1 Derivation

HJB is

$$0 = \rho \theta V_t \left(\frac{C_t^{\frac{1-\gamma}{\theta}}}{((1-\gamma)V_t)^{\frac{1}{\theta}}} - 1 \right) + \frac{E[dV_t]}{dt}$$

Let's define G_t such that

$$V_t = \frac{C_t^{1-\gamma}}{1-\gamma} G_t$$

By Ito,

$$0 = \rho \theta (G_t^{1 - \frac{1}{\theta}} - G_t) + G_t E \frac{\frac{dC_t^{1 - \gamma}}{C_t^{1 - \gamma}}}{dt} + E \frac{dG_t}{dt} + E \frac{dG_t}{dt} \frac{dC_t^{1 - \gamma}}{dt}$$

Denoting μ_C and σ_C the geometric drift of C_t , we have

$$\frac{dC_t^{1-\gamma}}{C_t^{1-\gamma}} = ((1-\gamma)\mu_C - \frac{1}{2}(1-\gamma)\gamma\sigma_C^2)dt + (1-\gamma)\sigma_C dW_t$$

Injecting this expression into HJB and denoting μ_G, σ_G the arithmetic drift and volatility of G_t

$$0 = \rho \theta (G_t^{1 - \frac{1}{\theta}} - G_t) + G_t ((1 - \gamma)\mu_C - \frac{1}{2}(1 - \gamma)\gamma \sigma_C' \sigma_C) + \mu_G + \sigma_G' (1 - \gamma)\sigma_C$$

2 Long run risk model

2.1 Derivation

We now assume that the evolution of consumption is driven by two state variables μ_t and σ_t :

$$\begin{aligned} \frac{dC_t}{C_t} &= \mu_t dt + \nu_D \sqrt{\sigma_t} dZ_t \\ d\mu_t &= \kappa_\mu (\bar{\mu} - \mu_t) dt + \nu_\mu \sqrt{\sigma_t} dZ_t^\mu \\ d\sigma_t &= \kappa_\sigma (1 - \sigma_t) dt + \nu_\sigma \sqrt{\sigma_t} dZ_t^\sigma \end{aligned}$$

We write $G_t = G(\mu, \sigma)$ and we get the PDE

$$0 = \rho \theta [G^{1-\frac{1}{\theta}} - G] + G((1-\gamma)\mu - \frac{1}{2}(1-\gamma)\gamma\nu_D^2\sigma)$$
$$+ \kappa_\mu (\bar{\mu} - \mu)\frac{\partial G}{\partial \mu} + \kappa_\sigma (1-\sigma)\frac{\partial G}{\partial \sigma}$$
$$+ \frac{1}{2}\nu_\mu^2 \sigma \frac{\partial^2 G}{\partial \mu^2} + \frac{1}{2}\nu_\sigma^2 \sigma \frac{\partial^2 G}{\partial \sigma^2}$$

2.1.1 Finite Difference Method

We can discretize this PDE on a grid using a Finite Difference Scheme.

$$\begin{split} 0 &= \rho \theta [(G_{ij})^{1-\frac{1}{\theta}} - G_{ij}] + G_{ij} ((1-\gamma)\mu_i - \frac{1}{2}(1-\gamma)\gamma \nu_D^2 \sigma_j) \\ &+ \kappa_{\mu_i} (\bar{\mu} - \mu_i) \frac{G_{i+1,j} - G_{i+1,j}}{2\Delta \mu} \\ &+ \kappa_{\sigma_j} (1-\sigma_j) \frac{G_{i,j+1} - G_{i,j-1}}{2\Delta \sigma} \\ &+ \frac{1}{2} \nu_{\mu_i}^2 \sigma_j \frac{G_{i+1,j} - 2G_{i,j} + G_{i-1,j}}{(\Delta \mu)^2} + \frac{1}{2} \nu_{\sigma_j}^2 \sigma_j \frac{G_{i,j+1} - 2G_{i,j} + G_{i,j-1}}{(\Delta \sigma)^2} \end{split}$$

At the border of the grid, we remove the second derivative term and we use a second order approximation for the first derivative¹. For instance at i = 1, the scheme is

$$\begin{split} \frac{G_{0,j}-G_{2,j}}{2} &== 0 \\ 0 &= \rho \theta [(G_{1j})^{1-\frac{1}{\theta}}-G_{1j}] + G_{1j}((1-\gamma)\mu_1 - \frac{1}{2}(1-\gamma)\gamma\nu_D^2\sigma_j) \\ &+ \kappa_{\mu_1}(\bar{\mu}-\mu_1) \frac{-(3G_{0,j}-4G_{1,j}+G_{2,j})}{2\Delta\mu} \\ &+ \kappa_{\sigma_j}(1-\sigma_j) \frac{G_{1,j+1}-G_{1,j-1}}{2\Delta\sigma} \\ &+ \frac{1}{2}\nu_{\sigma_j}^2\sigma_j \frac{G_{1,j+1}-2G_{1,j}+G_{1,j-1}}{(\Delta\sigma)^2} \end{split}$$

Denote Y the vector of $(G_{ij})_{1 \leq i,j \leq n}$. The scheme defines a function F such that F(Y) = 0. We can solve for Y using one of these methods:

- 1. Use a non linear solver for the system F(Y) = 0
- 2. Use an ODE solver for the system $F(Y) = \dot{Y}$. The solution when $T \to +\infty$ is the solution of the PDE. This method is called "the method of lines".

A solution that would not work is to solve for G by iterating over time

$$\frac{G_{n+1} - G_n}{\Delta t} = F(G_n)$$

This method can be seen as a special case of a non linear solver (fixed point method) or as a special case of an ODE solver (in this context, it is called the Euler method). The criterion for the convergence of this method is that F is monotonous in G (Barles Souganadis theorem). This is not the case here, due to the non linear term $\rho\theta[(G_{ij})^{1-\frac{1}{\theta}}-G_{ij}]$

For the initial guess, we use the value function for the stationary problem $\sigma=1$ and $\mu=\overline{\mu}$

¹A different boundary coundition would be to assume that μ and σ are reflecting processes. In this case, the first derivative of G is null at the border

2.1.2 Spectral Method (= collocation method)

We can also solve the PDE by looking at solutions of the form

$$V(\mu, \sigma) = \sum_{kl} a_{kl} \phi_k(\mu) \psi_l(\sigma)$$

where ϕ, ψ denote any basis of functions (splines or chebyshev polynomials). The value function is characterized by its coordinates a_{kl} on this basis. Writing the PDE on a grid gives a non linear system in term of the coordinates, which we can solve. We use the same border condition and initial guess as the Finite Difference method.

2.2 Comparison

Name	BY04	BY04	This paper	This paper	Link
mean growth rate	μ	0.0015	$ar{\mu}$	0.0015	$\mu = \bar{\mu}$
mean volatility	σ^2	0.00006084	$ u_D$	0.0078	$\sqrt{\sigma^2} = \nu_D$
growth persistence	ρ	0.979	κ_{μ}	0.0212	$-\log(\rho) = \kappa_{\mu}$
volatility persistence	ν_1	0.987	κ_{σ}	0.0131	$-\log\left(\nu_1\right) = \kappa_{\sigma}$
growth rate volatility	$arphi_e$	0.044	$ u_{\mu}$	0.0003432	$\varphi_e \times \sqrt{\sigma^2} = \nu_\mu$
volatility volatility	σ_w	0.0000023	ν_{σ}	0.0378	$\sigma_w/\sigma^2 = \nu_\sigma$
time discount	δ	0.998	ρ	0.002	$-\log\left(\delta\right) = \rho$
RRA	$1 - \gamma(RRA)$	7.5 or 10	$1-\gamma$	-6.5 or -9	$1 - RRA = 1 - \gamma$
IES	ψ	1.5	ψ	1.5	$\psi = \psi$

Also, $\theta = (1 - \gamma)/(1 - 1/\psi) = -19.50$ or -27. Let's express the wealth to consumption ratio K_t in term of state variables.

$$V = G_t K_t^{\gamma - 1} \frac{W^{1 - \gamma}}{(1 - \gamma)}$$

FOC for consumption can be written

$$K_t^{-1} = \rho^\psi K_t^{\psi-1} G_t^{\frac{1-\psi}{1-\gamma}}$$

We conclude

$$K_t = \rho^{-1} G_t^{1/\theta}$$

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$$\begin{split} \log K_t &\propto A_1 \mu_t + A_2 \nu_D^2 \sigma_t \\ A1 &= \frac{1 - \frac{1}{\psi}}{1 - 0.997 e^{-\kappa_\mu}} \\ A2 &= 0.5 \theta \frac{(1 - \frac{1}{\psi})^2 + (A_1 0.997 \frac{\nu_\mu}{\nu_D})^2}{1 - 0.997 e^{-\kappa_\sigma}} \end{split}$$