Numerical Solution of PDEs Using the Finite Element Method

EXERCISE 5: LOCAL REFINEMENT, HANGING NODES AND THE CONSTRAINTMATRIX

Jean-Paul Pelteret (jean-paul.pelteret@fau.de)
Luca Heltai (luca.heltai@sissa.it)

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Some useful resources

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https://www.dealii.org/8.5.1/doxygen/deal.II/step_4.html
https://www.dealii.org/8.5.1/doxygen/deal.II/step_5.html
https://www.dealii.org/8.5.1/doxygen/deal.II/namespaceGridGenerator.html
https://www.dealii.org/8.5.1/doxygen/deal.II/namespaceVectorTools.html
https://www.dealii.org/8.5.1/doxygen/deal.II/namespaceDoFTools.html
https://www.dealii.org/8.5.1/doxygen/deal.II/group__constraints.html
https://www.dealii.org/8.5.1/doxygen/deal.II/step_49.html
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- 1. Using step-5 (or your previously modified version of step-3) as a base:
 - (a) Solve Laplace's equation

$$-\Delta u(\mathbf{x}) = 0$$
 in Ω , with $u(\mathbf{x}) = 0$ on $\partial \Omega_1$, and $u(\mathbf{x}) = 1$ on $\partial \Omega_2$

on an L-shaped domain with length and width of dimension 1. Here, Ω_2 denotes one of the end-edges of the L, and $\partial\Omega_1 = \partial\Omega \setminus \partial\Omega_2$.

- (b) Starting from a coarse grid, perform successive global refinements to increase the accuracy of the solution and to locate the singularity.
- (c) Now switch from using global refinement to using local refinement in the vicinity of the singularity. To accomplish this, you'll need to build the hanging node constraints.
- (d) Build the Dirichlet boundary directly into a global ConstraintMatrix, along with the existing hanging node constraints. With this change, several parts of your code need to be modified:
 - i. The constraints need to be built in the setup function.

 Tip: You can use the VectorTools::interpolate function here.
 - ii. The ConstraintMatrix should be used to distribute local cell and vector contributions to their global counterparts.
 - iii. The constraints must be distributed to the solution.

2. Additional tasks

- (a) Following (c), what happens if you "forget" to distribute the (hanging node) constraints after solving the linear system?
- (b) Instead of using the VectorTools::interpolate function, construct the Dirichlet contributions to the ConstraintMatrix manually.
 - Tip: There are two ways to accomplish this: (1) Use the tools provided in the DoFTools namespace, or (2) loop over cell faces and interrogate them for global DoFs that have support there.
- (c) Experiment with some of the other grids in the GridGenerator namespace, such as GridGenerator::hyper_cross and GridGenerator::cheese, or create your own by using some of the grid modification tools discussed in step-49. In each case, find ways to efficiently increase the cell density in the location of singularities.

(d) Using your existing code, replicate the study performed in step-5. Note that the governing equation has changed slightly. Can you further improve the accuracy of the result in step-5 using Manifolds?

Tip: Look to the discussion "A better mesh" in the "Possibilities for extensions" section of step-6.