



Solving Poisson's equation

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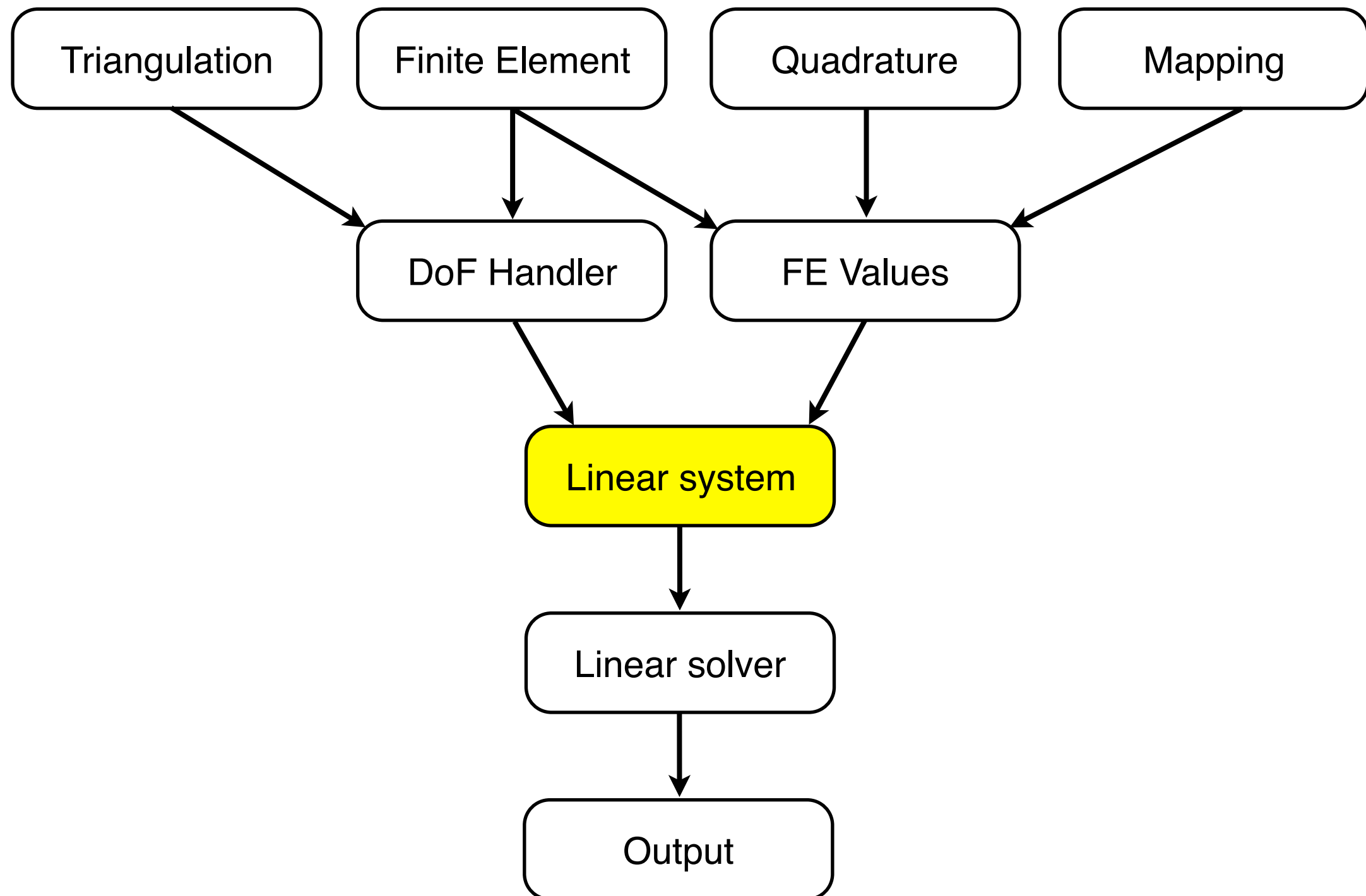
Aims for this module

- First introduction into assembly of sparse linear systems
- Translation of weak form to assembly loops
- Applying boundary conditions
- Using linear solvers
- Post-processing and visualisation

Reference material

- Tutorials
 - Step-3
https://dealii.org/8.5.1/doxygen/deal.II/step_3.html
- Documentation
 - https://www.dealii.org/developer/doxygen/deal.II/group_FE_vs_Mapping_vs_FEValues.html
 - https://www.dealii.org/developer/doxygen/deal.II/group_UpdateFlags.html

Structure of a prototypical FE problem



Sparse linear systems

- Minimise data storage
 - Evaluate grid connectivity
- Functions to help set up
 - Connectivity
 - Constraints
- Minimal access times
 - Direct manipulation of (non-zero) entries
 - Matrix-vector operations
 - Skip over zero-entries
- Types
 - Unity (monolithic, contiguous)
 - Block sparse structures
- Sub-organisation (e.g. component-wise)

$$[K] \{d\} = \{F\}$$

$$\begin{bmatrix} K_{11} & K_{12} \\ K_{21} & K_{22} \end{bmatrix} \begin{Bmatrix} d_1 \\ d_2 \end{Bmatrix} = \begin{Bmatrix} F_1 \\ F_2 \end{Bmatrix}$$

$$\begin{aligned} & \cdot \left(K_{11} - K_{12} K_{22}^{-1} K_{21} \right) d_1 \\ & \quad = F_1 - K_{12} K_{22}^{-1} F_2 \\ & \cdot d_2 = K_{22}^{-1} (F_2 - K_{21} d_1) \end{aligned}$$

Constraints on sparse linear systems

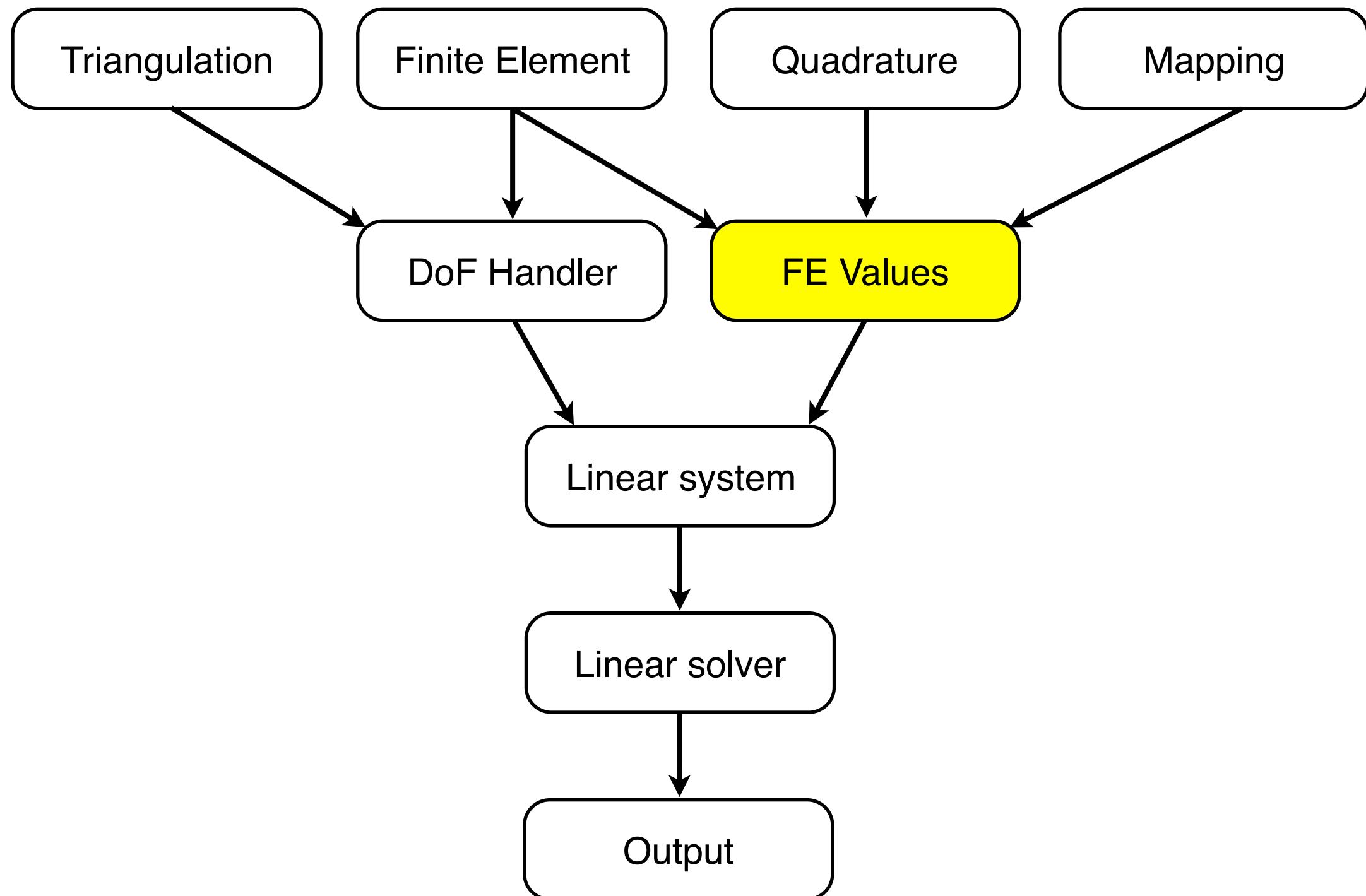
- Strong Dirichlet boundary conditions
 - Apply user-defined spatially-dependent functions to specific boundaries
 - Can restrict to components of a multi-dimensional field
 - Limited to fields with support points on faces
 - Possible to scale system matrix/RHS vector accordingly
 - Better matrix conditioning
- Neumann boundary conditions
 - Implementation dependent
- Other constraints need special consideration
 - Periodic boundary conditions
 - Refinement with hanging nodes
 - Some time-dependent formulations

$$[K] \{d\} = \{F\}$$

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Structure of a prototypical FE problem



Integration on a cell: the FEValues class

$$K = \int_{\Omega} \nabla \delta \phi \cdot k \nabla \phi dV$$

$$\approx \delta \phi^I \sum_h \left(\int_{\Omega^h} \nabla N^I \cdot k \nabla N^J dV^h \right) \phi^J$$

$$\approx \delta \phi^I \sum_h \underbrace{\left(\sum_q \nabla N^I (\mathbf{x}_q) \cdot k_q \nabla N^J (\mathbf{x}_q) w_q \right)}_{K_{IJ} = (\nabla \phi^I, k \nabla \phi^J)} \phi^J$$

$$\approx \delta \phi^I \sum_h \underbrace{\left(\sum_q [J_{\square}^h]_q^{-1} \nabla_{\square} N^I (\mathbf{x}_q) \cdot k_q [J_{\square}^h]_q^{-1} \nabla_{\square} N^J (\mathbf{x}_q) |\det J_q| w_q \right)}_{K_{IJ}} \phi^J$$

$$J_{\square}^h = \frac{\partial \mathbf{X}^{\xi}}{\partial \mathbf{X}}$$

Integration on a cell: the FEValues class

- Object that helps perform integration
- Combines information of:

- Cell geometry
- Finite-element system
- Quadrature rule

- Mappings

- Can provide:

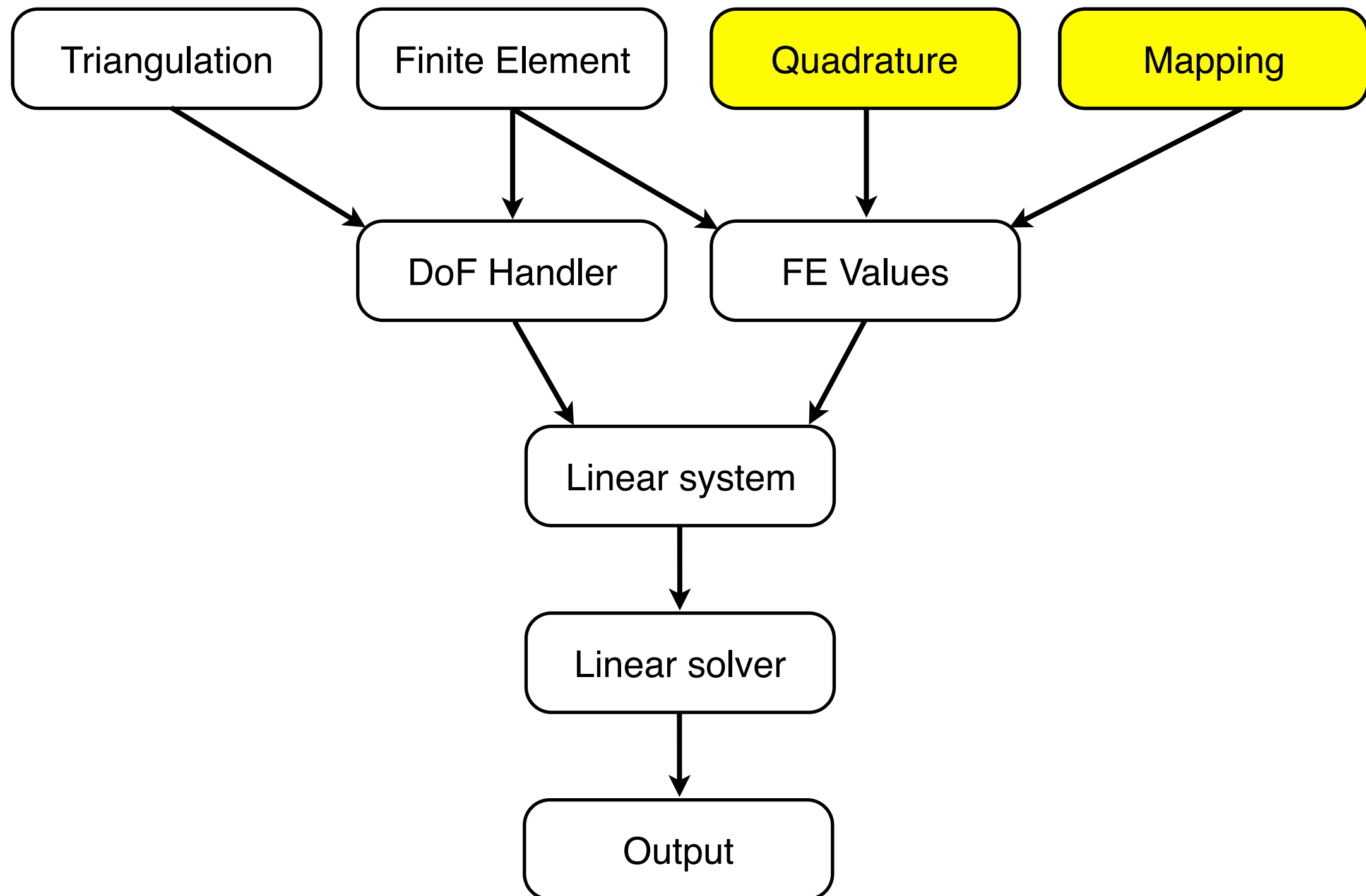
- Shape function data
- Quadrature weights and mapping jacobian at a point
- Normal on face surface
- Covariant/contravariant basis vectors

$$K_{IJ} = \sum_h \left(\sum_q \left[J_{\square}^h \right]_q^{-1} \nabla_{\square} N^I(\mathbf{x}_q) \cdot k_q \left[J_{\square}^h \right]_q^{-1} \nabla_{\square} N^J(\mathbf{x}_q) \mid \det J_q \mid w_q \right)$$

```
cell_matrix(I,J) += k
    * fe_values.shape_grad (I, q_point)
    * fe_values.shape_grad (J, q_point)
    * fe_values.JxW (q_point);
```

- More ways it can help:
 - Object to extract shape function data for individual fields
 - Natural expressions when coding
- Low level optimisations

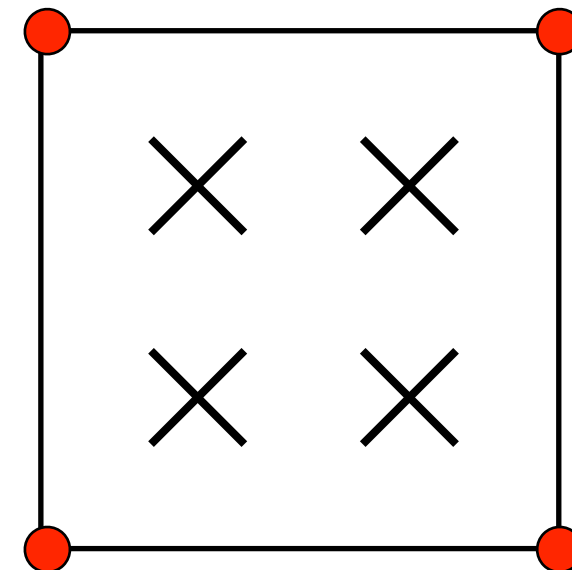
Structure of a prototypical FE problem



Integration on a cell: the Quadrature classes

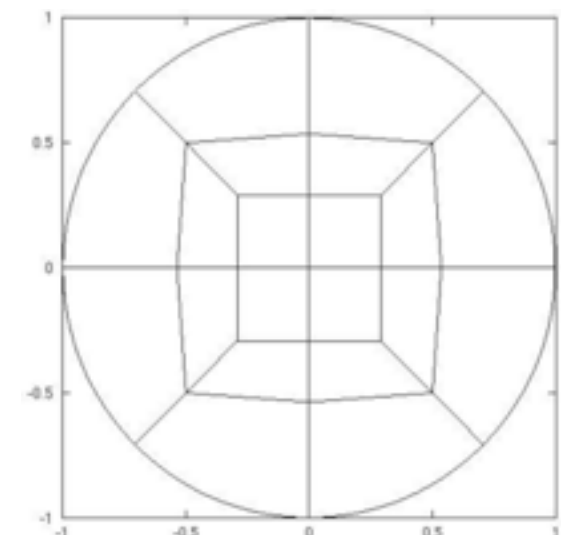
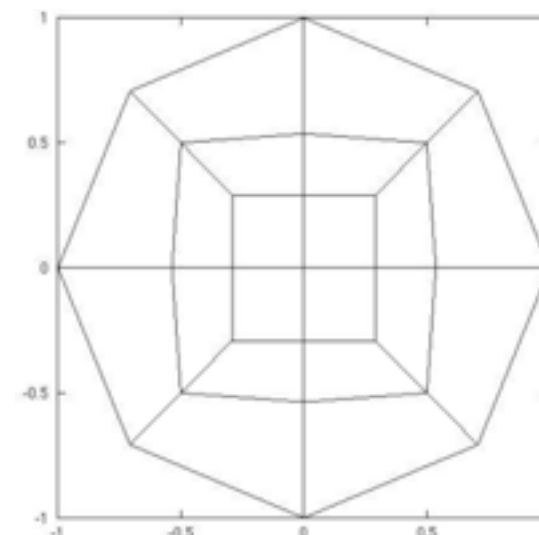
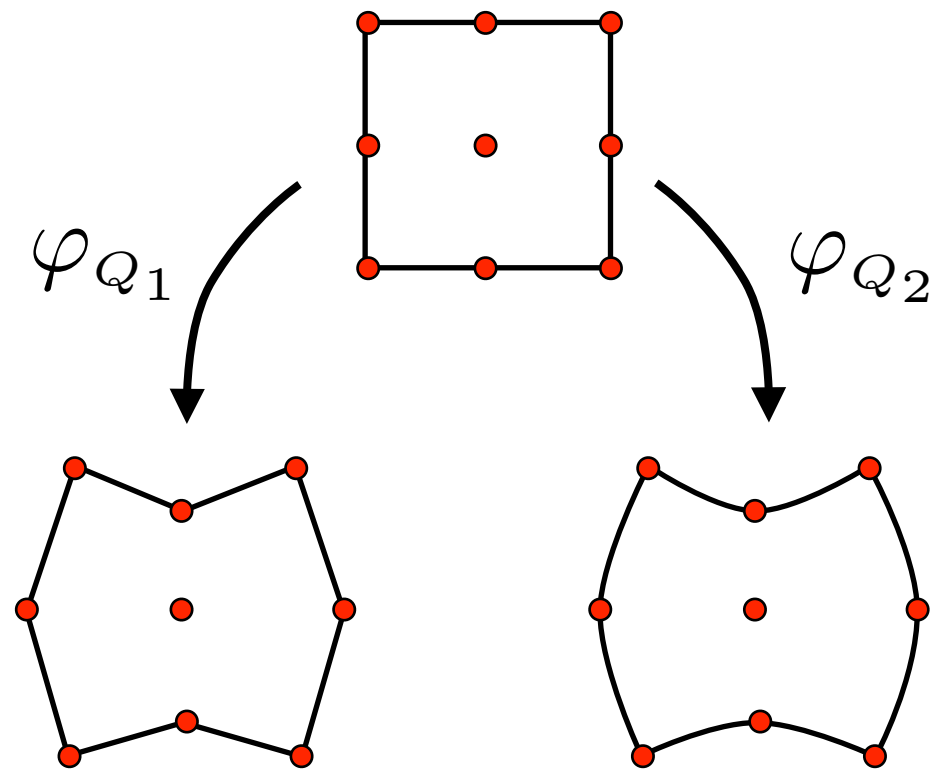
- n-Order Gauss quadrature
- Other rules
 - Gauss Lobatto
 - Simpson
 - Trapezoidal
 - Midpoint
 - A few others
- Anisotropic
 - Tensor product

FE_Q<2>(1)

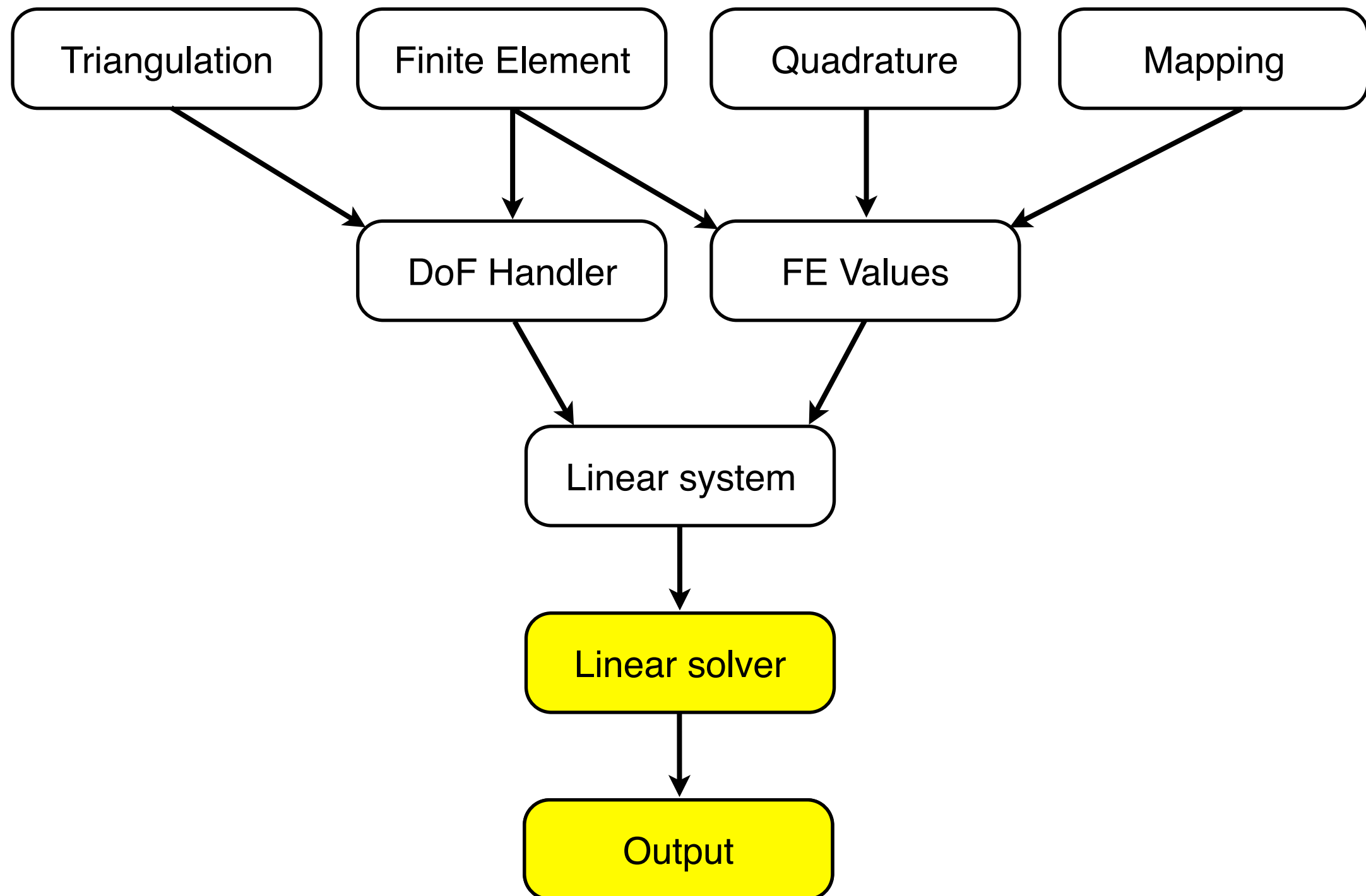


Integration on a cell: the Mapping classes

- n-order mappings
 - Increase accuracy of:
 - Integration schemes
 - Surface basis vectors
- Lagrangian / Eulerian
 - Latter useful for fluid and contact problems, data visualisation
- Boundary and interior manifolds



Structure of a prototypical FE problem



Solving Poisson's equation

- Demonstration: Step-3
https://www.dealii.org/8.5.1/doxygen/deal.II/step_3.html
<http://www.math.colostate.edu/~bangerth/videos.676.10.html>
- Key points
 - Local assembly + quadrature rules
 - Distribution of local contributions to the global linear system
 - Application of boundary conditions
 - Solving a linear system
 - Output for visualisation

