

CS-E4740 - Federated Learning

FL Design Principle

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Playlist



Glossary



Course Site



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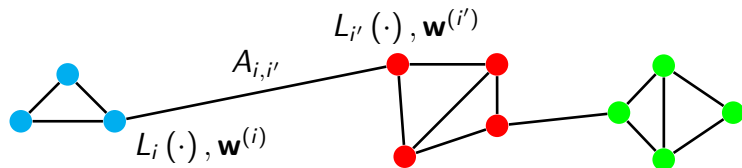
Formulating FL as Optimization

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An FL Network



- ▶ FL network consisting of devices $i=1, \dots, n$.
- ▶ Some i, i' connected by an edge with weight $A_{i,i'} > 0$.
- ▶ Device i learns model params. $\mathbf{w}^{(i)} \in \mathbb{R}^d$.
- ▶ Usefulness of $\mathbf{w}^{(i)}$ measured by some local loss, e.g.,

$$L_i(\mathbf{w}^{(i)}) := \frac{1}{m_i} \sum_{r=1}^{m_i} \left(y^{(i,r)} - (\mathbf{w}^{(i)})^T \mathbf{x}^{(i,r)} \right)^2.$$

FL via Regularization

- ▶ Each node carries a linear model $h^{(\mathbf{w}^{(i)})}(\mathbf{x}) := \mathbf{x}^T \mathbf{w}^{(i)}$.
- ▶ Each node carries m_i labelled data points.
- ▶ Node-wise ML fails if $m_i \ll d$ (overfitting).

Idea:

Use the neighbours $\mathcal{N}^{(i)} := \{i' : \{i, i'\} \in \mathcal{E}\}$ to regularize!

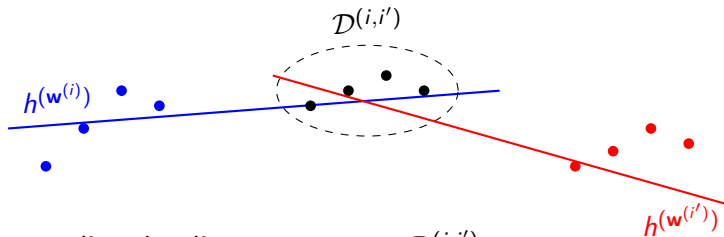
FL via Regularization (ctd.)

As for basic ML, regularization can be done either via

- ▶ **Data augmentation** using data from the neighbours.
- ▶ **Prune local models** by requiring them to agree across edges.
- ▶ **Add a penalty term** to the local loss function.

Building a Penalty Across Edges

- ▶ Consider two nodes i, i' with local datasets $\mathcal{D}^{(i)}, \mathcal{D}^{(i')}$.
- ▶ Assume there is a non-empty overlap $\mathcal{D}^{(i)} \cap \mathcal{D}^{(i')}$.



We penalize the disagreement on $\mathcal{D}(i, i')$:

$$\begin{aligned} \sum_{\mathbf{x} \in \mathcal{D}(i, i')} (h(\mathbf{w}^{(i)})(\mathbf{x}) - h(\mathbf{w}^{(i')})(\mathbf{x}))^2 &= \sum_{\mathbf{x} \in \mathcal{D}(i, i')} (\mathbf{x}^T \mathbf{w}^{(i)} - \mathbf{x}^T \mathbf{w}^{(i')})^2 \\ &= (\mathbf{w}^{(i)} - \mathbf{w}^{(i')})^T \left[\sum_{\mathbf{x} \in \mathcal{D}(i, i')} \mathbf{x}^T \mathbf{x} \right] (\mathbf{w}^{(i)} - \mathbf{w}^{(i')}). \end{aligned}$$

Generalized TV Minimization (GTVMin)

Learn model params. $\widehat{\mathbf{w}}^{(i)}$ by balancing local loss and GTV

$$\min_{\mathbf{w}^{(1)}, \dots, \mathbf{w}^{(n)} \in \mathbb{R}^d} \sum_{i=1}^n \left[L_i(\mathbf{w}^{(i)}) + \alpha \sum_{\{i, i'\} \in \mathcal{E}} A_{i, i'} \phi(\mathbf{w}^{(i)} - \mathbf{w}^{(i')}) \right]$$

- ▶ Penalty function $\phi(\mathbf{u})$ is a design choice.
- ▶ Previous slide used $\phi(\mathbf{u}) = \mathbf{u}^T \mathbf{Q} \mathbf{u}$ with $\mathbf{Q} := \sum_{\mathbf{x} \in \mathcal{D}(i, i')} \mathbf{x} \mathbf{x}^T$.
- ▶ Our focus is on the choice $\phi(\mathbf{u}) := \|\mathbf{u}\|_2^2$.
- ▶ Another popular choice is $\phi(\mathbf{u}) := \|\mathbf{u}\|$.¹

¹Y. SarcheshmehPour, et.al, "Clustered Federated Learning via Generalized Total Variation Minimization," in IEEE Trans. Sig. Proc, 2023, doi: 10.1109/TSP.2023.3322848.

Model-Agnostic GTVMin

Replacing $\phi(\mathbf{w}^{(i)} - \mathbf{w}^{(i')})$ with the disagreement measure

$$D(h^{(i)}, h^{(i')}) := \sum_{\mathbf{x} \in \mathcal{D}^{(i, i')}} (h^{(i)}(\mathbf{x}) - h^{(i')}(\mathbf{x}))^2$$

yields a model-agnostic generalization of GTVMin

$$\min_{\substack{h^{(i)} \in \mathcal{H}^{(i)} \\ i \in \mathcal{V}}} \sum_{i \in \mathcal{V}} \left[L_i(h^{(i)}) + \alpha \sum_{\{i, i'\} \in \mathcal{E}} A_{i, i'} D(h^{(i)}, h^{(i')}) \right].$$

This allows for VERY heterogeneous FL networks, e.g., $\mathcal{H}^{(1)} = \text{lin.model}$, $\mathcal{H}^{(2)} = \text{LLM}$, $\mathcal{H}^{(3)} = \text{decision tree}$.

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Computational Aspects

$$\min_{\mathbf{w}^{(1)}, \dots, \mathbf{w}^{(n)} \in \mathbb{R}^d} \sum_{i=1}^n \left[L_i(\mathbf{w}^{(i)}) + \alpha \sum_{\{i, i'\} \in \mathcal{E}} A_{i, i'} \phi(\mathbf{w}^{(i)} - \mathbf{w}^{(i')}) \right]$$

- ▶ How can we solve it efficiently over an FL network?
- ▶ How much compute/comm. is needed at least?
- ▶ What is the effect of different choices for the edges \mathcal{E} , loss funcs. $L_i(\cdot)$, and GTV penalty ϕ ?

Computational Aspects - Smooth GTVmin

Consider a GTVMin instance

$$\min_{\mathbf{w}^{(1)}, \dots, \mathbf{w}^{(n)} \in \mathbb{R}^d} \sum_{i=1}^n \left[L_i(\mathbf{w}^{(i)}) + \alpha \sum_{\{i, i'\} \in \mathcal{E}} A_{i, i'} \left\| \mathbf{w}^{(i)} - \mathbf{w}^{(i')} \right\|_2^2 \right]$$

with a smooth (differentiable) $L_i(\cdot)$.

If we use (distributed) gradient descent to solve GTVMin:

- ▶ How many iterations should we run?
- ▶ What is a good choice for the learning rate?
- ▶ How to communicate gradients over comm. links?

Characterizing GTVMin Solutions

- ▶ Consider GTVMin solution $\hat{\mathbf{w}}^{(i)} \in \mathbb{R}^d$, for $i = 1, \dots, n$.
- ▶ We stack them into a long vector

$$\hat{\mathbf{w}} := (\hat{\mathbf{w}}^{(1)}, \dots, \hat{\mathbf{w}}^{(n)})^T \in \mathbb{R}^{dn}.$$

- ▶ We characterize the solutions as a fixed-point of some \mathcal{F} ,

$$\hat{\mathbf{w}} \text{ solves GTVMin} \Leftrightarrow \hat{\mathbf{w}} = \mathcal{F}\hat{\mathbf{w}}$$

- ▶ The operator \mathcal{F} is not unique (design choice!).

Convex and Smooth GTVMin

Consider GTVMin with a smooth and convex $L_i(\cdot)$,

$$\min_{\mathbf{w}^{(1)}, \dots, \mathbf{w}^{(n)} \in \mathbb{R}^d} \sum_{i=1}^n \left[L_i(\mathbf{w}^{(i)}) + \alpha \sum_{\{i, i'\} \in \mathcal{E}} A_{i, i'} \left\| \mathbf{w}^{(i)} - \mathbf{w}^{(i')} \right\|_2^2 \right] \quad (1)$$

$$\hat{\mathbf{w}} \text{ solves (1)} \Leftrightarrow \hat{\mathbf{w}} = \mathcal{F}^{(\eta)} \hat{\mathbf{w}}$$

$\mathcal{F}^{(\eta)}$ maps $\mathbf{u} = (\mathbf{u}^{(1)}, \dots, \mathbf{u}^{(n)})^T$ to $\mathbf{v} = (\mathbf{v}^{(1)}, \dots, \mathbf{v}^{(n)})^T$,

$$\mathbf{v}^{(i)} = \mathbf{u}^{(i)} - \eta \left[\nabla L_i(\mathbf{u}^{(i)}) + 2\alpha \sum_{i' \in \mathcal{N}^{(i)}} A_{i, i'} (\mathbf{u}^{(i)} - \mathbf{u}^{(i')}) \right].$$

Different choices for “step-size” $\eta > 0$ yield different \mathcal{F} .

Fixed-Point Iterations

Q: How to compute a fixed point $\hat{\mathbf{w}}$ of \mathcal{F} ?

A: Start with initial guess $\hat{\mathbf{w}}^{(0)}$ and iterate

$$\hat{\mathbf{w}}^{(k)} = \mathcal{F}\hat{\mathbf{w}}^{(k-1)}, \text{ for } k = 1, 2, \dots$$

If \mathcal{F} is **firmly non-expansive** $\lim_{k \rightarrow \infty} \hat{\mathbf{w}}^{(k)} = \hat{\mathbf{w}}$.

If \mathcal{F} is even **contractive** with constant $\kappa < 1$,

$$\|\hat{\mathbf{w}}^{(k)} - \hat{\mathbf{w}}\|_2 \leq \kappa^k \|\hat{\mathbf{w}}^{(0)} - \hat{\mathbf{w}}\|_2.$$

Gradient Descent as Fixed-Point Iteration

GD for smooth and convex objective function $f(\mathbf{w})$,

$$\mathbf{w}^{(k)} = \mathbf{w}^{(k-1)} - \eta \nabla f(\mathbf{w}^{(k-1)})$$

is a fixed-point iteration with $\mathcal{F}^{(\eta)} : \mathbf{w} \mapsto \mathbf{w} - \eta \nabla f(\mathbf{w})$.

- ▶ In general, $\mathcal{F}^{(\eta)}$ is neither firmly non-exp. nor contractive.
- ▶ Convergence can still be ensured if η is sufficiently small.
- ▶ E.g., using learning rate $\eta_k = 1/k$ for smooth $f(\mathbf{w})$.

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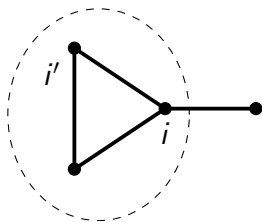
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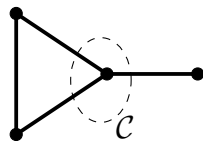
Statistical Aspects

- ▶ GTVMin solution yields model params. $\hat{\mathbf{w}}^{(i)}$, $i = 1, \dots, n$
- ▶ How useful are these model params. ?
- ▶ The local loss $L_i(\hat{\mathbf{w}}^{(i)})$ can be misleading (why?)
- ▶ Better to use aggregate $\sum_{i \in \mathcal{C}^{(i)}} L_i(\hat{\mathbf{w}}^{(i)})$, with cluster

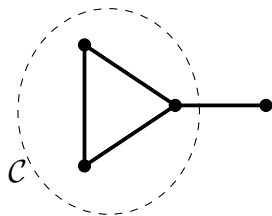


$$\mathcal{C}^{(i)} := \{i' : \hat{\mathbf{w}}^{(i)} \approx \hat{\mathbf{w}}^{(i')}\}.$$

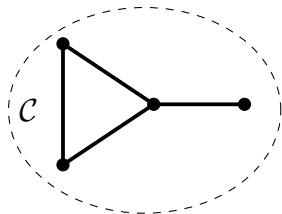
Clustering of GTVMin



small α



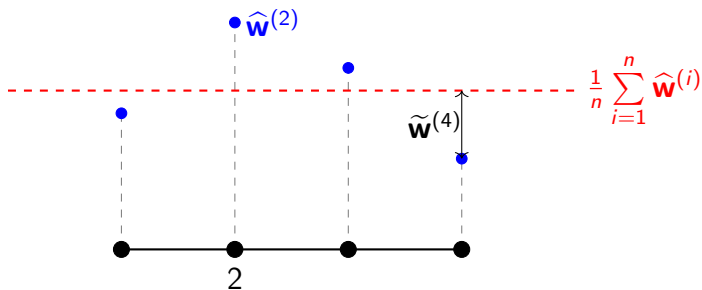
moderate α



large α

Analysis of Clustering - Assumptions

- ▶ Consider a connected FL network \mathcal{G} with $\lambda_2 > 0$.
- ▶ Assume loss funcs. satisfy $\min_{\mathbf{v} \in \mathbb{R}^d} \sum_{i=1}^n L_i(\mathbf{v}) \leq \varepsilon$
- ▶ Use GTVMin to learn local params. $\widehat{\mathbf{w}}^{(i)}$.
- ▶ Define the variation $\widetilde{\mathbf{w}}^{(i)} := \widehat{\mathbf{w}}^{(i)} - \frac{1}{n} \sum_{i=1}^n \widehat{\mathbf{w}}^{(i)}$.



Analysis of Clustering - Upper Bound

The variation $\tilde{\mathbf{w}}^{(i)}$ is upper bounded as

$$\sum_{i=1}^n \|\tilde{\mathbf{w}}^{(i)}\|_2^2 \leq \frac{\varepsilon}{\alpha \lambda_2}.$$

This bound involves the

- ▶ connectivity of FL network (via λ_2),
- ▶ the properties of local loss functions (via ε), and
- ▶ the GTVMin parameter α .

A large $\alpha \lambda_2$ results in nearly identical local params. $\tilde{\mathbf{w}}^{(i)} \approx \mathbf{0}$.

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We next discuss some interpretations of GTVMin

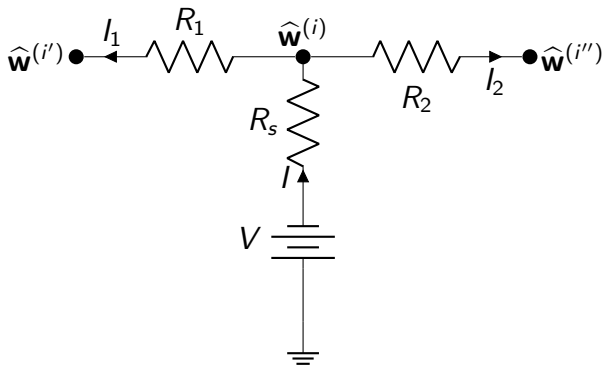
$$\min_{\mathbf{w}^{(1)}, \dots, \mathbf{w}^{(n)} \in \mathbb{R}^d} \sum_{i=1}^n \left[L_i(\mathbf{w}^{(i)}) + \alpha \sum_{\{i, i'\} \in \mathcal{E}} A_{i, i'} \left\| \mathbf{w}^{(i)} - \mathbf{w}^{(i')} \right\|_2^2 \right]$$

for some FL network with weighted undirected graph \mathcal{G} and smooth and convex loss func. $L_i(\mathbf{w}^{(i)})$.

We assume that there exists a solution $\hat{\mathbf{w}}^{(1)}, \dots, \hat{\mathbf{w}}^{(n)}$. (Do we really need to make this assumption?)

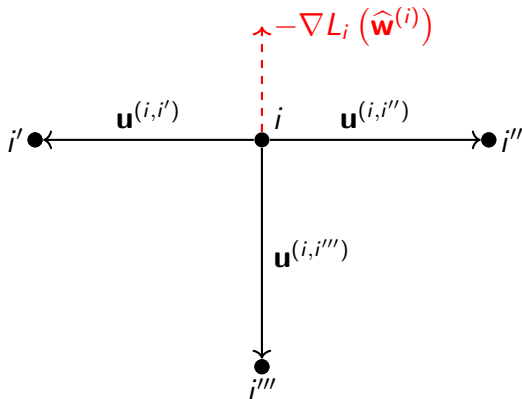
Electronic Circuit

Consider a node i with neighbours $\mathcal{N}^{(i)} = \{i', i''\}$.



$$\underbrace{-\nabla L_i(\hat{\mathbf{w}}^{(i)})}_{\textcolor{red}{I}} = \left[\underbrace{A_{i,i'}(\hat{\mathbf{w}}^{(i)} - \hat{\mathbf{w}}^{(i')})}_{\textcolor{red}{I_1}} + \underbrace{A_{i,i''}(\hat{\mathbf{w}}^{(i)} - \hat{\mathbf{w}}^{(i'')})}_{\textcolor{red}{I_2}} \right]$$

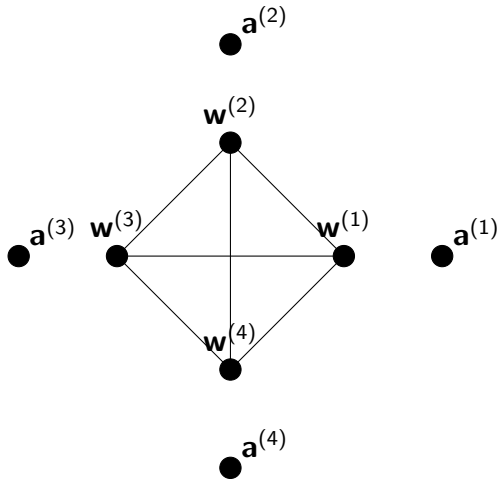
Vector-Valued Flows



Vector-valued flow $\mathbf{u}^{(i,i')} := \nabla \phi(\mathbf{u})|_{\mathbf{u}=\widehat{\mathbf{w}}^{(i)}-\widehat{\mathbf{w}}^{(i')}}.$

Locally Weighted Learning

Generalized Convex Clustering



$$\min_{\mathbf{w}^{(1)}, \dots, \mathbf{w}^{(n)}} \sum_{i=1}^n \left\| \mathbf{w}^{(i)} - \mathbf{a}^{(i)} \right\|_2^2 + \alpha \sum_{i, i' \in \mathcal{V}} \left\| \mathbf{w}^{(i)} - \mathbf{w}^{(i')} \right\|_2.$$

What's Next?

The next module applies optimization methods to solve GTVMin.

We can implement these methods as message passing over the edges of an FL network.

Further Resources

- ▶ **YouTube:** [@alexjung111](#)
- ▶ **LinkedIn:** [Alexander Jung](#)
- ▶ **GitHub:** [alexjungaalto](#)

