BluetoothPositioning

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1 Indice dei namespace

1.1 Package

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it.unibo.torsello.bluetoothpositioning.task	9
it.unibo.torsello.bluetoothpositioning.util	9

2 Indice della gerarchia

2.1 Gerarchia delle classi

Questo elenco di ereditarietà è ordinato approssimativamente, ma non completamente, in ordine alfabetico:

Adapter

it.unibo.torsello.bluetoothpositioning.util.CameraPreviewUtil	22
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5 Documentazione dei namespace

5.1 Package it

5.2 Package it.unibo 7

Package

• package unibo

5.2 Package it.unibo

Package

· package torsello

5.3 Package it.unibo.torsello

Package

· package bluetoothpositioning

5.4 Package it.unibo.torsello.bluetoothpositioning

Package

- · package activities
- · package adapter
- · package constant
- package distanceEstimation
- · package extra
- · package filters
- package fragment
- · package model
- · package observables
- · package task
- · package util

5.5 Package it.unibo.torsello.bluetoothpositioning.activities

Composti

- · class ApplicationActivity
- · class MainActivity

5.6 Package it.unibo.torsello.bluetoothpositioning.adapter

Composti

- · class DeviceCardViewAdapter
- class StatePagerAdapter

5.7 Package it.unibo.torsello.bluetoothpositioning.constant

Composti

- · class DeviceConstants
- class KFilterConstants
- · class SettingConstants
- 5.8 Package it.unibo.torsello.bluetoothpositioning.distanceEstimation

Composti

- · class Estimation
- 5.9 Package it.unibo.torsello.bluetoothpositioning.extra

Composti

- · class FABBehavior
- 5.10 Package it.unibo.torsello.bluetoothpositioning.filters

Package

package kalmanFilter

Composti

- · class MyArmaRssiFilter
- 5.11 Package it.unibo.torsello.bluetoothpositioning.filters.kalmanFilter

Composti

- class KFilter
- class KFilterBuilder
- 5.12 Package it.unibo.torsello.bluetoothpositioning.fragment

Composti

- class CameraFragment
- · class DeviceChartFragment
- · class DeviceDetailFragment
- class DeviceDetailInner0Fragment
- · class DeviceDetailInner1Fragment
- · class DeviceDetailInner2Fragment
- class DeviceDetailReportFragment
- · class DeviceDetailResumeFragment
- · class DeviceListFragment
- class SettingsFragment
- class UsbMeasurementFragment

5.13 Package it.unibo.torsello.bluetoothpositioning.model	
Composti	
• class Device	
5.14 Package it.unibo.torsello.bluetoothpositioning.observables	
Composti	
 class DeviceObservable class UsbMeasurementObservable 	
5.15 Package it.unibo.torsello.bluetoothpositioning.task	
Composti	
• class SaveImageTask	
5.16 Package it.unibo.torsello.bluetoothpositioning.util	
Composti	
 class CameraPreviewUtil class ChartUtil class ReportUtils 	

6 Documentazione delle classi

• class UsbUtil

6.1 Riferimenti per la classe it.unibo.torsello.bluetoothpositioning.activities.ApplicationActivity

Diagramma delle classi per it.unibo.torsello.bluetoothpositioning.activities.ApplicationActivity

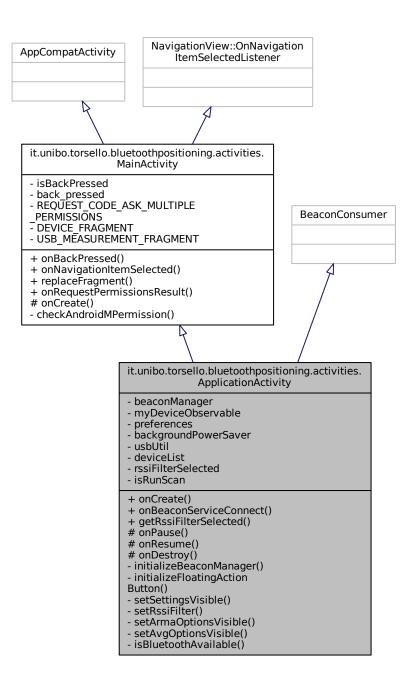
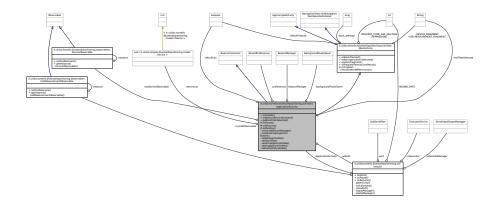


Diagramma di collaborazione per it.unibo.torsello.bluetoothpositioning.activities.ApplicationActivity:



Membri pubblici

- void onCreate (Bundle savedInstanceState)
- void onBeaconServiceConnect ()
- String getRssiFilterSelected ()

Membri protetti

- void onPause ()
- void onResume ()
- void onDestroy ()

Membri privati

- void initializeBeaconManager ()
- void initializeFloatingActionButton ()
- void setSettingsVisible (final boolean scanStarted)
- void setRssiFilter ()
- void setArmaOptionsVisible (final boolean visible)
- void setAvgOptionsVisible (final boolean visible)
- boolean isBluetoothAvailable ()

Attributi privati

- BeaconManager beaconManager
- DeviceObservable myDeviceObservable
- SharedPreferences preferences
- BackgroundPowerSaver backgroundPowerSaver
- UsbUtil usbUtil
- List< Device > deviceList
- · String rssiFilterSelected
- boolean isRunScan = false

6.1.1 Descrizione dettagliata

Created by Federico Torsello. federico.torsello@studio.unibo.it

6.1.2 Documentazione delle funzioni membro

6.1.2.1 getRssiFilterSelected()

```
String it.unibo.torsello.bluetoothpositioning.activities.ApplicationActivity.getRssiFilter←
Selected ( )

287
288 return rssiFilterSelected;
289 }
```

6.1.2.2 initializeBeaconManager()

```
73
           beaconManager = BeaconManager.getInstanceForApplication(getApplicationContext());
74
           beaconManager.bind(this);
7.5
76
           // Save battery whenever the application is not visible.
           // This reduces bluetooth power usage by about 60%
78
           backgroundPowerSaver = new BackgroundPowerSaver(getApplicationContext());
79
80 //
             Log.i("AltBeacon filter used:", BeaconManager.getRssiFilterImplClass().getSimpleName());
81
           // for finding different type of beacon,
82
83
           beaconManager.getBeaconParsers().clear();
84
85
86
           beaconManager.getBeaconParsers().add(new BeaconParser()
87
                    .setBeaconLayout(BeaconParser.ALTBEACON_LAYOUT));
           // Detect the main identifier (UID) frame:
beaconManager.getBeaconParsers().add(new BeaconParser())
88
89
90
                    .setBeaconLayout (BeaconParser.EDDYSTONE_UID_LAYOUT));
91
           // Detect the telemetry (TLM) frame:
92
           beaconManager.getBeaconParsers().add(new BeaconParser()
9.3
                    .setBeaconLayout(BeaconParser.EDDYSTONE_TLM_LAYOUT));
           // Detect the URL frame:
94
95
           beaconManager.getBeaconParsers().add(new BeaconParser()
                    .setBeaconLayout (BeaconParser.EDDYSTONE_URL_LAYOUT));
97
           // Standard Apple iBeacon
98
           beaconManager.getBeaconParsers().add(new BeaconParser()
99
                    . \verb|setBeaconLayout(DeviceConstants.APPLE_BEACON\_LAYOUT)||;
            // Estimote Nearable
100
            beaconManager.getBeaconParsers().add(new BeaconParser()
101
102
                     .setBeaconLayout(DeviceConstants.ESTIMOTE_NEARABLE_LAYOUT));
103
104
            beaconManager.setForegroundScanPeriod(500L);
            {\tt beaconManager.setForegroundBetweenScanPeriod(OL);}
105
106
107 //
              beaconManager.setMaxTrackingAge(2000);
108
```

6.1.2.3 initializeFloatingActionButton()

void it.unibo.torsello.bluetoothpositioning.activities.ApplicationActivity.initializeFloating← ActionButton () [private] 110 111 final FloatingActionButton fab = (FloatingActionButton) findViewById(R.id.fab); 112 Snackbar.make(fab, R.string.snackBar_start_scanning, Snackbar.LENGTH_INDEFINITE).show(); fab.setOnClickListener(new View.OnClickListener() 113 @Override 114 115 public void onClick(View view) { 116 117 if (isBluetoothAvailable()) { 118 119 isRunScan = !isRunScan; Region region = new Region("RegionId", null, null, null); 120 121 122 setSettingsVisible(isRunScan); 124 if (isRunScan) { 125 fab.setImageResource(R.drawable.ic_bluetooth_searching_white_24dp); 126 try { 127 beaconManager.startRangingBeaconsInRegion(region); 128 } catch (RemoteException e) { 129 e.printStackTrace(); 130 Snackbar.make(view, R.string.snackBar_scanning_enabled, Snackbar.LENGTH_SHORT).show(); 131 132 133 } else { 134 fab.setImageResource(R.drawable.ic_bluetooth_white_24dp); 135 try { 136 beaconManager.stopRangingBeaconsInRegion(region); 137 } catch (RemoteException e) { 138 e.printStackTrace(); 139 Snackbar.make(view, R.string.snackBar_scanning_disabled, 140 Snackbar.LENGTH_INDEFINITE).show(); 141 143 }

6.1.2.4 isBluetoothAvailable()

}
});

144

145 146

boolean it.unibo.torsello.bluetoothpositioning.activities.ApplicationActivity.isBluetooth↔
Available () [private]

```
355
356
                final FloatingActionButton fab = (FloatingActionButton) findViewById(R.id.fab);
357
358
                if (!beaconManager.checkAvailability()) {
359
                     new AlertDialog.Builder(this)
360
361
                             . \verb|setTitle| (R.string.dialog_bluetooth_title)|\\
362
                             .setMessage(R.string.dialog_bluetooth_text)
363
                             .setPositiveButton(android.R.string.ok, null)
364
                             .setOnDismissListener(new DialogInterface.OnDismissListener() {
365
                                 @Override
366
                                 public void onDismiss(DialogInterface dialog)
367
                                     BluetoothAdapter.getDefaultAdapter().enable();
368
                                      fab.setImageResource(R.drawable.ic_bluetooth_white_24dp);
369
                                     Snackbar.make(fab, R.string.snackBar start scanning,
370
                                              Snackbar.LENGTH_INDEFINITE).show();
371
372
                             }).show();
373
                     fab.setImageResource(R.drawable.ic_bluetooth_disabled_black_24dp);
374
                     Snackbar.make(fab, R.string.snackBar_scanning_disabled,
375
                             Snackbar.LENGTH_INDEFINITE).show();
376
                     return false:
377
                }
378
            } catch (RuntimeException e) {
379
                e.getStackTrace();
380
381
            return true;
        }
382
```

6.1.2.5 onBeaconServiceConnect()

```
Connect ( )
164
165
166
167
                beaconManager.updateScanPeriods();
              catch (RemoteException e) {
168
169
                e.printStackTrace();
171
172
            beaconManager.addRangeNotifier(new RangeNotifier() {
173
                @Override
                public void didRangeBeaconsInRegion(final Collection<Beacon> beacons, Region region) {
174
175
176
                    setRssiFilter();
177
178
                     for (Beacon b : beacons) {
179
180
                         // take from the list the device
                         Device device = DeviceConstants.DEVICE_MAP.get(b.getBluetoothAddress());
181
182
183
                         if (device != null) { // useful only if DEVICE_MAP is empty
184
                             double processNoise = preferences.getFloat(SettingConstants.
      KALMAN_NOISE_VALUE, 0);
185
                             device.setBeacon(b);
                             device.updateDistance(processNoise);
186
187
188
                             if (!deviceList.contains(device)) {
189
                                 deviceList.add(device);
190
191
                         }
192
193
194
                     new Thread(new Runnable() {
195
196
                         public void run() {
197
                             runOnUiThread(new Runnable() {
198
199
                                 @Override
200
                                 public void run() {
201
                                     myDeviceObservable.
      notifyObservers(deviceList);
202
203
                             });
204
205
                     }).start();
206
207
            });
208
```

6.1.2.6 onCreate()

```
\verb|void it.unibo.torsello.bluetoothpositioning.activities.Application \verb|Activity.onCreate|| (
               Bundle savedInstanceState )
55
56
           super.onCreate(savedInstanceState);
57
58
           deviceList = new ArrayList<>();
59
           myDeviceObservable = DeviceObservable.getInstance();
60
61
           preferences = getSharedPreferences(SettingConstants.SETTINGS_PREFERENCES, 0);
62
63
           usbUtil = new UsbUtil(this);
65
66
           initializeBeaconManager();
67
68
           initializeFloatingActionButton();
69
       }
```

6.1.2.7 onDestroy()

```
void it.unibo.torsello.bluetoothpositioning.activities.ApplicationActivity.onDestroy ( ) [protected]

346
347     if (beaconManager.isBound(this)) {
        beaconManager.unbind(this);
        backgroundPowerSaver.onActivityDestroyed(this);
        }
350     }
351
352     super.onDestroy();
353 }
```

6.1.2.8 onPause()

void it.unibo.torsello.bluetoothpositioning.activities.ApplicationActivity.onPause () [protected]

```
319
            if (beaconManager.isBound(this)) {
320
                beaconManager.setBackgroundMode(true);
321
                backgroundPowerSaver.onActivityPaused(this);
322
323
324
325
            usbUtil.onPause();
326
327
            super.onPause();
        }
328
```

6.1.2.9 onResume()

void it.unibo.torsello.bluetoothpositioning.activities.ApplicationActivity.onResume () [protected]

```
331
                                    {
332
            super.onResume();
333
334
            if (beaconManager.isBound(this)) {
335
                beaconManager.setBackgroundMode(false);
336
                backgroundPowerSaver.onActivityResumed(this);
337
338
339
            isBluetoothAvailable();
340
341
            usbUtil.onResume();
342
343
        }
```

6.1.2.10 setArmaOptionsVisible()

```
\verb|void| it.unibo.torsello.bluetoothpositioning.activities.ApplicationActivity.setArmaOptions \\ \leftarrow \\ |void| |void|
Visible (
                                                                                       final boolean visible ) [private]
  291
  292
                                                                       runOnUiThread(new Runnable() {
  293
                                                                                             @Override
 294
                                                                                             public void run() {
  295
                                                                                                                    if (visible) {
  296
                                                                                                                                            findViewById(R.id.radioGroupArmaOptions).setVisibility(View.VISIBLE);
  297
  298
                                                                                                                                            findViewById(R.id.radioGroupArmaOptions).setVisibility(View.GONE);
  299
  300
  301
                                                                      });
                                              }
  302
```

6.1.2.11 setAvgOptionsVisible()

```
void it.unibo.torsello.bluetoothpositioning.activities.ApplicationActivity.setAvgOptions↔
Visible (
              final boolean visible ) [private]
304
305
            runOnUiThread(new Runnable() {
306
               @Override
               public void run() {
307
308
                   if (visible) {
                       findViewById(R.id.radioGroupAverageOptions).setVisibility(View.VISIBLE);
309
310
311
                       findViewById(R.id.radioGroupAverageOptions).setVisibility(View.GONE);
312
313
            });
314
315
```

6.1.2.12 setRssiFilter()

```
\label{lem:condition} void it.unibo.torsello.bluetoothpositioning.activities. Application Activity.set RssiFilter () \\ [private]
```

```
210
                                      {
211
212
            StringBuilder selectOption = new StringBuilder();
213
214
            int sorting = preferences.getInt(SettingConstants.FILTER_RSSI, 0);
215
            switch (sorting) {
216
                case 0:
217
                case R.id.radioButton_no_rssi_filtering:
218
                    setArmaOptionsVisible(false);
219
                    setAvgOptionsVisible(false);
220
                    selectOption.append("No RSSI filtering");
221
222
223
                    MyArmaRssiFilter.enableArmaFilter(false);
                    BeaconManager.setRssiFilterImplClass(MyArmaRssiFilter.class);
224
225
226
227
                case R.id.radioButton_arma_rssi_filter:
228
                    setArmaOptionsVisible(true);
229
                    setAvgOptionsVisible(false);
230
231
                    selectOption.append("ARMA RSSI filter");
232
233
                    int armaOption = preferences.getInt(SettingConstants.ARMA_OPTION, 0);
234
                    switch (armaOption) {
235
                        case 0:
236
                        case R.id.radioButton_arma_op1:
237
                            MyArmaRssiFilter.setArmaSpeed(0.1D);
238
239
                        case R.id.radioButton_arma_op2:
240
                            MyArmaRssiFilter.setArmaSpeed(0.25D);
241
                            break:
242
                        case R.id.radioButton_arma_op3:
243
                            MyArmaRssiFilter.setArmaSpeed(0.5D);
244
245
                    }
246
                    selectOption.append(" - Speed ").append(MyArmaRssiFilter.getArmaSpeed());
247
248
249
                    MyArmaRssiFilter.enableArmaFilter(true);
250
                    BeaconManager.setRssiFilterImplClass(MyArmaRssiFilter.class);
251
252
253
                case R.id.radioButton_average_rssi_filter:
254
255
                    setArmaOptionsVisible(false);
256
                    setAvgOptionsVisible(true);
257
258
                    selectOption.append("AVG RSSI filter");
259
260
                    int avgOption = preferences.getInt(SettingConstants.AVG OPTION, 0);
261
262
                    long sampleExpirationMilliseconds = 0;
```

```
263
264
                     switch (avgOption) {
265
                        case 0:
266
                        case R.id.radioButton_avg_op1:
2.67
                             sampleExpirationMilliseconds = 20000L;
268
269
                        case R.id.radioButton_avg_op2:
270
                             sampleExpirationMilliseconds = 10000L;
271
2.72
                        case R.id.radioButton_avg_op3:
273
                             sampleExpirationMilliseconds = 5000L;
274
                             break:
275
                    }
276
277
                     selectOption.append(" - ").append(sampleExpirationMilliseconds).append(" ms");
278
279
                    RunningAverageRssiFilter.setSampleExpirationMilliseconds(sampleExpirationMilliseconds);
280
                    BeaconManager.setRssiFilterImplClass(RunningAverageRssiFilter.class);
281
                    break;
283
284
            rssiFilterSelected = String.valueOf(selectOption);
285
```

6.1.2.13 setSettingsVisible()

```
void it.unibo.torsello.bluetoothpositioning.activities.ApplicationActivity.setSettingsVisible
(
               final boolean scanStarted ) [private]
148
            runOnUiThread(new Runnable() {
149
150
                @Override
151
                public void run() {
152
                    if (!scanStarted) {
                        \verb|findViewById(R.id.text\_setting\_disabled).setVisibility(View.VISIBLE);|
153
154
                        findViewById (R.id.nested setting).setVisibility (View.GONE);
155
                        findViewById(R.id.text_setting_disabled).setVisibility(View.GONE);
156
157
                        findViewById(R.id.nested_setting).setVisibility(View.VISIBLE);
158
```

6.1.3 Documentazione dei membri dato

6.1.3.1 backgroundPowerSaver

});

 $\label{thm:backgroundPowerSaver} BackgroundPowerSaver it.unibo.torsello.bluetoothpositioning.activities. ApplicationActivity. \\ \leftarrow backgroundPowerSaver [private]$

6.1.3.2 beaconManager

159

160 161

BeaconManager it.unibo.torsello.bluetoothpositioning.activities.ApplicationActivity.beacon←
Manager [private]

6.1.3.3 deviceList

List<Device> it.unibo.torsello.bluetoothpositioning.activities.ApplicationActivity.deviceList [private]

6.1.3.4 isRunScan

boolean it.unibo.torsello.bluetoothpositioning.activities.ApplicationActivity.isRunScan =
false [private]

6.1.3.5 myDeviceObservable

DeviceObservable it.unibo.torsello.bluetoothpositioning.activities.ApplicationActivity.my← DeviceObservable [private]

6.1.3.6 preferences

 $Shared Preferences\ it.unibo.torsello.bluetooth positioning.activities. Application Activity. \hookleftarrow preferences\ [private]$

6.1.3.7 rssiFilterSelected

String it.unibo.torsello.bluetoothpositioning.activities.ApplicationActivity.rssiFilter \leftarrow Selected [private]

6.1.3.8 usbUtil

UsbUtil it.unibo.torsello.bluetoothpositioning.activities.ApplicationActivity.usbUtil [private]

La documentazione per questa classe è stata generata a partire dal seguente file:

· ApplicationActivity.java

6.2 Riferimenti per la classe it.unibo.torsello.bluetoothpositioning.fragment.CameraFragment

Diagramma delle classi per it.unibo.torsello.bluetoothpositioning.fragment.CameraFragment

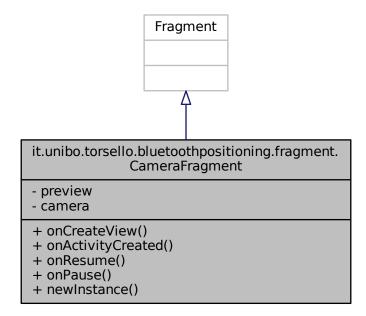
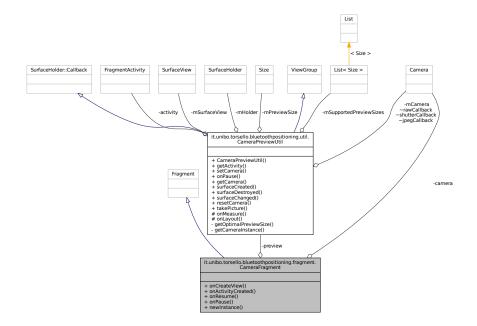


Diagramma di collaborazione per it.unibo.torsello.bluetoothpositioning.fragment.CameraFragment:



Membri pubblici

- View onCreateView (LayoutInflater inflater, ViewGroup container, Bundle savedInstanceState)
- void onActivityCreated (@Nullable Bundle savedInstanceState)
- void onResume ()
- void onPause ()

Membri pubblici statici

• static CameraFragment newInstance ()

Attributi privati

- CameraPreviewUtil preview
- · Camera camera

6.2.1 Descrizione dettagliata

Created by Federico Torsello. federico.torsello@studio.unibo.it

6.2.2 Documentazione delle funzioni membro

6.2.2.1 newInstance()

6.2.2.2 onActivityCreated()

```
void\ it.unibo.torsello.bluetooth positioning.fragment.Camera Fragment.on Activity Created\ (it.unibo.torsello.bluetooth positioning.fragment.on Camera Fragment.on Camera
                                @Nullable Bundle savedInstanceState )
                        super.onActivityCreated(savedInstanceState);
73
74
                        getActivity().findViewById(R.id.fab_camera).setOnClickListener(new View.OnClickListener() {
75
                                 @Override
76
                                 public void onClick(View v) {
                                         preview.takePicture();
78
79
                        });
80
81
6.2.2.3 onCreateView()
View it.unibo.torsello.bluetoothpositioning.fragment.CameraFragment.onCreateView (
                                LayoutInflater inflater,
                                ViewGroup container,
                                Bundle savedInstanceState )
31
32
33
                        View root = inflater.inflate(R.layout.fragment_camera, container, false);
34
                        preview = new CameraPreviewUtil(getContext(), (SurfaceView) root.findViewById(R.id.
             surfaceView));
                         ((FrameLayout) root.findViewById(R.id.layout)).addView(preview);
35
36
                        preview.setKeepScreenOn(true);
                        preview.setOnClickListener(new OnClickListener() {
37
38
39
                                 @Override
40
                                 public void onClick(View arg0) {
41 //
                                              preview.takePicture();
42
                                          camera.autoFocus(new Camera.AutoFocusCallback() {
43
                                                  @Override
                                                  public void onAutoFocus(boolean success, Camera arg1) {
45 //
                                                                if (success) {
46
                                                                        preview.takePicture();
47 //
48
                                                  }
49
                                         });
50
                                }
52
                        preview.setOnLongClickListener(new View.OnLongClickListener() {
53
                                 @Override
                                 public boolean onLongClick(View arg0) {
54
55
56
                                          camera.autoFocus(new Camera.AutoFocusCallback() {
                                                  @Override
58
                                                  public void onAutoFocus(boolean success, Camera arg1) {
59 //
                                                                if (success)
60 //
                                                                         preview.takePicture();
61 //
62
                                                  }
63
                                          });
64
65
66
                        });
                        return root;
67
68
6.2.2.4 onPause()
void it.unibo.torsello.bluetoothpositioning.fragment.CameraFragment.onPause ( )
91
92
                        preview.onPause();
93
                        super.onPause();
94
```

6.2.2.5 onResume()

```
\verb|void it.unibo.torsello.bluetoothpositioning.fragment.CameraFragment.onResume ()|\\
```

6.2.3 Documentazione dei membri dato

6.2.3.1 camera

Camera it.unibo.torsello.bluetoothpositioning.fragment.CameraFragment.camera [private]

6.2.3.2 preview

```
CameraPreviewUtil it.unibo.torsello.bluetoothpositioning.fragment.CameraFragment.preview [private]
```

La documentazione per questa classe è stata generata a partire dal seguente file:

• CameraFragment.java

6.3 Riferimenti per la classe it.unibo.torsello.bluetoothpositioning.util.CameraPreviewUtil

 $Diagramma\ delle\ classi\ per\ it.unibo.torsello.bluetoothpositioning.util. Camera Preview Util$

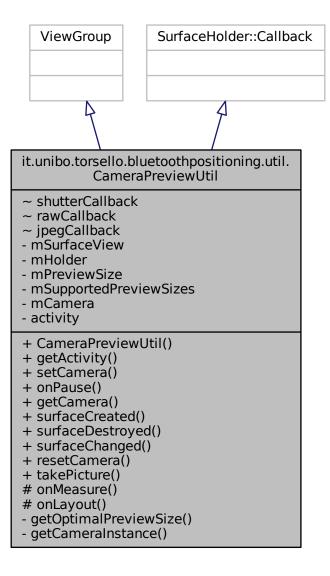
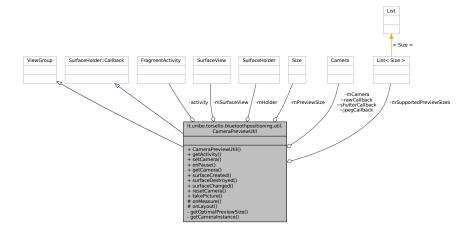


Diagramma di collaborazione per it.unibo.torsello.bluetoothpositioning.util.CameraPreviewUtil:



Membri pubblici

- CameraPreviewUtil (Context context, SurfaceView sv)
- FragmentActivity getActivity ()
- void setCamera (FragmentActivity fragmentActivity)
- void onPause ()
- Camera getCamera ()
- void surfaceCreated (SurfaceHolder holder)
- void surfaceDestroyed (SurfaceHolder holder)
- void surfaceChanged (SurfaceHolder holder, int format, int w, int h)
- void resetCamera ()
- void takePicture ()

Membri protetti

- void onMeasure (int widthMeasureSpec, int heightMeasureSpec)
- void onLayout (boolean changed, int I, int t, int r, int b)

Attributi con visibilità di package

- · Camera.ShutterCallback shutterCallback
- Camera.PictureCallback rawCallback
- Camera.PictureCallback jpegCallback

Membri privati

Size getOptimalPreviewSize (List< Size > sizes, int w, int h)

Membri privati statici

• static Camera getCameraInstance ()

Attributi privati

- SurfaceView mSurfaceView
- SurfaceHolder mHolder
- Size mPreviewSize
- List< Size > mSupportedPreviewSizes
- Camera mCamera
- · FragmentActivity activity

6.3.1 Descrizione dettagliata

Created by Federico Torsello. federico.torsello@studio.unibo.it

6.3.2 Documentazione dei costruttori e dei distruttori

6.3.2.1 CameraPreviewUtil()

6.3.3 Documentazione delle funzioni membro

6.3.3.1 getActivity()

```
Fragment Activity it.unibo.torsello.blue to oth positioning.util. Camera Preview Util.get Activity () \\
```

6.3.3.2 getCamera()

Camera it.unibo.torsello.bluetoothpositioning.util.CameraPreviewUtil.getCamera ()

6.3.3.3 getCameraInstance()

```
static Camera it.unibo.torsello.bluetoothpositioning.util.CameraPreviewUtil.getCameraInstance
( ) [static], [private]
```

A safe way to get an instance of the CameraUtil object.

```
88
89
90
           Camera c = null;
91
92
           try {
93
               int numCams = Camera.getNumberOfCameras();
94
               if (numCams > 0) {
                   c = Camera.open(0); // attempt to get a CameraUtil instance
95
96
           } catch (RuntimeException e) {
98
               // CameraUtil is not available (in use or does not exist)
99
               e.getStackTrace();
100
101
            return c; // returns null if camera is unavailable
102
103
```

6.3.3.4 getOptimalPreviewSize()

```
Size it.unibo.torsello.bluetoothpositioning.util.CameraPreviewUtil.getOptimalPreviewSize (
               List < Size > sizes,
               int w,
               int h ) [private]
169
170
            final double ASPECT_TOLERANCE = 0.1;
            double targetRatio = (double) w / h;
if (sizes == null) return null;
171
172
173
174
            Size optimalSize = null;
175
            double minDiff = Double.MAX_VALUE;
176
177 //
              int targetHeight = h;
178
179
             // Try to find an size match aspect ratio and size
180
             for (Size size : sizes) {
181
                 double ratio = (double) size.width / size.height;
182
                 if (Math.abs(ratio - targetRatio) > ASPECT_TOLERANCE) continue;
                 if (Math.abs(size.height - h) < minDiff) {</pre>
183
184
                     optimalSize = size;
                     minDiff = Math.abs(size.height - h);
185
186
                 }
187
188
             \ensuremath{//} Cannot find the one match the aspect ratio, ignore the requirement
189
             if (optimalSize == null) {
190
                 minDiff = Double.MAX_VALUE;
191
192
                 for (Size size : sizes) {
193
                     if (Math.abs(size.height - h) < minDiff) {</pre>
194
                          optimalSize = size;
                          minDiff = Math.abs(size.height - h);
195
196
                     }
197
                 }
198
             return optimalSize;
200
```

6.3.3.5 onLayout()

```
void it.unibo.torsello.bluetoothpositioning.util.CameraPreviewUtil.onLayout (
               boolean changed,
               int l,
               int t,
               int r.
               int b)
                          [protected]
120
                                                                                  {
121
             if (changed && getChildCount() > 0) {
122
                 final View child = getChildAt(0);
123
                 final int width = r - 1;
final int height = b - t;
124
125
126
127
                 int previewWidth = width;
128
                 int previewHeight = height;
129
                 if (mPreviewSize != null) {
130
                     previewWidth = mPreviewSize.width;
131
                     previewHeight = mPreviewSize.height;
132
133
134
                 // Center the child SurfaceView within the parent.
135
                 if (width * previewHeight > height * previewWidth) {
                     final int scaledChildWidth = previewWidth * height / previewHeight;
child.layout((width - scaledChildWidth) / 2, 0,
136
137
138
                              (width + scaledChildWidth) / 2, height);
139
                 } else {
140
                     final int scaledChildHeight = previewHeight * width / previewWidth;
                     141
142
143
144
145
6.3.3.6 onMeasure()
void it.unibo.torsello.bluetoothpositioning.util.CameraPreviewUtil.onMeasure (
               int widthMeasureSpec,
                int heightMeasureSpec ) [protected]
106
107
             // We purposely disregard child measurements because act as a
108
             // wrapper to a SurfaceView that centers the camera preview instead
             // of stretching it.
109
             final int width = resolveSize(getSuggestedMinimumWidth(), widthMeasureSpec);
final int height = resolveSize(getSuggestedMinimumHeight(), heightMeasureSpec);
110
111
             setMeasuredDimension(width, height);
112
113
             if (mSupportedPreviewSizes != null) {
114
                 mPreviewSize = getOptimalPreviewSize(
      mSupportedPreviewSizes, width, height);
116
117
6.3.3.7 onPause()
void it.unibo.torsello.bluetoothpositioning.util.CameraPreviewUtil.onPause ( )
73
74
            if (mCamera != null) {
75
                mCamera.stopPreview();
76
                mCamera.release();
77
                mCamera = null;
78
79
       }
```

6.3.3.8 resetCamera()

```
void it.unibo.torsello.bluetoothpositioning.util.CameraPreviewUtil.resetCamera ( )
215
216
           new Thread(new Runnable() {
217
               @Override
218
               public void run() {
219
                   mCamera.startPreview();
220
221
           }).start();
222
223
224
       }
6.3.3.9 setCamera()
void it.unibo.torsello.bluetoothpositioning.util.CameraPreviewUtil.setCamera (
              FragmentActivity fragmentActivity )
45
46
          this.activity = fragmentActivity;
47
48
```

```
mCamera = getCameraInstance();
49
           } catch (RuntimeException ex) {
51
               Toast.makeText(fragmentActivity, "camera_not_found", Toast.LENGTH_LONG).show();
52
           }
53
54
           if (mCamera != null) {
55
               mSupportedPreviewSizes = mCamera.getParameters().
56
      getSupportedPreviewSizes();
57
               requestLayout();
58
59
               // get Camera parameters
60
               Camera.Parameters params = mCamera.getParameters();
               List<String> focusModes = params.getSupportedFocusModes();
62
               if (focusModes.contains(Camera.Parameters.FOCUS_MODE_AUTO)) {
64
                    \ensuremath{//} set the focus mode
                   params.setFocusMode(Camera.Parameters.FOCUS_MODE_AUTO);
6.5
66
                    // set Camera parameters
67
                   mCamera.setParameters(params);
69
           }
70
71
       }
```

6.3.3.10 surfaceChanged()

```
SurfaceHolder holder,
           int format,
           int w_{,}
           int h)
203
204
         if (mCamera != null) {
205
            Camera.Parameters parameters = mCamera.getParameters();
206
            parameters.setPreviewSize(mPreviewSize.width,
    mPreviewSize.height);
207
            requestLayout();
208
209
            mCamera.setParameters(parameters);
211
            resetCamera();
212
      }
213
```

6.3.3.11 surfaceCreated()

```
SurfaceHolder holder )
148
149
          // The Surface has been created, acquire the camera and tell it where
          // to draw.
150
151
          try {
             if (mCamera != null) {
152
153
                 mCamera.setDisplayOrientation(90);
154
                 mCamera.setPreviewDisplay(holder);
155
          } catch (IOException exception) {
    Log.e(TAG, "IOException caused by setPreviewDisplay()", exception);
156
157 //
158
159
```

6.3.3.12 surfaceDestroyed()

6.3.3.13 takePicture()

```
void it.unibo.torsello.bluetoothpositioning.util.CameraPreviewUtil.takePicture ( )

246
247
248
mCamera.takePicture(shutterCallback, rawCallback,
jpegCallback);
249
}
```

6.3.4 Documentazione dei membri dato

6.3.4.1 activity

FragmentActivity it.unibo.torsello.bluetoothpositioning.util.CameraPreviewUtil.activity [private]

6.3.4.2 jpegCallback

 $\label{local_camera_previewUtil.jpeg} Camera. Picture Callback it.unibo.torsello.bluetoothpositioning.util. Camera Preview Util.jpeg \\ Callback [package]$

Valore iniziale:

```
= new Camera.PictureCallback() {
    public void onPictureTaken(byte[] data, final Camera camera) {
        new SaveImageTask(getActivity()).execute(data);

        resetCamera();
    }
}
```

6.3.4.3 mCamera

Camera it.unibo.torsello.bluetoothpositioning.util.CameraPreviewUtil.mCamera [private]

6.3.4.4 mHolder

SurfaceHolder it.unibo.torsello.bluetoothpositioning.util.CameraPreviewUtil.mHolder [private]

6.3.4.5 mPreviewSize

Size it.unibo.torsello.bluetoothpositioning.util.CameraPreviewUtil.mPreviewSize [private]

6.3.4.6 mSupportedPreviewSizes

List<Size> it.unibo.torsello.bluetoothpositioning.util.CameraPreviewUtil.mSupportedPreview← Sizes [private]

6.3.4.7 mSurfaceView

SurfaceView it.unibo.torsello.bluetoothpositioning.util.CameraPreviewUtil.mSurfaceView [private]

6.3.4.8 rawCallback

Camera.PictureCallback it.unibo.torsello.bluetoothpositioning.util.CameraPreviewUtil.raw← Callback [package]

Valore iniziale:

```
= new Camera.PictureCallback() {
    public void onPictureTaken(byte[] data, Camera camera) {
    }
}
```

6.3.4.9 shutterCallback

Camera.ShutterCallback it.unibo.torsello.bluetoothpositioning.util.CameraPreviewUtil.shutter← Callback [package]

Valore iniziale:

```
= new Camera.ShutterCallback() {
    public void onShutter() {
     }
}
```

La documentazione per questa classe è stata generata a partire dal seguente file:

• CameraPreviewUtil.java

6.4 Riferimenti per la classe it.unibo.torsello.bluetoothpositioning.util.ChartUtil

Diagramma delle classi per it.unibo.torsello.bluetoothpositioning.util.ChartUtil

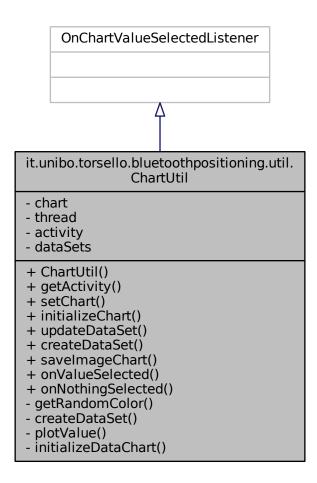
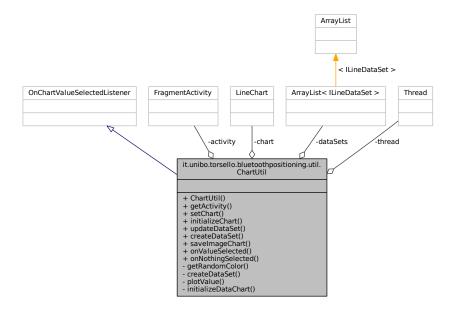


Diagramma di collaborazione per it.unibo.torsello.bluetoothpositioning.util.ChartUtil:



Membri pubblici

- · ChartUtil (FragmentActivity fragmentActivity)
- FragmentActivity getActivity ()
- void setChart (LineChart chart)
- · void initializeChart ()
- void updateDataSet (final ArrayList< Double > doubleArrayList)
- void createDataSet (ArrayList< String > args)
- void savelmageChart (String chartName, String formattedDate)
- void onValueSelected (Entry e, Highlight h)
- · void onNothingSelected ()

Membri privati

- int getRandomColor ()
- LineDataSet createDataSet (String nameDataSet, int color)
- void plotValue (LineData data, int index, Double value)
- void initializeDataChart (ArrayList< ILineDataSet > dataSets)

Attributi privati

- · LineChart chart
- Thread thread
- · FragmentActivity activity
- ArrayList < ILineDataSet > dataSets

6.4.1 Descrizione dettagliata

Created by Federico Torsello. federico.torsello@studio.unibo.it

6.4.2 Documentazione dei costruttori e dei distruttori

```
6.4.2.1 ChartUtil()
```

6.4.3 Documentazione delle funzioni membro

```
6.4.3.1 createDataSet() [1/2]
```

```
void it.unibo.torsello.bluetoothpositioning.util.ChartUtil.createDataSet (
                 ArrayList< String > args )
134
135
              // create a dataset and give it a type
136
              for (String s : args) {
138
                   if (s != null) {
139
                        if (s.equals(getActivity().getString(R.string.chart_arduino))) {
140
                            dataSets.add(createDataSet(s, Color.RED));
                        } else if (s.equals(getActivity().getString(R.string.chart_raw_distance))) {
    dataSets.add(createDataSet(s, Color.GREEN));
} else if (s.equals(getActivity().getString(R.string.chart_altbeacon))) {
141
142
143
144
                            dataSets.add(createDataSet(s, Color.BLUE));
145
                        } else if (s.equals(getActivity().getString(R.string.chart_kalman_filter))) {
146
                            dataSets.add(createDataSet(s, Color.CYAN));
                        } else {
147
                            dataSets.add(createDataSet(s,
148
       getRandomColor());
149
150
151
152
         }
153
```

6.4.3.2 createDataSet() [2/2]

6.4.3.3 getActivity()

```
\label{thm:continuity} Fragment Activity it.unibo.torsello.blue to oth positioning.util. Chart Util.get Activity () \\
```

```
46
47 return activity;
48 }
```

6.4.3.4 getRandomColor()

```
int it.unibo.torsello.bluetoothpositioning.util.ChartUtil.getRandomColor ( ) [private]
156
            Random rnd = new Random();
157
            return Color.argb(255, rnd.nextInt(255), rnd.nextInt(255));
158
6.4.3.5 initializeChart()
\verb|void| it.unibo.torsello.bluetoothpositioning.util.ChartUtil.initializeChart ( ) \\
55
           dataSets = new ArrayList<>();
56
           chart.setOnChartValueSelectedListener(this);
57
58
59
           // no description text
60
           chart.setDescription("");
61
           chart.setNoDataTextDescription("You need to provide data for the chart.");
62
63
           chart.setDrawGridBackground(true);
64
65
           // if disabled, scaling can be done on x- and y-axis separately
           chart.setPinchZoom(true);
67
68
           // set an alternative background color
69
           chart.setBackgroundColor(Color.LTGRAY);
70
71
           Typeface mTfLight = Typeface.createFromAsset(getActivity().getAssets(), "
      OpenSans-Light.ttf");
72
           Typeface mTfBold = Typeface.createFromAsset(getActivity().getAssets(), "
      OpenSans-Bold.ttf");
73
74
           // get the legend (only possible after setting data)
75
           Legend 1 = chart.getLegend();
             1.setPosition(Legend.LegendPosition.RIGHT_OF_CHART);
76 //
77
             1.setOrientation(Legend.LegendOrientation.VERTICAL);
78
           1.setXEntrySpace(7f);
79
           1.setYEntrySpace(7f);
80
           XAxis xl = chart.getXAxis();
81
           xl.setTypeface(mTfLight);
82
           xl.setGridColor(Color.LTGRAY);
83
84
           xl.setTextColor(Color.WHITE);
85
           YAxis leftAxis = chart.getAxisLeft();
leftAxis.setTypeface(mTfLight);
86
87
           leftAxis.setTextColor(Color.WHITE);
88
89
90
           YAxis rightAxis = chart.getAxisRight();
91
           rightAxis.setTypeface(mTfBold);
92
93
6.4.3.6 initializeDataChart()
void\ it.unibo.torsello.bluetoothpositioning.util.ChartUtil.initializeDataChart\ (
               ArrayList < ILineDataSet > dataSets ) [private]
185
186
187
            // create a data object with the datasets
188
            LineData lineData = new LineData(dataSets);
189
            lineData.setValueTextColor(Color.RED);
            lineData.setValueTextSize(9f):
190
191
            lineData.setValueFormatter(new DefaultValueFormatter(2));
192
193
             // set data
194
            chart.setData(lineData);
195
        }
```

6.4.3.7 onNothingSelected()

204

```
\verb|void| it.unibo.torsello.bluetoothpositioning.util.ChartUtil.onNothingSelected ()|\\
213
              Log.i("Nothing selected", "Nothing selected.");
214 //
215
6.4.3.8 onValueSelected()
void it.unibo.torsello.bluetoothpositioning.util.ChartUtil.onValueSelected (
              Entry e,
              Highlight h)
207
208
            Snackbar.make(getActivity().findViewById(R.id.fab), e.copy() + " selected"
209
                   , Snackbar.LENGTH_SHORT).show();
210
6.4.3.9 plotValue()
void it.unibo.torsello.bluetoothpositioning.util.ChartUtil.plotValue (
              LineData data,
              int index,
              Double value ) [private]
166
167
168
            ILineDataSet set = data.getDataSetByIndex(index);
169
170
            set.addEntry(new Entry(set.getEntryCount(), value.floatValue()));
171
172
            data.notifyDataChanged();
173
174
            // let the chart know it's data has changed
175
            chart.notifyDataSetChanged();
176
177
            \ensuremath{//} limit the number of visible entries
178
            chart.setVisibleXRangeMaximum(10);
179
180
            // move to the latest entry
181
            chart.moveViewToX(data.getEntryCount());
182
183
6.4.3.10 saveImageChart()
void it.unibo.torsello.bluetoothpositioning.util.ChartUtil.saveImageChart (
              String chartName,
              String formattedDate )
197
198
            String nameImage = chartName + " " + System.currentTimeMillis();
199
            chart.saveToGallery(nameImage, chartName
200
                    + " - " + formattedDate, null, Bitmap.CompressFormat.JPEG, 100);
201
            Snackbar.make(getActivity().findViewById(R.id.fab), chartName + " stored"
202
                    , Snackbar.LENGTH_SHORT).show();
203
```

6.4.3.11 setChart()

6.4.3.12 updateDataSet()

```
final ArrayList< Double > doubleArrayList )
9.5
                                                                         {
96
          if (thread != null)
97
               thread.interrupt();
98
          thread = new Thread(new Runnable() {
100
               @Override
101
               public void run() {
102
                   if (getActivity() != null) {
103
                       getActivity().runOnUiThread(new Runnable() {
104
105
                           @Override
106
                           public void run() {
107
108
                               LineData data = chart.getData();
                               if (data == null) {
   if (dataSets != null) {
     initializeDataChart(
109
110
111
      dataSets);
112
113
                                       throw new Error("Error: dataSet is null!!!");
114
115
                               } else {
                                   if (data.getDataSetCount() > 0) {
116
117
118 //
                                         Log.i("miao", data.getDataSetCount() +" ");
119
                                       for (int i = 0; i < doubleArrayList.size(); i++) {</pre>
120
                                           plotValue(data, i, doubleArrayList.get(i));
121
122
123
124
                              }
125
                      });
126
                   }
127
128
               }
129
            });
130
131
            thread.start();
132
       }
```

6.4.4 Documentazione dei membri dato

6.4.4.1 activity

FragmentActivity it.unibo.torsello.bluetoothpositioning.util.ChartUtil.activity [private]

6.4.4.2 chart

LineChart it.unibo.torsello.bluetoothpositioning.util.ChartUtil.chart [private]

6.4.4.3 dataSets

ArrayList<!LineDataSet> it.unibo.torsello.bluetoothpositioning.util.ChartUtil.dataSets [private]

6.4.4.4 thread

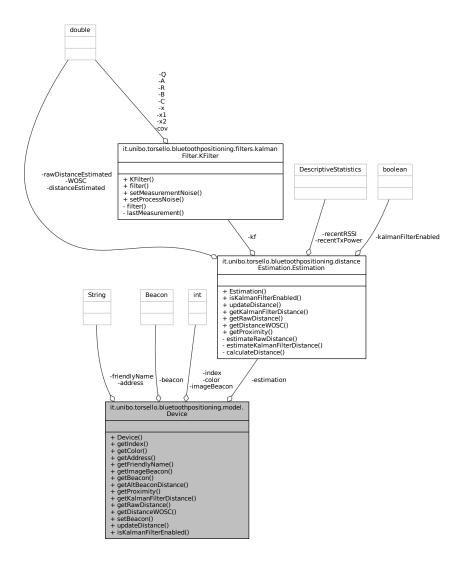
Thread it.unibo.torsello.bluetoothpositioning.util.ChartUtil.thread [private]

La documentazione per questa classe è stata generata a partire dal seguente file:

· ChartUtil.java

6.5 Riferimenti per la classe it.unibo.torsello.bluetoothpositioning.model.Device

Diagramma di collaborazione per it.unibo.torsello.bluetoothpositioning.model.Device:



Membri pubblici

- Device (int index, String address, String friendlyName, Integer color, Integer imageBeacon)
- int getIndex ()
- Integer getColor ()

- String getAddress ()
- String getFriendlyName ()
- Integer getImageBeacon ()
- Beacon getBeacon ()
- double getAltBeaconDistance ()
- String getProximity ()
- double getKalmanFilterDistance ()
- double getRawDistance ()
- double getDistanceWOSC ()
- void setBeacon (Beacon beacon)
- void updateDistance (double processNoise)
- boolean isKalmanFilterEnabled ()

Attributi privati

- · Estimation estimation
- String address
- String friendlyName
- Beacon beacon
- · int imageBeacon
- int color
- · int index

6.5.1 Descrizione dettagliata

Created by Federico Torsello. federico.torsello@studio.unibo.it

6.5.2 Documentazione dei costruttori e dei distruttori

6.5.2.1 Device()

6.5.3 Documentazione delle funzioni membro

6.5.3.1 getAddress()

```
6.5.3.2 getAltBeaconDistance()
```

```
{\tt double\ it.unibo.torsello.bluetoothpositioning.model.Device.getAltBeaconDistance\ (\ )}
54
55
          return beacon.getDistance();
6.5.3.3 getBeacon()
{\tt Beacon\ it.unibo.torsello.bluetoothpositioning.model.Device.getBeacon\ (\ )}
          return beacon;
6.5.3.4 getColor()
Integer\ it.unibo.torsello.bluetoothpositioning.model.Device.getColor\ (\ )
          return color;
36
6.5.3.5 getDistanceWOSC()
double it.unibo.torsello.bluetoothpositioning.model.Device.getDistanceWOSC ( )
76
77
          return estimation.getDistanceWOSC();
6.5.3.6 getFriendlyName()
String it.unibo.torsello.bluetoothpositioning.model.Device.getFriendlyName ( )
          return friendlyName;
43
6.5.3.7 getImageBeacon()
Integer\ it.unibo.torsello.bluetoothpositioning.model.Device.getImageBeacon\ (\ )
          return imageBeacon;
```

```
6.5.3.8 getIndex()
```

```
int it.unibo.torsello.bluetoothpositioning.model.Device.getIndex ( )
31
          return index;
32
6.5.3.9 getKalmanFilterDistance()
{\tt double\ it.unibo.torsello.bluetoothpositioning.model.Device.getKalmanFilterDistance\ (\ )}
           if (!estimation.isKalmanFilterEnabled()) {
64
65
              return 0;
66
          return estimation.getKalmanFilterDistance();
68
6.5.3.10 getProximity()
String it.unibo.torsello.bluetoothpositioning.model.Device.getProximity ( )
          return estimation.getProximity();
6.5.3.11 getRawDistance()
{\tt double\ it.unibo.torsello.bluetoothpositioning.model.Device.getRawDistance\ (\ )}
          return estimation.getRawDistance();
6.5.3.12 isKalmanFilterEnabled()
\verb|boolean| it.unibo.torsello.bluetoothpositioning.model.Device.isKalmanFilterEnabled ()|
89
          return estimation.isKalmanFilterEnabled();
90
6.5.3.13 setBeacon()
\verb|void it.unibo.torsello.bluetoothpositioning.model.Device.setBeacon | (
              Beacon beacon )
80
          this.beacon = beacon;
81
```

6.5.3.14 updateDistance()

6.5.4 Documentazione dei membri dato

6.5.4.1 address

String it.unibo.torsello.bluetoothpositioning.model.Device.address [private]

6.5.4.2 beacon

Beacon it.unibo.torsello.bluetoothpositioning.model.Device.beacon [private]

6.5.4.3 color

int it.unibo.torsello.bluetoothpositioning.model.Device.color [private]

6.5.4.4 estimation

Estimation it.unibo.torsello.bluetoothpositioning.model.Device.estimation [private]

6.5.4.5 friendlyName

String it.unibo.torsello.bluetoothpositioning.model.Device.friendlyName [private]

6.5.4.6 imageBeacon

 $\verb|int it.unibo.torsello.bluetoothpositioning.model.Device.imageBeacon [private]|\\$

6.5.4.7 index

int it.unibo.torsello.bluetoothpositioning.model.Device.index [private]

La documentazione per questa classe è stata generata a partire dal seguente file:

Device.java

6.6 Riferimenti per la classe it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter

Diagramma delle classi per it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter

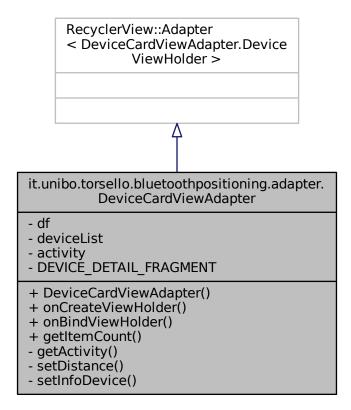
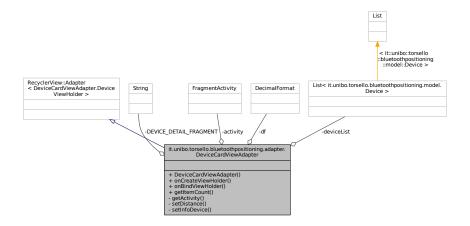


Diagramma di collaborazione per it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter:



Composti

• class DeviceViewHolder

Membri pubblici

- DeviceCardViewAdapter (final FragmentActivity fragmentActivity, List< Device > deviceList)
- DeviceViewHolder onCreateViewHolder (ViewGroup parent, int viewType)
- void onBindViewHolder (DeviceViewHolder holder, final int position)
- int getItemCount ()

Membri privati

- FragmentActivity getActivity ()
- · void setDistance (DeviceViewHolder holder, Device device)
- · void setInfoDevice (DeviceViewHolder holder, Beacon beacon)

Attributi privati

- DecimalFormat df
- List< Device > deviceList
- · FragmentActivity activity

Attributi privati statici

• static final String DEVICE_DETAIL_FRAGMENT = "device detail"

6.6.1 Descrizione dettagliata

Created by Federico Torsello. federico.torsello@studio.unibo.it

6.6.2 Documentazione dei costruttori e dei distruttori

6.6.2.1 DeviceCardViewAdapter()

6.6.3 Documentazione delle funzioni membro

6.6.3.1 getActivity()

```
FragmentActivity it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.get←
Activity ( ) [private]

47
48 return activity;
```

6.6.3.2 getItemCount()

6.6.3.3 onBindViewHolder()

```
void it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.onBindViewHolder (
               DeviceViewHolder holder,
               final int position )
61
62
           final Beacon beacon = deviceList.get(position).getBeacon();
63
           final Device device = deviceList.get(position);
64
65
           setInfoDevice(holder, beacon);
67
           setDistance(holder, device);
68
69
           final Integer imageBeacon = device.getImageBeacon();
70
           if (imageBeacon != null) {
71
               holder.imageView.setImageResource(imageBeacon);
73
               holder.imageView.setImageResource(R.drawable.beacon_unknown);
74
           }
75
           holder.rssiTextView.setText(String.format("%sdb", beacon.getTxPower()));
76
78
           holder.txPowerTextView.setText(String.format("%sdb", beacon.getRssi()));
79
80
           final String friendlyName = device.getFriendlyName();
81
           if (friendlyName != null) {
               holder.friendlyNameTextView.setText(friendlyName);
82
83
           } else {
               holder.friendlyNameTextView.setText(android.R.string.unknownName);
85
86
87
           final String bluetoothName = beacon.getBluetoothName();
88
           if (bluetoothName != null) {
89
               holder.defaultNameTextView.setText(bluetoothName);
90
               holder.defaultNameTextView.setText(android.R.string.unknownName);
93
94
           final String macAddress = beacon.getBluetoothAddress();
95
           if (macAddress != null) {
96
               holder.macTextView.setText(macAddress);
98
               holder.macTextView.setText(android.R.string.unknownName);
99
           }
100
101
            final String proximity = device.getProximity();
102
            if (proximity != null) {
103
                holder.proximityTextView.setText(proximity);
104
105
                holder.proximityTextView.setText(android.R.string.unknownName);
106
            }
107
108
            final Integer color = device.getColor();
109
            if (color != null) {
                holder.colorTextView.setText(color);
110
111
112
                holder.colorTextView.setText(android.R.string.unknownName);
            }
113
114
            holder.view.setOnClickListener(new View.OnClickListener() {
115
116
                @Override
                public void onClick(View v)
                    final String deviceDetailName;
if (device.getFriendlyName() != null) {
118
119
120
                        deviceDetailName = device.getFriendlyName();
121
                     } else {
```

deviceDetailName = device.getAddress();

122

```
123
                      }
124
125
                      new Thread(new Runnable() {
126
                          @Override
127
                          public void run() {
128
                              getActivity().runOnUiThread(new Runnable() {
129
                                   @Override
130
                                   public void run() {
131
132
                                       Fragment currentFrag = getActivity().getSupportFragmentManager()
                                                .findFragmentByTag(
133
      DEVICE DETAIL FRAGMENT):
134
135
                                       if (currentFrag == null) {
136
                                           getActivity().getSupportFragmentManager().beginTransaction()
137
                                                    .replace(R.id.contentMainLayout,
                                                             DeviceDetailFragment.newInstance(deviceDetailName), DEVICE_DETAIL_FRAGMENT)
138
139
140
                                                    .commit();
141
142
                              });
143
144
                     }).start();
145
146
                 }
147
            });
148
```

6.6.3.4 onCreateViewHolder()

6.6.3.5 setDistance()

```
void it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.setDistance (
              DeviceViewHolder holder,
              Device device ) [private]
150
           holder.altbeaconDistanceTextView.setText(String.format("%sm", df.format(device.
151
      getAltBeaconDistance()));
152
153
           holder.standardRawDistanceTextView.setText(String.format("%sm", df.format(device.getRawDistance()
      )));
154
            if (!device.isKalmanFilterEnabled()){
155
               holder.kalmanFilterDistanceTextView.setText(getActivity().getText(R.string.
156
      kalman_filter_disabled));
157
158
               holder.kalmanFilterDistanceTextView.setText(String.format("%s", df.format(device.
      getKalmanFilterDistance()));
159
           }
160
```

6.6.3.6 setInfoDevice()

```
\verb|void it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.setInfoDevice (in the context of 
                             DeviceViewHolder holder,
                             Beacon beacon ) [private]
162
                                                                                                                                                        {
163
                        if (beacon.getServiceUuid() == 0xfeaa) {
164
165
                                holder.visibilityUUIDLinearLayout.setVisibility(View.GONE);
166
                                holder.visibilityNameSpaceLinearLayout.setVisibility(View.VISIBLE);
167
168
                                if (beacon.getBeaconTypeCode() == 0x00) {
169
                                         // Eddystone-UID
170
                                         if (beacon.getId1() != null) {
171
                                                holder.nameSpaceTextView.setText(beacon.getId1().toString());
172
173
                                                holder.nameSpaceTextView.setText(android.R.string.unknownName);
                                        }
174
175
176
                                        if (beacon.getId2() != null) {
177
                                                holder.instanceTextView.setText(beacon.getId2().toString());
178
179
                                                \verb|holder.instanceTextView.setText(and roid.R.string.unknownName)|;\\
180
181
182
                                } else if (beacon.getBeaconTypeCode() == 0x10) {
183
                                         // Eddystone-URL
184
                                         // String url = UrlBeaconUrlCompressor.uncompress(beacon.getId1().toByteArray());
185
                                } else if (beacon.getBeaconTypeCode() == 0x20) {
186
                                        if (!beacon.getExtraDataFields().isEmpty()) {
187
                                                // Eddystone-TLM
188
                                         }
189
190
                        } else if (beacon.getServiceUuid() == 0xbeac) {
191
                                // AltBeacon
192
                        else if (beacon.getBeaconTypeCode() == 0x0215) { //533 in dec)}
193
194
                                holder.visibilityUUIDLinearLayout.setVisibility(View.VISIBLE);
195
                                holder.visibilityNameSpaceLinearLayout.setVisibility(View.GONE);
196
197
                                // AppleIBeacon
                                if (beacon.getId1() != null) {
198
                                        holder.uuidTextView.setText(beacon.getId1().toString());
199
200
                                } else {
201
                                        holder.uuidTextView.setText(android.R.string.unknownName);
202
                                }
203
204
                                if (beacon.getId2() != null) {
205
                                        holder.majorTextView.setText(beacon.getId2().toString());
206
207
                                        holder.majorTextView.setText(android.R.string.unknownName);
208
209
210
                                if (beacon.getId3() != null) {
211
                                        holder.minorTextView.setText(beacon.getId3().toString());
212
                                } else {
213
                                        holder.minorTextView.setText(android.R.string.unknownName);
214
215
216
                        } else if (beacon.getBeaconTypeCode() == 0x0101) {
217
                               // EstimoteNearable
218
219
220
                }
```

6.6.4 Documentazione dei membri dato

6.6.4.1 activity

FragmentActivity it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.activity [private]

6.6.4.2 DEVICE_DETAIL_FRAGMENT

final String it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.DEVICE_DET \leftarrow AIL_FRAGMENT = "device detail" [static], [private]

6.6.4.3 deviceList

List < Device > it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.deviceList [private]

6.6.4.4 df

DecimalFormat it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.df [private]

La documentazione per questa classe è stata generata a partire dal seguente file:

• DeviceCardViewAdapter.java

6.7 Riferimenti per la classe it.unibo.torsello.bluetoothpositioning.fragment.DeviceChartFragment

Diagramma delle classi per it.unibo.torsello.bluetoothpositioning.fragment.DeviceChartFragment

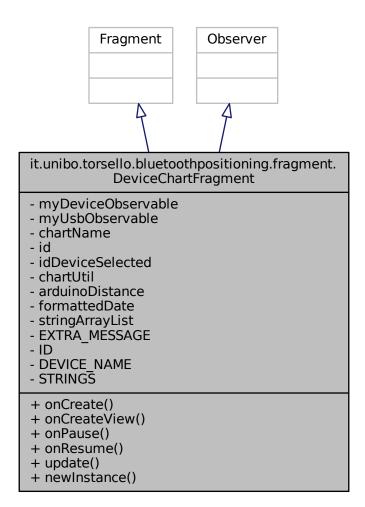
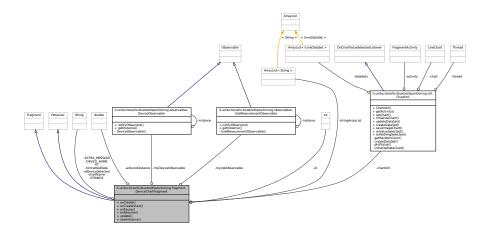


Diagramma di collaborazione per it.unibo.torsello.bluetoothpositioning.fragment.DeviceChartFragment:



Membri pubblici

- void onCreate (Bundle savedInstanceState)
- View onCreateView (LayoutInflater inflater, ViewGroup container, Bundle savedInstanceState)
- void onPause ()
- void onResume ()
- void update (Observable observable, Object arg)

Membri pubblici statici

static DeviceChartFragment newInstance (String message, int id, String deviceName, ArrayList< String > strings)

Attributi privati

- DeviceObservable myDeviceObservable
- UsbMeasurementObservable myUsbObservable
- · String chartName
- int id
- String idDeviceSelected
- ChartUtil chartUtil
- double arduinoDistance = 0D
- String formattedDate
- ArrayList < String > stringArrayList

Attributi privati statici

- static final String EXTRA_MESSAGE = "EXTRA_MESSAGE"
- static final String ID = "ID"
- static final String DEVICE NAME = "DEVICE NAME"
- static final String STRINGS = "STRINGS"

6.7.1 Descrizione dettagliata

Created by Federico Torsello. federico.torsello@studio.unibo.it

6.7.2 Documentazione delle funzioni membro

6.7.2.1 newInstance()

```
\texttt{static} \ \ \underline{\texttt{DeviceChartFragment}} \ \ \texttt{it.unibo.torsello.bluetoothpositioning.fragment.} \\ \underline{\texttt{DeviceChartFragment}} \ \ \texttt{it.unibo.torsello.bluetoothpositioning.fragment.} \\ \underline{\texttt{DeviceChartFragment.}} \\ \underline{\texttt{De
newInstance (
                                                                                                                String message,
                                                                                                                int id.
                                                                                                                String deviceName,
                                                                                                                ArrayList< String > strings ) [static]
 53
                                                                                    DeviceChartFragment fragment = new DeviceChartFragment();
                                                                                  Bundle args = new Bundle();
args.putString(EXTRA_MESSAGE, message);
 54
 55
                                                                                   args.putInt(ID, id);
args.putString(DEVICE_NAME, deviceName);
 56
 58
                                                                                    args.putStringArrayList(STRINGS, strings);
 59
                                                                                    fragment.setArguments(args);
 60
                                                                                    return fragment;
 61
```

6.7.2.2 onCreate()

```
Bundle savedInstanceState )
           super.onCreate(savedInstanceState);
65
66
67
           id = getArguments().getInt(ID);
           chartName = getArguments().getString(EXTRA_MESSAGE);
68
69
           idDeviceSelected = getArguments().getString(DEVICE_NAME);
70
           stringArrayList = getArguments().getStringArrayList(
     STRINGS);
71
72
          myDeviceObservable = DeviceObservable.getInstance();
73
          myUsbObservable = UsbMeasurementObservable.getInstance();
74
75
           chartUtil = new ChartUtil(getActivity());
76
           SimpleDateFormat df = new SimpleDateFormat("dd-MMM-yyyy", Locale.getDefault());
77
78
           formattedDate = df.format(Calendar.getInstance().getTime());
79
```

6.7.2.3 onCreateView()

```
82
83
84
           View root = inflater.inflate(R.layout.fragment_device_detail_chart, container, false);
8.5
           Button button = (Button) root.findViewById(R.id.button_save_image);
86
87
           button.setOnClickListener(new View.OnClickListener() {
88
               @Override
89
               public void onClick(View v) {
90
                   chartUtil.saveImageChart(chartName,
      formattedDate);
91
92
           });
93
94
           LineChart lineChart = (LineChart) root.findViewById(R.id.chart);
95
96
           // add the charts
97
           chartUtil.setChart(lineChart);
98
99
           return root;
100
6.7.2.4 onPause()
void it.unibo.torsello.bluetoothpositioning.fragment.DeviceChartFragment.onPause ( )
103
104
            myDeviceObservable.deleteObserver(this);
105
            mvUsbObservable.deleteObserver(this);
            super.onPause();
106
107
6.7.2.5 onResume()
void it.unibo.torsello.bluetoothpositioning.fragment.DeviceChartFragment.onResume ( )
110
111
            super.onResume();
112
            myDeviceObservable.addObserver(this);
myUsbObservable.addObserver(this);
113
114
            chartUtil.initializeChart();
6.7.2.6 update()
void it.unibo.torsello.bluetoothpositioning.fragment.DeviceChartFragment.update (
               Observable observable,
               Object arg )
118
119
120
            if (observable instanceof UsbMeasurementObservable) {
121
                if (arg instanceof Double) {
122
                    arduinoDistance = (Double) arg;
123
124
            }
125
126
            if (observable instanceof DeviceObservable) {
127
                if (arg instanceof List) {
128
                    List<Device> devices = (List<Device>) arg;
129
130
131
                     for (Device deviceSelected : devices) {
132
                         if (deviceSelected.getFriendlyName().equals(idDeviceSelected) ||
133
                                 deviceSelected.getAddress().equals(idDeviceSelected)) {
134
                             if (chartUtil != null) {
135
136
137
                                 chartUtil.createDataSet(
      stringArrayList);
```

```
138
139
                                 ArrayList<Double> dataSetForUpdates = new ArrayList<>();
140
141
                                 for (String s : stringArrayList) {
142
                                     if (s.equals(getString(R.string.chart_arduino))) {
143
                                        dataSetForUpdates.add(arduinoDistance);
144
145
146
                                     if (s.equals(getString(R.string.chart_raw_distance))) {
147
                                         dataSetForUpdates.add(deviceSelected.getRawDistance());
148
149
                                     if (s.equals(getString(R.string.chart_altbeacon))) {
150
151
                                         dataSetForUpdates.add(deviceSelected.getAltBeaconDistance());
152
153
154
                                     if (s.equals(getString(R.string.chart kalman filter))) {
155
156
                                         dataSetForUpdates.add(deviceSelected.getKalmanFilterDistance());
157
158
159
160
                                 chartUtil.updateDataSet(dataSetForUpdates);
161
                            }
                  }
162
163
164
165
166
        }
```

6.7.3 Documentazione dei membri dato

6.7.3.1 arduinoDistance

double it.unibo.torsello.bluetoothpositioning.fragment.DeviceChartFragment.arduinoDistance =
OD [private]

6.7.3.2 chartName

String it.unibo.torsello.bluetoothpositioning.fragment.DeviceChartFragment.chartName [private]

6.7.3.3 chartUtil

ChartUtil it.unibo.torsello.bluetoothpositioning.fragment.DeviceChartFragment.chartUtil [private]

6.7.3.4 DEVICE_NAME

final String it.unibo.torsello.bluetoothpositioning.fragment.DeviceChartFragment.DEVICE_NAME =
"DEVICE_NAME" [static], [private]

6.7.3.5 EXTRA_MESSAGE

final String it.unibo.torsello.bluetoothpositioning.fragment.DeviceChartFragment.EXTRA_MESSAGE
= "EXTRA_MESSAGE" [static], [private]

6.7.3.6 formattedDate

String it.unibo.torsello.bluetoothpositioning.fragment.DeviceChartFragment.formattedDate [private]

6.7.3.7 ID

final String it.unibo.torsello.bluetoothpositioning.fragment.DeviceChartFragment.ID = "ID"
[static], [private]

6.7.3.8 id

int it.unibo.torsello.bluetoothpositioning.fragment.DeviceChartFragment.id [private]

6.7.3.9 idDeviceSelected

String it.unibo.torsello.bluetoothpositioning.fragment.DeviceChartFragment.idDeviceSelected [private]

6.7.3.10 myDeviceObservable

DeviceObservable it.unibo.torsello.bluetoothpositioning.fragment.DeviceChartFragment.my← DeviceObservable [private]

6.7.3.11 myUsbObservable

 $\label{thm:continuity} \textbf{UsbMeasurementObservable} \ \, \textbf{it.unibo.torsello.bluetoothpositioning.fragment.DeviceChartFragment.} \\ \leftarrow \\ \text{myUsbObservable} \ \, \text{[private]}$

6.7.3.12 stringArrayList

6.7.3.13 STRINGS

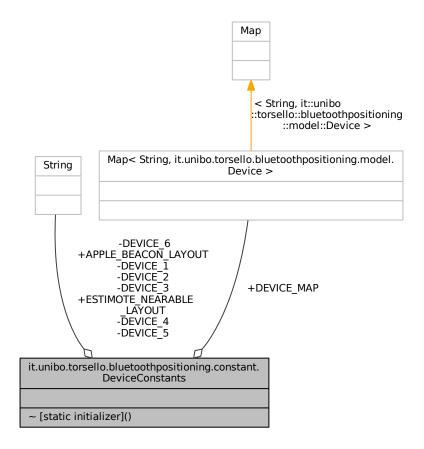
final String it.unibo.torsello.bluetoothpositioning.fragment.DeviceChartFragment.STRINGS =
"STRINGS" [static], [private]

La documentazione per questa classe è stata generata a partire dal seguente file:

• DeviceChartFragment.java

6.8 Riferimenti per la classe it.unibo.torsello.bluetoothpositioning.constant.DeviceConstants

Diagramma di collaborazione per it.unibo.torsello.bluetoothpositioning.constant.DeviceConstants:



Attributi pubblici statici

- static final String APPLE BEACON LAYOUT = "m:2-3=0215,i:4-19,i:20-21,i:22-23,p:24-24"
- static final String ESTIMOTE_NEARABLE_LAYOUT
- static final Map < String, Device > DEVICE_MAP

Funzioni statiche con visibilità di package

· [static initializer]

Attributi privati statici

- static final String DEVICE 1 = "C1:9B:B0:B9:01:9E"
- static final String DEVICE_2 = "D1:BE:E2:E9:67:A6"
- static final String DEVICE_3 = "FA:6B:72:1E:EB:46"
- static final String DEVICE_4 = "D9:80:00:B7:16:78"
- static final String DEVICE_5 = "DB:F6:F5:0C:23:BF"
- static final String DEVICE_6 = "E7:E4:0E:F6:79:3F"

6.8.1 Descrizione dettagliata

Created by Federico Torsello. federico.torsello@studio.unibo.it

6.8.2 Documentazione delle funzioni membro

6.8.2.1 [static initializer]()

it.unibo.torsello.bluetoothpositioning.constant.DeviceConstants.[static initializer] () [static],
[package]

6.8.3 Documentazione dei membri dato

6.8.3.1 APPLE_BEACON_LAYOUT

final String it.unibo.torsello.bluetoothpositioning.constant.DeviceConstants.APPLE_BEACON_LA \leftarrow YOUT = "m:2-3=0215,i:4-19,i:20-21,i:22-23,p:24-24" [static]

6.8.3.2 DEVICE 1

final String it.unibo.torsello.bluetoothpositioning.constant.DeviceConstants.DEVICE_1 = "C1 \leftrightarrow :9B:B0:B9:01:9E" [static], [private]

6.8.3.3 DEVICE_2

final String it.unibo.torsello.bluetoothpositioning.constant.DeviceConstants.DEVICE_2 = "D1: \leftrightarrow BE:E2:E9:67:A6" [static], [private]

6.8.3.4 DEVICE 3

final String it.unibo.torsello.bluetoothpositioning.constant.DeviceConstants.DEVICE_3 = "FA \leftrightarrow :6B:72:1E:EB:46" [static], [private]

6.8.3.5 DEVICE_4

final String it.unibo.torsello.bluetoothpositioning.constant.DeviceConstants.DEVICE_4 = "D9 \leftrightarrow :80:00:B7:16:78" [static], [private]

6.8.3.6 DEVICE_5

final String it.unibo.torsello.bluetoothpositioning.constant.DeviceConstants.DEVICE_5 = "DB: \leftarrow F6:F5:0C:23:BF" [static], [private]

6.8.3.7 DEVICE_6

final String it.unibo.torsello.bluetoothpositioning.constant.DeviceConstants.DEVICE_6 = "E7: \leftarrow E4:0E:F6:79:3F" [static], [private]

6.8.3.8 DEVICE_MAP

final Map<String, Device> it.unibo.torsello.bluetoothpositioning.constant.DeviceConstants.DE \leftarrow VICE_MAP [static]

6.8.3.9 ESTIMOTE_NEARABLE_LAYOUT

 $\label{thm:constant} final String it.unibo.torsello.bluetoothpositioning.constant.DeviceConstants.ESTIMOTE_NEARAB \leftarrow \\ \text{LE_LAYOUT} \quad [static]$

Valore iniziale:

La documentazione per questa classe è stata generata a partire dal seguente file:

· DeviceConstants.java

6.9 Riferimenti per la classe it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailFragment

Diagramma delle classi per it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailFragment

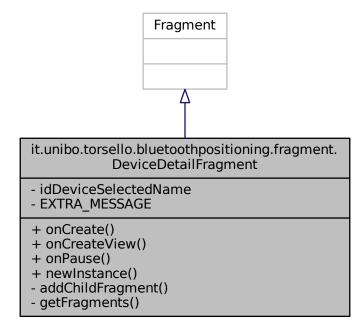
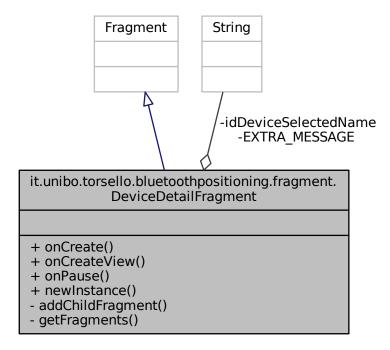


Diagramma di collaborazione per it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailFragment:



Membri pubblici

- void onCreate (Bundle savedInstanceState)
- View onCreateView (LayoutInflater inflater, ViewGroup container, Bundle savedInstanceState)
- void onPause ()

Membri pubblici statici

• static DeviceDetailFragment newInstance (String message)

Membri privati

- void addChildFragment (View root)
- ArrayList< Fragment > getFragments ()

Attributi privati

• String idDeviceSelectedName

Attributi privati statici

static final String EXTRA_MESSAGE = "EXTRA_MESSAGE"

6.9.1 Descrizione dettagliata

Created by Federico Torsello. federico.torsello@studio.unibo.it

6.9.2 Documentazione delle funzioni membro

6.9.2.1 addChildFragment()

```
\verb|void it.unibo.torsello.bluetooth| positioning.fragment.DeviceDetailFragment.addChildFragment (|include the continuous of the continuou
                                                                  View root ) [private]
 62
 63
 64
                                                  ViewPager mViewPager = (ViewPager) root.findViewById(R.id.view_pager);
 65
                                                  StatePagerAdapter myPageAdapter = new StatePagerAdapter(getChildFragmentManager(),
                            getFragments());
 66
                                                mViewPager.setAdapter(myPageAdapter);
                                                 mViewPager.setOffscreenPageLimit(getFragments().size());
 67
 68
                                                mViewPager.setCurrentItem(1);
 70
                                                 TabLayout tabLayout = (TabLayout) root.findViewById(R.id.sliding_tabs);
 71
                                                  tabLayout.setupWithViewPager(mViewPager);
 72
```

6.9.2.2 getFragments()

 $\label{lem:arrayList} $$\operatorname{ArrayList}(Fragment) = i.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailFragment.get $$\mathcal{C}$$$ Fragments () [private]

```
74
75
76
           ArrayList<Fragment> fragments = new ArrayList<>();
77
78
           // fragment 0
79
           fragments.add(DeviceDetailInnerOFragment.newInstance(
      idDeviceSelectedName));
80
           // fragment 1
82
           {\tt fragments.add(DeviceDetailInner1Fragment.newInstance(}
      idDeviceSelectedName));
83
           // fragment 2
84
85
           fragments.add(DeviceDetailInner2Fragment.newInstance(
      idDeviceSelectedName));
86
87
88
           return fragments;
89
```

6.9.2.3 newInstance()

```
\texttt{static DeviceDetailFragment it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetail} \leftarrow \texttt{static DeviceDetailFragment it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetail}
Fragment.newInstance (
                   String message ) [static]
28
              DeviceDetailFragment fragment = new DeviceDetailFragment();
29
30
              Bundle args = new Bundle();
31
              args.putString(EXTRA_MESSAGE, message);
32
              fragment.setArguments(args);
33
              return fragment;
34
         }
```

6.9.2.4 onCreate()

6.9.2.5 onCreateView()

```
\label{thm:position} View \ \ \text{it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailFragment.onCreateView} \ \ \text{(}
               LayoutInflater inflater,
               ViewGroup container,
               Bundle savedInstanceState )
44
45
            final View root = inflater.inflate(R.layout.fragment_device_detail, container, false);
46
            qetActivity().findViewById(R.id.toolbar).setVisibility(View.GONE);
47
48
49 //
              ((AppBarLayout) root.findViewById(R.id.appbar_detail)).setExpanded(false);
50 //
              ((CollapsingToolbarLayout)
       root.findViewById(R.id.collapsing_toolbar)).setTitle(idDeviceSelectedName);
51
52
            addChildFragment(root);
5.3
            return root;
54
```

6.9.2.6 onPause()

6.9.3 Documentazione dei membri dato

6.9.3.1 EXTRA_MESSAGE

```
final String it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailFragment.EXTRA_MESS \leftarrow AGE = "EXTRA_MESSAGE" [static], [private]
```

6.9.3.2 idDeviceSelectedName

String it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailFragment.idDeviceSelected \leftarrow Name [private]

La documentazione per questa classe è stata generata a partire dal seguente file:

DeviceDetailFragment.java

6.10 Riferimenti per la classe it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInner0Fragment

Diagramma delle classi per it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInner0Fragment

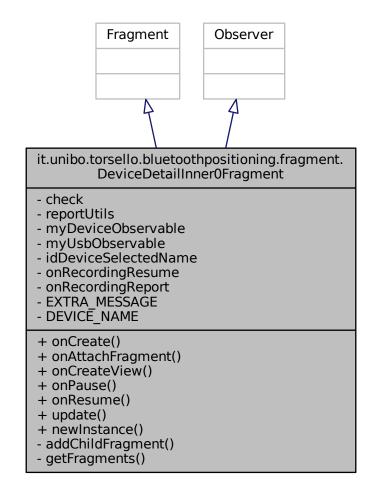
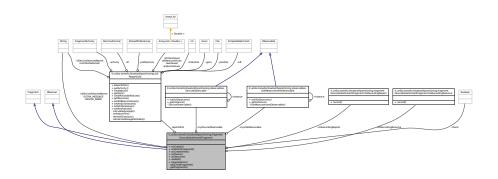


Diagramma di collaborazione per it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInner0Fragment:



Composti

- interface OnRecordingReport
- interface OnRecordingResume

Membri pubblici

- · void onCreate (Bundle savedInstanceState)
- void onAttachFragment (Fragment childFragment)
- · View onCreateView (LayoutInflater inflater, ViewGroup container, Bundle savedInstanceState)
- void onPause ()
- void onResume ()
- void update (Observable observable, Object arg)

Membri pubblici statici

• static DeviceDetailInner0Fragment newInstance (String deviceName)

Membri privati

- void addChildFragment (View root)
- ArrayList< Fragment > getFragments ()

Attributi privati

- · boolean check
- · ReportUtils reportUtils
- DeviceObservable myDeviceObservable
- UsbMeasurementObservable myUsbObservable
- · String idDeviceSelectedName
- · OnRecordingResume onRecordingResume
- OnRecordingReport onRecordingReport

Attributi privati statici

- static final String EXTRA_MESSAGE = "EXTRA_MESSAGE"
- static final String DEVICE NAME = "DEVICE NAME"

6.10.1 Descrizione dettagliata

Created by Federico Torsello. federico.torsello@studio.unibo.it

6.10.2 Documentazione delle funzioni membro

6.10.2.1 addChildFragment()

```
\verb|void it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInnerOFragment.addChild+\\
Fragment (
               View root ) [private]
143
144
145
            ViewPager mViewPager = (ViewPager) root.findViewById(R.id.view_pager_inner_0);
146
            // avoid casual fragment's destruction
mViewPager.setOffscreenPageLimit(getFragments().size());
147
148
149
150
            StatePagerAdapter myPageAdapter = new StatePagerAdapter(getChildFragmentManager(),
      getFragments());
151
            mViewPager.setAdapter(myPageAdapter);
152
             TabLayout tabLayout = (TabLayout) root.findViewById(R.id.sliding_tabs);
153
             tabLayout.setupWithViewPager(mViewPager);
154
155
```

6.10.2.2 getFragments()

 $\label{lem:arrayList} $$ArrayList<Fragment>$ it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInner0Fragment.$$\hookrightarrow $$ getFragments () [private]$

```
157
            ArrayList<Fragment> fragments = new ArrayList<>();
158
159
160
            // nested fragment 0
161
            fragments.add(DeviceDetailResumeFragment.newInstance());
162
163
            // nested fragment 1
            fragments.add(DeviceDetailReportFragment.newInstance());
164
165
166
            return fragments;
```

6.10.2.3 newInstance()

```
\verb|static DeviceDetailInnerOFragment it.unibo.torsello.bluetoothpositioning.fragment.Device \leftarrow|
DetailInnerOFragment.newInstance (
              String deviceName ) [static]
58
           DeviceDetailInnerOFragment fragment = new DeviceDetailInnerOFragment();
59
60
           Bundle args = new Bundle();
           args.putString(EXTRA_MESSAGE, "testing");
62
           args.putString(DEVICE_NAME, deviceName);
63
           fragment.setArguments(args);
64
           return fragment;
65
```

6.10.2.4 onAttachFragment()

89

6.10.2.5 onCreate()

```
Bundle savedInstanceState )
68
69
                        super.onCreate(savedInstanceState);
 70
                        idDeviceSelectedName = getArguments().getString(
71
             DEVICE_NAME);
72
73
                        mvDeviceObservable = DeviceObservable.getInstance();
                       myUsbObservable = UsbMeasurementObservable.getInstance();
74
 75
76
                        reportUtils = new ReportUtils(getActivity(),
             idDeviceSelectedName);
77
               }
6.10.2.6 onCreateView()
\label{thm:policy} {\tt View it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInnerOFragment.onCreateView (Constitution of the property of the prop
                                LayoutInflater inflater,
                                ViewGroup container,
                                Bundle savedInstanceState )
92
                        final View root = inflater.inflate(R.layout.fragment_device_detail_inner_0, container, false);
93
94
                        final ToggleButton toggle = (ToggleButton) root.findViewById(R.id.toggleButton);
96
                        toggle.setOnCheckedChangeListener(new CompoundButton.OnCheckedChangeListener()
97
                                public void onCheckedChanged(CompoundButton buttonView, boolean isChecked) {
98
                                         check = isChecked;
                                         if (isChecked) {
99
100
101
                                                    reportUtils.clearRecordedValues();
102
103
                                                    toggle.setClickable(false);
104
105
                                                    new Handler().postDelayed(new Runnable() {
106
                                                            @Override
107
                                                            public void run() {
108
                                                                     toggle.setClickable(true);
109
                                                                     toggle.setChecked(false);
110
111
                                                                     onRecordingReport.record(
             reportUtils.getJson());
112
                                                                     onRecordingResume.record(
             reportUtils.getResume());
113
114
                                                    }, 5000);
115
                                                    Snackbar.make(getActivity().findViewById(R.id.fab),
    "Start recording", Snackbar.LENGTH_SHORT).show();
116
117
118
119
                                                    reportUtils.createJson();
120
121
                          });
122
123
124
                          addChildFragment(root);
125
126
                          return root;
127
6.10.2.7 onPause()
\verb|void it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInnerOFragment.onPause ()|\\
```

mvDeviceObservable.deleteObserver(this);

mvUsbObservable.deleteObserver(this);

super.onPause();

130 131

132

133

134

6.10.2.8 onResume()

```
void it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInnerOFragment.onResume ( )
137
138
                                   super.onResume();
139
                                  mvDeviceObservable.addObserver(this);
                                  myUsbObservable.addObserver(this);
140
6.10.2.9 update()
\verb|void| it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInnerOFragment.update (|a.a., |a.a., 
                                          Observable observable,
                                          Object arg )
170
171
                                   if (observable instanceof UsbMeasurementObservable) {
                                              if (arg instanceof Double) {
172
173
                                                         Double arduinoDistance = (Double) arg;
174
                                                          if (check) {
175
                                                                     reportUtils.setArduinoValues(arduinoDistance);
176
177
                                               }
178
                                  }
179
180
                                   if (observable instanceof DeviceObservable) {
181
                                              if (arg instanceof List) {
182
183
                                                          List<Device> devices = (List<Device>) arg;
184
185
                                                          for (Device deviceSelected : devices)
186
                                                                      if (deviceSelected.getFriendlyName().equals(
                  idDeviceSelectedName) ||
187
                                                                                             deviceSelected.getAddress().equals(
                 idDeviceSelectedName)) {
188
189
                                                                                 if (check) {
190
                                                                                             reportUtils.setAltBeaconValues(deviceSelected.
                 getAltBeaconDistance());
191
                                                                                             reportUtils.setkFilterValues(deviceSelected.
```

6.10.3 Documentazione dei membri dato

getKalmanFilterDistance());

}

}

6.10.3.1 check

192

193 194

195

196 197 198

199

);

}

boolean it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInnerOFragment.check [private]

 ${\tt reportUtils.setRawValues} \ ({\tt deviceSelected.getRawDistance} \ ()$

6.10.3.2 DEVICE_NAME

final String it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInner0Fragment.DEVI \leftarrow CE_NAME = "DEVICE_NAME" [static], [private]

6.10.3.3 EXTRA_MESSAGE

final String it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInnerOFragment.EXTR ← A_MESSAGE = "EXTRA_MESSAGE" [static], [private]

6.10.3.4 idDeviceSelectedName

String it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInner0Fragment.idDevice \leftarrow SelectedName [private]

6.10.3.5 myDeviceObservable

DeviceObservable it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInnerOFragment.←
myDeviceObservable [private]

6.10.3.6 myUsbObservable

 $\label{lem:usbMeasurementObservable} UsbMeasurementObservable it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInnerO \leftarrow Fragment.myUsbObservable [private]$

6.10.3.7 onRecordingReport

6.10.3.8 onRecordingResume

 $\begin{tabular}{ll} On Recording Resume & it.unibo.torsello.bluetooth positioning.fragment.Device Detail Inner OF ragment. \\ &configresume & [private] \end{tabular}$

6.10.3.9 reportUtils

 $\label{lem:reportUtils} ReportUtils it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInner0Fragment. \\ \leftarrow reportUtils [private]$

La documentazione per questa classe è stata generata a partire dal seguente file:

• DeviceDetailInner0Fragment.java

6.11 Riferimenti per la classe it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInner1Fragment

Diagramma delle classi per it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInner1Fragment

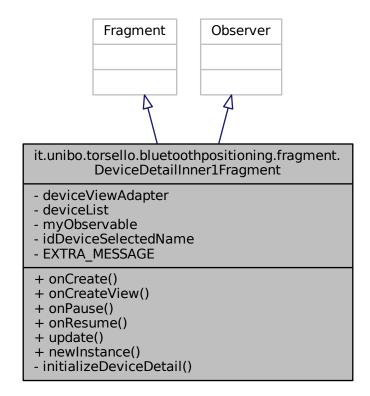
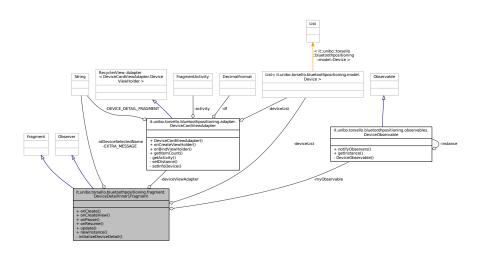


Diagramma di collaborazione per it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInner1Fragment:



Membri pubblici

- void onCreate (@Nullable Bundle savedInstanceState)
- View onCreateView (LayoutInflater inflater, ViewGroup container, Bundle savedInstanceState)
- void onPause ()
- · void onResume ()
- void update (Observable o, Object arg)

Membri pubblici statici

static DeviceDetailInner1Fragment newInstance (String message)

Membri privati

void initializeDeviceDetail (View root)

Attributi privati

- DeviceCardViewAdapter deviceViewAdapter
- List< Device > deviceList
- DeviceObservable myObservable
- String idDeviceSelectedName

Attributi privati statici

• static final String EXTRA_MESSAGE = "EXTRA_MESSAGE"

6.11.1 Descrizione dettagliata

Created by Federico Torsello. federico.torsello@studio.unibo.it

6.11.2 Documentazione delle funzioni membro

6.11.2.1 initializeDeviceDetail()

6.11.2.2 newInstance()

64 65

myObservable.deleteObserver(this);

super.onPause();

```
DetailInner1Fragment.newInstance (
                                    String message ) [static]
35
36
                           DeviceDetailInner1Fragment fragment = new DeviceDetailInner1Fragment();
                           Bundle args = new Bundle();
args.putString(EXTRA_MESSAGE, message);
37
38
39
                           fragment.setArguments(args);
40
                           return fragment;
6.11.2.3 onCreate()
\verb|void it.unibo.torsello.bluetooth| positioning.fragment.DeviceDetailInner1Fragment.onCreate (in the contrast of the contras
                                    @Nullable Bundle savedInstanceState )
44
45
                           super.onCreate(savedInstanceState);
46
47
                           myObservable = DeviceObservable.getInstance();
48
49
                           idDeviceSelectedName = getArguments().getString(
               EXTRA_MESSAGE);
50
                           deviceList = new ArrayList<>();
51
                           deviceViewAdapter = new DeviceCardViewAdapter(getActivity(),
               deviceList);
52
6.11.2.4 onCreateView()
View it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInnerlFragment.onCreateView (
                                    LayoutInflater inflater,
                                    ViewGroup container,
                                    Bundle savedInstanceState )
56
                           View root = inflater.inflate(R.layout.fragment_device_detail_inner_1, container, false);
57
58
                           initializeDeviceDetail(root);
59
60
                           return root;
6.11.2.5 onPause()
void it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInner1Fragment.onPause ( )
```

6.11.2.6 onResume()

```
void it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInner1Fragment.update (
              Observable o,
              Object arg )
83
84
          if (arg instanceof List) {
8.5
86
               if (!deviceList.isEmpty()) {
                  deviceList.clear();
90
91
               List<Device> devices = (List<Device>) arg;
92
               for (Device deviceSelected : devices) {
93
                  if (deviceSelected.getFriendlyName().equals(idDeviceSelectedName) ||
95
                          deviceSelected.getAddress().equals(idDeviceSelectedName))
96
                      deviceList.add(deviceSelected);
97
98
99
100
               deviceViewAdapter.notifyDataSetChanged();
101
102
```

6.11.3 Documentazione dei membri dato

6.11.3.1 deviceList

 $\label{list} List < \texttt{Device} > \texttt{it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInner1Fragment.} \leftarrow \texttt{deviceList} \quad [\texttt{private}]$

6.11.3.2 deviceViewAdapter

 $\label{lem:deviceCardViewAdapter} \begin{center} DeviceCardViewAdapter it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInner1 \leftarrow Fragment.deviceViewAdapter [private] \end{center}$

6.11.3.3 EXTRA_MESSAGE

final String it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInner1Fragment.EXTR↔
A_MESSAGE = "EXTRA_MESSAGE" [static], [private]

6.11.3.4 idDeviceSelectedName

String it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInnerlFragment.idDevice↔ SelectedName [private]

6.11.3.5 myObservable

 $\label{lem:decomposition} \begin{center} DeviceObservable it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInner1Fragment. \\ \leftarrow myObservable [private]$

La documentazione per questa classe è stata generata a partire dal seguente file:

- DeviceDetailInner1Fragment.java
- 6.12 Riferimenti per la classe it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInner2Fragment

Diagramma delle classi per it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInner2Fragment

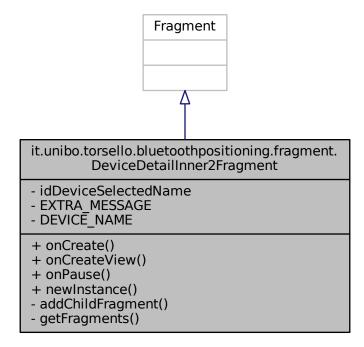
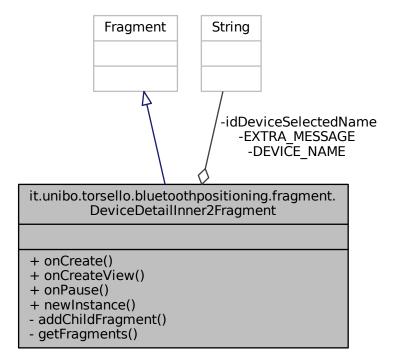


Diagramma di collaborazione per it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInner2Fragment:



Membri pubblici

- void onCreate (Bundle savedInstanceState)
- · View onCreateView (LayoutInflater inflater, ViewGroup container, Bundle savedInstanceState)
- void onPause ()

Membri pubblici statici

• static DeviceDetailInner2Fragment newInstance (String deviceName)

Membri privati

- void addChildFragment (View root)
- ArrayList< Fragment > getFragments ()

Attributi privati

• String idDeviceSelectedName

Attributi privati statici

- static final String EXTRA MESSAGE = "EXTRA MESSAGE"
- static final String DEVICE_NAME = "DEVICE_NAME"

6.12.1 Descrizione dettagliata

Created by Federico Torsello. federico.torsello@studio.unibo.it

6.12.2 Documentazione delle funzioni membro

6.12.2.1 addChildFragment()

```
\verb|void| it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInner2Fragment.addChild+\\
Fragment (
              View root ) [private]
58
59
           ViewPager mViewPager = (ViewPager) root.findViewById(R.id.view_pager_inner_2);
60
           // avoid casual fragment's destruction
61
           mViewPager.setOffscreenPageLimit(getFragments().size());
62
63
64
           StatePagerAdapter myPageAdapter = new StatePagerAdapter(getChildFragmentManager(),
6.5
           mViewPager.setAdapter(myPageAdapter);
66
           TabLayout tabLayout = (TabLayout) root.findViewById(R.id.sliding_tabs);
67
           tabLayout.setupWithViewPager(mViewPager);
68
69
```

6.12.2.2 getFragments()

 $\label{lem:arrayList} $$\operatorname{Fragment}$ it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInner2Fragment.$\longleftrightarrow getFragments () [private]$

```
72
           ArrayList<Fragment> fragments = new ArrayList<>();
73
74
75
           ArrayList<String> params1 = new ArrayList<>();
          params1.add(getString(R.string.chart_arduino));
params1.add(getString(R.string.chart_raw_distance));
76
77
78
           params1.add(getString(R.string.chart_altbeacon));
79
           params1.add(getString(R.string.chart_kalman_filter));
80
81
           idDeviceSelectedName, params1));
82
83
           // inner fragment 1
           ArrayList<String> params2 = new ArrayList<>();
85
           params2.add(getString(R.string.chart_arduino));
86
           params2.add(getString(R.string.chart_raw_distance));
87
           params2.add(getString(R.string.chart_kalman_filter));
88
           fragments.add(DeviceChartFragment.newInstance("chart2", 2,
89
      idDeviceSelectedName, params2));
90
91
           // inner fragment 2
92
           ArrayList<String> params3 = new ArrayList<>();
           params3.add(getString(R.string.chart_arduino));
93
94
           params3.add(getString(R.string.chart_altbeacon));
95
          params3.add(getString(R.string.chart_kalman_filter));
97
           fragments.add(DeviceChartFragment.newInstance("chart3", 3,
      idDeviceSelectedName, params3));
98
99
           return fragments:
100
```

6.12.2.3 newInstance()

```
static DeviceDetailInner2Fragment it.unibo.torsello.bluetoothpositioning.fragment.Device↔
DetailInner2Fragment.newInstance (
              String deviceName ) [static]
27
28
          DeviceDetailInner2Fragment fragment = new DeviceDetailInner2Fragment();
          Bundle args = new Bundle();
           args.putString(EXTRA_MESSAGE, "real time charts");
30
31
           args.putString(DEVICE_NAME, deviceName);
32
           {\tt fragment.setArguments(args);}
3.3
          return fragment;
34
```

6.12.2.4 onCreate()

6.12.2.5 onCreateView()

6.12.2.6 onPause()

54

5.5

```
void it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInner2Fragment.onPause ()
```

6.12.3 Documentazione dei membri dato

super.onPause();

6.12.3.1 DEVICE NAME

final String it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInner2Fragment.DEVI \leftarrow CE_NAME = "DEVICE_NAME" [static], [private]

6.12.3.2 EXTRA_MESSAGE

final String it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInner2Fragment.EXTR↔

A_MESSAGE = "EXTRA_MESSAGE" [static], [private]

6.12.3.3 idDeviceSelectedName

String it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInner2Fragment.idDevice \leftarrow SelectedName [private]

La documentazione per questa classe è stata generata a partire dal seguente file:

• DeviceDetailInner2Fragment.java

6.13 Riferimenti per la classe it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailReportFragment

Diagramma delle classi per it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailReportFragment

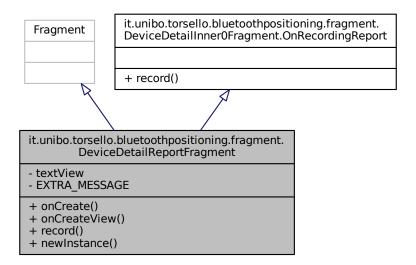
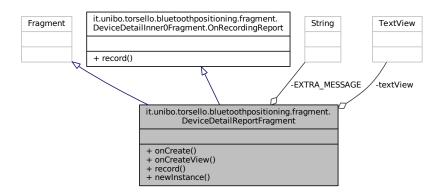


Diagramma di collaborazione per it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailReportFragment:



Membri pubblici

- void onCreate (@Nullable Bundle savedInstanceState)
- View onCreateView (LayoutInflater inflater, ViewGroup container, Bundle savedInstanceState)
- void record (String newRecord)

Membri pubblici statici

• static DeviceDetailReportFragment newInstance ()

Attributi privati

TextView textView

Attributi privati statici

static final String EXTRA_MESSAGE = "EXTRA_MESSAGE"

6.13.1 Descrizione dettagliata

Created by Federico Torsello. federico.torsello@studio.unibo.it

6.13.2 Documentazione delle funzioni membro

6.13.2.1 newInstance()

6.13.2.2 onCreate()

6.13.2.3 onCreateView()

```
View it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailReportFragment.onCreateView (
              LayoutInflater inflater,
              ViewGroup container,
              Bundle savedInstanceState )
43
44
          // Inflate the layout for this fragment
45
          final View root = inflater.inflate(R.layout.fragment_device_detail_report, container, false);
46
47
          textView = (TextView) root.findViewById(R.id.textView_report);
48
49
          return root;
50
```

6.13.2.4 record()

```
void it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailReportFragment.record ( String \ newRecord \ )
```

Implementa it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInner0Fragment.OnRecordingReport.

```
53
54          textView.setText(newRecord);
55 }
```

6.13.3 Documentazione dei membri dato

6.13.3.1 EXTRA_MESSAGE

```
final String it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailReportFragment.EXTR \leftarrow A_MESSAGE = "EXTRA_MESSAGE" [static], [private]
```

6.13.3.2 textView

TextView it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailReportFragment.textView [private]

La documentazione per questa classe è stata generata a partire dal seguente file:

• DeviceDetailReportFragment.java

6.14 Riferimenti per la classe it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailResume ← Fragment

 $Diagramma\ delle\ classi\ per\ it. unibo. torsello. blue to oth positioning. fragment. Device Detail Resume Fragment$

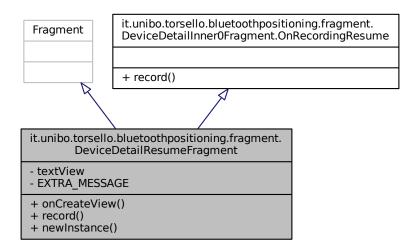
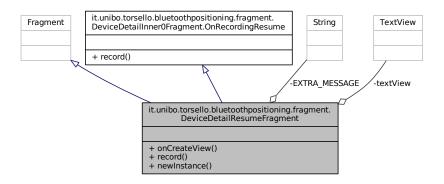


Diagramma di collaborazione per it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailResumeFragment:



Membri pubblici

- View onCreateView (LayoutInflater inflater, ViewGroup container, Bundle savedInstanceState)
- void record (String newRecord)

Membri pubblici statici

static DeviceDetailResumeFragment newInstance ()

Attributi privati

TextView textView

Attributi privati statici

static final String EXTRA_MESSAGE = "EXTRA_MESSAGE"

6.14.1 Descrizione dettagliata

Created by federico on 12/10/16.

6.14.2 Documentazione delle funzioni membro

6.14.2.1 newInstance()

6.14.2.2 onCreateView()

33

```
\label{thm:policy} {\tt View it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailResumeFragment.onCreateView\ (} \\
               LayoutInflater inflater,
               ViewGroup container,
               Bundle savedInstanceState )
37
            \ensuremath{//} Inflate the layout for this fragment
38
39
            final View root = inflater.inflate(R.layout.fragment_device_detail_resume, container, false);
40
41
            textView = (TextView) root.findViewById(R.id.textView_resume);
42
43
            return root;
44
```

6.14.2.3 record()

```
\label{lem:cond} \mbox{void it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailResumeFragment.record (} \\ \mbox{String } newRecord \mbox{)}
```

 $Implement a \ it. unibo. torsello. blue to oth positioning. fragment. Device Detail Inner OF ragment. On Recording Resume.$

```
47
48 textView.setText(newRecord);
49 }
```

6.14.3 Documentazione dei membri dato

6.14.3.1 EXTRA_MESSAGE

final String it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailResumeFragment.EXTR←
A_MESSAGE = "EXTRA_MESSAGE" [static], [private]

6.14.3.2 textView

TextView it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailResumeFragment.textView [private]

La documentazione per questa classe è stata generata a partire dal seguente file:

· DeviceDetailResumeFragment.java

6.15 Riferimenti per la classe it.unibo.torsello.bluetoothpositioning.fragment.DeviceListFragment

Diagramma delle classi per it.unibo.torsello.bluetoothpositioning.fragment.DeviceListFragment

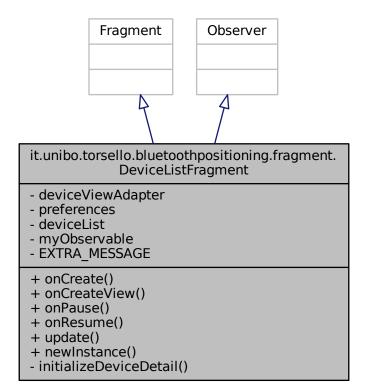
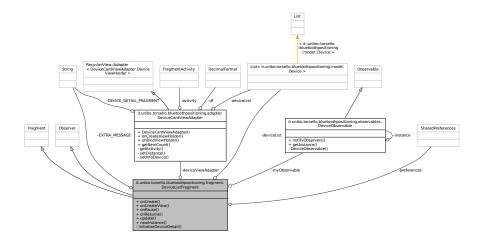


Diagramma di collaborazione per it.unibo.torsello.bluetoothpositioning.fragment.DeviceListFragment:



Membri pubblici

- void onCreate (@Nullable Bundle savedInstanceState)
- · View onCreateView (LayoutInflater inflater, ViewGroup container, Bundle savedInstanceState)
- void onPause ()
- void onResume ()
- void update (Observable o, Object arg)

Membri pubblici statici

• static DeviceListFragment newInstance ()

Membri privati

• void initializeDeviceDetail (View root)

Attributi privati

- · DeviceCardViewAdapter deviceViewAdapter
- SharedPreferences preferences
- List< Device > deviceList
- DeviceObservable myObservable

Attributi privati statici

• static final String EXTRA_MESSAGE = "EXTRA_MESSAGE"

6.15.1 Descrizione dettagliata

Created by Federico Torsello. federico.torsello@studio.unibo.it

6.15.2 Documentazione delle funzioni membro

6.15.2.1 initializeDeviceDetail()

```
\verb|void it.unibo.torsello.bluetoothpositioning.fragment.DeviceListFragment.initializeDeviceDetail|\\
(
              View root ) [private]
83
84
           // add RecyclerView
          RecyclerView recyclerView = (RecyclerView) root.findViewById(R.id.recycler_view);
85
86
           recyclerView.setLayoutManager(new LinearLayoutManager(getContext()));
          deviceViewAdapter = new DeviceCardViewAdapter(getActivity(),
87
     deviceList);
88
          recyclerView.setAdapter(deviceViewAdapter);
89
```

6.15.2.2 newInstance()

6.15.2.3 onCreate()

6.15.2.4 onCreateView()

6.15.2.5 onPause()

```
\verb|void it.unibo.torsello.bluetoothpositioning.fragment.DeviceListFragment.onPause ()|\\
92
93
           myObservable.deleteObserver(this);
94
           super.onPause();
95
6.15.2.6 onResume()
void it.unibo.torsello.bluetoothpositioning.fragment.DeviceListFragment.onResume ( )
98
99
           super.onResume();
100
            myObservable.addObserver(this);
101
6.15.2.7 update()
\verb|void| it.unibo.torsello.bluetoothpositioning.fragment.DeviceListFragment.update | (
               Observable o,
               Object arg )
104
105
106
            if (arg instanceof List) {
107
108
                if (!deviceList.isEmpty()) {
109
                     deviceList.clear();
110
111
112
                List<Device> devices = (List<Device>) arg;
113
114
                 // optional sorting
115
                Collections.sort(devices, new Comparator<Device>() {
116
                     public int compare(Device b1, Device b2) {
117
                         int sorting = preferences.getInt(SettingConstants.DISTANCE_SORTING, 0);
118
                         switch (sorting) {
119
                             case 0:
120
                             case R.id.radioButton_default_sorting:
121
                                 return Double.compare(b1.getIndex(), b2.getIndex());
122
                             case R.id.radioButton_color_sorting:
123
                                 return Double.compare(b1.getColor(), b2.getColor());
                             case R.id.radioButton_distance_sorting:
    return Double.compare(bl.getKalmanFilterDistance(), b2.getKalmanFilterDistance()
124
125
      ));
126
                         \} // default sorting (a good basic ordering for the other options)
127
                         return Double.compare(b1.getIndex(), b2.getIndex());
128
129
                });
130
131
                deviceList.addAll(devices);
132
                deviceViewAdapter.notifyDataSetChanged();
133
134
```

6.15.3 Documentazione dei membri dato

6.15.3.1 deviceList

List<Device> it.unibo.torsello.bluetoothpositioning.fragment.DeviceListFragment.deviceList [private]

6.15.3.2 deviceViewAdapter

DeviceCardViewAdapter it.unibo.torsello.bluetoothpositioning.fragment.DeviceListFragment.← deviceViewAdapter [private]

6.15.3.3 EXTRA_MESSAGE

final String it.unibo.torsello.bluetoothpositioning.fragment.DeviceListFragment.EXTRA_MESSAGE
= "EXTRA_MESSAGE" [static], [private]

6.15.3.4 myObservable

DeviceObservable it.unibo.torsello.bluetoothpositioning.fragment.DeviceListFragment.myObservable [private]

6.15.3.5 preferences

SharedPreferences it.unibo.torsello.bluetoothpositioning.fragment.DeviceListFragment.preferences [private]

La documentazione per questa classe è stata generata a partire dal seguente file:

· DeviceListFragment.java

6.16 Riferimenti per la classe it.unibo.torsello.bluetoothpositioning.observables.DeviceObservable

Diagramma delle classi per it.unibo.torsello.bluetoothpositioning.observables.DeviceObservable

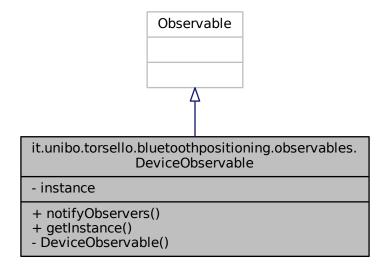
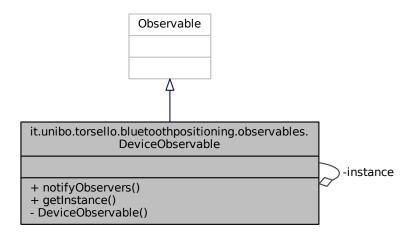


Diagramma di collaborazione per it.unibo.torsello.bluetoothpositioning.observables.DeviceObservable:



Membri pubblici

• void notifyObservers (Object data)

Membri pubblici statici

• static DeviceObservable getInstance ()

Membri privati

• DeviceObservable ()

Attributi privati statici

• static DeviceObservable instance = new DeviceObservable()

6.16.1 Descrizione dettagliata

Created by Federico Torsello. federico.torsello@studio.unibo.it

6.16.2 Documentazione dei costruttori e dei distruttori

6.16.2.1 DeviceObservable()

6.16.3 Documentazione delle funzioni membro

6.16.3.1 getInstance()

 $static\ DeviceObservable\ it.unibo.torsello.bluetoothpositioning.observables. DeviceObservable. \\ equal to the property of t$

6.16.3.2 notifyObservers()

```
\label{lem:condition} void it.unibo.torsello.bluetoothpositioning.observables. DeviceObservable.notifyObservers \ ( \\ Object \ data \ )
```

```
22
23     setChanged();
24     super.notifyObservers(data);
25 }
```

6.16.4 Documentazione dei membri dato

6.16.4.1 instance

DeviceObservable it.unibo.torsello.bluetoothpositioning.observables.DeviceObservable.instance
= new DeviceObservable() [static], [private]

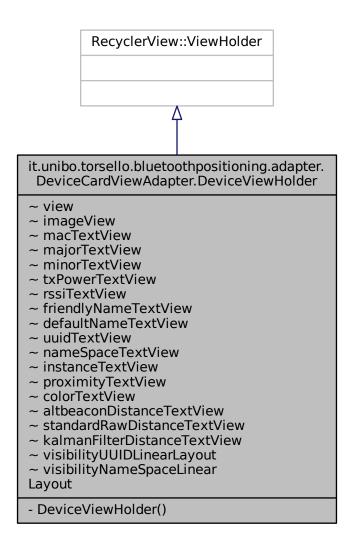
La documentazione per questa classe è stata generata a partire dal seguente file:

• DeviceObservable.java

6.17 Riferimenti per la classe it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.

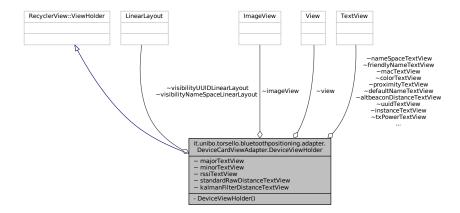
DeviceViewHolder

Diagramma delle classi per it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.DeviceView← Holder



 $Diagramma\ di\ collaborazione\ per\ it.unibo.torsello.blueto oth positioning. adapter. Device Card View Adapter. Device \leftarrow control of the co$

ViewHolder:



Attributi con visibilità di package

- View view
- ImageView imageView
- TextView macTextView
- TextView majorTextView
- TextView minorTextView
- TextView txPowerTextView
- TextView rssiTextView
- TextView friendlyNameTextView
- TextView defaultNameTextView
- TextView uuidTextView
- TextView nameSpaceTextView
- TextView instanceTextView
- TextView proximityTextView
- TextView colorTextView
- TextView altbeaconDistanceTextView
- TextView standardRawDistanceTextView
- TextView kalmanFilterDistanceTextView
- · LinearLayout visibilityUUIDLinearLayout
- LinearLayout visibilityNameSpaceLinearLayout

Membri privati

• DeviceViewHolder (View view)

6.17.1 Documentazione dei costruttori e dei distruttori

6.17.1.1 DeviceViewHolder()

 $it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.DeviceViewHolder.Device \\ \\ \\ ViewHolder ($

View view) [private]

```
250
                                                    {
251
252
                 super(view);
                 this view = view;
imageView = (ImageView) view.findViewById(R.id.imageBeacon);
253
254
255
                 defaultNameTextView = (TextView) view.findViewById(R.id.
      value_default_name);
256
                 friendlyNameTextView = (TextView) view.findViewById(R.id.
      value_friendly_name);
2.57
                 macTextView = (TextView) view.findViewById(R.id.value_mac_address);
                 majorTextView = (TextView) view.findViewById(R.id.value_major);
minorTextView = (TextView) view.findViewById(R.id.value_minor);
258
259
                 txPowerTextView = (TextView) view.findViewById(R.id.value_power);
260
261
                 rssiTextView = (TextView) view.findViewById(R.id.value_rssi);
262
                 uuidTextView = (TextView) view.findViewById(R.id.value_uuid);
263
                 nameSpaceTextView = (TextView) view.findViewById(R.id.value_name_space);
264
                 proximityTextView = (TextView) view.findViewById(R.id.value_proximity);
                 instanceTextView = (TextView) view.findViewById(R.id.value_instance);
265
266
                 colorTextView = (TextView) view.findViewById(R.id.value_color);
267
268
                 altbeaconDistanceTextView = (TextView) view.findViewById(R.id.
      value_altbeacon_distance);
2.69
                 kalmanFilterDistanceTextView = (TextView)
      view.findViewById(R.id.value_kalman_filter_distance);
270
                 standardRawDistanceTextView = (TextView)
      view.findViewById(R.id.value_standard_raw_distance);
271
272
                 visibilityUUIDLinearLayout = (LinearLayout)
      view.findViewById(R.id.visibility_uuid_minor_major_nmb);
273
                 visibilityNameSpaceLinearLayout = (LinearLayout)
      view.findViewById(R.id.visibilityNameSpace_Instance);
274
```

6.17.2 Documentazione dei membri dato

6.17.2.1 altbeaconDistanceTextView

TextView it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.DeviceView← Holder.altbeaconDistanceTextView [package]

6.17.2.2 colorTextView

TextView it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.DeviceView← Holder.colorTextView [package]

6.17.2.3 defaultNameTextView

6.17.2.4 friendlyNameTextView

TextView it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.DeviceView← Holder.friendlyNameTextView [package]

6.17.2.5 imageView

ImageView it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.DeviceView←
Holder.imageView [package]

6.17.2.6 instanceTextView

TextView it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.DeviceView← Holder.instanceTextView [package]

6.17.2.7 kalmanFilterDistanceTextView

TextView it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.DeviceView← Holder.kalmanFilterDistanceTextView [package]

6.17.2.8 macTextView

TextView it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.DeviceView← Holder.macTextView [package]

6.17.2.9 majorTextView

TextView it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.DeviceView← Holder.majorTextView [package]

6.17.2.10 minorTextView

TextView it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.DeviceView← Holder.minorTextView [package]

6.17.2.11 nameSpaceTextView

TextView it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.DeviceView← Holder.nameSpaceTextView [package]

6.17.2.12 proximityTextView

TextView it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.DeviceView← Holder.proximityTextView [package]

6.17.2.13 rssiTextView

TextView it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.DeviceView← Holder.rssiTextView [package]

6.17.2.14 standardRawDistanceTextView

 $\label{torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.DeviceView} \\ Holder.standardRawDistanceTextView \quad [package]$

6.17.2.15 txPowerTextView

TextView it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.DeviceView← Holder.txPowerTextView [package]

6.17.2.16 uuidTextView

TextView it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.DeviceView← Holder.uuidTextView [package]

6.17.2.17 view

 $\label{thm:position} \begin{tabular}{ll} View it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.DeviceViewHolder. & view & [package] \end{tabular}$

6.17.2.18 visibilityNameSpaceLinearLayout

LinearLayout it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.DeviceView← Holder.visibilityNameSpaceLinearLayout [package]

6.17.2.19 visibilityUUIDLinearLayout

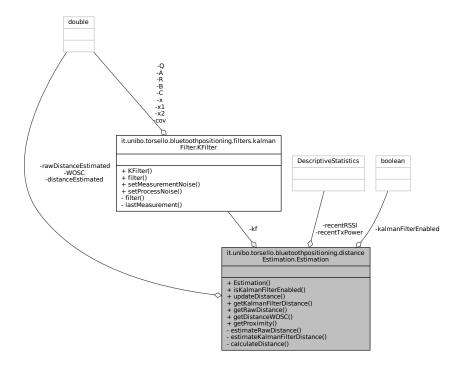
LinearLayout it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.DeviceView← Holder.visibilityUUIDLinearLayout [package]

La documentazione per questa classe è stata generata a partire dal seguente file:

DeviceCardViewAdapter.java

6.18 Riferimenti per la classe it.unibo.torsello.bluetoothpositioning.distanceEstimation.Estimation

Diagramma di collaborazione per it.unibo.torsello.bluetoothpositioning.distanceEstimation.Estimation:



Membri pubblici

- Estimation ()
- boolean isKalmanFilterEnabled ()
- · void updateDistance (Beacon b, double processNoise)
- double getKalmanFilterDistance ()
- double getRawDistance ()
- double getDistanceWOSC ()
- String getProximity ()

Membri privati

- void estimateRawDistance (Beacon b)
- void estimateKalmanFilterDistance (Beacon b, double processNoise)
- double calculateDistance (double txPower, double rssi)

Attributi privati

- DescriptiveStatistics recentRSSI
- DescriptiveStatistics recentTxPower
- · KFilter kf
- · double distanceEstimated
- · double rawDistanceEstimated
- double WOSC
- · boolean kalmanFilterEnabled

6.18.1 Descrizione dettagliata

Created by Federico Torsello. federico.torsello@studio.unibo.it

6.18.2 Documentazione dei costruttori e dei distruttori

6.18.2.1 Estimation()

 ${\tt it.unibo.torsello.bluetoothpositioning.distance} {\tt Estimation.Estimation} \ (\ {\tt)}$

```
26
           rawDistanceEstimated = 0;
28
           // limit on the number of values that can be stored in the dataset
29
           recentRSSI = new DescriptiveStatistics();
30
           recentRSSI.setWindowSize(KFilterConstants.WINDOW);
32
           recentTxPower = new DescriptiveStatistics();
           recentTxPower.setWindowSize(KFilterConstants.WINDOW);
33
34
35
          distanceEstimated = 0;
36
          WOSC = 0;
37
38
           kf = new KFilterBuilder()
39
                   // filter for RSSI
                   .R(KFilterConstants.INITIAL_PROCESS_NOISE) // Initial process noise
40
                   .Q(KFilterConstants.INITIAL_MEASUREMENT_NOISE) // Initial measurement noise
41
42
                   .build();
43
```

6.18.3 Documentazione delle funzioni membro

6.18.3.1 calculateDistance()

```
double txPower,
           double rssi ) [private]
92
93
        if (rssi == 0.0D) {
            return -1.0D; // if we cannot determine accuracy, return -1.
94
9.5
96
        double ratio = (rssi * 1.0D) / txPower;
98
        if (ratio < 1.0D) {</pre>
99
            return Math.pow(ratio, 10.0D);
100
101
102 //
          return (0.89976D * Math.pow(ratio, 7.7095D)) + 0.125D;
103
         return (0.89976D * Math.pow(ratio, 7.7095D)) + 0.111D;
104
```

6.18.3.2 estimateKalmanFilterDistance()

```
FilterDistance (
             Beacon b_{i}
             double processNoise ) [private]
61
62
63
          if (!(processNoise > 0)){
             kalmanFilterEnabled = false;
65
          } else {
66
             kalmanFilterEnabled = true;
67
             recentRSSI.addValue(b.getRssi());
68
69
             recentTxPower.addValue(b.getTxPower());
70
71
              // Update measurement noise continually
72
             double mNoise = Math.sqrt((100 * 9 / Math.log(10)) *
                    Math.log(1 + Math.pow(recentRSSI.getMean() /
73
     recentRSSI.getStandardDeviation(), 2)));
74
             if (!Double.isInfinite(mNoise) && !Double.isNaN(mNoise)) {
75
76
                 kf.setMeasurementNoise(mNoise);
77
78
79
             kf.setProcessNoise(processNoise);
80
              // update measurement, z parameter
81
82
             double lastFilteredReading = kf.filter(recentRSSI.getPercentile(50));
83
84
             WOSC = calculateDistance(b.getTxPower(), lastFilteredReading);
85
             distanceEstimated = calculateDistance(
86
     recentTxPower.getPercentile(50), lastFilteredReading);
87
          }
88
```

6.18.3.3 estimateRawDistance()

6.18.3.4 getDistanceWOSC()

6.18.3.5 getKalmanFilterDistance()

6.18.3.6 getProximity()

String it.unibo.torsello.bluetoothpositioning.distanceEstimation.Estimation.getProximity ()

```
118
                double proximity = distanceEstimated;
119
120
                String accuracy;
121
               if (proximity <= 0) {
   accuracy = "unknown";
} else if (proximity <= 0.5) {</pre>
122
123
124
                     accuracy = "immediate";
125
               } else if (proximity <= 4.0) {
   accuracy = "near";</pre>
126
127
128
                     accuracy = "far";
129
130
131
                return accuracy;
132
```

6.18.3.7 getRawDistance()

 ${\tt double\ it.unibo.torsello.bluetoothpositioning.distance Estimation. Estimation. get Raw Distance\ (\)}$

```
110
111          return rawDistanceEstimated;
112    }
```

6.18.3.8 isKalmanFilterEnabled()

 $boolean\ it.unibo.torsello.bluetoothpositioning.distance Estimation. Estimation. is Kalman Filter \leftarrow Enabled\ (\)$

6.18.3.9 updateDistance()

6.18.4 Documentazione dei membri dato

6.18.4.1 distanceEstimated

double it.unibo.torsello.bluetoothpositioning.distanceEstimation.Estimation.distanceEstimated [private]

6.18.4.2 kalmanFilterEnabled

 $boolean\ it.unibo.torsello.bluetoothpositioning.distance Estimation. Estimation. kalman Filter \leftarrow Enabled\ [private]$

6.18.4.3 kf

KFilter it.unibo.torsello.bluetoothpositioning.distanceEstimation.Estimation.kf [private]

6.18.4.4 rawDistanceEstimated

 $\label{lem:double_double} double it.unibo.torsello.bluetoothpositioning.distance \texttt{Estimation.Estimation.rawDistance} \leftarrow \texttt{Estimated} \quad [private]$

6.18.4.5 recentRSSI

 $\label{thm:position} \begin{tabular}{ll} Descriptive Statistics it.unibo.torsello.blue to oth positioning. distance Estimation. Estimation. \\ \leftarrow recent RSSI & [private] \end{tabular}$

6.18.4.6 recentTxPower

 $\label{lem:post_distance} Descriptive Statistics it.unibo.torsello.blue to oth positioning. distance Estimation. \\ Estimation. \\ \leftarrow recent Tx Power \quad [private]$

6.18.4.7 WOSC

double it.unibo.torsello.bluetoothpositioning.distanceEstimation.Estimation.WOSC [private]

La documentazione per questa classe è stata generata a partire dal seguente file:

· Estimation.java

6.19 Riferimenti per la classe it.unibo.torsello.bluetoothpositioning.extra.FABBehavior

Diagramma delle classi per it.unibo.torsello.bluetoothpositioning.extra.FABBehavior

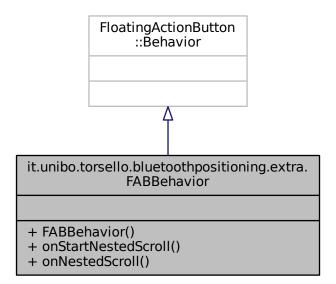
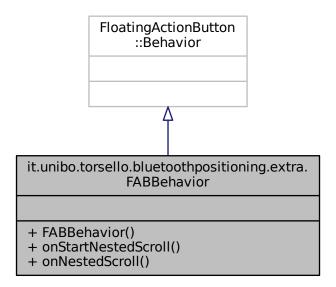


Diagramma di collaborazione per it.unibo.torsello.bluetoothpositioning.extra.FABBehavior:



Membri pubblici

- FABBehavior (Context context, AttributeSet attrs)
- boolean onStartNestedScroll (CoordinatorLayout coordinatorLayout, final FloatingActionButton child, View directTargetChild, View target, int nestedScrollAxes)
- void onNestedScroll (CoordinatorLayout coordinatorLayout, final FloatingActionButton child, View target, int dxConsumed, int dyConsumed, int dyUnconsumed)

6.19.1 Descrizione dettagliata

Created by Federico Torsello. federico.torsello@studio.unibo.it

6.19.2 Documentazione dei costruttori e dei distruttori

6.19.2.1 FABBehavior()

6.19.3 Documentazione delle funzioni membro

6.19.3.1 onNestedScroll()

```
void it.unibo.torsello.bluetoothpositioning.extra.FABBehavior.onNestedScroll (
                                                               CoordinatorLayout coordinatorLayout,
                                                               final FloatingActionButton child,
                                                               View target,
                                                               int dxConsumed,
                                                               int dyConsumed,
                                                               int dxUnconsumed,
                                                                int dyUnconsumed )
34
                                                \verb|super.onNestedScroll(coordinatorLayout, child, target, dxConsumed, dyConsumed, dxUnconsumed, dxU
36
                                                                                   dyUnconsumed);
37
                                                if ((dyConsumed > 0 || dyUnconsumed == 0) && child.getVisibility() == View.VISIBLE) {
38
39
                                                                 child.hide();
                                                                 new Handler().postDelayed(new Runnable() {
41
                                                                                   @Override
42
                                                                                  public void run()
43
                                                                                                  child.show();
44
                                                                 }, 1000);
45
46
```

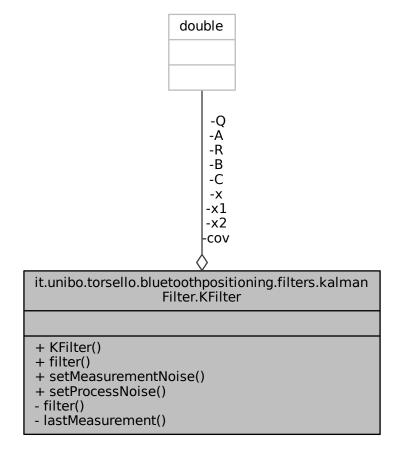
6.19.3.2 onStartNestedScroll()

La documentazione per questa classe è stata generata a partire dal seguente file:

· FABBehavior.java

6.20 Riferimenti per la classe it.unibo.torsello.bluetoothpositioning.filters.kalmanFilter.KFilter

Diagramma di collaborazione per it.unibo.torsello.bluetoothpositioning.filters.kalmanFilter.KFilter:



Membri pubblici

- KFilter (double R, double Q, double A, double B, double C)
- double filter (double z)
- void setMeasurementNoise (double noise)
- void setProcessNoise (double noise)

Membri privati

- double filter (double z, double u)
- double lastMeasurement ()

Attributi privati

- double R
- double Q
- double A
- double B
- double C
- double cov
- double x
- double x1
- double x2

6.20.1 Descrizione dettagliata

Created by Federico Torsello. federico.torsello@studio.unibo.it

6.20.2 Documentazione dei costruttori e dei distruttori

6.20.2.1 KFilter()

```
it.unibo.torsello.bluetoothpositioning.filters.kalmanFilter.KFilter.KFilter ( double R, double Q, double A, double B, double C)
```

Create 1-dimensional kalman filter

Parametri

R	Process noise
Q	Measurement noise
Α	State vector
В	Control vector
С	Measurement vector

```
28
                                                                                     {
            this.R = R;
30
            this.Q = Q;
31
            this.A = A;
this.B = B;
32
33
            this.C = C;
34
35
36
            cov = Double.NaN;
37
            x = Double.NaN;
       }
38
```

6.20.3 Documentazione delle funzioni membro

Filter a new value

Parametri

Z	Measurement
и	Control

Restituisce

Χ

```
52
53
              if (Double.isNaN(x)) {
54
55
                   x = (1 / C) * z;
                    x1 = x;

x2 = x1;
57
                    cov = (1 / C) * Q * (1 / C);
58
              } else {
59
60
                   // Calculate previous update step B = (x - x1) / 2;
61
62
                    // Compute prediction
                   double predX = (A * x) + (B * u);
double predCov = ((A * cov) * A) + R;
65
66
67
68
                    // Kalman gain
69
                   double K = predCov * C * (1 / ((C * predCov * C) + Q));
70
71
72
73
                    // Correction
                   x1 = x;
x = predX + K * (z - (C * predX));
cov = predCov - (K * C * predCov);
74
               }
```

6.20.3.3 lastMeasurement()

```
\label{thm:continuous} double it.unibo.torsello.bluetoothpositioning.filters.kalmanFilter.KFilter.lastMeasurement () \\ [private]
```

Return the last filtered measurement

Restituisce

x Estimated signal without noise

```
85
86     return x;
87 }
```

6.20.3.4 setMeasurementNoise()

```
\label{lem:condition} \mbox{void it.unibo.torsello.bluetoothpositioning.filters.kalmanFilter.KFilter.setMeasurementNoise ( \\ \mbox{double } noise \mbox{)}
```

Set measurement noise INITIAL MEASUREMENT NOISE

Parametri

noise	Measurement noise
-------	-------------------

6.20.3.5 setProcessNoise()

```
\label{local_post_post} \mbox{void it.unibo.torsello.bluetoothpositioning.filters.kalmanFilter.KFilter.setProcessNoise ( \\ \mbox{double } noise \mbox{)}
```

Set the process noise INITIAL_PROCESS_NOISE

Parametri

```
noise Process noise
```

```
103
104 R = noise;
105 }
```

6.20.4 Documentazione dei membri dato

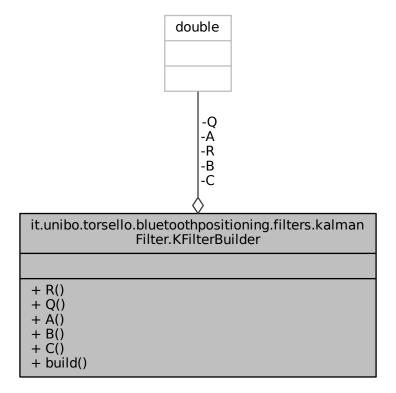
6.20.4.1 A double it.unibo.torsello.bluetoothpositioning.filters.kalmanFilter.KFilter.A [private] 6.20.4.2 B double it.unibo.torsello.bluetoothpositioning.filters.kalmanFilter.KFilter.B [private] 6.20.4.3 C double it.unibo.torsello.bluetoothpositioning.filters.kalmanFilter.KFilter.C [private] 6.20.4.4 cov double it.unibo.torsello.bluetoothpositioning.filters.kalmanFilter.KFilter.cov [private] 6.20.4.5 Q double it.unibo.torsello.bluetoothpositioning.filters.kalmanFilter.KFilter.Q [private] 6.20.4.6 R double it.unibo.torsello.bluetoothpositioning.filters.kalmanFilter.KFilter.R [private] 6.20.4.7 x double it.unibo.torsello.bluetoothpositioning.filters.kalmanFilter.KFilter.x [private] 6.20.4.8 x1 double it.unibo.torsello.bluetoothpositioning.filters.kalmanFilter.KFilter.x1 [private] 6.20.4.9 x2 double it.unibo.torsello.bluetoothpositioning.filters.kalmanFilter.KFilter.x2 [private]

La documentazione per questa classe è stata generata a partire dal seguente file:

KFilter.java

6.21 Riferimenti per la classe it.unibo.torsello.bluetoothpositioning.filters.kalmanFilter.KFilterBuilder

Diagramma di collaborazione per it.unibo.torsello.bluetoothpositioning.filters.kalmanFilter.KFilterBuilder:



Membri pubblici

- KFilterBuilder R (double R)
- KFilterBuilder Q (double Q)
- KFilterBuilder A (double A)
- KFilterBuilder B (double B)
- KFilterBuilder C (double C)
- KFilter build ()

Attributi privati

- double R = 1
- double Q = 1
- double **A** = 1
- double B = 0
- double **C** = 1

6.21.1 Descrizione dettagliata

Created by Federico Torsello. federico.torsello@studio.unibo.it

Simple builder class for 1-dimensional Kalman filter with predefined

6.21.2 Documentazione delle funzioni membro

```
6.21.2.1 A()
```

6.21.2.2 B()

6.21.2.3 build()

6.21.2.4 C()

6.21.2.5 Q()

6.21.2.6 R()

6.21.3 Documentazione dei membri dato

6.21.3.1 A

 $\verb|double it.unibo.torsello.bluetoothpositioning.filters.kalmanFilter.KFilterBuilder.A = 1 \quad [private] \\$

6.21.3.2 B

 $\label{lem:control_double} double it.unibo.torsello.bluetoothpositioning.filters.kalmanFilter.KFilterBuilder.B = 0 \quad [private]$

6.21.3.3 C

double it.unibo.torsello.bluetoothpositioning.filters.kalmanFilter.KFilterBuilder.C = 1 [private]

6.21.3.4 Q

double it.unibo.torsello.bluetoothpositioning.filters.kalmanFilter.KFilterBuilder.Q = 1 [private]

6.21.3.5 R

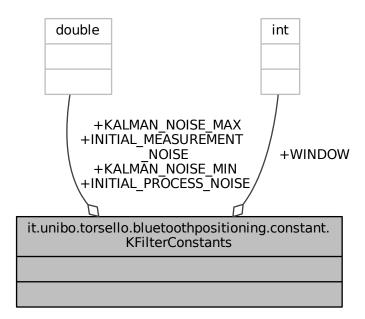
double it.unibo.torsello.bluetoothpositioning.filters.kalmanFilter.KFilterBuilder.R = 1 [private]

La documentazione per questa classe è stata generata a partire dal seguente file:

· KFilterBuilder.java

6.22 Riferimenti per la classe it.unibo.torsello.bluetoothpositioning.constant.KFilterConstants

Diagramma di collaborazione per it.unibo.torsello.bluetoothpositioning.constant.KFilterConstants:



Attributi pubblici statici

- static final double KALMAN_NOISE_MIN = 0D
- static final double KALMAN NOISE MAX = 5D
- static final double INITIAL_PROCESS_NOISE = 5D
- static final double INITIAL_MEASUREMENT_NOISE = 5D
- static final int WINDOW = 5

6.22.1 Descrizione dettagliata

Created by Federico Torsello. federico.torsello@studio.unibo.it

6.22.2 Documentazione dei membri dato

6.22.2.1 INITIAL_MEASUREMENT_NOISE

final double it.unibo.torsello.bluetoothpositioning.constant.KFilterConstants.INITIAL_MEASUR \leftarrow EMENT_NOISE = 5D [static]

104 **INDICE** 6.22.2.2 INITIAL_PROCESS_NOISE $final\ double\ it.unibo.torsello.bluetoothpositioning.constant.KFilterConstants.INITIAL_PROCES \leftrightarrow and all of the constants of the constant of$ S_NOISE = 5D [static] 6.22.2.3 KALMAN_NOISE_MAX $final\ double\ it.unibo.torsello.bluetoothpositioning.constant. KFilterConstants. KALMAN_NOISE_MAX$ = 5D [static] 6.22.2.4 KALMAN_NOISE_MIN final double it.unibo.torsello.bluetoothpositioning.constant.KFilterConstants.KALMAN_NOISE_MIN = 0D [static] 6.22.2.5 WINDOW $final int it.unibo.torsello.bluetoothpositioning.constant.KFilterConstants.WINDOW = 5 \quad [static] \\$ La documentazione per questa classe è stata generata a partire dal seguente file: • KFilterConstants.java

6.23 Riferimenti per la classe it.unibo.torsello.bluetoothpositioning.activities.MainActivity

Diagramma delle classi per it.unibo.torsello.bluetoothpositioning.activities.MainActivity

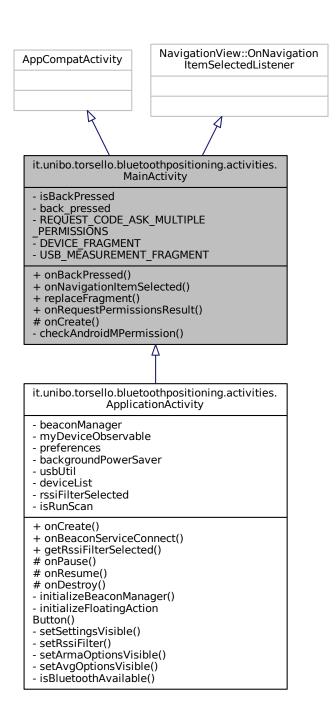
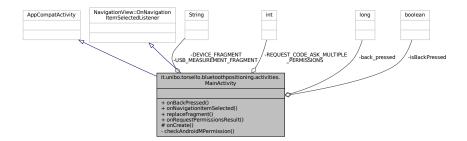


Diagramma di collaborazione per it.unibo.torsello.bluetoothpositioning.activities.MainActivity:



Membri pubblici

- void onBackPressed ()
- · boolean onNavigationItemSelected (MenuItem item)
- void replaceFragment (String fragTag)
- void onRequestPermissionsResult (int requestCode, @NonNull String permissions[], @NonNull int[] grant

 Results)

Membri protetti

void onCreate (Bundle savedInstanceState)

Membri privati

• void checkAndroidMPermission ()

Attributi privati

- boolean isBackPressed = false
- · long back_pressed
- final int REQUEST_CODE_ASK_MULTIPLE_PERMISSIONS = 124

Attributi privati statici

- static final String DEVICE_FRAGMENT = "device"
- static final String USB_MEASUREMENT_FRAGMENT = "usb measurement"

6.23.1 Descrizione dettagliata

Created by Federico Torsello. federico.torsello@studio.unibo.it

6.23.2 Documentazione delle funzioni membro

6.23.2.1 checkAndroidMPermission()

```
void it.unibo.torsello.bluetoothpositioning.activities.MainActivity.checkAndroidMPermission (
) [private]
165
166
167
             if (Build.VERSION.SDK_INT >= Build.VERSION_CODES.M) {
168
                 final List<String> permissions = new ArrayList<>();
169
                 if (checkSelfPermission(Manifest.permission.ACCESS_FINE_LOCATION)
170
                          != PackageManager.PERMISSION_GRANTED) {
171
172
                      permissions.add(Manifest.permission.ACCESS_FINE_LOCATION);
173
                 }
174
175
                 if (checkSelfPermission(Manifest.permission.ACCESS_COARSE_LOCATION)
176
                     != PackageManager.PERMISSION_GRANTED) {
permissions.add(Manifest.permission.ACCESS_COARSE_LOCATION);
177
178
                 }
179
180
                 if (!permissions.isEmpty())
181
                     new AlertDialog.Builder(this)
182
                               .setTitle(R.string.dialog_location_access_title)
183
                               .setMessage(R.string.dialog_bluetooth_text)
.setPositiveButton(android.R.string.ok, null)
184
185
                               .setOnDismissListener(new DialogInterface.OnDismissListener() {
186
                                   @TargetApi(23)
187
                                   @Override
188
                                   public void onDismiss(DialogInterface dialog) {
                                       requestPermissions(permissions.toArray(new String[permissions.size()]),
189
                                                REQUEST_CODE_ASK_MULTIPLE_PERMISSIONS
190
      );
191
192
193
                               }).show();
194
195
196
```

6.23.2.2 onBackPressed()

```
\verb|void it.unibo.torsello.bluetoothpositioning.activities.MainActivity.onBackPressed ()|\\
```

```
68
69
70
           DrawerLayout drawer = (DrawerLayout) findViewById(R.id.drawer_layout);
71
           if (drawer.isDrawerOpen(GravityCompat.START)) {
72
               drawer.closeDrawer(GravityCompat.START);
7.3
           } else if (drawer.isDrawerOpen(GravityCompat.END)) {
74
               drawer.closeDrawer(GravityCompat.END);
75
           } else {
76
77
               replaceFragment(DEVICE_FRAGMENT);
78
79
               final long DOUBLE_PRESS_INTERVAL = 1500L;
               if (!isBackPressed || back_pressed + DOUBLE_PRESS_INTERVAL <= System.</pre>
80
      currentTimeMillis()) {
81
                    isBackPressed = true;
82
                    FloatingActionButton fab = (FloatingActionButton) findViewById(R.id.fab);
                    assert fab != null;
83
                   Snackbar.make(fab, R.string.snackBar_exit, Snackbar.LENGTH_SHORT).show();
84
               } else {
85
                   super.finish();
86
               back_pressed = System.currentTimeMillis();
89
           }
90
```

6.23.2.3 onCreate()

```
void it.unibo.torsello.bluetoothpositioning.activities.MainActivity.onCreate (
              Bundle savedInstanceState ) [protected]
45
46
           super.onCreate(savedInstanceState);
47
           setContentView(R.layout.activity_main);
48
           Toolbar toolbar = (Toolbar) findViewById(R.id.toolbar);
49
           setSupportActionBar(toolbar);
50
51
           DrawerLayout drawer = (DrawerLayout) findViewById(R.id.drawer_layout);
53
           ActionBarDrawerToggle toggle = new ActionBarDrawerToggle(
54
                   this, drawer, toolbar, R.string.navigation_drawer_open, R.string.navigation_drawer_close);
5.5
           drawer.addDrawerListener(toggle);
56
           toggle.syncState();
58
           ((NavigationView) findViewById(R.id.nav_view)).setNavigationItemSelectedListener(this);
59
60
           ((NavigationView) findViewById(R.id.nav_view2)).setNavigationItemSelectedListener(this);
61
62
           replaceFragment (DEVICE_FRAGMENT);
63
           checkAndroidMPermission();
65
```

6.23.2.4 onNavigationItemSelected()

```
\verb|boolean| it.unibo.torsello.bluetoothpositioning.activities.MainActivity.onNavigationItem \leftarrow |
Selected (
               MenuItem item )
94
9.5
96
           DrawerLayout drawer = (DrawerLayout) findViewById(R.id.drawer_layout);
98
           // Handle navigation view item clicks here.
99
           switch (item.getItemId()) {
100
                case R.id.nav_home:
101
                     replaceFragment(DEVICE_FRAGMENT);
102
                    break:
103
                case R.id.nav_settings:
104
                    drawer.openDrawer(GravityCompat.END);
105
                    break;
106
                 case R.id.nav_measurement:
                    replaceFragment(USB_MEASUREMENT_FRAGMENT);
107
108
                    break;
109
            }
110
            if (drawer.isDrawerOpen(GravityCompat.START)) {
112
                 drawer.closeDrawer(GravityCompat.START);
113
114
115
            return true:
116
```

6.23.2.5 onRequestPermissionsResult()

```
void it.unibo.torsello.bluetoothpositioning.activities.MainActivity.onRequestPermissionsResult
(
    int requestCode,
    @NonNull String permissions[],
    @NonNull int [] grantResults)
```

```
138
                                                                                                       {
139
                switch (requestCode) {
140
                     case REQUEST_CODE_ASK_MULTIPLE_PERMISSIONS:
141
                          for (int i = 0; i < permissions.length; i++) {</pre>
                                if (grantResults[i] == PackageManager.PERMISSION_GRANTED) {
    Log.d(TAG_CLASS, "Permission Granted: " + permissions[i]);
} else if (grantResults[i] == PackageManager.PERMISSION_DENIED) {
    Log.d(TAG_CLASS, "Permission Denied: " + permissions[i]);
142
143 //
144
145 //
146
                                      new AlertDialog.Builder(this)
147
                                                 . \verb|setTitle| (R.string.dialog_permissions_location_access\_title)|\\
148
                                                 . \verb|setMessage(R.string.dialog_permissions_location_access\_text)|\\
149
                                                 .setPositiveButton(android.R.string.ok, null)
150
                                                 .setOnDismissListener(new DialogInterface.OnDismissListener() {
151
152
                                                      @Override
153
                                                      public void onDismiss(DialogInterface dialog) {
154
155
156
                                                }).show();
157
                                }
158
                          break;
159
                     default:
160
161
                           super.onRequestPermissionsResult(requestCode, permissions, grantResults);
162
163
          }
```

6.23.2.6 replaceFragment()

```
void it.unibo.torsello.bluetoothpositioning.activities.MainActivity.replaceFragment (
              String fragTag )
119
           Fragment currentFragment = getSupportFragmentManager().findFragmentByTag(fragTag);
120
           switch (fragTag) {
               case DEVICE_FRAGMENT:
121
122
                   currentFragment = DeviceListFragment.newInstance();
123
124
               case USB_MEASUREMENT_FRAGMENT:
125
                   currentFragment = UsbMeasurementFragment.newInstance();
126
                   break;
127
           }
128
129
            if (currentFragment != null) {
130
               getSupportFragmentManager().beginTransaction()
131
                       .replace(R.id.contentMainLayout, currentFragment, fragTag)
132
                        .commit();
133
            }
       }
134
```

6.23.3 Documentazione dei membri dato

6.23.3.1 back_pressed

long it.unibo.torsello.bluetoothpositioning.activities.MainActivity.back pressed [private]

6.23.3.2 DEVICE FRAGMENT

final String it.unibo.torsello.bluetoothpositioning.activities.MainActivity.DEVICE_FRAGMENT =
"device" [static], [private]

6.23.3.3 isBackPressed

boolean it.unibo.torsello.bluetoothpositioning.activities.MainActivity.isBackPressed = false
[private]

6.23.3.4 REQUEST_CODE_ASK_MULTIPLE_PERMISSIONS

final int it.unibo.torsello.bluetoothpositioning.activities.MainActivity.REQUEST_CODE_ASK_MU \leftarrow LTIPLE_PERMISSIONS = 124 [private]

6.23.3.5 USB MEASUREMENT FRAGMENT

final String it.unibo.torsello.bluetoothpositioning.activities.MainActivity.USB_MEASUREMENT_←
FRAGMENT = "usb measurement" [static], [private]

La documentazione per questa classe è stata generata a partire dal seguente file:

· MainActivity.java

6.24 Riferimenti per la classe it.unibo.torsello.bluetoothpositioning.filters.MyArmaRssiFilter

Diagramma delle classi per it.unibo.torsello.bluetoothpositioning.filters.MyArmaRssiFilter

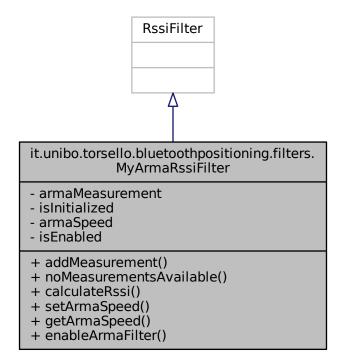
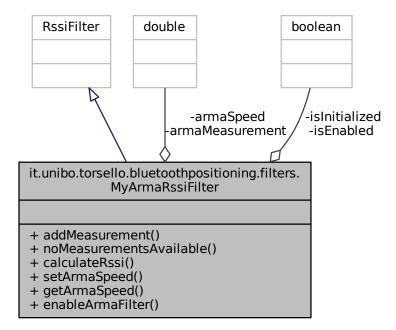


Diagramma di collaborazione per it.unibo.torsello.bluetoothpositioning.filters.MyArmaRssiFilter:



Membri pubblici

- void addMeasurement (Integer rssi)
- boolean noMeasurementsAvailable ()
- double calculateRssi ()

Membri pubblici statici

- static void setArmaSpeed (double arma_speed)
- static double getArmaSpeed ()
- static void enableArmaFilter (boolean set)

Attributi privati

- · double armaMeasurement
- boolean isInitialized = false

Attributi privati statici

- static double armaSpeed = 0.1D
- static boolean isEnabled = true

6.24.1 Descrizione dettagliata

Created by Federico Torsello. federico.torsello@studio.unibo.it

6.24.2 Documentazione delle funzioni membro

```
6.24.2.1 addMeasurement()
```

```
void\ it.unibo.torsello.bluetoothpositioning.filters.MyArmaRssiFilter.addMeasurement\ (
              Integer rssi )
30
31
32
           if (isEnabled) {
33
               if (!isInitialized) {
34
                  armaMeasurement = rssi;
                   isInitialized = true;
35
36
37
38
               armaMeasurement = (armaMeasurement -
      armaSpeed * (armaMeasurement - rssi));
          } else {
39
               armaMeasurement = rssi;
40
41
42
```

6.24.2.2 calculateRssi()

6.24.2.3 enableArmaFilter()

6.24.2.4 getArmaSpeed()

```
static\ double\ it.unibo.torsello.bluetoothpositioning.filters. My ArmaRssiFilter.get ArmaSpeed\ (\ ) \\ [static]
```

6.24.2.5 noMeasurementsAvailable()

```
boolean it.unibo.torsello.bluetoothpositioning.filters.MyArmaRssiFilter.noMeasurementsAvailable
( )

46
47     return false;
48 }
```

6.24.2.6 setArmaSpeed()

6.24.3 Documentazione dei membri dato

6.24.3.1 armaMeasurement

double it.unibo.torsello.bluetoothpositioning.filters.MyArmaRssiFilter.armaMeasurement [private]

6.24.3.2 armaSpeed

double it.unibo.torsello.bluetoothpositioning.filters.MyArmaRssiFilter.armaSpeed = 0.1D [static],
[private]

6.24.3.3 isEnabled

boolean it.unibo.torsello.bluetoothpositioning.filters.MyArmaRssiFilter.isEnabled = true [static],
[private]

6.24.3.4 isInitialized

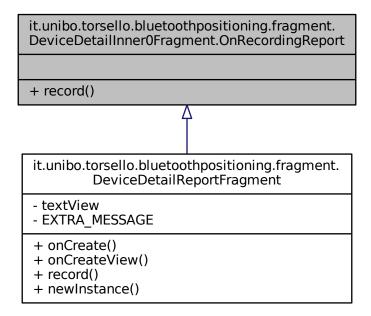
boolean it.unibo.torsello.bluetoothpositioning.filters.MyArmaRssiFilter.isInitialized = false
[private]

La documentazione per questa classe è stata generata a partire dal seguente file:

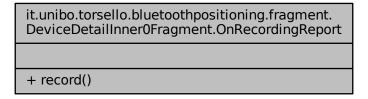
· MyArmaRssiFilter.java

6.25 Riferimenti per l'interfaccia it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInner0← Fragment.OnRecordingReport

 $\label{lem:delta-delta$



 $\label{lem:decomposition} Diagramma\ di\ collaborazione\ per\ it.unibo.torsello.bluetoothpositioning.fragment. Device DetailInner 0\ Fragment. On \leftarrow Recording Report:$



Membri pubblici

• void record (String newRecord)

6.25.1 Documentazione delle funzioni membro

6.25.1.1 record()

```
void it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInner0Fragment.OnRecording \leftarrow Report.record (
String newRecord)
```

Implementato in it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailReportFragment.

La documentazione per questa interfaccia è stata generata a partire dal seguente file:

- DeviceDetailInner0Fragment.java
- 6.26 Riferimenti per l'interfaccia it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInner0← Fragment.OnRecordingResume

 $\label{lem:delta$

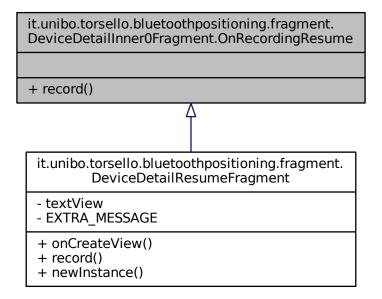
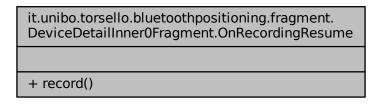


Diagramma di collaborazione per it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInner0Fragment.On← RecordingResume:



Membri pubblici

• void record (String newRecord)

6.26.1 Documentazione delle funzioni membro

6.26.1.1 record()

```
void it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInner0Fragment.OnRecording \leftarrow Resume.record (
String newRecord)
```

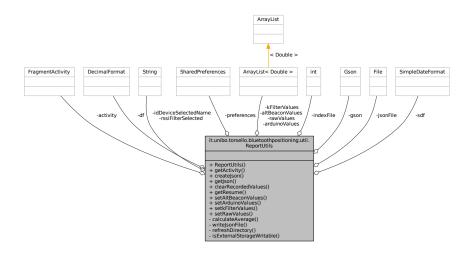
 $Implementato\ in\ it. unibo. torsello. blue to oth positioning. fragment. Device Detail Resume Fragment.$

La documentazione per questa interfaccia è stata generata a partire dal seguente file:

• DeviceDetailInner0Fragment.java

6.27 Riferimenti per la classe it.unibo.torsello.bluetoothpositioning.util.ReportUtils

Diagramma di collaborazione per it.unibo.torsello.bluetoothpositioning.util.ReportUtils:



Membri pubblici

- ReportUtils (FragmentActivity fragmentActivity, String deviceName)
- FragmentActivity getActivity ()
- · void createJson ()
- String getJson ()
- void clearRecordedValues ()
- String getResume ()
- · void setAltBeaconValues (Double altBeaconValues)
- · void setArduinoValues (Double arduinoValues)
- void setkFilterValues (Double kFilterValues)
- void setRawValues (Double rawValues)

Membri privati

- double calculateAverage (ArrayList< Double > value)
- void writeJsonFile ()
- · void refreshDirectory (File file)
- boolean isExternalStorageWritable ()

Attributi privati

- Gson gson
- String idDeviceSelectedName
- int indexFile = 0
- String rssiFilterSelected
- ArrayList< Double > arduinoValues
- ArrayList< Double > rawValues
- ArrayList< Double > altBeaconValues
- ArrayList< Double > kFilterValues
- · SimpleDateFormat sdf
- · DecimalFormat df
- FragmentActivity activity
- File jsonFile
- SharedPreferences preferences

6.27.1 Descrizione dettagliata

Created by federico on 11/10/16.

6.27.2 Documentazione dei costruttori e dei distruttori

6.27.2.1 ReportUtils()

```
it.unibo.torsello.bluetoothpositioning.util.ReportUtils.ReportUtils (
               FragmentActivity fragmentActivity,
               String deviceName )
62
           this.activity = fragmentActivity;
this.idDeviceSelectedName = deviceName;
63
64
65
66
           arduinoValues = new ArrayList<>();
           rawValues = new ArrayList<>();
           altBeaconValues = new ArrayList<>();
68
69
           kFilterValues = new ArrayList<>();
70
71
           sdf = new SimpleDateFormat("dd-MMM-yyyy", Locale.getDefault());
72
73
           df = new DecimalFormat("00", DecimalFormatSymbols.getInstance());
74
75
76
           gson = new GsonBuilder().setPrettyPrinting().create();
77
           preferences = getActivity().
78
                   getSharedPreferences(SettingConstants.SETTINGS_PREFERENCES, 0);
80
```

6.27.3 Documentazione delle funzioni membro

6.27.3.1 calculateAverage()

```
\verb|double it.unibo.torsello.bluetoothpositioning.util.ReportUtils.calculate \verb|Average|| (
               ArrayList< Double > value ) [private]
230
231
            Double sum = OD;
232
            if(!value.isEmpty()) {
233
                for (Double mark : value) {
234
                    sum += mark;
235
236
                return sum / value.size();
237
238
            return sum;
```

6.27.3.2 clearRecordedValues()

6.27.3.3 createJson()

```
void it.unibo.torsello.bluetoothpositioning.util.ReportUtils.createJson ( )
86
88
           String formattedDate = sdf.format(Calendar.getInstance().getTime());
89
90
           double processNoise = preferences.getFloat(SettingConstants.KALMAN_NOISE_VALUE, 0);
91
           String tempFilter = "";
92
93
           if (rssiFilterSelected != null) {
               tempFilter = rssiFilterSelected;
95
96
97
           rssiFilterSelected = ((ApplicationActivity)
      getActivity()).getRssiFilterSelected();
98
99
           if (!rssiFilterSelected.equals(tempFilter)) {
100
                 indexFile = 0;
101
            }
102
103
            if (isExternalStorageWritable()) {
104
                File root = Environment.getExternalStorageDirectory();
105
106
                File dir = new File(root.getAbsolutePath()
107
                         + File.separator
                         + getActivity().getString(R.string.app_name)
+ " Report");
108
109
                dir.mkdirs();
110
111
112
                File subDir1 = new File(dir.getAbsolutePath() + File.separator
113
                         + formattedDate);
114
                subDir1.mkdirs();
115
116
                File subDir2 = new File(subDir1.getAbsolutePath() + File.separator
117
                         + "KF process noise " + processNoise);
118
                subDir2.mkdirs();
119
120
                File subDir3 = new File(subDir2.getAbsolutePath() + File.separator
121
                         + rssiFilterSelected);
                subDir3.mkdirs();
122
123
124
                String fileName = String.format(idDeviceSelectedName + " - %s.json",
      df.format(indexFile));
125
126
                jsonFile = new File(subDir3, fileName);
127
128
                if (jsonFile.exists()) {
129
                     if (!rssiFilterSelected.equals(tempFilter)) {
130
                         indexFile = 0;
131
132
                         String name = jsonFile.getName();
                         String substring = name.substring(name.length() - 7, name.length() - 5); indexFile = Integer.parseInt(substring);
133
134
135
                         indexFile++;
                         fileName = String.format(idDeviceSelectedName + " - %s.json",
136
      df.format(indexFile));
137
                         jsonFile = new File(subDir3, fileName);
138
139
140
                } else {
141
                     indexFile = 0;
142
143
144
145
                     jsonFile.createNewFile();
                } catch (IOException e) {
146
147
                     e.printStackTrace();
148
149
150
                writeJsonFile();
151
152
                refreshDirectory(jsonFile);
153
154
155
        }
```

6.27.3.4 getActivity()

Fragment Activity it.unibo.torsello.bluetooth positioning.util. Report Utils.get Activity ()

```
82
                      return activity;
84
6.27.3.5 getJson()
String it.unibo.torsello.bluetoothpositioning.util.ReportUtils.getJson ( )
157
159
                        String temp = "";
160
161
                        try {
                                FileInputStream fin = new FileInputStream(jsonFile);
162
163
164
                                int chars;
165
166
                                while ((chars = fin.read()) != -1) {
167
                                        temp = temp + Character.toString((char) chars);
168
169
170
                                //string temp contains all the data of the file.
171
                                fin.close();
172
                        } catch (IOException e) {
173
                                e.printStackTrace();
174
175
                        return temp;
176
6.27.3.6 getResume()
String it.unibo.torsello.bluetoothpositioning.util.ReportUtils.getResume ( )
185
                                                                  {
186
                        boolean isKalmanFilterEnabled = preferences
187
188
                                        .getBoolean (SettingConstants.KALMAN_FILTER_ENABLED, false);
189
190
                       StringBuilder sb = new StringBuilder();
191
192
                        String min = "Min ";
                        String max = "Max ";
193
194
                       String avg = "AVG ";
195
196
                        String arduino = "Arduino values: ";
197
                        String altBeacon = "AltBeacon values: ";
198
                        String raw = "Raw values: ";
                        String kf = "Kalman Filter values: ";
199
200
201
                        if (!arduinoValues.isEmpty()) {
202
                                sb.append(min).append(arduino).append(Collections.min(arduinoValues)).append("\n")
203
                                204
                                sb.append(avg).append(arduino).append(calculateAverage(
            arduinoValues)).append("\n");
205
206
                                sb.append("\n\n");
207
208
                        \verb|sb.append(min).append(raw).append(Collections.min(rawValues)).append("\n");\\
209
                        sb.append(max).append(raw).append(Collections.max(rawValues)).append("\n");
210
211
                        sb.append(avg).append(raw).append(calculateAverage(
            rawValues)).append("\n");
212
213
                        sb.append("\n\n");
214
215
                        ");
216
                        \verb|sb.append(max).append(altBeacon).append(Collections.max(altBeaconValues)).append("\\ \\ | name of the converse of the conver
            ");
217
                        sb.append(avg).append(altBeacon).append(calculateAverage(
            altBeaconValues)).append("\n");
218
219
                        sb.append("\n\n");
220
```

```
221
            if (isKalmanFilterEnabled) {
222
               \verb|sb.append(min).append(kf).append(Collections.min(kFilterValues)).append("\n");\\
223
               \verb|sb.append(max).append(kf).append(Collections.max(kFilterValues)).append("\n");\\
     sb.append(avg).append(kf).append(calculateAverage(kFilterValues)).append("\n");\\
224
225
226
227
            return String.valueOf(sb);
228
6.27.3.7 isExternalStorageWritable()
boolean it.unibo.torsello.bluetoothpositioning.util.ReportUtils.isExternalStorageWritable ( )
[private]
326
327
            String state = Environment.getExternalStorageState();
328
           if (Environment.MEDIA_MOUNTED.equals(state)) {
329
               return true;
330
           Log.d("sure", "not writeable");
331
332
           return false;
333
6.27.3.8 refreshDirectory()
void it.unibo.torsello.bluetoothpositioning.util.ReportUtils.refreshDirectory (
              File file ) [private]
311
312
            if (file != null) {
               Intent mediaScanIntent = new Intent(Intent.ACTION_MEDIA_SCANNER_SCAN_FILE);
313
               mediaScanIntent.setData(Uri.fromFile(file));
314
315
               getActivity().sendBroadcast(mediaScanIntent);
316
317
               Snackbar.make(getActivity().findViewById(R.id.fab),
318
                       "Report saved", Snackbar.LENGTH_SHORT).show();
319
            } else {
320
               Snackbar.make(getActivity().findViewById(R.id.fab),
                       "Report retrieval failed", Snackbar.LENGTH_SHORT).show();
321
323
6.27.3.9 setAltBeaconValues()
Double altBeaconValues )
335
336
           this.altBeaconValues.add(altBeaconValues);
6.27.3.10 setArduinoValues()
\verb|void| it.unibo.torsello.bluetoothpositioning.util.ReportUtils.setArduinoValues | (
```

339 340

341

Double arduinoValues)

this.arduinoValues.add(arduinoValues);

6.27.3.11 setkFilterValues()

```
void it.unibo.torsello.bluetoothpositioning.util.ReportUtils.setkFilterValues (
               Double kFilterValues )
343
            this.kFilterValues.add(kFilterValues);
344
345
6.27.3.12 setRawValues()
void it.unibo.torsello.bluetoothpositioning.util.ReportUtils.setRawValues (
               Double rawValues )
347
348
            this.rawValues.add(rawValues);
349
6.27.3.13 writeJsonFile()
void it.unibo.torsello.bluetoothpositioning.util.ReportUtils.writeJsonFile ( ) [private]
241
242
            String formattedDate = sdf.format(Calendar.getInstance().getTime());
            SimpleDateFormat sdf2 = new SimpleDateFormat("hh:mm", Locale.getDefault());
243
244
            String time = sdf2.format(Calendar.getInstance().getTime());
245
246
            double processNoise = preferences.getFloat(SettingConstants.KALMAN_NOISE_VALUE, 0);
247
            boolean isKalmanFilterEnabled = preferences.getBoolean(SettingConstants.
      KALMAN_FILTER_ENABLED, false);
248
249
250
                Writer writer = new FileWriter(jsonFile);
251
252
                JsonWriter jw = gson.newJsonWriter(writer);
253
254
                jw.beginObject();
255
                    jw.name("id").value("report " + df.format(indexFile));
256
                    jw.name("date").value(formattedDate);
257
258
                    jw.name("time").value(time);
259
                    jw.name("filter").value(rssiFilterSelected);
                    jw.name("distance_estimation");
260
                    jw.beginObject();
261
262
263
                        jw.name("arduino");
264
                        if (arduinoValues.isEmpty()) {
265
                            jw.value("no data");
266
                        } else {
2.67
                            jw.beginArray();
268
                            for (Double value : arduinoValues) {
269
                                jw.value(value);
271
                            jw.endArray();
2.72
273
274
                        iw.name("raw");
275
                        jw.beginArray();
276
                        for (Double value : rawValues) {
277
                            jw.value(value);
278
279
                        jw.endArray();
280
                        jw.name("altbeacon");
281
282
                        jw.beginArray();
283
                        for (Double value : altBeaconValues) {
284
                            jw.value(value);
285
286
                        jw.endArray();
287
288
                        jw.name("kFilter");
289
                        if (isKalmanFilterEnabled) {
```

```
290
                             jw.name("kFilter_processNoise").value(processNoise);
291
                             jw.beginArray();
292
                             for (Double value : kFilterValues) {
293
                                 jw.value(value);
294
295
                             jw.endArray();
296
                         } else {
297
                             jw.value(getActivity().getString(R.string.kalman_filter_disabled));
298
299
                     jw.endObject();
300
301
302
                jw.endObject();
303
304
                writer.close();
305
            } catch (IOException e) {
306
                e.printStackTrace();
307
308
        }
```

6.27.4 Documentazione dei membri dato

6.27.4.1 activity

FragmentActivity it.unibo.torsello.bluetoothpositioning.util.ReportUtils.activity [private]

6.27.4.2 altBeaconValues

ArrayList<Double> it.unibo.torsello.bluetoothpositioning.util.ReportUtils.altBeaconValues [private]

6.27.4.3 arduinoValues

ArrayList<Double> it.unibo.torsello.bluetoothpositioning.util.ReportUtils.arduinoValues [private]

6.27.4.4 df

DecimalFormat it.unibo.torsello.bluetoothpositioning.util.ReportUtils.df [private]

6.27.4.5 gson

 ${\tt Gson\ it.unibo.torsello.bluetoothpositioning.util.Report \tt Utils.gson\ [private]$

6.27.4.6 idDeviceSelectedName

String it.unibo.torsello.bluetoothpositioning.util.ReportUtils.idDeviceSelectedName [private]

6.27.4.7 indexFile

int it.unibo.torsello.bluetoothpositioning.util.ReportUtils.indexFile = 0 [private]

6.27.4.8 jsonFile

File it.unibo.torsello.bluetoothpositioning.util.ReportUtils.jsonFile [private]

6.27.4.9 kFilterValues

ArrayList<Double> it.unibo.torsello.bluetoothpositioning.util.ReportUtils.kFilterValues [private]

6.27.4.10 preferences

SharedPreferences it.unibo.torsello.bluetoothpositioning.util.ReportUtils.preferences [private]

6.27.4.11 rawValues

ArrayList<Double> it.unibo.torsello.bluetoothpositioning.util.ReportUtils.rawValues [private]

6.27.4.12 rssiFilterSelected

String it.unibo.torsello.bluetoothpositioning.util.ReportUtils.rssiFilterSelected [private]

6.27.4.13 sdf

SimpleDateFormat it.unibo.torsello.bluetoothpositioning.util.ReportUtils.sdf [private]

La documentazione per questa classe è stata generata a partire dal seguente file:

· ReportUtils.java

6.28 Riferimenti per la classe it.unibo.torsello.bluetoothpositioning.task.SavelmageTask

Diagramma delle classi per it.unibo.torsello.bluetoothpositioning.task.SaveImageTask

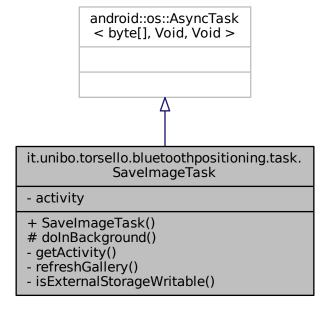
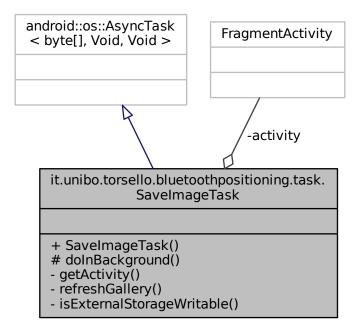


Diagramma di collaborazione per it.unibo.torsello.bluetoothpositioning.task.SaveImageTask:



Membri pubblici

• SaveImageTask (FragmentActivity fragmentActivity)

Membri protetti

• Void doInBackground (byte[]... data)

Membri privati

- FragmentActivity getActivity ()
- void refreshGallery (File file)
- boolean isExternalStorageWritable ()

Attributi privati

· FragmentActivity activity

6.28.1 Descrizione dettagliata

Created by Federico Torsello. federico.torsello@studio.unibo.it

6.28.2 Documentazione dei costruttori e dei distruttori

6.28.2.1 SavelmageTask()

6.28.3 Documentazione delle funzioni membro

6.28.3.1 dolnBackground()

```
\label{thm:point} Void it.unibo.torsello.bluetoothpositioning.task.SaveImageTask.doInBackground \ (it) and it.un
                                                     byte... [] data ) [protected]
                                                                                                                                                                                                  {
36
37
                                         // Write to disk
38
                                         if (isExternalStorageWritable()) {
                                                       File root = Environment.getExternalStorageDirectory();
39
40
                                                       File dir = new File(root.getAbsolutePath() + File.separator
41
                                                                                     + getActivity().getString(R.string.app_name));
42
                                                       dir.mkdir();
43
                                                       String fileName = String.format(Locale.getDefault(), "%d.jpg", System.currentTimeMillis());
44
                                                       File outFile = new File(dir, fileName);
45
46
                                                       try {
48
                                                                     FileOutputStream outStream = new FileOutputStream(outFile);
                                                                      outStream.write(data[0]);
49
50
                                                                      outStream.flush();
51
                                                                    outStream.close();
52
53
                                                                     refreshGallery(outFile);
                                                       } catch (IOException e) {
55
                                                                     e.printStackTrace();
56
57
                                         return null;
58
59
```

6.28.3.2 getActivity()

6.28.3.3 isExternalStorageWritable()

6.28.3.4 refreshGallery()

```
void it.unibo.torsello.bluetoothpositioning.task.SaveImageTask.refreshGallery (
               File file ) [private]
           if (file != null) {
                Intent mediaScanIntent = new Intent(Intent.ACTION_MEDIA_SCANNER_SCAN_FILE);
                mediaScanIntent.setData(Uri.fromFile(file));
64
6.5
                getActivity().sendBroadcast(mediaScanIntent);
66
                Snackbar.make(getActivity().findViewById(R.id.fab),
                         "Your picture has been saved", Snackbar.LENGTH_SHORT).show();
69
           } else {
                Snackbar.make(getActivity().findViewById(R.id.fab),
    "Image retrieval failed", Snackbar.LENGTH_SHORT).show();
70
71
72
73
       }
```

6.28.4 Documentazione dei membri dato

6.28.4.1 activity

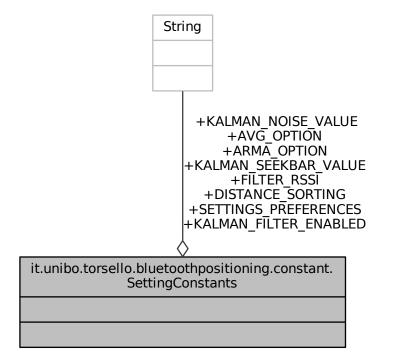
FragmentActivity it.unibo.torsello.bluetoothpositioning.task.SaveImageTask.activity [private]

La documentazione per questa classe è stata generata a partire dal seguente file:

· SaveImageTask.java

6.29 Riferimenti per la classe it.unibo.torsello.bluetoothpositioning.constant.SettingConstants

Diagramma di collaborazione per it.unibo.torsello.bluetoothpositioning.constant.SettingConstants:



Attributi pubblici statici

- static final String SETTINGS_PREFERENCES = "settings_preferences"
- static final String FILTER_RSSI = "filter_rssi"
- static final String ARMA OPTION = "arma option"
- static final String AVG_OPTION = "avg_option"
- static final String KALMAN_SEEKBAR_VALUE = "kalman_filter_seek_value"
- static final String KALMAN_NOISE_VALUE = "kalman_filter_noise_value"
- static final String KALMAN_FILTER_ENABLED = "kalma_filrer_enabled"
- static final String DISTANCE_SORTING = "distance_sorting_selected"

6.29.1 Descrizione dettagliata

Created by Federico Torsello. federico.torsello@studio.unibo.it

A class containing constants for the SharedPreference objects.

6.29.2 Documentazione dei membri dato

6.29.2.1 ARMA_OPTION

final String it.unibo.torsello.bluetoothpositioning.constant.SettingConstants.ARMA_OPTION =
"arma_option" [static]

6.29.2.2 AVG OPTION

final String it.unibo.torsello.bluetoothpositioning.constant.SettingConstants.AVG_OPTION =
"avg_option" [static]

6.29.2.3 DISTANCE_SORTING

final String it.unibo.torsello.bluetoothpositioning.constant.SettingConstants.DISTANCE_SORTING
= "distance_sorting_selected" [static]

6.29.2.4 FILTER_RSSI

final String it.unibo.torsello.bluetoothpositioning.constant.SettingConstants.FILTER_RSSI =
"filter_rssi" [static]

6.29.2.5 KALMAN_FILTER_ENABLED

final String it.unibo.torsello.bluetoothpositioning.constant.SettingConstants.KALMAN_FILTER_ \leftarrow ENABLED = "kalma_filrer_enabled" [static]

6.29.2.6 KALMAN_NOISE_VALUE

final String it.unibo.torsello.bluetoothpositioning.constant.SettingConstants.KALMAN_NOISE_V \leftarrow ALUE = "kalman_filter_noise_value" [static]

6.29.2.7 KALMAN_SEEKBAR_VALUE

final String it.unibo.torsello.bluetoothpositioning.constant.SettingConstants.KALMAN_SEEKBAR←
_VALUE = "kalman_filter_seek_value" [static]

6.29.2.8 SETTINGS_PREFERENCES

final String it.unibo.torsello.bluetoothpositioning.constant.SettingConstants.SETTINGS_PREFE←
RENCES = "settings_preferences" [static]

La documentazione per questa classe è stata generata a partire dal seguente file:

· SettingConstants.java

6.30 Riferimenti per la classe it.unibo.torsello.bluetoothpositioning.fragment.SettingsFragment

Diagramma delle classi per it.unibo.torsello.bluetoothpositioning.fragment.SettingsFragment

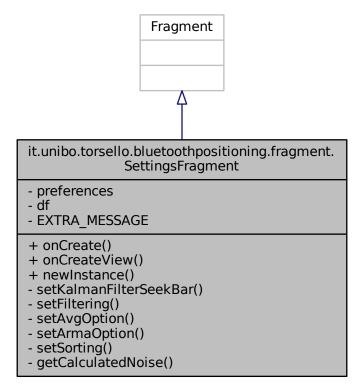
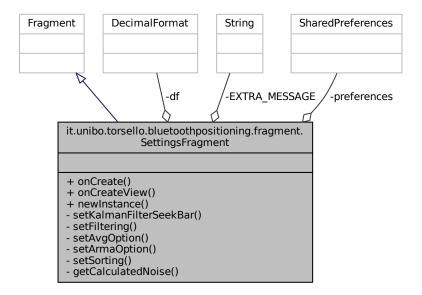


Diagramma di collaborazione per it.unibo.torsello.bluetoothpositioning.fragment.SettingsFragment:



Membri pubblici

- void onCreate (Bundle savedInstanceState)
- · View onCreateView (LayoutInflater inflater, ViewGroup container, Bundle savedInstanceState)

Membri pubblici statici

• static SettingsFragment newInstance ()

Membri privati

- void setKalmanFilterSeekBar (View root)
- void setFiltering (View root)
- void setAvgOption (View root)
- void setArmaOption (View root)
- void setSorting (View root)

Membri privati statici

• static float getCalculatedNoise (int p)

Attributi privati

- SharedPreferences preferences
- DecimalFormat df

Attributi privati statici

• static final String EXTRA_MESSAGE = "EXTRA_MESSAGE"

6.30.1 Descrizione dettagliata

Created by Federico Torsello. federico.torsello@studio.unibo.it

6.30.2 Documentazione delle funzioni membro

6.30.2.1 getCalculatedNoise()

6.30.2.2 newInstance()

6.30.2.3 onCreate()

6.30.2.4 onCreateView()

```
{\tt View it.unibo.torsello.bluetoothpositioning.fragment.SettingsFragment.onCreateView (}
              LayoutInflater inflater,
              ViewGroup container,
              Bundle savedInstanceState )
46
          View root = inflater.inflate(R.layout.fragment_settings, container, false);
48
49
           setKalmanFilterSeekBar(root);
50
51
          setFiltering(root);
52
53
          setArmaOption(root);
55
          setAvgOption(root);
56
57
          setSorting(root);
58
59
           return root;
60
6.30.2.5 setArmaOption()
View root ) [private]
146
147
           RadioGroup rg = (RadioGroup) root.findViewById(R.id.radioGroupArmaOptions);
148
           int checkedRadioButton;
           if (rg.getCheckedRadioButtonId() != 0) {
149
               checkedRadioButton = preferences.getInt(SettingConstants.ARMA_OPTION, rg.
150
      getCheckedRadioButtonId());
151
           } else {
152
               checkedRadioButton = 0;
153
           rg.check(checkedRadioButton);
154
           rg.setOnCheckedChangeListener(new RadioGroup.OnCheckedChangeListener() {
155
156
               @Override
               public void onCheckedChanged(RadioGroup group, int checkedId) {
158
                   SharedPreferences.Editor editor = preferences.edit();
159
                   editor.putInt(SettingConstants.ARMA_OPTION, checkedId);
160
                   editor.apply();
161
           });
162
        }
163
6.30.2.6 setAvgOption()
void it.unibo.torsello.bluetoothpositioning.fragment.SettingsFragment.setAvgOption (
              View root ) [private]
127
128
           RadioGroup rg = (RadioGroup) root.findViewById(R.id.radioGroupAverageOptions);
129
           int checkedRadioButton;
           if (rg.getCheckedRadioButtonId() != 0) {
130
131
               checkedRadioButton = preferences.getInt(SettingConstants.AVG_OPTION, rg.
      getCheckedRadioButtonId());
132
           } else {
133
               checkedRadioButton = 0;
134
135
           rg.check(checkedRadioButton);
136
           rg.setOnCheckedChangeListener(new RadioGroup.OnCheckedChangeListener() {
137
               @Override
138
               public void onCheckedChanged(RadioGroup group, int checkedId) {
139
                   SharedPreferences.Editor editor = preferences.edit();
                   editor.putInt(SettingConstants.AVG_OPTION, checkedId);
140
141
                   editor.apply();
142
143
           });
144
       }
```

6.30.2.7 setFiltering()

```
void it.unibo.torsello.bluetoothpositioning.fragment.SettingsFragment.setFiltering (
              View root ) [private]
108
109
            RadioGroup rg = (RadioGroup) root.findViewById(R.id.radioGroupFilter);
110
            int checkedRadioButton;
            if (rg.getCheckedRadioButtonId() != 0) {
111
112
                checkedRadioButton = preferences.getInt(SettingConstants.FILTER_RSSI, rg.
      getCheckedRadioButtonId());
113
           } else {
114
               checkedRadioButton = 0;
115
116
            rg.check(checkedRadioButton);
117
           rg.setOnCheckedChangeListener(new RadioGroup.OnCheckedChangeListener() {
118
                @Override
119
                public void onCheckedChanged(RadioGroup group, int checkedId) {
120
                    SharedPreferences.Editor editor = preferences.edit();
                    editor.putInt(SettingConstants.FILTER_RSSI, checkedId);
121
122
                    editor.apply();
123
124
           });
125
       }
```

6.30.2.8 setKalmanFilterSeekBar()

```
\verb|void it.unibo.torsello.bluetoothpositioning.fragment.SettingsFragment.setKalmanFilterSeekBar (linear temperature) | the following of the context of the 
                                    View root ) [private]
63
                           SeekBar kalmanSeek = (SeekBar) root.findViewById(R.id.kalmanSeek);
64
                           int seekValue = preferences.getInt(SettingConstants.KALMAN_SEEKBAR_VALUE, 1);
65
66
                           kalmanSeek.setProgress(seekValue);
68
                           final TextView kalmanFilterValue = (TextView) root.findViewById(R.id.kalmanValue);
69
                           kalmanFilterValue.setText(df.format(getCalculatedNoise(seekValue)));
70
71
                           kalmanSeek.setOnSeekBarChangeListener(new SeekBar.OnSeekBarChangeListener() {
72
                                     @Override
                                     public void onProgressChanged(SeekBar seekBar, int seekValue, boolean fromUser) {
74 //
                                                    kalmanFilterValue.setText(df.format(getCalculatedNoise(seekValue)));
7.5
                                     }
76
77
                                     @Override
78
                                     public void onStartTrackingTouch(SeekBar seekBar) {
79
80
81
                                     @Override
                                     public void onStopTrackingTouch(SeekBar seekBar) {
82
83
                                              SharedPreferences.Editor editor = preferences.edit();
84
                                               int progress = seekBar.getProgress();
86
                                               if (!(progress>0)){
87
                                                         editor.putBoolean(SettingConstants.KALMAN_FILTER_ENABLED, false);
88
89
90
                                               float storeProgress = getCalculatedNoise(progress);
                                               editor.putInt(SettingConstants.KALMAN_SEEKBAR_VALUE, progress);
91
                                               editor.putFloat(SettingConstants.KALMAN_NOISE_VALUE, storeProgress);
93
                                               editor.apply();
94
                                               kalmanFilterValue.setText(df.format(storeProgress));
95
96
                           });
```

6.30.2.9 setSorting()

```
void it.unibo.torsello.bluetoothpositioning.fragment.SettingsFragment.setSorting (  \mbox{ View } root \mbox{ ) [private]}
```

```
165
166
                                                   RadioGroup rg = (RadioGroup) root.findViewById(R.id.radioGroupSortingMode);
167
                                                    int checkedRadioButton;
                                                    if (rg.getCheckedRadioButtonId() != 0) {
168
169
                                                                    getCheckedRadioButtonId());
170
                                                 } else {
171
                                                                   checkedRadioButton = 0;
172
173
                                                   rg.check(checkedRadioButton);
                                                  \verb|rg.setOnCheckedChangeListener(new RadioGroup.OnCheckedChangeListener() | \{ (in the context of the context o
174
175
                                                                   @Override
                                                                   public void onCheckedChanged(RadioGroup group, int checkedId) {
    SharedPreferences.Editor editor = preferences.edit();
176
177
178
                                                                                       editor.putInt(SettingConstants.DISTANCE_SORTING, checkedId);
179
                                                                                      editor.apply();
180
181
                                                  });
182
```

6.30.3 Documentazione dei membri dato

6.30.3.1 df

DecimalFormat it.unibo.torsello.bluetoothpositioning.fragment.SettingsFragment.df [private]

6.30.3.2 EXTRA_MESSAGE

final String it.unibo.torsello.bluetoothpositioning.fragment.SettingsFragment.EXTRA_MESSAGE =
"EXTRA_MESSAGE" [static], [private]

6.30.3.3 preferences

SharedPreferences it.unibo.torsello.bluetoothpositioning.fragment.SettingsFragment.preferences [private]

La documentazione per questa classe è stata generata a partire dal seguente file:

• SettingsFragment.java

0.04	Different continuous	La la La La La Status State	Association to be a secured to a secure	Manager and a second	ata Danian Aslantan
6.31	Riterimenti ber	ia ciasse it.unido	torsello.bluetoothpos.	itioning.agapter.St	atePaderAdabter

 $Diagramma\ delle\ classi\ per\ it. unibo. torsello. blue to oth positioning. adapter. State Pager Adapter$

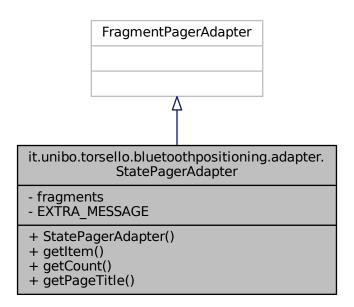
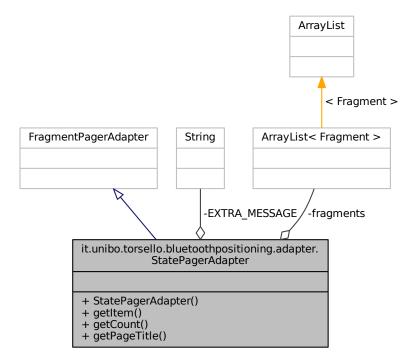


Diagramma di collaborazione per it.unibo.torsello.bluetoothpositioning.adapter.StatePagerAdapter:



Membri pubblici

- $\bullet \ \, {\sf StatePagerAdapter} \, ({\sf FragmentManager} \, {\sf fm}, \, {\sf ArrayList} {<} \, {\sf Fragments}) \\$
- Fragment getItem (int position)
- int getCount ()
- CharSequence getPageTitle (int position)

Attributi privati

 $\bullet \ \, \mathsf{ArrayList} \! < \mathsf{Fragment} \! > \mathsf{fragments}$

Attributi privati statici

• static final String EXTRA_MESSAGE = "EXTRA_MESSAGE"

6.31.1 Descrizione dettagliata

Created by Federico Torsello. federico.torsello@studio.unibo.it

6.31.2 Documentazione dei costruttori e dei distruttori

6.31.2.1 StatePagerAdapter()

6.31.3 Documentazione delle funzioni membro

6.31.3.1 getCount()

6.31.3.2 getItem()

6.31.3.3 getPageTitle()

6.31.4 Documentazione dei membri dato

6.31.4.1 EXTRA_MESSAGE

```
final String it.unibo.torsello.bluetoothpositioning.adapter.StatePagerAdapter.EXTRA_MESSAGE =
"EXTRA_MESSAGE" [static], [private]
```

6.31.4.2 fragments

ArrayList<Fragment> it.unibo.torsello.bluetoothpositioning.adapter.StatePagerAdapter.fragments [private]

La documentazione per questa classe è stata generata a partire dal seguente file:

- StatePagerAdapter.java
- 6.32 Riferimenti per la classe it.unibo.torsello.bluetoothpositioning.fragment.UsbMeasurementFragment

Diagramma delle classi per it.unibo.torsello.bluetoothpositioning.fragment.UsbMeasurementFragment

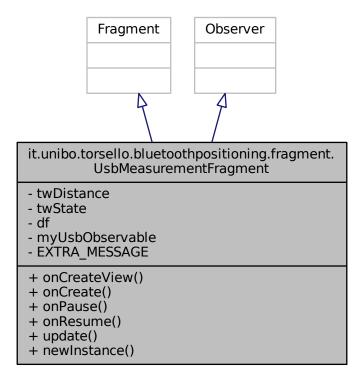
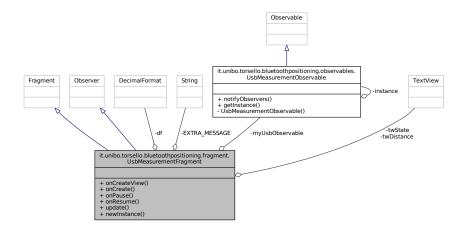


Diagramma di collaborazione per it.unibo.torsello.bluetoothpositioning.fragment.UsbMeasurementFragment:



Membri pubblici

- · View onCreateView (LayoutInflater inflater, ViewGroup container, Bundle savedInstanceState)
- void onCreate (@Nullable Bundle savedInstanceState)
- void onPause ()
- void onResume ()
- void update (Observable o, final Object arg)

Membri pubblici statici

• static UsbMeasurementFragment newInstance ()

Attributi privati

- TextView twDistance
- TextView twState
- · DecimalFormat df
- UsbMeasurementObservable myUsbObservable

Attributi privati statici

static final String EXTRA_MESSAGE = "EXTRA_MESSAGE"

6.32.1 Descrizione dettagliata

Created by Federico Torsello. federico.torsello@studio.unibo.it

6.32.2 Documentazione delle funzioni membro

```
6.32.2.1 newInstance()
```

```
\verb|static UsbMeasurementFragment| it.unibo.torsello.bluetoothpositioning.fragment.UsbMeasurement \\ \leftarrow \\
Fragment.newInstance ( ) [static]
36
          UsbMeasurementFragment fragment = new UsbMeasurementFragment();
          Bundle args = new Bundle();
args.putString(EXTRA_MESSAGE, "Measurement");
37
38
39
          fragment.setArguments(args);
          return fragment;
40
41
6.32.2.2 onCreate()
@Nullable Bundle savedInstanceState )
5.5
56
          super.onCreate(savedInstanceState);
57
58
          myUsbObservable = UsbMeasurementObservable.getInstance();
          df = new DecimalFormat("0.00", DecimalFormatSymbols.getInstance());
60
61
6.32.2.3 onCreateView()
View it.unibo.torsello.bluetoothpositioning.fragment.UsbMeasurementFragment.onCreateView (
              LayoutInflater inflater,
              ViewGroup container,
              Bundle savedInstanceState )
45
46
          View root = inflater.inflate(R.layout.fragment_usb_measurement, container, false);
47
48
          twDistance = (TextView) root.findViewById(R.id.tw_distance_value);
49
          twState = (TextView) root.findViewById(R.id.tw_state_value);
50
          return root;
52
6.32.2.4 onPause()
void it.unibo.torsello.bluetoothpositioning.fragment.UsbMeasurementFragment.onPause ( )
64
          myUsbObservable.deleteObserver(this);
65
          super.onPause();
6.32.2.5 onResume()
void it.unibo.torsello.bluetoothpositioning.fragment.UsbMeasurementFragment.onResume ()
70
71
          super.onResume();
72
          myUsbObservable.addObserver(this);
```

6.32.2.6 update()

```
void it.unibo.torsello.bluetoothpositioning.fragment.UsbMeasurementFragment.update (
               Observable o,
               final Object arg )
76
78
           getActivity().runOnUiThread(new Runnable() {
               @Override
80
               public void run() {
81
                   if (arg instanceof Double) {
82
                        Double arduinoDistance = (Double) arg;
                   twDistance.setText(String.format("%s m", df.format(arduinoDistance)));
} else if (arg instanceof String) {
83
84
85
                       String message = (String) arg;
86
                        twState.setText(message);
87
                    } else if (arg instanceof Boolean)
88
                        boolean state = (Boolean) arg;
89
                        if (state) {
                            twState.setTextColor(Color.GREEN);
90
                        } else {
92
                            twState.setTextColor(Color.RED);
93
94
                   }
               }
9.5
          });
96
```

6.32.3 Documentazione dei membri dato

6.32.3.1 df

DecimalFormat it.unibo.torsello.bluetoothpositioning.fragment.UsbMeasurementFragment.df [private]

6.32.3.2 EXTRA_MESSAGE

final String it.unibo.torsello.bluetoothpositioning.fragment.UsbMeasurementFragment.EXTRA_ME \leftarrow SSAGE = "EXTRA_MESSAGE" [static], [private]

6.32.3.3 myUsbObservable

UsbMeasurementObservable it.unibo.torsello.bluetoothpositioning.fragment.UsbMeasurement←
Fragment.myUsbObservable [private]

6.32.3.4 twDistance

 $\label{thm:continuity} \textbf{TextView it.unibo.torsello.bluetoothpositioning.fragment.UsbMeasurementFragment.twDistance} \ [private]$

6.32.3.5 twState

TextView it.unibo.torsello.bluetoothpositioning.fragment.UsbMeasurementFragment.twState [private]

La documentazione per questa classe è stata generata a partire dal seguente file:

UsbMeasurementFragment.java

6.33 Riferimenti per la classe it.unibo.torsello.bluetoothpositioning.observables.UsbMeasurement ← Observable

Diagramma delle classi per it.unibo.torsello.bluetoothpositioning.observables.UsbMeasurementObservable

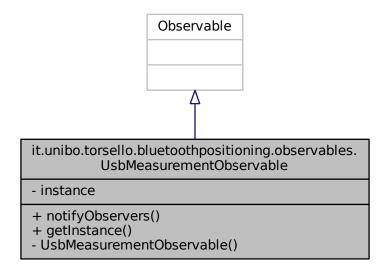
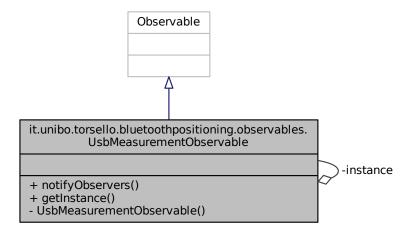


Diagramma di collaborazione per it.unibo.torsello.bluetoothpositioning.observables.UsbMeasurementObservable:



Membri pubblici

• void notifyObservers (Object data)

Membri pubblici statici

• static UsbMeasurementObservable getInstance ()

Membri privati

UsbMeasurementObservable ()

Attributi privati statici

static UsbMeasurementObservable instance = new UsbMeasurementObservable()

6.33.1 Descrizione dettagliata

Created by Federico Torsello. federico.torsello@studio.unibo.it

6.33.2 Documentazione dei costruttori e dei distruttori

6.33.2.1 UsbMeasurementObservable()

6.33.3 Documentazione delle funzioni membro

6.33.3.1 getInstance()

```
static \ \ \ Usb \texttt{MeasurementObservable} \ \ it.unibo.torsello.blueto oth positioning.observables. Usb \texttt{Measurement} \hookrightarrow \texttt{Observable.getInstance} \ \ (\ ) \ \ [static]
```

```
18
19          return instance;
20     }
```

6.33.3.2 notifyObservers()

6.33.4 Documentazione dei membri dato

6.33.4.1 instance

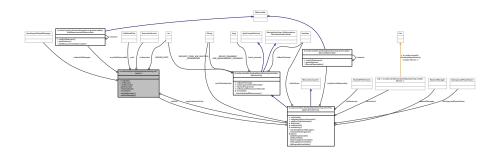
UsbMeasurementObservable it.unibo.torsello.bluetoothpositioning.observables.UsbMeasurement↔
Observable.instance = new UsbMeasurementObservable() [static], [private]

La documentazione per questa classe è stata generata a partire dal seguente file:

• UsbMeasurementObservable.java

6.34 Riferimenti per la classe it.unibo.torsello.bluetoothpositioning.util.UsbUtil

Diagramma di collaborazione per it.unibo.torsello.bluetoothpositioning.util.UsbUtil:



Membri pubblici

- UsbUtil (ApplicationActivity applicationActivity)
- void onPause ()
- void onResume ()

Membri privati

- ApplicationActivity getActivity ()
- void initializeUsb ()
- void closePort ()
- void stoploManager ()
- void startloManager ()

Attributi privati

- UsbMeasurementObservable myUsbObservable
- final ExecutorService mExecutor = Executors.newSingleThreadExecutor()
- UsbSerialPort port
- SerialInputOutputManager mSerialIoManager
- · ApplicationActivity applicationActivity

Attributi privati statici

• static final int BOUND_RATE = 115200

6.34.1 Descrizione dettagliata

Created by Federico Torsello. federico.torsello@studio.unibo.it

6.34.2 Documentazione dei costruttori e dei distruttori

6.34.2.1 UsbUtil()

6.34.3 Documentazione delle funzioni membro

6.34.3.1 closePort()

void it.unibo.torsello.bluetoothpositioning.util.UsbUtil.closePort () [private]

6.34.3.2 getActivity()

ApplicationActivity it.unibo.torsello.bluetoothpositioning.util.UsbUtil.getActivity () [private]

```
45
46 return applicationActivity;
47 }
```

6.34.3.3 initializeUsb()

52

```
void it.unibo.torsello.bluetoothpositioning.util.UsbUtil.initializeUsb ( ) [private]
59
60
             // Find all available drivers from attached devices.
61
            UsbManager usbManager = (UsbManager) getActivity().getSystemService(Context.USB_SERVICE)
62
63
             List<UsbSerialDriver> availableDrivers = UsbSerialProber.getDefaultProber().findAllDrivers(
       usbManager);
64
            if (!availableDrivers.isEmpty()) {
65
                  // Open a connection to the first available driver.
66
                 UsbSerialDriver driver = availableDrivers.get(0);
68
                 if (usbManager.hasPermission(driver.getDevice())) {
70
                      if (usbManager.openDevice(driver.getDevice()) != null) {
71
                           // Read some data! Most have just one port (port 0).
72
                          port = driver.getPorts().get(0);
73
                      }
74
                 } else {
75
                      Intent startIntent = new Intent(getActivity(), getClass());
76
                      PendingIntent pendingIntent =
77
                              PendingIntent.getService(getActivity(), 0, startIntent, 0);
78
                      usbManager.requestPermission(driver.getDevice(), pendingIntent);
79
80 //
                        PendingIntent mPendingIntent = PendingIntent.getBroadcast(getActivity(), 0, new
        Intent("intent"), 0);
81
                        usbManager.requestPermission(driver.getDevice(), mPendingIntent);
82
                 }
83
                 if (port != null) {
84
85
                      UsbDeviceConnection connection = usbManager.openDevice(port.getDriver().getDevice());
88
                      if (connection != null) {
89
                           try {
90
                               port.open(connection);
                               port.setParameters(BOUND_RATE, UsbSerialPort.DATABITS_8,
91
92
                                        UsbSerialPort.STOPBITS_1, UsbSerialPort.PARITY_NONE);
93
94 //
                             String details = "CD - Carrier Detect" + port.getCD() + '\n' +
                                      details = "CD - Carrier Detect" + port.getUD() + '\n'
"CTS - Clear To Send" + port.getCTS() + '\n' +
"DSR - Data Set Ready" + port.getDSR() + '\n' +
"DTR - Data Terminal Ready" + port.getDTR() + '\n' +
"DSR - Data Set Ready" + port.getDSR() + '\n' +
"RI - Ring Indicator" + port.getRI() + '\n' +
"RTS - Request To Send" + port.getRTS();
95 //
96 //
97 //
98 //
99 //
100 //
101
102
                            } catch (IOException e) {
                                myUsbObservable.notifyObservers(
103
       getActivity().getString(R.string.error_opening_device)
104
                                          + " " + e.getMessage());
105
                                myUsbObservable.notifyObservers(false);
106
                                closePort();
107
                                return;
                            }
108
109
110
                            stopIoManager();
111
                            startIoManager();
112
                       }
113
                  }
             }
114
115
6.34.3.4 onPause()
void it.unibo.torsello.bluetoothpositioning.util.UsbUtil.onPause ( )
49
50
             stopIoManager();
51
             closePort();
```

6.34.3.5 onResume()

6.34.3.6 startloManager()

void it.unibo.torsello.bluetoothpositioning.util.UsbUtil.startIoManager () [private]

```
135
136
           if (port != null) {
137
138
               SerialInputOutputManager.Listener mListener =
139
                      new SerialInputOutputManager.Listener() {
140
141
                          @Override
142
                          public void onRunError(Exception e) {
143
                              myUsbObservable.notifyObservers(false);
144
                              myUsbObservable.notifyObservers(
     getActivity().getString(R.string.usb_device_not_connected));
145
                              myUsbObservable.notifyObservers(OD);
146
147
148
                          @Override
149
                          public void onNewData(final byte[] data) {
150
151
                                  myUsbObservable.notifyObservers(true);
152
                                  \verb|myUsbObservable.notifyObservers||\\
     153
154
155
                                  myUsbObservable.notifyObservers(
     distanceEstimate);
156
                              } catch (NumberFormatException | UnsupportedEncodingException nfe) {
157
                                  nfe.printStackTrace();
158
159
160
                      };
161
162
               mSerialIoManager = new SerialInputOutputManager(port, mListener);
               mExecutor.submit(mSerialIoManager);
163
164
165
       }
```

6.34.3.7 stoploManager()

void it.unibo.torsello.bluetoothpositioning.util.UsbUtil.stopIoManager () [private]

6.34.4 Documentazione dei membri dato

6.34.4.1 applicationActivity

ApplicationActivity it.unibo.torsello.bluetoothpositioning.util.UsbUtil.applicationActivity [private]

6.34.4.2 BOUND_RATE

final int it.unibo.torsello.bluetoothpositioning.util.UsbUtil.BOUND_RATE = 115200 [static],
[private]

6.34.4.3 mExecutor

final ExecutorService it.unibo.torsello.bluetoothpositioning.util.UsbUtil.mExecutor = Executors. \leftarrow newSingleThreadExecutor() [private]

6.34.4.4 mSerialIoManager

SerialInputOutputManager it.unibo.torsello.bluetoothpositioning.util.UsbUtil.mSerialIoManager [private]

6.34.4.5 myUsbObservable

UsbMeasurementObservable it.unibo.torsello.bluetoothpositioning.util.UsbUtil.myUsbObservable
[private]

6.34.4.6 port

UsbSerialPort it.unibo.torsello.bluetoothpositioning.util.UsbUtil.port [private]

La documentazione per questa classe è stata generata a partire dal seguente file:

· UsbUtil.java

7 Documentazione dei file

7.1 Riferimenti per il file ApplicationActivity.java

Composti

· class it.unibo.torsello.bluetoothpositioning.activities.ApplicationActivity

Package

· package it.unibo.torsello.bluetoothpositioning.activities

7.2 Riferimenti per il file CameraFragment.java

Composti

class it.unibo.torsello.bluetoothpositioning.fragment.CameraFragment

Package

· package it.unibo.torsello.bluetoothpositioning.fragment

7.3 Riferimenti per il file CameraPreviewUtil.java

Composti

· class it.unibo.torsello.bluetoothpositioning.util.CameraPreviewUtil

Package

· package it.unibo.torsello.bluetoothpositioning.util

7.4 Riferimenti per il file ChartUtil.java

Composti

class it.unibo.torsello.bluetoothpositioning.util.ChartUtil

Package

· package it.unibo.torsello.bluetoothpositioning.util

7.5 Riferimenti per il file Device.java

Composti

class it.unibo.torsello.bluetoothpositioning.model.Device

Package

· package it.unibo.torsello.bluetoothpositioning.model

7.6 Riferimenti per il file DeviceCardViewAdapter.java

Composti

- · class it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter
- class it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.DeviceViewHolder

Package

package it.unibo.torsello.bluetoothpositioning.adapter

7.7 Riferimenti per il file DeviceChartFragment.java

Composti

· class it.unibo.torsello.bluetoothpositioning.fragment.DeviceChartFragment

Package

· package it.unibo.torsello.bluetoothpositioning.fragment

7.8 Riferimenti per il file DeviceConstants.java

Composti

· class it.unibo.torsello.bluetoothpositioning.constant.DeviceConstants

Package

· package it.unibo.torsello.bluetoothpositioning.constant

7.9 Riferimenti per il file DeviceDetailFragment.java

Composti

· class it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailFragment

Package

· package it.unibo.torsello.bluetoothpositioning.fragment

7.10 Riferimenti per il file DeviceDetailInner0Fragment.java

Composti

- · class it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInner0Fragment
- interface it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInner0Fragment.OnRecordingResume
- interface it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInner0Fragment.OnRecordingReport

Package

· package it.unibo.torsello.bluetoothpositioning.fragment

7.11 Riferimenti per il file DeviceDetailInner1Fragment.java

Composti

class it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInner1Fragment

Package

· package it.unibo.torsello.bluetoothpositioning.fragment

7.12 Riferimenti per il file DeviceDetailInner2Fragment.java

Composti

 $\bullet \ \ class \ it. unibo. torsello. blue to oth positioning. fragment. Device Detail Inner 2 Fragment$

Package

· package it.unibo.torsello.bluetoothpositioning.fragment

7.13 Riferimenti per il file DeviceDetailReportFragment.java

Composti

• class it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailReportFragment

Package

· package it.unibo.torsello.bluetoothpositioning.fragment

7.14 Riferimenti per il file DeviceDetailResumeFragment.java

Composti

• class it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailResumeFragment

Package

· package it.unibo.torsello.bluetoothpositioning.fragment

7.15 Riferimenti per il file DeviceListFragment.java

Composti

 $\bullet \ class \ it. unibo. torsello. blue to oth positioning. fragment. Device List Fragment$

Package

package it.unibo.torsello.bluetoothpositioning.fragment

7.16 Riferimenti per il file DeviceObservable.java

Composti

• class it.unibo.torsello.bluetoothpositioning.observables.DeviceObservable

Package

• package it.unibo.torsello.bluetoothpositioning.observables

7.17 Riferimenti per il file Estimation.java

Composti

· class it.unibo.torsello.bluetoothpositioning.distanceEstimation.Estimation

Package

• package it.unibo.torsello.bluetoothpositioning.distanceEstimation

7.18 Riferimenti per il file FABBehavior.java

Composti

· class it.unibo.torsello.bluetoothpositioning.extra.FABBehavior

Package

· package it.unibo.torsello.bluetoothpositioning.extra

7.19 Riferimenti per il file KFilter.java

Composti

· class it.unibo.torsello.bluetoothpositioning.filters.kalmanFilter.KFilter

Package

• package it.unibo.torsello.bluetoothpositioning.filters.kalmanFilter

7.20 Riferimenti per il file KFilterBuilder.java

Composti

· class it.unibo.torsello.bluetoothpositioning.filters.kalmanFilter.KFilterBuilder

Package

· package it.unibo.torsello.bluetoothpositioning.filters.kalmanFilter

7.21 Riferimenti per il file KFilterConstants.java

Composti

· class it.unibo.torsello.bluetoothpositioning.constant.KFilterConstants

Package

· package it.unibo.torsello.bluetoothpositioning.constant

7.22 Riferimenti per il file MainActivity.java

Composti

· class it.unibo.torsello.bluetoothpositioning.activities.MainActivity

Package

· package it.unibo.torsello.bluetoothpositioning.activities

7.23 Riferimenti per il file MyArmaRssiFilter.java

Composti

· class it.unibo.torsello.bluetoothpositioning.filters.MyArmaRssiFilter

Package

· package it.unibo.torsello.bluetoothpositioning.filters

7.24 Riferimenti per il file ReportUtils.java

Composti

 $\bullet \ class \ it. unibo. torsello. blue to oth positioning. util. Report Utils$

Package

package it.unibo.torsello.bluetoothpositioning.util

7.25 Riferimenti per il file SavelmageTask.java

Composti

• class it.unibo.torsello.bluetoothpositioning.task.SaveImageTask

Package

• package it.unibo.torsello.bluetoothpositioning.task

7.26 Riferimenti per il file SettingConstants.java

Composti

· class it.unibo.torsello.bluetoothpositioning.constant.SettingConstants

Package

· package it.unibo.torsello.bluetoothpositioning.constant

7.27 Riferimenti per il file SettingsFragment.java

Composti

· class it.unibo.torsello.bluetoothpositioning.fragment.SettingsFragment

Package

· package it.unibo.torsello.bluetoothpositioning.fragment

7.28 Riferimenti per il file StatePagerAdapter.java

Composti

· class it.unibo.torsello.bluetoothpositioning.adapter.StatePagerAdapter

Package

• package it.unibo.torsello.bluetoothpositioning.adapter

7.29 Riferimenti per il file UsbMeasurementFragment.java

Composti

class it.unibo.torsello.bluetoothpositioning.fragment.UsbMeasurementFragment

Package

· package it.unibo.torsello.bluetoothpositioning.fragment

7.30 Riferimenti per il file UsbMeasurementObservable.java

Composti

• class it.unibo.torsello.bluetoothpositioning.observables.UsbMeasurementObservable

Package

• package it.unibo.torsello.bluetoothpositioning.observables

7.31 Riferimenti per il file UsbUtil.java

Composti

• class it.unibo.torsello.bluetoothpositioning.util.UsbUtil

Package

• package it.unibo.torsello.bluetoothpositioning.util

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