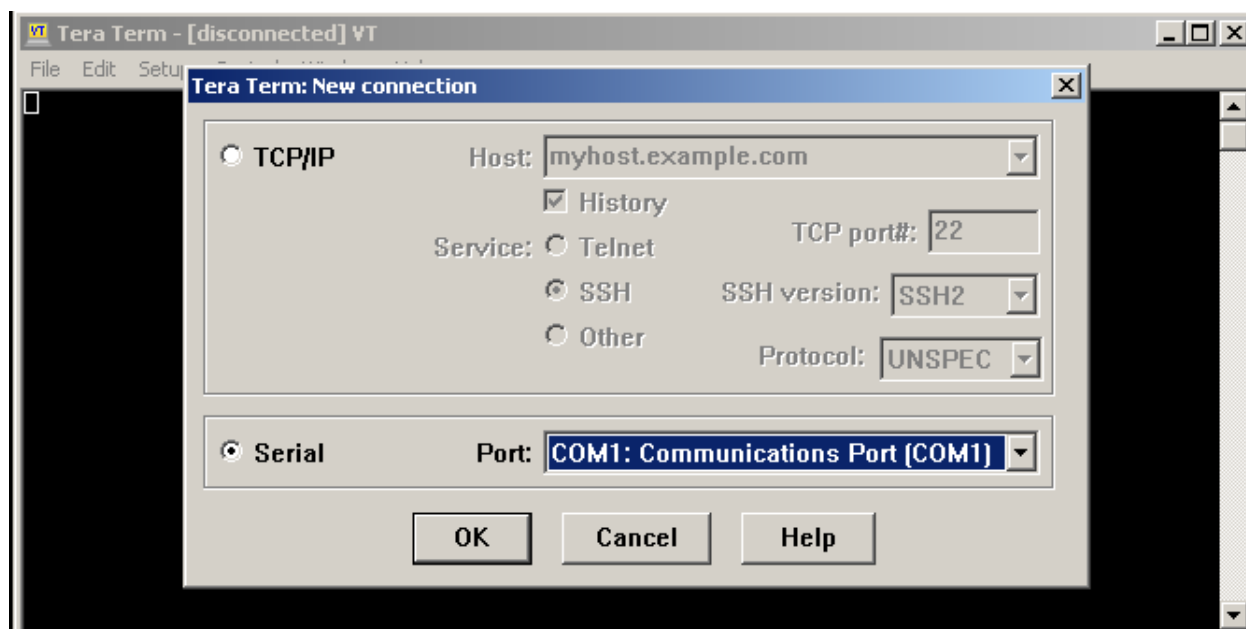
Interfacing PC with GSM GPRS SIM800C Module

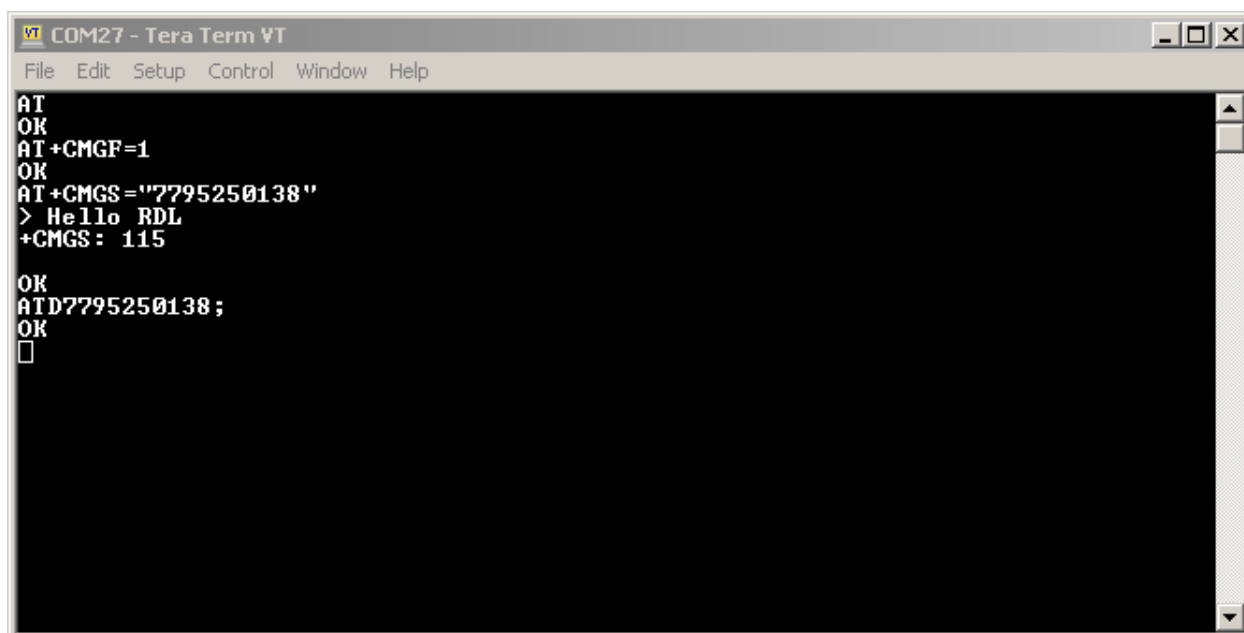


Interfacing PLC with GSM GPRS SIM800C Module



Step 6: Open any Serial Terminal software(eg: Tera Term, HyperTerminal), choose appropriate COM port and then use AT commands listed in this manual for basic testing GPRS GSM messaging and voice calling.





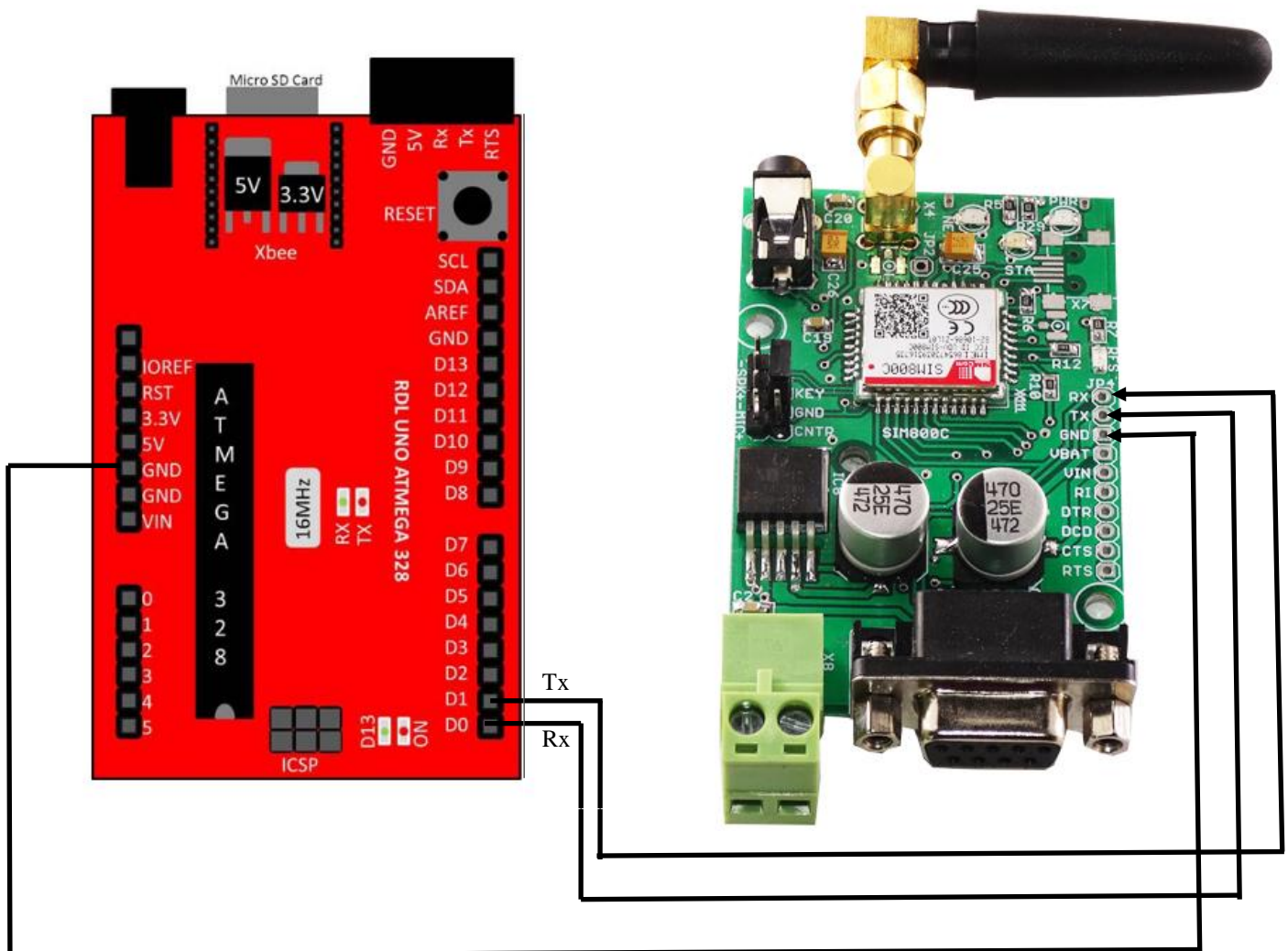
The screenshot shows a Tera Term VT window titled 'COM27 - Tera Term VT'. The window has a menu bar with 'File', 'Edit', 'Setup', 'Control', 'Window', and 'Help'. The main area is a black terminal window with white text. The text shows the following sequence of commands and responses:

```
AT
OK
AT+CMGF=1
OK
AT+CMGS="7795250138"
> Hello RDL
+CMGS: 115

OK
ATD7795250138;
OK
□
```


11. Block Diagrams

Interfacing Arduino UNO and GSM GPRS SIM800C Module



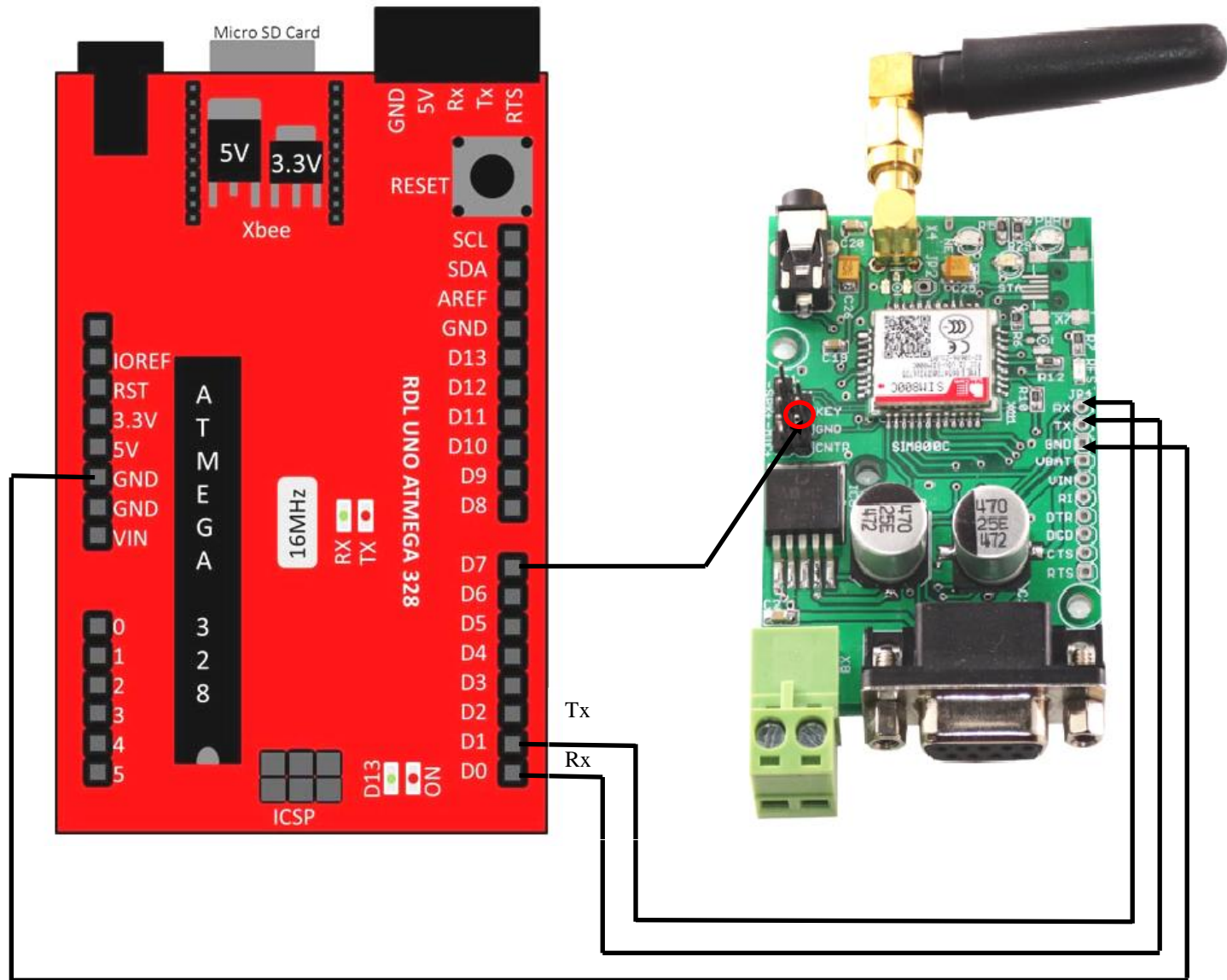
Arduino Code for Sending SMS and Making Voice Call

```
void setup()
{
  Serial.begin(9600);
  delay(5000);

}

void loop()
{
  Serial.println("AT");//TO CHECK THE MODEM
  delay(1000);
  Serial.println("AT+CMGF=1"); //TO CHANGE THE SMS SENDING MODE
  delay(1000);
  Serial.println("AT+CMGS=\"7795250138\""); //CHANGE TO DESTINATION NUMBER
  delay(1000);
  Serial.print("hi"); // MESSAGE TO BE SENT
  Serial.write(26);
  delay(1000);
  Serial.println("AT");
  delay(1000);
  Serial.println("AT+CMGF=1");
  delay(1000);
  Serial.println("ATD7795250138;");//TO MAKE VOICE CALL
  delay(1000);
}
```


Interfacing Arduino UNO and GSM GPRS SIM800C Module for GPRS Communication



Arduino Code for GPRS Connection

```
#include <SoftwareSerial.h>

SoftwareSerial mySerial(2, 3); // RX, TX

char aux_string[30];
String buffer1="/code2.php?V1=78&V2=98&V3=67&V4=65&V5=56"; //Values to be uploaded in the server
int8_t K=0;
int8_t answer;
int x = 0;

void setup ()
{
    pinMode(7, OUTPUT);
    digitalWrite(7, LOW);
    Serial.begin(9600);
    delay(100);
    mySerial.begin(9600);
    Serial.println("STARTING...");
    power_on();
    delay(3000);

    sendATcommand("AT+CMGF=1", "OK", 1000); //To Change SMS Sending Mode
    delay(1000);

    delay(1000);
    Serial.println("GSM IS READY...");
}

void loop ()
{
    UPLOAD();
}

void UPLOAD()
{
    delay(300);
    answer = sendATcommand("AT+CIPSTART=\\"TCP\\",\\"kanwalk.eu5.org\\",\\"80\\",
    "CONNECT OK", 15000); // To Start up TCP Connection, Change to your domain link
```

```
if (answer == 1)
{
    K=10;
    delay(500);
    Serial.println("Connected");
    answer = sendATcommand("AT+CIPSEND", ">", 5000); // To send Data through TCP
    if (answer == 1)
    {
        mySerial.print("GET ");
        mySerial.print(buffer1);
        mySerial.println(" HTTP/1.1");
        mySerial.print("Host: ");
        mySerial.println("kanwalk.eu5.org");
        mySerial.println("Connection: close");
        mySerial.println();
        mySerial.write(byte(0x1A));

        answer = sendATcommand("", "HTTP/1.1 200 OK", 15000); //To check the response of uploading
        if (answer == 1)
        {
            Serial.println("Uploaded");
            mySerial.flush();
        }
    }
}

void power_on()
{
    uint8_t answer=0;

    start:
    delay(2000);
    digitalWrite(7, HIGH);
    delay(2000);
    digitalWrite(7, LOW);
    answer=0;
    while(answer==0)
    {
```

```
answer = sendATcommand("", "Call Ready", 20000);
answer = sendATcommand("AT", "OK", 2000); //To Check the Modem
answer = sendATcommand("AT+IPR=9600", "OK", 2000); //To Set A Particular Baud Rate
if(answer==1)
{
    answer = sendATcommand("AT", "OK", 2000); //To Check the Modem

    if(answer==1)
    {
        delay(300);
        sendATcommand("AT+CMGF=1", "OK", 1000); //To Change SMS Sending Mode

    }
}

}

sendATcommand("AT+CFUN=1", "OK", 1000); //To set the phone functionality
answer = sendATcommand("AT+CSTT=\"Tata Docomo\", \"\", \"\", \"\", \"\", \"OK\", 5000); //To Start Task and Set APN
delay(1000);
sendATcommand("AT+CIFSR", "OK", 15000); //To get Local IP Address

}

int8_t sendATcommand(char* ATcommand, char* expected_answer1, unsigned int timeout){

    uint8_t x=0, answer=0;
    char response[200];
    unsigned long previous;

    memset(response, '\0', 200); // Initialize the string

    delay(100);

    while( mySerial.available() > 0) mySerial.read(); // Clean the input buffer

    mySerial.println(ATcommand); // Send the AT command

    x = 0;
    previous = millis();

    // this loop waits for the answer
    do{
        if(mySerial.available() != 0){
            response[x] = mySerial.read();
```

```
    Serial.write(response[x]);  
    x++;  
    // check if the desired answer is in the response of the module  
    if (strstr(response, expected_answer1) != NULL)  
    {  
        answer = 1;  
    }  
    if(x>180)  
        x=0;  
    }  
    // Waits for the answer with time out  
    }  
    while((answer == 0) && ((millis() - previous) < timeout));  
  
    return answer;  
}
```


Arduino Code for Sending/Receiving SMS

```
int8_t answer;
int onModulePin= 2;
char aux_string[30];
char phone_number[]="*****"; // ***** is the number to call
char sms_text[]="Hello World";

void setup() {

    pinMode(onModulePin, OUTPUT);
    Serial.begin(9600);

    Serial.println("Starting...");
    power_on();

    delay(3000);

    Serial.println("Connecting to the network...");

    while( (sendATcommand("AT+CREG?", "+CREG: 0,1", 500) ||
            sendATcommand("AT+CREG?", "+CREG: 0,5", 500)) == 0 );

    Serial.print("Setting SMS mode...");
    sendATcommand("AT+CMGF=1", "OK", 1000); // sets the SMS mode to text
    Serial.println("Sending SMS");

    sprintf(aux_string, "AT+CMGS=\"%s\"", phone_number); //To send the sms
    answer = sendATcommand(aux_string, ">", 2000); // send the SMS number
```

```
if (answer == 1)
{
    Serial.println(sms_text);
    Serial.write(0x1A);
    answer = sendATcommand("", "OK", 20000);
    if (answer == 1)
    {
        Serial.print("Sent ");
    }
    else
    {
        Serial.print("error ");
    }
}
else
{
    Serial.print("error ");
    Serial.println(answer, DEC);
}

}

void loop() {

}

void power_on() {

    uint8_t answer=0;

    // checks if the module is started
    answer = sendATcommand("AT", "OK", 2000);
    if (answer == 0)
    {
        // power on pulse
        digitalWrite(onModulePin,HIGH);
        delay(3000);
        digitalWrite(onModulePin,LOW);

        // waits for an answer from the module
        while(answer == 0){ // Send AT every two seconds and wait for the answer
```

```
        answer = sendATcommand("AT", "OK", 2000);
    }
}

int8_t sendATcommand(char* ATcommand, char* expected_answer, unsigned int timeout){

uint8_t x=0,  answer=0;
char response[100];
unsigned long previous;

memset(response, '\0', 100);    // Initialize the string

delay(100);

while( Serial.available() > 0) Serial.read();    // Clean the input buffer

Serial.println(ATcommand);    // Send the AT command

x = 0;
previous = millis();

// this loop waits for the answer
do{
    // if there are data in the UART input buffer, reads it and checks for the answer
    if(Serial.available() != 0){
        response[x] = Serial.read();
        x++;
        // check if the desired answer is in the response of the module
        if (strstr(response, expected_answer) != NULL)
        {
            answer = 1;
        }
    }
    // Waits for the answer with time out
}while((answer == 0) && ((millis() - previous) < timeout));

return answer;
}
```

Arduino Power Saving Code

```
int8_t answer;
int onModulePin= 2;
char aux_string[30];
char phone_number[]="*****"; // ***** is the number to call
char sms_text[]="Hello World";

void setup() {

    pinMode(onModulePin, OUTPUT);
    Serial.begin(9600);

    Serial.println("Starting...");
    power_on();

    delay(3000);

    Serial.println("Connecting to the network...");

    while( (sendATcommand("AT+CREG?", "+CREG: 0,1", 500) ||
            sendATcommand("AT+CREG?", "+CREG: 0,5", 500)) == 0 );//For Network Registration

    Serial.print("Setting SMS mode...");
    sendATcommand("AT+CMGF=1", "OK", 1000);// sets the SMS mode to text
    Serial.println("Sending SMS");

    sprintf(aux_string,"AT+CMGS=\"\n%s\n\"", phone_number); //To send the sms
    answer = sendATcommand(aux_string, ">", 2000); // send the SMS number

    if (answer == 1)
    {
        Serial.println(sms_text);
        Serial.write(0x1A);
        answer = sendATcommand("", "OK", 20000);
        if (answer == 1)
        {
            Serial.print("Sent ");
        }
        else
        {
            -
        }
    }
}
```

```
        {
            Serial.print("error ");
        }
    }

    power_off();

}

void loop() {

}

void power_on() {

    uint8_t answer=0;

    // checks if the module is started
    answer = sendATcommand("AT", "OK", 2000);
    if (answer == 0)
    {

        // power on pulse
        digitalWrite(onModulePin,HIGH);
        delay(3000);
        digitalWrite(onModulePin,LOW);

        // waits for an answer from the module
        while(answer == 0){        // Send AT every two seconds and wait for the answer
            answer = sendATcommand("AT", "OK", 2000);
        }
    }

}
```

```
void power_off(){

    digitalWrite(onModulePin,HIGH);
    delay(3000);
    digitalWrite(onModulePin,LOW);

}

int8_t sendATcommand(char* ATcommand, char* expected_answer, unsigned int timeout){

    uint8_t x=0,  answer=0;
    char response[100];
    unsigned long previous;

    memset(response, '\0', 100);    // Initialize the string

    delay(100);

    while( Serial.available() > 0) Serial.read();    // Clean the input buffer

    Serial.println(ATcommand);    // Send the AT command

    x = 0;
    previous = millis();

    // this loop waits for the answer
    do{
        // if there are data in the UART input buffer, reads it and checks for the answer
        if(Serial.available() != 0){
            response[x] = Serial.read();
            x++;
            // check if the desired answer is in the response of the module
        }
    }
    while( (millis() - previous) < timeout);
}
```

```
        if (strstr(response, expected_answer) != NULL)
        {
            answer = 1;
        }
    }
    // Waits for the answer with time out
}while((answer == 0) && ((millis() - previous) < timeout));

return answer;
}
```

12. Documents