

BluetoothPositioning

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1 Indice dei namespace

1.1 Package

Questi sono i package e una loro breve descrizione (se disponibile):

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it.unibo.torsello	6
it.unibo.torsello.bluetoothpositioning	6
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it.unibo.torsello.bluetoothpositioning.observables	8
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it.unibo.torsello.bluetoothpositioning.util	9

2 Indice della gerarchia

2.1 Gerarchia delle classi

Questo elenco di ereditarietà è ordinato approssimativamente, ma non completamente, in ordine alfabetico:

Adapter

[it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter](#) 38

Behavior

[it.unibo.torsello.bluetoothpositioning.extra.FABBehavior](#) 77

Callback

[it.unibo.torsello.bluetoothpositioning.util.CameraPreviewUtil](#) 19

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AppCompatActivity	
it.unibo.torsello.bluetoothpositioning.activities.MainActivity	89
AsyncTask	
it.unibo.torsello.bluetoothpositioning.task.SaveImageTask	97
BeaconConsumer	
it.unibo.torsello.bluetoothpositioning.activities.ApplicationActivity	9
Fragment	
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it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailFragment	50
it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInner2Fragment	58
it.unibo.torsello.bluetoothpositioning.fragment.devicesObservers.DeviceChartFragment	43
it.unibo.torsello.bluetoothpositioning.fragment.devicesObservers.DeviceDetailInner1Fragment	54
it.unibo.torsello.bluetoothpositioning.fragment.devicesObservers.DeviceListFragment	62
it.unibo.torsello.bluetoothpositioning.fragment.SettingsFragment	102
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Observable	
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3 Indice dei tipi composti

3.1 Elenco dei tipi composti

Queste sono le classi, le struct, le union e le interfacce con una loro breve descrizione:

it.unibo.torsello.bluetoothpositioning.activities.ApplicationActivity	9
it.unibo.torsello.bluetoothpositioning.fragment.CameraFragment	15
it.unibo.torsello.bluetoothpositioning.util.CameraPreviewUtil	19
it.unibo.torsello.bluetoothpositioning.util.ChartUtil	27
it.unibo.torsello.bluetoothpositioning.model.Device	33
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it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailFragment	50
it.unibo.torsello.bluetoothpositioning.fragment.devicesObservers.DeviceDetailInner1Fragment	54
it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInner2Fragment	58
it.unibo.torsello.bluetoothpositioning.fragment.devicesObservers.DeviceListFragment	62
it.unibo.torsello.bluetoothpositioning.observable.DeviceObservable	66
it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.DeviceViewHolder	69
it.unibo.torsello.bluetoothpositioning.distanceEstimation.Estimation	73
it.unibo.torsello.bluetoothpositioning.extra.FABBehavior	77
it.unibo.torsello.bluetoothpositioning.kalmanFilter.KFilter	80
it.unibo.torsello.bluetoothpositioning.kalmanFilter.KFilterBuilder	84
it.unibo.torsello.bluetoothpositioning.constant.KFilterConstants	87
it.unibo.torsello.bluetoothpositioning.activities.MainActivity	89

it.unibo.torsello.bluetoothpositioning.configuration.MyArmaRssiFilter	94
it.unibo.torsello.bluetoothpositioning.task.SaveImageTask	97
it.unibo.torsello.bluetoothpositioning.constant.SettingConstants	100
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it.unibo.torsello.bluetoothpositioning.observable.UsbMeasurementObservable	113
it.unibo.torsello.bluetoothpositioning.util.UsbUtil	115

4 Indice dei file

4.1 Elenco dei file

Questo è un elenco di tutti i file con una loro breve descrizione:

ApplicationActivity.java	119
CameraFragment.java	120
CameraPreviewUtil.java	120
ChartUtil.java	120
Device.java	120
DeviceCardViewAdapter.java	120
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KFilter.java	123
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MyArmaRssiFilter.java	124
SaveImageTask.java	124
SettingConstants.java	124
SettingsFragment.java	124
StatePagerAdapter.java	124
UsbMeasurementFragment.java	125
UsbMeasurementObservable.java	125
UsbUtil.java	125

5 Documentazione dei namespace

5.1 Package it

Package

- package [unibo](#)

5.2 Package it.unibo

Package

- package [torsello](#)

5.3 Package it.unibo.torsello

Package

- package [bluetoothpositioning](#)

5.4 Package it.unibo.torsello.bluetoothpositioning

Package

- package [activities](#)
- package [adapter](#)
- package [configuration](#)
- package [constant](#)
- package [distanceEstimation](#)
- package [extra](#)
- package [fragment](#)
- package [kalmanFilter](#)
- package [model](#)
- package [observables](#)
- package [task](#)
- package [util](#)

5.5 Package it.unibo.torsello.bluetoothpositioning.activities

Composti

- class [ApplicationActivity](#)
- class [MainActivity](#)

5.6 Package it.unibo.torsello.bluetoothpositioning.adapter

Composti

- class [DeviceCardViewAdapter](#)
- class [StatePagerAdapter](#)

5.7 Package it.unibo.torsello.bluetoothpositioning.configuration

Composti

- class [MyArmaRssiFilter](#)

5.8 Package it.unibo.torsello.bluetoothpositioning.constant

Composti

- class [DeviceConstants](#)
- class [KFilterConstants](#)
- class [SettingConstants](#)

5.9 Package it.unibo.torsello.bluetoothpositioning.distanceEstimation

Composti

- class [Estimation](#)

5.10 Package it.unibo.torsello.bluetoothpositioning.extra

Composti

- class [FABBehavior](#)

5.11 Package it.unibo.torsello.bluetoothpositioning.fragment

Package

- package [devicesObservers](#)
- package [usbObservers](#)

Composti

- class [CameraFragment](#)
- class [DeviceDetailFragment](#)
- class [DeviceDetailInner2Fragment](#)
- class [SettingsFragment](#)

5.12 Package it.unibo.torsello.bluetoothpositioning.fragment.devicesObservers

Composti

- class [DeviceChartFragment](#)
- class [DeviceDetailInner1Fragment](#)
- class [DeviceListFragment](#)

5.13 Package it.unibo.torsello.bluetoothpositioning.fragment.usbObservers

Composti

- class [UsbMeasurementFragment](#)

5.14 Package it.unibo.torsello.bluetoothpositioning.kalmanFilter

Composti

- class [KFilter](#)
- class [KFilterBuilder](#)

5.15 Package it.unibo.torsello.bluetoothpositioning.model

Composti

- class [Device](#)

5.16 Package it.unibo.torsello.bluetoothpositioning.observables

Composti

- class [DeviceObservable](#)
- class [UsbMeasurementObservable](#)

5.17 Package it.unibo.torsello.bluetoothpositioning.task

Composti

- class [SaveImageTask](#)

5.18 Package it.unibo.torsello.bluetoothpositioning.util

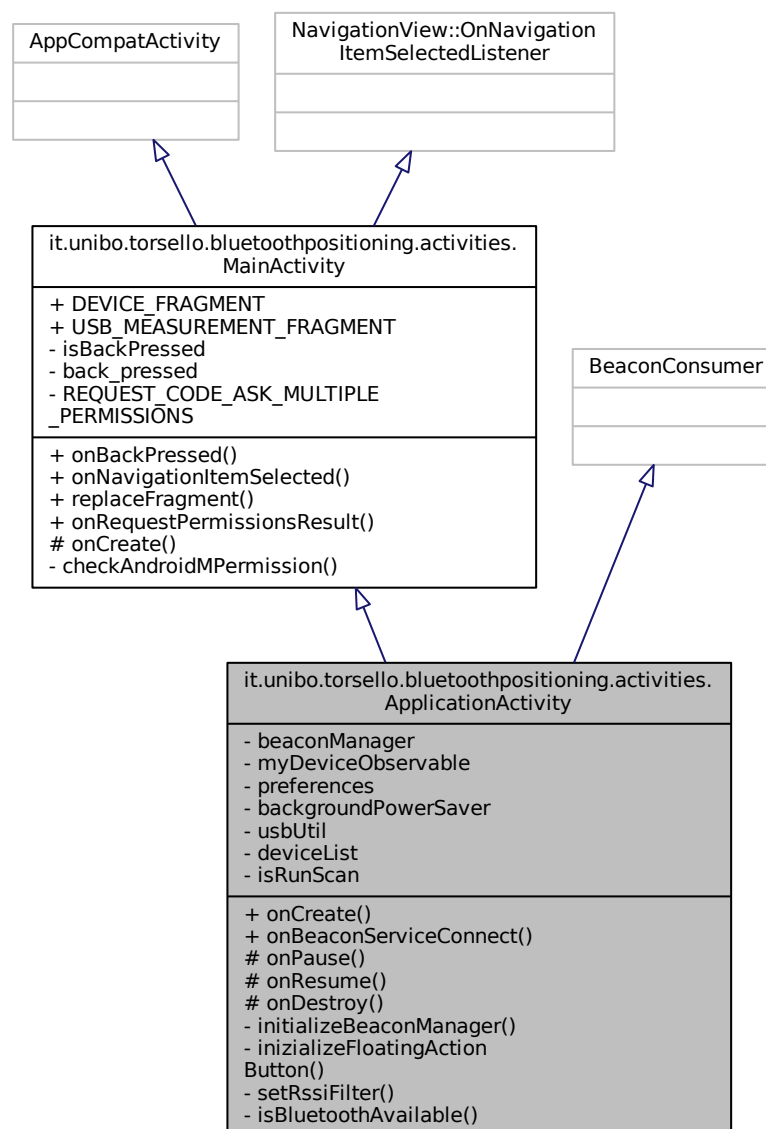
Composti

- class [CameraPreviewUtil](#)
- class [ChartUtil](#)
- class [UsbUtil](#)

6 Documentazione delle classi

6.1 Riferimenti per la classe it.unibo.torsello.bluetoothpositioning.activities.ApplicationActivity

Diagramma delle classi per it.unibo.torsello.bluetoothpositioning.activities.ApplicationActivity



6.1.2 Documentazione delle funzioni membro

6.1.2.1 `initializeBeaconManager()`

```
void it.unibo.torsello.bluetoothpositioning.activities.ApplicationActivity.initializeBeaconManager ( ) [private]
```

```
70
71         {
72             beaconManager = BeaconManager.getInstanceForApplication(this);
73             beaconManager.bind(this);
74
75             // Save battery whenever the application is not visible.
76             // This reduces bluetooth power usage by about 60%
77             backgroundPowerSaver = new BackgroundPowerSaver(this);
78
79             // Log.i("AltBeacon filter used:", BeaconManager.getRssiFilterImplClass().getSimpleName());
80
81             // for finding different type of beacon,
82             beaconManager.getBeaconParsers().clear();
83
84             // Alt beacon
85             beaconManager.getBeaconParsers().add(new BeaconParser()
86                 .setBeaconLayout(BeaconParser.ALTBEACON_LAYOUT));
87             // Detect the main identifier (UID) frame:
88             beaconManager.getBeaconParsers().add(new BeaconParser()
89                 .setBeaconLayout(BeaconParser.EDDYSTONE_UID_LAYOUT));
90             // Detect the telemetry (TLM) frame:
91             beaconManager.getBeaconParsers().add(new BeaconParser()
92                 .setBeaconLayout(BeaconParser.EDDYSTONE_TLM_LAYOUT));
93             // Detect the URL frame:
94             beaconManager.getBeaconParsers().add(new BeaconParser()
95                 .setBeaconLayout(BeaconParser.EDDYSTONE_URL_LAYOUT));
96             // Standard Apple iBeacon
97             beaconManager.getBeaconParsers().add(new BeaconParser()
98                 .setBeaconLayout(DeviceConstants.APPLE_BEACON_LAYOUT));
99             // Estimote Nearable
100            beaconManager.getBeaconParsers().add(new BeaconParser()
101                .setBeaconLayout(DeviceConstants.ESTIMOTE_NEARABLE_LAYOUT));
102
103            beaconManager.setForegroundScanPeriod(250L);
104            beaconManager.setForegroundBetweenScanPeriod(0L);
105            beaconManager.setBackgroundScanPeriod(250L);
106            beaconManager.setBackgroundBetweenScanPeriod(0L);
107
108            beaconManager.setMaxTrackingAge(1000);
109        }
```

6.1.2.2 `initalizeFloatingActionButton()`

```
void it.unibo.torsello.bluetoothpositioning.activities.ApplicationActivity.initalizeFloatingActionButton ( ) [private]
```

```
110
111        {
112            final FloatingActionButton fab = (FloatingActionButton) findViewById(R.id.fab);
113            assert fab != null;
114            Snackbar.make(fab, R.string.snackBar_start_scanning, Snackbar.LENGTH_LONG).show();
115            fab.setOnClickListener(new View.OnClickListener() {
116                @Override
117                public void onClick(View view) {
118
119                    if (isBluetoothAvailable()) {
120
121                        isRunScan = !isRunScan;
122                        Region region = new Region("RegionId", null, null, null);
123
124                        if (isRunScan) {
125                            fab.setImageResource(R.drawable.ic_bluetooth_searching_white_24dp);
126                            try {
127                                beaconManager.startRangingBeaconsInRegion(region);
128                            } catch (RemoteException e) {
129                                e.printStackTrace();
130                            }
131                            Snackbar.make(view, R.string.snackBar_scanning_enabled,
132                                Snackbar.LENGTH_SHORT).show();
133                        } else {
134
135                        }
```

```

133         fab.setImageResource(R.drawable.ic_bluetooth_white_24dp);
134     try {
135         beaconManager.stopRangingBeaconsInRegion(region);
136     } catch (RemoteException e) {
137         e.printStackTrace();
138     }
139     Snackbar.make(view, R.string.snackBar_scanning_disabled,
140         Snackbar.LENGTH_INDEFINITE).show();
141 }
142 }
143 }
144 });
145 }

```

6.1.2.3 isBluetoothAvailable()

boolean it.unibo.torsello.bluetoothpositioning.activities.ApplicationActivity.isBluetoothAvailable () [private]

```

250     {
251
252     try {
253         if (!beaconManager.checkAvailability()) {
254
255             final FloatingActionButton fab = (FloatingActionButton) findViewById(R.id.fab);
256             assert fab != null;
257
258             new AlertDialog.Builder(this)
259                 .setTitle(R.string.dialog_bluetooth_title)
260                 .setMessage(R.string.dialog_bluetooth_text)
261                 .setPositiveButton(android.R.string.ok, null)
262                 .setOnDismissListener(new DialogInterface.OnDismissListener() {
263                     @Override
264                     public void onDismiss(DialogInterface dialog) {
265                         fab.setImageResource(R.drawable.ic_bluetooth_white_24dp);
266                         BluetoothAdapter.getDefaultAdapter().enable();
267                     }
268                 }).show();
269             fab.setImageResource(R.drawable.ic_bluetooth_disabled_black_24dp);
270             return false;
271         }
272     } catch (RuntimeException e) {
273         e.printStackTrace();
274     }
275     return true;
276 }

```

6.1.2.4 onBeaconServiceConnect()

void it.unibo.torsello.bluetoothpositioning.activities.ApplicationActivity.onBeaconServiceConnect ()

```

148     {
149
150     try {
151         beaconManager.updateScanPeriods();
152     } catch (RemoteException e) {
153         e.printStackTrace();
154     }
155
156     beaconManager.addRangeNotifier(new RangeNotifier() {
157         @Override
158         public void didRangeBeaconsInRegion(final Collection<Beacon> beacons, Region region) {
159
160             setRssiFilter();
161
162             for (Beacon b : beacons) {
163
164                 // take from the list the device
165                 Device device = DeviceConstants.DEVICE_MAP.get(b.getBluetoothAddress());
166
167                 if (device != null) { // useful only if DEVICE_MAP is empty
168                     double processNoise = preferences.getFloat(SettingConstants.
169                         KALMAN_NOISE_VALUE, 0);
169                     device.setBeacon(b);
170                 }
171             }
172         }
173     });
174 }

```

```

170         device.updateDistance(processNoise);
171
172         if (!deviceList.contains(device)) {
173             deviceList.add(device);
174         }
175     }
176 }
177
178     new Thread(new Runnable() {
179         @Override
180         public void run() {
181             runOnUiThread(new Runnable() {
182
183                 @Override
184                 public void run() {
185                     myDeviceObservable.
notifyObservers(deviceList);
186                 }
187             });
188         }
189     }).start();
190 }
191 });
192 }

```

6.1.2.5 onCreate()

```

void it.unibo.torsello.bluetoothpositioning.activities.ApplicationActivity.onCreate (
    Bundle savedInstanceState )

```

```

54     {
55         super.onCreate(savedInstanceState);
56
57         deviceList = new ArrayList<>();
58
59         myDeviceObservable = DeviceObservable.getInstance();
60
61         preferences = getSharedPreferences(SettingConstants.SETTINGS_PREFERENCES, 0);
62
63         usbUtil = new UsbUtil(this);
64
65         initializeBeaconManager();
66
67         initializeFloatingActionButton();
68     }

```

6.1.2.6 onDestroy()

```

void it.unibo.torsello.bluetoothpositioning.activities.ApplicationActivity.onDestroy ( ) [protected]

```

```

241     {
242         if (beaconManager.isBound(this)) {
243             beaconManager.unbind(this);
244             backgroundPowerSaver.onActivityDestroyed(this);
245         }
246
247         super.onDestroy();
248     }

```

6.1.2.7 onPause()

```

void it.unibo.torsello.bluetoothpositioning.activities.ApplicationActivity.onPause ( ) [protected]

```

```

214     {
215         if (beaconManager.isBound(this)) {
216             beaconManager.setBackgroundMode(true);
217             backgroundPowerSaver.onActivityPaused(this);
218         }
219
220         usbUtil.onPause();
221
222         super.onPause();
223     }

```

6.1.2.8 onResume()

```
void it.unibo.torsello.bluetoothpositioning.activities.ApplicationActivity.onResume ( ) [protected]
```

```
226         {
227         super.onResume();
228
229         if (beaconManager.isBound(this)) {
230             beaconManager.setBackgroundMode(false);
231             backgroundPowerSaver.onActivityResumed(this);
232         }
233
234         isBluetoothAvailable();
235
236         usbUtil.onResume();
237
238     }
```

6.1.2.9 setRssiFilter()

```
void it.unibo.torsello.bluetoothpositioning.activities.ApplicationActivity.setRssiFilter ( )
[private]
```

```
194         {
195
196         int sorting = preferences.getInt(SettingConstants.FILTER_RSSI, 0);
197         switch (sorting) {
198             case 0:
199                 R.id.radioButton_no_rssi_filtering:
200                 MyArmaRssiFilter.enableArmaFilter(false);
201                 BeaconManager.setRssiFilterImplClass(MyArmaRssiFilter.class);
202                 break;
203             case R.id.radioButton_arma_rssi_filter:
204                 MyArmaRssiFilter.enableArmaFilter(true);
205                 BeaconManager.setRssiFilterImplClass(MyArmaRssiFilter.class);
206                 break;
207             case R.id.radioButton_average_rssi_filter:
208                 BeaconManager.setRssiFilterImplClass(RunningAverageRssiFilter.class);
209                 break;
210         }
211     }
```

6.1.3 Documentazione dei membri dato

6.1.3.1 backgroundPowerSaver

```
BackgroundPowerSaver it.unibo.torsello.bluetoothpositioning.activities.ApplicationActivity.↔
backgroundPowerSaver [private]
```

6.1.3.2 beaconManager

```
BeaconManager it.unibo.torsello.bluetoothpositioning.activities.ApplicationActivity.beacon↔
Manager [private]
```

6.1.3.3 deviceList

```
List<Device> it.unibo.torsello.bluetoothpositioning.activities.ApplicationActivity.deviceList
[private]
```

6.1.3.4 isRunScan

```
boolean it.unibo.torsello.bluetoothpositioning.activities.ApplicationActivity.isRunScan =
false [private]
```

6.1.3.5 myDeviceObservable

```
DeviceObservable it.unibo.torsello.bluetoothpositioning.activities.ApplicationActivity.my↔  
DeviceObservable [private]
```

6.1.3.6 preferences

```
SharedPreferences it.unibo.torsello.bluetoothpositioning.activities.ApplicationActivity.↔  
preferences [private]
```

6.1.3.7 usbUtil

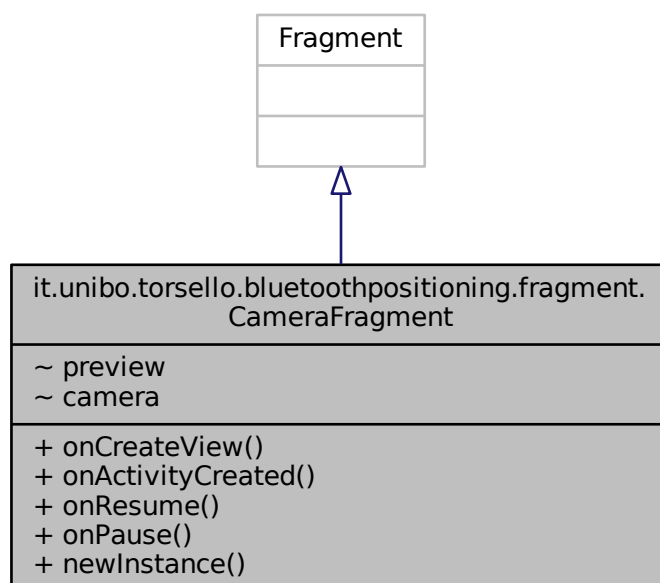
```
UsbUtil it.unibo.torsello.bluetoothpositioning.activities.ApplicationActivity.usbUtil [private]
```

La documentazione per questa classe è stata generata a partire dal seguente file:

- [ApplicationActivity.java](#)

6.2 Riferimenti per la classe it.unibo.torsello.bluetoothpositioning.fragment.CameraFragment

Diagramma delle classi per it.unibo.torsello.bluetoothpositioning.fragment.CameraFragment



6.2.2.2 `onActivityCreated()`

```

void it.unibo.torsello.bluetoothpositioning.fragment.CameraFragment.onActivityCreated (
    @Nullable Bundle savedInstanceState )

70                                     {
71     super.onActivityCreated(savedInstanceState);
72
73     getActivity().findViewById(R.id.fab_camera).setOnClickListener(new View.OnClickListener() {
74         @Override
75         public void onClick(View v) {
76             preview.takePicture();
77         }
78     });
79
80 }
```

6.2.2.3 `onCreateView()`

```

View it.unibo.torsello.bluetoothpositioning.fragment.CameraFragment.onCreateView (
    LayoutInflater inflater,
    ViewGroup container,
    Bundle savedInstanceState )

30                                     {
31
32     View root = inflater.inflate(R.layout.fragment_camera, container, false);
33     preview = new CameraPreviewUtil(getContext(), (SurfaceView) root.findViewById(R.id.
surfaceView));
34     ((FrameLayout) root.findViewById(R.id.layout)).addView(preview);
35     preview.setKeepScreenOn(true);
36     preview.setOnClickListener(new OnClickListener() {
37
38         @Override
39         public void onClick(View arg0) {
40         //         preview.takePicture();
41             camera.autoFocus(new Camera.AutoFocusCallback() {
42                 @Override
43                 public void onAutoFocus(boolean success, Camera arg1) {
44                 //                 if (success) {
45                 //                     preview.takePicture();
46                 //                 }
47             });
48         });
49     });
50
51     preview.setOnLongClickListener(new View.OnLongClickListener() {
52         @Override
53         public boolean onLongClick(View arg0) {
54
55             camera.autoFocus(new Camera.AutoFocusCallback() {
56                 @Override
57                 public void onAutoFocus(boolean success, Camera arg1) {
58                 //                 if (success) {
59                 //                     preview.takePicture();
60                 //                 }
61             });
62         });
63         return true;
64     });
65
66     return root;
67 }
```

6.2.2.4 `onPause()`

```

void it.unibo.torsello.bluetoothpositioning.fragment.CameraFragment.onPause ( )

90                                     {
91     preview.onPause();
92     super.onPause();
93 }
```

6.2.2.5 onResume()

```
void it.unibo.torsello.bluetoothpositioning.fragment.CameraFragment.onResume ( )
```

```
83         {  
84             super.onResume();  
85             preview.setCamera(getActivity());  
86             camera = preview.getCamera();  
87         }
```

6.2.3 Documentazione dei membri dato

6.2.3.1 camera

```
Camera it.unibo.torsello.bluetoothpositioning.fragment.CameraFragment.camera [package]
```

6.2.3.2 preview

```
CameraPreviewUtil it.unibo.torsello.bluetoothpositioning.fragment.CameraFragment.preview [package]
```

La documentazione per questa classe è stata generata a partire dal seguente file:

- [CameraFragment.java](#)

6.3 Riferimenti per la classe `it.unibo.torsello.bluetoothpositioning.util.CameraPreviewUtil`

Diagramma delle classi per `it.unibo.torsello.bluetoothpositioning.util.CameraPreviewUtil`

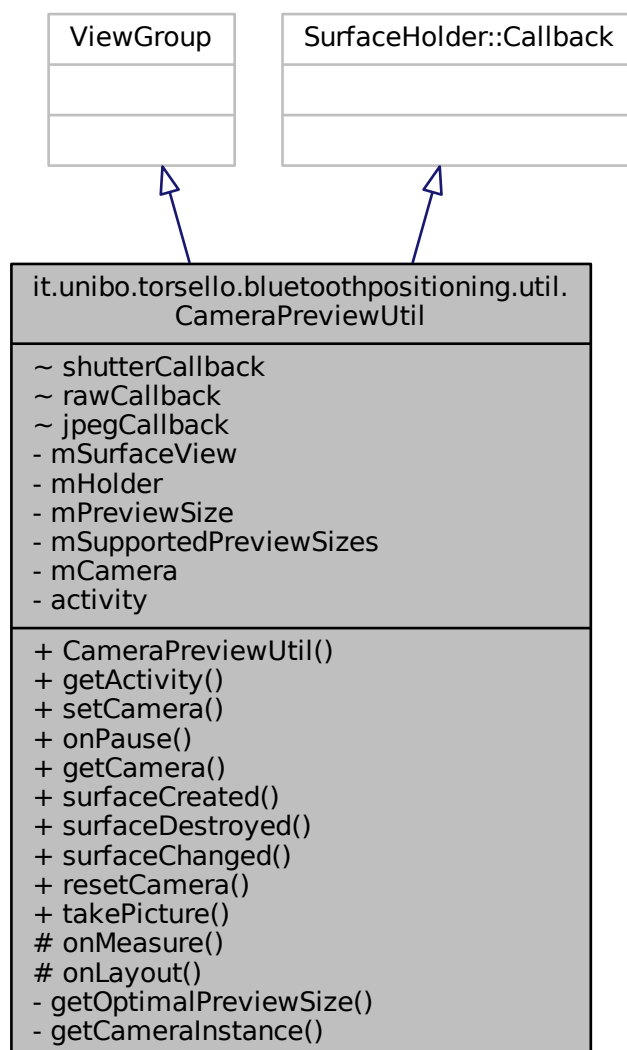
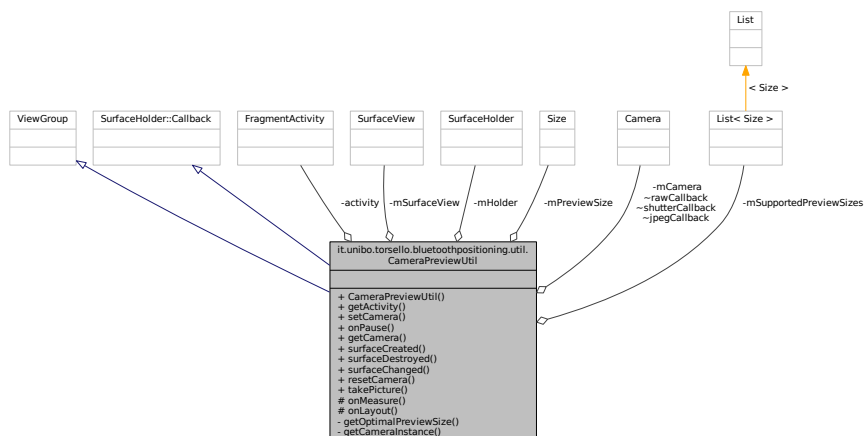


Diagramma di collaborazione per `it.unibo.torsello.bluetoothpositioning.util.CameraPreviewUtil`:



Membri pubblici

- `CameraPreviewUtil` (Context context, SurfaceView sv)
- `FragmentActivity` `getActivity ()`
- void `setCamera` (FragmentActivity fragmentActivity)
- void `onPause ()`
- `Camera` `getCamera ()`
- void `surfaceCreated` (SurfaceHolder holder)
- void `surfaceDestroyed` (SurfaceHolder holder)
- void `surfaceChanged` (SurfaceHolder holder, int format, int w, int h)
- void `resetCamera ()`
- void `takePicture ()`

Membri protetti

- void `onMeasure` (int widthMeasureSpec, int heightMeasureSpec)
- void `onLayout` (boolean changed, int l, int t, int r, int b)

Attributi con visibilità di package

- `Camera.ShutterCallback` `shutterCallback`
- `Camera.PictureCallback` `rawCallback`
- `Camera.PictureCallback` `jpegCallback`

Membri privati

- `Size` `getOptimalPreviewSize` (List< Size > sizes, int w, int h)

Membri privati statici

- static `Camera` `getCameraInstance ()`

Attributi privati

- SurfaceView `mSurfaceView`
- SurfaceHolder `mHolder`
- Size `mPreviewSize`
- List< Size > `mSupportedPreviewSizes`
- Camera `mCamera`
- FragmentActivity `activity`

6.3.1 Descrizione dettagliata

Created by Federico Torsello. federico.torsello@studio.unibo.it

6.3.2 Documentazione dei costruttori e dei distruttori

6.3.2.1 CameraPreviewUtil()

```
it.unibo.torsello.bluetoothpositioning.util.CameraPreviewUtil.CameraPreviewUtil (
    Context context,
    SurfaceView sv )

32                                     {
33     super(context);
34     mSurfaceView = sv;
35
36     mHolder = mSurfaceView.getHolder();
37     mHolder.addCallback(this);
38     mHolder.setType(SurfaceHolder.SURFACE_TYPE_PUSH_BUFFERS);
39 }
```

6.3.3 Documentazione delle funzioni membro

6.3.3.1 getActivity()

```
FragmentActivity it.unibo.torsello.bluetoothpositioning.util.CameraPreviewUtil.getActivity ( )

41                                     {
42     return activity;
43 }
```

6.3.3.2 getCamera()

```
Camera it.unibo.torsello.bluetoothpositioning.util.CameraPreviewUtil.getCamera ( )

81                                     {
82     return mCamera;
83 }
```

6.3.3.3 getCameraInstance()

```
static Camera it.unibo.torsello.bluetoothpositioning.util.CameraPreviewUtil.getCameraInstance
( ) [static], [private]
```

A safe way to get an instance of the CameraUtil object.

```
88                                     {
89
90         Camera c = null;
91
92         try {
93             int numCams = Camera.getNumberOfCameras();
94             if (numCams > 0) {
95                 c = Camera.open(0); // attempt to get a CameraUtil instance
96             }
97         } catch (RuntimeException e) {
98             // CameraUtil is not available (in use or does not exist)
99             e.printStackTrace();
100         }
101
102         return c; // returns null if camera is unavailable
103     }
```

6.3.3.4 getOptimalPreviewSize()

```
Size it.unibo.torsello.bluetoothpositioning.util.CameraPreviewUtil.getOptimalPreviewSize (
    List< Size > sizes,
    int w,
    int h ) [private]
```

```
169                                     {
170         final double ASPECT_TOLERANCE = 0.1;
171         double targetRatio = (double) w / h;
172         if (sizes == null) return null;
173
174         Size optimalSize = null;
175         double minDiff = Double.MAX_VALUE;
176
177         //      int targetHeight = h;
178
179         // Try to find an size match aspect ratio and size
180         for (Size size : sizes) {
181             double ratio = (double) size.width / size.height;
182             if (Math.abs(ratio - targetRatio) > ASPECT_TOLERANCE) continue;
183             if (Math.abs(size.height - h) < minDiff) {
184                 optimalSize = size;
185                 minDiff = Math.abs(size.height - h);
186             }
187         }
188
189         // Cannot find the one match the aspect ratio, ignore the requirement
190         if (optimalSize == null) {
191             minDiff = Double.MAX_VALUE;
192             for (Size size : sizes) {
193                 if (Math.abs(size.height - h) < minDiff) {
194                     optimalSize = size;
195                     minDiff = Math.abs(size.height - h);
196                 }
197             }
198         }
199         return optimalSize;
200     }
```

6.3.3.5 `onLayout()`

```

void it.unibo.torsello.bluetoothpositioning.util.CameraPreviewUtil.onLayout (
    boolean changed,
    int l,
    int t,
    int r,
    int b ) [protected]

120
121                                     {
122     if (changed && getChildCount() > 0) {
123         final View child = getChildAt(0);
124
125         final int width = r - l;
126         final int height = b - t;
127
128         int previewWidth = width;
129         int previewHeight = height;
130         if (mPreviewSize != null) {
131             previewWidth = mPreviewSize.width;
132             previewHeight = mPreviewSize.height;
133         }
134
135         // Center the child SurfaceView within the parent.
136         if (width * previewHeight > height * previewWidth) {
137             final int scaledChildWidth = previewWidth * height / previewHeight;
138             child.layout((width - scaledChildWidth) / 2, 0,
139                         (width + scaledChildWidth) / 2, height);
140         } else {
141             final int scaledChildHeight = previewHeight * width / previewWidth;
142             child.layout(0, (height - scaledChildHeight) / 2,
143                         width, (height + scaledChildHeight) / 2);
144         }
145     }
146 }

```

6.3.3.6 `onMeasure()`

```

void it.unibo.torsello.bluetoothpositioning.util.CameraPreviewUtil.onMeasure (
    int widthMeasureSpec,
    int heightMeasureSpec ) [protected]

106
107                                     {
108     // We purposely disregard child measurements because act as a
109     // wrapper to a SurfaceView that centers the camera preview instead
110     // of stretching it.
111     final int width = resolveSize(getSuggestedMinimumWidth(), widthMeasureSpec);
112     final int height = resolveSize(getSuggestedMinimumHeight(), heightMeasureSpec);
113     setMeasuredDimension(width, height);
114
115     if (mSupportedPreviewSizes != null) {
116         mPreviewSize = getOptimalPreviewSize(
117             mSupportedPreviewSizes, width, height);
118     }
119 }

```

6.3.3.7 `onPause()`

```

void it.unibo.torsello.bluetoothpositioning.util.CameraPreviewUtil.onPause ( )

73                                     {
74     if (mCamera != null) {
75         mCamera.stopPreview();
76         mCamera.release();
77         mCamera = null;
78     }
79 }

```

6.3.3.8 resetCamera()

```
void it.unibo.torsello.bluetoothpositioning.util.CameraPreviewUtil.resetCamera ( )
```

```
215         {
216         new Thread(new Runnable() {
217             @Override
218             public void run() {
219                 mCamera.startPreview();
220             }
221         }).start();
222
223
224     }
```

6.3.3.9 setCamera()

```
void it.unibo.torsello.bluetoothpositioning.util.CameraPreviewUtil.setCamera (
    FragmentActivity fragmentActivity )
```

```
45         {
46
47         this.activity = fragmentActivity;
48         try {
49             mCamera = getCameraInstance();
50         } catch (RuntimeException ex) {
51             Toast.makeText(fragmentActivity, "camera_not_found", Toast.LENGTH_LONG).show();
52         }
53
54         if (mCamera != null) {
55
56             mSupportedPreviewSizes = mCamera.getParameters().
getSupportedPreviewSizes();
57             requestLayout();
58
59             // get Camera parameters
60             Camera.Parameters params = mCamera.getParameters();
61
62             List<String> focusModes = params.getSupportedFocusModes();
63             if (focusModes.contains(Camera.Parameters.FOCUS_MODE_AUTO)) {
64                 // set the focus mode
65                 params.setFocusMode(Camera.Parameters.FOCUS_MODE_AUTO);
66                 // set Camera parameters
67                 mCamera.setParameters(params);
68             }
69         }
70
71     }
```

6.3.3.10 surfaceChanged()

```
void it.unibo.torsello.bluetoothpositioning.util.CameraPreviewUtil.surfaceChanged (
    SurfaceHolder holder,
    int format,
    int w,
    int h )
```

```
203         {
204         if (mCamera != null) {
205             Camera.Parameters parameters = mCamera.getParameters();
206             parameters.setPreviewSize(mPreviewSize.width,
mPreviewSize.height);
207             requestLayout();
208
209             mCamera.setParameters(parameters);
210
211             resetCamera();
212         }
213     }
```

6.3.3.11 `surfaceCreated()`

```
void it.unibo.torsello.bluetoothpositioning.util.CameraPreviewUtil.surfaceCreated (
    SurfaceHolder holder )
```

```
148                                     {
149     // The Surface has been created, acquire the camera and tell it where
150     // to draw.
151     try {
152         if (mCamera != null) {
153             mCamera.setDisplayOrientation(90);
154             mCamera.setPreviewDisplay(holder);
155         }
156     } catch (IOException exception) {
157         // Log.e(TAG, "IOException caused by setPreviewDisplay()", exception);
158     }
159 }
```

6.3.3.12 `surfaceDestroyed()`

```
void it.unibo.torsello.bluetoothpositioning.util.CameraPreviewUtil.surfaceDestroyed (
    SurfaceHolder holder )
```

```
162                                     {
163     // Surface will be destroyed when we return, so stop the preview.
164     if (mCamera != null) {
165         mCamera.stopPreview();
166     }
167 }
```

6.3.3.13 `takePicture()`

```
void it.unibo.torsello.bluetoothpositioning.util.CameraPreviewUtil.takePicture ( )
```

```
246                                     {
247
248     mCamera.takePicture(shutterCallback, rawCallback,
249         jpegCallback);
249 }
```

6.3.4 Documentazione dei membri dato

6.3.4.1 `activity`

```
FragmentActivity it.unibo.torsello.bluetoothpositioning.util.CameraPreviewUtil.activity [private]
```

6.3.4.2 `jpegCallback`

```
Camera.PictureCallback it.unibo.torsello.bluetoothpositioning.util.CameraPreviewUtil.jpeg↵
Callback [package]
```

Valore iniziale:

```
= new Camera.PictureCallback() {
    public void onPictureTaken(byte[] data, final Camera camera) {
        new SaveImageTask(getActivity()).execute(data);

        resetCamera();
    }
}
```

6.3.4.3 mCamera

Camera it.unibo.torsello.bluetoothpositioning.util.CameraPreviewUtil.mCamera [private]

6.3.4.4 mHolder

SurfaceHolder it.unibo.torsello.bluetoothpositioning.util.CameraPreviewUtil.mHolder [private]

6.3.4.5 mPreviewSize

Size it.unibo.torsello.bluetoothpositioning.util.CameraPreviewUtil.mPreviewSize [private]

6.3.4.6 mSupportedPreviewSizes

List<Size> it.unibo.torsello.bluetoothpositioning.util.CameraPreviewUtil.mSupportedPreview↵
Sizes [private]

6.3.4.7 mSurfaceView

SurfaceView it.unibo.torsello.bluetoothpositioning.util.CameraPreviewUtil.mSurfaceView [private]

6.3.4.8 rawCallback

Camera.PictureCallback it.unibo.torsello.bluetoothpositioning.util.CameraPreviewUtil.raw↵
Callback [package]

Valore iniziale:

```
= new Camera.PictureCallback() {  
    public void onPictureTaken(byte[] data, Camera camera) {  
    }  
}
```

6.3.4.9 shutterCallback

Camera.ShutterCallback it.unibo.torsello.bluetoothpositioning.util.CameraPreviewUtil.shutter↵
Callback [package]

Valore iniziale:

```
= new Camera.ShutterCallback() {  
    public void onShutter() {  
    }  
}
```

La documentazione per questa classe è stata generata a partire dal seguente file:

- [CameraPreviewUtil.java](#)

6.4 Riferimenti per la classe it.unibo.torsello.bluetoothpositioning.util.ChartUtil

Diagramma delle classi per it.unibo.torsello.bluetoothpositioning.util.ChartUtil

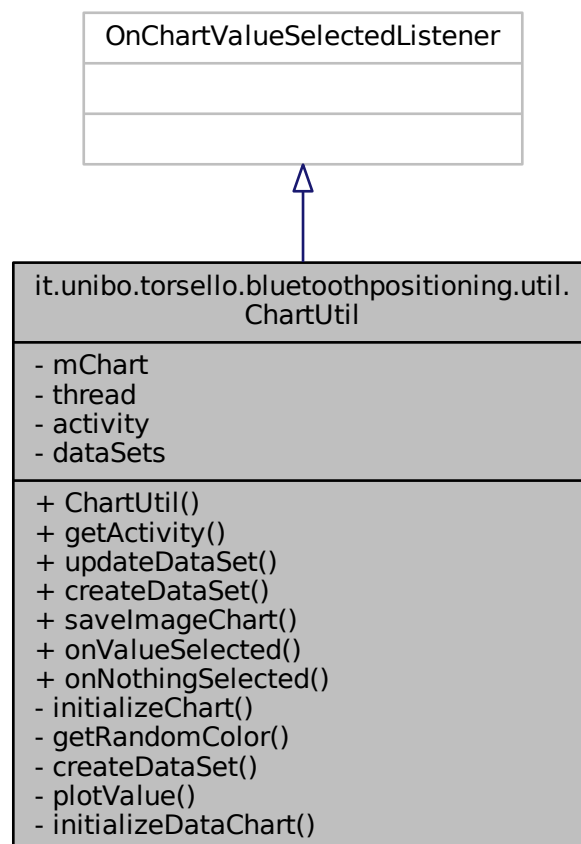
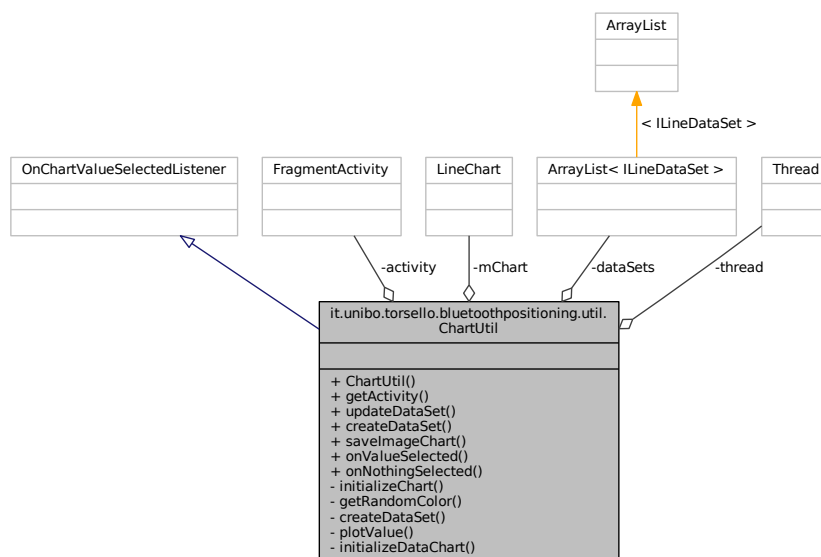


Diagramma di collaborazione per `it.unibo.torsello.bluetoothpositioning.util.ChartUtil`:



Membri pubblici

- `ChartUtil` (`FragmentActivity fragmentActivity`, `LineChart chart`)
- `FragmentActivity getActivity ()`
- `void updateDataSet (final ArrayList< Double > doubleArrayList)`
- `ArrayList< ILineDataSet > createDataSet (ArrayList< String > args)`
- `void saveImageChart ()`
- `void onValueSelected (Entry e, Highlight h)`
- `void onNothingSelected ()`

Membri privati

- `void initializeChart ()`
- `int getRandomColor ()`
- `LineDataSet createDataSet (String nameDataSet, int color)`
- `void plotValue (LineData data, int index, Double value)`
- `void initializeDataChart (ArrayList< ILineDataSet > dataSets)`

Attributi privati

- `LineChart mChart`
- `Thread thread`
- `FragmentActivity activity`
- `ArrayList< ILineDataSet > dataSets`

6.4.1 Descrizione dettagliata

Created by Federico Torsello. federico.torsello@studio.unibo.it

6.4.2 Documentazione dei costruttori e dei distruttori

6.4.2.1 `ChartUtil()`

```
it.unibo.torsello.bluetoothpositioning.util.ChartUtil.ChartUtil (
    FragmentActivity fragmentActivity,
    LineChart chart )

37
38         this.activity = fragmentActivity;
39         this.mChart = chart;
40         initializeChart();
41     }
```

6.4.3 Documentazione delle funzioni membro

6.4.3.1 `createDataSet()` [1/2]

```
ArrayList<ILineDataSet> it.unibo.torsello.bluetoothpositioning.util.ChartUtil.createDataSet (
    ArrayList< String > args )

126
127         // create a dataset and give it a type
128
129         for (String s : args) {
130             if (s != null) {
131                 if (s.equals(getActivity().getString(R.string.chart_arduino))) {
132                     dataSets.add(createDataSet(s, Color.RED));
133                 } else {
134                     dataSets.add(createDataSet(s,
135                     getRandomColor()));
136                 }
137             }
138
139             return dataSets;
140         }
```

6.4.3.2 `createDataSet()` [2/2]

```
LineDataSet it.unibo.torsello.bluetoothpositioning.util.ChartUtil.createDataSet (
    String nameDataSet,
    int color ) [private]

151
152         LineDataSet set = new LineDataSet(null, nameDataSet);
153         set.setColor(color);
154         return set;
155     }
```

6.4.3.3 `getActivity()`

```
FragmentActivity it.unibo.torsello.bluetoothpositioning.util.ChartUtil.getActivity ( )

43
44         return activity;
45     }
```

6.4.3.4 getRandomColor()

```
int it.unibo.torsello.bluetoothpositioning.util.ChartUtil.getRandomColor ( ) [private]

142
143     Random rnd = new Random();
144     int color = 0;
145     while (color == 0) {
146         color = Color.argb(255, rnd.nextInt(255), rnd.nextInt(255), rnd.nextInt(255));
147     }
148     return color;
149 }
```

6.4.3.5 initializeChart()

```
void it.unibo.torsello.bluetoothpositioning.util.ChartUtil.initializeChart ( ) [private]

47
48     dataSets = new ArrayList<ILineDataSet>();
49
50     mChart.setOnChartValueSelectedListener(this);
51
52     // no description text
53     mChart.setDescription("");
54     mChart.setNoDataTextDescription("You need to provide data for the chart.");
55
56     mChart.setDrawGridBackground(true);
57
58     // if disabled, scaling can be done on x- and y-axis separately
59     mChart.setPinchZoom(true);
60
61     // set an alternative background color
62     mChart.setBackgroundColor(Color.LTGRAY);
63
64     Typeface mTfLight = Typeface.createFromAsset(getActivity().getAssets(), "
OpenSans-Light.ttf");
65     Typeface mTfBold = Typeface.createFromAsset(getActivity().getAssets(), "
OpenSans-Bold.ttf");
66
67     // get the legend (only possible after setting data)
68     Legend l = mChart.getLegend();
69     //     l.setPosition(Legend.LegendPosition.RIGHT_OF_CHART);
70     //     l.setOrientation(Legend.LegendOrientation.VERTICAL);
71     l.setXEntrySpace(7f);
72     l.setYEntrySpace(7f);
73
74     XAxis xl = mChart.getXAxis();
75     xl.setTypeface(mTfLight);
76     xl.setGridColor(Color.LTGRAY);
77     xl.setTextColor(Color.WHITE);
78
79     YAxis leftAxis = mChart.getAxisLeft();
80     leftAxis.setTypeface(mTfLight);
81     leftAxis.setTextColor(Color.WHITE);
82
83     YAxis rightAxis = mChart.getAxisRight();
84     rightAxis.setTypeface(mTfBold);
85
86 }
```

6.4.3.6 initializeDataChart()

```
void it.unibo.torsello.bluetoothpositioning.util.ChartUtil.initializeDataChart (
    ArrayList< ILineDataSet > dataSets ) [private]

175
176
177     // create a data object with the datasets
178     LineData lineData = new LineData(dataSets);
179     lineData.setValueTextColor(Color.RED);
180     lineData.setValueTextSize(9f);
181     lineData.setValueFormatter(new DefaultValueFormatter(2));
182
183     // set data
184     mChart.setData(lineData);
185 }
```

6.4.3.7 `onNothingSelected()`

```
void it.unibo.torsello.bluetoothpositioning.util.ChartUtil.onNothingSelected ( )
```

```
197         {
198         Log.i("Nothing selected", "Nothing selected.");
199         }
```

6.4.3.8 `onValueSelected()`

```
void it.unibo.torsello.bluetoothpositioning.util.ChartUtil.onValueSelected (
    Entry e,
    Highlight h )
```

```
192         {
193         Log.i("Entry selected", e.toString());
194         }
```

6.4.3.9 `plotValue()`

```
void it.unibo.torsello.bluetoothpositioning.util.ChartUtil.plotValue (
    LineData data,
    int index,
    Double value ) [private]
```

```
157         {
158
159         ILineDataSet set = data.getDataSetByIndex(index);
160
161         set.addEntry(new Entry(set.getEntryCount(), value.floatValue()));
162
163         data.notifyDataChanged();
164
165         // let the chart know it's data has changed
166         mChart.notifyDataSetChanged();
167
168         // limit the number of visible entries
169         mChart.setVisibleXRangeMaximum(10);
170
171         // move to the latest entry
172         mChart.moveToX(data.getEntryCount());
173     }
```

6.4.3.10 `saveImageChart()`

```
void it.unibo.torsello.bluetoothpositioning.util.ChartUtil.saveImageChart ( )
```

```
187         {
188         mChart.saveToGallery("prova", 100);
189     }
```

6.4.3.11 updateDataSet()

```

void it.unibo.torsello.bluetoothpositioning.util.ChartUtil.updateDataSet (
    final ArrayList< Double > doubleArrayList )

88
89                                     {
90     if (thread != null)
91         thread.interrupt();
92
93     thread = new Thread(new Runnable() {
94         @Override
95         public void run() {
96             if (getActivity() != null) {
97                 getActivity().runOnUiThread(new Runnable() {
98                     @Override
99                     public void run() {
100
101                         LineData data = mChart.getData();
102
103                         if (data == null) {
104                             if (dataSets != null) {
105                                 initializeDataChart(
106                                     dataSets);
107                             } else {
108                                 throw new Error("Error: dataSet is null!!!");
109                             }
110                         } else {
111                             if (data.getDataSetCount() > 0) {
112                                 for (int i = 0; i < doubleArrayList.size(); i++) {
113                                     plotValue(data, i, doubleArrayList.get(i));
114                                 }
115                             }
116                         }
117                     }
118                 });
119             }
120         }
121     });
122     thread.start();
123 }

```

6.4.4 Documentazione dei membri dato

6.4.4.1 activity

FragmentActivity it.unibo.torsello.bluetoothpositioning.util.ChartUtil.activity [private]

6.4.4.2 dataSets

ArrayList<ILineDataSet> it.unibo.torsello.bluetoothpositioning.util.ChartUtil.dataSets [private]

6.4.4.3 mChart

LineChart it.unibo.torsello.bluetoothpositioning.util.ChartUtil.mChart [private]

6.4.4.4 thread

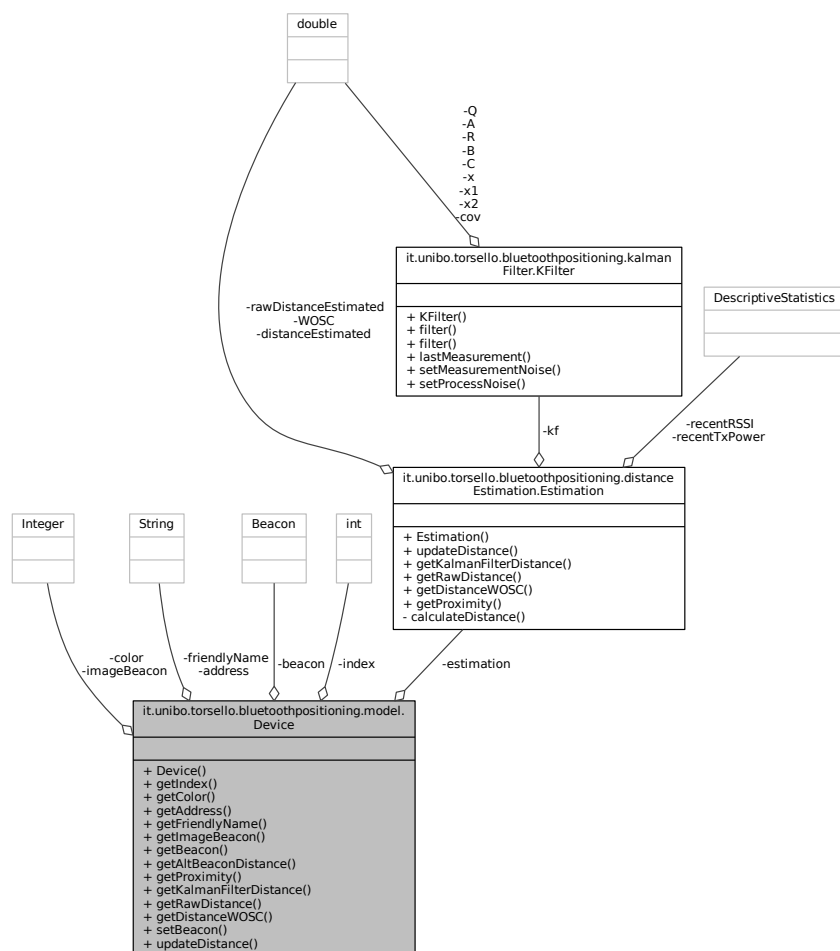
Thread it.unibo.torsello.bluetoothpositioning.util.ChartUtil.thread [private]

La documentazione per questa classe è stata generata a partire dal seguente file:

- [ChartUtil.java](#)

6.5 Riferimenti per la classe it.unibo.torsello.bluetoothpositioning.model.Device

Diagramma di collaborazione per it.unibo.torsello.bluetoothpositioning.model.Device:



Membri pubblici

- `Device` (int `index`, String `address`, String `friendlyName`, Integer `color`, Integer `imageBeacon`)
- int `getIndex` ()
- Integer `getColor` ()
- String `getAddress` ()
- String `getFriendlyName` ()
- Integer `getImageBeacon` ()
- Beacon `getBeacon` ()
- double `getAltBeaconDistance` ()
- String `getProximity` ()
- double `getKalmanFilterDistance` ()
- double `getRawDistance` ()
- double `getDistanceWOSC` ()
- void `setBeacon` (Beacon `beacon`)
- void `updateDistance` (double `processNoise`)

Attributi privati

- [Estimation estimation](#)
- String [address](#)
- String [friendlyName](#)
- Beacon [beacon](#)
- Integer [imageBeacon](#)
- Integer [color](#)
- int [index](#)

6.5.1 Descrizione dettagliata

Created by Federico Torsello. federico.torsello@studio.unibo.it

6.5.2 Documentazione dei costruttori e dei distruttori

6.5.2.1 Device()

```
it.unibo.torsello.bluetoothpositioning.model.Device.Device (
    int index,
    String address,
    String friendlyName,
    Integer color,
    Integer imageBeacon )

21                                     {
22     this.index = index;
23     this.address = address;
24     this.friendlyName = friendlyName;
25     this.estimation = new Estimation();
26     this.imageBeacon = imageBeacon;
27     this.color = color;
28 }
```

6.5.3 Documentazione delle funzioni membro

6.5.3.1 getAddress()

```
String it.unibo.torsello.bluetoothpositioning.model.Device.getAddress ( )

38                                     {
39     return this.address;
40 }
```

6.5.3.2 getAltBeaconDistance()

```
double it.unibo.torsello.bluetoothpositioning.model.Device.getAltBeaconDistance ( )

54                                     {
55     return beacon.getDistance();
56 }
```


6.5.3.3 `getBeacon()`

`Beacon it.unibo.torsello.bluetoothpositioning.model.Device.getBeacon ()`

```
50      {  
51      return beacon;  
52      }
```

6.5.3.4 `getColor()`

`Integer it.unibo.torsello.bluetoothpositioning.model.Device.getColor ()`

```
34      {  
35      return color;  
36      }
```

6.5.3.5 `getDistanceWOSC()`

`double it.unibo.torsello.bluetoothpositioning.model.Device.getDistanceWOSC ()`

```
71      {  
72      return estimation.getDistanceWOSC();  
73      }
```

6.5.3.6 `getFriendlyName()`

`String it.unibo.torsello.bluetoothpositioning.model.Device.getFriendlyName ()`

```
42      {  
43      return friendlyName;  
44      }
```

6.5.3.7 `getImageBeacon()`

`Integer it.unibo.torsello.bluetoothpositioning.model.Device.getImageBeacon ()`

```
46      {  
47      return imageBeacon;  
48      }
```

6.5.3.8 `getIndex()`

`int it.unibo.torsello.bluetoothpositioning.model.Device.getIndex ()`

```
30      {  
31      return index;  
32      }
```

6.5.3.9 getKalmanFilterDistance()

```
double it.unibo.torsello.bluetoothpositioning.model.Device.getKalmanFilterDistance ( )
```

```
63                                     {
64         return estimation.getKalmanFilterDistance();
65     }
```

6.5.3.10 getProximity()

```
String it.unibo.torsello.bluetoothpositioning.model.Device.getProximity ( )
```

```
58                                     {
59         return estimation.getProximity();
60     }
```

6.5.3.11 getRawDistance()

```
double it.unibo.torsello.bluetoothpositioning.model.Device.getRawDistance ( )
```

```
67                                     {
68         return estimation.getRawDistance();
69     }
```

6.5.3.12 setBeacon()

```
void it.unibo.torsello.bluetoothpositioning.model.Device.setBeacon (
    Beacon beacon )
```

```
75                                     {
76         this.beacon = beacon;
77     }
```

6.5.3.13 updateDistance()

```
void it.unibo.torsello.bluetoothpositioning.model.Device.updateDistance (
    double processNoise )
```

```
79                                     {
80         if (beacon != null) {
81             estimation.updateDistance(beacon, processNoise);
82         }
83     }
```

6.5.4 Documentazione dei membri dato

6.5.4.1 address

```
String it.unibo.torsello.bluetoothpositioning.model.Device.address [private]
```

6.5.4.2 beacon

`Beacon it.unibo.torsello.bluetoothpositioning.model.Device.beacon [private]`

6.5.4.3 color

`Integer it.unibo.torsello.bluetoothpositioning.model.Device.color [private]`

6.5.4.4 estimation

`Estimation it.unibo.torsello.bluetoothpositioning.model.Device.estimation [private]`

6.5.4.5 friendlyName

`String it.unibo.torsello.bluetoothpositioning.model.Device.friendlyName [private]`

6.5.4.6 imageBeacon

`Integer it.unibo.torsello.bluetoothpositioning.model.Device.imageBeacon [private]`

6.5.4.7 index

`int it.unibo.torsello.bluetoothpositioning.model.Device.index [private]`

La documentazione per questa classe è stata generata a partire dal seguente file:

- [Device.java](#)

6.6 Riferimenti per la classe `it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter`

Diagramma delle classi per `it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter`

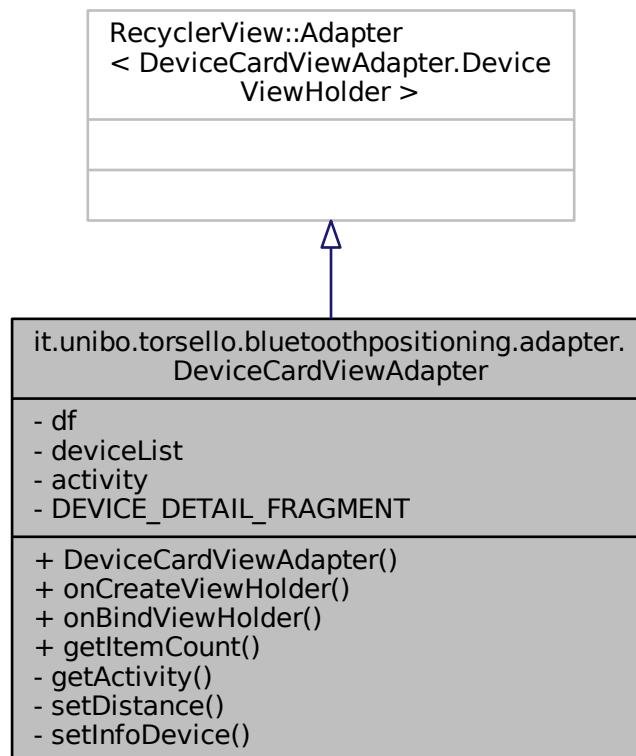
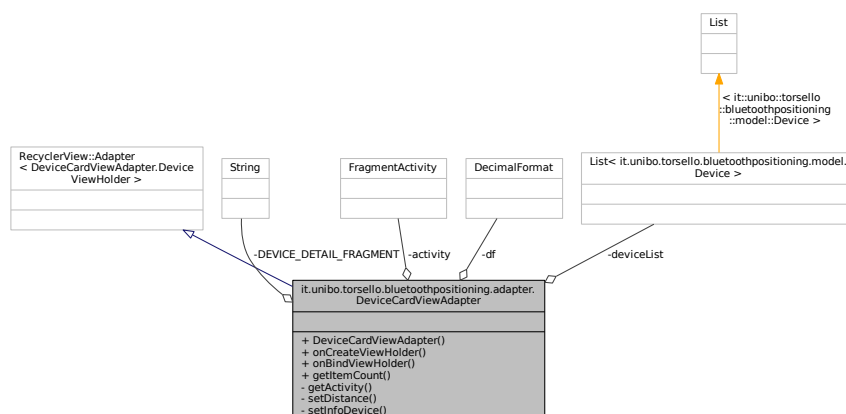


Diagramma di collaborazione per `it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter`:



Composti

- class [DeviceViewHolder](#)

Membri pubblici

- `DeviceCardViewAdapter` (final `FragmentActivity` `fragmentActivity`, `List< Device >` `deviceList`)
- `DeviceViewHolder onCreateViewHolder` (`ViewGroup` `parent`, `int` `viewType`)
- void `onBindViewHolder` (`DeviceViewHolder` `holder`, final `int` `position`)
- `int getItemCount` ()

Membri privati

- `FragmentActivity` `getActivity` ()
- void `setDistance` (`DeviceViewHolder` `holder`, `Device` `device`)
- void `setInfoDevice` (`DeviceViewHolder` `holder`, `Beacon` `beacon`)

Attributi privati

- `DecimalFormat` `df`
- `List< Device >` `deviceList`
- `FragmentActivity` `activity`

Attributi privati statici

- static final `String` `DEVICE_DETAIL_FRAGMENT` = "device detail"

6.6.1 Descrizione dettagliata

Created by Federico Torsello. federico.torsello@studio.unibo.it

6.6.2 Documentazione dei costruttori e dei distruttori**6.6.2.1 DeviceCardViewAdapter()**

```

it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.DeviceCardViewAdapter (
    final FragmentActivity fragmentActivity,
    List< Device > deviceList )

36
37
38     this.deviceList = new ArrayList<>();
39     this.deviceList = deviceList;
40     this.activity = fragmentActivity;
41
42     df = new DecimalFormat ("0.00", DecimalFormatSymbols.getInstance());
43 }
```

6.6.3 Documentazione delle funzioni membro**6.6.3.1 getActivity()**

```

FragmentActivity it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.get↔
Activity ( ) [private]

45
46     return activity;
47 }
```

6.6.3.2 getItemCount()

```
int it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.getItemCount ( )
```

```
217         {
218         return deviceList.size();
219     }
```

6.6.3.3 onBindViewHolder()

```
void it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.onBindViewHolder (
    DeviceViewHolder holder,
    final int position )
```

```
58
59
60     final Beacon beacon = deviceList.get(position).getBeacon();
61     final Device device = deviceList.get(position);
62
63     setInfoDevice(holder, beacon);
64
65     setDistance(holder, device);
66
67     final Integer imageBeacon = device.getImageBeacon();
68     if (imageBeacon != null) {
69         holder.imageView.setImageResource(imageBeacon);
70     } else {
71         holder.imageView.setImageResource(R.drawable.beacon_unknown);
72     }
73
74     holder.rssiTextView.setText(String.format("%sdb", beacon.getTxPower()));
75
76     holder.txPowerTextView.setText(String.format("%sdb", beacon.getRssi()));
77
78     final String friendlyName = device.getFriendlyName();
79     if (friendlyName != null) {
80         holder.friendlyNameTextView.setText(friendlyName);
81     } else {
82         holder.friendlyNameTextView.setText(android.R.string.unknownName);
83     }
84
85     final String bluetoothName = beacon.getBluetoothName();
86     if (bluetoothName != null) {
87         holder.defaultNameTextView.setText(bluetoothName);
88     } else {
89         holder.defaultNameTextView.setText(android.R.string.unknownName);
90     }
91
92     final String macAddress = beacon.getBluetoothAddress();
93     if (macAddress != null) {
94         holder.macTextView.setText(macAddress);
95     } else {
96         holder.macTextView.setText(android.R.string.unknownName);
97     }
98
99     final String proximity = device.getProximity();
100    if (proximity != null) {
101        holder.proximityTextView.setText(proximity);
102    } else {
103        holder.proximityTextView.setText(android.R.string.unknownName);
104    }
105
106    final Integer color = device.getColor();
107    if (color != null) {
108        holder.colorTextView.setText(color);
109    } else {
110        holder.colorTextView.setText(android.R.string.unknownName);
111    }
112
113    holder.view.setOnClickListener(new View.OnClickListener() {
114        @Override
115        public void onClick(View v) {
116            final String deviceDetailName;
117            if (device.getFriendlyName() != null) {
118                deviceDetailName = device.getFriendlyName();
119            } else {
120                deviceDetailName = device.getAddress();
121            }
122        }
123    });
```

```

121         }
122
123         new Thread(new Runnable() {
124             @Override
125             public void run() {
126                 getActivity().runOnUiThread(new Runnable() {
127                     @Override
128                     public void run() {
129
130                         Fragment currentFrag = getActivity().getSupportFragmentManager()
131                             .findFragmentByTag(
132                                 DEVICE_DETAIL_FRAGMENT);
133
134                         if (currentFrag == null) {
135                             getActivity().getSupportFragmentManager().beginTransaction()
136                                 .replace(R.id.contentMainLayout,
137                                     DeviceDetailFragment.newInstance(deviceDetailName),
138                                     DEVICE_DETAIL_FRAGMENT)
139                                 .commit();
140                         }
141                     }
142                 });
143             }.start();
144         }
145     });
146 }

```

6.6.3.4 onCreateViewHolder()

`DeviceViewHolder` `it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.onCreateViewHolder` ←

```

CreateViewHolder (
    ViewGroup parent,
    int viewType )

50
51
52     View root = LayoutInflater.from(parent.getContext())
53         .inflate(R.layout.list_items, parent, false);
54     return new DeviceViewHolder(root);
55 }

```

6.6.3.5 setDistance()

```

void it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.setDistance (
    DeviceViewHolder holder,
    Device device ) [private]

148
149     holder.altbeaconDistanceTextView.setText(String.format("%sm", df.format(device.
150         getAltBeaconDistance())));
151     holder.standardRawDistanceTextView.setText(String.format("%sm", df.format(device.getRawDistance()
152         )));
153     holder.kalmanFilterDistanceTextView.setText(String.format("%s", df.format(device.
154         getKalmanFilterDistance())));
155 }

```

6.6.3.6 setInfoDevice()

```

void it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.setInfoDevice (
    DeviceViewHolder holder,
    Beacon beacon ) [private]

```

```

156                                     {
157         if (beacon.getServiceUuid() == 0xfeaa) {
158
159             holder.visibilityUUIDLinearLayout.setVisibility(View.GONE);
160             holder.visibilityNameSpaceLinearLayout.setVisibility(View.VISIBLE);
161
162             if (beacon.getBeaconTypeCode() == 0x00) {
163                 // Eddystone-UID
164                 if (beacon.getId1() != null) {
165                     holder.nameSpaceTextView.setText(beacon.getId1().toString());
166                 } else {
167                     holder.nameSpaceTextView.setText(android.R.string.unknownName);
168                 }
169
170                 if (beacon.getId2() != null) {
171                     holder.instanceTextView.setText(beacon.getId2().toString());
172                 } else {
173                     holder.instanceTextView.setText(android.R.string.unknownName);
174                 }
175
176             } else if (beacon.getBeaconTypeCode() == 0x10) {
177                 // Eddystone-URL
178                 // String url = UrlBeaconUrlCompressor.uncompress(beacon.getId1().toByteArray());
179             } else if (beacon.getBeaconTypeCode() == 0x20) {
180                 if (!beacon.getExtraDataFields().isEmpty()) {
181                     // Eddystone-TLM
182                 }
183             }
184         } else if (beacon.getServiceUuid() == 0xbeac) {
185             // AltBeacon
186         } else if (beacon.getBeaconTypeCode() == 0x0215) { //533 in dec
187
188             holder.visibilityUUIDLinearLayout.setVisibility(View.VISIBLE);
189             holder.visibilityNameSpaceLinearLayout.setVisibility(View.GONE);
190
191             // AppleIBeacon
192             if (beacon.getId1() != null) {
193                 holder.uuidTextView.setText(beacon.getId1().toString());
194             } else {
195                 holder.uuidTextView.setText(android.R.string.unknownName);
196             }
197
198             if (beacon.getId2() != null) {
199                 holder.majorTextView.setText(beacon.getId2().toString());
200             } else {
201                 holder.majorTextView.setText(android.R.string.unknownName);
202             }
203
204             if (beacon.getId3() != null) {
205                 holder.minorTextView.setText(beacon.getId3().toString());
206             } else {
207                 holder.minorTextView.setText(android.R.string.unknownName);
208             }
209
210         } else if (beacon.getBeaconTypeCode() == 0x0101) {
211             // EstimoteNearable
212         }
213     }
214 }

```

6.6.4 Documentazione dei membri dato

6.6.4.1 activity

```

FragmentActivity it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.activity
[private]

```

6.6.4.2 DEVICE_DETAIL_FRAGMENT

```

final String it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.DEVICE_DET←
AIL_FRAGMENT = "device detail" [static], [private]

```

6.6.4.3 deviceList

```

List<Device> it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.deviceList
[private]

```


6.6.4.4 df

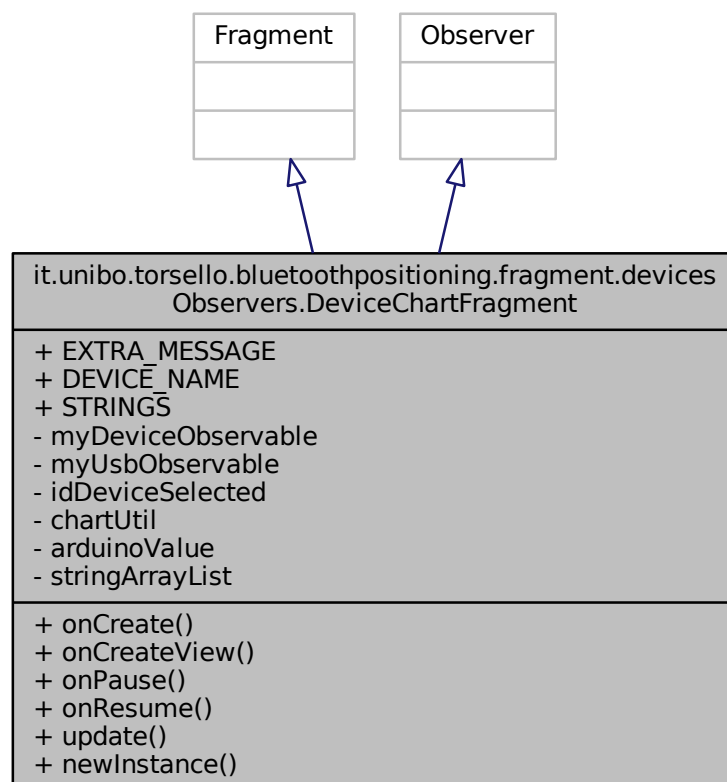
```
DecimalFormat it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.df [private]
```

La documentazione per questa classe è stata generata a partire dal seguente file:

- [DeviceCardViewAdapter.java](#)

6.7 Riferimenti per la classe it.unibo.torsello.bluetoothpositioning.fragment.devicesObservers.DeviceChartFragment

Diagramma delle classi per it.unibo.torsello.bluetoothpositioning.fragment.devicesObservers.DeviceChartFragment



6.7.2 Documentazione delle funzioni membro

6.7.2.1 newInstance()

```

static DeviceChartFragment it.unibo.torsello.bluetoothpositioning.fragment.devicesObservers.↵
DeviceChartFragment.newInstance (
    String message,
    String deviceName,
    ArrayList< String > strings ) [static]

44
45     DeviceChartFragment fragment = new DeviceChartFragment();
46     Bundle args = new Bundle();
47     args.putString(EXTRA_MESSAGE, message);
48     args.putString(DEVICE_NAME, deviceName);
49     args.putStringArrayList(STRINGS, strings);
50     fragment.setArguments(args);
51     return fragment;
52 }
```

6.7.2.2 onCreate()

```

void it.unibo.torsello.bluetoothpositioning.fragment.devicesObservers.DeviceChartFragment.on↵
Create (
    Bundle savedInstanceState )

55
56     super.onCreate(savedInstanceState);
57
58     myDeviceObservable = DeviceObservable.getInstance();
59     myUsbObservable = UsbMeasurementObservable.getInstance();
60
61     idDeviceSelected = getArguments().getString(DEVICE_NAME);
62     stringArrayList = getArguments().getStringArrayList(
63     STRINGS);
64 }
```

6.7.2.3 onCreateView()

```

View it.unibo.torsello.bluetoothpositioning.fragment.devicesObservers.DeviceChartFragment.on↵
CreateView (
    LayoutInflater inflater,
    ViewGroup container,
    Bundle savedInstanceState )

66
67
68     View root = inflater.inflate(R.layout.fragment_device_chart, container, false);
69
70     LineChart lineChart = (LineChart) root.findViewById(R.id.chart);
71
72     // add the charts
73     chartUtil = new ChartUtil(getActivity(), lineChart);
74
75     return root;
76 }
```

6.7.2.4 onPause()

```
void it.unibo.torsello.bluetoothpositioning.fragment.devicesObservers.DeviceChartFragment.onPause() {
```

```
79         {
80             myDeviceObservable.deleteObserver(this);
81             myUsbObservable.deleteObserver(this);
82             super.onPause();
83         }
84     }
```

6.7.2.5 onResume()

```
void it.unibo.torsello.bluetoothpositioning.fragment.devicesObservers.DeviceChartFragment.onResume() {
```

```
86         {
87             super.onResume();
88             myDeviceObservable.addObserver(this);
89             myUsbObservable.addObserver(this);
90         }
91     }
```

6.7.2.6 update()

```
void it.unibo.torsello.bluetoothpositioning.fragment.devicesObservers.DeviceChartFragment.update(
```

```
    Observable o,
    Object arg )
{
    93         {
    94             if (o instanceof UsbMeasurementObservable) {
    95                 if (arg instanceof Double) {
    96                     arduinoValue = (Double) arg;
    97                 }
    98             }
    99         }
    100         if (o instanceof DeviceObservable) {
    101             if (arg instanceof List) {
    102                 List<Device> devices = (List<Device>) arg;
    103                 for (Device deviceSelected : devices) {
    104                     if (deviceSelected.getFriendlyName().equals(idDeviceSelected) ||
    105                         deviceSelected.getAddress().equals(idDeviceSelected)) {
    106                         if (chartUtil != null) {
    107                             chartUtil.createDataSet(
    108                                 stringArrayList);
    109                             ArrayList<Double> doubleArrayList = new ArrayList<>();
    110                             for (String s : stringArrayList) {
    111                                 if (s.equals(getString(R.string.chart_arduino))) {
    112                                     doubleArrayList.add(arduinoValue);
    113                                 }
    114                                 if (s.equals(getString(R.string.chart_raw_distance))) {
    115                                     doubleArrayList.add(deviceSelected.getRawDistance());
    116                                 }
    117                                 if (s.equals(getString(R.string.chart_altbeacon))) {
    118                                     doubleArrayList.add(deviceSelected.getAltBeaconDistance());
    119                                 }
    120                                 if (s.equals(getString(R.string.chart_kalman_filter))) {
    121                                     doubleArrayList.add(deviceSelected.getKalmanFilterDistance());
    122                                 }
    123                             }
    124                             chartUtil.updateDataSet(doubleArrayList);
    125                         }
    126                     }
    127                 }
    128             }
    129         }
    130     }
    131 }
    132 }
    133 }
    134 }
    135 }
    136 }
    137 }
    138 }
    139 }
    140 }
```

6.7.3 Documentazione dei membri dato

6.7.3.1 arduinoValue

```
Double it.unibo.torsello.bluetoothpositioning.fragment.devicesObservers.DeviceChartFragment.↔  
arduinoValue = 0D [private]
```

6.7.3.2 chartUtil

```
ChartUtil it.unibo.torsello.bluetoothpositioning.fragment.devicesObservers.DeviceChartFragment.↔  
chartUtil [private]
```

6.7.3.3 DEVICE_NAME

```
final String it.unibo.torsello.bluetoothpositioning.fragment.devicesObservers.DeviceChart↔  
Fragment.DEVICE_NAME = "DEVICE_NAME" [static]
```

6.7.3.4 EXTRA_MESSAGE

```
final String it.unibo.torsello.bluetoothpositioning.fragment.devicesObservers.DeviceChart↔  
Fragment.EXTRA_MESSAGE = "EXTRA_MESSAGE" [static]
```

6.7.3.5 idDeviceSelected

```
String it.unibo.torsello.bluetoothpositioning.fragment.devicesObservers.DeviceChartFragment.↔  
idDeviceSelected [private]
```

6.7.3.6 myDeviceObservable

```
DeviceObservable it.unibo.torsello.bluetoothpositioning.fragment.devicesObservers.Device↔  
ChartFragment.myDeviceObservable [private]
```

6.7.3.7 myUsbObservable

```
UsbMeasurementObservable it.unibo.torsello.bluetoothpositioning.fragment.devicesObservers.↔  
DeviceChartFragment.myUsbObservable [private]
```

6.7.3.8 stringArrayList

```
ArrayList<String> it.unibo.torsello.bluetoothpositioning.fragment.devicesObservers.Device↔  
ChartFragment.stringArrayList [private]
```

6.7.3.9 STRINGS

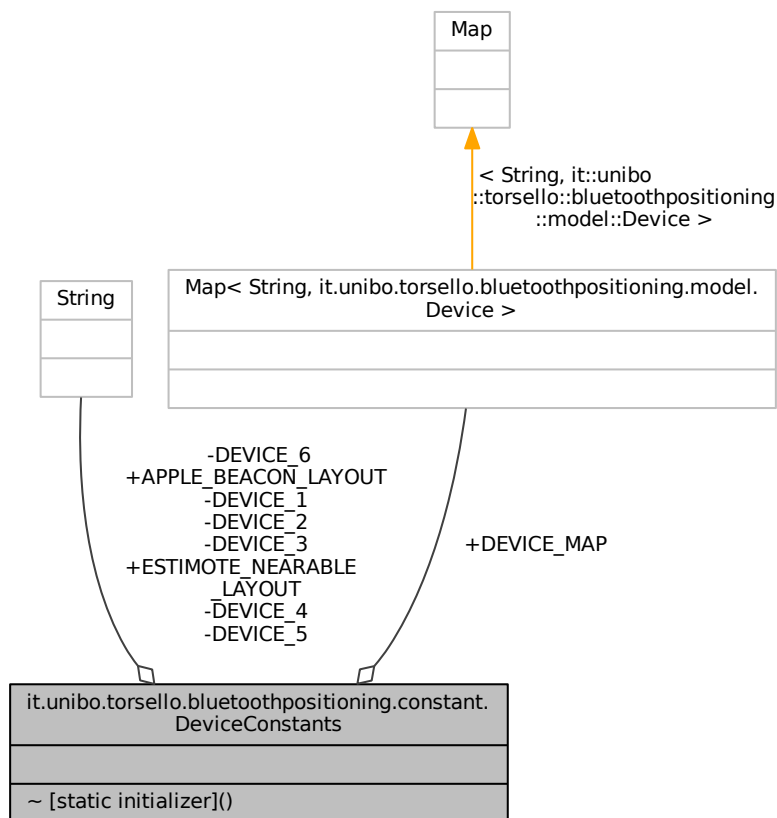
```
final String it.unibo.torsello.bluetoothpositioning.fragment.devicesObservers.DeviceChart↔  
Fragment.STRINGS = "STRINGS" [static]
```

La documentazione per questa classe è stata generata a partire dal seguente file:

- [DeviceChartFragment.java](#)

6.8 Riferimenti per la classe `it.unibo.torsello.bluetoothpositioning.constant.DeviceConstants`

Diagramma di collaborazione per `it.unibo.torsello.bluetoothpositioning.constant.DeviceConstants`:



Attributi pubblici statici

- static final String `APPLE_BEACON_LAYOUT` = "m:2-3=0215,i:4-19,i:20-21,i:22-23,p:24-24"
- static final String `ESTIMOTE_NEARABLE_LAYOUT`
- static final Map< String, Device > `DEVICE_MAP`

Funzioni statiche con visibilità di package

- `[static initializer]`

Attributi privati statici

- static final String `DEVICE_1` = "C1:9B:B0:B9:01:9E"
- static final String `DEVICE_2` = "D1:BE:E2:E9:67:A6"
- static final String `DEVICE_3` = "FA:6B:72:1E:EB:46"
- static final String `DEVICE_4` = "D9:80:00:B7:16:78"
- static final String `DEVICE_5` = "DB:F6:F5:0C:23:BF"
- static final String `DEVICE_6` = "E7:E4:0E:F6:79:3F"

6.8.1 Descrizione dettagliata

Created by Federico Torsello. federico.torsello@studio.unibo.it

6.8.2 Documentazione delle funzioni membro

6.8.2.1 `[static initializer]()`

```
it.unibo.torsello.bluetoothpositioning.constant.DeviceConstants.[static initializer] ( ) [static],  
[package]
```

6.8.3 Documentazione dei membri dato

6.8.3.1 `APPLE_BEACON_LAYOUT`

```
final String it.unibo.torsello.bluetoothpositioning.constant.DeviceConstants.APPLE_BEACON_LAYOUT = "m:2-3=0215,i:4-19,i:20-21,i:22-23,p:24-24" [static]
```

6.8.3.2 `DEVICE_1`

```
final String it.unibo.torsello.bluetoothpositioning.constant.DeviceConstants.DEVICE_1 = "C1:9B:B0:B9:01:9E" [static], [private]
```

6.8.3.3 `DEVICE_2`

```
final String it.unibo.torsello.bluetoothpositioning.constant.DeviceConstants.DEVICE_2 = "D1:BE:E2:E9:67:A6" [static], [private]
```

6.8.3.4 `DEVICE_3`

```
final String it.unibo.torsello.bluetoothpositioning.constant.DeviceConstants.DEVICE_3 = "FA:6B:72:1E:EB:46" [static], [private]
```

6.8.3.5 `DEVICE_4`

```
final String it.unibo.torsello.bluetoothpositioning.constant.DeviceConstants.DEVICE_4 = "D9:80:00:B7:16:78" [static], [private]
```

6.8.3.6 `DEVICE_5`

```
final String it.unibo.torsello.bluetoothpositioning.constant.DeviceConstants.DEVICE_5 = "DB:F6:F5:0C:23:BF" [static], [private]
```

6.8.3.7 `DEVICE_6`

```
final String it.unibo.torsello.bluetoothpositioning.constant.DeviceConstants.DEVICE_6 = "E7:E4:0E:F6:79:3F" [static], [private]
```

6.8.3.8 DEVICE_MAP

```
final Map<String, Device> it.unibo.torsello.bluetoothpositioning.constant.DeviceConstants.DEVICE_MAP [static]
```

6.8.3.9 ESTIMATE_NEARABLE_LAYOUT

```
final String it.unibo.torsello.bluetoothpositioning.constant.DeviceConstants.ESTIMATE_NEARABLE_LAYOUT [static]
```

Valore iniziale:

```
= "m:1-2=0101,i:3-10,d:11-11,d:12-12," +  
   "d:13-14,d:15-15,d:16-16,d:17-17,d:18-18,d:19-19,d:20-20, p:21-21"
```

La documentazione per questa classe è stata generata a partire dal seguente file:

- [DeviceConstants.java](#)

6.9 Riferimenti per la classe it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailFragment

Diagramma delle classi per it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailFragment

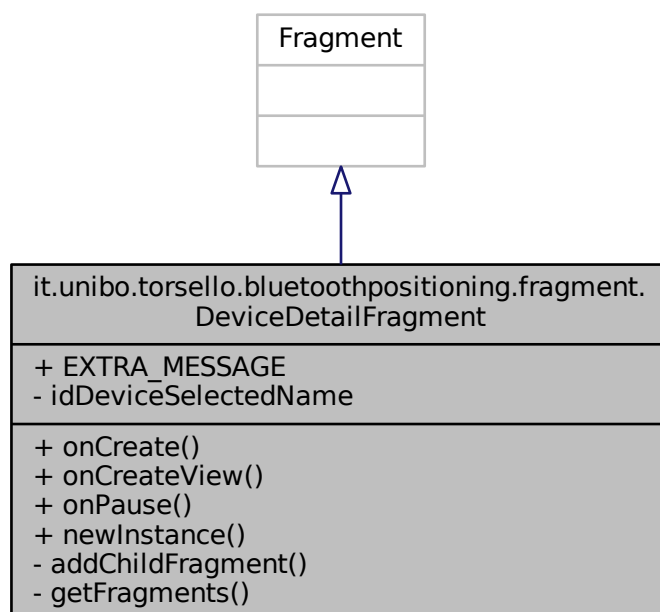
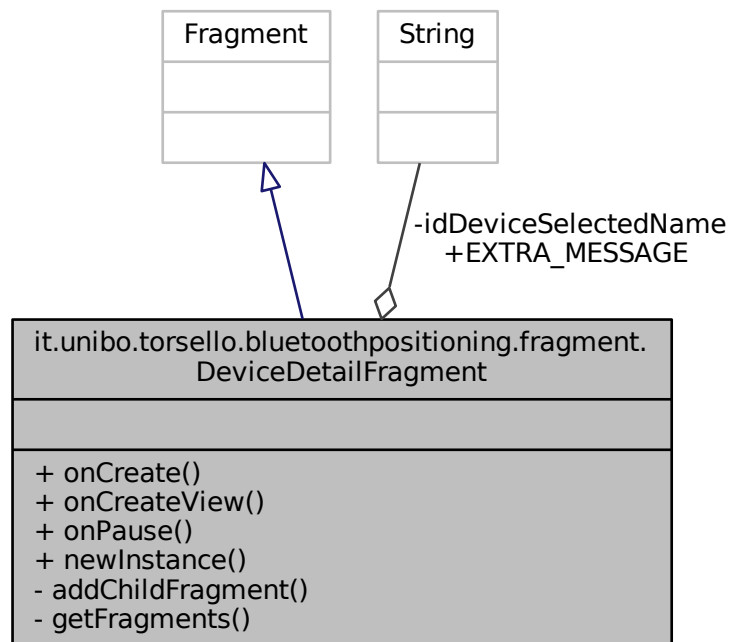


Diagramma di collaborazione per `it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailFragment`:



Membri pubblici

- void `onCreate` (Bundle savedInstanceState)
- View `onCreateView` (LayoutInflater inflater, ViewGroup container, Bundle savedInstanceState)
- void `onPause` ()

Membri pubblici statici

- static `DeviceDetailFragment newInstance` (String message)

Attributi pubblici statici

- static final String `EXTRA_MESSAGE` = "EXTRA_MESSAGE"

Membri privati

- void `addChildFragment` (View root)
- ArrayList< Fragment > `getFragments` ()

Attributi privati

- String `idDeviceSelectedName`

6.9.1 Descrizione dettagliata

Created by Federico Torsello. federico.torsello@studio.unibo.it

6.9.2 Documentazione delle funzioni membro

6.9.2.1 addChildFragmentManager()

```
void it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailFragment.addChildFragmentManager (
    View root ) [private]
```

```
62                                     {
63
64         ViewPager mViewPager = (ViewPager) root.findViewById(R.id.view_pager);
65         StatePagerAdapter myPagerAdapter = new StatePagerAdapter(getChildFragmentManager(),
66         getFragments());
67         mViewPager.setAdapter(myPagerAdapter);
68
69         TabLayout tabLayout = (TabLayout) root.findViewById(R.id.sliding_tabs);
70         tabLayout.setupWithViewPager(mViewPager);
71     }
```

6.9.2.2 getFragments()

```
ArrayList<Fragment> it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailFragment.getFragments ( ) [private]
```

```
72                                     {
73         ArrayList<Fragment> fragments = new ArrayList<>();
74         // fragment 0
75         fragments.add(DeviceDetailInner1Fragment.newInstance(
76         idDeviceSelectedName));
77
78         // fragment 1
79         fragments.add(DeviceDetailInner2Fragment.newInstance("Details",
80         idDeviceSelectedName));
81         return fragments;
82     }
```

6.9.2.3 newInstance()

```
static DeviceDetailFragment it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailFragment.newInstance (
    String message ) [static]
```

```
28
29         DeviceDetailFragment fragment = new DeviceDetailFragment();
30         Bundle args = new Bundle();
31         args.putString(EXTRA_MESSAGE, message);
32         fragment.setArguments(args);
33         return fragment;
34     }
```

6.9.2.4 onCreate()

```
void it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailFragment.onCreate (
    Bundle savedInstanceState )
```

```
37                                     {
38     super.onCreate(savedInstanceState);
39
40     idDeviceSelectedName = getArguments().getString(
41         EXTRA_MESSAGE);
42 }
```

6.9.2.5 onCreateView()

```
View it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailFragment.onCreateView (
    LayoutInflater inflater,
    ViewGroup container,
    Bundle savedInstanceState )
```

```
44                                     {
45     View root = inflater.inflate(R.layout.fragment_device_detail, container, false);
46
47     getActivity().findViewById(R.id.toolbar).setVisibility(View.GONE);
48
49     ((CollapsingToolbarLayout) root.findViewById(R.id.collapsing_toolbar)).setTitle(
50         idDeviceSelectedName);
51
52     addChildFragment(root);
53
54     return root;
55 }
```

6.9.2.6 onPause()

```
void it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailFragment.onPause ( )
```

```
57                                     {
58     getActivity().findViewById(R.id.toolbar).setVisibility(View.VISIBLE);
59     super.onPause();
60 }
```

6.9.3 Documentazione dei membri dato

6.9.3.1 EXTRA_MESSAGE

```
final String it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailFragment.EXTRA_MESSAGE = "EXTRA_MESSAGE" [static]
```

6.9.3.2 idDeviceSelectedName

```
String it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailFragment.idDeviceSelectedName [private]
```

La documentazione per questa classe è stata generata a partire dal seguente file:

- [DeviceDetailFragment.java](#)

Membri pubblici

- void [onCreate](#) (@Nullable Bundle savedInstanceState)
- View [onCreateView](#) (LayoutInflater inflater, ViewGroup container, Bundle savedInstanceState)
- void [onPause](#) ()
- void [onResume](#) ()
- void [update](#) (Observable o, Object arg)

Membri pubblici statici

- static [DeviceDetailInner1Fragment newInstance](#) (String message)

Attributi pubblici statici

- static final String [EXTRA_MESSAGE](#) = "EXTRA_MESSAGE"

Membri privati

- void [initializeDeviceDetail](#) (View root)

Attributi privati

- [DeviceCardViewAdapter](#) [deviceViewAdapter](#)
- List< [Device](#) > [deviceList](#)
- [DeviceObservable](#) [myObservable](#)
- String [idDeviceSelectedName](#)

6.10.1 Descrizione dettagliata

Created by Federico Torsello. federico.torsello@studio.unibo.it

6.10.2 Documentazione delle funzioni membro**6.10.2.1 initializeDeviceDetail()**

```
void it.unibo.torsello.bluetoothpositioning.fragment.devicesObservers.DeviceDetailInner1←
Fragment.initializeDeviceDetail (
    View root ) [private]

77                                     {
78     // add RecyclerView
79     RecyclerView recyclerView = (RecyclerView) root.findViewById(R.id.recycler_view);
80     recyclerView.setLayoutManager(new LinearLayoutManager(getContext()));
81     recyclerView.setAdapter(deviceViewAdapter);
82 }
```

6.10.2.2 newInstance()

```
static DeviceDetailInner1Fragment it.unibo.torsello.bluetoothpositioning.fragment.devicesObservers.DeviceDetailInner1Fragment.newInstance (
    String message ) [static]
```

```
36
37         DeviceDetailInner1Fragment fragment = new DeviceDetailInner1Fragment();
38         Bundle args = new Bundle();
39         args.putString(EXTRA_MESSAGE, message);
40         fragment.setArguments(args);
41         return fragment;
42     }
```

6.10.2.3 onCreate()

```
void it.unibo.torsello.bluetoothpositioning.fragment.devicesObservers.DeviceDetailInner1Fragment.onCreate (
    @Nullable Bundle savedInstanceState )
```

```
45
46         super.onCreate(savedInstanceState);
47
48         myObservable = DeviceObservable.getInstance();
49
50         idDeviceSelectedName = getArguments().getString(
51             EXTRA_MESSAGE);
52         deviceList = new ArrayList<>();
53         deviceViewAdapter = new DeviceCardViewAdapter(getActivity(),
54             deviceList);
```

6.10.2.4 onCreateView()

```
View it.unibo.torsello.bluetoothpositioning.fragment.devicesObservers.DeviceDetailInner1Fragment.onCreateView (
    LayoutInflater inflater,
    ViewGroup container,
    Bundle savedInstanceState )
```

```
57
58         View root = inflater.inflate(R.layout.fragment_device_detail_inner_1, container, false);
59
60         initializeDeviceDetail(root);
61
62         return root;
63     }
```

6.10.2.5 onPause()

```
void it.unibo.torsello.bluetoothpositioning.fragment.devicesObservers.DeviceDetailInner1Fragment.onPause ( )
```

```
66
67         myObservable.deleteObserver(this);
68         super.onPause();
69     }
```

6.10.2.6 onResume()

```
void it.unibo.torsello.bluetoothpositioning.fragment.devicesObservers.DeviceDetailInner1Fragment.onResume ( )
```

```
72         {
73             super.onResume();
74             myObservable.addObserver(this);
75         }
```

6.10.2.7 update()

```
void it.unibo.torsello.bluetoothpositioning.fragment.devicesObservers.DeviceDetailInner1Fragment.update (
    Observable o,
    Object arg )
```

```
85         {
86
87             if (arg instanceof List) {
88
89                 if (!deviceList.isEmpty()) {
90                     deviceList.clear();
91                 }
92
93                 List<Device> devices = (List<Device>) arg;
94
95                 for (Device deviceSelected : devices) {
96                     if (deviceSelected.getFriendlyName().equals(idDeviceSelectedName) ||
97                         deviceSelected.getAddress().equals(idDeviceSelectedName)) {
98                         deviceList.add(deviceSelected);
99                     }
100                 }
101
102                 deviceViewAdapter.notifyDataSetChanged();
103             }
104         }
```

6.10.3 Documentazione dei membri dato

6.10.3.1 deviceList

```
List<Device> it.unibo.torsello.bluetoothpositioning.fragment.devicesObservers.DeviceDetailInner1Fragment.deviceList [private]
```

6.10.3.2 deviceViewAdapter

```
DeviceCardViewAdapter it.unibo.torsello.bluetoothpositioning.fragment.devicesObservers.DeviceDetailInner1Fragment.deviceViewAdapter [private]
```

6.10.3.3 EXTRA_MESSAGE

```
final String it.unibo.torsello.bluetoothpositioning.fragment.devicesObservers.DeviceDetailInner1Fragment.EXTRA_MESSAGE = "EXTRA_MESSAGE" [static]
```

6.10.3.4 idDeviceSelectedName

```
String it.unibo.torsello.bluetoothpositioning.fragment.devicesObservers.DeviceDetailInner1Fragment.idDeviceSelectedName [private]
```

6.10.3.5 myObservable

```
DeviceObservable it.unibo.torsello.bluetoothpositioning.fragment.devicesObservers.Device↔  
DetailInner1Fragment.myObservable [private]
```

La documentazione per questa classe è stata generata a partire dal seguente file:

- [DeviceDetailInner1Fragment.java](#)

6.11 Riferimenti per la classe it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInner2Fragment

Diagramma delle classi per it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInner2Fragment

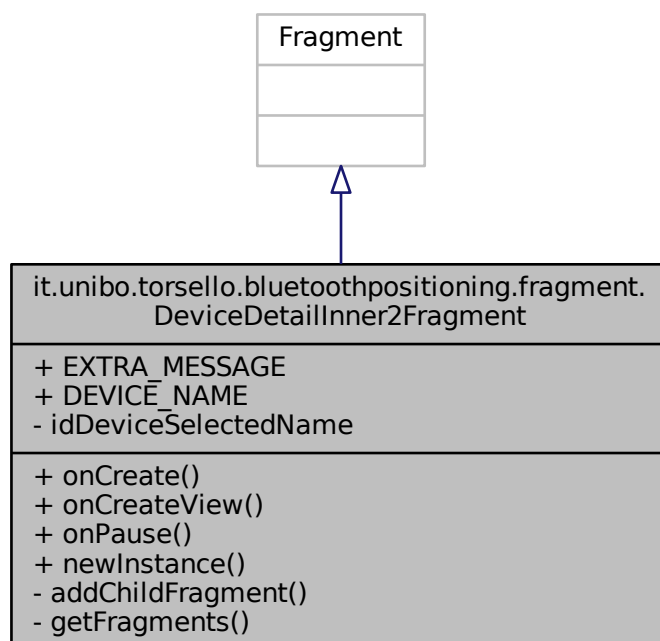
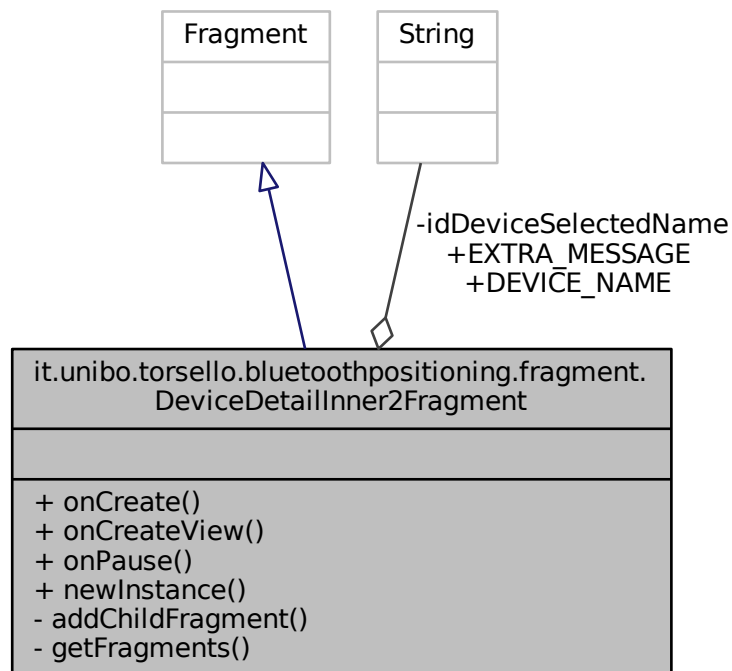


Diagramma di collaborazione per it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInner2Fragment:



Membri pubblici

- void [onCreate](#) (Bundle savedInstanceState)
- View [onCreateView](#) (LayoutInflater inflater, ViewGroup container, Bundle savedInstanceState)
- void [onPause](#) ()

Membri pubblici statici

- static [DeviceDetailInner2Fragment newInstance](#) (String message, String deviceName)

Attributi pubblici statici

- static final String [EXTRA_MESSAGE](#) = "EXTRA_MESSAGE"
- static final String [DEVICE_NAME](#) = "DEVICE_NAME"

Membri privati

- void [addChildFragment](#) (View root)
- ArrayList< Fragment > [getFragments](#) ()

Attributi privati

- String `idDeviceSelectedName`

6.11.1 Descrizione dettagliata

Created by Federico Torsello. federico.torsello@studio.unibo.it

6.11.2 Documentazione delle funzioni membro

6.11.2.1 addChildFragmentManager()

```
void it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInner2Fragment.addChild↳
FragmentManager (
    View root ) [private]

58
59
60     ViewPager mViewPager = (ViewPager) root.findViewById(R.id.view_pager);
61     StatePagerAdapter myPagerAdapter = new StatePagerAdapter(getChildFragmentManager(),
    getFragments());
62     mViewPager.setAdapter(myPagerAdapter);
63
64     TabLayout tabLayout = (TabLayout) root.findViewById(R.id.sliding_tabs);
65     tabLayout.setupWithViewPager(mViewPager);
66 }
```

6.11.2.2 getFragments()

```
ArrayList<Fragment> it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInner2Fragment.↳
getFragments ( ) [private]

68
69     ArrayList<Fragment> fragments = new ArrayList<>();
70
71     // inner fragment 0
72     ArrayList<String> params1 = new ArrayList<>();
73     params1.add(getString(R.string.chart_arduino));
74     params1.add(getString(R.string.chart_raw_distance));
75     params1.add(getString(R.string.chart_altbeacon));
76     params1.add(getString(R.string.chart_kalman_filter));
77
78     fragments.add(DeviceChartFragment.newInstance("chart1",
    idDeviceSelectedName, params1));
79
80     // inner fragment 1
81     ArrayList<String> params2 = new ArrayList<>();
82     params2.add(getString(R.string.chart_arduino));
83     params2.add(getString(R.string.chart_raw_distance));
84     params2.add(getString(R.string.chart_kalman_filter));
85
86     fragments.add(DeviceChartFragment.newInstance("chart2",
    idDeviceSelectedName, params2));
87
88     // inner fragment 2
89     ArrayList<String> params3 = new ArrayList<>();
90     params3.add(getString(R.string.chart_arduino));
91     params3.add(getString(R.string.chart_altbeacon));
92     params3.add(getString(R.string.chart_kalman_filter));
93
94     fragments.add(DeviceChartFragment.newInstance("chart3",
    idDeviceSelectedName, params3));
95
96     return fragments;
97 }
```

6.11.2.3 newInstance()

```

static DeviceDetailInner2Fragment it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInner2Fragment.newInstance (
    String message,
    String deviceName ) [static]

28
29         DeviceDetailInner2Fragment fragment = new DeviceDetailInner2Fragment();
30         Bundle args = new Bundle();
31         args.putString(EXTRA_MESSAGE, message);
32         args.putString(DEVICE_NAME, deviceName);
33         fragment.setArguments(args);
34         return fragment;
35     }

```

6.11.2.4 onCreate()

```

void it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInner2Fragment.onCreate (
    Bundle savedInstanceState )

38
39         super.onCreate(savedInstanceState);
40
41         idDeviceSelectedName = getArguments().getString(
42             DEVICE_NAME);

```

6.11.2.5 onCreateView()

```

View it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInner2Fragment.onCreateView (
    LayoutInflater inflater,
    ViewGroup container,
    Bundle savedInstanceState )

45
46         View root = inflater.inflate(R.layout.fragment_device_detail_inner_2, container, false);
47
48         addChildFragment(root);
49
50         return root;
51     }

```

6.11.2.6 onPause()

```

void it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInner2Fragment.onPause ( )

54
55         super.onPause();
56     }

```

6.11.3 Documentazione dei membri dato

6.11.3.1 DEVICE_NAME

```

final String it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInner2Fragment.DEVICE_NAME = "DEVICE_NAME" [static]

```

6.11.3.2 EXTRA_MESSAGE

```
final String it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInner2Fragment.EXTRA_MESSAGE = "EXTRA_MESSAGE" [static]
```

6.11.3.3 idDeviceSelectedName

```
String it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInner2Fragment.idDeviceSelectedName [private]
```

La documentazione per questa classe è stata generata a partire dal seguente file:

- [DeviceDetailInner2Fragment.java](#)

6.12 Riferimenti per la classe it.unibo.torsello.bluetoothpositioning.fragment.devicesObservers.DeviceListFragment

Diagramma delle classi per it.unibo.torsello.bluetoothpositioning.fragment.devicesObservers.DeviceListFragment

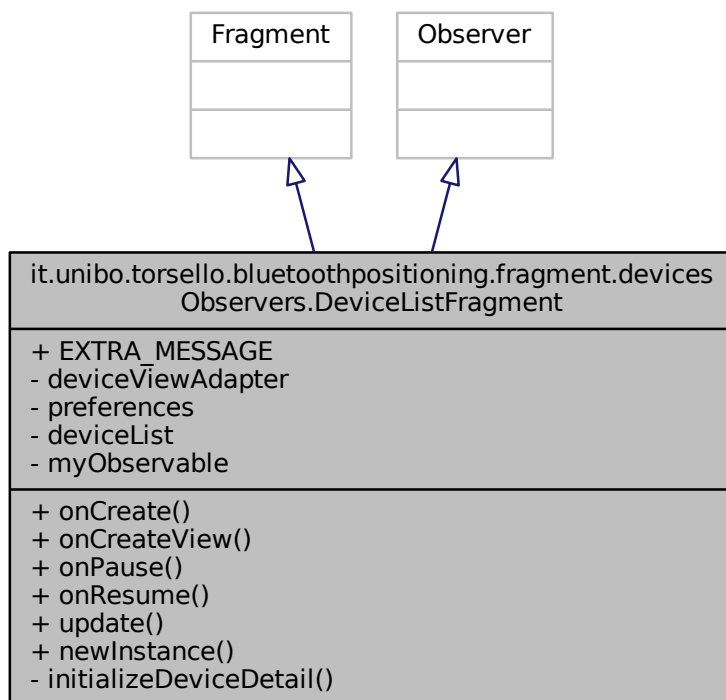
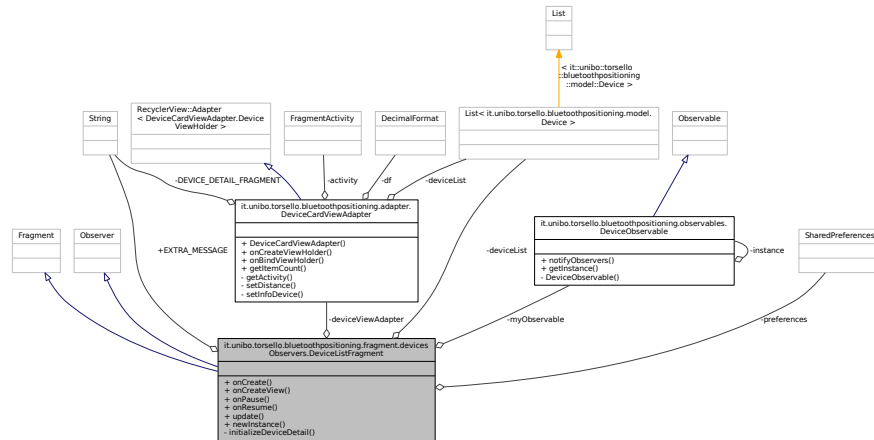


Diagramma di collaborazione per `it.unibo.torsello.bluetoothpositioning.fragment.devicesObservers.DeviceList`←
Fragment:



Membri pubblici

- void **onCreate** (@Nullable Bundle savedInstanceState)
- View **onCreateView** (LayoutInflater inflater, ViewGroup container, Bundle savedInstanceState)
- void **onPause** ()
- void **onResume** ()
- void **update** (Observable o, Object arg)

Membri pubblici statici

- static DeviceListFragment newInstance ()

Attributi pubblici statici

- static final String EXTRA_MESSAGE = "EXTRA_MESSAGE"

Membri privati

- void **initializeDeviceDetail** (View root)

Attributi privati

- DeviceCardViewAdapter deviceViewAdapter
- SharedPreferences preferences
- List< Device > deviceList
- DeviceObservable myObservable

6.12.1 Descrizione dettagliata

Created by Federico Torsello. federico.torsello@studio.unibo.it

6.12.2 Documentazione delle funzioni membro

6.12.2.1 initializeDeviceDetail()

```
void it.unibo.torsello.bluetoothpositioning.fragment.devicesObservers.DeviceListFragment.↵
initializeDeviceDetail (
    View root ) [private]

84                                     {
85     // add RecyclerView
86     RecyclerView recyclerView = (RecyclerView) root.findViewById(R.id.recycler_view);
87     recyclerView.setLayoutManager(new LinearLayoutManager(getContext()));
88     deviceViewAdapter = new DeviceCardViewAdapter(getActivity(),
deviceList);
89     recyclerView.setAdapter(deviceViewAdapter);
90 }
```

6.12.2.2 newInstance()

```
static DeviceListFragment it.unibo.torsello.bluetoothpositioning.fragment.devicesObservers.↵
DeviceListFragment.newInstance ( ) [static]

56                                     {
57     DeviceListFragment fragment = new DeviceListFragment();
58     Bundle args = new Bundle();
59     args.putString(EXTRA_MESSAGE, "Scan Device");
60     fragment.setArguments(args);
61     return fragment;
62 }
```

6.12.2.3 onCreate()

```
void it.unibo.torsello.bluetoothpositioning.fragment.devicesObservers.DeviceListFragment.on↵
Create (
    @Nullable Bundle savedInstanceState )

65                                     {
66     super.onCreate(savedInstanceState);
67
68     myObservable = DeviceObservable.getInstance();
69
70     deviceList = new ArrayList<>();
71     preferences = getActivity().getSharedPreferences(SettingConstants.SETTINGS_PREFERENCES,
0);
72 }
```

6.12.2.4 onCreateView()

```
View it.unibo.torsello.bluetoothpositioning.fragment.devicesObservers.DeviceListFragment.on↵
CreateView (
    LayoutInflater inflater,
    ViewGroup container,
    Bundle savedInstanceState )

75                                     {
76
77     View root = inflater.inflate(R.layout.fragment_device_list, container, false);
78
79     initializeDeviceDetail(root);
80
81     return root;
82 }
```

6.12.2.5 onPause()

```
void it.unibo.torsello.bluetoothpositioning.fragment.devicesObservers.DeviceListFragment.onPause() {
```

```
93         {
94             myObservable.deleteObserver(this);
95             super.onPause();
96         }
}
```

6.12.2.6 onResume()

```
void it.unibo.torsello.bluetoothpositioning.fragment.devicesObservers.DeviceListFragment.onResume() {
```

```
99         {
100             super.onResume();
101             myObservable.addObserver(this);
102         }
}
```

6.12.2.7 update()

```
void it.unibo.torsello.bluetoothpositioning.fragment.devicesObservers.DeviceListFragment.update(
```

```
    Observable o,
    Object arg )
{
105
106
107     if (arg instanceof List) {
108
109         if (!deviceList.isEmpty()) {
110             deviceList.clear();
111         }
112
113         List<Device> devices = (List<Device>) arg;
114
115         // optional sorting
116         Collections.sort(devices, new Comparator<Device>() {
117             public int compare(Device b1, Device b2) {
118                 int sorting = preferences.getInt(SettingConstants.DISTANCE_SORTING, 0);
119                 switch (sorting) {
120                     case 0:
121                         return Double.compare(b1.getIndex(), b2.getIndex());
122                     case R.id.radioButton_color_sorting:
123                         return Double.compare(b1.getColor(), b2.getColor());
124                     case R.id.radioButton_distance_sorting:
125                         return Double.compare(b1.getKalmanFilterDistance(), b2.getKalmanFilterDistance());
126                 }
127             } // default sorting (a good basic ordering for the other options)
128             return Double.compare(b1.getIndex(), b2.getIndex());
129         });
130     }
131
132     deviceList.addAll(devices);
133     deviceListAdapter.notifyDataSetChanged();
134 }
135 }
```

6.12.3 Documentazione dei membri dato

6.12.3.1 deviceList

```
List<Device> it.unibo.torsello.bluetoothpositioning.fragment.devicesObservers.DeviceListFragment.deviceList [private]
```

6.12.3.2 deviceViewAdapter

```
DeviceCardViewAdapter it.unibo.torsello.bluetoothpositioning.fragment.devicesObservers.↔
DeviceListFragment.deviceViewAdapter [private]
```

6.12.3.3 EXTRA_MESSAGE

```
final String it.unibo.torsello.bluetoothpositioning.fragment.devicesObservers.DeviceList↔
Fragment.EXTRA_MESSAGE = "EXTRA_MESSAGE" [static]
```

6.12.3.4 myObservable

```
DeviceObservable it.unibo.torsello.bluetoothpositioning.fragment.devicesObservers.DeviceList↔
Fragment.myObservable [private]
```

6.12.3.5 preferences

```
SharedPreferences it.unibo.torsello.bluetoothpositioning.fragment.devicesObservers.Device↔
ListFragment.preferences [private]
```

La documentazione per questa classe è stata generata a partire dal seguente file:

- [DeviceListFragment.java](#)

6.13 Riferimenti per la classe it.unibo.torsello.bluetoothpositioningobservables.DeviceObservable

Diagramma delle classi per it.unibo.torsello.bluetoothpositioningobservables.DeviceObservable

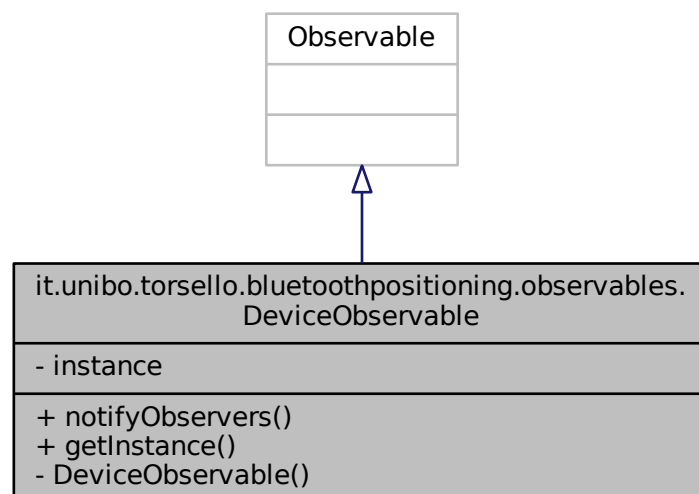
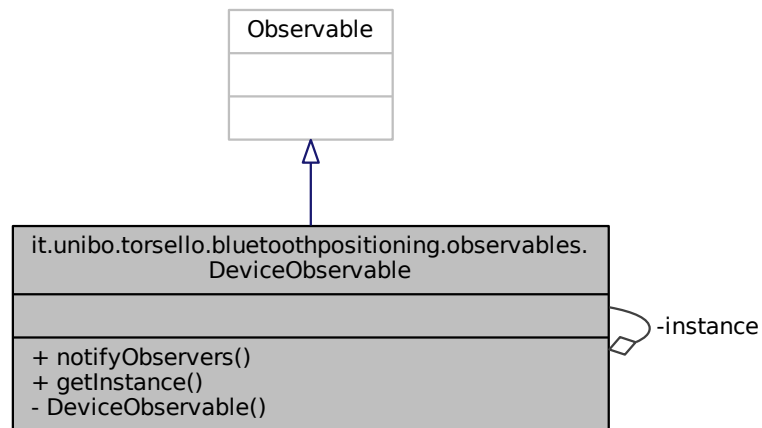


Diagramma di collaborazione per `it.unibo.torsello.bluetoothpositioning.observable.DeviceObservable`:



Membri pubblici

- void `notifyObservers` (Object data)

Membri pubblici statici

- static `DeviceObservable getInstance` ()

Membri privati

- `DeviceObservable` ()

Attributi privati statici

- static `DeviceObservable instance` = new `DeviceObservable`()

6.13.1 Descrizione dettagliata

Created by Federico Torsello. federico.torsello@studio.unibo.it

6.13.2 Documentazione dei costruttori e dei distruttori

6.13.2.1 DeviceObservable()

```
it.unibo.torsello.bluetoothpositioning.observable.DeviceObservable.DeviceObservable ( ) [private]
```

```

17         {
18         super();
19     }
  
```

6.13.3 Documentazione delle funzioni membro

6.13.3.1 getInstance()

```
static DeviceObservable it.unibo.torsello.bluetoothpositioning.observables.DeviceObservable.↵  
getInstance ( ) [static]
```

```
13                                     {  
14         return instance;  
15     }
```

6.13.3.2 notifyObservers()

```
void it.unibo.torsello.bluetoothpositioning.observables.DeviceObservable.notifyObservers (↵  
    Object data )
```

```
22                                     {  
23         setChanged();  
24         super.notifyObservers(data);  
25     }
```

6.13.4 Documentazione dei membri dato

6.13.4.1 instance

```
DeviceObservable it.unibo.torsello.bluetoothpositioning.observables.DeviceObservable.instance  
= new DeviceObservable() [static], [private]
```

La documentazione per questa classe è stata generata a partire dal seguente file:

- [DeviceObservable.java](#)

6.14 Riferimenti per la classe it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.DeviceViewHolder↔

Diagramma delle classi per it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.DeviceView↔
Holder

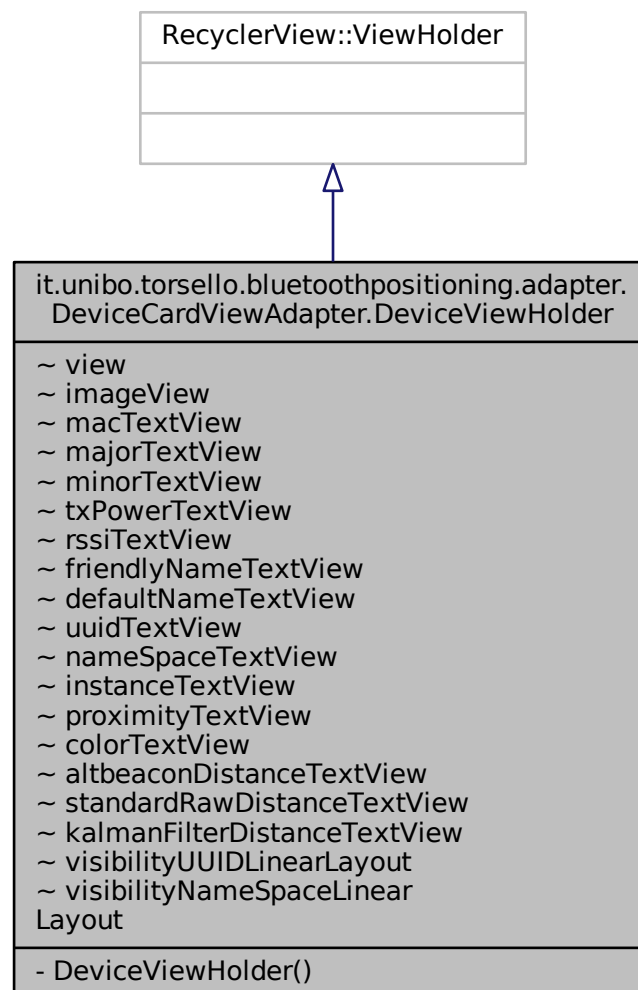
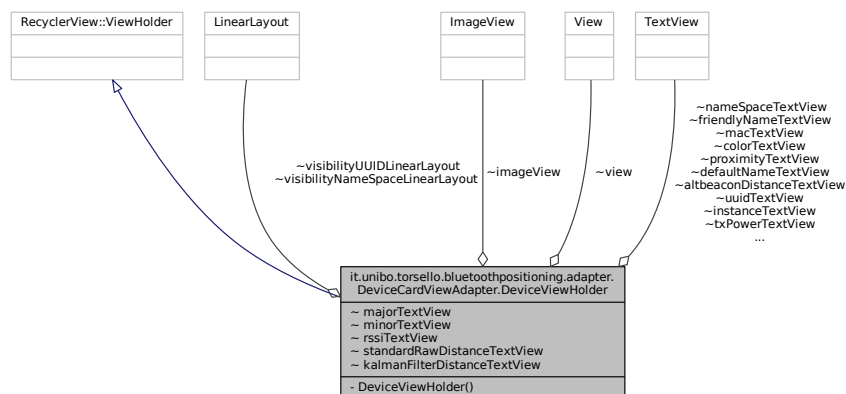


Diagramma di collaborazione per it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.Device↔

ViewHolder:



Attributi con visibilità di package

- View [view](#)
- ImageView [imageView](#)
- TextView [macTextView](#)
- TextView [majorTextView](#)
- TextView [minorTextView](#)
- TextView [txPowerTextView](#)
- TextView [rsiTextView](#)
- TextView [friendlyNameTextView](#)
- TextView [defaultNameTextView](#)
- TextView [uuidTextView](#)
- TextView [nameSpaceTextView](#)
- TextView [instanceTextView](#)
- TextView [proximityTextView](#)
- TextView [colorTextView](#)
- TextView [altbeaconDistanceTextView](#)
- TextView [standardRawDistanceTextView](#)
- TextView [kalmanFilterDistanceTextView](#)
- LinearLayout [visibilityUiThreadLinearLayout](#)
- LinearLayout [visibilityNameSpaceLinearLayout](#)

Membri privati

- [DeviceViewHolder](#) (View [view](#))

6.14.1 Documentazione dei costruttori e dei distruttori

6.14.1.1 DeviceViewHolder()

```

it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.DeviceViewHolder.Device<
ViewHolder (
    View view ) [private]
  
```

```

244                                     {
245
246         super(view);
247         this.view = view;
248         imageView = (ImageView) view.findViewById(R.id.imageBeacon);
249         defaultNameTextView = (TextView) view.findViewById(R.id.
value_default_name);
250         friendlyNameTextView = (TextView) view.findViewById(R.id.
value_friendly_name);
251         macTextView = (TextView) view.findViewById(R.id.value_mac_address);
252         majorTextView = (TextView) view.findViewById(R.id.value_major);
253         minorTextView = (TextView) view.findViewById(R.id.value_minor);
254         txPowerTextView = (TextView) view.findViewById(R.id.value_power);
255         rssiTextView = (TextView) view.findViewById(R.id.value_rssi);
256         uuidTextView = (TextView) view.findViewById(R.id.value_uuid);
257         nameSpaceTextView = (TextView) view.findViewById(R.id.value_name_space);
258         proximityTextView = (TextView) view.findViewById(R.id.value_proximity);
259         instanceTextView = (TextView) view.findViewById(R.id.value_instance);
260         colorTextView = (TextView) view.findViewById(R.id.value_color);
261
262         altbeaconDistanceTextView = (TextView) view.findViewById(R.id.
value_altbeacon_distance);
263         kalmanFilterDistanceTextView = (TextView)
view.findViewById(R.id.value_kalman_filter_distance);
264         standardRawDistanceTextView = (TextView)
view.findViewById(R.id.value_standard_raw_distance);
265
266         visibilityUUIDLinearLayout = (LinearLayout)
view.findViewById(R.id.visibility_uuid_minor_major_nmb);
267         visibilityNameSpaceLinearLayout = (LinearLayout)
view.findViewById(R.id.visibilityNameSpace_Instance);
268     }

```

6.14.2 Documentazione dei membri dato

6.14.2.1 altbeaconDistanceTextView

TextView it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.DeviceViewHolder.altbeaconDistanceTextView [package]

6.14.2.2 colorTextView

TextView it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.DeviceViewHolder.colorTextView [package]

6.14.2.3 defaultNameTextView

TextView it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.DeviceViewHolder.defaultNameTextView [package]

6.14.2.4 friendlyNameTextView

TextView it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.DeviceViewHolder.friendlyNameTextView [package]

6.14.2.5 imageView

ImageView it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.DeviceViewHolder.imageView [package]

6.14.2.6 instanceTextView

TextView it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.DeviceViewHolder.instanceTextView [package]

6.14.2.7 kalmanFilterDistanceTextView

```
TextView it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.DeviceView↔  
Holder.kalmanFilterDistanceTextView [package]
```

6.14.2.8 macTextView

```
TextView it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.DeviceView↔  
Holder.macTextView [package]
```

6.14.2.9 majorTextView

```
TextView it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.DeviceView↔  
Holder.majorTextView [package]
```

6.14.2.10 minorTextView

```
TextView it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.DeviceView↔  
Holder.minorTextView [package]
```

6.14.2.11 nameSpaceTextView

```
TextView it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.DeviceView↔  
Holder.nameSpaceTextView [package]
```

6.14.2.12 proximityTextView

```
TextView it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.DeviceView↔  
Holder.proximityTextView [package]
```

6.14.2.13 rssiTextView

```
TextView it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.DeviceView↔  
Holder.rssiTextView [package]
```

6.14.2.14 standardRawDistanceTextView

```
TextView it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.DeviceView↔  
Holder.standardRawDistanceTextView [package]
```

6.14.2.15 txPowerTextView

```
TextView it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.DeviceView↔  
Holder.txPowerTextView [package]
```

6.14.2.16 uuidTextView

```
TextView it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.DeviceView↔  
Holder.uuidTextView [package]
```

6.14.2.17 view

```
View it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.DeviceViewHolder.↔
view [package]
```

6.14.2.18 visibilityNameSpaceLinearLayout

```
LinearLayout it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.DeviceView↔
Holder.visibilityNameSpaceLinearLayout [package]
```

6.14.2.19 visibilityUUIDLinearLayout

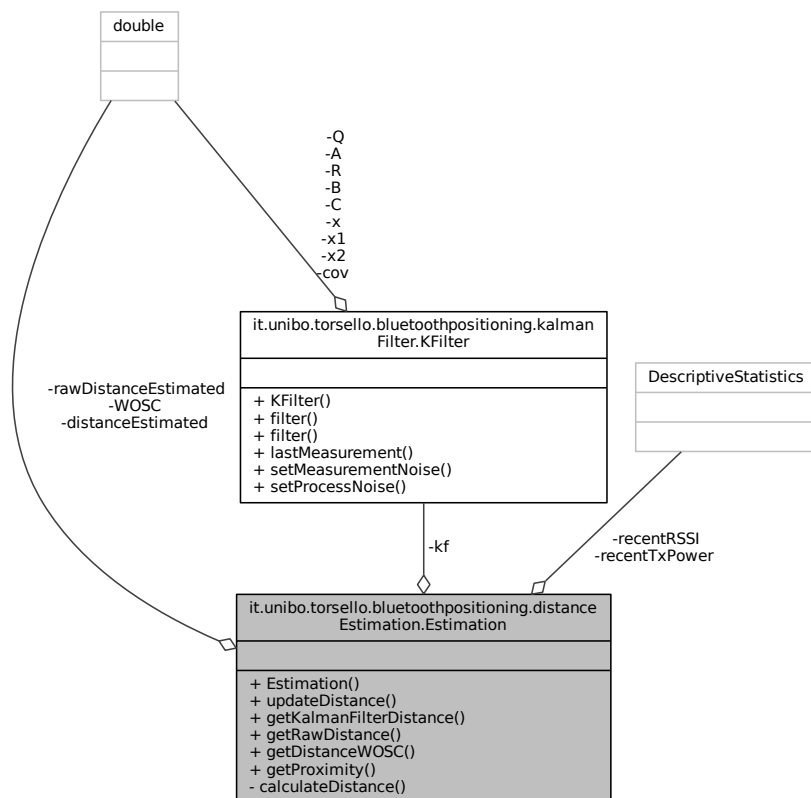
```
LinearLayout it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.DeviceView↔
Holder.visibilityUUIDLinearLayout [package]
```

La documentazione per questa classe è stata generata a partire dal seguente file:

- [DeviceCardViewAdapter.java](#)

6.15 Riferimenti per la classe `it.unibo.torsello.bluetoothpositioning.distanceEstimation.Estimation`

Diagramma di collaborazione per `it.unibo.torsello.bluetoothpositioning.distanceEstimation.Estimation`:



Membri pubblici

- [Estimation](#) ()
- void [updateDistance](#) (Beacon b, double processNoise)
- double [getKalmanFilterDistance](#) ()
- double [getRawDistance](#) ()
- double [getDistanceWOSC](#) ()
- String [getProximity](#) ()

Membri privati

- double [calculateDistance](#) (double txPower, double rssi)

Attributi privati

- DescriptiveStatistics [recentRSSI](#)
- DescriptiveStatistics [recentTxPower](#)
- [KFilter](#) kf
- double [distanceEstimated](#)
- double [rawDistanceEstimated](#)
- double [WOSC](#)

6.15.1 Descrizione dettagliata

Created by Federico Torsello. federico.torsello@studio.unibo.it

6.15.2 Documentazione dei costruttori e dei distruttori

6.15.2.1 Estimation()

```
it.unibo.torsello.bluetoothpositioning.distanceEstimation.Estimation.Estimation ( )
```

```

23         {
24
25         // limit on the number of values that can be stored in the dataset
26         recentRSSI = new DescriptiveStatistics();
27         recentRSSI.setWindowSize(KFilterConstants.WINDOW);
28         recentTxPower = new DescriptiveStatistics();
29         recentTxPower.setWindowSize(KFilterConstants.WINDOW);
30
31         distanceEstimated = 0;
32         rawDistanceEstimated = 0;
33         WOSC = 0;
34
35         kf = new KFilterBuilder()
36             // filter for RSSI
37             .R(KFilterConstants.INITIAL_PROCESS_NOISE) // Initial process noise
38             .Q(KFilterConstants.INITIAL_MEASUREMENT_NOISE) // Initial measurement noise
39             .build();
40     }
```


6.15.3 Documentazione delle funzioni membro

6.15.3.1 `calculateDistance()`

```
double it.unibo.torsello.bluetoothpositioning.distanceEstimation.Estimation.calculateDistance
(
    double txPower,
    double rssi ) [private]

63                                     {
64
65     if (rssi == 0.0D) {
66         return -1.0D; // if we cannot determine accuracy, return -1.
67     }
68
69     double ratio = (rssi * 1.0D) / txPower;
70     if (ratio < 1.0D) {
71         return Math.pow(ratio, 10.0D);
72     }
73
74     // return (0.89976D * Math.pow(ratio, 7.7095D)) + 0.125D;
75     return (0.89976D * Math.pow(ratio, 7.7095D)) + 0.111D;
76
77     /*
78     * RSSI = TxPower - 10 * n * lg(d)
79     * n = 2 (in free space)
80     * d = 10 ^ ((TxPower - RSSI) / (10 * n))
81     */
82     // return Math.pow(10D, (txPower - rssi) / (10 * 2));
83 }
```

6.15.3.2 `getDistanceWOSC()`

```
double it.unibo.torsello.bluetoothpositioning.distanceEstimation.Estimation.getDistanceWOSC (
)

93                                     {
94     return WOSC;
95 }
```

6.15.3.3 `getKalmanFilterDistance()`

```
double it.unibo.torsello.bluetoothpositioning.distanceEstimation.Estimation.getKalmanFilter↵
Distance ( )

85                                     {
86     return distanceEstimated;
87 }
```

6.15.3.4 `getProximity()`

```
String it.unibo.torsello.bluetoothpositioning.distanceEstimation.Estimation.getProximity ( )

97                                     {
98     double proximity = distanceEstimated;
99     String accuracy;
100
101     if (proximity <= 0) {
102         accuracy = "unknown";
103     } else if (proximity <= 0.5) {
104         accuracy = "immediate";
105     } else if (proximity <= 4.0) {
106         accuracy = "near";
107     } else {
108         accuracy = "far";
109     }
110     return accuracy;
111 }
```

6.15.3.5 getRawDistance()

```
double it.unibo.torsello.bluetoothpositioning.distanceEstimation.Estimation.getRawDistance ( )
```

```
89         {
90         return rawDistanceEstimated;
91     }
```

6.15.3.6 updateDistance()

```
void it.unibo.torsello.bluetoothpositioning.distanceEstimation.Estimation.updateDistance (
    Beacon b,
    double processNoise )
```

```
42         {
43
44         recentRSSI.addValue(b.getRssi());
45         recentTxPower.addValue(b.getTxPower());
46
47         // Update measurement noise continually
48         double mNoise = Math.sqrt((100 * 9 / Math.log(10)) *
49             Math.log(1 + Math.pow(recentRSSI.getMean() /
recentRSSI.getStandardDeviation(), 2)));
50
51         if (!Double.isInfinite(mNoise) && !Double.isNaN(mNoise)) {
52             kf.setMeasurementNoise(mNoise);
53         }
54
55         kf.setProcessNoise(processNoise);
56         double lastFilteredReading = kf.filter(recentRSSI.getPercentile(50));
57         distanceEstimated = calculateDistance(
recentTxPower.getPercentile(50), lastFilteredReading);
58         rawDistanceEstimated = calculateDistance(b.getTxPower(), b.
getRssi());
59         WOSC = calculateDistance(b.getTxPower(), lastFilteredReading);
60     }
```

6.15.4 Documentazione dei membri dato

6.15.4.1 distanceEstimated

```
double it.unibo.torsello.bluetoothpositioning.distanceEstimation.Estimation.distanceEstimated
[private]
```

6.15.4.2 kf

```
KFilter it.unibo.torsello.bluetoothpositioning.distanceEstimation.Estimation.kf [private]
```

6.15.4.3 rawDistanceEstimated

```
double it.unibo.torsello.bluetoothpositioning.distanceEstimation.Estimation.rawDistance↔
Estimated [private]
```

6.15.4.4 recentRSSI

```
DescriptiveStatistics it.unibo.torsello.bluetoothpositioning.distanceEstimation.Estimation.↔
recentRSSI [private]
```

6.15.4.5 `recentTxPower`

```
DescriptiveStatistics it.unibo.torsello.bluetoothpositioning.distanceEstimation.Estimation.↔  
recentTxPower [private]
```

6.15.4.6 `WOSC`

```
double it.unibo.torsello.bluetoothpositioning.distanceEstimation.Estimation.WOSC [private]
```

La documentazione per questa classe è stata generata a partire dal seguente file:

- [Estimation.java](#)

6.16 Riferimenti per la classe `it.unibo.torsello.bluetoothpositioning.extra.FABBehavior`

Diagramma delle classi per `it.unibo.torsello.bluetoothpositioning.extra.FABBehavior`

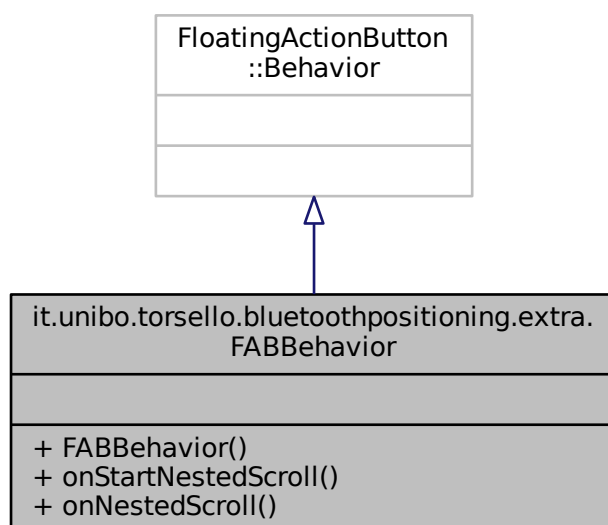
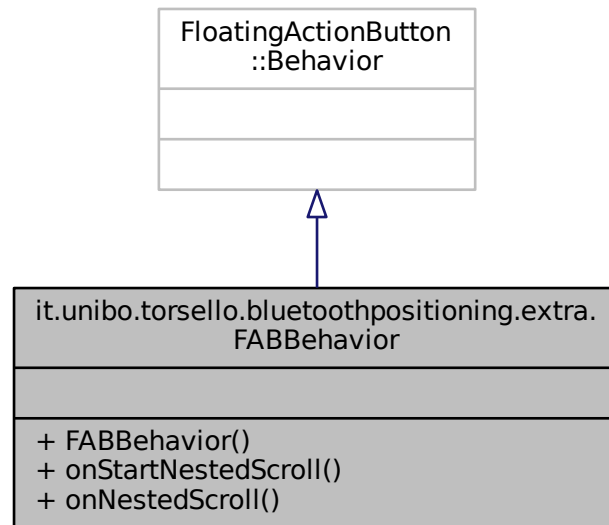


Diagramma di collaborazione per `it.unibo.torsello.bluetoothpositioning.extra.FABBehavior`:



Membri pubblici

- [FABBehavior](#) (Context context, AttributeSet attrs)
- boolean [onStartNestedScroll](#) (CoordinatorLayout coordinatorLayout, final FloatingActionButton child, View directTargetChild, View target, int nestedScrollAxes)
- void [onNestedScroll](#) (CoordinatorLayout coordinatorLayout, final FloatingActionButton child, View target, int dxConsumed, int dyConsumed, int dxUnconsumed, int dyUnconsumed)

6.16.1 Descrizione dettagliata

Created by Federico Torsello. federico.torsello@studio.unibo.it

6.16.2 Documentazione dei costruttori e dei distruttori

6.16.2.1 FABBehavior()

```

it.unibo.torsello.bluetoothpositioning.extra.FABBehavior.FABBehavior (
    Context context,
    AttributeSet attrs )
  
```

```

17                                     {
18         super();
19     }
  
```

6.16.3 Documentazione delle funzioni membro

6.16.3.1 `onNestedScroll()`

```
void it.unibo.torsello.bluetoothpositioning.extra.FABBehavior.onNestedScroll (
    CoordinatorLayout coordinatorLayout,
    final FloatingActionButton child,
    View target,
    int dxConsumed,
    int dyConsumed,
    int dxUnconsumed,
    int dyUnconsumed )

32
33     {
34     super.onNestedScroll(coordinatorLayout, child, target, dxConsumed, dyConsumed, dxUnconsumed,
35                          dyUnconsumed);
36
37     if ((dyConsumed > 0 || dyUnconsumed == 0) && child.getVisibility() == View.VISIBLE) {
38         child.hide();
39         new Handler().postDelayed(new Runnable() {
40             @Override
41             public void run() {
42                 child.show();
43             }
44             }, 1000);
45     }
```

6.16.3.2 `onStartNestedScroll()`

```
boolean it.unibo.torsello.bluetoothpositioning.extra.FABBehavior.onStartNestedScroll (
    CoordinatorLayout coordinatorLayout,
    final FloatingActionButton child,
    View directTargetChild,
    View target,
    int nestedScrollAxes )

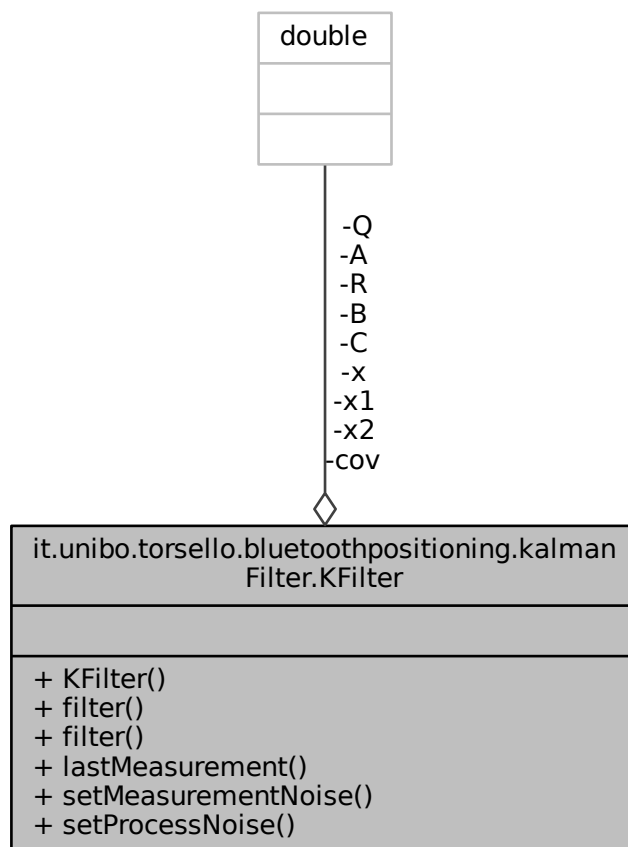
23
24
25     {
26     return nestedScrollAxes == ViewCompat.SCROLL_AXIS_VERTICAL ||
27         super.onStartNestedScroll(coordinatorLayout, child, directTargetChild, target,
28                                   nestedScrollAxes);
29 }
```

La documentazione per questa classe è stata generata a partire dal seguente file:

- [FABBehavior.java](#)

6.17 Riferimenti per la classe `it.unibo.torsello.bluetoothpositioning.kalmanFilter.KFilter`

Diagramma di collaborazione per `it.unibo.torsello.bluetoothpositioning.kalmanFilter.KFilter`:



Membri pubblici

- `KFilter` (`double R`, `double Q`, `double A`, `double B`, `double C`)
- `double filter` (`double z`)
- `double filter` (`double z`, `double u`)
- `double lastMeasurement` ()
- `void setMeasurementNoise` (`double noise`)
- `void setProcessNoise` (`double noise`)

Attributi privati

- `double R`
- `double Q`
- `double A`
- `double B`
- `double C`

- double `cov`
- double `x`
- double `x1`
- double `x2`

6.17.1 Descrizione dettagliata

Created by Federico Torsello. federico.torsello@studio.unibo.it

6.17.2 Documentazione dei costruttori e dei distruttori

6.17.2.1 KFilter()

```
it.unibo.torsello.bluetoothpositioning.kalmanFilter.KFilter.KFilter (
    double R,
    double Q,
    double A,
    double B,
    double C )
```

Create 1-dimensional kalman filter

Parametri

<i>R</i>	Process noise
<i>Q</i>	Measurement noise
<i>A</i>	State vector
<i>B</i>	Control vector
<i>C</i>	Measurement vector

```
28                                     {
29
30         this.R = R;
31         this.Q = Q;
32         this.A = A;
33         this.B = B;
34         this.C = C;
35
36         cov = Double.NaN;
37         x = Double.NaN;
38     }
```

6.17.3 Documentazione delle funzioni membro

6.17.3.1 filter() [1/2]

```
double it.unibo.torsello.bluetoothpositioning.kalmanFilter.KFilter.filter (
    double z )

41                                     {
42         return filter(z, 0);
43     }
```

6.17.3.2 filter() [2/2]

```
double it.unibo.torsello.bluetoothpositioning.kalmanFilter.KFilter.filter (
    double z,
    double u )
```

Filter a new value

Parametri

z	Measurement
u	Control

Restituisce

x

```
52                                     {
53
54     if (Double.isNaN(x)) {
55         x = (1 / C) * z;
56         x1 = x;
57         x2 = x1;
58         cov = (1 / C) * Q * (1 / C);
59     } else {
60
61         // Calculate previous update step
62         B = (x - x1) / 2;
63
64         // Compute prediction
65         double predX = (A * x) + (B * u);
66         double predCov = ((A * cov) * A) + R;
67
68         // Kalman gain
69         double K = predCov * C * (1 / ((C * predCov * C) + Q));
70
71         // Correction
72         x1 = x;
73         x = predX + K * (z - (C * predX));
74         cov = predCov - (K * C * predCov);
75     }
76
77     return x;
78 }
```

6.17.3.3 lastMeasurement()

```
double it.unibo.torsello.bluetoothpositioning.kalmanFilter.KFilter.lastMeasurement ( )
```

Return the last filtered measurement

Restituisce

x Estimated signal without noise

```
85                                     {
86     return x;
87 }
```

6.17.3.4 setMeasurementNoise()

```
void it.unibo.torsello.bluetoothpositioning.kalmanFilter.KFilter.setMeasurementNoise (
    double noise )
```

Set measurement noise INITIAL_MEASUREMENT_NOISE

Parametri

<i>noise</i>	Measurement noise
--------------	-------------------

```
94                                     {
95         Q = noise;
96     }
```

6.17.3.5 setProcessNoise()

```
void it.unibo.torsello.bluetoothpositioning.kalmanFilter.KFilter.setProcessNoise (
    double noise )
```

Set the process noise INITIAL_PROCESS_NOISE

Parametri

<i>noise</i>	Process noise
--------------	---------------

```
103                                     {
104         R = noise;
105     }
```

6.17.4 Documentazione dei membri dato**6.17.4.1 A**

```
double it.unibo.torsello.bluetoothpositioning.kalmanFilter.KFilter.A [private]
```

6.17.4.2 B

```
double it.unibo.torsello.bluetoothpositioning.kalmanFilter.KFilter.B [private]
```

6.17.4.3 C

```
double it.unibo.torsello.bluetoothpositioning.kalmanFilter.KFilter.C [private]
```

6.17.4.4 cov

```
double it.unibo.torsello.bluetoothpositioning.kalmanFilter.KFilter.cov [private]
```

6.17.4.5 Q

```
double it.unibo.torsello.bluetoothpositioning.kalmanFilter.KFilter.Q [private]
```

6.17.4.6 R

```
double it.unibo.torsello.bluetoothpositioning.kalmanFilter.KFilter.R [private]
```

6.17.4.7 x

```
double it.unibo.torsello.bluetoothpositioning.kalmanFilter.KFilter.x [private]
```

6.17.4.8 x1

```
double it.unibo.torsello.bluetoothpositioning.kalmanFilter.KFilter.x1 [private]
```

6.17.4.9 x2

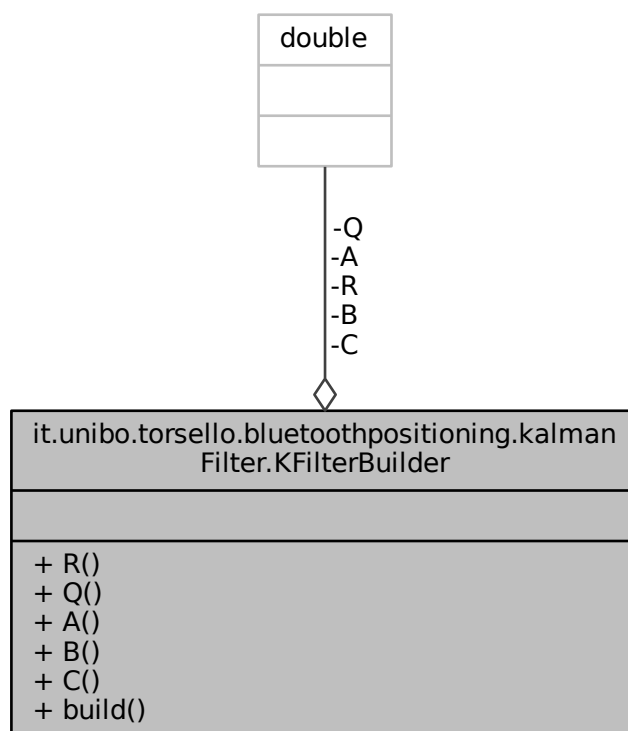
```
double it.unibo.torsello.bluetoothpositioning.kalmanFilter.KFilter.x2 [private]
```

La documentazione per questa classe è stata generata a partire dal seguente file:

- [KFilter.java](#)

6.18 Riferimenti per la classe it.unibo.torsello.bluetoothpositioning.kalmanFilter.KFilterBuilder

Diagramma di collaborazione per it.unibo.torsello.bluetoothpositioning.kalmanFilter.KFilterBuilder:



Membri pubblici

- `KFilterBuilder R` (double R)
- `KFilterBuilder Q` (double Q)
- `KFilterBuilder A` (double A)
- `KFilterBuilder B` (double B)
- `KFilterBuilder C` (double C)
- `KFilter build` ()

Attributi privati

- double `R` = 1
- double `Q` = 1
- double `A` = 1
- double `B` = 0
- double `C` = 1

6.18.1 Descrizione dettagliata

Created by Federico Torsello. federico.torsello@studio.unibo.it

Simple builder class for 1-dimensional Kalman filter with predefined

6.18.2 Documentazione delle funzioni membro

6.18.2.1 `A()`

```
KFilterBuilder it.unibo.torsello.bluetoothpositioning.kalmanFilter.KFilterBuilder.A (  
    double A )
```

```
27                                     {  
28         this.A = A;  
29         return this;  
30     }
```

6.18.2.2 `B()`

```
KFilterBuilder it.unibo.torsello.bluetoothpositioning.kalmanFilter.KFilterBuilder.B (  
    double B )
```

```
32                                     {  
33         this.B = B;  
34         return this;  
35     }
```

6.18.2.3 `build()`

```
KFilter it.unibo.torsello.bluetoothpositioning.kalmanFilter.KFilterBuilder.build ( )
```

```
42                                     {  
43         return new KFilter(R, Q, A, B, C);  
44     }
```

6.18.2.4 C()

```
KFilterBuilder it.unibo.torsello.bluetoothpositioning.kalmanFilter.KFilterBuilder.C (  
    double C )
```

```
37                                     {  
38     this.C = C;  
39     return this;  
40 }
```

6.18.2.5 Q()

```
KFilterBuilder it.unibo.torsello.bluetoothpositioning.kalmanFilter.KFilterBuilder.Q (  
    double Q )
```

```
22                                     {  
23     this.Q = Q;  
24     return this;  
25 }
```

6.18.2.6 R()

```
KFilterBuilder it.unibo.torsello.bluetoothpositioning.kalmanFilter.KFilterBuilder.R (  
    double R )
```

```
17                                     {  
18     this.R = R;  
19     return this;  
20 }
```

6.18.3 Documentazione dei membri dato

6.18.3.1 A

```
double it.unibo.torsello.bluetoothpositioning.kalmanFilter.KFilterBuilder.A = 1 [private]
```

6.18.3.2 B

```
double it.unibo.torsello.bluetoothpositioning.kalmanFilter.KFilterBuilder.B = 0 [private]
```

6.18.3.3 C

```
double it.unibo.torsello.bluetoothpositioning.kalmanFilter.KFilterBuilder.C = 1 [private]
```

6.18.3.4 Q

```
double it.unibo.torsello.bluetoothpositioning.kalmanFilter.KFilterBuilder.Q = 1 [private]
```

6.18.3.5 R

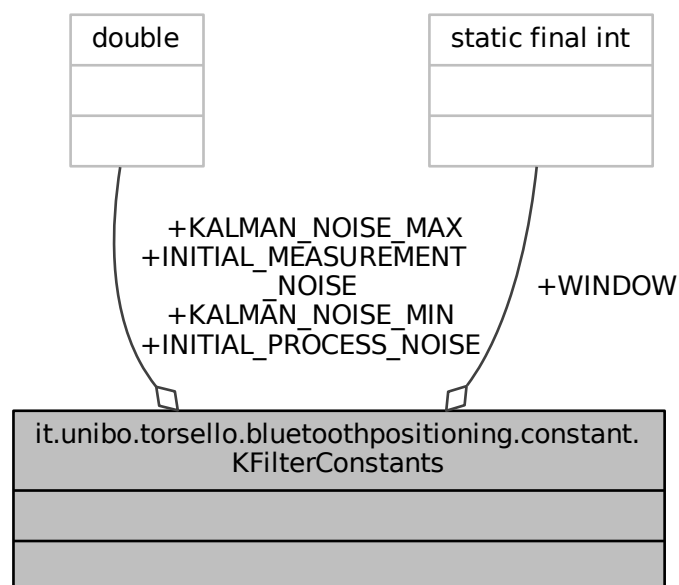
```
double it.unibo.torsello.bluetoothpositioning.kalmanFilter.KFilterBuilder.R = 1 [private]
```

La documentazione per questa classe è stata generata a partire dal seguente file:

- [KFilterBuilder.java](#)

6.19 Riferimenti per la classe `it.unibo.torsello.bluetoothpositioning.constant.KFilterConstants`

Diagramma di collaborazione per `it.unibo.torsello.bluetoothpositioning.constant.KFilterConstants`:



Attributi pubblici statici

- static final double `KALMAN_NOISE_MIN` = 0D
- static final double `KALMAN_NOISE_MAX` = 5D
- static final double `INITIAL_PROCESS_NOISE` = 5D
- static final double `INITIAL_MEASUREMENT_NOISE` = 5D
- static final int `WINDOW` = 5

6.19.1 Descrizione dettagliata

Created by Federico Torsello. federico.torsello@studio.unibo.it

6.19.2 Documentazione dei membri dato

6.19.2.1 INITIAL_MEASUREMENT_NOISE

```
final double it.unibo.torsello.bluetoothpositioning.constant.KFilterConstants.INITIAL_MEASUREMENT_NOISE = 5D [static]
```

6.19.2.2 INITIAL_PROCESS_NOISE

```
final double it.unibo.torsello.bluetoothpositioning.constant.KFilterConstants.INITIAL_PROCESS_NOISE = 5D [static]
```

6.19.2.3 KALMAN_NOISE_MAX

```
final double it.unibo.torsello.bluetoothpositioning.constant.KFilterConstants.KALMAN_NOISE_MAX = 5D [static]
```

6.19.2.4 KALMAN_NOISE_MIN

```
final double it.unibo.torsello.bluetoothpositioning.constant.KFilterConstants.KALMAN_NOISE_MIN = 0D [static]
```

6.19.2.5 WINDOW

```
final int it.unibo.torsello.bluetoothpositioning.constant.KFilterConstants.WINDOW = 5 [static]
```

La documentazione per questa classe è stata generata a partire dal seguente file:

- [KFilterConstants.java](#)

6.20 Riferimenti per la classe it.unibo.torsello.bluetoothpositioning.activities.MainActivity

Diagramma delle classi per it.unibo.torsello.bluetoothpositioning.activities.MainActivity

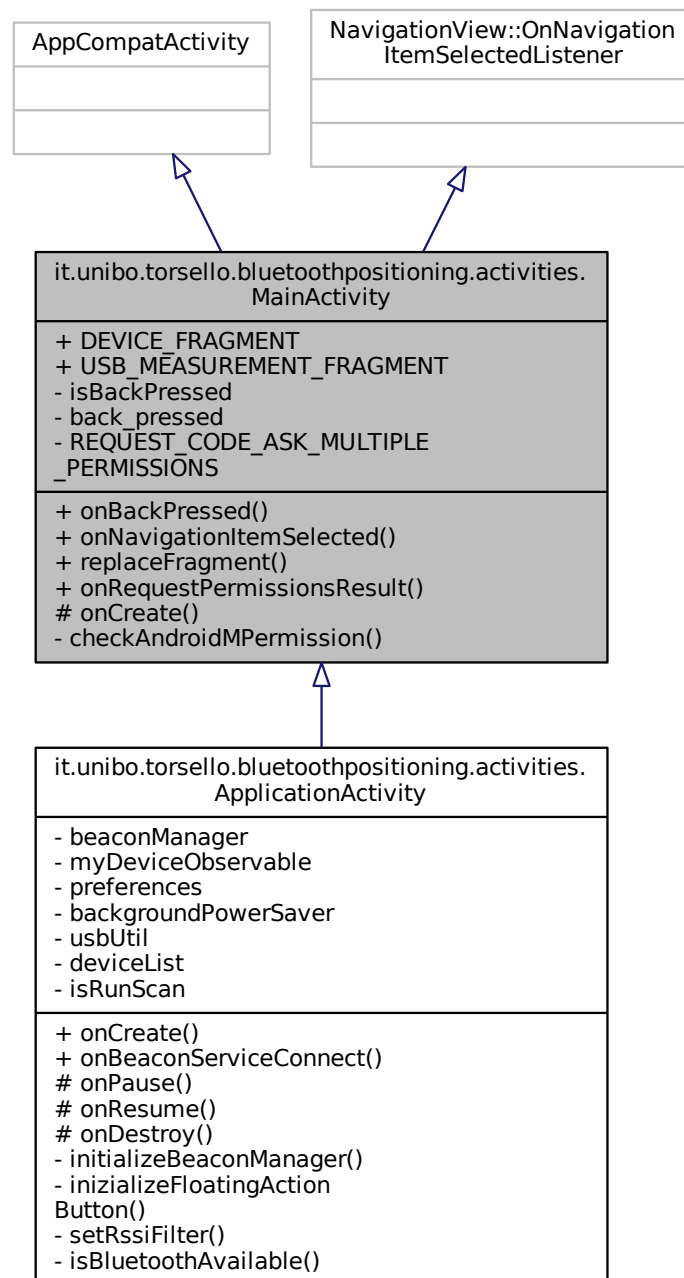
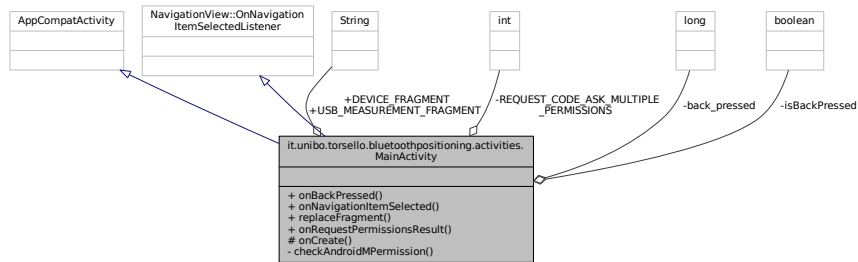


Diagramma di collaborazione per `it.unibo.torsello.bluetoothpositioning.activities.MainActivity`:



Membri pubblici

- void `onBackPressed` ()
- boolean `onNavigationItemSelectedListener` (MenuItem item)
- void `replaceFragment` (String fragTag)
- void `onRequestPermissionsResult` (int requestCode, @NonNull String permissions[], @NonNull int[] grantResults)

Attributi pubblici statici

- static final String `DEVICE_FRAGMENT` = "device"
- static final String `USB_MEASUREMENT_FRAGMENT` = "usb measurement"

Membri protetti

- void `onCreate` (Bundle savedInstanceState)

Membri privati

- void `checkAndroidMPermission` ()

Attributi privati

- boolean `isBackPressed` = false
- long `back_pressed`
- final int `REQUEST_CODE_ASK_MULTIPLE_PERMISSIONS` = 124

6.20.1 Descrizione dettagliata

Created by Federico Torsello. federico.torsello@studio.unibo.it

6.20.2 Documentazione delle funzioni membro

6.20.2.1 `checkAndroidMPermission()`

```
void it.unibo.torsello.bluetoothpositioning.activities.MainActivity.checkAndroidMPermission (
) [private]
```

```

166                                     {
167
168         if (Build.VERSION.SDK_INT >= Build.VERSION_CODES.M) {
169             final List<String> permissions = new ArrayList<>();
170
171             if (checkSelfPermission(Manifest.permission.ACCESS_FINE_LOCATION)
172                 != PackageManager.PERMISSION_GRANTED) {
173                 permissions.add(Manifest.permission.ACCESS_FINE_LOCATION);
174             }
175
176             if (checkSelfPermission(Manifest.permission.ACCESS_COARSE_LOCATION)
177                 != PackageManager.PERMISSION_GRANTED) {
178                 permissions.add(Manifest.permission.ACCESS_COARSE_LOCATION);
179             }
180
181             if (!permissions.isEmpty()) {
182                 new AlertDialog.Builder(this)
183                     .setTitle(R.string.dialog_location_access_title)
184                     .setMessage(R.string.dialog_bluetooth_text)
185                     .setPositiveButton(android.R.string.ok, null)
186                     .setOnDismissListener(new DialogInterface.OnDismissListener() {
187                         @TargetApi(23)
188                         @Override
189                         public void onDismiss(DialogInterface dialog) {
190                             requestPermissions(permissions.toArray(new String[permissions.size()]),
191                                 REQUEST_CODE_ASK_MULTIPLE_PERMISSIONS
192                             );
193                         }
194                     }).show();
195             }
196         }
197     }
```

6.20.2.2 `onBackPressed()`

```
void it.unibo.torsello.bluetoothpositioning.activities.MainActivity.onBackPressed ( )
```

```

69                                     {
70
71         DrawerLayout drawer = (DrawerLayout) findViewById(R.id.drawer_layout);
72         if (drawer.isDrawerOpen(GravityCompat.START)) {
73             drawer.closeDrawer(GravityCompat.START);
74         } else if (drawer.isDrawerOpen(GravityCompat.END)) {
75             drawer.closeDrawer(GravityCompat.END);
76         } else {
77
78             replaceFragment(DEVICE_FRAGMENT);
79
80             final long DOUBLE_PRESS_INTERVAL = 1500L;
81             if (!isBackPressed || back_pressed + DOUBLE_PRESS_INTERVAL <= System.
currentTimeMillis()) {
82                 isBackPressed = true;
83                 FloatingActionButton fab = (FloatingActionButton) findViewById(R.id.fab);
84                 assert fab != null;
85                 Snackbar.make(fab, R.string.snackBar_exit, Snackbar.LENGTH_SHORT).show();
86             } else {
87                 super.finish();
88             }
89             back_pressed = System.currentTimeMillis();
90         }
91     }
```

6.20.2.3 onCreate()

```
void it.unibo.torsello.bluetoothpositioning.activities.MainActivity.onCreate (
    Bundle savedInstanceState ) [protected]

46                                     {
47     super.onCreate(savedInstanceState);
48     setContentView(R.layout.activity_main);
49
50     Toolbar toolbar = (Toolbar) findViewById(R.id.toolbar);
51     setSupportActionBar(toolbar);
52
53     DrawerLayout drawer = (DrawerLayout) findViewById(R.id.drawer_layout);
54     ActionBarDrawerToggle toggle = new ActionBarDrawerToggle(
55         this, drawer, toolbar, R.string.navigation_drawer_open, R.string.navigation_drawer_close);
56     drawer.addDrawerListener(toggle);
57     toggle.syncState();
58
59     ((NavigationView) findViewById(R.id.nav_view)).setNavigationItemSelectedListener(this);
60
61     ((NavigationView) findViewById(R.id.nav_view2)).setNavigationItemSelectedListener(this);
62
63     replaceFragment(DRIVER_FRAGMENT);
64
65     checkAndroidMPPermission();
66 }
```

6.20.2.4 onNavigationItemSelectedListener()

```
boolean it.unibo.torsello.bluetoothpositioning.activities.MainActivity.onNavigationItemSelectedListener←
Selected (
    MenuItem item )
```

```
95                                     {
96
97     DrawerLayout drawer = (DrawerLayout) findViewById(R.id.drawer_layout);
98
99     // Handle navigation view item clicks here.
100     switch (item.getItemId()) {
101         case R.id.nav_home:
102             replaceFragment(DRIVER_FRAGMENT);
103             break;
104         case R.id.nav_settings:
105             drawer.openDrawer(GravityCompat.END);
106             break;
107         case R.id.nav_measurement:
108             replaceFragment(USB_MEASUREMENT_FRAGMENT);
109             break;
110     }
111
112     if (drawer.isDrawerOpen(GravityCompat.START)) {
113         drawer.closeDrawer(GravityCompat.START);
114     }
115
116     return true;
117 }
```

6.20.2.5 onRequestPermissionsResult()

```
void it.unibo.torsello.bluetoothpositioning.activities.MainActivity.onRequestPermissionsResult
(
    int requestCode,
    @NonNull String permissions[],
    @NonNull int [] grantResults )
```

```

139                                     {
140         switch (requestCode) {
141             case REQUEST_CODE_ASK_MULTIPLE_PERMISSIONS:
142                 for (int i = 0; i < permissions.length; i++) {
143                     if (grantResults[i] == PackageManager.PERMISSION_GRANTED) {
144                         // Log.d(TAG_CLASS, "Permission Granted: " + permissions[i]);
145                     } else if (grantResults[i] == PackageManager.PERMISSION_DENIED) {
146                         // Log.d(TAG_CLASS, "Permission Denied: " + permissions[i]);
147                         new AlertDialog.Builder(this)
148                             .setTitle(R.string.dialog_permissions_location_access_title)
149                             .setMessage(R.string.dialog_permissions_location_access_text)
150                             .setPositiveButton(android.R.string.ok, null)
151                             .setOnDismissListener(new DialogInterface.OnDismissListener() {
152
153                                 @Override
154                                 public void onDismiss(DialogInterface dialog) {
155
156
157                                     }).show();
158                     }
159                 }
160                 break;
161             default:
162                 super.onRequestPermissionsResult(requestCode, permissions, grantResults);
163         }
164     }

```

6.20.2.6 `replaceFragment()`

```

void it.unibo.torsello.bluetoothpositioning.activities.MainActivity.replaceFragment (
    String fragTag )

```

```

119                                     {
120         Fragment currentFragment = getSupportFragmentManager().findFragmentByTag(fragTag);
121         switch (fragTag) {
122             case DEVICE_FRAGMENT:
123                 currentFragment = DeviceListFragment.newInstance();
124                 break;
125             case USB_MEASUREMENT_FRAGMENT:
126                 currentFragment = UsbMeasurementFragment.newInstance();
127                 break;
128         }
129         if (currentFragment != null) {
130             getSupportFragmentManager().beginTransaction()
131                 .replace(R.id.contentMainLayout, currentFragment, fragTag)
132                 .commit();
133         }
134     }
135 }

```

6.20.3 Documentazione dei membri dato

6.20.3.1 `back_pressed`

```

long it.unibo.torsello.bluetoothpositioning.activities.MainActivity.back_pressed [private]

```

6.20.3.2 `DEVICE_FRAGMENT`

```

final String it.unibo.torsello.bluetoothpositioning.activities.MainActivity.DEVICE_FRAGMENT =
    "device" [static]

```

6.20.3.3 `isBackPressed`

```

boolean it.unibo.torsello.bluetoothpositioning.activities.MainActivity.isBackPressed = false
[private]

```

6.20.3.4 REQUEST_CODE_ASK_MULTIPLE_PERMISSIONS

```
final int it.unibo.torsello.bluetoothpositioning.activities.MainActivity.REQUEST_CODE_ASK_MULTIPLE_PERMISSIONS = 124 [private]
```

6.20.3.5 USB_MEASUREMENT_FRAGMENT

```
final String it.unibo.torsello.bluetoothpositioning.activities.MainActivity.USB_MEASUREMENT_FRAGMENT = "usb measurement" [static]
```

La documentazione per questa classe è stata generata a partire dal seguente file:

- [MainActivity.java](#)

6.21 Riferimenti per la classe it.unibo.torsello.bluetoothpositioning.configuration.MyArmaRssiFilter

Diagramma delle classi per it.unibo.torsello.bluetoothpositioning.configuration.MyArmaRssiFilter

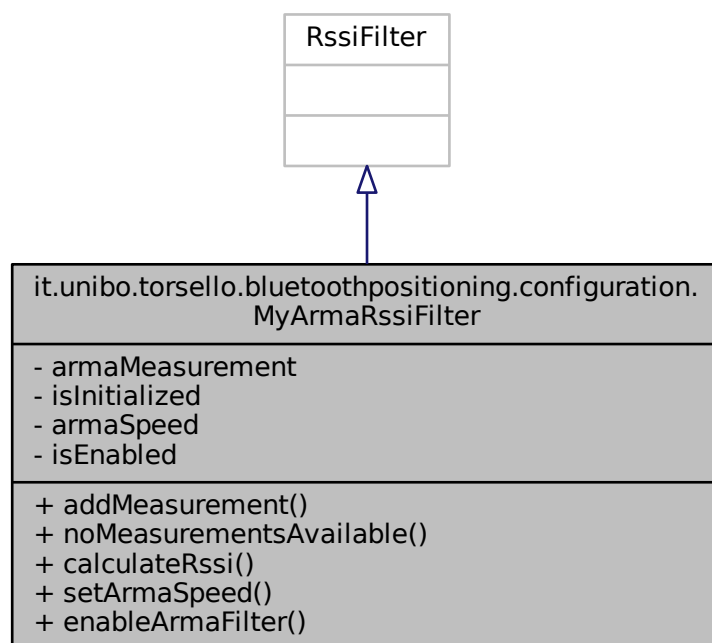
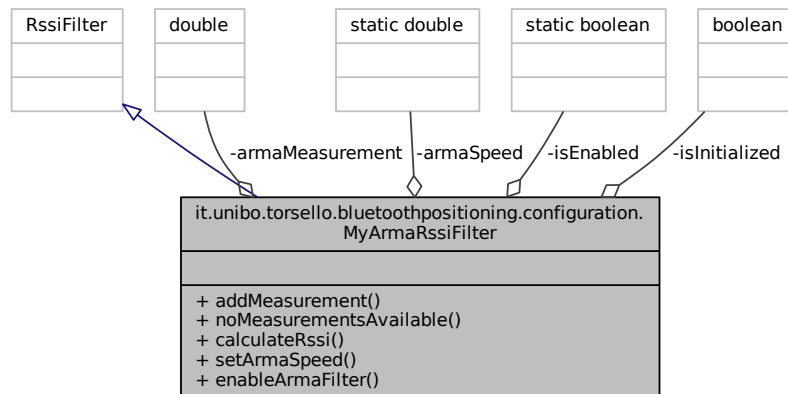


Diagramma di collaborazione per `it.unibo.torsello.bluetoothpositioning.configuration.MyArmaRssiFilter`:



Membri pubblici

- void `addMeasurement` (Integer rssi)
- boolean `noMeasurementsAvailable` ()
- double `calculateRssi` ()

Membri pubblici statici

- static void `setArmaSpeed` (double arma_speed)
- static void `enableArmaFilter` (boolean set)

Attributi privati

- double `armaMeasurement`
- boolean `isInitialized` = false

Attributi privati statici

- static double `armaSpeed` = 0.08D
- static boolean `isEnabled` = true

6.21.1 Descrizione dettagliata

Created by Federico Torsello. federico.torsello@studio.unibo.it

6.21.2 Documentazione delle funzioni membro

6.21.2.1 addMeasurement()

```
void it.unibo.torsello.bluetoothpositioning.configuration.MyArmaRssiFilter.addMeasurement (
    Integer rssi )
```

```
24                                     {
25
26         if (isEnabled) {
27             if (!isInitialized) {
28                 armaMeasurement = rssi;
29                 isInitialized = true;
30             }
31
32             armaMeasurement = (armaMeasurement -
armaSpeed * (armaMeasurement - rssi));
33         } else {
34             armaMeasurement = rssi;
35         }
36     }
37 }
```

6.21.2.2 calculateRssi()

```
double it.unibo.torsello.bluetoothpositioning.configuration.MyArmaRssiFilter.calculateRssi ( )
```

```
45                                     {
46         return armaMeasurement;
47     }
```

6.21.2.3 enableArmaFilter()

```
static void it.unibo.torsello.bluetoothpositioning.configuration.MyArmaRssiFilter.enableArma←
Filter (
    boolean set ) [static]
```

```
19                                     {
20         isEnabled = set;
21     }
```

6.21.2.4 noMeasurementsAvailable()

```
boolean it.unibo.torsello.bluetoothpositioning.configuration.MyArmaRssiFilter.noMeasurements←
Available ( )
```

```
40                                     {
41         return false;
42     }
```

6.21.2.5 setArmaSpeed()

```
static void it.unibo.torsello.bluetoothpositioning.configuration.MyArmaRssiFilter.setArmaSpeed
(
    double arma_speed ) [static]
```

```
15                                     {
16         armaSpeed = arma_speed;
17     }
```

6.21.3 Documentazione dei membri dato

6.21.3.1 armaMeasurement

```
double it.unibo.torsello.bluetoothpositioning.configuration.MyArmaRssiFilter.armaMeasurement
[private]
```

6.21.3.2 armaSpeed

```
double it.unibo.torsello.bluetoothpositioning.configuration.MyArmaRssiFilter.armaSpeed = 0.08D
[static], [private]
```

6.21.3.3 isEnabled

```
boolean it.unibo.torsello.bluetoothpositioning.configuration.MyArmaRssiFilter.isEnabled = true
[static], [private]
```

6.21.3.4 isInitialized

```
boolean it.unibo.torsello.bluetoothpositioning.configuration.MyArmaRssiFilter.isInitialized =
false [private]
```

La documentazione per questa classe è stata generata a partire dal seguente file:

- [MyArmaRssiFilter.java](#)

6.22 Riferimenti per la classe it.unibo.torsello.bluetoothpositioning.task.SaveImageTask

Diagramma delle classi per it.unibo.torsello.bluetoothpositioning.task.SaveImageTask

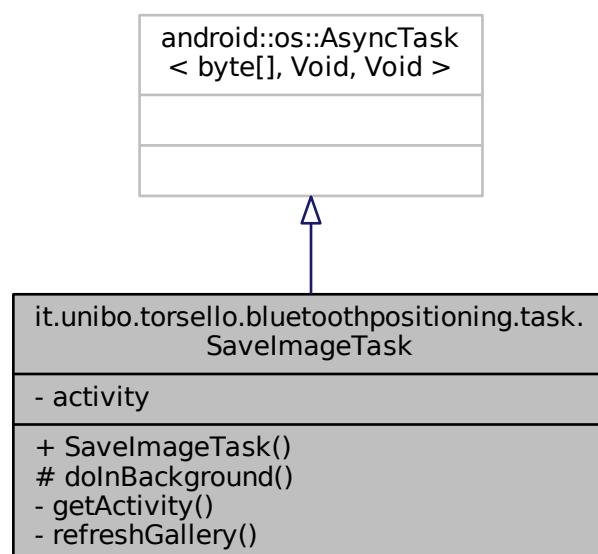
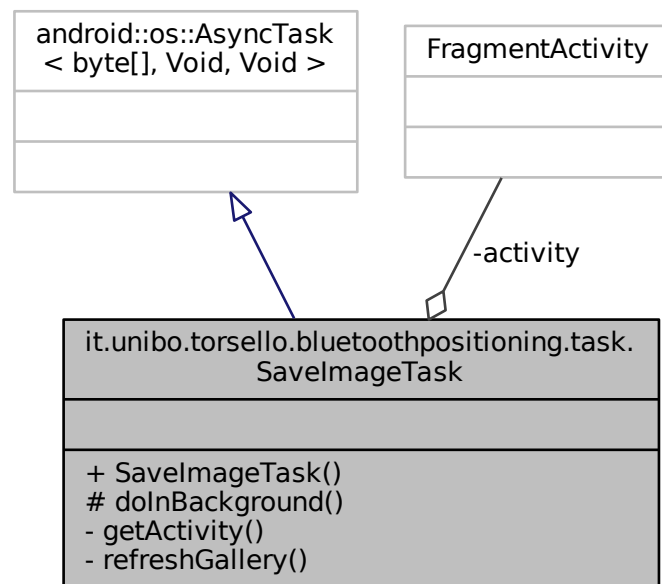


Diagramma di collaborazione per `it.unibo.torsello.bluetoothpositioning.task.SaveImageTask`:



Membri pubblici

- [SaveImageTask](#) (FragmentActivity fragmentActivity)

Membri protetti

- Void [doInBackground](#) (byte[]... data)

Membri privati

- FragmentActivity [getActivity](#) ()
- void [refreshGallery](#) (File file)

Attributi privati

- FragmentActivity [activity](#)

6.22.1 Descrizione dettagliata

Created by Federico Torsello. federico.torsello@studio.unibo.it

6.22.2 Documentazione dei costruttori e dei distruttori

6.22.2.1 `SaveImageTask()`

```
it.unibo.torsello.bluetoothpositioning.task.SaveImageTask.SaveImageTask (
    FragmentActivity fragmentActivity )
```

```
26                                     {
27         this.activity = fragmentActivity;
28     }
```

6.22.3 Documentazione delle funzioni membro

6.22.3.1 `doInBackground()`

```
Void it.unibo.torsello.bluetoothpositioning.task.SaveImageTask.doInBackground (
    byte... [] data ) [protected]
```

```
35                                     {
36
37         // Write to SD Card
38         try {
39             File sdCard = Environment.getExternalStorageDirectory();
40             File dir = new File(sdCard.getAbsolutePath() + "/" + getActivity().getString(R.
string.app_name));
41             dir.mkdirs();
42
43             String fileName = String.format(Locale.getDefault(), "%d.jpg", System.currentTimeMillis());
44             File outFile = new File(dir, fileName);
45
46             FileOutputStream outputStream = new FileOutputStream(outFile);
47             outputStream.write(data[0]);
48             outputStream.flush();
49             outputStream.close();
50
51             refreshGallery(outFile);
52         } catch (IOException e) {
53             e.printStackTrace();
54         }
55         return null;
56     }
```

6.22.3.2 `getActivity()`

```
FragmentActivity it.unibo.torsello.bluetoothpositioning.task.SaveImageTask.getActivity ( )
[private]
```

```
30                                     {
31         return activity;
32     }
```

6.22.3.3 `refreshGallery()`

```
void it.unibo.torsello.bluetoothpositioning.task.SaveImageTask.refreshGallery (
    File file ) [private]
```

```
58                                     {
59         if (file != null){
60             Intent mediaScanIntent = new Intent(Intent.ACTION_MEDIA_SCANNER_SCAN_FILE);
61             mediaScanIntent.setData(Uri.fromFile(file));
62             getActivity().sendBroadcast(mediaScanIntent);
63
64             Snackbar.make(getActivity().findViewById(R.id.fab),
65                 "Your picture has been saved", Snackbar.LENGTH_SHORT).show();
66         } else {
67             Snackbar.make(getActivity().findViewById(R.id.fab),
68                 "Image retrieval failed", Snackbar.LENGTH_SHORT).show();
69         }
70     }
```

6.22.4 Documentazione dei membri dato

6.22.4.1 activity

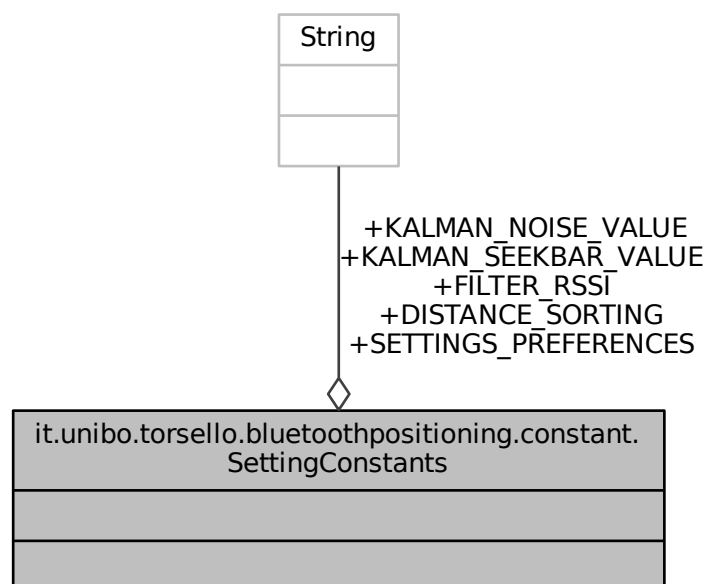
FragmentActivity it.unibo.torsello.bluetoothpositioning.task.SaveImageTask.activity [private]

La documentazione per questa classe è stata generata a partire dal seguente file:

- [SaveImageTask.java](#)

6.23 Riferimenti per la classe it.unibo.torsello.bluetoothpositioning.constant.SettingConstants

Diagramma di collaborazione per it.unibo.torsello.bluetoothpositioning.constant.SettingConstants:



Attributi pubblici statici

- static final String `SETTINGS_PREFERENCES` = "settings_preferences"
- static final String `FILTER_RSSI` = "filter_rssi"
- static final String `KALMAN_SEEKBAR_VALUE` = "kalman_filter_seek_value"
- static final String `KALMAN_NOISE_VALUE` = "kalman_filter_noise_value"
- static final String `DISTANCE_SORTING` = "distance_sorting_selected"

6.23.1 Descrizione dettagliata

Created by Federico Torsello. federico.torsello@studio.unibo.it

A class containing constants for the SharedPreferences objects.

6.23.2 Documentazione dei membri dato

6.23.2.1 DISTANCE_SORTING

```
final String it.unibo.torsello.bluetoothpositioning.constant.SettingConstants.DISTANCE_SORTING  
= "distance_sorting_selected" [static]
```

6.23.2.2 FILTER_RSSI

```
final String it.unibo.torsello.bluetoothpositioning.constant.SettingConstants.FILTER_RSSI =  
"filter_rssi" [static]
```

6.23.2.3 KALMAN_NOISE_VALUE

```
final String it.unibo.torsello.bluetoothpositioning.constant.SettingConstants.KALMAN_NOISE_V↵  
ALUE = "kalman_filter_noise_value" [static]
```

6.23.2.4 KALMAN_SEEKBAR_VALUE

```
final String it.unibo.torsello.bluetoothpositioning.constant.SettingConstants.KALMAN_SEEKBAR↵  
_VALUE = "kalman_filter_seek_value" [static]
```

6.23.2.5 SETTINGS_PREFERENCES

```
final String it.unibo.torsello.bluetoothpositioning.constant.SettingConstants.SETTINGS_PREFE↵  
RENCES = "settings_preferences" [static]
```

La documentazione per questa classe è stata generata a partire dal seguente file:

- [SettingConstants.java](#)

6.24 Riferimenti per la classe `it.unibo.torsello.bluetoothpositioning.fragment.SettingsFragment`

Diagramma delle classi per `it.unibo.torsello.bluetoothpositioning.fragment.SettingsFragment`

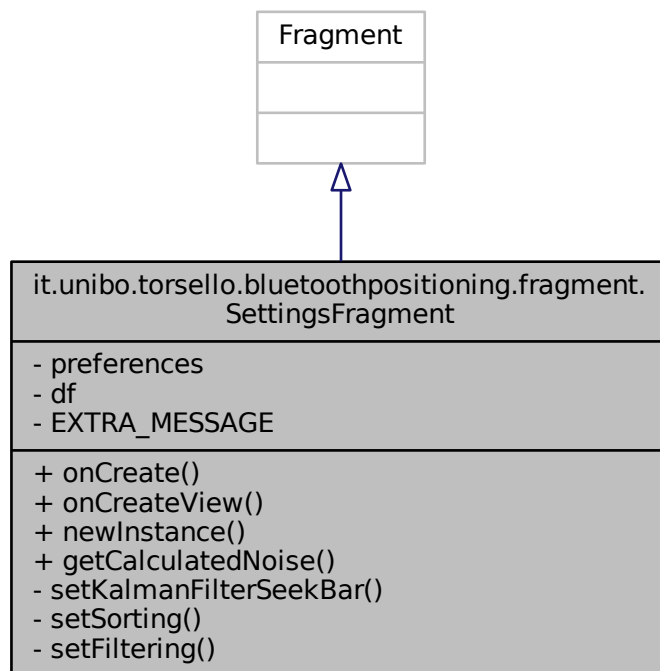
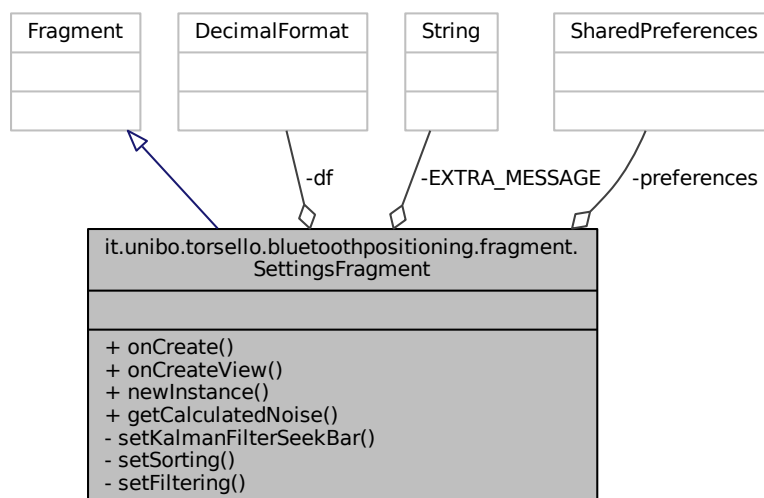


Diagramma di collaborazione per `it.unibo.torsello.bluetoothpositioning.fragment.SettingsFragment`:



Membri pubblici

- void `onCreate` (Bundle savedInstanceState)
- View `onCreateView` (LayoutInflater inflater, ViewGroup container, Bundle savedInstanceState)

Membri pubblici statici

- static `SettingsFragment newInstance` ()
- static float `getCalculatedNoise` (int p)

Membri privati

- void `setKalmanFilterSeekBar` (View root)
- void `setSorting` (View root)
- void `setFiltering` (View root)

Attributi privati

- SharedPreferences `preferences`
- DecimalFormat `df`

Attributi privati statici

- static final String `EXTRA_MESSAGE` = "EXTRA_MESSAGE"

6.24.1 Descrizione dettagliata

Created by Federico Torsello. federico.torsello@studio.unibo.it

6.24.2 Documentazione delle funzioni membro

6.24.2.1 `getCalculatedNoise()`

```
static float it.unibo.torsello.bluetoothpositioning.fragment.SettingsFragment.getCalculatedNoise (
    int p ) [static]

90
91         {
92             double percent = (p / 10D);
93             double noise = KFilterConstants.KALMAN_NOISE_MIN +
94                 (KFilterConstants.KALMAN_NOISE_MAX - KFilterConstants.KALMAN_NOISE_MIN) * percent;
95             return (float) noise;
96         }
97     }
```

6.24.2.2 newInstance()

```
static SettingsFragment it.unibo.torsello.bluetoothpositioning.fragment.SettingsFragment.new←
Instance ( ) [static]
```

```
29         {
30         SettingsFragment fragment = new SettingsFragment();
31         Bundle args = new Bundle();
32         args.putString(EXTRA_MESSAGE, "Settings");
33         fragment.setArguments(args);
34         return fragment;
35     }
```

6.24.2.3 onCreate()

```
void it.unibo.torsello.bluetoothpositioning.fragment.SettingsFragment.onCreate (
    Bundle savedInstanceState )
```

```
38         {
39         super.onCreate(savedInstanceState);
40
41         preferences = getActivity().getSharedPreferences(SettingConstants.SETTINGS_PREFERENCES,
42         0);
43         df = new DecimalFormat("0.0#");
44     }
```

6.24.2.4 onCreateView()

```
View it.unibo.torsello.bluetoothpositioning.fragment.SettingsFragment.onCreateView (
    LayoutInflater inflater,
    ViewGroup container,
    Bundle savedInstanceState )
```

```
46         {
47         View root = inflater.inflate(R.layout.fragment_settings, container, false);
48
49         setKalmanFilterSeekBar(root);
50
51         setSorting(root);
52
53         setFiltering(root);
54
55         return root;
56     }
```

6.24.2.5 setFiltering()

```
void it.unibo.torsello.bluetoothpositioning.fragment.SettingsFragment.setFiltering (
    View root ) [private]
```

```
118         {
119         RadioGroup rg = (RadioGroup) root.findViewById(R.id.radioGroupFilter);
120         int checkedRadioButton;
121         if (rg.getCheckedRadioButtonId() != 0) {
122             checkedRadioButton = preferences.getInt(SettingConstants.FILTER_RSSI, rg.
getCheckedRadioButtonId());
123         } else {
124             checkedRadioButton = 0;
125         }
126         rg.check(checkedRadioButton);
127         rg.setOnCheckedChangeListener(new RadioGroup.OnCheckedChangeListener() {
128             @Override
129             public void onCheckedChanged(RadioGroup group, int checkedId) {
130                 SharedPreferences.Editor editor = preferences.edit();
131                 editor.putInt(SettingConstants.FILTER_RSSI, checkedId);
132                 editor.apply();
133             }
134         });
135     }
```

6.24.2.6 `setKalmanFilterSeekBar()`

```

void it.unibo.torsello.bluetoothpositioning.fragment.SettingsFragment.setKalmanFilterSeekBar (
    View root ) [private]

59
60     {
61         SeekBar kalmanSeek = (SeekBar) root.findViewById(R.id.kalmanSeek);
62         int seekValue = preferences.getInt(SettingConstants.KALMAN_SEEKBAR_VALUE, 4);
63         kalmanSeek.setMax(10);
64         kalmanSeek.setProgress(kalmanSeek.getMax() / 2);
65
66         final TextView kalmanFilterValue = (TextView) root.findViewById(R.id.kalmanValue);
67         kalmanFilterValue.setText(df.format(getCalculatedNoise(seekValue)));
68
69         kalmanSeek.setOnSeekBarChangeListener(new SeekBar.OnSeekBarChangeListener() {
70             @Override
71             public void onProgressChanged(SeekBar seekBar, int seekValue, boolean fromUser) {
72                 kalmanFilterValue.setText(df.format(getCalculatedNoise(seekValue)));
73             }
74
75             @Override
76             public void onStartTrackingTouch(SeekBar seekBar) {
77             }
78
79             @Override
80             public void onStopTrackingTouch(SeekBar seekBar) {
81                 SharedPreferences.Editor editor = preferences.edit();
82                 int progress = seekBar.getProgress();
83                 editor.putInt(SettingConstants.KALMAN_SEEKBAR_VALUE, progress);
84                 editor.putFloat(SettingConstants.KALMAN_NOISE_VALUE,
85                     getCalculatedNoise(progress));
86                 editor.apply();
87                 kalmanFilterValue.setText(df.format(getCalculatedNoise(progress)));
88             }
89         });
90     }

```

6.24.2.7 `setSorting()`

```

void it.unibo.torsello.bluetoothpositioning.fragment.SettingsFragment.setSorting (
    View root ) [private]

99
100     {
101         RadioGroup rg = (RadioGroup) root.findViewById(R.id.radioGroupSortingMode);
102         int checkedRadioButton;
103         if (rg.getCheckedRadioButtonId() != 0) {
104             checkedRadioButton = preferences.getInt(SettingConstants.DISTANCE_SORTING, rg.
105                 getCheckedRadioButtonId());
106         } else {
107             checkedRadioButton = 0;
108         }
109         rg.check(checkedRadioButton);
110         rg.setOnCheckedChangeListener(new RadioGroup.OnCheckedChangeListener() {
111             @Override
112             public void onCheckedChanged(RadioGroup group, int checkedId) {
113                 SharedPreferences.Editor editor = preferences.edit();
114                 editor.putInt(SettingConstants.DISTANCE_SORTING, checkedId);
115                 editor.apply();
116             }
117         });
118     }

```

6.24.3 Documentazione dei membri dato

6.24.3.1 `df`

```

DecimalFormat it.unibo.torsello.bluetoothpositioning.fragment.SettingsFragment.df [private]

```

6.24.3.2 EXTRA_MESSAGE

```
final String it.unibo.torsello.bluetoothpositioning.fragment.SettingsFragment.EXTRA_MESSAGE =  
"EXTRA_MESSAGE" [static], [private]
```

6.24.3.3 preferences

```
SharedPreferences it.unibo.torsello.bluetoothpositioning.fragment.SettingsFragment.preferences  
[private]
```

La documentazione per questa classe è stata generata a partire dal seguente file:

- [SettingsFragment.java](#)

6.25 Riferimenti per la classe it.unibo.torsello.bluetoothpositioning.adapter.StatePagerAdapter

Diagramma delle classi per it.unibo.torsello.bluetoothpositioning.adapter.StatePagerAdapter

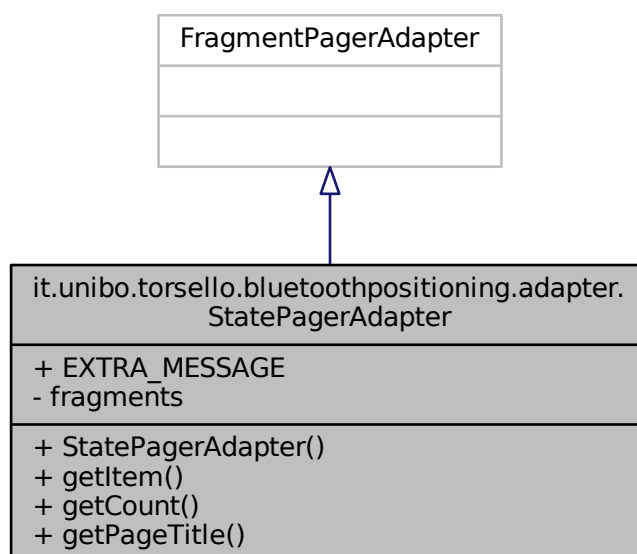
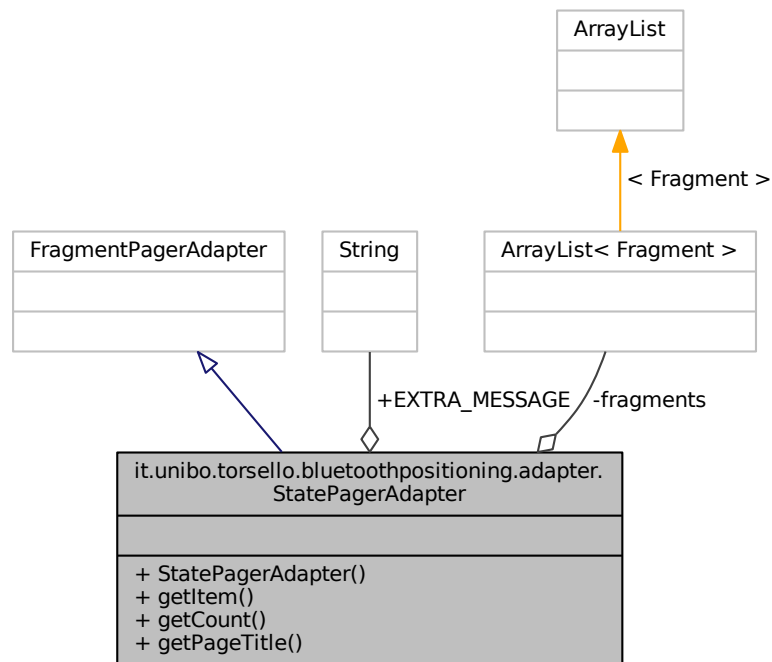


Diagramma di collaborazione per `it.unibo.torsello.bluetoothpositioning.adapter.StatePagerAdapter`:



Membri pubblici

- `StatePagerAdapter` (`FragmentManager fm`, `ArrayList< Fragment > fragments`)
- `Fragment getItem` (`int position`)
- `int getCount` ()
- `CharSequence getPageTitle` (`int position`)

Attributi pubblici statici

- `static final String EXTRA_MESSAGE = "EXTRA_MESSAGE"`

Attributi privati

- `ArrayList< Fragment > fragments`

6.25.1 Descrizione dettagliata

Created by Federico Torsello. federico.torsello@studio.unibo.it

6.25.2 Documentazione dei costruttori e dei distruttori

6.25.2.1 StatePagerAdapter()

```
it.unibo.torsello.bluetoothpositioning.adapter.StatePagerAdapter.StatePagerAdapter (
    FragmentManager fm,
    ArrayList< Fragment > fragments )
```

```
21                                     {
22     super(fm);
23     this.fragments = fragments;
24 }
```

6.25.3 Documentazione delle funzioni membro

6.25.3.1 getCount()

```
int it.unibo.torsello.bluetoothpositioning.adapter.StatePagerAdapter.getCount ( )
```

```
32     {
33     return this.fragments.size();
34 }
```

6.25.3.2 getItem()

```
Fragment it.unibo.torsello.bluetoothpositioning.adapter.StatePagerAdapter.getItem (
    int position )
```

```
27     {
28     return this.fragments.get(position);
29 }
```

6.25.3.3 getPageTitle()

```
CharSequence it.unibo.torsello.bluetoothpositioning.adapter.StatePagerAdapter.getPageTitle (
    int position )
```

```
37     {
38     return fragments.get(position).getArguments().getString(
    EXTRA_MESSAGE);
39 }
```

6.25.4 Documentazione dei membri dato

6.25.4.1 EXTRA_MESSAGE

```
final String it.unibo.torsello.bluetoothpositioning.adapter.StatePagerAdapter.EXTRA_MESSAGE =
"EXTRA_MESSAGE" [static]
```

6.25.4.2 fragments

```
ArrayList<Fragment> it.unibo.torsello.bluetoothpositioning.adapter.StatePagerAdapter.fragments  
[private]
```

La documentazione per questa classe è stata generata a partire dal seguente file:

- [StatePagerAdapter.java](#)

6.26 Riferimenti per la classe it.unibo.torsello.bluetoothpositioning.fragment.usbObservers.UsbMeasurementFragment

Diagramma delle classi per it.unibo.torsello.bluetoothpositioning.fragment.usbObservers.UsbMeasurementFragment

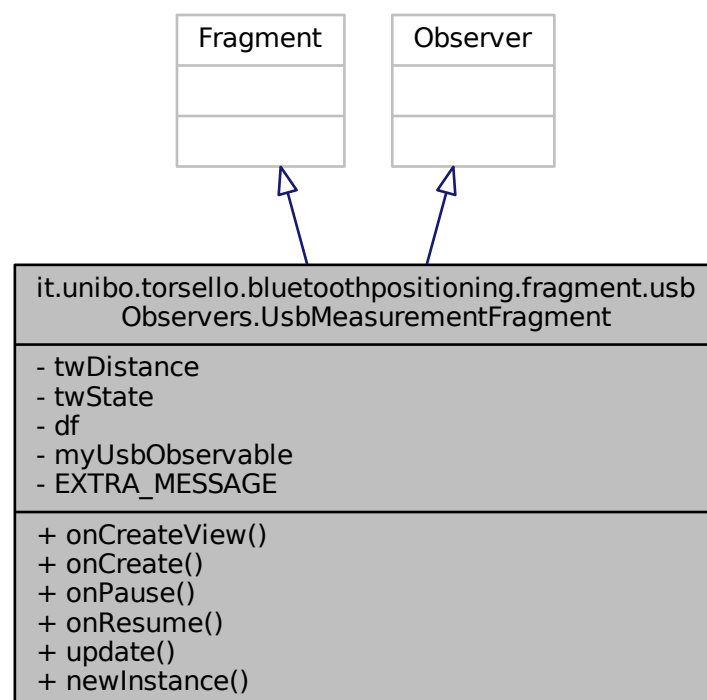
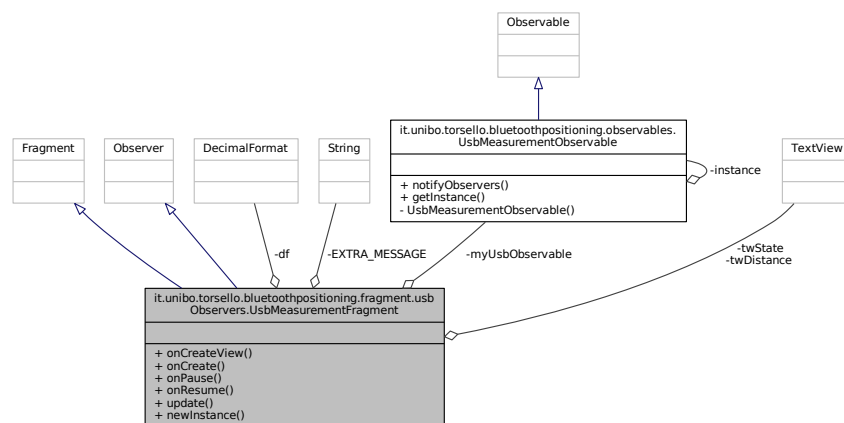


Diagramma di collaborazione per `it.unibo.torsello.bluetoothpositioning.fragment.usbObservers.UsbMeasurementFragment`:



Membri pubblici

- View `onCreateView` (LayoutInflater inflater, ViewGroup container, Bundle savedInstanceState)
- void `onCreate` (@Nullable Bundle savedInstanceState)
- void `onPause` ()
- void `onResume` ()
- void `update` (Observable o, final Object arg)

Membri pubblici statici

- static `UsbMeasurementFragment newInstance` ()

Attributi privati

- TextView `twDistance`
- TextView `twState`
- DecimalFormat `df`
- `UsbMeasurementObservable myUsbObservable`

Attributi privati statici

- static final String `EXTRA_MESSAGE` = "EXTRA_MESSAGE"

6.26.1 Descrizione dettagliata

Created by Federico Torsello. federico.torsello@studio.unibo.it

6.26.2 Documentazione delle funzioni membro

6.26.2.1 newInstance()

```
static UsbMeasurementFragment it.unibo.torsello.bluetoothpositioning.fragment.usbObservers.↵
UsbMeasurementFragment.newInstance ( ) [static]
```

```
35                                     {
36     UsbMeasurementFragment fragment = new UsbMeasurementFragment();
37     Bundle args = new Bundle();
38     args.putString(EXTRA_MESSAGE, "Measurement");
39     fragment.setArguments(args);
40     return fragment;
41 }
```

6.26.2.2 onCreate()

```
void it.unibo.torsello.bluetoothpositioning.fragment.usbObservers.UsbMeasurementFragment.↵
Create (
    @Nullable Bundle savedInstanceState )
```

```
55                                     {
56     super.onCreate(savedInstanceState);
57
58     myUsbObservable = UsbMeasurementObservable.getInstance();
59     df = new DecimalFormat("0.00", DecimalFormatSymbols.getInstance());
60
61 }
```

6.26.2.3 onCreateView()

```
View it.unibo.torsello.bluetoothpositioning.fragment.usbObservers.UsbMeasurementFragment.↵
CreateView (
    LayoutInflater inflater,
    ViewGroup container,
    Bundle savedInstanceState )
```

```
45                                     {
46     View root = inflater.inflate(R.layout.fragment_usb_measurement, container, false);
47
48     twDistance = (TextView) root.findViewById(R.id.tw_distance_value);
49     twState = (TextView) root.findViewById(R.id.tw_state_value);
50
51     return root;
52 }
```

6.26.2.4 onPause()

```
void it.unibo.torsello.bluetoothpositioning.fragment.usbObservers.UsbMeasurementFragment.↵
Pause ( )
```

```
64                                     {
65     myUsbObservable.deleteObserver(this);
66     super.onPause();
67 }
```

6.26.2.5 onResume()

```
void it.unibo.torsello.bluetoothpositioning.fragment.usbObservers.UsbMeasurementFragment.onResume ( )
```

```
70      {
71      super.onResume();
72      myUsbObservable.addObserver(this);
73      }
```

6.26.2.6 update()

```
void it.unibo.torsello.bluetoothpositioning.fragment.usbObservers.UsbMeasurementFragment.update (
```

```
Observable o,
final Object arg )
```

```
76      {
77
78      getActivity().runOnUiThread(new Runnable() {
79      @Override
80      public void run() {
81          if (arg instanceof Double) {
82              Double arduinoDistance = (Double) arg;
83              twDistance.setText(String.format("%s m", df.format(arduinoDistance)));
84          } else if (arg instanceof String) {
85              String message = (String) arg;
86              twState.setText(message);
87          } else if (arg instanceof Boolean) {
88              boolean state = (Boolean) arg;
89              if (state) {
90                  twState.setTextColor(Color.GREEN);
91              } else {
92                  twState.setTextColor(Color.RED);
93              }
94          }
95      }
96      });
97      }
```

6.26.3 Documentazione dei membri dato

6.26.3.1 df

```
DecimalFormat it.unibo.torsello.bluetoothpositioning.fragment.usbObservers.UsbMeasurementFragment.df [private]
```

6.26.3.2 EXTRA_MESSAGE

```
final String it.unibo.torsello.bluetoothpositioning.fragment.usbObservers.UsbMeasurementFragment.EXTRA_MESSAGE = "EXTRA_MESSAGE" [static], [private]
```

6.26.3.3 myUsbObservable

```
UsbMeasurementObservable it.unibo.torsello.bluetoothpositioning.fragment.usbObservers.UsbMeasurementFragment.myUsbObservable [private]
```

6.26.3.4 twDistance

```
TextView it.unibo.torsello.bluetoothpositioning.fragment.usbObservers.UsbMeasurementFragment.twDistance [private]
```

6.26.3.5 twState

```
TextView it.unibo.torsello.bluetoothpositioning.fragment.usbObservers.UsbMeasurementFragment.↵  
twState [private]
```

La documentazione per questa classe è stata generata a partire dal seguente file:

- [UsbMeasurementFragment.java](#)

6.27 Riferimenti per la classe it.unibo.torsello.bluetoothpositioning.observables.UsbMeasurementObservable↵

Diagramma delle classi per it.unibo.torsello.bluetoothpositioning.observables.UsbMeasurementObservable

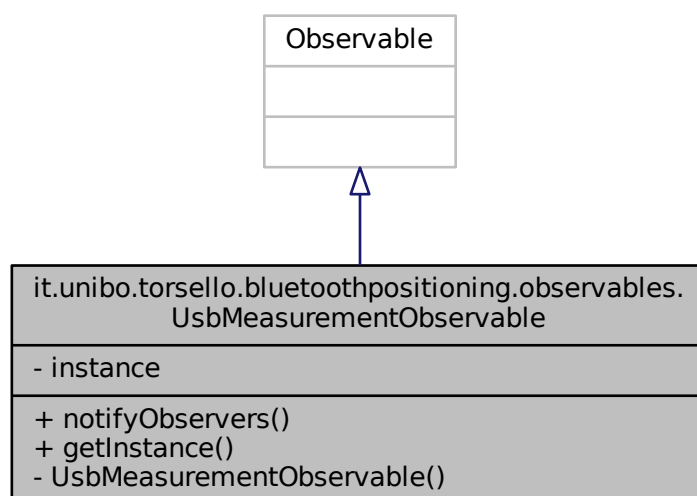
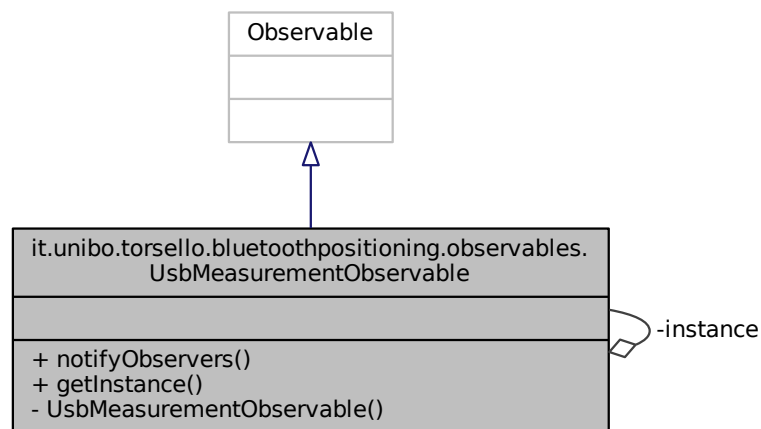


Diagramma di collaborazione per `it.unibo.torsello.bluetoothpositioning.observables.UsbMeasurementObservable`:



Membri pubblici

- void `notifyObservers` (Object data)

Membri pubblici statici

- static `UsbMeasurementObservable getInstance` ()

Membri privati

- `UsbMeasurementObservable` ()

Attributi privati statici

- static `UsbMeasurementObservable instance` = new `UsbMeasurementObservable`()

6.27.1 Descrizione dettagliata

Created by Federico Torsello. federico.torsello@studio.unibo.it

6.27.2 Documentazione dei costruttori e dei distruttori

6.27.2.1 `UsbMeasurementObservable()`

```

it.unibo.torsello.bluetoothpositioning.observables.UsbMeasurementObservable.UsbMeasurementObservable ( ) [private]
  
```

```

17         {
18             super();
19         }
  
```


Membri privati

- [ApplicationActivity getActivity \(\)](#)
- void [initializeUsb \(\)](#)
- void [closePort \(\)](#)
- void [stopIoManager \(\)](#)
- void [startIoManager \(\)](#)

Attributi privati

- [UsbMeasurementObservable myUsbObservable](#)
- final ExecutorService [mExecutor](#) = Executors.newSingleThreadExecutor()
- UsbSerialPort [port](#)
- SerialInputOutputManager [mSerialIoManager](#)
- [ApplicationActivity applicationActivity](#)
- int [BOUND_RATE](#) = 115200

6.28.1 Descrizione dettagliata

Created by Federico Torsello. federico.torsello@studio.unibo.it

6.28.2 Documentazione dei costruttori e dei distruttori

6.28.2.1 UsbUtil()

```
it.unibo.torsello.bluetoothpositioning.util.UsbUtil.UsbUtil (
    ApplicationActivity applicationActivity )
```

```
39
40         this.applicationActivity = applicationActivity;
41         myUsbObservable = UsbMeasurementObservable.getInstance();
42     }
```

6.28.3 Documentazione delle funzioni membro

6.28.3.1 closePort()

```
void it.unibo.torsello.bluetoothpositioning.util.UsbUtil.closePort ( ) [private]
```

```
116
117         if (port != null) {
118             try {
119                 port.close();
120             } catch (IOException e) {
121                 // Ignore.
122             }
123             port = null;
124         }
125     }
```

6.28.3.2 `getActivity()`

```
ApplicationActivity it.unibo.torsello.bluetoothpositioning.util.UsbUtil.getActivity ( ) [private]
```

```
44                                     {
45         return applicationActivity;
46     }
```

6.28.3.3 `initializeUsb()`

```
void it.unibo.torsello.bluetoothpositioning.util.UsbUtil.initializeUsb ( ) [private]
```

```
58                                     {
59
60         // Find all available drivers from attached devices.
61         UsbManager usbManager = (UsbManager) getActivity().getSystemService(Context.USB_SERVICE)
62     ;
63         List<UsbSerialDriver> availableDrivers = UsbSerialProber.getDefaultProber().findAllDrivers(
64         usbManager);
65         if (!availableDrivers.isEmpty()) {
66             // Open a connection to the first available driver.
67             UsbSerialDriver driver = availableDrivers.get(0);
68             if (usbManager.hasPermission(driver.getDevice())) {
69                 if (usbManager.openDevice(driver.getDevice()) != null) {
70                     // Read some data! Most have just one port (port 0).
71                     port = driver.getPorts().get(0);
72                 }
73             } else {
74                 Intent startIntent = new Intent(getActivity(), getClass());
75                 PendingIntent pendingIntent =
76                     PendingIntent.getService(getActivity(), 0, startIntent, 0);
77                 usbManager.requestPermission(driver.getDevice(), pendingIntent);
78
79                 PendingIntent mPendingIntent = PendingIntent.getBroadcast(getActivity(), 0, new
80                 Intent("intent"), 0);
81                 usbManager.requestPermission(driver.getDevice(), mPendingIntent);
82             }
83             if (port != null) {
84
85                 UsbDeviceConnection connection = usbManager.openDevice(port.getDriver().getDevice());
86
87                 if (connection != null) {
88                     try {
89                         port.open(connection);
90                         port.setParameters(BOUND_RATE, UsbSerialPort.DATABITS_8,
91                         UsbSerialPort.STOPBITS_1, UsbSerialPort.PARITY_NONE);
92
93                         String details = "CD - Carrier Detect" + port.getCD() + '\n' +
94                         "CTS - Clear To Send" + port.getCTS() + '\n' +
95                         "DSR - Data Set Ready" + port.getDSR() + '\n' +
96                         "DTR - Data Terminal Ready" + port.getDTR() + '\n' +
97                         "DSR - Data Set Ready" + port.getDSR() + '\n' +
98                         "RI - Ring Indicator" + port.getRI() + '\n' +
99                         "RTS - Request To Send" + port.getRTS();
100
101                     } catch (IOException e) {
102                         myUsbObservable.notifyObservers(
103                         getActivity().getString(R.string.error_opening_device)
104                         + " " + e.getMessage());
105                         myUsbObservable.notifyObservers(false);
106                         closePort();
107                         return;
108                     }
109                     stopIoManager();
110                     startIoManager();
111                 }
112             }
113         }
114     }
```

6.28.3.4 onPause()

```
void it.unibo.torsello.bluetoothpositioning.util.UsbUtil.onPause ( )
```

```
48      {
49          stopIoManager();
50          closePort();
51      }
```

6.28.3.5 onResume()

```
void it.unibo.torsello.bluetoothpositioning.util.UsbUtil.onResume ( )
```

```
53      {
54          initializeUsb();
55      }
```

6.28.3.6 startIoManager()

```
void it.unibo.torsello.bluetoothpositioning.util.UsbUtil.startIoManager ( ) [private]
```

```
134      {
135          if (port != null) {
136              SerialInputOutputManager.Listener mListener =
137                  new SerialInputOutputManager.Listener() {
138                      @Override
139                      public void onRunError(Exception e) {
140                          myUsbObservable.notifyObservers(false);
141                          myUsbObservable.notifyObservers(
142                              getActivity().getString(R.string.usb_device_not_connected));
143                          myUsbObservable.notifyObservers(0D);
144                      }
145                      @Override
146                      public void onNewData(final byte[] data) {
147                          try {
148                              myUsbObservable.notifyObservers(true);
149                              myUsbObservable.notifyObservers(
150                                  getActivity().getString(R.string.usb_device_connected));
151                              Double distanceEstimate = Double.valueOf(new String(data).trim()) / 100;
152                              myUsbObservable.notifyObservers(
153                                  distanceEstimate);
154                              } catch (NumberFormatException nfe) {
155                                  }
156                      }
157              };
158              mSerialIoManager = new SerialInputOutputManager(port, mListener);
159              mExecutor.submit(mSerialIoManager);
160          }
161      }
162  }
```

6.28.3.7 stopIoManager()

```
void it.unibo.torsello.bluetoothpositioning.util.UsbUtil.stopIoManager ( ) [private]
```

```
127      {
128          if (mSerialIoManager != null) {
129              mSerialIoManager.stop();
130              mSerialIoManager = null;
131          }
132      }
```

6.28.4 Documentazione dei membri dato

6.28.4.1 applicationActivity

```
ApplicationActivity it.unibo.torsello.bluetoothpositioning.util.UsbUtil.applicationActivity  
[private]
```

6.28.4.2 BOUND_RATE

```
int it.unibo.torsello.bluetoothpositioning.util.UsbUtil.BOUND_RATE = 115200 [private]
```

6.28.4.3 mExecutor

```
final ExecutorService it.unibo.torsello.bluetoothpositioning.util.UsbUtil.mExecutor = Executors.↵  
newSingleThreadExecutor() [private]
```

6.28.4.4 mSerialIoManager

```
SerialInputOutputManager it.unibo.torsello.bluetoothpositioning.util.UsbUtil.mSerialIoManager  
[private]
```

6.28.4.5 myUsbObservable

```
UsbMeasurementObservable it.unibo.torsello.bluetoothpositioning.util.UsbUtil.myUsbObservable  
[private]
```

6.28.4.6 port

```
UsbSerialPort it.unibo.torsello.bluetoothpositioning.util.UsbUtil.port [private]
```

La documentazione per questa classe è stata generata a partire dal seguente file:

- [UsbUtil.java](#)

7 Documentazione dei file

7.1 Riferimenti per il file ApplicationActivity.java

Composti

- class [it.unibo.torsello.bluetoothpositioning.activities.ApplicationActivity](#)

Package

- package [it.unibo.torsello.bluetoothpositioning.activities](#)

7.2 Riferimenti per il file CameraFragment.java

Composti

- class [it.unibo.torsello.bluetoothpositioning.fragment.CameraFragment](#)

Package

- package [it.unibo.torsello.bluetoothpositioning.fragment](#)

7.3 Riferimenti per il file CameraPreviewUtil.java

Composti

- class [it.unibo.torsello.bluetoothpositioning.util.CameraPreviewUtil](#)

Package

- package [it.unibo.torsello.bluetoothpositioning.util](#)

7.4 Riferimenti per il file ChartUtil.java

Composti

- class [it.unibo.torsello.bluetoothpositioning.util.ChartUtil](#)

Package

- package [it.unibo.torsello.bluetoothpositioning.util](#)

7.5 Riferimenti per il file Device.java

Composti

- class [it.unibo.torsello.bluetoothpositioning.model.Device](#)

Package

- package [it.unibo.torsello.bluetoothpositioning.model](#)

7.6 Riferimenti per il file DeviceCardViewAdapter.java

Composti

- class [it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter](#)
- class [it.unibo.torsello.bluetoothpositioning.adapter.DeviceCardViewAdapter.DeviceViewHolder](#)

Package

- package [it.unibo.torsello.bluetoothpositioning.adapter](#)

7.7 Riferimenti per il file DeviceChartFragment.java

Composti

- class [it.unibo.torsello.bluetoothpositioning.fragment.devicesObservers.DeviceChartFragment](#)

Package

- package [it.unibo.torsello.bluetoothpositioning.fragment.devicesObservers](#)

7.8 Riferimenti per il file DeviceConstants.java

Composti

- class [it.unibo.torsello.bluetoothpositioning.constant.DeviceConstants](#)

Package

- package [it.unibo.torsello.bluetoothpositioning.constant](#)

7.9 Riferimenti per il file DeviceDetailFragment.java

Composti

- class [it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailFragment](#)

Package

- package [it.unibo.torsello.bluetoothpositioning.fragment](#)

7.10 Riferimenti per il file DeviceDetailInner1Fragment.java

Composti

- class [it.unibo.torsello.bluetoothpositioning.fragment.devicesObservers.DeviceDetailInner1Fragment](#)

Package

- package [it.unibo.torsello.bluetoothpositioning.fragment.devicesObservers](#)

7.11 Riferimenti per il file DeviceDetailInner2Fragment.java

Composti

- class [it.unibo.torsello.bluetoothpositioning.fragment.DeviceDetailInner2Fragment](#)

Package

- package [it.unibo.torsello.bluetoothpositioning.fragment](#)

7.12 Riferimenti per il file DeviceListFragment.java

Composti

- class [it.unibo.torsello.bluetoothpositioning.fragment.devicesObservers.DeviceListFragment](#)

Package

- package [it.unibo.torsello.bluetoothpositioning.fragment.devicesObservers](#)

7.13 Riferimenti per il file DeviceObservable.java

Composti

- class [it.unibo.torsello.bluetoothpositioningobservables.DeviceObservable](#)

Package

- package [it.unibo.torsello.bluetoothpositioningobservables](#)

7.14 Riferimenti per il file Estimation.java

Composti

- class [it.unibo.torsello.bluetoothpositioning.distanceEstimation.Estimation](#)

Package

- package [it.unibo.torsello.bluetoothpositioning.distanceEstimation](#)

7.15 Riferimenti per il file FABBehavior.java

Composti

- class [it.unibo.torsello.bluetoothpositioning.extra.FABBehavior](#)

Package

- package [it.unibo.torsello.bluetoothpositioning.extra](#)

7.16 Riferimenti per il file KFilter.java

Composti

- class [it.unibo.torsello.bluetoothpositioning.kalmanFilter.KFilter](#)

Package

- package [it.unibo.torsello.bluetoothpositioning.kalmanFilter](#)

7.17 Riferimenti per il file KFilterBuilder.java

Composti

- class [it.unibo.torsello.bluetoothpositioning.kalmanFilter.KFilterBuilder](#)

Package

- package [it.unibo.torsello.bluetoothpositioning.kalmanFilter](#)

7.18 Riferimenti per il file KFilterConstants.java

Composti

- class [it.unibo.torsello.bluetoothpositioning.constant.KFilterConstants](#)

Package

- package [it.unibo.torsello.bluetoothpositioning.constant](#)

7.19 Riferimenti per il file MainActivity.java

Composti

- class [it.unibo.torsello.bluetoothpositioning.activities.MainActivity](#)

Package

- package [it.unibo.torsello.bluetoothpositioning.activities](#)

7.20 Riferimenti per il file MyArmaRssiFilter.java

Composti

- class [it.unibo.torsello.bluetoothpositioning.configuration.MyArmaRssiFilter](#)

Package

- package [it.unibo.torsello.bluetoothpositioning.configuration](#)

7.21 Riferimenti per il file SavelImageTask.java

Composti

- class [it.unibo.torsello.bluetoothpositioning.task.SavelImageTask](#)

Package

- package [it.unibo.torsello.bluetoothpositioning.task](#)

7.22 Riferimenti per il file SettingConstants.java

Composti

- class [it.unibo.torsello.bluetoothpositioning.constant.SettingConstants](#)

Package

- package [it.unibo.torsello.bluetoothpositioning.constant](#)

7.23 Riferimenti per il file SettingsFragment.java

Composti

- class [it.unibo.torsello.bluetoothpositioning.fragment.SettingsFragment](#)

Package

- package [it.unibo.torsello.bluetoothpositioning.fragment](#)

7.24 Riferimenti per il file StatePagerAdapter.java

Composti

- class [it.unibo.torsello.bluetoothpositioning.adapter.StatePagerAdapter](#)

Package

- package [it.unibo.torsello.bluetoothpositioning.adapter](#)

7.25 Riferimenti per il file `UsbMeasurementFragment.java`

Composti

- class [it.unibo.torsello.bluetoothpositioning.fragment.usbObservers.UsbMeasurementFragment](#)

Package

- package [it.unibo.torsello.bluetoothpositioning.fragment.usbObservers](#)

7.26 Riferimenti per il file `UsbMeasurementObservable.java`

Composti

- class [it.unibo.torsello.bluetoothpositioning.observable.UsbMeasurementObservable](#)

Package

- package [it.unibo.torsello.bluetoothpositioning.observable](#)

7.27 Riferimenti per il file `UsbUtil.java`

Composti

- class [it.unibo.torsello.bluetoothpositioning.util.UsbUtil](#)

Package

- package [it.unibo.torsello.bluetoothpositioning.util](#)

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