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- Or run **2D LiDAR SLAM** when no map exists.

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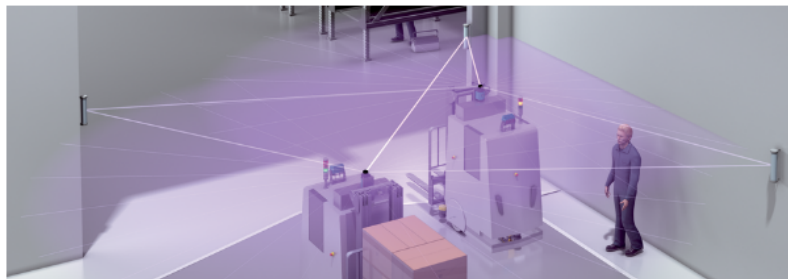
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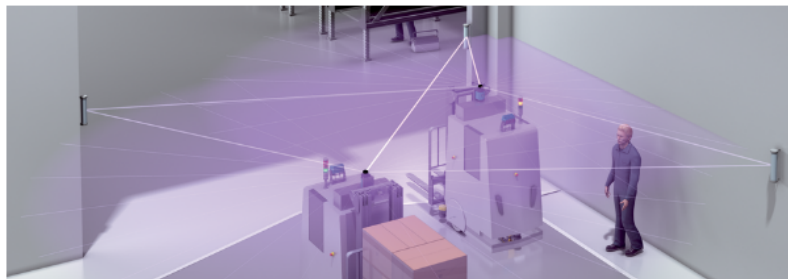
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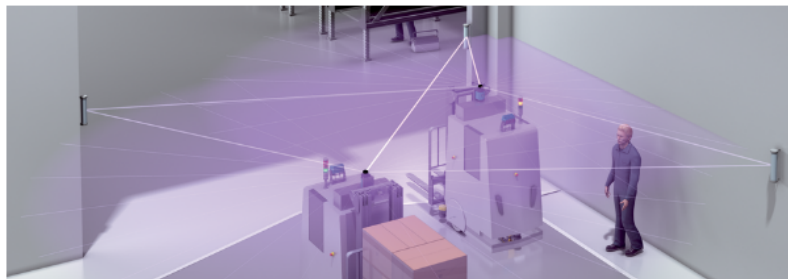
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