generate environment

find a path

visualize results

import Flatland packages

create custom (or random) environment

return rail, rail_map, optionals



in this version, it makes sense to use references that mimic **Flatland track IDs** vs. (**track type, rotation**)

```
cell((1,0), (21,270)). \rightarrow cell((1,0), 3089).
```

represent custom environment in a format readable by clingo

```
class clingo_map():
    def __init__(self, rail_map):
        self.clingo_str = ""
        self.mapping = {}
```

utilize Clingo API to process custom environment

```
ctl = clingo.Control()

# load the map into clingo
ctl.add("base", [], env.clingo_str)
ctl.add("base", [], types)
ctl.add("base", [], encoding)

# ground & solve
ctl.ground([("base", [])])
ctl.solve(on model=on model)
```

translate Clingo solution into Flatland actions

```
def is_switch(loc, env):
    return env[loc] in switch_ids
def next_move(dirs, locs, env):
```

the logic of determining which action is necessary is done by considering a change in location, a change in orientation, and the cell itself:

- if the cell doesn't change, STOP MOVING
- else if the orientation shifts by -90° and the cell is a switch, MOVE LEFT
- else if the orientation shifts by +90° and the cell is a switch, MOVE_RIGHT
- else move forward