

# MANIFOLD LEARNING

## DISTANCE PRESERVATION

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Master Informatique

Parcours MALIA

# Plan

1. Metrics
2. MDS
3. Sammon's nonlinear mapping
4. Isomap

## METRICS

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## Definition (distance or metric)

A distance over the set  $\mathcal{Y}$  is an application  $d : \mathcal{Y} \times \mathcal{Y} \mapsto \mathbb{R}$  satisfying the following properties ( $x, y, z \in \mathcal{Y}$ )

$$d(x, y) \geq 0 \quad (\text{positive definite})$$

$$d(x, y) = 0 \text{ iff } x = y \quad (\text{identity})$$

$$d(x, y) = d(y, x) \quad (\text{symmetry})$$

$$d(x, y) \leq d(x, z) + d(z, y) \quad (\text{triangle inequality})$$

Over  $\mathbb{R}^D$ , the most usual ones are derived from Minkowski (or  $L_p$ ) norms (see Lab x001 of PC4DS).

## Definition (similarity)

A similarity over the set  $\mathcal{Y}$  is an application  $s : \mathcal{Y} \times \mathcal{Y} \mapsto \mathbb{R}$  satisfying the following property ( $x, y \in \mathcal{Y}$ )

$$s(x, y) \leq s(x, x)$$

A way to convert a similarity  $s$  into a distance  $d$  is by setting

$$d(x, y) = (s(x, x) + s(y, y) - 2s(x, y))^2$$

MDS



# Multidimensional Scaling (MDS)

- Not a single method but a family of methods
- Aim: construct a configuration of points into a target metric (e.g. euclidean) space from interpoint distances
- Metric MDS : Young and Householder (1938), Torgerson (1952), Nonmetric MDS: Shepard (1962), Kruskal (1964)
- Several application on human sciences

[illegible]

# Classical metric multidimensional scaling

Modèle :  $y = Wx$

- $y \in \mathbb{R}^D$  observed
- $x \in \mathbb{R}^s$  latent (unobserved)
- $W$  unknown  $D \times s$  matrix  $W$  such that  $W^T W = I$
- Call  $Y = [y_1, \dots, y_i, \dots, y_N]$  the (coordinates) data matrix ( $D \times N$  constructed by concatenation of  $y_i$ 's)

Definition (Gramm's matrix)

$$S = Y^T Y = X^T X$$



# Spectral decomposition of Gramm matrix

Since  $\mathbf{S}$  is a  $N \times N$  square symmetric matrix, we have (through the SVD of  $\mathbf{Y}$ )

$$\begin{aligned}\mathbf{S} &= \mathbf{U} \mathbf{\Lambda} \mathbf{U}^T \\ &= (\mathbf{U} \mathbf{\Lambda}^{1/2}) (\mathbf{\Lambda}^{1/2} \mathbf{U}^T) \\ &= (\mathbf{\Lambda}^{1/2} \mathbf{U}^T)^T (\mathbf{\Lambda}^{1/2} \mathbf{U}^T)\end{aligned}$$

where  $\mathbf{U}$  is a  $N \times N$  orthonormal matrix and  $\mathbf{\Lambda}$  is a diagonal matrix with the eigenvalues arranged in decreasing order.

Then, the configuration set of points is

$$\check{\mathbf{X}} = \mathbf{I}_{s \times N} \mathbf{\Lambda}^{1/2} \mathbf{U}^T$$

# If coordinates are not available

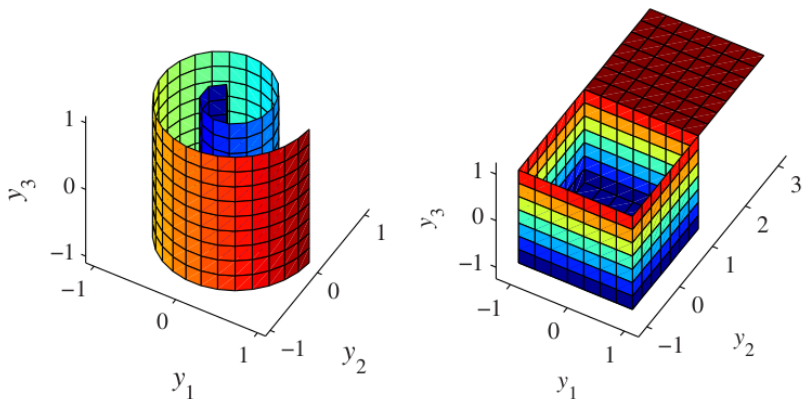
- When coordinates are available: equivalence between from MDS & PCA
- If they are not, MDS can still be used from distance matrix  $\mathbf{D}$  where the general term is  $d(y_i, y_j)^2$
- Then, we obtain  $\mathbf{S}$  from  $\mathbf{D}$  using

$$\mathbf{S} = -\frac{1}{2} \left\{ \mathbf{D} - \frac{1}{N} \mathbf{D} \mathbf{1}_N \mathbf{1}_N^T - \frac{1}{N} \mathbf{1}_N \mathbf{1}_N^T \mathbf{D} + \frac{1}{N^2} \mathbf{1}_N \mathbf{1}_N^T \mathbf{D} \mathbf{1}_N \mathbf{1}_N^T \right\}$$

# The MDS algo

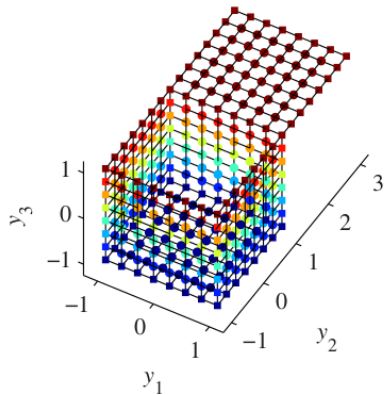
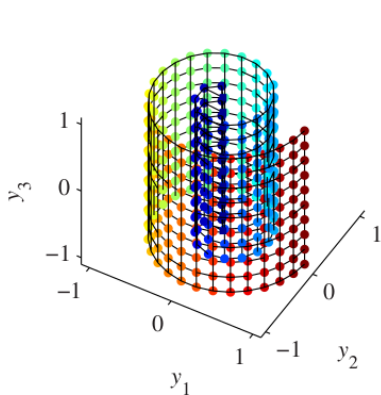
1. If available data consists of vectors gathered in  $\mathbf{Y}$ , then center them, compute the pairwise scalar products  $\mathbf{S} = \mathbf{Y}^T \mathbf{Y}$ , and go to step 3.
2. If available data consists of pairwise Euclidean distance, transform them into scalar products :
  - Square the distances and build  $\mathbf{D}$
  - Perform the double centering of  $\mathbf{D}$ , this yields  $\mathbf{S}$
3. Compute the eigenvalue decomposition  $\mathbf{S} = \mathbf{U} \mathbf{\Lambda} \mathbf{U}^T$
4. A  $s$ -dimensional representation is obtained by computing the product  $\check{\mathbf{X}} = \mathbf{I}_{s \times N} \mathbf{\Lambda}^{1/2} \mathbf{U}^T$

# Two benchmark manifolds

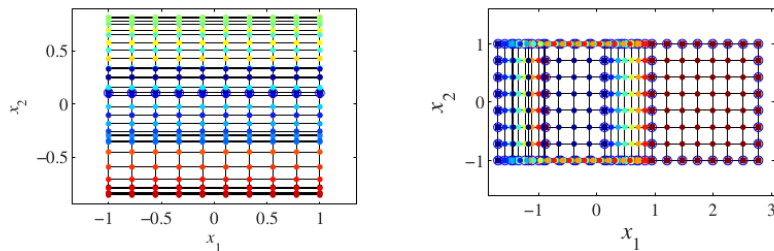


**Fig. 1.3.** Two benchmark manifold: the ‘Swiss roll’ and the ‘open box’.

# Sampled versions



# MDS-based projection on the plan



**Fig. 4.2.** Two-dimensional embeddings of the “Swiss roll” and “open box” data sets (Fig. [1.4](#)), found by metric MDS.

# Metric & nonparametric MDS

Metric MDS : preserve distances (instead of  $\langle ., . \rangle$ )

Stress function (used as objective function)

$$E_{\text{mMDS}} = \frac{1}{2} \sum_{i,j=1}^N w_{i,j} (d_y(i, j) - d_x(i, j))^2$$

Nonparametric MDS : introduce disparities

$$E_{\text{nMDS}} = \sqrt{\frac{\sum_{i,j=1}^N w_{i,j} |f(\delta_{i,j}) - d_x(i, j)|}{c}}$$

## SAMMON'S NONLINEAR MAPPING

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# Stress function

- Related to metric MDS, looks for configuration minimizing

$$E_{\text{NLM}} = \frac{1}{c} \sum_{i=1, i < j}^N \frac{(d_y(i, j) - d_x(i, j))^2}{d_y(i, j)}$$

where  $c = \sum_{i=1, i < j}^N d_y(i, j)$  and  $d_x$  will be Euclidean.

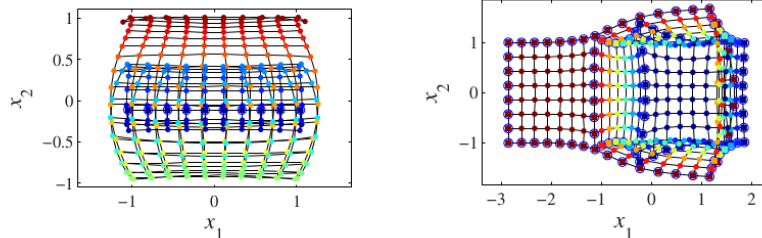
- Optimization problem solved with quasi-Newton optimization
- Initialize with MDS, then use the update rule ( $\alpha$  is call the magic number)

$$x_k(i) \leftarrow x_k(i) - \alpha \frac{\frac{\partial E_{\text{NLM}}}{\partial x_k(i)}}{\left| \frac{\partial^2 E_{\text{NLM}}}{\partial x_k(i)^2} \right|}$$

# MDS-based projection on the plan

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1. Compute all pairwise distances  $d_{\mathbf{y}}(i, j)$  in the  $D$ -dimensional data space.
  2. Initialize the  $P$ -dimensional coordinates of all points  $\mathbf{x}(i)$ , either randomly or on the hyperplane spanned by the first  $P$  principal components of the data set (after PCA or MDS).
  3. Compute the right-hand side of Eq. (4.68) for the coordinates of all points  $\mathbf{x}(i)$ .
  4. Update the coordinates of all points  $\mathbf{x}(i)$ .
  5. Return to step 3 until the value of the stress function no longer decreases.
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# MDS-based projection on the plan



**Fig. 4.4.** Two-dimensional embeddings of the ‘Swiss roll’ and ‘open box’ data sets (Fig. 1.4), found by Sammon’s NLM.

ISOMAP



# How to de generalize PCA or MDS?

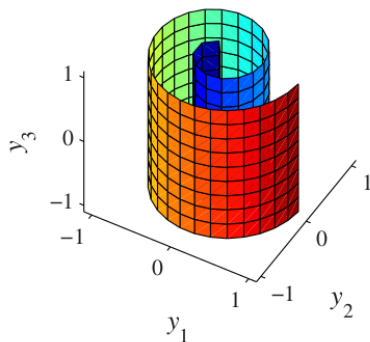
## Aim

- Avoid globally *linearity, euclidean distances* or *normality*
- + Find a new representation where linearity is a reasonable assumption
- + a fully non parametric approach is desireable

## 3 approaches to be studied (partially) based on graphs

- ISOMAP : extension of MDS to geodesic
- LLE (Local linear embeddings ) : conserve local geometry
- Laplacian Eigenmaps : based on spectral techniques

# Global distance and manifolds identified by uns

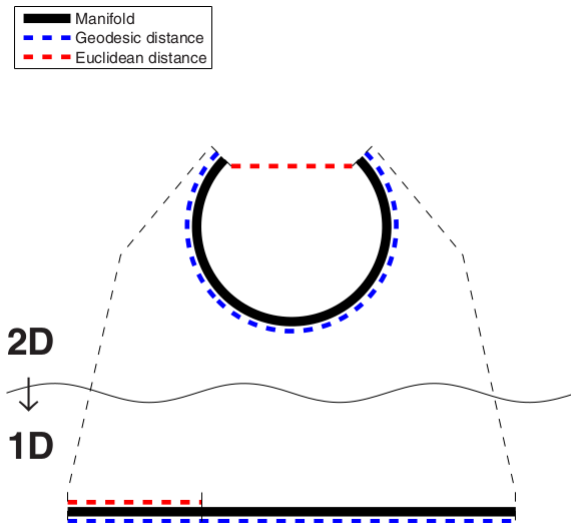


Recall:

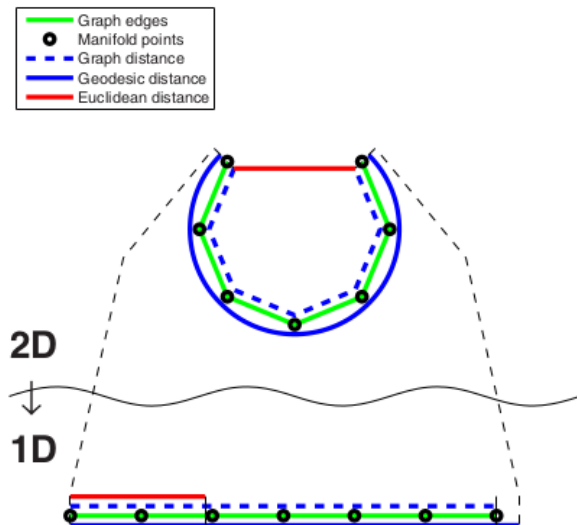
- we need a more general notion than euclidean distance
- global vs local

A *manifold* is a space regular enough so that **LOCALLY** has all the properties of a linear space. Its *dimension* can be view as as the number of free coordinates needed to navigate along the manifold.

# Geodesic distance



# Graph distance





**KEY IDEA** perform a non metric MDS only replacing the euclidean by the geodesic distance

1. Build a graph with either the  $K$ -rule or the  $\epsilon$ -rule.
2. Weight the graph by labeling each edge with its Euclidean length.
3. Compute all pairwise graph distances with Dijkstra's algorithm, square them, and store them in matrix  $\mathbf{D}$ .
4. Convert the matrix of distances  $\mathbf{D}$  into a Gram matrix  $\mathbf{S}$  by double centering.
5. Once the Gram matrix is known, compute its spectral decomposition  $\mathbf{S} = \mathbf{U}\mathbf{\Lambda}\mathbf{U}^T$ .
6. A  $P$ -dimensional representation of  $\mathbf{Y}$  is obtained by computing the product  $\hat{\mathbf{X}} = \mathbf{I}_{P \times N} \mathbf{\Lambda}^{1/2} \mathbf{U}^T$ .

# Isomap on benchmark

