



Expert Systems with Applications 00 (2019) 1-6

Bernstain-Search Differential Evolution Algorithm: BSD

Pinar Civicioglu 1

Erciyes University, Faculty of Aeronautics and Astronautics, Dept. of Aircraft Electrics and Electronics, Kayseri, Turkey

Erkan Besdok 2,*

Erciyes University, Faculty of Engineering, Dept. of Geomatics Eng., Kayseri, Turkey

1. Cite As;

Civicioglu, P., Besdok, E., (2019), Bernstain-search differential evolution algorithm for numerical function optimization, Expert Systems with Applications, 138 (30), 112831

Terminology;

"Bernstain polynomials" (Azhari & et al , 2018) == "Bernstein polynomials" (Badea, , 2011)

2. Bernstain-Search Differential Evolution Algorithm: BSD

In the literature of evolutionary algorithms, a random solution is called a *pattern vector* and N *pattern vectors* form the *pattern matrix* P. Each *pattern vector* consists of D *individuals*. EAs can perform *bounded* and/or *unbounded* search. Bounded search works between the upper and lower limits of the individuals (Civicioglu , 2013a, 2012, 2013b; Civicioglu, Besdok, & et al , 2018). BSD is designed as a global minimizer algorithm that performs bounded search.

In BSD, individuals are determined using Eq 1;

$$P_{i,j} \sim \mathbf{U}(low_j, up_j) \mid i = [1:N], j = [1:D], i, j \in \mathbb{Z}^+$$
 (1)

The objective function values of the $pattern\ vectors$ are calculated using Eq 2;

$$fitP_i = \mathcal{F}(P_i) \tag{2}$$

 ${\it Email addresses: civici@erciyes.edu.tr~(Pinar~Civicioglu), ebesdok@erciyes.edu.tr~(Erkan~Besdok~)}$

^{*}Corresponding author

 $^{^{1}}$ Tel.: +xxx-xx fax: +xxx-xx.

 $^{^2\}mathrm{Tel.:}\ +\mathrm{xxx-xx};\;\mathrm{fax:}\ +\mathrm{xxx-xxx}.$

The global minimizer pattern vector, bestP, which provides the best solution to the problem, and the objective function value of the global minimizer pattern vector, solP, are obtained with Eq 3;

$$[solP, bestP] = [fitP_{(\gamma)}, P_{(\gamma)}] \mid fitP_{(\gamma)} = \min(fitP) \mid \gamma \in [1:N]$$
(3)

BSD controls the *crossover* ratio with M by using Eq 4-Eq 5. The initial value of M is determined by using Eq 4.

$$M_{(i=1:N,j=1:D)} = 0 (4)$$

$$M_{(i,u(1:\lceil \rho \cdot D\rceil))} = 1 \tag{5}$$

Here, ρ is defined using Eq 6;

switch
$$\kappa_0$$

$$case \ 1 \quad \rho = (1 - \beta)^2$$

$$case \ 2 \quad \rho = 2 \cdot \beta \cdot (1 - \beta)$$

$$case \ 3 \quad \rho = \beta^2$$
endsw

where $\beta \sim \mathbf{U}(0,1)$ and $\kappa_0 = \left[3 \cdot \kappa_1^3\right]$, $\kappa_1 \sim \mathbf{U}[0\ 1]$, $\kappa_0 \in \mathbf{U}\{1:3\}$. In the Eq 6, the ρ value is computed by using 2^{nd} degree Bernstain polynomials (Azhari & et al , 2018). The 2^{nd} degree Bernstain polynomials are described in Subsection 2.2, Bernstain Polynomials.

The u vector, in Eq 5, is defined by using Eq 7;

$$\mathbf{u} = permute(1:\mathbf{D}) \tag{7}$$

Here, the $permute(\cdot)$ function randomly changes the order of the elements of (\cdot) . The evolutionary step size, F, is determined by using Eq 8.

$$\begin{cases}
If & \kappa_2 \prec \kappa_3 \text{ then} \\
F = \left(\left[\eta_{(1,1:D)}^3 \circ \left| \lambda_{(1,1:D)}^3 \right| \right]' \times Q_{(1,1:N)} \right)' \\
else \\
F = \lambda_{(N,1)}^3 \times Q_{(1,D)} \\
end
\end{cases} (8)$$

Here, $\kappa_{2:3}$, η , and λ are random numbers that receive a new value in each call, where $\kappa_{2:3}$, $\eta \sim \mathbf{U}(0,1)$, $\lambda \sim \mathbf{N}(0,1)$, and (\cdot,\cdot) sized all-ones matrix $Q_{(\cdot,\cdot)} = 1$.

BSD's trial pattern vector (i.e., T_i) generation process is a random crossover process. In the BSD, the trial pattern vectors are generated by using the system equation defined in Eq 9.

$$T = P + F \circ M \circ \left((w^*)^3 \circ E + \left(1 - (w^*)^3 \right) \circ best P - P \right) \mid w^*_{(1:N,1)} \sim \mathbf{U}(0,1)$$
 (9)

where, $E = w \cdot P_{L_1} + (1 - w) \cdot P_{L_2}$ | $w_{(1:N,1:D)} \sim \mathbf{U}(0,1)$ and \mathbf{L}_1 and \mathbf{L}_2 are defined in Eq 10.

$$L_1 = permute(1:N), L_2 = permute(1:N) \mid L_1 \neq [1:N], L_1 \neq L_2$$
 (10)

If an individual of a trial pattern vector exceeds the search space, the individual is updated using the Eq 11.

If
$$(T_{i,j} < low_j)$$
 or $(T_{i,j} > up_j)$ then $T_{i,j} = low_j + \delta \cdot (up_j - low_j)$ (11)

Here, $\delta \sim \mathbf{U}(0,1)$.

The objective function, $\mathcal{F}(\cdot)$, values, fitT, of the trial pattern vectors are computed by using Eq 12;

$$fitT = \mathcal{F}(T) \tag{12}$$

Trial pattern vector, which provides a better objective function value than the corresponding pattern vector, is used to update the relevant pattern vector. It is also updated in the objective function value of the pattern vector. This process is achieved by using Eq 13.

$$If \ fitT_{(i^*)} < fitP_{(i^*)}, \ [P_{(i^*)}, \ fitP_{(i^*)}] = [T_{(i^*)}, fitT_{(i^*)}] \ | \ i^* \in [1:N]$$

$$(13)$$

In the present iteration step, the *pattern vector* which provides the best solution, bestP, and its objective function value, solP, are obtained by using Eq 14.

$$[solP, bestP] = [fitP_{(\gamma)}, P_{(\gamma)}] \mid fitP_{(\gamma)} = \min(fitP)$$
(14)

The pseudo-code of BSD is given in Fig. 1.

```
Input: Objective Function: \mathcal{F}, Search-Space Limits: (low, up), Size of Pattern Matrix: N, Dimension of problem: D, Maximum Number of Iterations: MaxCycle
      Output: solP: Global Minimum, bestP: Global Minimizer
      // Initialization
 1 P_{i,j} \sim \mathbf{U}(low_j, up_j) \mid i = [1:N], j = [1:D], where i, j \in \mathbb{Z}^+
              P_i = \mathcal{F}(P_i)
 3 [solP, bestP] = [fitP<sub>(\gamma)</sub>, P<sub>(\gamma)</sub>] | fitP<sub>(\gamma)</sub> = min(fitP) | \gamma \in [1:N]
4 for Iteration=1 to MaxCycle do
              // Generation of Mutation Control Matrix ; M
               M_{(i=1:N,j=1:D)}=0
              for i=1 to N do
 6
                      u = permute(1:D)
                      Generate \beta, where \beta \sim \mathbf{U}(0,1)
 8
                      Generate \kappa_0, where \kappa_0 = \left[3 \cdot \kappa_1^3\right], \kappa_1 \sim U[0\ 1], \kappa_0 \in \mathbf{U}\{1:3\}
 9
                      switch \kappa_0 do
10
                              case 1, \rho = (1 - \beta)^2
case 2, \rho = 2 \cdot \beta \cdot (1 - \beta)
case 3, \rho = \beta^2
12
13
                      endsw
14
                      M_{(i,u(1:\lceil\rho\cdot D\rceil))}=1
15
              end
16
              // Generation of Evolutionary Step Size; F
              \kappa_{2:3}, \eta, and \lambda are random numbers, where \kappa_{2:3} \sim \mathbf{U}(0,1), \ \eta \sim \mathbf{U}(0,1), \ \lambda \sim \mathbf{N}(0,1), \ \text{and all-ones matrix } Q_{(\cdot,\cdot)} = 1
17
18
                      F = \left( \left[ \eta_{(1,1:D)}^3 \circ \left| \lambda_{(1,1:D)}^3 \right| \right]' \times Q_{(1,1:N)} \right)'
19
20
21
22
              // Generation of Trial Pattern Vectors; T
             77 Generation of Irial Pattern Vectors; 1 L_1 = permute(1:N), \ L_2 = permute(1:N) \mid L_1 \neq [1:N], \ L_1 \neq L_2 E = w \cdot P_{L_1} + (1-w) \cdot P_{L_2} \quad | \quad w_{(1:N,1:D)} \sim \mathbf{U}(0,1) T = P + F \circ M \circ \left( (w^*)^3 \circ E + \left( 1 - (w^*)^3 \right) \circ best P - P \right) \quad | \quad w_{(1:N,1)}^* \sim \mathbf{U}(0,1)
23
25
              // Boundary Control Mechanism if (T_{i,j} < low_j) or (T_{i,j} > up_j) then T_{i,j} = low_j + \delta \cdot (up_j - low_j) \mid \delta \sim \mathbf{U}(0,1)
26
27
               \begin{array}{l} fitT_{(i^*)} < fitP_{(i^*)} \text{ then } [P_{(i^*)}, fitP_{(i^*)}] = [T_{(i^*)}, fitT_{(i^*)}] \mid i^* \in [1:N] \\ \text{// Get the solutions} \end{array} 
28
              [solP,bestP] = [fitP_{(\gamma)},P_{(\gamma)}] \ | \ fitP_{(\gamma)} = \min(fitP)
29
30 end
```

Figure 1. Pseudo code of the Bernstain-Search Differential Evolution Algorithm (BSD). The unoptimized Matlab code of the BSD is publicly available at (Mathworks, 2019).

The similarities and differences of BSD and the tested methods are as follows:

- BSD's random crossover process differs from the corresponding crossover processes of the tested methods.
- The BSD's *crossover* process is a stochastic process based on the use of Bernstain polynomials and there is no parameter controlling this process.
- Since BSD uses the global minimizer pattern vector in its system equation (i.e., Eq 9), it shows a partially elitist behavior whereas ABC and CUCKOO are elitist algorithms.
- The BSD is sensitive to the values of common control parameters (*i.e.*, N, D and number of iterations) such as tested methods (*i.e.*, ABC, JADE, CUCKOO and WDE).
- BSD can operate in parallel to calculate the objective function values, and BSD can perform bounded / unbounded search without any modification.
- BSD has a one-step search process, unlike ABC and CUCKOO.

2.1. Nomenclature

Symbol	Meaning / Definition
$\overline{\mathcal{F}}$	Objective function.
low, up	Lower and upper limits of search-space.
N	Size of pattern matrix.
D	Dimension of problem.
MaxCycle	Maximum number of iterations.
gmin	Global minimum value.
gbest	The global minimizer pattern vector.
$\kappa_{(\cdot)} \sim U(0,1), \kappa_{(\cdot)} \neq 0$	κ is a uniform random number.
$\lambda_{(\cdot)} \sim N(0,1)$	λ is a normal random number.
$\eta \sim N(0,1)$	η is a normal random number.
$\beta \sim U(0,1)$	β is a uniform random number.
$U(\cdot)$	Continuous Uniform Distribution.
$U\{\cdot\}$	Discrete Uniform Distribution.
$P_{(i0,j0)} \mid P_{(i0,j0)} \sim \mathbf{U}(low_{(j0)}, up_{(j0)})$	Pattern vectors of pattern matrix.
$fitP_{(i0)}$	Fitness values of $P_{i0=1:N}$.
permute()	Permuting function.
0	Hadamart multiplication operator.

2.2. Bernstain Polynomials

The 2^{nd} degree Bernstain polynomials (Azhari & et al , 2018) are identified using Eq.s 15-16;

$$B_{s,n}(t) = \binom{n}{s} t^s (1-t)^{n-s}$$
(15)

Here s=0:n, $\binom{n}{s}=\frac{n!}{s!(n-s)!}$. Eq. 16 generates (n+1) sized n^{th} degree Bernstain polynomials. For s<0 and s>n, $B_{s,n}=0$.

$$B_{0,2}(t) = (1-t)^2$$

$$B_{1,2}(t) = 2t(1-t)$$

$$B_{2,2}(t) = t^2$$
(16)

Fig. 2 illustrates 2^{nd} degree Bernstain (Azhari & et al , 2018) polynomials for $0 \leq t \leq 1$;

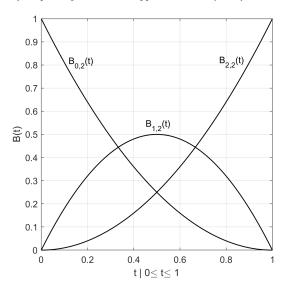


Figure 2. 2^{nd} degree Bernstain polynomials.

References

 $Atlasus,\,http://atlasus.com.tr/Atlas/UAV~(Access~18.12.2018)$

Azhari, F., Heidarpour, A., & Zhao, X.L. (2018). On the use of Bernstain-Bezier functions for modelling the post-fire stress-strain relationship of ultra-high strength steel (Grade 1200). *Engineering Structures*. 175, 605-616.

Bergen, S., & Ross, J.R. (2009). Automatic and interactive evolution of vector graphics images with genetic algorithms. *The Visual Computer*, 28, 35-45.

Besdok, E., Civicioglu, P., & Alcı, M. (2004). Impulsive noise suppression from highly corrupted images by using resilient neural networks. Lecture Notes in Artificial Intelligence, 3070, 670-675.

Brest, J., Greiner, S., Boskovic, B., Mernik, M., & Zumer V. (2006). Self-adapting control parameters in differential evolution: a comparative study on numerical benchmark problems. *IEEE Transactions on Evolutionary Computation*, 10, 646-657.

Chen, J., Zheng, J., Wu, P., et al. (2017). Dynamic particle swarm optimizer with escaping prey for solving constrained non-convex and piecewise optimization problems. *Expert Systems with Applications*, 86, 208-223.

Chernikov, A.N. & Chrisochoides, N.P. (2012). Generalized Insertion Region Guides For Delaunay Mesh Refinement, SIAM Journal On Scientific Computing, 34, A1333-A1350.

Civicioglu, P. (2013,a). Backtracking search optimization algorithm for numerical optimization problems. Applied Mathematics and Computation, 219, 8121-8144.

Civicioglu, P. (2012). Transforming geocentric cartesian coordinates to geodetic coordinates by using differential search algorithm. Computers & Geosciences, 46, 229-247.

Civicioglu, P. (2013,b). Artificial cooperative search algorithm for numerical optimization problems. *Information Sciences*, 229 - 58-76.

Civicioglu, P., & Alci M. (2004). Impulsive noise suppression from highly distorted images with triangular interpolants. *AEU* - *International Journal of Electronics and Communications*, 58, 311-318.

Civicioglu, P., & Beşdok, E. (2013). A conceptual comparison of the cuckoo-search, particle swarm optimization, differential evolution and artificial bee colony algorithms. *Artificial Intelligence Review*, 39, 315-346.

Civicioglu, P., & Beşdok E. (2014). Comparative Analysis of the Cuckoo Search Algorithm, Cuckoo Search and Firefly Algorithm Theory and Applications, Springer, London, 85-113.

Civicioglu, P., Besdok, E., Gunen, M.A., & Atasever, U.H. (2018). Weighted differential evolution algorithm for numerical function optimization: a comparative study with cuckoo search, artificial bee colony, adaptive differential evolution, and backtracking search optimization algorithms. Neural Computing and Applications. Article online. https://doi.org/10.1007/s00521-018-3822-5 (Access 18.12.2018)

 $The \ matlab \ codes \ of \ classic \ benchmark \ problems \ (2019). \ https://www.mathworks.com/matlabcentral/fileexchange/69827-bernstain-search-differential-evolution-algorithm?s_tid=FX_rc2_behav \ (last \ access \ 23.06.2019)$

The matlab codes of classic benchmark problems (2019). https: //www.sfu.ca/ssurjano/optimization.html (last access 23.06.2019)

Clerc, M., & Kennedy, J. (2002). The particle swarm-explosion, stability, and convergence in a multidimensional complex space. *IEEE Transactions on Evolutionary Computation*, 6, 58-73.

Das, S., Mullick, S.S., & Suganthan, P.N. (2016). Recent advances in differential evolution - An updated survey. Swarm and Evolutionary Computation, 27, 1-30.

- Derrac, J., Garca, S., Molina, D., & Herrera, F. (2011). A practical tutorial on the use of nonparametric statistical tests as a methodology for comparing evolutionary and swarm intelligence algorithms. Swarm and Evolutionary Computation, 1 3-18. Karaboğa, D., & Basturk B. (2007). A powerful and efficient algorithm for numerical function optimization: artificial bee colony
- (ABC) algorithm. Journal of Global Optimization, 39, 459-471.
- Liang, J.J., & Qu, B.Y., & Suganthan, P.N. (2013). Problem Definitions and Evaluation Criteria for the CEC 2014 Special Session and Competition on Single Objective Real-Parameter Numerical Optimization, Technical Report 201311, Computational Intelligence Laboratory, Zhengzhou University, Zhengzhou, China and Technical Report, Nanyang Technological University, Singapore, December 2013.
- Liu, J., & Zhang, H., & He, K. & et al. (2018). Multi-objective particle swarm optimization algorithm based on objective space division for the unequal-area facility layout problem. Expert Systems with Applications, 102, 179-192.
- Lynn, N., & Suganthan P.N., (2017). Ensemble particle swarm optimizer. Applied Soft Computing, 55, 533-548.
- Opara K, Arabas J (2018). Comparison of mutation strategies in Differential Evolution A probabilistic perspective, Swarm and Evolutionary Computation. 39, 53–69.
- Matsumoto, M., & Nishimura, T. (1998). Mersenne twister: A 623-dimensionally equidistributed uniform pseudo-random number generator. ACM Transactions on Modeling and Computer Simulation, 8, 3-30.
- Mathworks, Matlab File Exchange, (2019), https://www.mathworks.com/matlabcentral/fileexchange/69819-bernstain-search-differential-evolution-algorithm (Last access 25.06.2019)
- Mlakar, U., Potocnik, B., & Brest, J., (2016). A hybrid differential evolution for optimal multilevel image thresholding. *Expert Systems with Applications*, 65, 221-232.
- Mohamed, A.W., & Suganthan P.N., (2018). Real-parameter unconstrained optimization based on enhanced fitness-adaptive differential evolution algorithm with novel mutation. Soft Computing, 22, 3215-3235.
- Price, K.V., Storn, R., & Lampinen, J. (2005). Differential evolution: A practical approach to global optimization. Springer, Berlin, Germany.
- Özsoydan, F.B., & Baykaşoğlu, A., (2019). Quantum firefly swarms for multimodal dynamic optimization problems. Expert Systems with Applications, 115, 189-199.
- Qin, Q., Cheng, S., Zhang, Q., & et al. (2014). Multiple strategies based orthogonal design particle swarm optimizer for numerical optimization. *Computers & Operations Research*, 60, 91-110.
- Zhang, Q., Zou, D., Duan, N., et al. (2019). An adaptive differential evolutionary algorithm incorporating multiple mutation strategies for the economic load dispatch problem. *Applied Soft Computing*, 78, 641-669.
- Turef, https://epsg.io/5256 (Last access 25.06.2019)
- Yang, X.S., & Deb, S. (2009). Cuckoo search via levy flights. World Congress on Nature and Biologically Inspired Computing-Nabic'2009, Coimbatore, India, 4, 210-214.
- Zhang, J., & Sanderson, A.C. (2009). JADE: Adaptive differential evolution with optional external archive. *IEEE Transactions on Evolutionary Computation*, 13, 945-958.
- Zhang, W.B., & Zhu, G.Y. (2011). Comparison and application of four versions of particle swarm optimization algorithms in the sequence optimization. Expert Systems with Applications, Volume: 38 Issue: 7 Pages: 8858-8864 Published: JUL 2011
- Badea, C. Bernstein Polynomials and Operator Theory. Results. Math. (2009) 53: 229. https://doi.org/10.1007/s00025-008-0333-1