

Moving-Target TSP in two-orthogonal-axes

Pseudocode-BF

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Algorithmus 1 Exact Algorithm for One-Dimensional Moving-Target TSP

Input: The initial positions and velocities of n targets, and the maximum pursuer speed

Output: A time-optimal tour intercepting all targets, and returning back to the origin

Preprocessing

Partition the list of targets into the targets on the left side, the right side of the origin

Sort the targets on the left into list *Left* in order of nonincreasing speeds

Sort the targets on the right into list *Right* in order of nonincreasing speeds

Delete targets from *Left* which are closer to the origin than faster targets in this list

Delete targets from *Right* which are closer to the origin than faster targets in this list

if *Left* or *Right* is empty **then**

 Calculate the time required to intercept all remaining targets; and

 Go to the postprocessing step

end if

Main Algorithm

Let A_0 be the start state

Let A_{final} be the final state

STATE is the sorted list of states in order of nondecreasing sum of the indices
 of each state's targets in lists *Left* and *Right*

Place A_0 first in the list *STATE*

Place A_{final} last in the list *STATE*

$t(A) \leftarrow \infty$ for any state $A \neq A_0$

$t(A_0) \leftarrow 0$

current $\leftarrow 0$

while *current* \leq the number of states in *STATE* **do**

$A = STATE[current]$

if there are no transitions into A **then**

 Increment *current* and jump back to the beginning of the while loop

end if

if for state A , all remaining targets are on one side of the origin **then**

$t(\tau_{final}) \leftarrow$ time required to intercept the remaining targets and
 return to the origin

else

 Calculate the two transitions τ_{left} and τ_{right} from state A using lists *Left* and *Right*

if $t(A) + t(\tau_{left}) < t(A_{left})$ **then**

$t(A_{left}) \leftarrow t(A) + t(\tau_{left})$

end if

if $t(A) + t(\tau_{right}) < t(A_{right})$ **then**

$t(A_{right}) \leftarrow t(A) + t(\tau_{right})$

end if

end if

 Increment *current*

end while

OUTPUT \leftarrow the reverse list of states from A_{final} back to A_0

Postprocessing

for pair of consecutive states in *OUTPUT* **do**

 Calculate which targets are intercepted between the state pair

 Sort the intercepted targets by the interception order

end for

Output the concatenated sorted lists of targets
