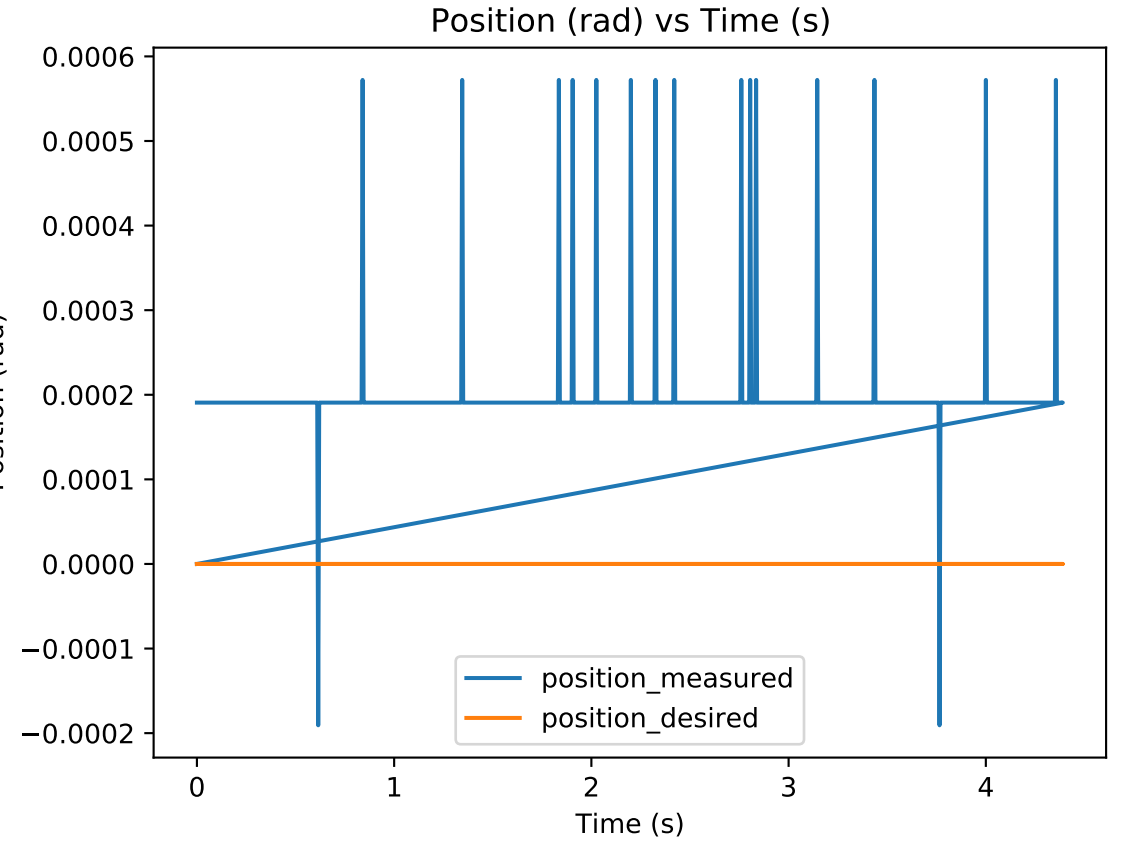
Position (rad) vs Time (s)
0.0006
0.0005
0.0004
0.0003
0.0002
0.0001
0.0000
−0.0001
−0.0002
0
1
2
3
4
Time (s)
position_measured
position_desired