

18.303 Problem Set 2

Due Monday, 28 September 2015.

Problem 1: Hermitian vs. Self-adjoint

One of the tricky issues that we will mostly gloss over in this class is the distinction between Hermitian (or “symmetric”) operators and self-adjoint operators. \hat{A} Hermitian means that $\langle u, \hat{A}v \rangle = \langle \hat{A}u, v \rangle$ for all u, v in the domain of \hat{A} . To be truly self-adjoint, however, we also need for \hat{A}^* to have the same domain as \hat{A} . In this problem you will explore this distinction a *little* bit, for the famously problematic example of the operator $\hat{A} = i \frac{\partial}{\partial x}$ acting on differentiable functions $u(x)$ on $\Omega = [0, L]$ with $u(0) = u(L) = 0$, for the inner product $\langle u, v \rangle = \int_0^L \overline{u(x)}v(x)dx$.

- (a) Show that $\langle \hat{A}^*u, v \rangle = \langle u, \hat{A}v \rangle$ for all (differentiable) v with $v(0) = v(L) = 0$ with $\hat{A} = i \frac{\partial}{\partial x}$. However, you should be able to see that this is still true even for u that *don't* satisfy the boundary conditions, so that the domain of \hat{A}^* is larger than the domain of \hat{A} .

The analogous property in the discretized (matrix) system is the fact that our first-derivative matrix D from class was *non-square*: it was $(N+1) \times N$, so that D^T operated on a larger (higher-dimensional) vector space than D . Non-square matrices don't have eigenvectors!

- (b) What happens if you try to find eigenfunctions $\hat{A}u = \lambda u$ satisfying these boundary conditions? (Something bad!)
- (c) Describe the analogue of the 18.06 singular-value decomposition (SVD) for \hat{A} : orthogonal bases for the inputs (domain) and outputs (range) of \hat{A} .
- (d) Consider instead the same operator \hat{A} , but for *periodic* functions $u(L) = u(0)$.
- (i) In this case, show that $\hat{A}^* = \hat{A}$: $\langle \hat{A}^*u, v \rangle = \langle u, \hat{A}v \rangle$ is only true if *both* u and v are periodic.
- (ii) Show that, in this case, \hat{A} has perfectly okay periodic eigenfunctions (what are they?).

Problem 2: Modified inner products for column vectors

Consider the inner product $\langle \mathbf{x}, \mathbf{y} \rangle = \mathbf{x}^* B \mathbf{y}$ from class (lecture 5.5 notes), where the vectors are in \mathbb{C}^N and B is an $N \times N$ Hermitian positive-definite matrix.

- (a) Show that this inner product satisfies the required properties of inner products from class: $\langle \mathbf{x}, \mathbf{y} \rangle = \overline{\langle \mathbf{y}, \mathbf{x} \rangle}$, $\langle \mathbf{x}, \mathbf{x} \rangle > 0$ except for $\mathbf{x} = 0$. (Linearity $\langle \mathbf{x}, \alpha \mathbf{y} + \mathbf{z} \rangle = \alpha \langle \mathbf{x}, \mathbf{y} \rangle + \langle \mathbf{x}, \mathbf{z} \rangle$ is obvious from linearity of the of matrix operations; you need not show it.)
- (b) If M is an arbitrary (possibly complex) $N \times N$ matrix, define the adjoint M^\dagger by $\langle \mathbf{x}, M \mathbf{y} \rangle = \langle M^\dagger \mathbf{x}, \mathbf{y} \rangle$ (for all \mathbf{x}, \mathbf{y}). (In this problem, we use \dagger instead of $*$ for the adjoint in order to avoid confusion with the conjugate transpose: for this inner product, the adjoint M^\dagger is *not* the conjugate transpose $M^* = \overline{M^T}$.) Give an explicit formula for M^\dagger in terms of M and B .
- (c) Using your formula from above, show that $M^\dagger = M$ (i.e., M is self-adjoint/Hermitian for *this* inner product) if $M = B^{-1}A$ for some $A = A^*$.
- (d) In Julia, construct a random 5×5 Hermitian matrix A in Julia by `A=randn(5,5); A=A+A'`, and a random 5×5 Hermitian positive-definite matrix B by `B=randn(5,5); B=B'*B`, and check that $M = B^{-1}A$ has real eigenvalues by `eigvals(B\A)`. [Optional: also check that the eigenvectors, from the `eig` function, are orthogonal under your inner product.]

- (e) In Julia, do the same thing except just make a random indefinite matrix B by `B=randn(5,5); B=B+B'`. Check that `eigvals(B\A)` does *not* generally give real eigenvalues (unless you get “lucky” and B happens to be definite by chance, but you can just repeat the process a few times to be sure).

Problem 3: More Hermitian operators

Consider

$$\hat{A}u = a \frac{d}{dx} \left[b \frac{d(cu)}{dx} \right] + d$$

for some real-valued functions $a(x) > 0$, $b(x)$, $c(x) > 0$, and $d(x)$, acting on functions $u(x)$ defined on $\Omega = [0, L]$.

- (a) Show that \hat{A} is Hermitian for an appropriate choice of inner product $\langle u, v \rangle$ when:
- (i) You have Dirichlet boundary conditions $u(0) = u(L) = 0$
 - (ii) You have “Neumann” boundary conditions $(cu)'(0) = (cu)'(L) = 0$
 - (iii) You have periodic boundary conditions $u(0) = u(L)$, and the coefficients are also periodic.
- (b) Under what conditions on b and d , and for which of the above boundary conditions, is \hat{A} positive-definite?

Problem 4: Finite-difference approximations

For this question you may find it helpful to refer to the notes and readings from lecture 3. Suppose that we want to compute the operation

$$\hat{A}u = \frac{d}{dx} \left[c \frac{du}{dx} \right]$$

for some smooth function $c(x)$ (you can assume c has a convergent Taylor series everywhere). Now, we want to construct a finite-difference approximation for \hat{A} with $u(x)$ on $\Omega = [0, L]$ and Dirichlet boundary conditions $u(0) = u(L) = 0$, similar to class, approximating $u(m\Delta x) \approx u_m$ for M equally spaced points $m = 1, 2, \dots, M$, $u_0 = u_{M+1} = 0$, and $\Delta x = \frac{L}{M+1}$.

- (a) Using center-difference operations, construct a finite-difference approximation for $\hat{A}u$ evaluated at $m\Delta x$. (Hint: use a centered first-derivative evaluated at grid points $m + 0.5$, as in class, followed by multiplication by c , followed by another centered first derivative. Do *not* separate $\hat{A}u$ by the product rule into $c'u' + cu''$ first, as that will make the factorization in part (d) more difficult.)
- (b) Show that your finite-difference expressions correspond to approximating $\hat{A}u$ by $A\mathbf{u}$ where \mathbf{u} is the column vector of the M points u_m and A is a real-symmetric matrix of the form $A = -D^T C D$ (give C , and show that D is the same as the 1st-derivative matrix from lecture).
- (c) In Julia, the `diagm(c)` command will create a diagonal matrix from a vector `c`. The function `diff1(M) = [[1.0 zeros(1,M-1)]; diagm(ones(M-1),1) - eye(M)]` will allow you to create the $(M+1) \times M$ matrix D from class via `D = diff1(M)` for any given value of M . Using these two commands, construct the matrix A from part (d) for $M = 100$ and $L = 1$ and $c(x) = e^{3x}$ via
- ```
L = 1
M = 100
D = diff1(M)
```

```

dx = L / (M+1)
x = dx*0.5:dx:L # sequence of x values from 0.5*dx to <= L in steps of dx
C =something from c(x)...hint: use diag...
A = -D' * C * D / dx^2

```

You can now get the eigenvalues and eigenvectors by  $\lambda$ ,  $U = \text{eig}(A)$ , where  $\lambda$  is an array of eigenvalues and  $U$  is a matrix whose columns are the corresponding eigenvectors (notice that all the  $\lambda$  are  $< 0$  since  $A$  is negative-definite).

- (i) Plot the eigenvectors for the smallest-magnitude four eigenvalues. Since the eigenvalues are negative and are sorted in increasing order, these are the *last* four columns of  $U$ . You can plot them with:

```

using PyPlot
plot(dx:dx:L-dx, U[:,end-3:end])
xlabel("x"); ylabel("eigenfunctions")
legend(["fourth", "third", "second", "first"])

```
- (ii) Verify that the first two eigenfunctions are indeed orthogonal with `dot(U[:,end], U[:,end-1])` in Julia, which should be zero up to roundoff errors  $\lesssim 10^{-15}$ .
- (iii) Verify that you are getting second-order convergence of the eigenvalues: compute the smallest-magnitude eigenvalue  $\lambda_M[\text{end}]$  for  $M = 100, 200, 400, 800$  and check that the *differences* are decreasing by roughly a factor of 4 (i.e.  $|\lambda_{100} - \lambda_{200}|$  should be about 4 times larger than  $|\lambda_{200} - \lambda_{400}|$ , and so on), since doubling the resolution should multiply errors by 1/4.
- (d) For  $c(x) = 1$ , we saw in class that the eigenfunctions are  $\sin(n\pi x/L)$ . How do these compare to the eigenvectors you plotted in the previous part? Try changing  $c(x)$  to some other function (note: still needs to be real and  $> 0$ ), and see how different you can make the eigenfunctions from  $\sin(n\pi x/L)$ . Is there some feature that always remains similar, no matter how much you change  $c$ ?
- (e) How could you change your code to handle  $\hat{A} = c \frac{d^2}{dx^2}$ ?