

# 18.303 Problem Set

Due Wednesday, 10 November 2010.

## Problem 1: Stability

- (a) For the 1d diffusion equation  $\frac{\partial^2 u}{\partial x^2} = \frac{\partial u}{\partial t}$  on  $x \in [-\infty, \infty]$ , use Von Neumann analysis to analyze the stability of the following discretization:

$$\frac{u_m^{n+1} - \frac{1}{2}(u_{m+1}^n + u_{m-1}^n)}{\Delta t} = \frac{u_{m+1}^n - 2u_m^{n+1} + u_{m-1}^n}{\Delta x^2}.$$

That is, assume that the solution on the  $n$ -th timestep is  $\mathbf{u}^n = g^n \mathbf{u}$  for an eigenvalue (“growth factor”)  $g$  and eigenvector  $\mathbf{u}$ , and solve for  $g$  under the assumption that  $u_m = e^{ikx}$ . Then find conditions on  $\Delta t$  (if any) such that it is stable (no exponential growth, i.e.  $|g| \leq 1$ ). What is the order of accuracy, in time and space, of this discretization? If you get  $|g| = 1$  anywhere, what does this mean about the solutions (especially as  $\Delta x$  and  $\Delta t \rightarrow 0$ )?

- (b) Suppose we are discretizing a wave equation  $\frac{\partial \mathbf{w}}{\partial t} = \hat{D} \mathbf{w}$  for some  $\hat{D}^* = -\hat{D}$ . First, we discretize  $\hat{D}$  in space, replacing it by some matrix  $D$  to obtain an ODE  $\frac{d\mathbf{u}}{dt} = D\mathbf{u}$ ; assume  $D$  is real and  $D^T = -D$  (i.e. we have chosen the discretization to mimic the properties of  $\hat{D}$ ), and thus  $D$  has purely imaginary eigenvalues  $\lambda = i\omega$ . Now consider the Crank–Nicolson discretization:

$$\frac{\mathbf{u}^{n+1} - \mathbf{u}^n}{\Delta t} = D \frac{\mathbf{u}^{n+1} + \mathbf{u}^n}{2}.$$

(As shown in class, this is 2nd-order accurate in time and space.) Show that this is unconditionally stable (different from the proof in class: in class, we did it for a matrix  $A$  that was negative-definite). Do the solutions of this discretized equation grow, decay, or...? How does this compare to the exact equation  $\frac{\partial \mathbf{w}}{\partial t} = \hat{D} \mathbf{w}$ ?

## Problem 2: Waves, boundary conditions, and conservation laws

In class (and notes), we showed that we can turn the scalar wave equation  $b\nabla \cdot (a\nabla u) = \frac{\partial^2 u}{\partial t^2}$  ( $a > 0$  and  $b > 0$ ) into two coupled first-derivative equations:  $\frac{\partial u}{\partial t} = b\nabla \cdot \mathbf{v}$ ,  $\frac{\partial \mathbf{v}}{\partial t} = a\nabla u$  by introducing a new (vector) unknown  $\mathbf{v}(\mathbf{x}, t)$ . By defining  $\mathbf{w} = (u, \mathbf{v})^T$ , we obtained the form

$$\frac{\partial \mathbf{w}}{\partial t} = \begin{pmatrix} & b\nabla \cdot \\ a\nabla & \end{pmatrix} \mathbf{w} = \hat{D} \mathbf{w},$$

where  $\hat{D}$  was anti-Hermitian under the inner product  $\langle \mathbf{w}, \mathbf{w}' \rangle = \int_{\Omega} (\frac{1}{b} \bar{u} u' + \frac{1}{a} \bar{\mathbf{v}} \cdot \mathbf{v}')$ , for appropriate boundary conditions (e.g.  $u|_{\partial\Omega} = 0$ ).

- (a) Suppose  $u|_{\partial\Omega} = 0$ . What boundary condition does this imply for  $\mathbf{v}$ ?
- (b) Suppose  $\mathbf{v} \cdot \hat{n}|_{\partial\Omega} = 0$ , where  $\hat{n}$  is a unit vector perpendicular to the  $\partial\Omega$  boundary. What boundary conditions does this imply for  $u$ ?
- (c) In class, we showed that  $\hat{D}^* = -\hat{D}$  implies “conservation of energy:”  $\langle \mathbf{w}, \mathbf{w} \rangle$  must be constant in time if  $\frac{\partial \mathbf{w}}{\partial t} = \hat{D} \mathbf{w}$ . Here, you will give a different conservation law: just as we saw in class for the in the diffusion equation, for any function  $\mathbf{n}(\mathbf{x})$  in the left nullspace  $\hat{D}^* \mathbf{n} = 0 = -\hat{D} \mathbf{n}$ , show that  $\langle \mathbf{n}, \mathbf{w} \rangle$  is constant in time if  $\frac{\partial \mathbf{w}}{\partial t} = \hat{D} \mathbf{w}$ . Describe the left nullspace of the operator  $\hat{D}$  above, for the boundary conditions in part (b), and give the resulting conservation law(s). [Tip 1: the nullspace of  $\nabla \cdot$  in 3d is the curl of any vector field. Tip 2: for any vector fields  $\mathbf{F}$  and  $\mathbf{G}$ ,  $\nabla \cdot (\mathbf{F} \times \mathbf{G}) = \mathbf{G} \cdot (\nabla \times \mathbf{F}) - \mathbf{F} \cdot (\nabla \times \mathbf{G})$ , which allows you to “integrate by parts” on  $\mathbf{F} \cdot (\nabla \times \mathbf{G})$ .]