

A few important PDEs

constant coefficients = 1

variable coefficients = $c(\mathbf{x})$

Poisson's equation:

$$\nabla^2 u = f$$

$$\nabla \cdot (c \nabla u) = f$$

example: f = charge density,

u = -electric potential

example: f = heat source/sink rate

u = steady-state temperature

example: f = solute source/sink rate,

u = steady-state concentration

example: $f \sim$ force on stretched string/drum

u = steady-state displacement

c = permittivity ϵ

c = thermal conductivity

c = diffusion coefficient

$c \sim$ "springy-ness"

Laplace's equation:

$$\nabla^2 u = 0$$

$$\nabla \cdot (c \nabla u) = 0$$

examples: as for Poisson, but no sources

Heat/diffusion equation:

$$\frac{\partial u}{\partial t} = \nabla^2 u$$

$$\frac{\partial u}{\partial t} = \nabla \cdot (c \nabla u)$$

examples: u = temperature

u = solute concentration

c = thermal conductivity

c = diffusion coefficient

Scalar wave equation:

$$\frac{\partial^2 u}{\partial t^2} = \nabla^2 u$$

$$\frac{\partial^2 u}{\partial t^2} = \nabla \cdot (c \nabla u)$$

examples: u = displacement of stretched string/drum

u = density of gas/fluid

$c^2 = 1$ / wave speed

+ many, many others...

Maxwell (electromagnetism)

Schrödinger (quantum mechanics)

Navier–Stokes / Stokes / Euler (fluids)

Black-Scholes (options pricing)

Lamé–Navier (linear elastic solids)

beam equation (bending thin solid strips)

advection-diffusion (diffusion in flows)

reaction-diffusion (diffusion+chemistry)

minimal-surface equation (soap films)

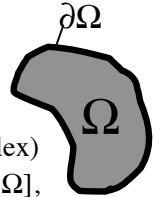
nonlinear wave equation (e.g. solitary ocean waves)

18.06

finite-dimensional linear algebra

18.303

linear algebra w/ functions & derivatives



unknowns:

vector space of
column vectors \mathbf{x} (or $\bar{\mathbf{x}}$) in \mathbb{R}^n (or \mathbb{C}^n),
or possibly $\mathbf{x}(t)$ [time-dependent]

vector space:

we can add, subtract, &
multiply by constants
without leaving the space

vector space of real-valued (or complex)
functions $u(\mathbf{x})$ [for \mathbf{x} in some domain Ω],
or possibly $u(\mathbf{x}, t)$ [time-dependent],

...

possibly restricted by some *boundary conditions*
at the boundary $\partial\Omega$ [e.g. $u(\mathbf{x}) = 0$ on $\partial\Omega$]

...

possibly with vector-valued $\mathbf{u}(\mathbf{x})$ [vector fields]

linear operators: matrices A

linearity:

$$A(\alpha\mathbf{x} + \beta\mathbf{y}) = \alpha A\mathbf{x} + \beta A\mathbf{y}$$

$$\hat{A}(\alpha u + \beta v) = \alpha \hat{A}u + \beta \hat{A}v$$

linear operators on functions \hat{A} ,

[$\hat{A}u = \text{function}$]

using *partial derivatives*. **examples:**

$$\hat{A}_1 u = \nabla^2 u \quad [\text{Laplacian operator}]$$

$$\hat{A}_2 u = 3u \quad [\text{mult. by constant}]$$

$$\hat{A}_3 u|_{\mathbf{x}} = a(\mathbf{x}) u(\mathbf{x}) \quad [\text{mult. by function}]$$

$$\hat{A} = 4\hat{A}_1 + \hat{A}_2 + 7\hat{A}_3 \quad [\text{linear comb. of ops.}]$$

dot product
and transpose:

$$\mathbf{x} \cdot \mathbf{y} = \mathbf{x}^T \mathbf{y} = \sum_i x_i y_i$$

$$\mathbf{x} \cdot A\mathbf{y} = \mathbf{x}^T A\mathbf{y} = (A\mathbf{x})^T \mathbf{y}$$

$$\Leftrightarrow (A^T)_{ij} = A_{ji} \quad [\text{swap rows/cols}]$$

complex \mathbf{x} :

$$\mathbf{x}^T \rightarrow \overline{\mathbf{x}^T} = \mathbf{x}^*$$

$$\left(\frac{\partial}{\partial \mathbf{x}}\right)^T = ???$$

$$u(\mathbf{x}) \cdot v(\mathbf{x}) = \langle u, v \rangle = \text{????????} \quad [\text{inner product}]$$

$$\langle u, \hat{A}v \rangle = \langle \hat{A}^* u, v \rangle$$

$$\Rightarrow \hat{A}^* = \text{????????} (= \hat{A}^\dagger \text{ in physics}) \quad [\text{adjoint}]$$

basis:

set of vectors \mathbf{b}_i with span = whole space

\Leftrightarrow any $\mathbf{x} = \sum_i c_i \mathbf{b}_i$ for some coefficients c_i
... if *orthonormal basis*, then $c_i = \mathbf{b}_i^T \mathbf{x}$

[e.g.
Fourier series!]

∞ set of functions $b_i(\mathbf{x})$ with span = whole space

\Leftrightarrow any $u(\mathbf{x}) = \sum_i c_i b_i(\mathbf{x})$ for some coefficients c_i
... if *orthonormal basis*, then $c_i = \langle b_i, u \rangle$

linear equations:

solve $A\mathbf{x} = \mathbf{b}$ for \mathbf{x}

solve $\hat{A}u = f$ for $u(\mathbf{x})$

existence
& uniqueness:

$A\mathbf{x} = \mathbf{b}$ solvable if \mathbf{b} in column space of A .
Solution unique if null space of $A = \{\mathbf{0}\}$,
or equivalently if eigenvalues of A are $\neq 0$.

$\hat{A}u = f$ solvable if $f(\mathbf{x})$ in col. space (*image*) of \hat{A} .
Solution unique if null space (*kernel*) of $\hat{A} = \{\mathbf{0}\}$,
or equivalently if eigenvalues of \hat{A} are $\neq 0$.

eigenvalues/vectors:

solve $A\mathbf{x} = \lambda\mathbf{x}$ for \mathbf{x} and λ .
For this \mathbf{x} , A acts just like a number (λ).
[e.g. $A^n \mathbf{x} = \lambda^n \mathbf{x}$, $e^{A\lambda} \mathbf{x} = e^{\lambda \mathbf{x}}$.]

solve $\hat{A}u = \lambda u$ for $u(\mathbf{x})$ [*eigenfunction*] and λ .
For this u , \hat{A} acts just like a number (λ).

[e.g. $\hat{A}^n u = \lambda^n u$, $e^{\hat{A}u} = e^{\lambda u}$.] example:
 $\frac{\partial^2}{\partial x^2} \sin(kx) = (-k^2) \sin(kx)$

time-evolution
initial-value
problem:

solve $d\mathbf{x}/dt = A\mathbf{x}$ for $\mathbf{x}(0)=\mathbf{b}$ [system of *ODEs*]
 $\Rightarrow \mathbf{x} = e^{At} \mathbf{b}$ [if A constant]
... expand \mathbf{b} in eigenvectors, mult. each by $e^{\lambda t}$

solve $\partial u / \partial t = \hat{A}u$ for $u(\mathbf{x}, 0)=f(\mathbf{x})$
 $\Rightarrow u(\mathbf{x}, t) = e^{\hat{A}t} f(\mathbf{x})$ [if \hat{A} constant]
... expand f in eigenfunctions, mult. each by $e^{\lambda t}$

symmetric:

$A = A^T$
 \Rightarrow real λ , orthogonal eigenvectors, diagonalizable

$\hat{A} = \hat{A}^T$ [??????]
 \Rightarrow real λ , orthogonal eigenvectors (???)
diagonalizable (???)

positive definite
/ semi-definite:

$A = A^T$, $\mathbf{x}^T A \mathbf{x} > 0$ for any $\mathbf{x} \neq \mathbf{0}$ / $\mathbf{x}^T A \mathbf{x} \geq 0$
 \Leftrightarrow real $\lambda > 0 / \geq 0$, $A = B^T B$ for some B

important fact: $-\nabla^2$ is symmetric positive definite or semi-definite!

$\hat{A} = \hat{A}^*$, $\langle u, \hat{A}u \rangle > 0 / \geq 0$ for $u \neq 0$ (???)
 \Leftrightarrow real $\lambda > 0 / \geq 0$, $\hat{A} = B^* B$ for some B (???)

inverses:

$A^{-1} A = A A^{-1} = 1$ [if it exists]
 $\Rightarrow A\mathbf{x}=\mathbf{b}$ solved by $\mathbf{x} = A^{-1}\mathbf{b}$

$$\left(\frac{\partial}{\partial \mathbf{x}}\right)^{-1} = ???$$

... some kind of integral?

$\hat{A}^{-1} = \text{??????}$
 $\Rightarrow \hat{A}u = f$ solved by $f = \hat{A}^{-1}u$???

[...delta functions
& Green's functions]

orthogonal /
unitary:

$A^{-1} = A^T \Leftrightarrow (A\mathbf{x}) \cdot (A\mathbf{x}) = \mathbf{x} \cdot \mathbf{x}$ for any \mathbf{x}
 $\Rightarrow |\lambda|=1$, orthogonal eigenvectors, diagonalizable

$\hat{A}^{-1} = \hat{A}^* \Leftrightarrow \langle \hat{A}u, \hat{A}u \rangle = \langle u, u \rangle$ for any u
 $\Rightarrow |\lambda|=1$, orthogonal eigenvectors (???)
diagonalizable (???)