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# Proposal for a revision of the CityGML LOD concept

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- **Common understanding** of the distinct levels of detail
  - City models are categorized into LODs
  - Used in tender documents to specify the requirements for data acquisition and modelling
  - Software tools (and vendors) are associated with LODs
  - Applications of city models are associated with LODs

→ **Strong (market) acceptance**
- **Manageable complexity**
- One of the **most successful** concepts of CityGML



- **WHY?** Revision of LOD concept must be **use case driven**
  - Every change must be argued and justified against a use case
- **HOW?** Keep it **simple**
  - If a use case can be supported in two alternative ways, there must be very good arguments to not choose the more simple one
- **IMPACT?** Clear **link** to current LOD concept
  - Reliability for and acceptance by existing and new users, software vendors, data providers, ...
  - Protection of investment as well as willingness to invest
  - Possibility to migrate existing CityGML models

- *Example use cases:* Indoor space management, indoor navigation, disaster management (e.g. CR 12-044)

## Room (Space)

- Number
- Function, usage, etc.

## Window

- Emergency exit?

**Same feature types as currently defined in CityGML – but CityGML cannot be used**

## Wall(Surface)

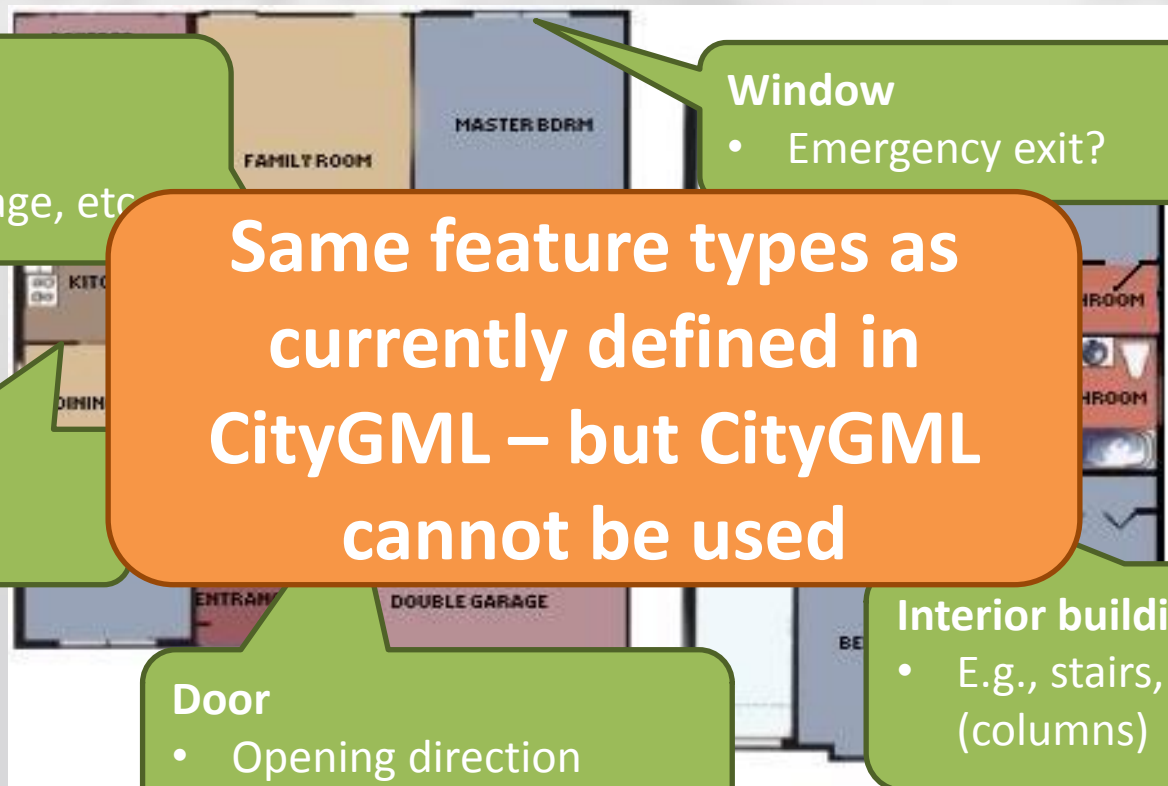
- Material

## Door

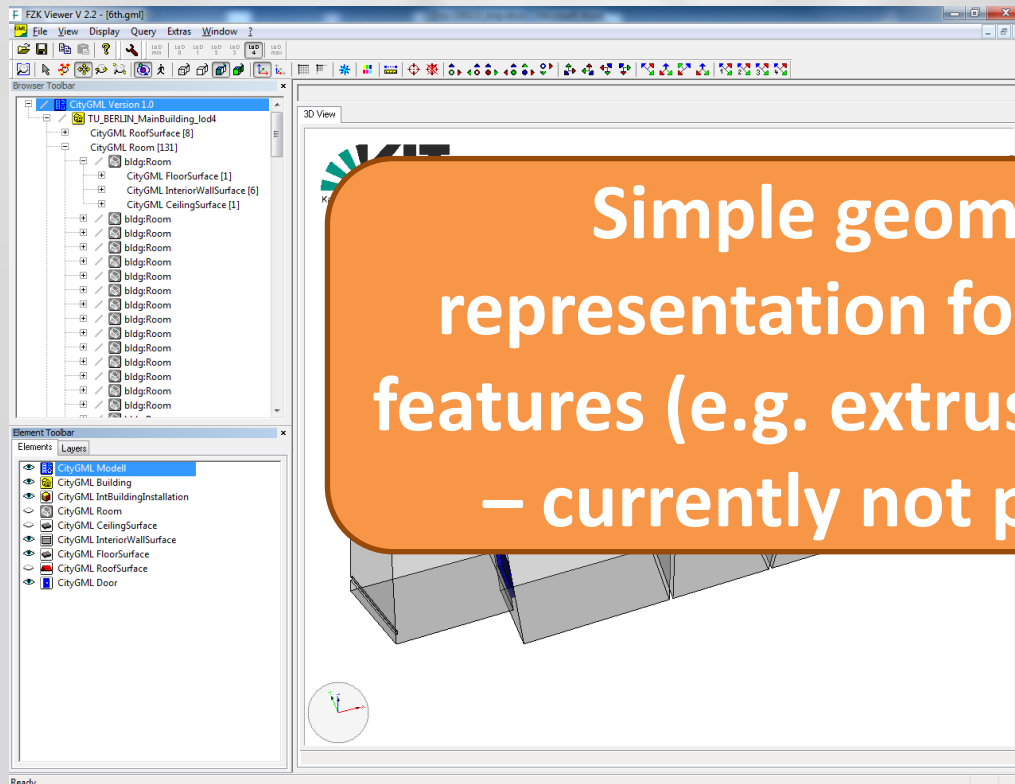
- Opening direction
- Access restrictions

## Interior building installation

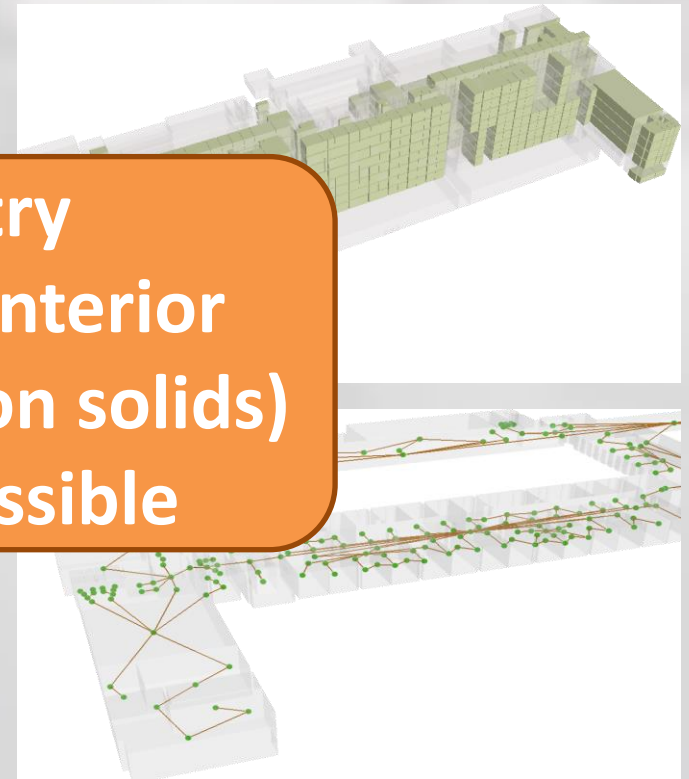
- E.g., stairs, obstacles (columns)



- *Example use cases:* Indoor space management, indoor navigation, disaster management (e.g. CR 12-044)



Simple geometry  
representation for interior  
features (e.g. extrusion solids)  
– currently not possible



## One change: Cancel usage restrictions on feature types in LODs

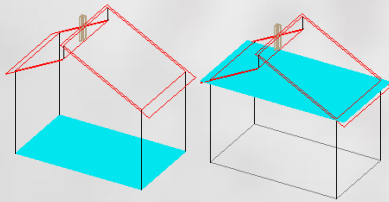
- *Currently:* BoundarySurfaces from LOD2, openings from LOD3, rooms from LOD4

## Idea: Every feature(!) can be *geometrically* described in **four LODs**

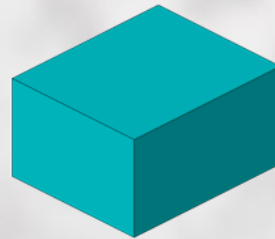
- LOD0: Projection onto a 2.5d reference surface (e.g. terrain, floor) as point, line or surface
- LOD1: Block representation (simple extrusion solids)
- LOD2: Generalized representation
- LOD3: Detailed representation

**That's it!** (Current LOD4 is not required any more)

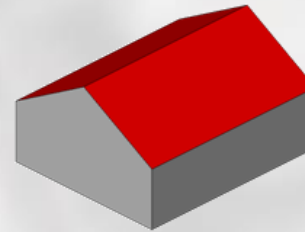
**LOD0**



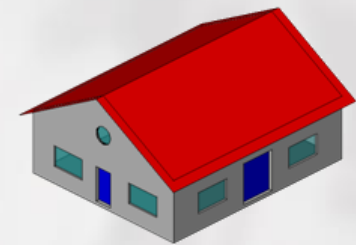
**LOD1**



**LOD2**



**LOD3**



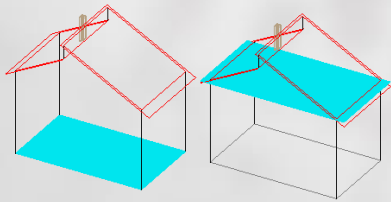
**Building (outer shell! → not boundary surfaces)**

**Strong advantage:**  
Close to CityGML  
1.0/2.0

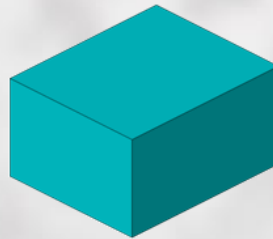
LOD2 building shell with LOD2  
openings?  
**Sure, go ahead**  
(it is not in the figures though)



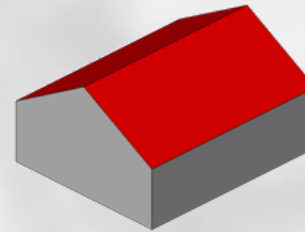
**LOD0**



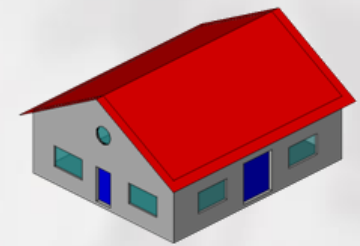
**LOD1**



**LOD2**



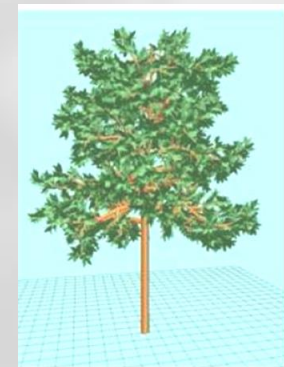
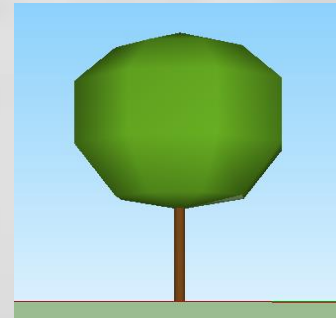
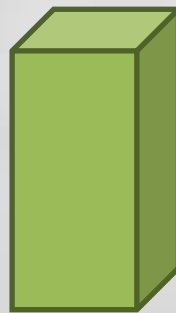
**LOD3**



**Building (outer shell! → not boundary surfaces)**

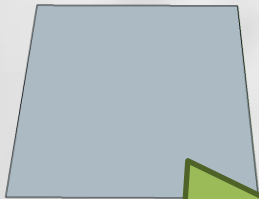
**Solid**

For example, projected  
onto terrain

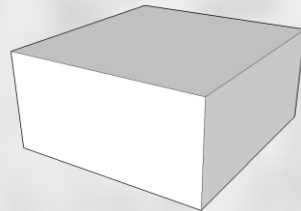




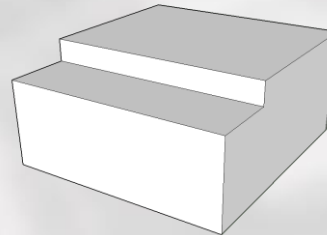
**LOD0**



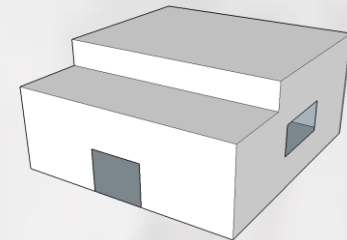
**LOD1**



**LOD2**



**LOD3**

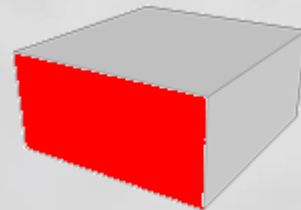


**Room**

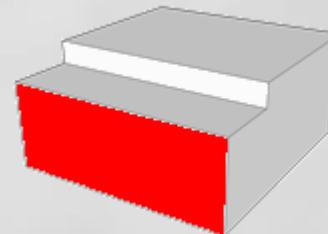
For example, projected  
onto floor plane



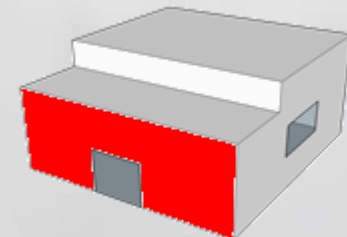
**LOD1**



**LOD2**



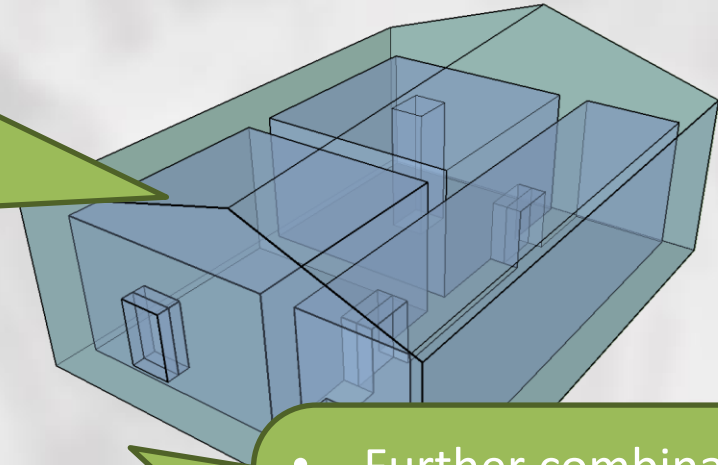
**LOD3**



**(Interior)WallSurface**

- LOD2 building outer shell comes from LiDAR / photogrammetry
- LOD1 rooms come from extrusion of CAD plans
- **WHY NOT?**

**LOD1 Rooms**  
**LOD1 Building (shell)**



**LOD1 Ro**  
**LOD2 Bu**

- Further combinations possible (sorry for not providing images...)
- The same idea applies to **all modules**

- Reasonable combinations will follow from ***use cases / applications***
- The CityGML standard **should not restrict** combinations a priori



LOD0 Room

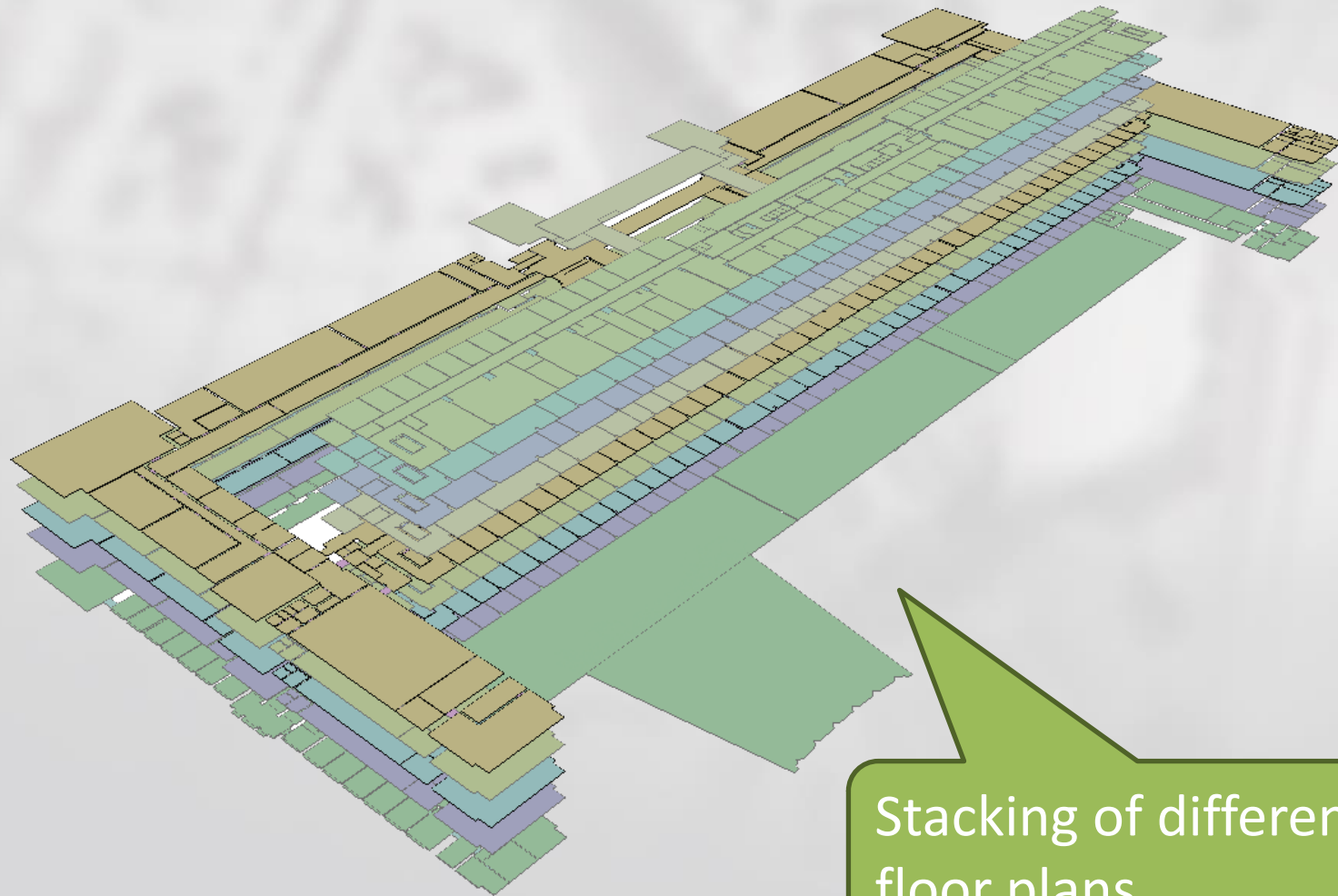
The diagram shows a floor plan with various rooms and corridors. A large room on the right is highlighted in red. A corridor on the left has a red line segment. A door or window is marked with a red line segment. Callout boxes point to specific features: 'LOD0 Room' points to the red room, 'LOD0 Stair?' points to a staircase area, 'LOD0 Elevator?' points to an elevator area, 'LOD0 InteriorWallSurface' points to a wall segment, and 'LOD0 Door/Window' points to a door/window opening.

LOD0 Stair?

LOD0 Elevator?

LOD0 InteriorWallSurface

LOD0 Door/Window



Stacking of different LOD0 floor plans

- **How to realize the current LOD representations based on the new concept?**
- Restrict the CityGML data model to the application needs
  - **Idea:** Simply disallow specific LOD representations for some feature types or even complete feature types
  - **Technical how:** Profiling is the ISO way to restrict application schemas
  - Profiles can be validated and are supported by COTS CityGML software (in contrast to ADEs)
- Example “old LOD2” for buildings:
  - Only allow feature types Building, BuildingPart, WallSurface, GroundSurface, RoofSurface and ClosureSurface
  - Only allow LOD2 representation for these features

- LODs focus on geometric description only
  - Semantic depth naturally follows from the number and type of the modelled features
  - It **cannot be mandated** to always model all possible feature types
- No (academic) differentiation into “exterior/interior” or “geometric/semantic” LODs
  - Benefit: LOD4 in its current form is no longer required → current issues with this LOD are resolved
- Combinations between LODs possible
  - E.g., LOD3 building shell with LOD1 rooms or vice versa
  - Whatever is required for an application / use case
  - CityGML makes no a priori assumptions

- Clear link to existing concept
  - No new terminology
  - Same understanding of LOD0 – LOD3 (geometrically)
  - Clear mapping from “old LODs” (e.g., using profiles)  
→ **Existing CityGML data does not become invalid**
- All current use cases plus additional use cases outlined in this presentation can be covered
- **SIMPLE, SIMPLE, SIMPLE**
  - Just **one change** to the current LOD concept: *Cancel the usage restrictions on feature types in LODs*



The base LOD concept should be accompanied by:

- Metadata for LODs
  - Geometry accuracy / precision; vertical / horizontal reference
  - Semantic richness
  - Suitability for a specific application
  - Data quality?
- Functional dependency between LODs
  - Can lower LODs be computed from higher LODs?
  - IMHO, not really a necessary requirement
- UML modelling and encoding rules for LODs in ADEs (!)
  - Currently, an ADE parser cannot understand LODs of ADE features in an ADE-enriched instance document