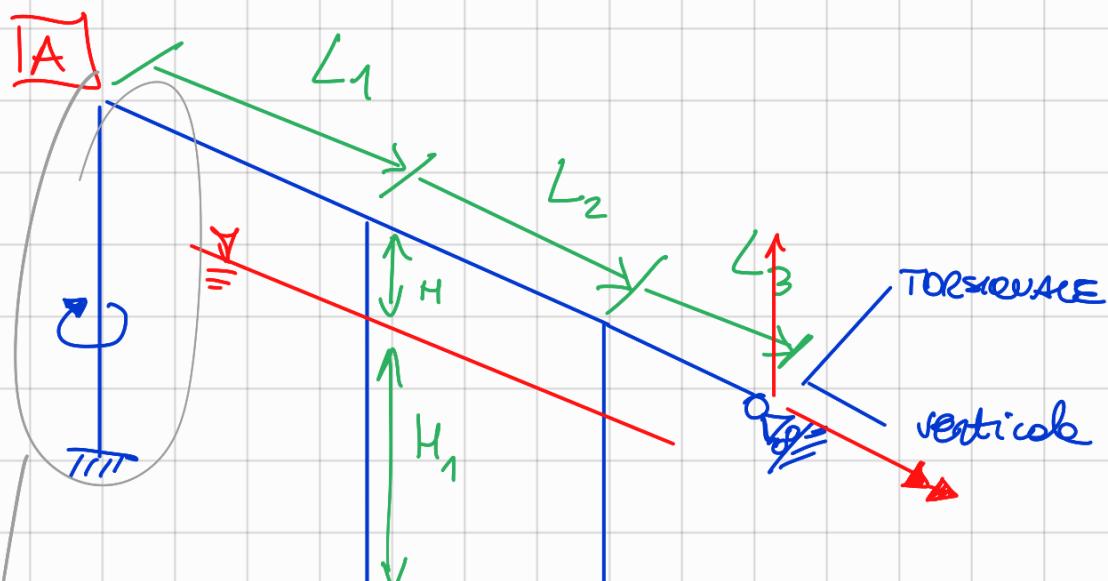
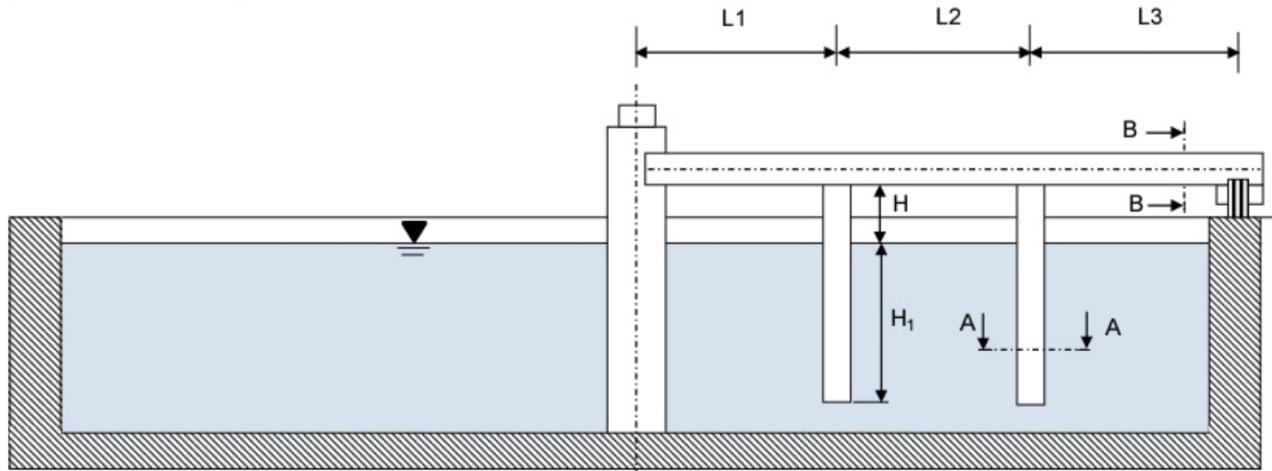


$\frac{\partial z}{\partial t}$

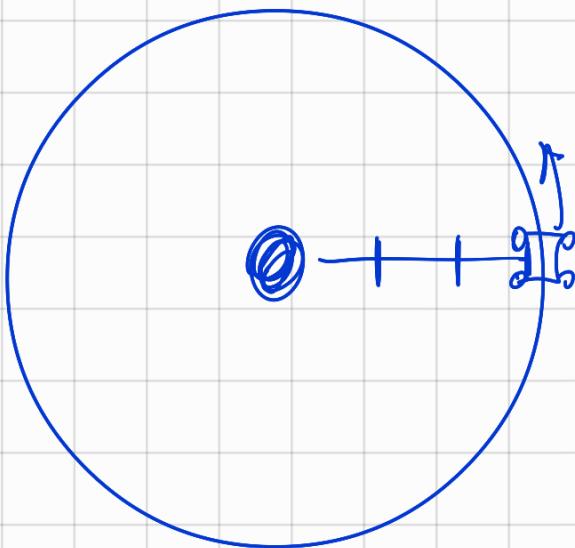
GIP

$$\Delta \theta_{sx} = \frac{M_{z1}}{GIP} l_3 + \frac{M_{z1}}{GIP} l_2 + \frac{M_{z2}}{GIP} l_1$$

$$\Delta \theta_{dx} = \frac{M_{z1}}{GIP} (l_4 + l_5) + \frac{M_{z2}}{GIP} l_6$$



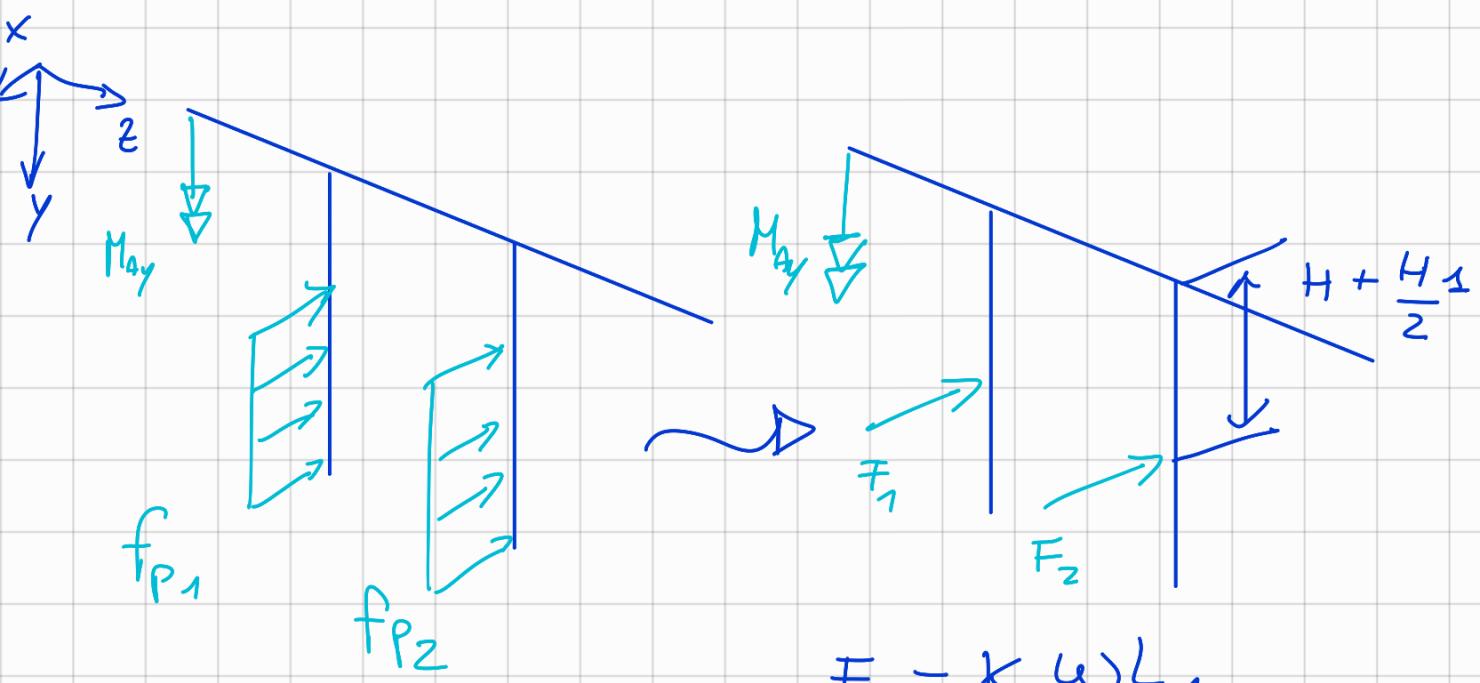
SOTTOPOSTO
ad AZIONE
TORSIONALE
COSTANTE



① AZ. ROTÉ

$$\omega = \frac{2\pi n}{c_0} = 0,42 \text{ rad/s}$$

$$P = M_{Ay} \cdot \omega \Rightarrow M_{Ay} = \frac{P}{\omega} = 17,9 \cdot 10^6 \text{ Nmm}$$



$$F_1 = K \omega L_1$$

$$F_2 = K \omega (L_1 + L_2)$$

$$M_{Ay} = F_1 l_1 + F_2 (l_1 + l_2)$$

$$= k \omega (L_1^2 + (L_1 + L_2)^2)$$

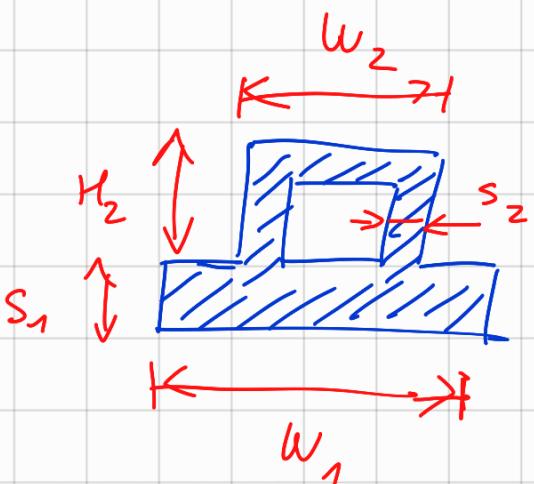
$$K = \frac{M_{Ay}}{\omega(L_1^2 + (L_1 + L_2)^2)}$$

$$f_{P1} = \frac{F_1}{H_1} = 2390 \frac{N}{m} \quad \leftarrow \quad \left\{ \begin{array}{l} F_1 = \frac{L_1}{L_1^2 + (L_1 + L_2)^2} M_{Ay} = \\ = 2870 N \end{array} \right.$$

$$f_{P2} = \frac{F_2}{H_2} = 4650 \frac{N}{m} \quad \leftarrow \quad \left\{ \begin{array}{l} F_2 = \frac{L_1 + L_2}{L_1^2 + (L_1 + L_2)^2} M_{Ay} = \\ = 5340 N \end{array} \right.$$

(2) PESI

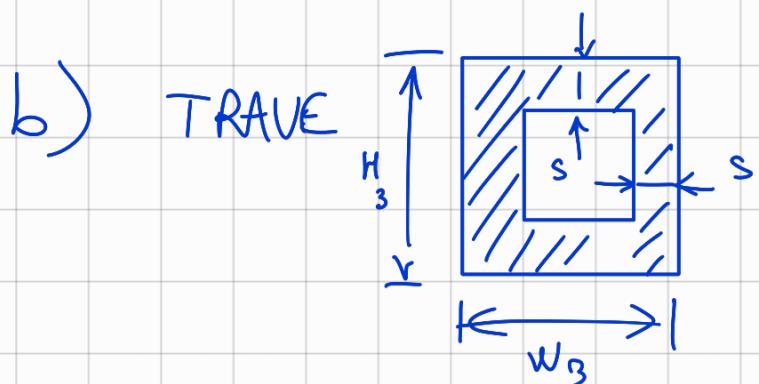
caso a) Palo



$$\begin{aligned} A_p &= W_1 S_1 + H_2 W_2 - (H_2 - S_2)(W_2 - 2S_2) \\ &= 3888 \text{ m m}^2 \end{aligned}$$

$$q_p = A_p \cdot p \cdot f = 299,6 \text{ N/m} \quad (\text{Peso distribuito})$$

$$P_p = q_p (H + H_1) = 449,1 \text{ N}$$

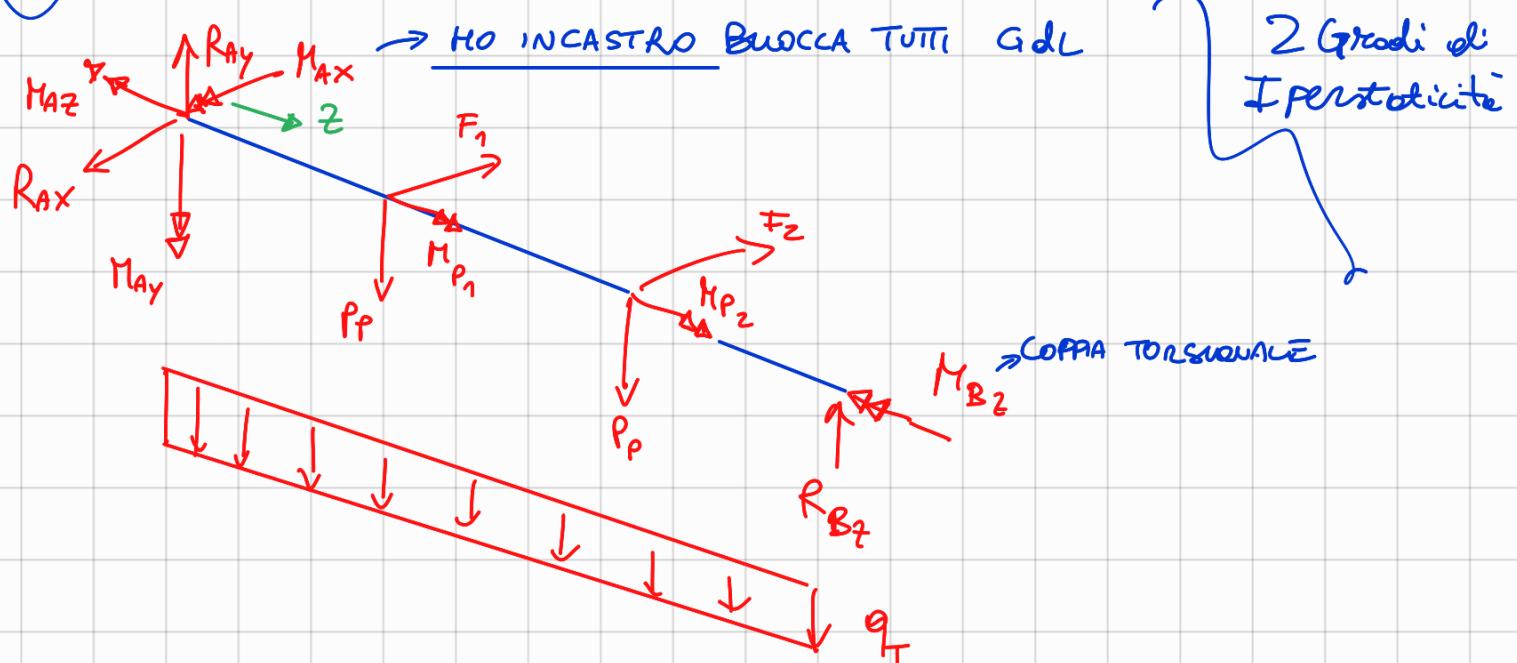


$$A_T = H_3 W_3 - (H_3 - 2s)(W_3 - 2s) = 6200 \text{ mm}^2$$

$$q_T = A_T \cdot p \cdot f = 677,6 \text{ N/m}$$

$$P_T = q_T \cdot L = 1910 \text{ N}$$

③ REAZIONI VIN COLARE



a) Torsionale

$$\theta(0) = 0 \quad , \quad \theta(L) = 0$$

conoscere
sisteme x

definire incognite
iperstatica

$$M_z = \begin{cases} M_{Az} & 0 \leq z \leq L_1 \\ M_{Az} - M_{p_1} & L_1 \leq z \leq L_1 + L_2 \\ M_{Az} - M_{p_1} - M_{p_2} & L_1 + L_2 \leq z \leq L \end{cases}$$

$$M_{Az} + M_{Bz} = M_{p_1} + M_{p_2}$$

o castigliano o linee elastiche
+ facile

$$\theta(L) = \int_0^L \frac{M_z}{GJ_T} dz = 0$$

→ semplifica per "GJ_T"

$$\rightarrow M_{Az} \cdot L_1 + (M_{Az} - M_{p_1}) L_2 + (M_{Az} - M_{p_1} - M_{p_2}) L_3 = 0$$

↑ condizioni
con
 $\theta(L) = 0$

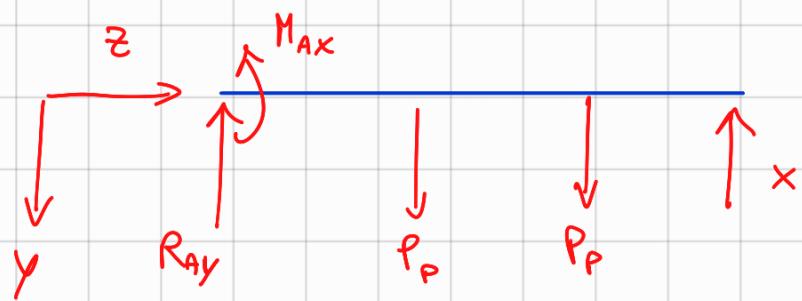
$$M_{Az} \cdot L = M_{p_1} (L_2 + L_3) + M_{p_2} \cdot (L_3)$$

$$M_{Az} = 3,37 \cdot 10^6 \text{ Nmm}$$

$$M_{Bz} = 4,03 \cdot 10^6 \text{ Nmm}$$

b) 2° INCognita iperstatica R_{By} in + rispetto a incost

$$K_{By} = X \text{ (incognita iperbolica)}$$



trovare R_{Ax} in funzione di x
Azioni interne in funzione di x

equilibrio

$$y: R_{Ax} = 2P_p - x + P_T$$

$$\text{rot: } M_{Ax} = P_p (2L_1 + L_2) - xL$$

$$a) 0 \leq z \leq L_1$$

$$M_x = -\cancel{M_{Ax}} + \cancel{R_{Ax}} \cdot z - q_T \frac{z^2}{2}$$

$$b) L_1 \leq z \leq L_1 + L_2$$

$$M_x = -\cancel{M_{Ax}} + \cancel{R_{Ax}} \cdot z - P_p(z - L_1) - q_T \frac{z^2}{2}$$

$$c) L_1 + L_2 \leq z \leq L$$

$$M_x = -\cancel{M_{Ax}} + \cancel{R_{Ax}} \cdot z - P_p(z - L_1) - P_p(z - (L_1 + L_2)) - q_T \frac{z^2}{2}$$

DISPLACEMENTS

$$S_{By} = \frac{\partial U}{\partial X} = 0$$

$$= \int_0^L \frac{M_x}{EI_x} \frac{\partial M_x}{\partial X} dz$$

$$= \int_0^{L_1} \frac{R_{Ay} \cdot z - M_{Ax} - q_T \frac{z^2}{2}}{EI_x} (-z + L) dz +$$

derivative

$$+ \int_{L_1}^{L_1+L_2} \frac{R_{Ay} \cdot z - M_{Ax} - q_T \frac{z^2}{2} + P_p(z-L_1)}{EI_x} \frac{\partial R_{Ay}/z}{\partial X} (-z + L) dz +$$

$$+ \int_{L_1+L_2}^L \frac{R_{Ay} - M_{Ax} - q_T \frac{z^2}{2} - P_p(z-L_1) - P_p(z-(L_1+L_2))}{EI_x} (-z + L) dz = 0$$

$$\int_0^L \left(R_{Ay} - M_{Ax} - q_T \frac{z^2}{2} \right) (L-z) dz - \int_{L_1}^L P_p(z-L_1)(L-z) dz - \int_{L_1+L_2}^L P_p(z-(L_1+L_2))(L-z) dz$$

$$= \left[q_T \frac{z^4}{8} + \left(-\frac{q_T}{2} - R_{Ay} \right) \frac{z^3}{3} + \left(R_{Ay}L + M_{Ax} \right) \frac{z^2}{2} - M_{Ax}L \right]_0^L -$$

$$- P_p \left[-\frac{z^3}{3} + (L_1 + L) \frac{z^2}{2} - L_1 L_2 \right]_{L_1}^L -$$

$$- P_p \left[-\frac{z^3}{3} + (L_1 + L_2 + L) \frac{z^2}{2} - (L_1 + L_2)L_2 \right]_{L_1+L_2}^L$$

$$= q_T \frac{L'}{8} - \left(\frac{q_T}{2} + R_{AY} \right) \frac{L}{3} + \left(R_{AY} L + M_{AX} \right) \frac{L}{2} - M_{AX} L +$$

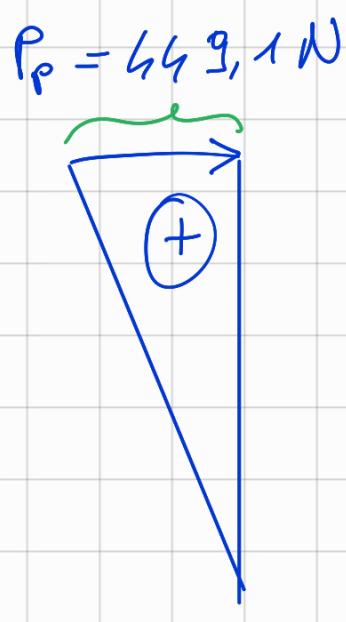
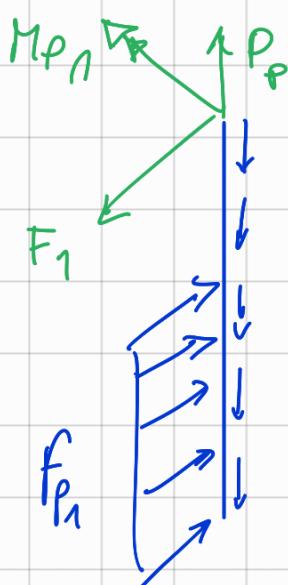
$$P_P \left(\frac{L^3}{3} - (L_1 + L) \frac{L^2}{2} + L_1 L^2 - \frac{L_1^3}{3} + (L_1 + L) \frac{L_1^2}{2} - L_1 L^2 + \right)$$

$$+ P_P \left(\frac{L^3}{3} - (L_1 + L_2 + L) \frac{L^2}{2} + (L_1 + L_2) L^2 - \frac{(L_1 + L_2)^3}{3} + (L_1 + L_2 + L) \frac{(L_1 + L_2)^2}{2} - (L_1 + L_2)^2 L \right) = 0$$

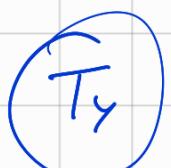
$$X = 1012 \text{ N}$$

$$R_{BY} = 1012 \text{ N}, R_{AY} = 1736 \text{ N}, M_{AX} = 1,57 \cdot 10^6 \text{ Nmm}$$

⑤ AZIUNI INTERVE



$$-F_1 = -2870 \text{ N}$$



$$-F_2 = -5340 \text{ N}$$

$$M_{P_2} = 5,81 \cdot 10^5 \text{ Nmm}$$

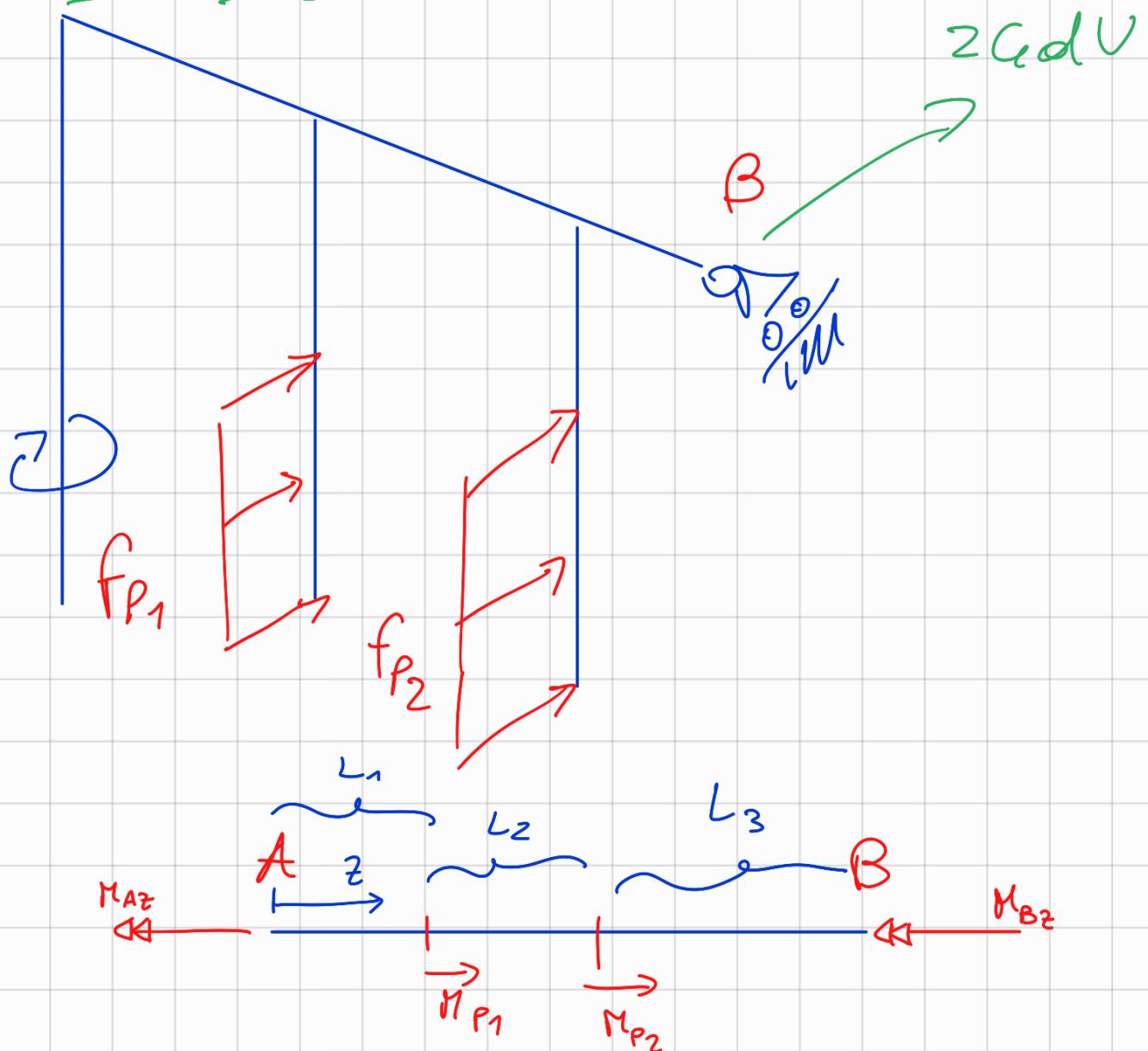


Punto d'immersione

RIPRENDO ES. DI PRECEDENTE

A

$\rightarrow 6 \text{ CdV}$



Linee elastiche

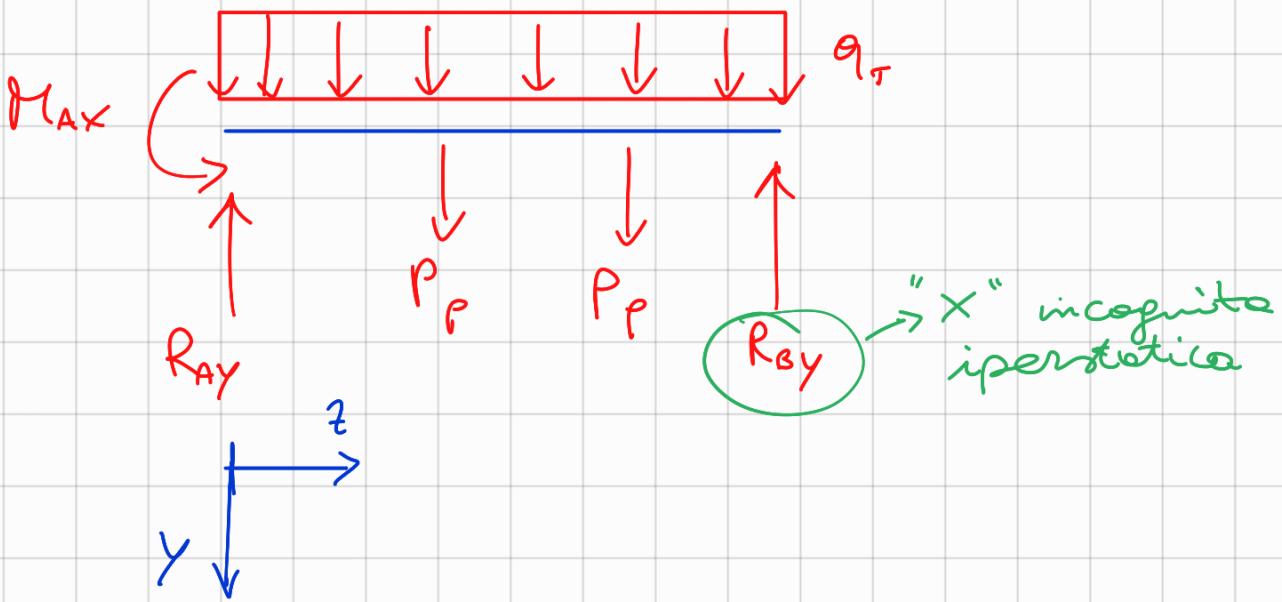
$$\theta_z(0) = 0$$

$$\theta_z(L) = 0$$

$$M_z = \begin{cases} - & [0, L_1] \\ - & [L_1, L_1 + L_2] \\ - & [L_1 + L_2, L] \end{cases}$$

$$\frac{\partial \theta}{\partial z} = \frac{M_3}{G J_b}$$

② FUSSIONE



$$\text{equazione y: } 2P_p = R_{\theta y} + \cancel{R_{By}} - q_T \cdot L$$

$$R_{\theta y} = 2P_p - \cancel{x} + q_T \cdot L$$

$$\text{Voto A} \quad M_{\text{Ax}} = \underbrace{P_p L_1}_{\text{Peso della palo}} + P_p (L_1 + L_2) - \cancel{x} L + q_T \frac{L^2}{2}$$

$$z \in [0, L_1]$$

$$T_y = +R_{\theta y} - q_T \cdot z$$

$$\rightarrow M_x = -M_{\text{Ax}} + R_{\theta y} \cdot z - q_T \cdot \frac{z^2}{2}$$

$$z \in [L_1, L_1 + L_2]$$

$$T_y = +R_{Ay} - q_T \cdot z + P_p$$

$$\rightarrow M_x = -M_{Ax} + R_{Ay} z - q_T \frac{z^2}{2} + P_p (z - L_1)$$

$$z \in [L_1 + L_2, L]$$

$$T_y = +R_{Ay} - q_T \cdot z + 2P_p$$

$$\rightarrow M_x = -M_{Ax} + R_{Ay} \cdot z - q_T \frac{z^2}{2} + P_p (z - L_1) + P_p (z - (L_1 + L_2))$$

$$V(L) = 0 \rightarrow \frac{\partial^2 V}{\partial z^2} = -\frac{M_x}{EI_x} \rightarrow V(0) = 0$$

$$\theta(0) = \frac{\partial V}{\partial z}(0) = 0$$

CONDIZ.
eq. linea
elastica

$$\left\{ \begin{array}{l} \frac{\partial U}{\partial X} = 0 \\ \frac{\partial^2 U}{\partial X^2} = 0 \end{array} \right. \quad \left\{ \begin{array}{l} \text{CASTIGLIANO} \\ (\text{no cedimento strutturale}) \end{array} \right.$$

ottima x
se le
sono
contributi
soluz

$$\frac{\partial U}{\partial X} = \int_{\text{SIR}} \frac{M_x}{EI_x} \frac{\partial M_x}{\partial X} dz = 0$$



le metto qui dentro

1° SPEZ.

$$\frac{\partial U}{\partial X} = \int_{-L_1}^{L_1} \left(R_{Ay} z - q_T \frac{z^2}{2} - M_{Ax} \right) (-z + L) dz +$$

$\frac{\partial U}{\partial x} = 0$ leva EI_x (tendo no a zero)

$$\int_{L_1}^{L_1+L_2} \left(R_{Ay} z - q_T \frac{z^2}{2} - M_{Ax} - P_p(z-L_1) - P_p(z-(L_1+L_2)) \right) (L-z) dz + \int_{L_1+L_2}^L \left(R_{Ay} z - q_T \frac{z^2}{2} - M_{Ax} \right) (L-z) dz = 0$$

↓

Qui compare x

$$M_x = R_{Ay} z - q_T \frac{z^2}{2} - M_{Ax} - P_p(z-L_1) - P_p(z-(L_1+L_2))$$

$$R_{Ay} = 2P_p + q_T \cdot L$$

$-x$ → parti che entrano nella derivata

$$M_{Ax} = P_p (2(L_1+L_2) - xL + q_T \frac{L^2}{2})$$

$$\begin{aligned} \frac{\partial U}{\partial x} &= \int_0^L \left(R_{Ay} z - q_T \frac{z^2}{2} - M_{Ax} \right) (L-z) dz + \int_{L_1}^L P_p \cdot (z-L_1)(L-z) dz + \int_{L_1+L_2}^L P_p (z-(L_1+L_2))(L-z) dz \\ &= \left[q_T \frac{z^4}{8} + \left(-R_{Ay} - \frac{q_T L}{2} \right) \frac{z^3}{3} + \left(R_{Ay} L + M_{Ax} \right) \frac{z^2}{2} - M_{Ax} L z \right]_0^L + \\ &\quad + \left[P_p \left(-\frac{z^3}{3} + (L_1+L) \frac{z^2}{3} - L_1 L z \right) \right]_{L_1}^L + \\ &\quad + \left[P_p \left(-\frac{z^3}{3} + (L_1+L_2+L) \frac{z^2}{2} - (L_1+L_2)L z \right) \right]_{L_1+L_2}^L = 0 \end{aligned}$$

$$\frac{\partial U}{\partial x} = q_T \frac{L^4}{8} - \left(R_{Ay} + \frac{q_T L}{2} \right) \frac{L^3}{3} + \left(R_{Ay} L + M_{Ax} \right) \frac{L^2}{2} - M_{Ax} L^2 +$$

$$+ P_p \left[-\frac{L^3}{3} + (L_1 + L) \frac{L^2}{2} - L_1 L^2 + \frac{L_1}{3} - (L_1 + L) \frac{L_1^2}{2} + L_1^2 L \right]$$

$$- \frac{L^3}{3} + (L_1 + L_2 + L) \frac{L^2}{2} - (L_1 + L_2) L^2 + \frac{(L_1 + L_2)^3}{3} - \\ - (L_1 + L_2 + L) \frac{(L_1 + L_2)^2}{2} + (L_1 + L_2)^2 L \Big]$$

$$R_{Ay} = 2 P_p + q_T L - x$$

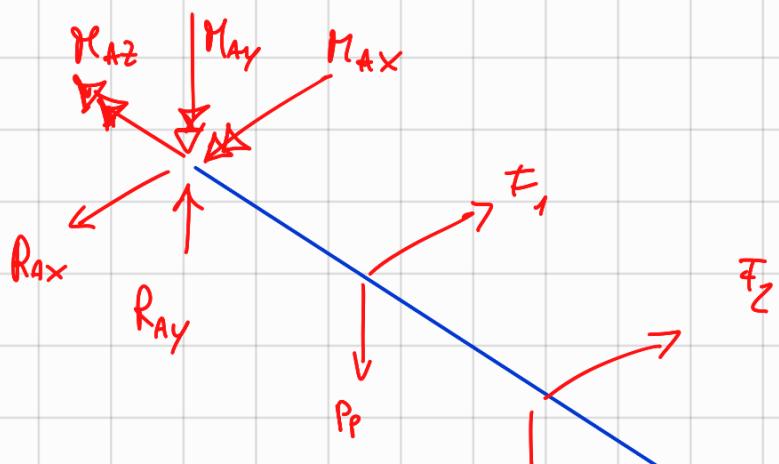
$$M_{Ax} = P_p (2 L_1 + L_2) - x L + q_T \frac{L^2}{2}$$

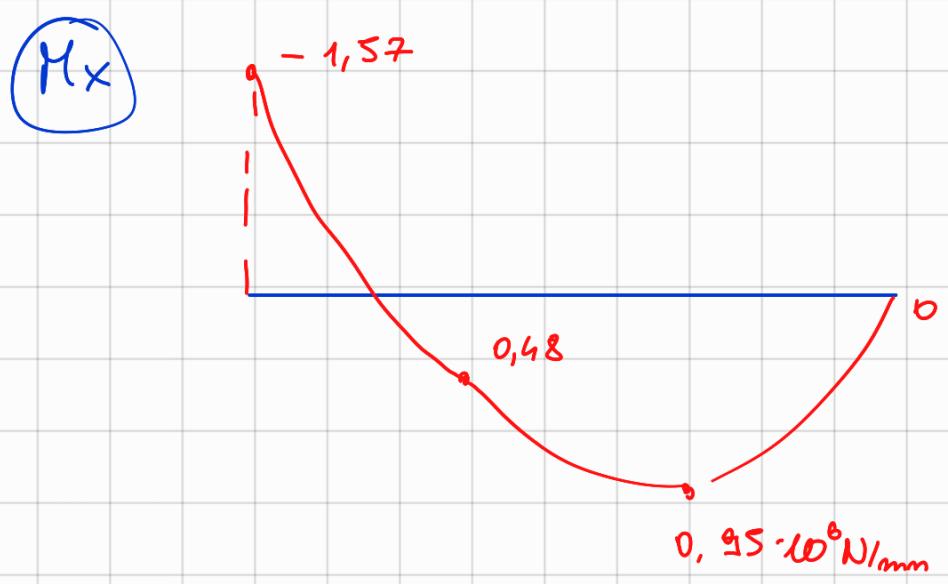
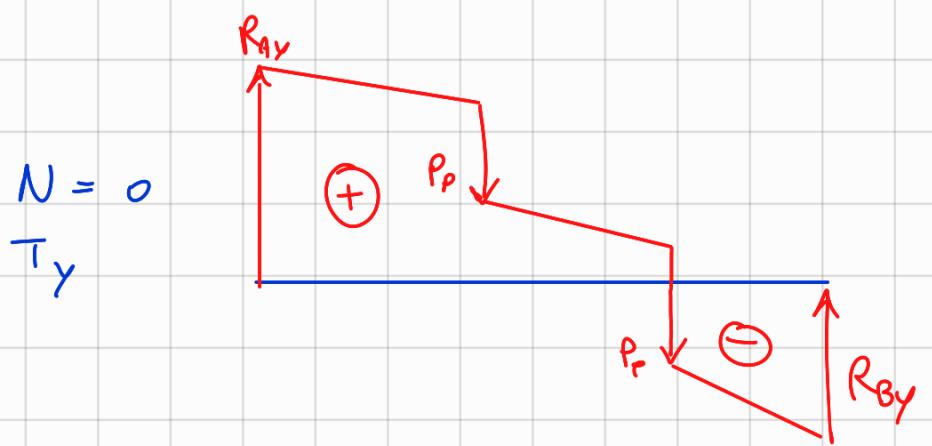
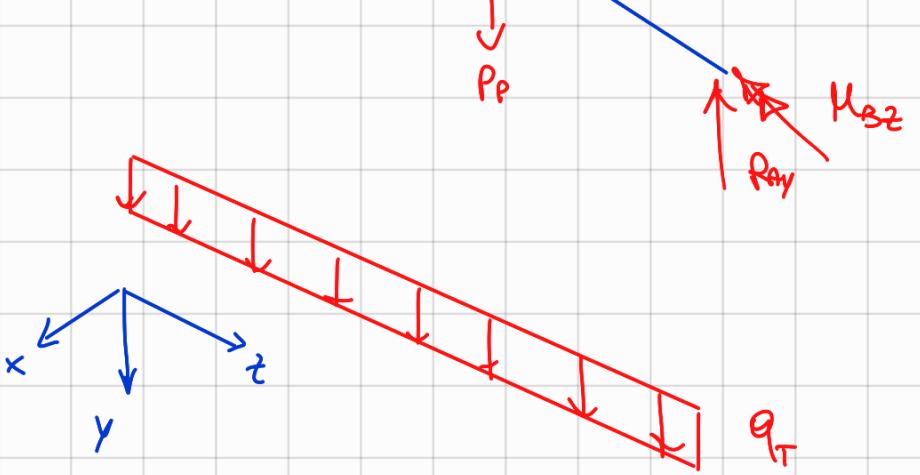
$$- R_{Ay} \frac{L^3}{3} + R_{Ay} \frac{L^3}{2} + M_{Ax} \frac{L^2}{2} - M_{Ax} L^2 = - q_T \frac{L^5}{8} - q_T \frac{L^5}{6} - P_p [\dots]$$

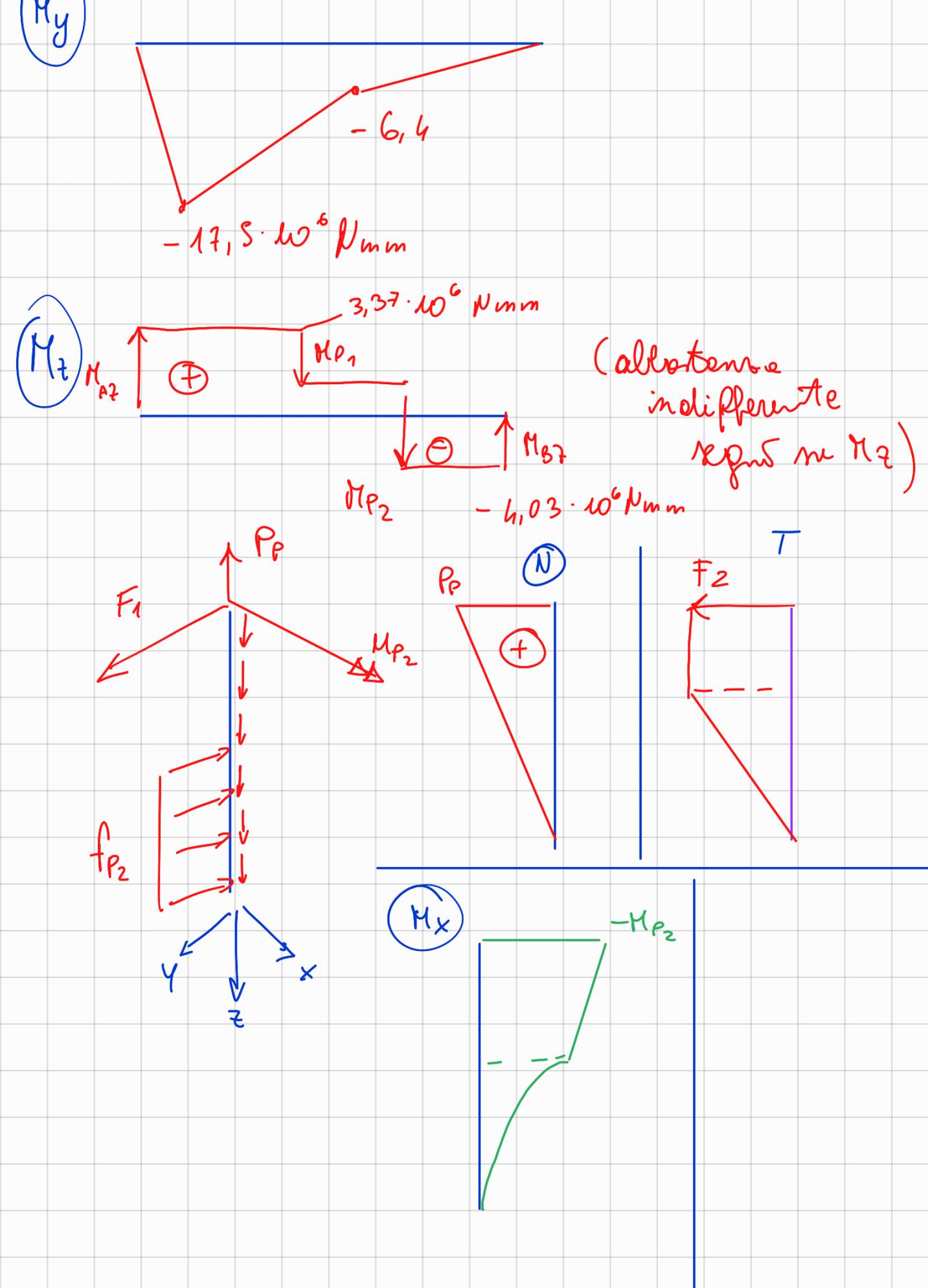
$$R_{Ay} \frac{L^3}{6} - M_{Ax} \frac{L^2}{2} = [\dots]$$

$$- x \frac{L^3}{6} + x L \frac{L^2}{2} = [\dots] - (2 P_p + q_T L) \frac{L^3}{6} + (P_p (2 L_1 + L_2) + q_T \frac{L^2}{2}) \frac{L^2}{2}$$

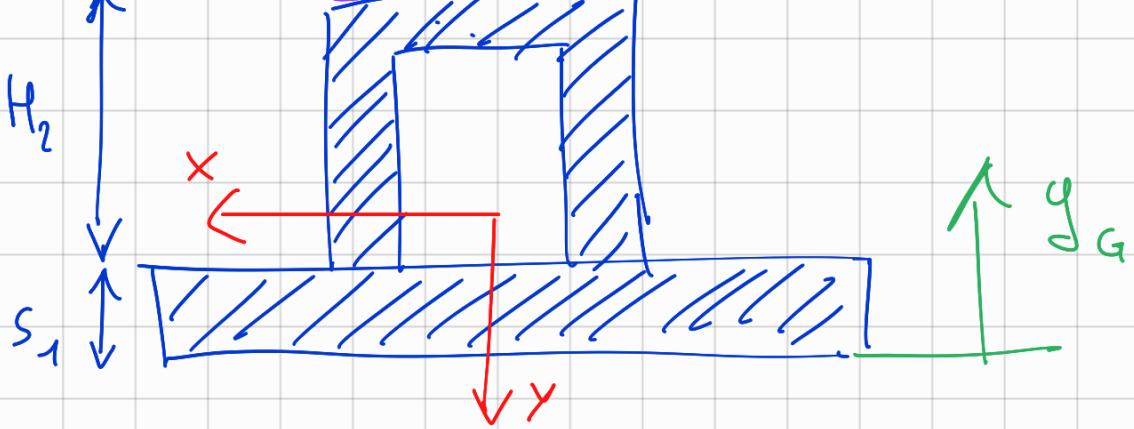
$$x \frac{L^3}{3} = [\dots] \quad x = 1012 N$$







Punto critico in $\boxed{z=0}$



$$\left\{ \begin{array}{l} N = 449,1 \text{ N} \\ M_x = 1,81 \cdot 10^6 \text{ Nmm} \end{array} \right.$$

$$\rightarrow A = 3888 \text{ mm}^2$$

$$\rightarrow y_G \text{ (ho molo } M_x) = \frac{s_x}{A} = 39,6 \text{ mm}$$

$$\rightarrow I_x = 8,01 \cdot 10^6 \text{ mm}^4$$

$$-\sigma_{zz} = \frac{N}{A} + \frac{M_x}{I_x} y$$

$$y_{MAX} = y_G$$

$$\begin{aligned} y_{MIN} &= -82,4 \text{ mm} \\ &= -(s_1 + h_2 - y_G) \end{aligned}$$

$$\sigma_{zz,\text{MAX}} = 23,63 \text{ MPa}$$

opportunità

$$\sigma_{zz,\text{MIN}} = -55,3 \text{ MPa}$$

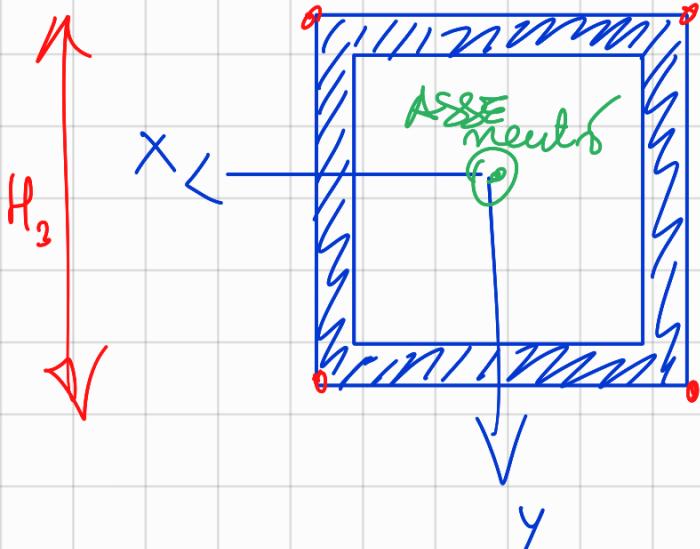
$$(\ell = \frac{\sigma_{ys}}{\sigma_{zz,\text{MIN}}} = 7,2$$

$$t = 0$$

$$M_x = -1,57 \cdot 10^6 \text{ Nmm}$$

$$M_y = -17,9 \cdot 10^6 \text{ Nmm}$$

$$M_z = 3,37 \cdot 10^6 \text{ Nmm}$$



$$I_x = 28,5 \cdot 10^6 \text{ Nmm}$$

$$I_y = 21,3 \cdot 10^6 \text{ Nmm}$$

$$\sigma_{zz,\text{MAX}} = \frac{|M_x|}{I_x} \frac{H_3}{2} + \frac{|M_y|}{I_y} \frac{W_3}{2} = \\ = 30,1 \text{ MPa}$$

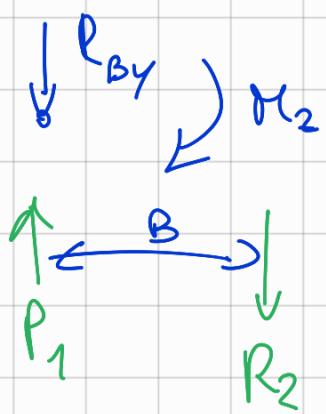
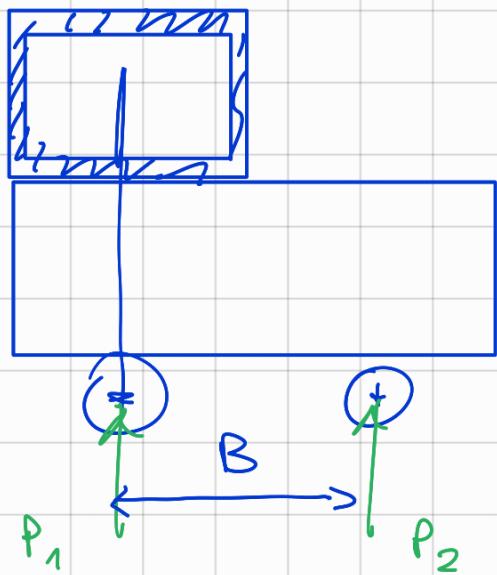
$$\gamma_{xz} = \frac{M_z}{2 \cdot Q_s} = 7,1 \text{ MPa}$$

$$\sigma_{VM} = \sqrt{\sigma^2 + 3\gamma^2} = 32,5 \text{ MPa}$$

$$\varphi = 12,3$$

Trovare reazione corrispondente

$$Z = L$$



$$\text{equi lungo y: } R_1 + R_2 = R_{By}$$

$$\text{Rotors: } R_2 \cdot B = M_z$$



$$R_2 = 8,96 \text{ kN}$$

$$R_1 = 7,26 \text{ kN}$$