

#### Divide&Conquer: MergeSort

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### Divide-and-Conquer Algorithms

- \* Divide-and-conquer algorithms work according to the following general plan:
  - 1. A problem's instance is divided into several smaller instances of the same problem, ideally of about the same size.
  - 2. The smaller instances are solved (typically recursively, though sometimes a different algorithm is employed when instances become small enough).
  - 3. If necessary, the solutions obtained for the smaller instances are combined to get a solution to the original instance.

### Sorting

- \* Given a list L of n elements, we want to sort them in ascending order.
- \* The most basic brute-force algorithm would go through every permutation of the n elements, and return one that is sorted in ascending order.
- \* In the worst case, this algorithm takes  $O(n \cdot n!)$  time, since there are O(n!) permutations, and for each one, it takes O(n) to check if it is sorted in ascending order.
- Can we do better? Of course; much better!

### MergeSort: Verbal Description

- \* MergeSort divides the list L[0..n-1] into two halves L[0..[n/2]-1] and L[[n/2]..n-1], sorting each of them recursively, and then merging the two smaller sorted arrays into a single sorted one.
- Question: How do we sort each of the two halves?
  - \* Answer: by dividing each into two halves, sorting them, and then merging.
- Question: When do we stop dividing the list?
  - \* Answer: When we reach a list of size 1 (since we know how to sort it).

### MergeSort: Pseudo-Code The Divide Phase

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#### MergeSort

Input: List L of ``orderable" elements

**Modifies**: List L is sorted in-place in ascending order

Output: None

```
If n>1
  copy L[0..[n/2]-1] to A[0..[n/2]-1];
  copy L[[n/2]..n-1] to B[0.. [n/2]];
  MergeSort(A[0..[n/2]-1]);
  MergeSort(B[0..[n/2]-1]);
  Merge(A,B,L);
```

### MergeSort: Pseudo-Code The Combine Phase

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Merge

```
Input: Two sorted lists A[0..p-1] and B[0..q-1], and list L
Modifies: List L contains the elements of A and B sorted in ascending order
Output: None
i\leftarrow 0; j\leftarrow 0; k\leftarrow 0;
While i<p and j<q
   If A[i] \leq B[j]
       L[k] \leftarrow A[i];
       i\leftarrow i+1;
   Else
       L[k] \leftarrow B[j];
       j←j+1;
   k \leftarrow k+1;
If i=p
   copy B[j..q-1] to L[k..p+q-1]
Else
   copy A[i..p-1] to L[k..p+q-1]
```

# What Is The Running Time of MergeSort?

- \* For simplicity, let us assume n is a power of 2 (that is, n=2<sup>m</sup> for some m).
- \* Let C(n) be the number of steps **MergeSort** takes on a list L that has n elements.
- \* Then, we have the <u>recurrence</u>

$$C(n) = 2C(n/2) + C_{merge}(n)$$
 for  $n>1$ , and  $C(1)=1$ .

- \* Notice that  $C_{merge}(n)=O(n)$ .
- \* Question: What function g(n) gives us C(n) = O(g(n))?

- \* A (numerical) <u>sequence</u> is an ordered list of numbers.
- \* Examples: 1,1,2,3,5,8,13,21,...
- \* A sequence can also be viewed as a function x(n): its argument n indicates a position of a number in the list, while the function's value x(n) stands for that number itself.
- \* x(n) is called the generic term of the sequence.

- \* There are two principal ways to define a sequence:
  - \* by an explicit formula expressing its generic term as a function of n; e.g., x(n) = 2n for  $n \ge 0$ ,
  - \* by an an equation relating its generic term to one or more other terms of the sequences, combined with one or more explicit values for the first term(s); e.g.,

$$x(n) = x(n-1) + n$$
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\* To solve a given recurrence subject to a given initial condition means to find an explicit formula for the generic term of the sequence that satisfies both the recurrence and the initial condition or to prove that such a sequence does not exist.

## Common Recurrence Types in Algorithm Analysis

- \* There are a few recurrence types that arise in the analysis of algorithms with remarkable regularity.
- \* This happens because they reflect one of the fundamental design techniques.
- \* Of particular interest to us is a recurrence that arises when analyzing the running time of divide&conquer algorithms.

## Common Recurrence Types in Algorithm Analysis

\* Assuming all smaller instances (resulting from the divide phase) have the same size n/b, with a of them being actually solved, we get the following recurrence valid for  $n=b^k$ , k=1,2,...:

$$T(n) = aT(n/b) + f(n)$$

where  $a \ge 1$ ,  $b \ge 2$ , and f(n) is a function that accounts for the time spent on dividing the problem into smaller ones and combining their solutions.

#### The Master Theorem

\* Let T(n) be an eventually nondecreasing function that satisfies the recurrence

$$T(n) = aT(n/b) + f(n)$$
 for  $n = b^k$ ,  $k = 1, 2, ...$   
 $T(1) = c$ ,

where  $a \ge 1$ ,  $b \ge 2$ , c > 0.

\* If  $f(n)=O(n^d)$  where  $d\ge 0$ , then

$$T(n) = \begin{cases} O(n^d) & \text{if } a < b^d \\ O(n^d \log n) & \text{if } a = b^d \\ O(n^{\log_b a}) & \text{if } a > b^d \end{cases}$$

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- \* Thus, we have: a=2, b=2, c=1, and  $f(n)=O(n^1)$ , i.e., d=1.
- \* Since we have  $a=b^d$ , it follows from the Master Theorem that

$$T(n) = O(n^1 \log n) = O(n \log n)$$