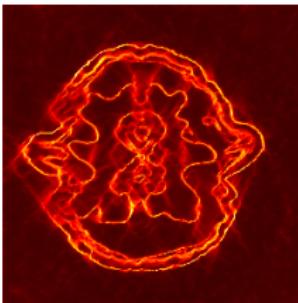


Recent Advances in Bayesian Inference for Inverse Problems

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cmic

Centre for Medical Image Computing

Applied Inverse Problems
Helsinki, May 25, 2015

Noisy, ill-posed inverse problems:

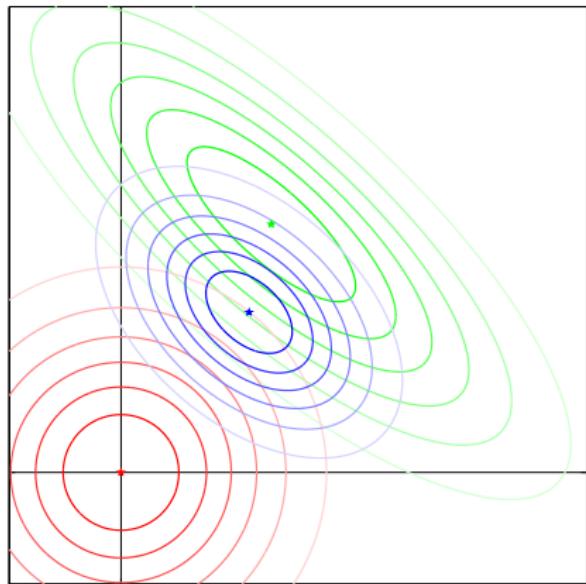
$$f = N(\mathcal{A}(u), \varepsilon)$$

Example: $f = Au + \varepsilon$

$$\begin{aligned} p_{\text{like}}(f|u) &\propto \\ &\exp\left(-\frac{1}{2}\|f - Au\|_{\Sigma_\varepsilon^{-1}}^2\right) \end{aligned}$$

$$\begin{aligned} p_{\text{prior}}(u) &\propto \\ &\exp(-\lambda \|D^T u\|_2^2) \end{aligned}$$

$$\begin{aligned} p_{\text{post}}(u|f) &\propto \\ &\exp\left(-\frac{1}{2}\|f - Au\|_{\Sigma_\varepsilon^{-1}}^2 - \lambda \|D^T u\|_2^2\right) \end{aligned}$$



Probabilistic representation of solution allows for a rigorous **quantification of its uncertainties**.



Inverse problems in the Bayesian framework
edited by Daniela Calvetti, Jari P Kaipio and Erkki
Somersalo.
Special issue of *Inverse Problems*, November 2014.

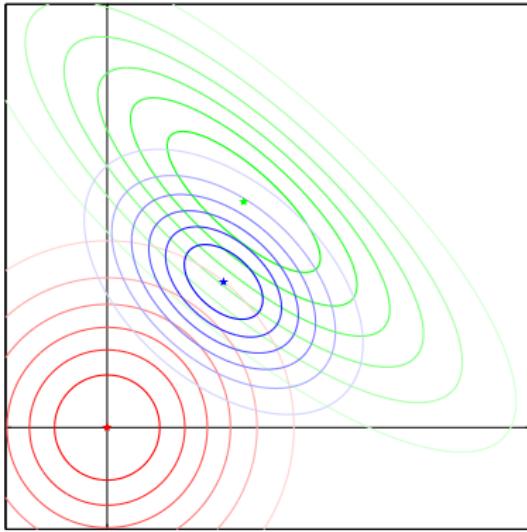


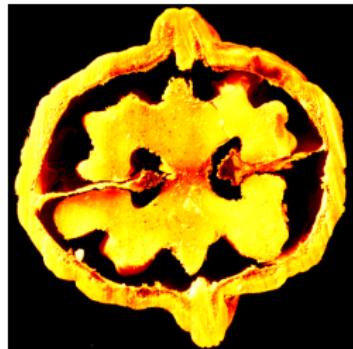
UQ and a Model Inverse Problem
Marco Iglesias and Andrew M. Stuart
SIAM News, July/August 2014.

Advantageous for high uncertainties:

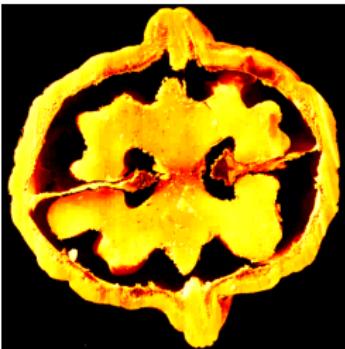
- ▶ Strongly non-linear problems.
- ▶ Severely ill-posed problems.
- ▶ Little analytical structure
- ▶ Additional model uncertainties.

- ▶ Uncertainty quantification of inverse solutions.
- ▶ Dynamic Bayesian inversion for prediction or control of dynamical systems
- ▶ Infinite dimensional Bayesian inversion.
 - ~~ M26: "Theoretical perspectives in Bayesian inverse problems"
- ▶ Incorporating model uncertainties.
- ▶ New ways of encoding a-priori information.
 - ~~ "M29: Priors and SPDEs"
- ▶ Large-scale posterior sampling techniques.
 - ~~ M23: "Sampling methods for high dimensional Bayesian inverse problems"

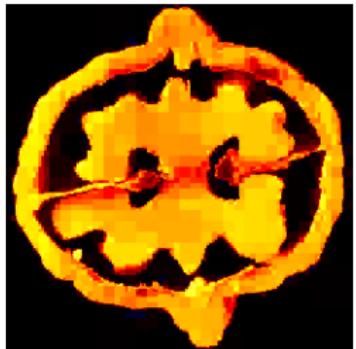




(a) 100%



(b) 10%

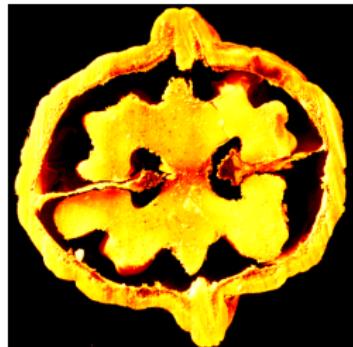


(c) 1%

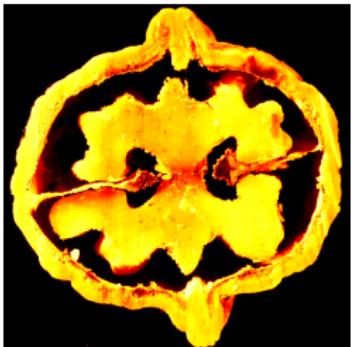
Sparsity a-priori constraints are used in variational regularization, compressed sensing and ridge regression:

$$\hat{u}_\lambda = \underset{u}{\operatorname{argmin}} \left\{ \frac{1}{2} \|f - Au\|_2^2 + \lambda \|D^T u\|_1 \right\}$$

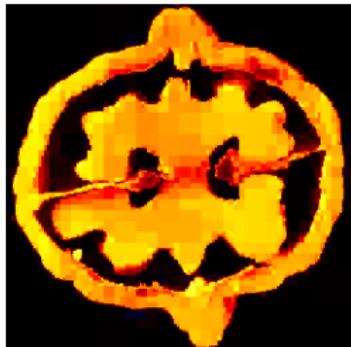
(e.g. *total variation, wavelet shrinkage, LASSO,...*)



(a) 100%



(b) 10%



(c) 1%

Sparsity a-priori constraints are used in variational regularization, compressed sensing and ridge regression:

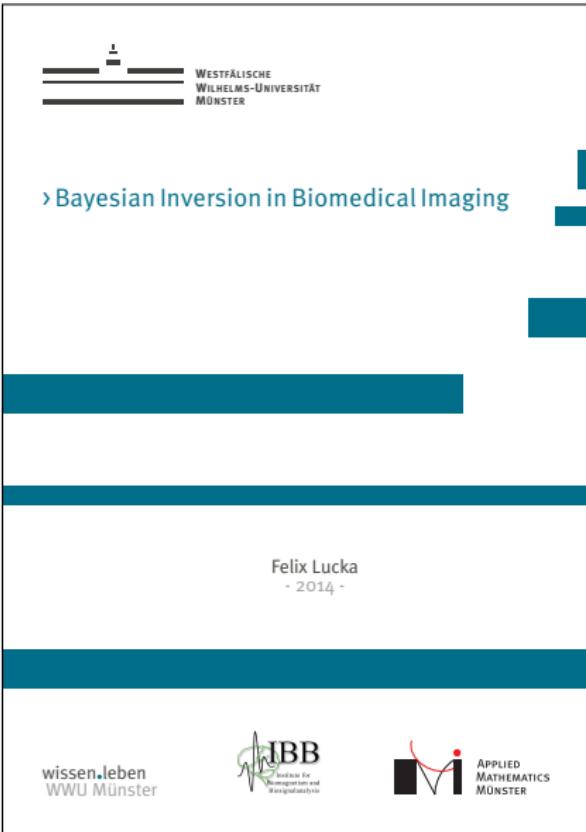
$$\hat{u}_\lambda = \underset{u}{\operatorname{argmin}} \left\{ \frac{1}{2} \|f - Au\|_2^2 + \lambda \|D^T u\|_1 \right\}$$

(e.g. *total variation*, *wavelet shrinkage*, *LASSO*,...)

How about sparsity as a-priori information in the Bayesian approach?

- ▶ Submitted 2014, supervised by Martin Burger and Carsten H. Wolters.
- ▶ Linear inverse problems in biomedical imaging applications.
- ▶ Simulated data scenarios and experimental CT and EEG/MEG data.
- ▶ Sparsity by means of
 - ▶ ℓ_p -norm based priors
 - ▶ Hierarchical prior modeling
- ▶ Focus on computation and application.

Here: Results for ℓ_p -priors and CT.



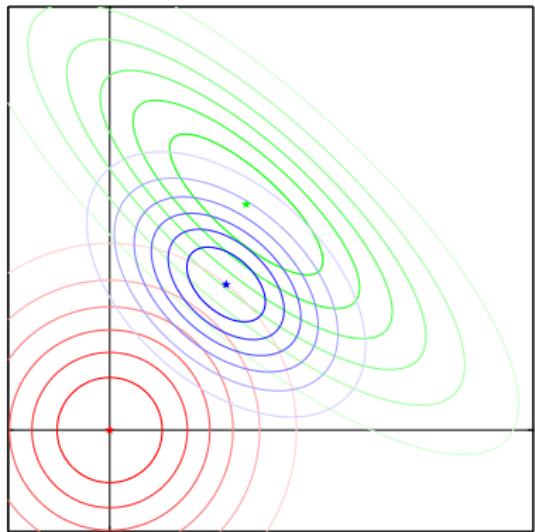
$$p_{prior}(u) \propto \exp\left(-\lambda \|D^T u\|_p^p\right), \quad p_{post}(u|f) \propto \exp\left(-\frac{1}{2}\|f - A u\|_{\Sigma_\varepsilon^{-1}}^2 - \lambda \|D^T u\|_p^p\right)$$

Decrease p from 2 to 0 and stop at $p = 1$ for convenience.

The ℓ_p Approach to Sparse Bayesian Inversion

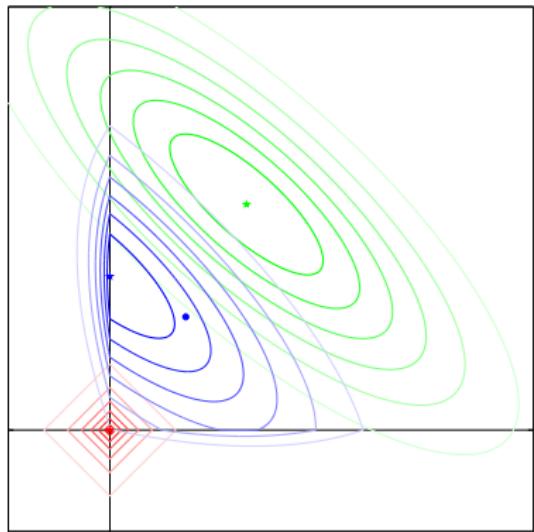
$$p_{prior}(u) \propto \exp\left(-\lambda \|D^T u\|_p^p\right), \quad p_{post}(u|f) \propto \exp\left(-\frac{1}{2}\|f - A u\|_{\Sigma_\varepsilon^{-1}}^2 - \lambda \|D^T u\|_p^p\right)$$

Decrease p from 2 to 0 and stop at $p = 1$ for convenience.



$$\exp\left(-\lambda \|D^T u\|_2^2\right)$$

$$\exp\left(-\frac{1}{2}\|f - A u\|_{\Sigma_\varepsilon^{-1}}^2 - \lambda \|D^T u\|_2^2\right)$$



$$\exp\left(-\lambda \|D^T u\|_1\right)$$

$$\exp\left(-\frac{1}{2}\|f - A u\|_{\Sigma_\varepsilon^{-1}}^2 - \lambda \|D^T u\|_1\right)$$

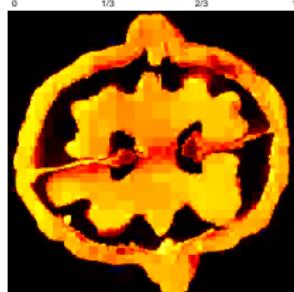
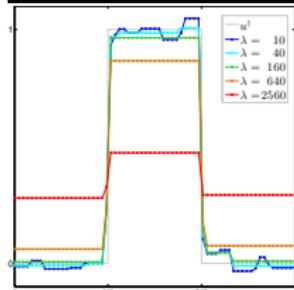
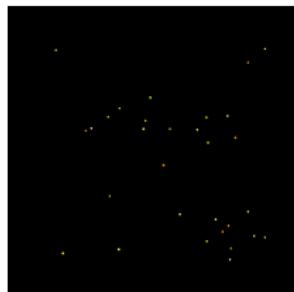
$$p_{post}(u|f) \propto \exp\left(-\frac{1}{2}\|f - A u\|_{\Sigma_\varepsilon^{-1}}^2 - \lambda \|D^T u\|_1\right)$$

Aims: Bayesian inversion in high dimensions ($n \rightarrow \infty$).

Priors: Simple ℓ_1 , total variation (TV), Besov space priors.

Starting points:

- ❑ M. Lassas, S. Siltanen, 2004. *Can one use total variation prior for edge-preserving Bayesian inversion?* *Inverse Problems*, 20.
- ❑ M. Lassas, E. Saksman, S. Siltanen, 2009. *Discretization invariant Bayesian inversion and Besov space priors.* *Inverse Problems and Imaging*, 3(1).
- ❑ V. Kolehmainen, M. Lassas, K. Niinimäki, S. Siltanen, 2012. *Sparsity-promoting Bayesian inversion* *Inverse Problems*, 28(2).



Task: Monte Carlo integration by samples from

$$p_{post}(u|f) \propto \exp\left(-\frac{1}{2}\|f - Au\|_{\Sigma_\varepsilon^{-1}}^2 - \lambda \|Du\|_1\right)$$

Problem: Standard Markov chain Monte Carlo (MCMC) sampler (Metropolis-Hastings) inefficient for large n or λ .

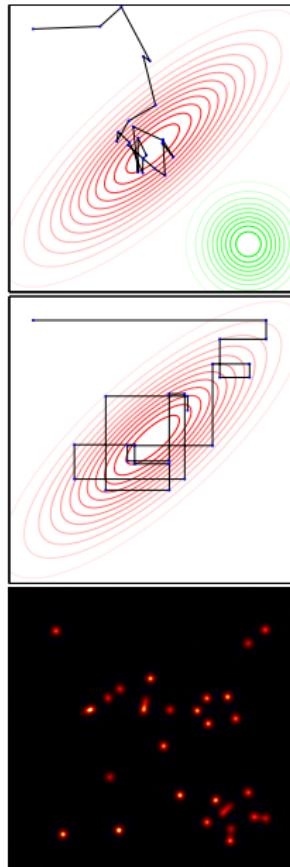
Contributions:

- ▶ Development of explicit single component Gibbs sampler.
- ▶ Tedious implementation for different scenarios.
- ▶ Still efficient in high dimensions ($n > 10^6$).
- ▶ Detailed evaluation and comparison to MH.



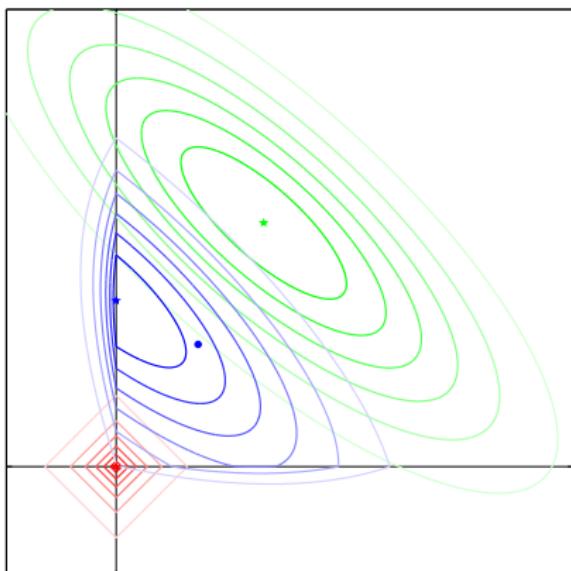
F.L., 2012. *Fast Markov chain Monte Carlo sampling for sparse Bayesian inference in high-dimensional inverse problems using L1-type priors.*

Inverse Problems, 28(12):125012.



$$\hat{u}_{\text{MAP}} := \underset{u \in \mathbb{R}^n}{\operatorname{argmax}} \{ p_{\text{post}}(u|f) \} \quad \text{vs.} \quad \hat{u}_{\text{CM}} := \int u \, p_{\text{post}}(u|f) \, du$$

- ▶ CM preferred in theory, dismissed in practice.
- ▶ MAP discredited by theory, chosen in practice.

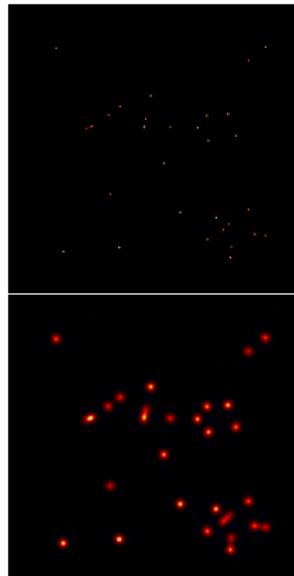
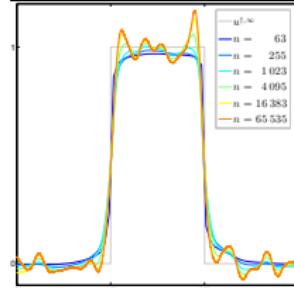
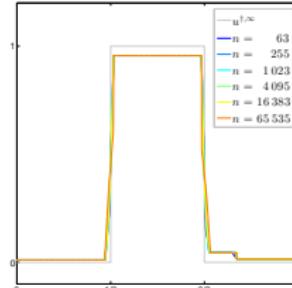
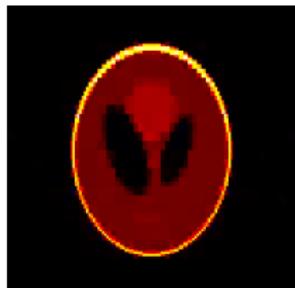


$$\hat{u}_{\text{MAP}} := \underset{u \in \mathbb{R}^n}{\operatorname{argmax}} \{ p_{\text{post}}(u|f) \} \quad \text{vs.} \quad \hat{u}_{\text{CM}} := \int u \, p_{\text{post}}(u|f) \, du$$

- ▶ CM preferred in theory, dismissed in practice.
- ▶ MAP discredited by theory, chosen in practice.

However:

- ▶ MAP results looks/perform better or similar to CM.
- ▶ Gaussian priors: $\text{MAP} = \text{CM}$. Funny coincidence?
- ▶ Theoretical argument has a logical flaw.



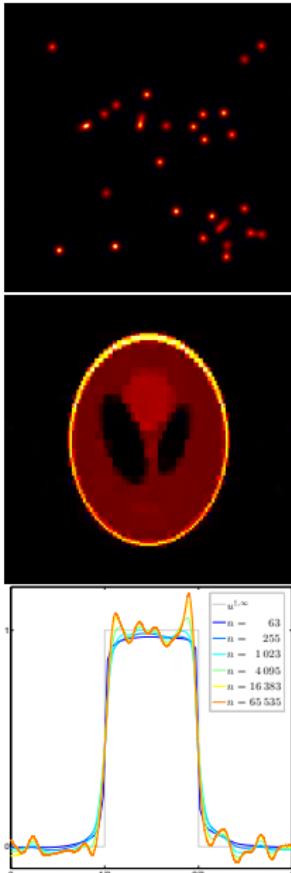
$$\hat{u}_{\text{MAP}} := \underset{u \in \mathbb{R}^n}{\operatorname{argmax}} \{ p_{post}(u|f) \} \quad \text{vs.} \quad \hat{u}_{\text{CM}} := \int u \, p_{post}(u|f) \, du$$

- ▶ CM preferred in theory, dismissed in practice.
- ▶ MAP discredited by theory, chosen in practice.

Contributions:

- ▶ Theoretical rehabilitation of MAP.
 - ▶ Key: Bayes cost functions based on Bregman distances.
 - ▶ Gaussian case consistent in this framework.
-  M. Burger, F.L., 2014. *Maximum a posteriori estimates in linear inverse problems with log-concave priors are proper Bayes estimators.*, *Inverse Problems*, 30(11):114004.
-  T. Helin, M. Burger, 2015. *Maximum a posteriori probability estimates in infinite-dimensional Bayesian inverse problems.*, *arXiv:1412.5816v2*

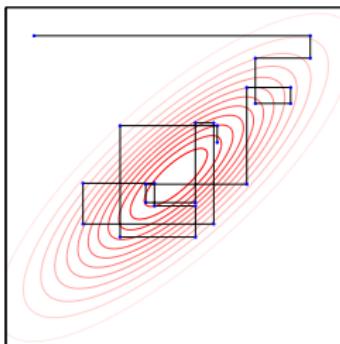
↝ Talk by Martin Burger in M40-III



$$p_{prior}(u) \propto \exp(-\lambda \|D^T u\|_1)$$

Limitations:

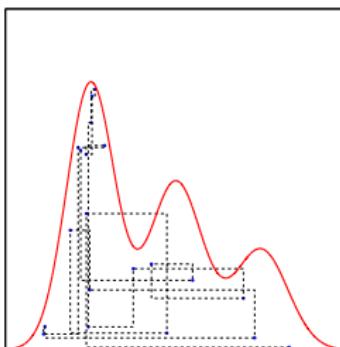
- ▶ D must be diagonalizable (synthesis priors):
- ▶ ℓ_p^q -prior: $\exp(-\lambda \|D^T u\|_p^q)$? TV in 2D/3D?
- ▶ Additional hard-constraints?



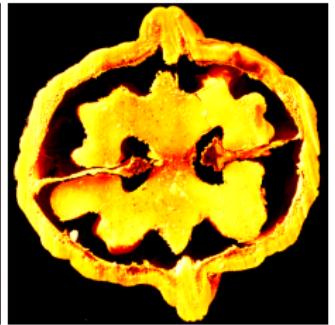
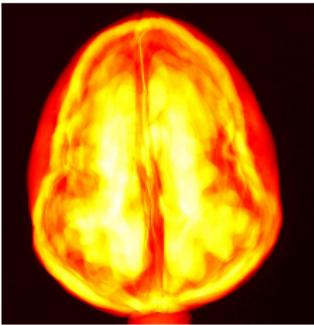
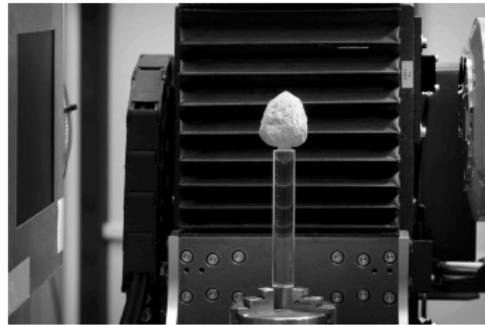
Contributions:

- ▶ Replace explicit by generalized slice sampling.
- ▶ Implementation & evaluation for most common priors.

-  R.M. Neal, 2003. *Slice Sampling*. *Annals of Statistics* 31(3)
-  F.L., 2015. *Fast Gibbs sampling for high-dimensional Bayesian inversion*. (in preparation)



- ▶ Cooperation with [Samuli Siltanen](#), [Esa Niemi](#) et al.
- ▶ Implementation of MCMC methods for [Fanbeam-CT](#).
- ▶ Besov and TV prior; non-negativity constraints.
- ▶ Stochastic [noise modeling](#).
- ▶ Bayesian perspective on [limited angle CT](#).



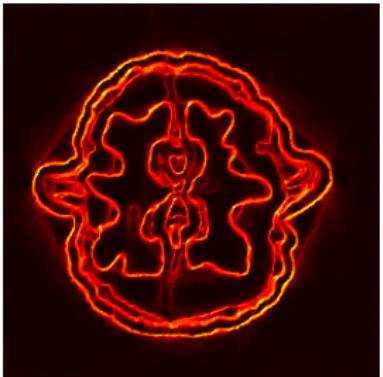
Walnut-CT with TV Prior: Full vs. Limited Angle



(a) MAP, full



(b) CM, full



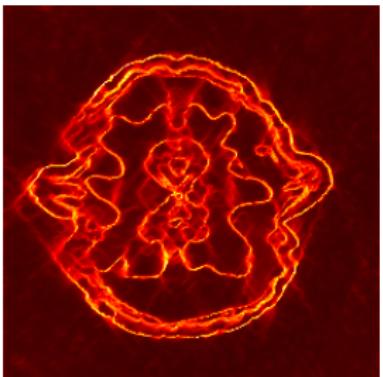
(c) CStd, full



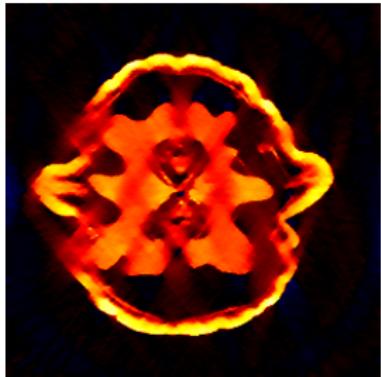
(d) MAP, limited



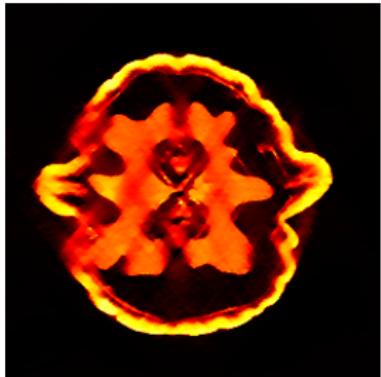
(e) CM, limited



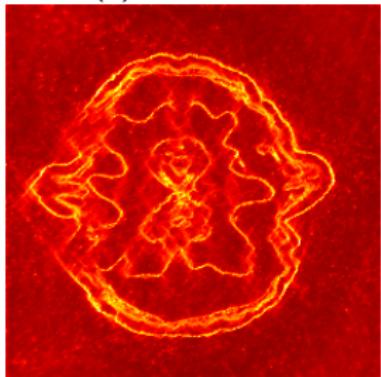
(f) CStd, limited



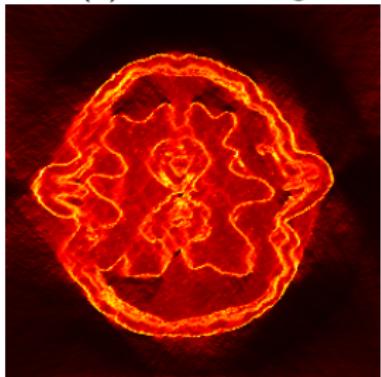
(a) CM, uncon



(b) CM, non-neg



(c) CStd, uncon



(d) CStd, non-neg

- ▶ Sparsity as a-priori information can be modeled in different ways.
- ▶ The elementary MCMC posterior samplers may show very different performance.
- ▶ Contrary to common beliefs they are not in general slow and scale bad with increasing dimension.
- ▶ Sample-based Bayesian inversion in high dimensions ($n > 10^6$) is feasible if tailored samplers are developed.
- ▶ MAP estimates are proper Bayes estimators.
- ▶ But "MAP or CM?" is NOT the key question in Bayesian inversion.
- ▶ Everything beyond point-estimates is far more interesting and can really complement variational approaches.

- ▶ Fast samplers can be used for simulated annealing.
- ▶ Reason for the efficiency of the Gibbs samplers is unclear.
- ▶ Adaptation, parallelization, multimodality, multi-grid.
- ▶ Combine ℓ_p -type and hierarchical priors: ℓ_p -hypermodels.
- ▶ Application studies had proof-of-concept character up to now.
- ▶ Specific UQ task to explore full potential of the Bayesian approach.

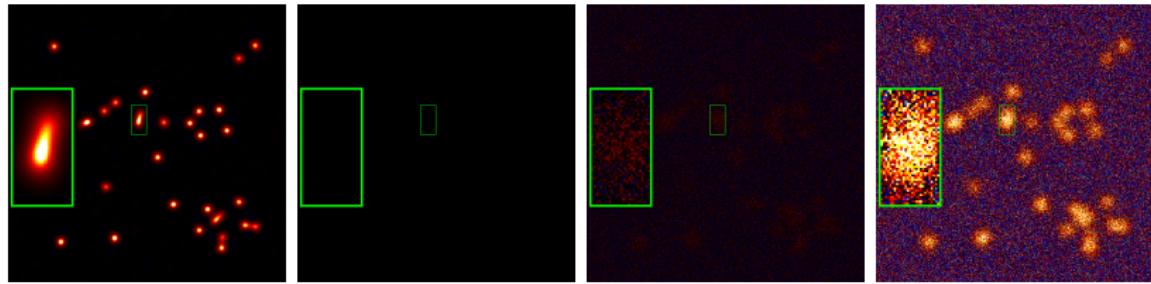
-  F.L., 2014. *Bayesian Inversion in Biomedical Imaging*
PhD Thesis, University of Münster.
-  M. Burger, F.L., 2014. Maximum a posteriori estimates in linear inverse problems with log-concave priors are proper Bayes estimators
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-  F.L., 2012. Fast Markov chain Monte Carlo sampling for sparse Bayesian inference in high-dimensional inverse problems using L1-type priors.
Inverse Problems, 28(12):125012.

Thank you for
your attention!

-  F.L., 2014. *Bayesian Inversion in Biomedical Imaging*
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-  M. Burger, F.L., 2014. Maximum a posteriori estimates in linear inverse problems with log-concave priors are proper Bayes estimators
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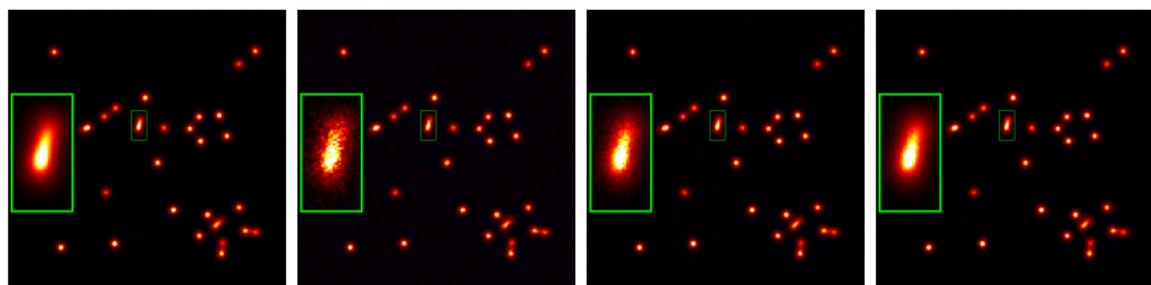


(a) Reference

(b) MH-Iso, 1h

(c) MH-Iso, 4h

(d) MH-Iso, 16h



(e) Reference

(f) SC Gibbs, 1h

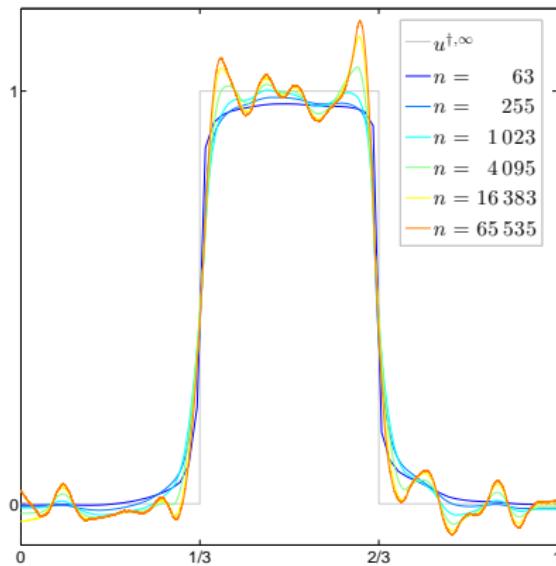
(g) SC Gibbs, 4h

(h) SC Gibbs, 16h

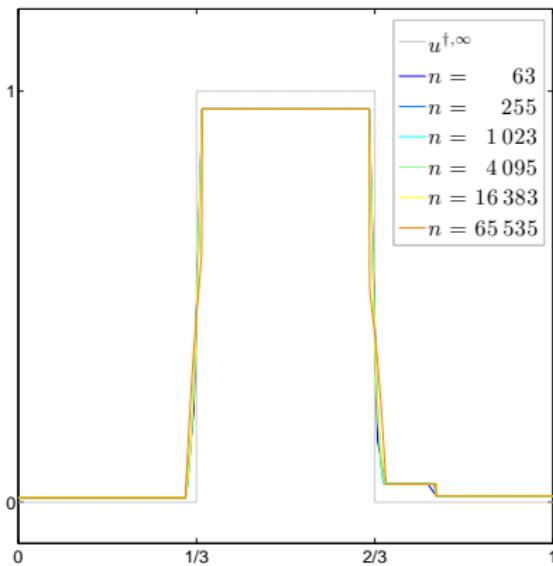
Deconvolution, simple ℓ_1 prior, $n = 513 \times 513 = 263\,169$.

Numerical verification of the discretization dilemma of the TV prior
(Lassas & Siltanen, 2004):

- ▶ For $\lambda_n = \text{const.}, n \rightarrow \infty$ the TV prior diverges.
- ▶ CM diverges.
- ▶ MAP converges to edge-preserving limit.



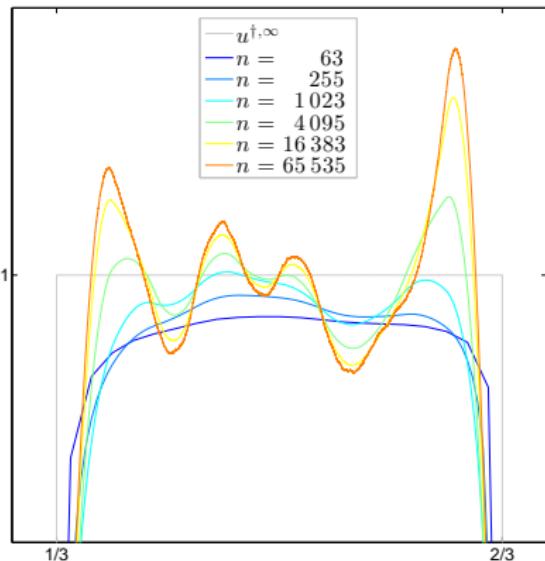
(a) CM by our Gibbs Sampler



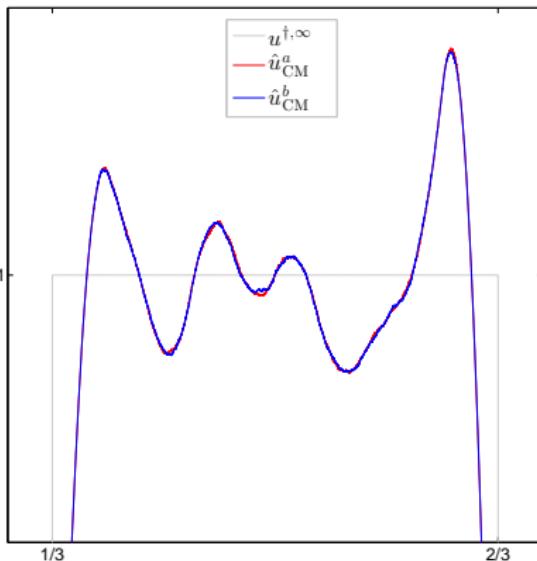
(b) MAP by ADMM

Numerical verification of the discretization dilemma of the TV prior
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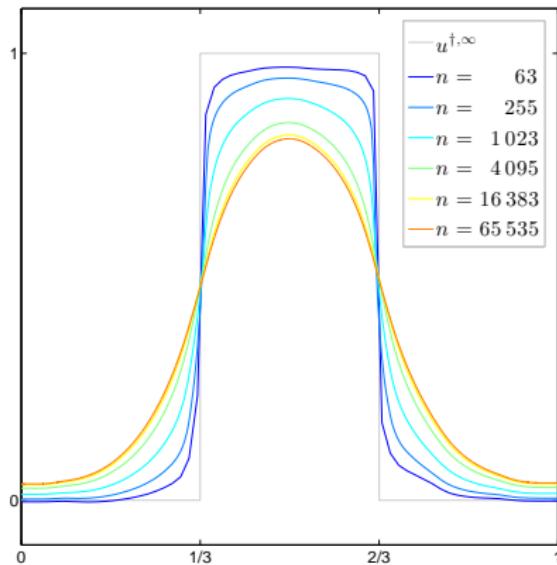
(a) Zoom into CM estimates



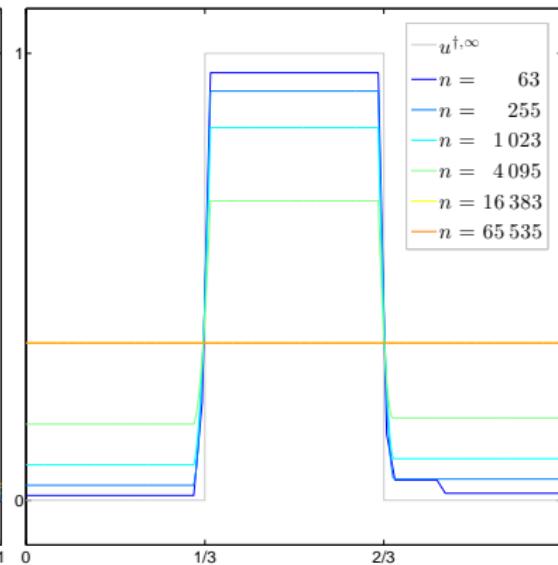
(b) MCMC convergence check

Numerical verification of the discretization dilemma of the TV prior
(Lassas & Siltanen, 2004):

- ▶ For $\lambda_n \propto \sqrt{n+1}$, $n \rightarrow \infty$ the TV prior converges to a smoothness prior.
- ▶ CM converges to smooth limit.
- ▶ MAP converges to constant.



(a) CM by our Gibbs Sampler

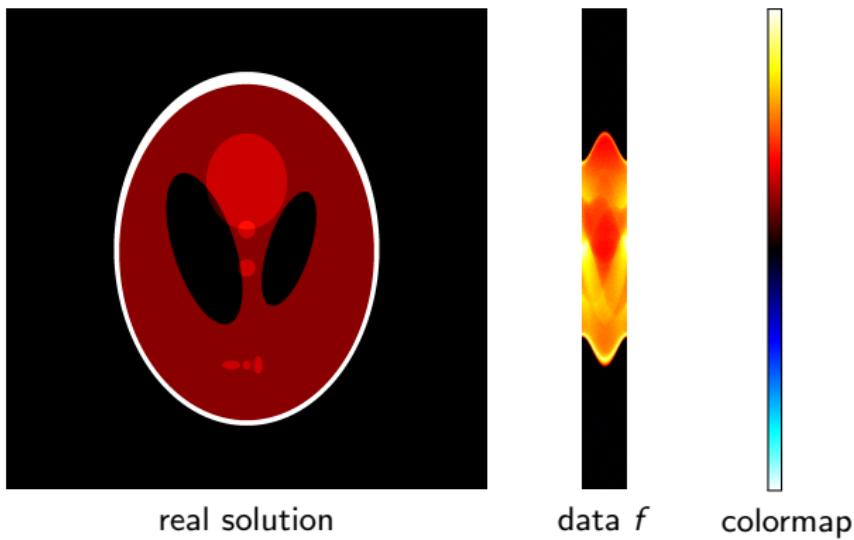


(b) MAP by ADMM

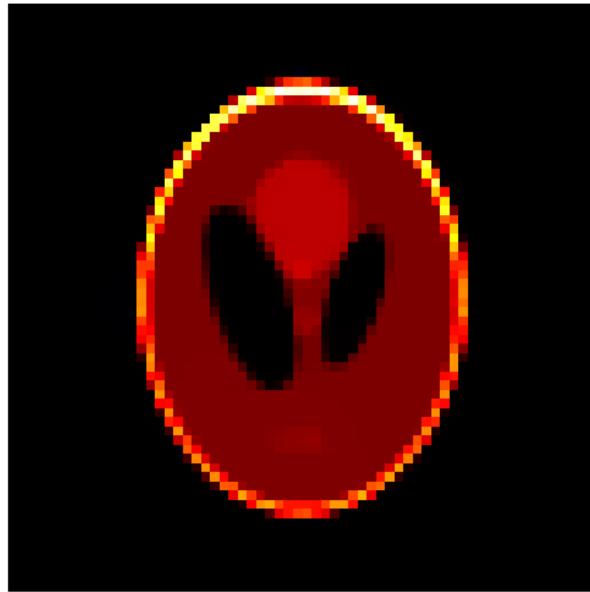
For images dimensions > 1 : No theory yet...but we can compute it.

Test scenario:

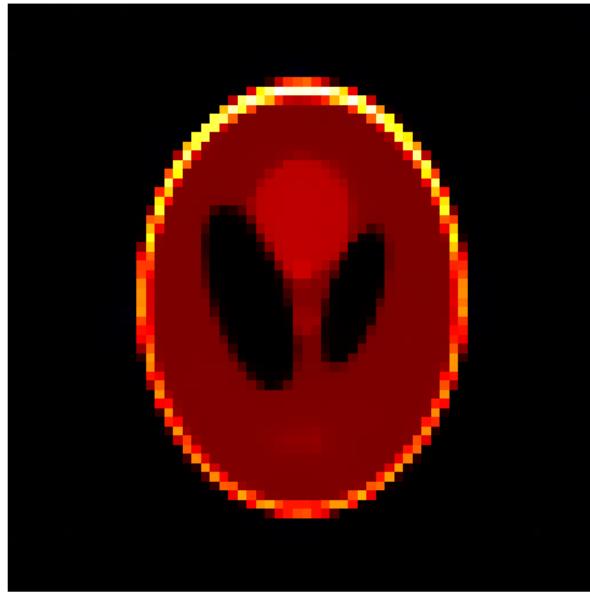
- ▶ CT using only 45 projection angles and 500 measurement pixel.



For images dimensions > 1 : No theory yet...but we can compute it.

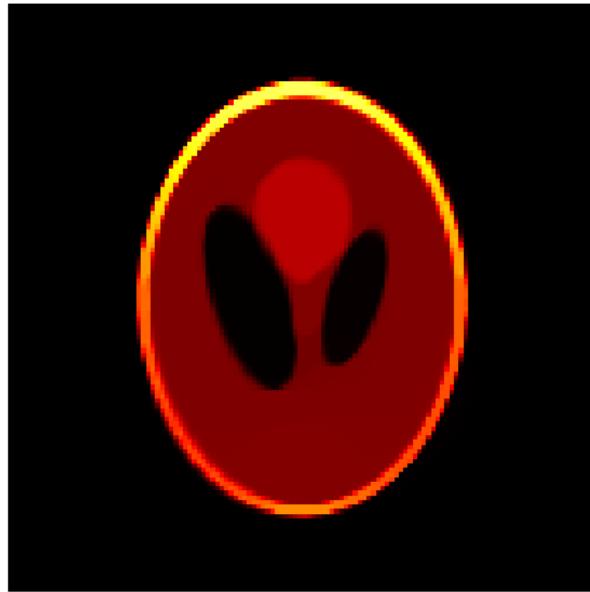


MAP, $n = 64^2$, $\lambda = 500$



CM, $n = 64^2$, $\lambda = 500$

For images dimensions > 1 : No theory yet...but we can compute it.

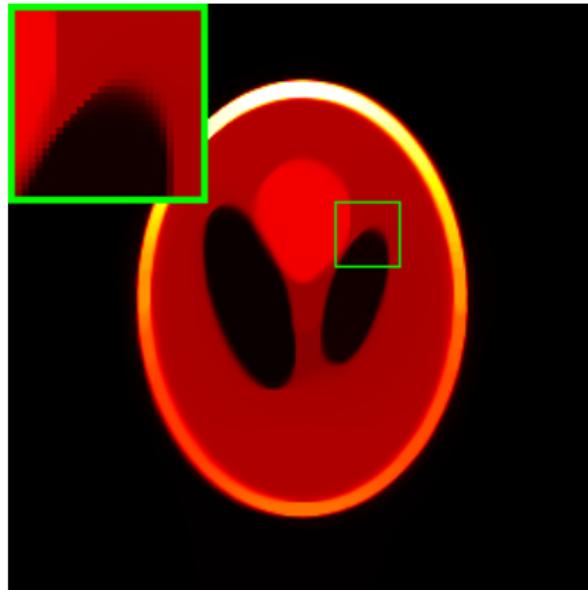


MAP, $n = 128^2$, $\lambda = 500$

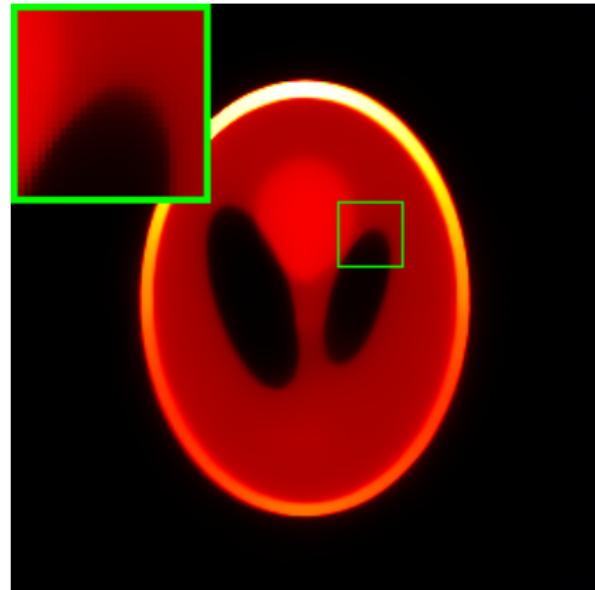


CM, $n = 128^2$, $\lambda = 500$

For images dimensions > 1 : No theory yet...but we can compute it.



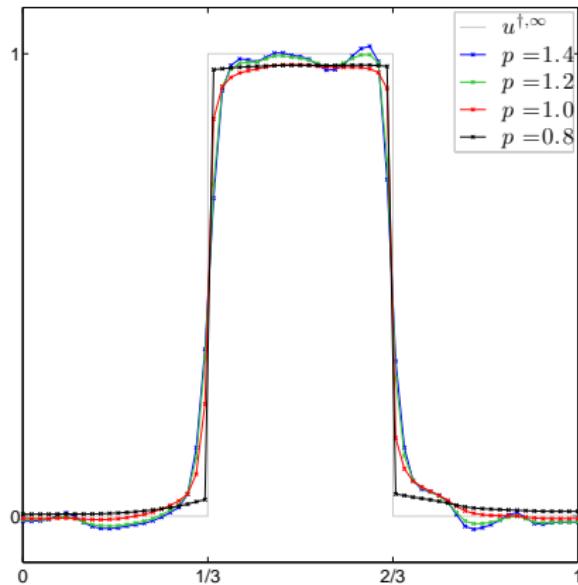
MAP, $n = 256^2$, $\lambda = 500$



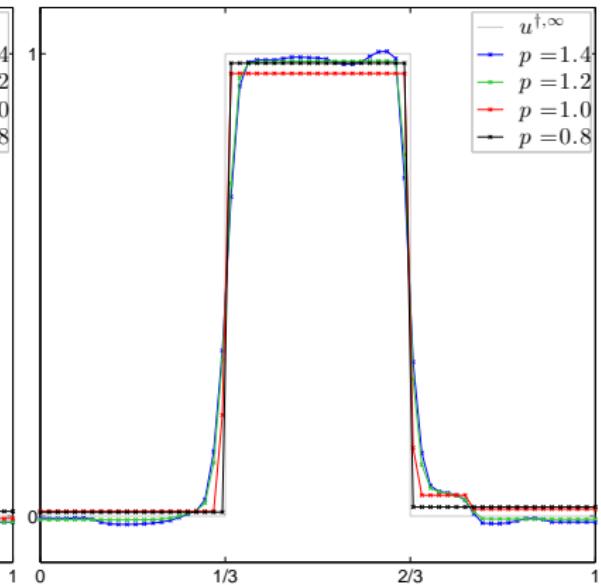
CM, $n = 256^2$, $\lambda = 500$

cf. Louchet, 2008, Louchet & Moisan, 2013 for the denoising case, $A = I$.

$$p_{post}(u) \propto \exp\left(-\frac{1}{2}\|f - Au\|_{\Sigma_\varepsilon^{-1}}^2 - \lambda \|D^T u\|_p^p\right)$$



(c) CM (Gibbs-MCMC)



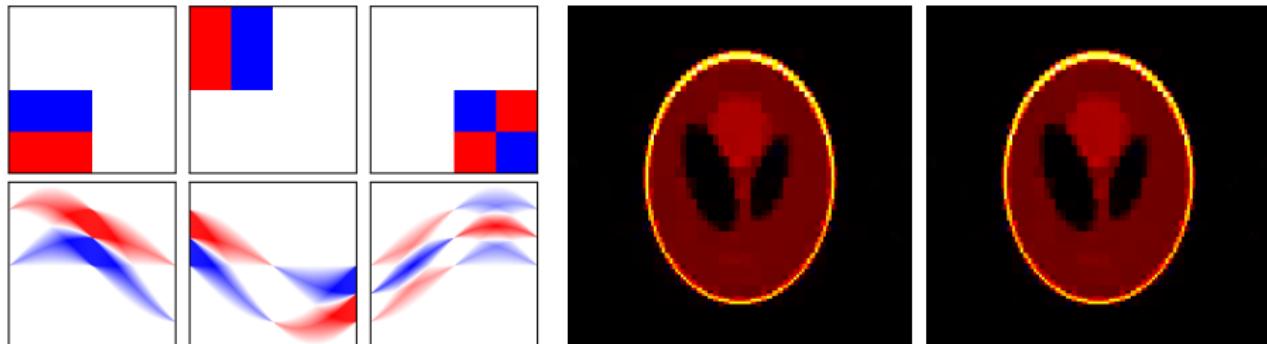
(d) MAP (Simulated Annealing)

An ℓ_1 -type, wavelet-based prior:

$$p_{prior}(u) \propto \exp(-\lambda \|WV^T u\|_1)$$

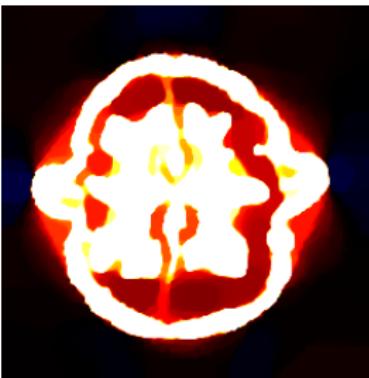
motivated by:

-  M. Lassas, E. Saksman, S. Siltanen, 2009. *Discretization invariant Bayesian inversion and Besov space priors.*, *Inverse Probl Imaging*, 3(1).
-  V. Kolehmainen, M. Lassas, K. Niinimäki, S. Siltanen, 2012. *Sparsity-promoting Bayesian inversion*, *Inverse Probl*, 28(2).
-  K. Hämäläinen, A. Kallonen, V. Kolehmainen, M. Lassas, K. Niinimäki, S. Siltanen, 2013. *Sparse Tomography*, *SIAM J Sci Comput*, 35(3).

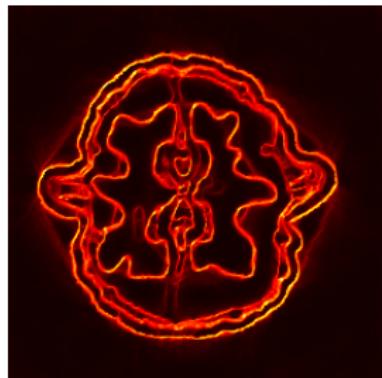




(a) MAP



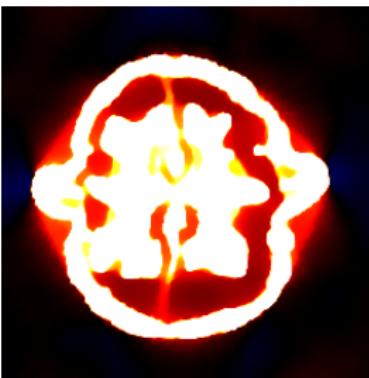
(b) MAP, special color scale



(c) CStd



(d) CM



(e) CM, special color scale



(f) CM of $\|\nabla u\|_2$