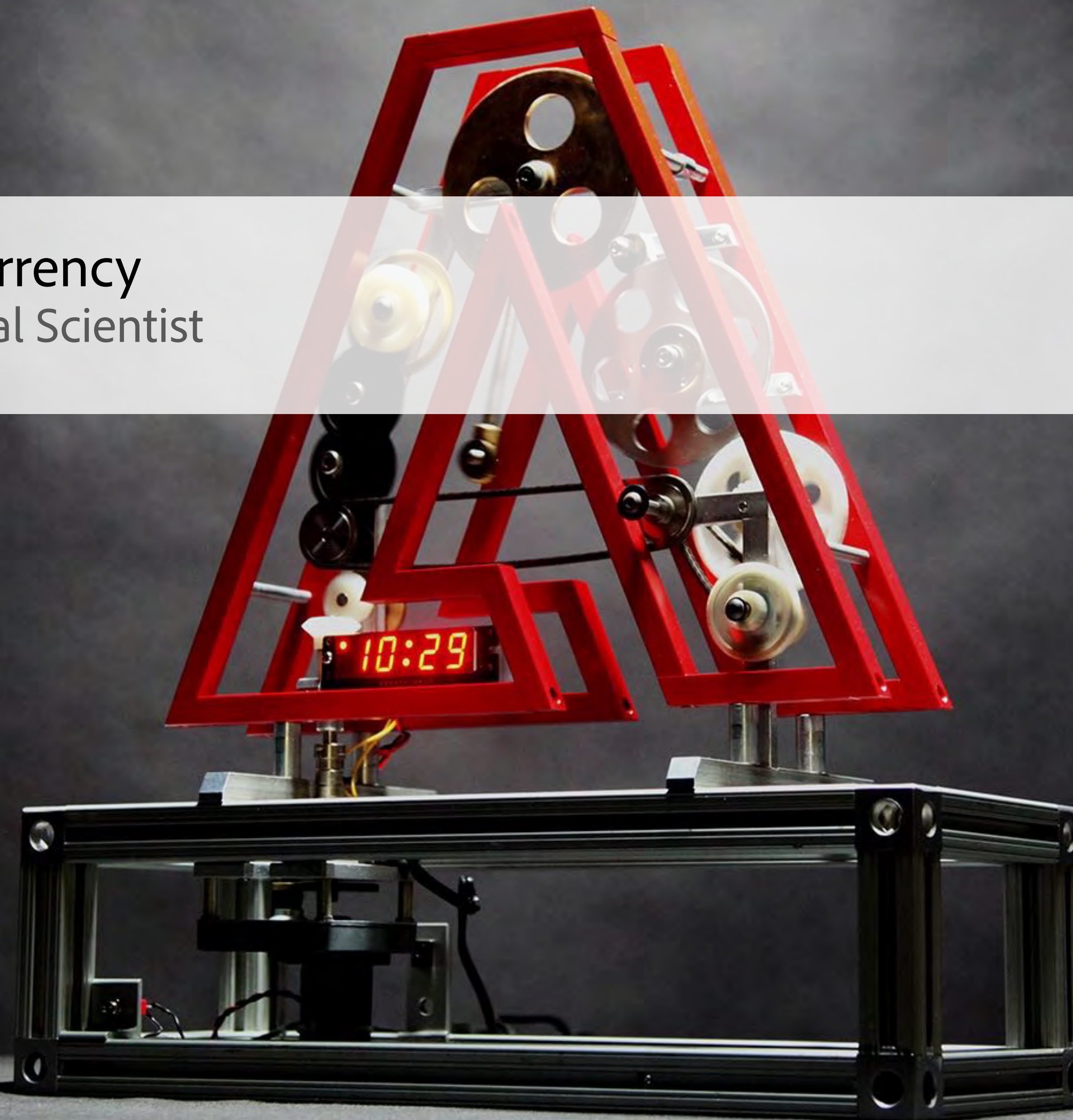




Better Code: Concurrency

Sean Parent | Principal Scientist



- Regular Type
 - Goal: Implement Complete and Efficient Types
- Algorithms
 - Goal: No Raw Loops
- Data Structures
 - Goal: No Incidental Data Structures
- Runtime Polymorphism
 - Goal: No Inheritance
- Concurrency
 - Goal: No Raw Synchronization Primitives
- ...

- Regular Type
 - Goal: Implement Complete and Efficient Types
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Common Themes

- Manage Relationships
- Understand the Fundamentals
- Code Simply




lightroom.adobe.com

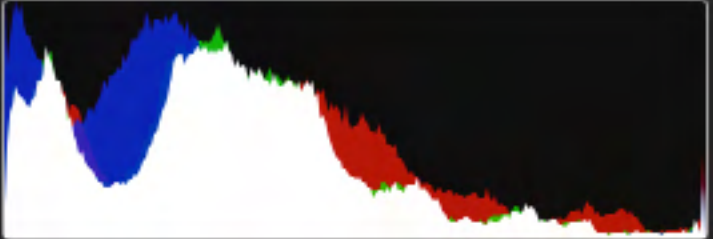
Revert to OriginalUndo Edits

Save & Exit

CROP PRESETS ADJUST



HISTOGRAM



TREATMENT

Color | Black & White

WHITE BALANCE

TONE

Auto

Exposure

Contrast

Highlights

Shadows

Whites

Blacks

PRESENCE

Clarity

Vibrance

Saturation

COLOR / B&W

SPLIT TONING

- Concurrency: when tasks start, run, and complete in overlapping time periods
- Parallelism: when two or more tasks execute simultaneously
- Why?
 - Enable performance through parallelism
 - Improve interactivity by handling user actions concurrent with processing and IO

Goal: No Raw Synchronization Primitives

What are raw synchronization primitives?

- Synchronization primitives are basic constructs such as:
 - Mutex
 - Atomic
 - Semaphore
 - Memory Fence
 - Condition Variable

You Will Likely Get It Wrong

Problems with Locks

```
template <typename T>
class bad_cow {
    struct object_t {
        explicit object_t(const T& x) : data_m(x) { ++count_m; }
        atomic<int> count_m;
        T data_m; };
    object_t* object_m;
public:
    explicit bad_cow(const T& x) : object_m(new object_t(x)) { }
    ~bad_cow() { if (0 == --object_m->count_m) delete object_m; }
    bad_cow(const bad_cow& x) : object_m(x.object_m) { ++object_m->count_m; }

    bad_cow& operator=(const T& x) {
        if (object_m->count_m == 1) object_m->data_m = x;
        else {
            object_t* tmp = new object_t(x);
            --object_m->count_m;
            object_m = tmp;
        }
        return *this;
    }
};
```

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            object_t* tmp = new object_t(x);
            --object_m->count_m;
            object_m = tmp;
        }
        return *this;
    }
};
```

- There is a subtle race condition here:
- if count != 1 then the bad_cow could also be owned by another thread(s)
- if the other thread(s) releases the bad_cow between these two atomic operations
- then our count will fall to zero and we will leak the object

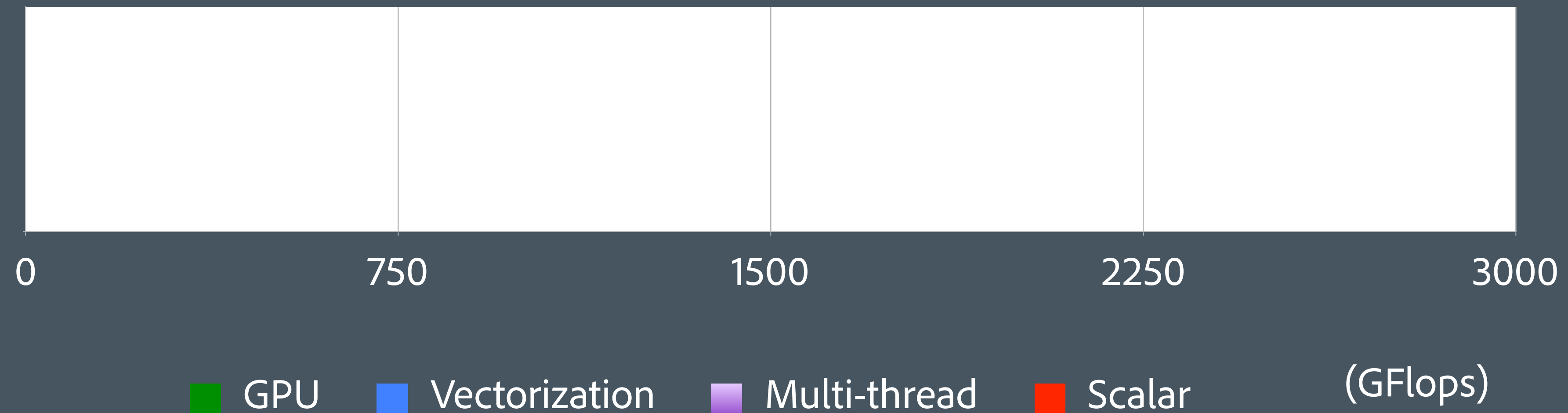
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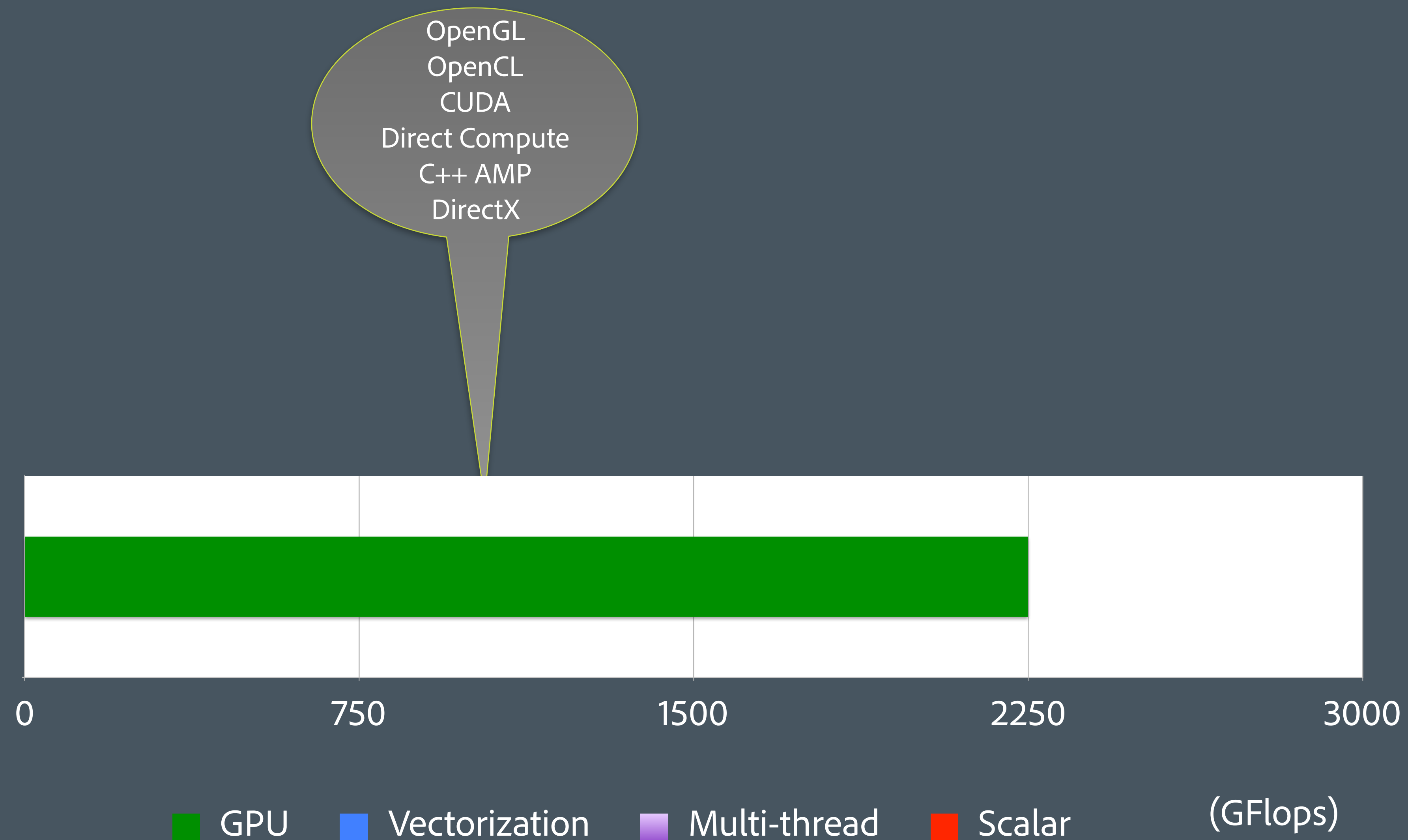
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```


Performance through Parallelism

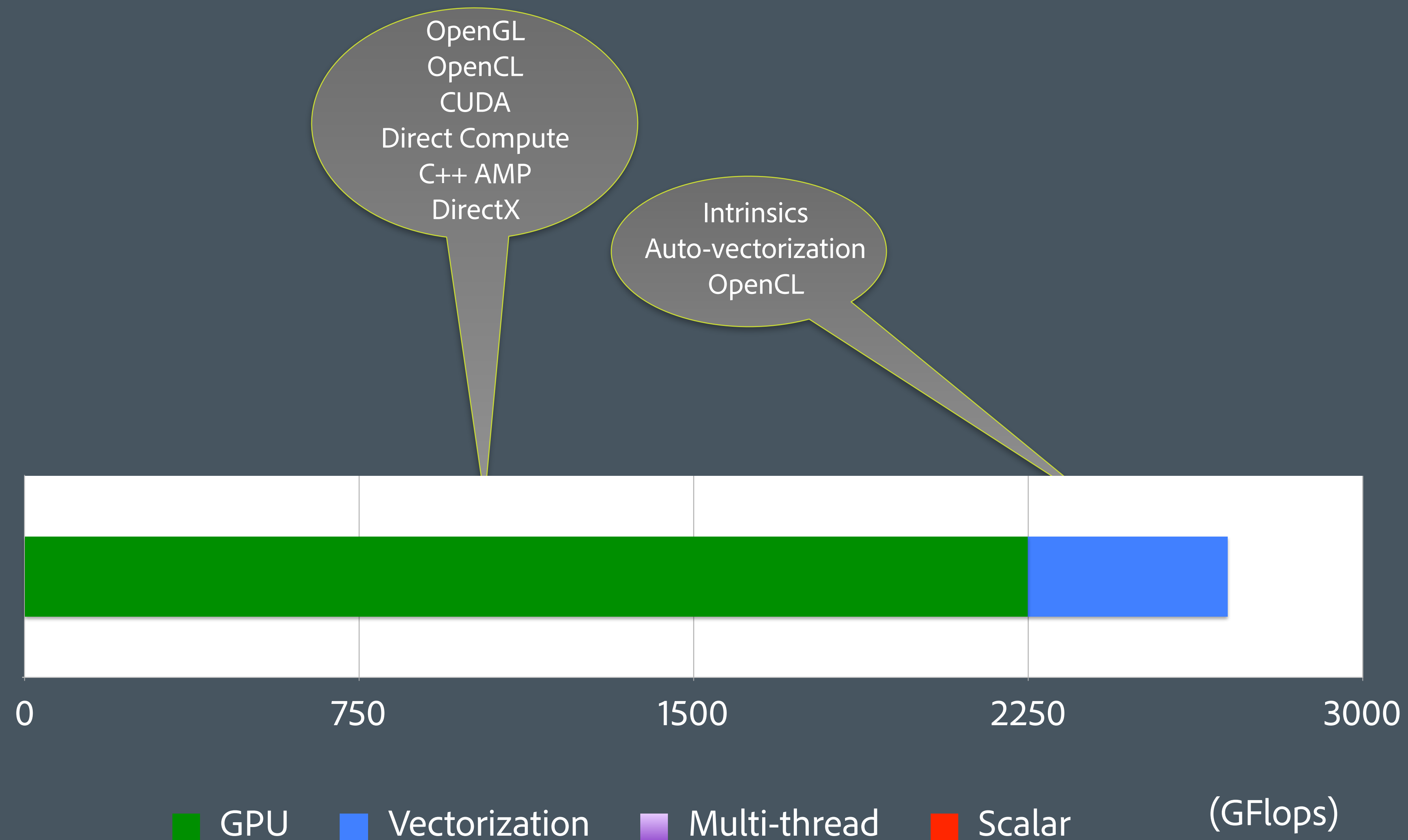
Desktop Compute Power (8-core 3.5GHz Sandy Bridge + AMD Radeon 6950)



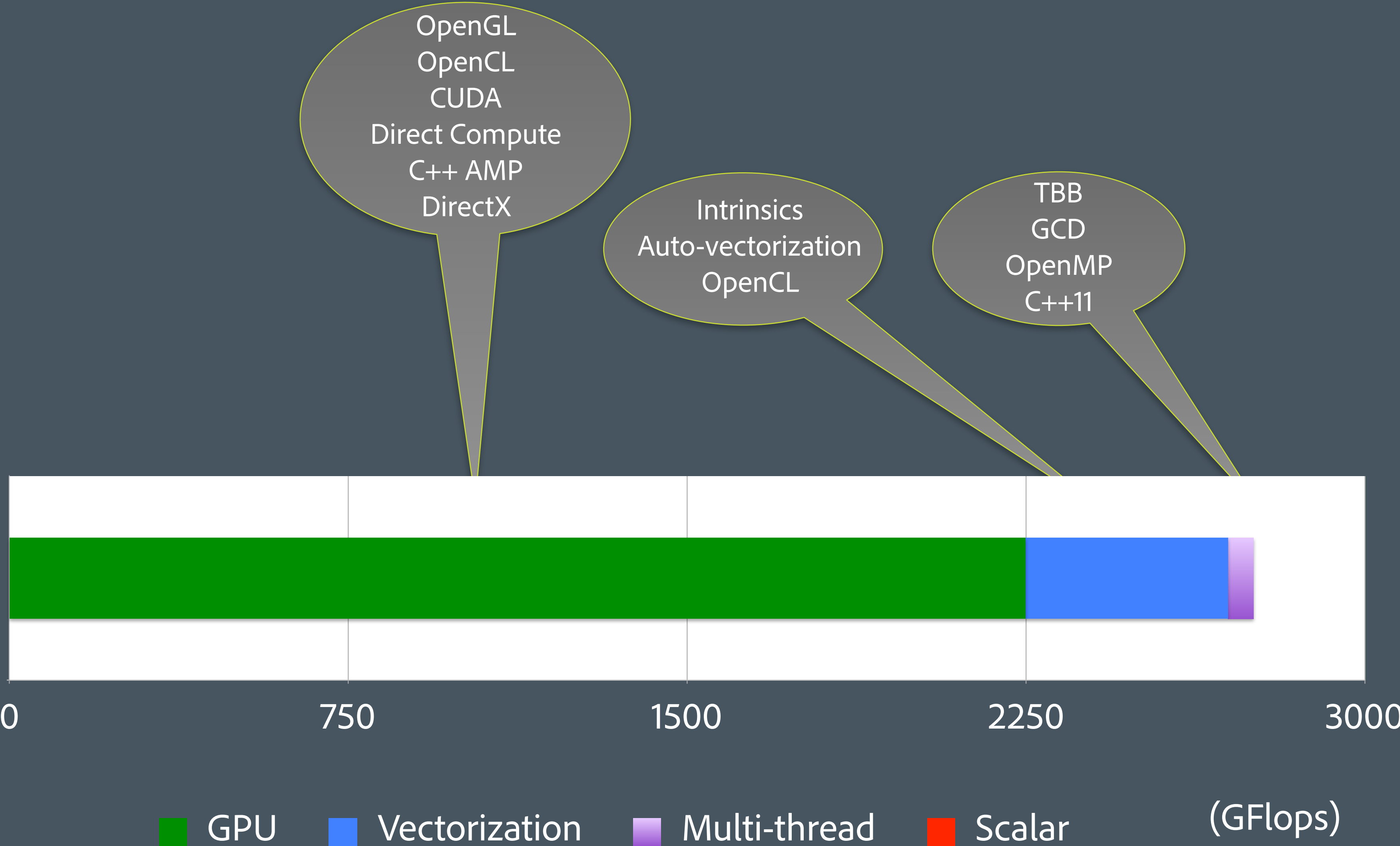
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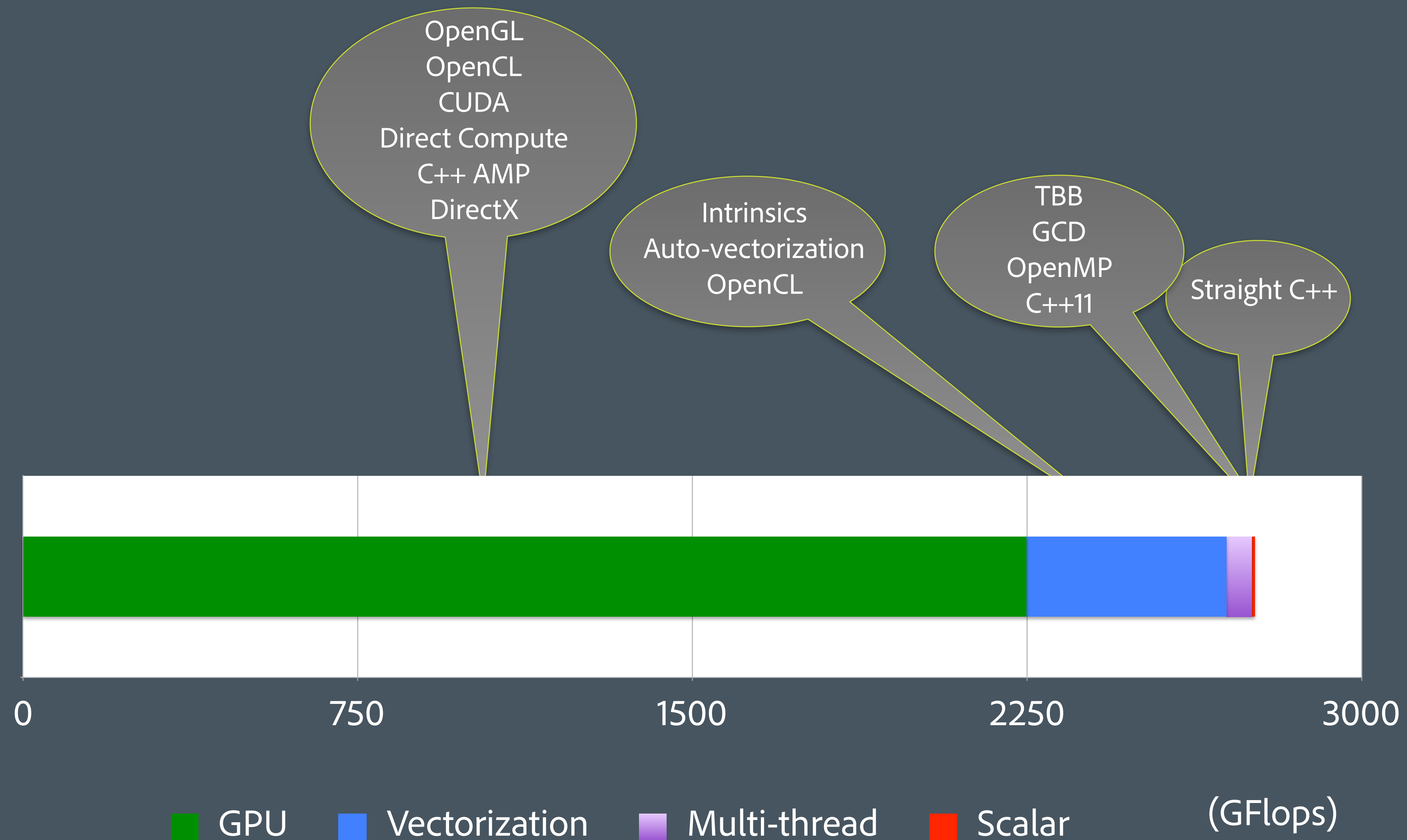
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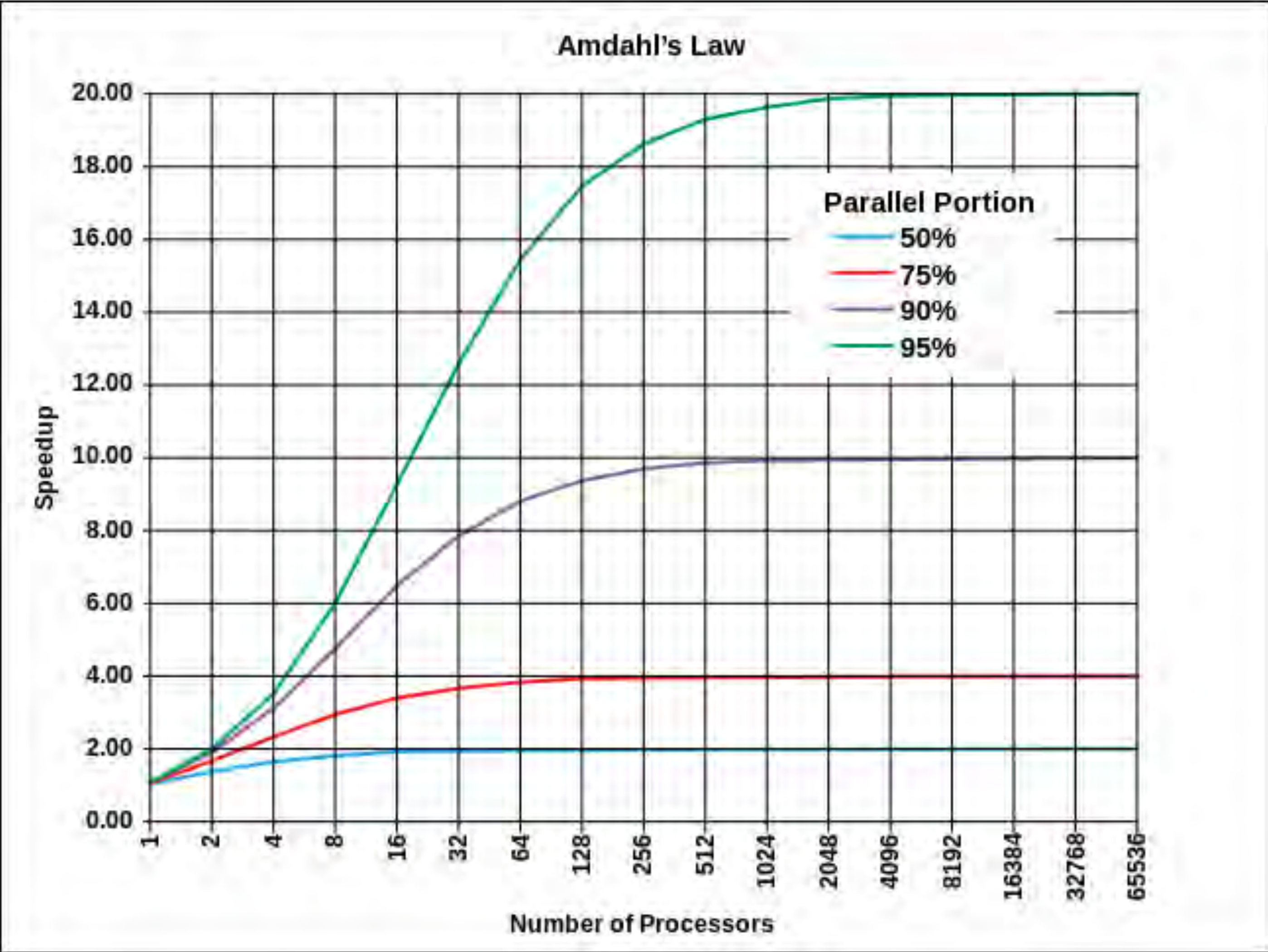


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Amdahl's Law

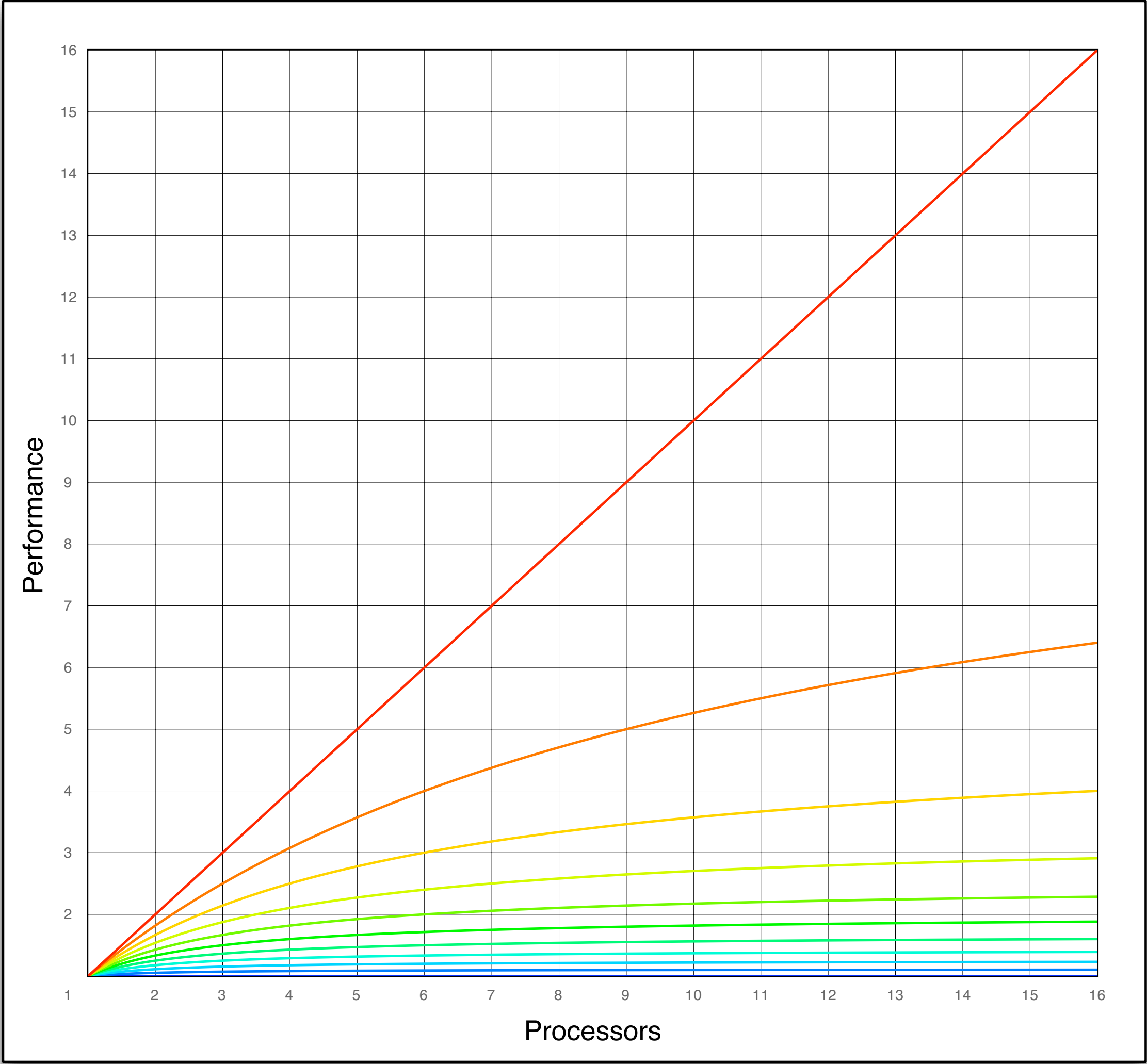
$$S(N) = \frac{1}{(1 - P) + \frac{P}{N}}$$



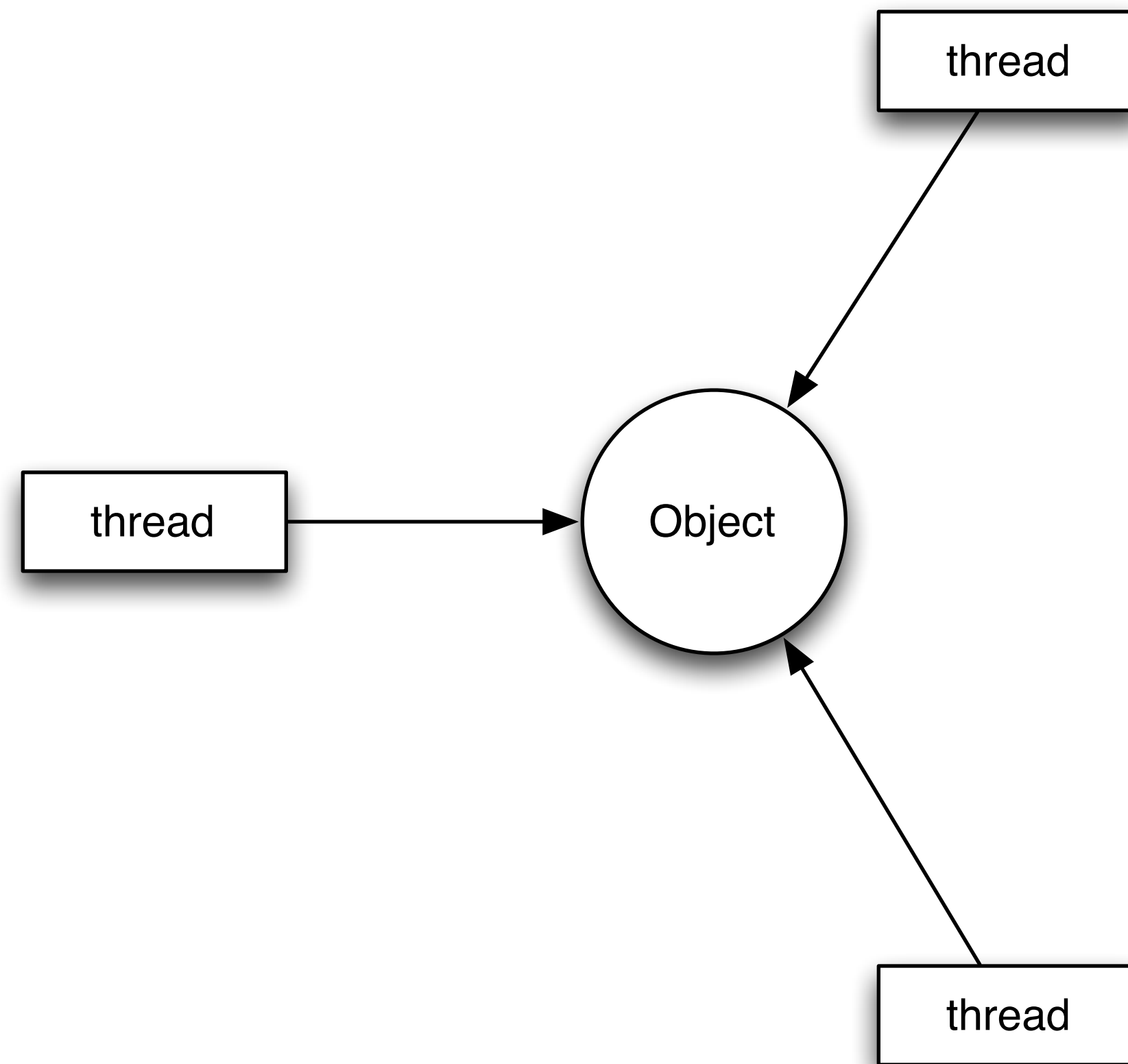
http://en.wikipedia.org/wiki/Amdahl%27s_law

Amdahl's Law

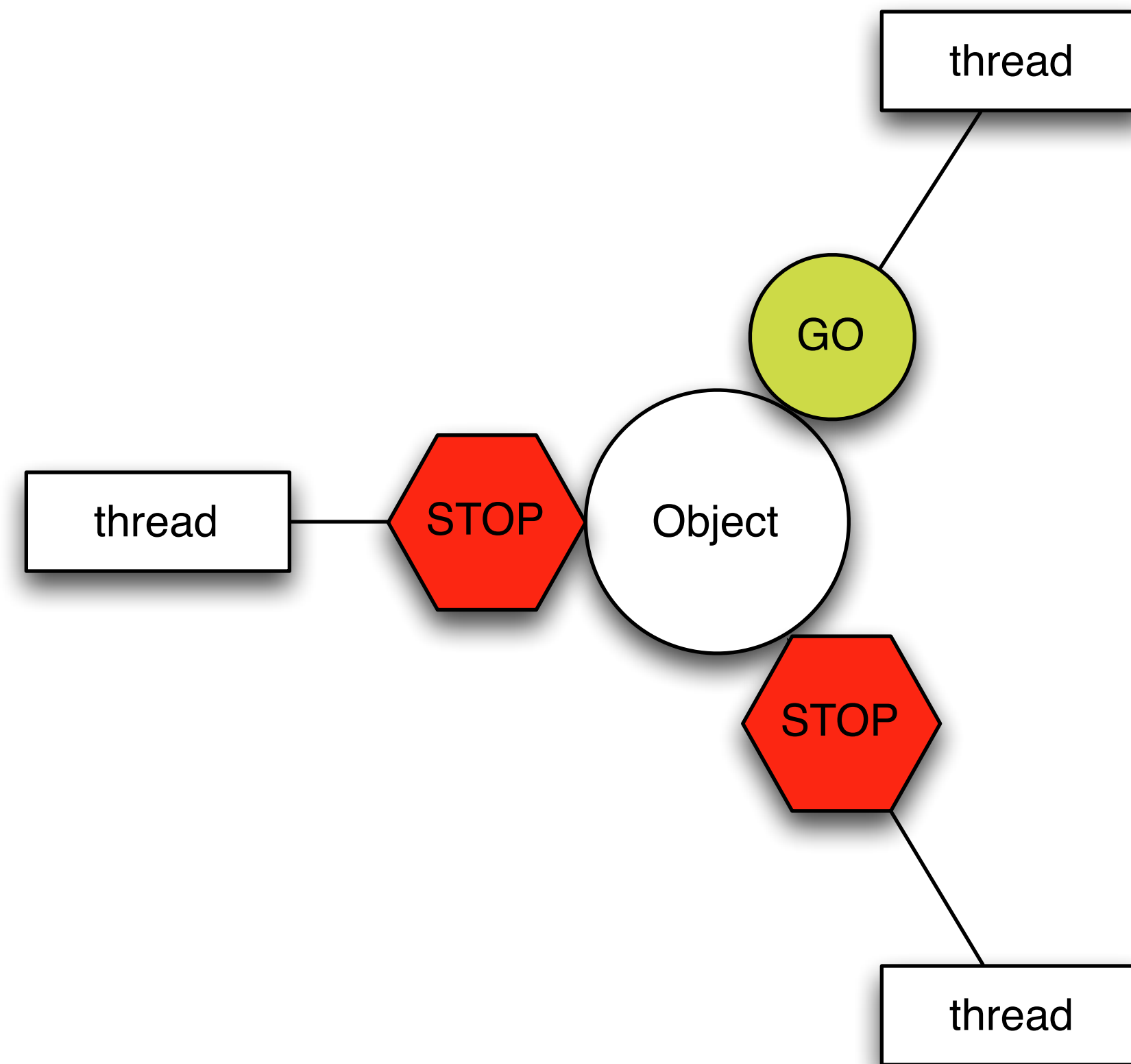
Each line represents 10% more
synchronization



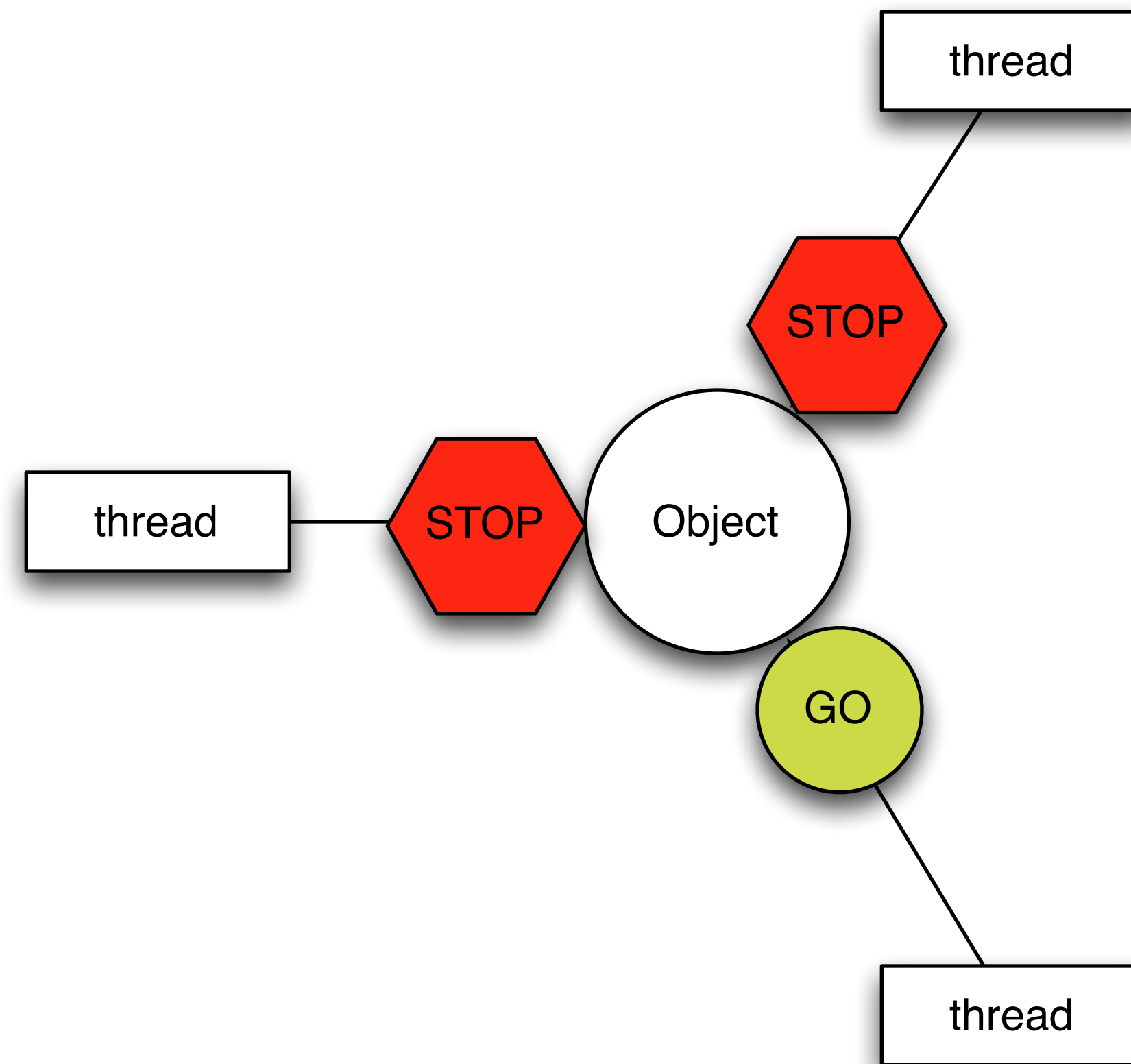
Why No Raw Synchronization Primitives?



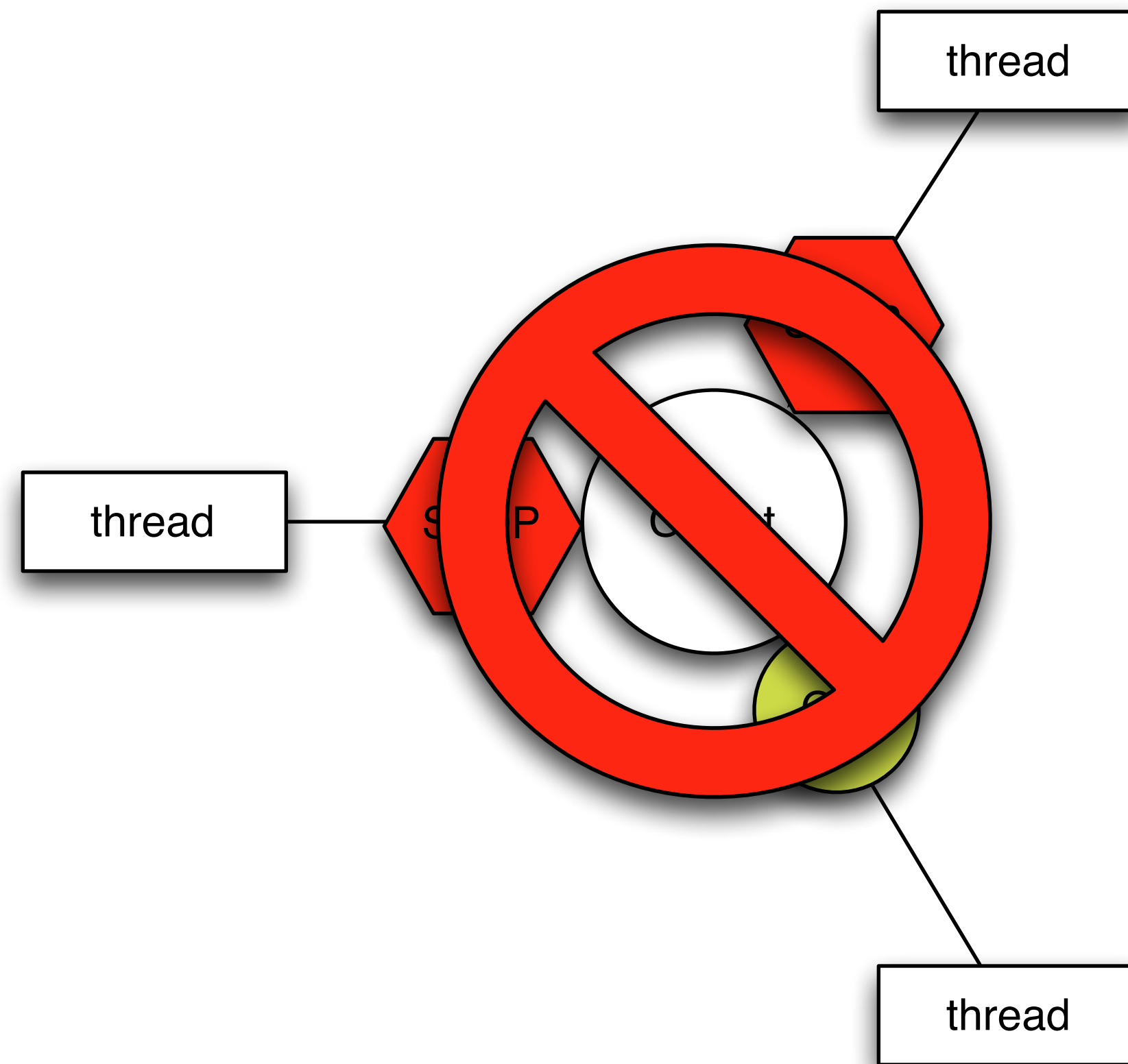
Why No Raw Synchronization Primitives?



Why No Raw Synchronization Primitives?



Why No Raw Synchronization Primitives?





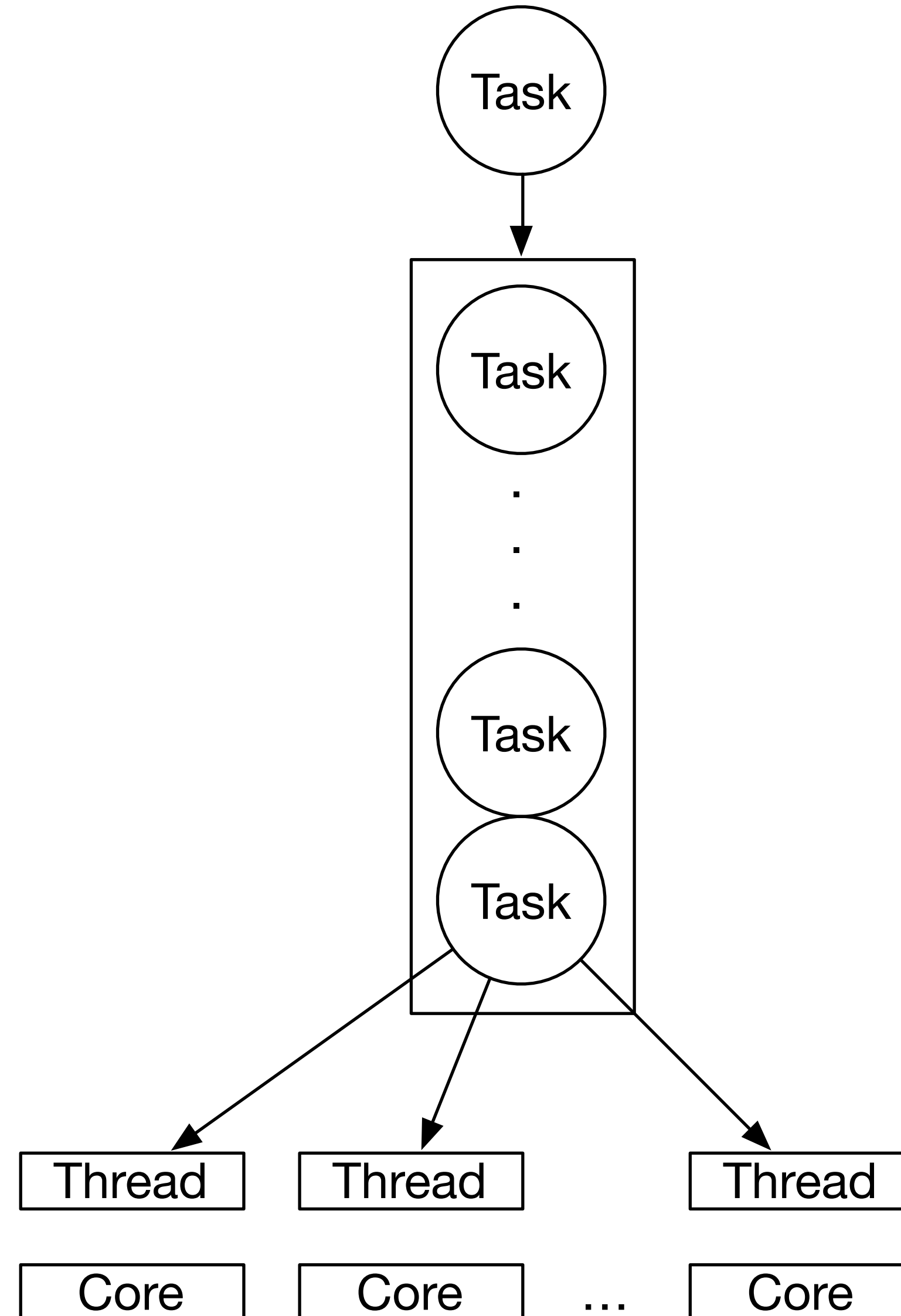


- Thread: Execution environment consisting of a stack and processor state running in parallel to other threads
- Task: A unit of work, often a function, to be executed on a thread
- Tasks are scheduled on a thread pool to optimize machine utilization

- C++14 does not (really) have a task system
 - Threads
 - Futures
- It is implementation defined if `std::async()` spins up a thread or executes on a thread pool.

- Portable Reference Implementation in C++14
- Windows - Window Thread Pool and PPL
- Apple - Grand Central Dispatch (libdispatch)
 - open source, runs on Linux and Android
- Intel TBB - many platforms
 - open source
- HPX - many platforms
 - open source

Building a Task System



<http://docs.oracle.com/cd/E19253-01/816-5137/ggedn/index.html>

Building a Task System

```
using lock_t = unique_lock<mutex>;
```


Building a Task System

```
using lock_t = unique_lock<mutex>;  
  
class notification_queue {  
    deque<function<void()>> _q;  
    mutex _mutex;  
    condition_variable _ready;
```

Building a Task System

```
using lock_t = unique_lock<mutex>;

class notification_queue {
    deque<function<void()>> _q;
    mutex _mutex;
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public:
    void pop(function<void()>& x) {
        lock_t lock{_mutex};
        while (_q.empty()) _ready.wait(lock);
        x = move(_q.front());
        _q.pop_front();
    }
}
```

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    }

    template<typename F>
    void push(F&& f) {
        {
            lock_t lock{_mutex};
            _q.emplace_back(forward<F>(f));
        }
        _ready.notify_one();
    }
};
```


Building a Task System

```
class task_system {  
    const unsigned  
    vector<thread>  
    notification_queue  
    _count{thread::hardware_concurrency()};  
    _threads;  
    _q;
```


Building a Task System

```
class task_system {  
    const unsigned          _count{thread::hardware_concurrency()};  
    vector<thread>          _threads;  
    notification_queue      _q;  
  
    void run(unsigned i) {  
        while (true) {  
            function<void()> f;  
            _q.pop(f);  
            f();  
        }  
    }  
}
```

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            _q.pop(f);
            f();
        }
    }

public:
    task_system() {
        for (unsigned n = 0; n != _count; ++n) {
            _threads.emplace_back([&, n]{ run(n); });
        }
    }
}
```

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    }
};
```

Building a Task System

```
class notification_queue {
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    bool _done{false};
    mutex _mutex;
    condition_variable _ready;

public:
    void done() {
        {
            unique_lock<mutex> lock{_mutex};
            _done = true;
        }
        _ready.notify_all();
    }

    bool pop(function<void()>& x) {
        lock_t lock{_mutex};
        while (_q.empty() && !_done) _ready.wait(lock);
        if (_q.empty()) return false;
        x = move(_q.front());
        _q.pop_front();
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    }

    template<typename F>
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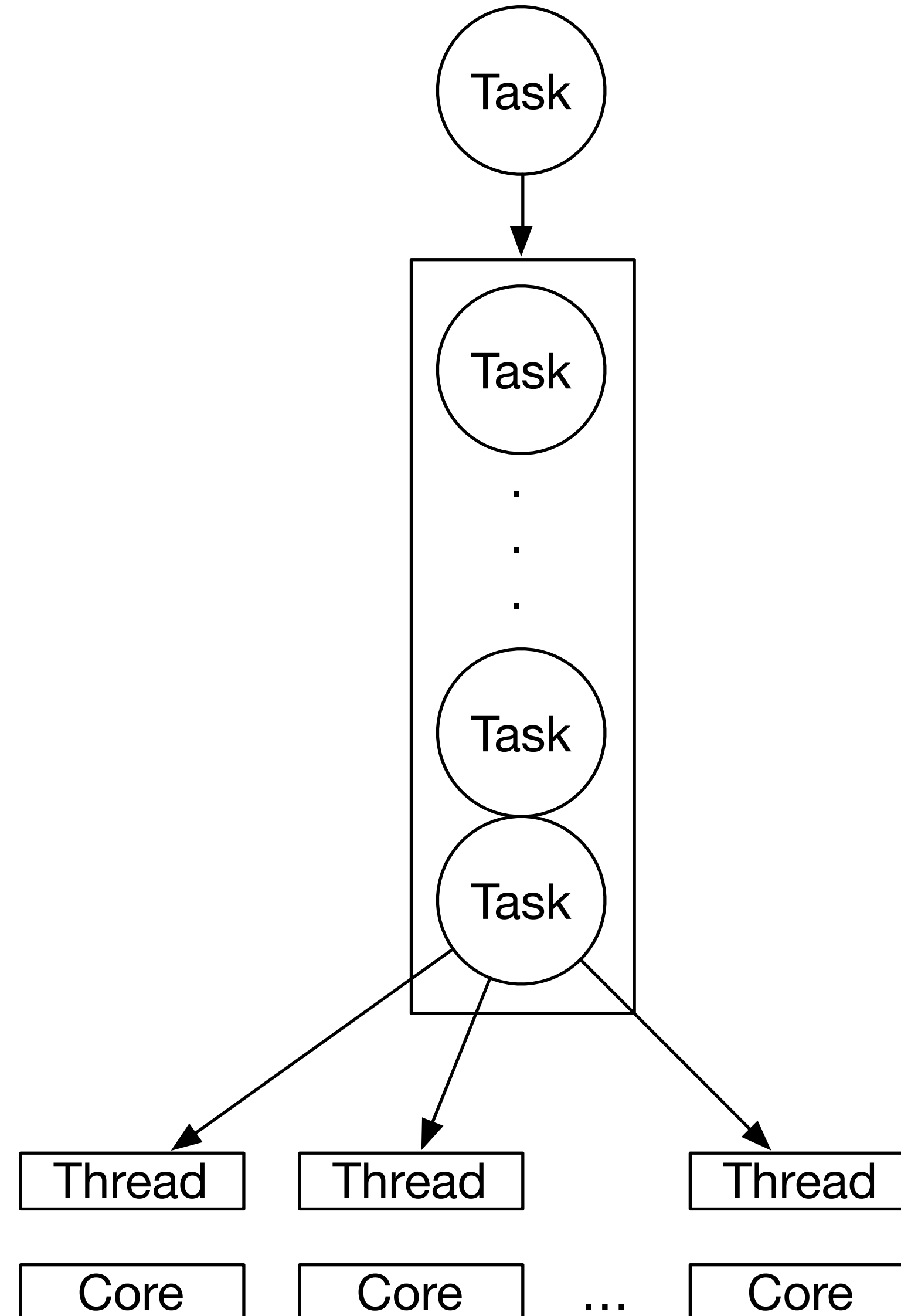
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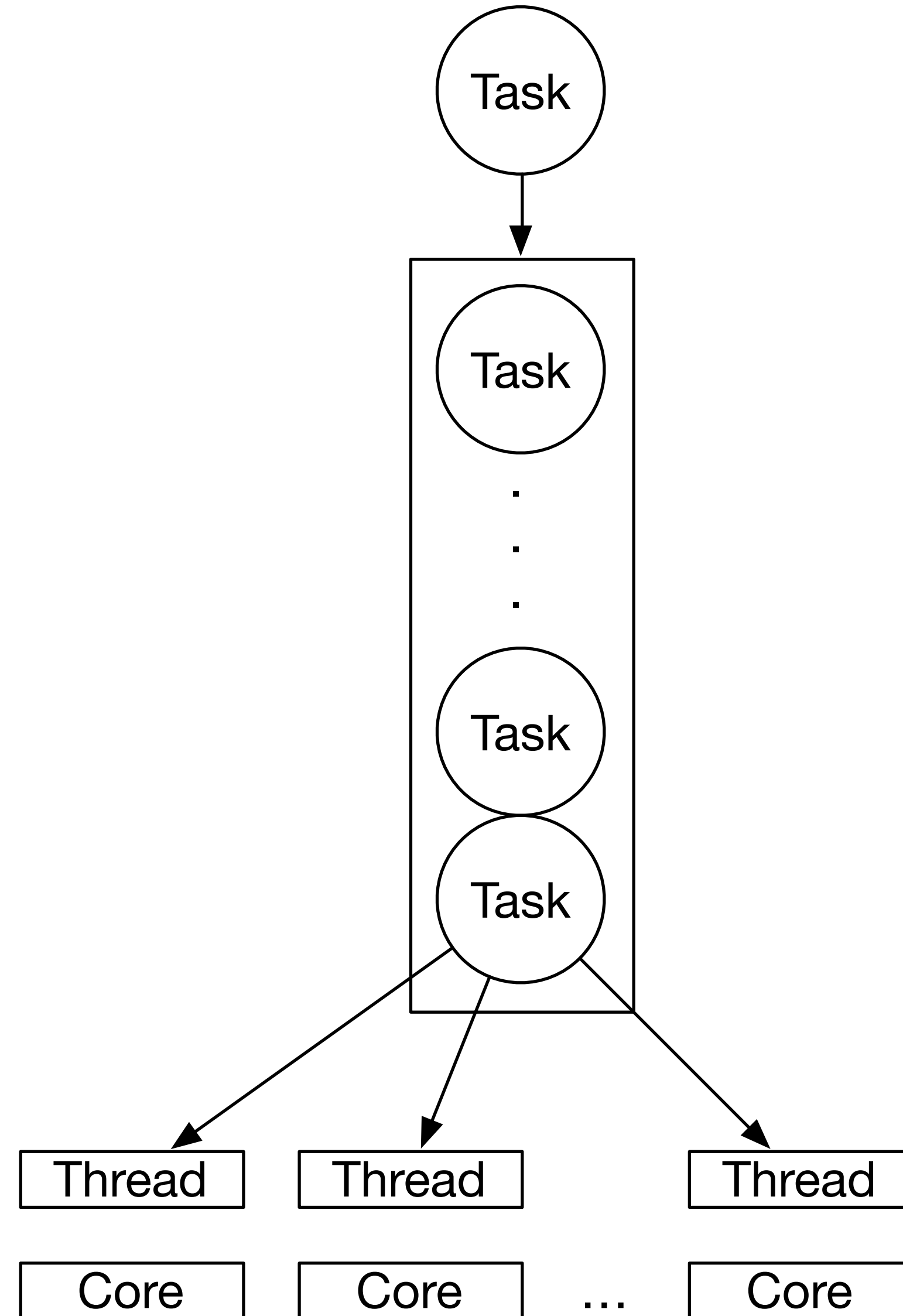
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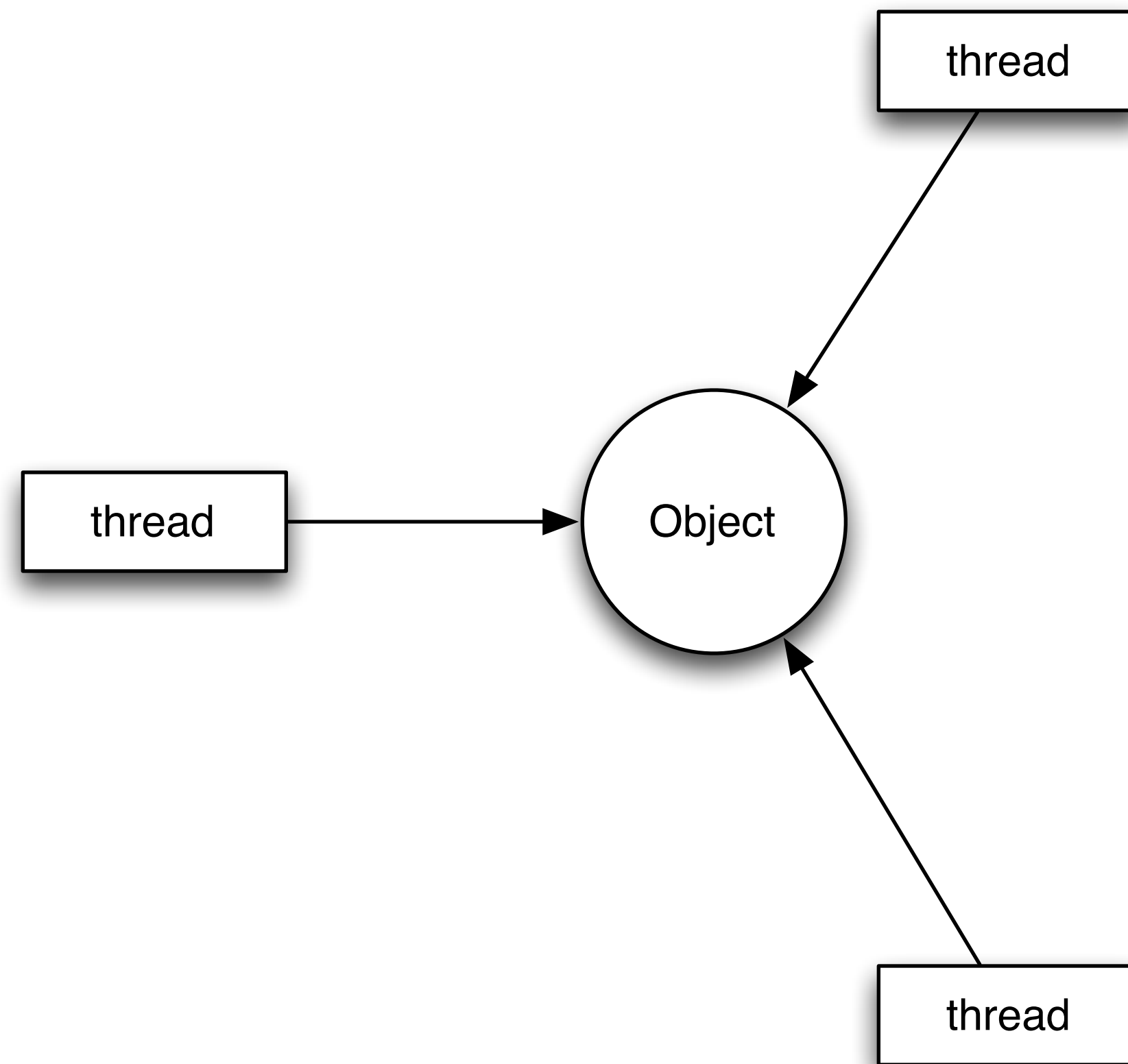
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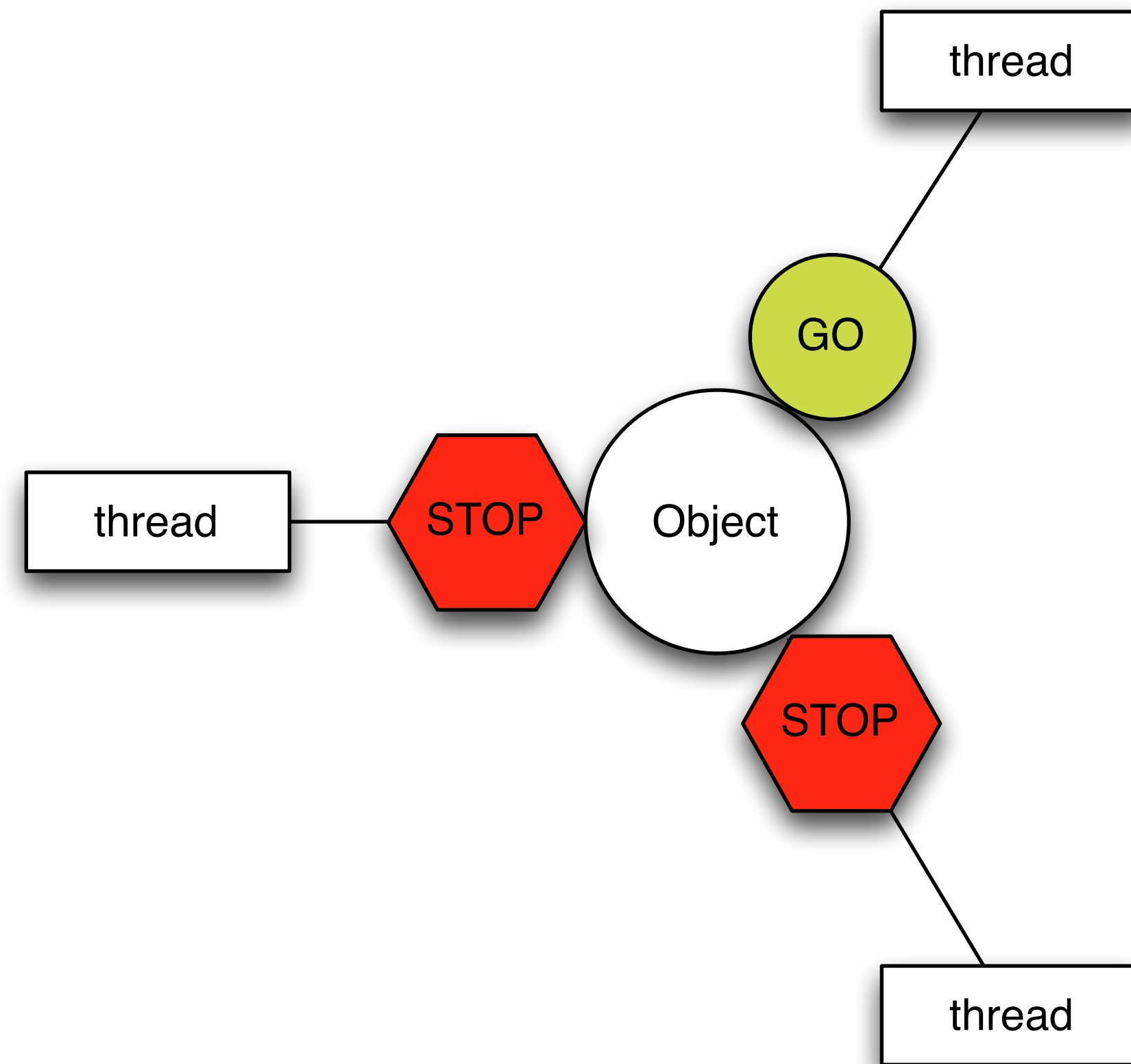
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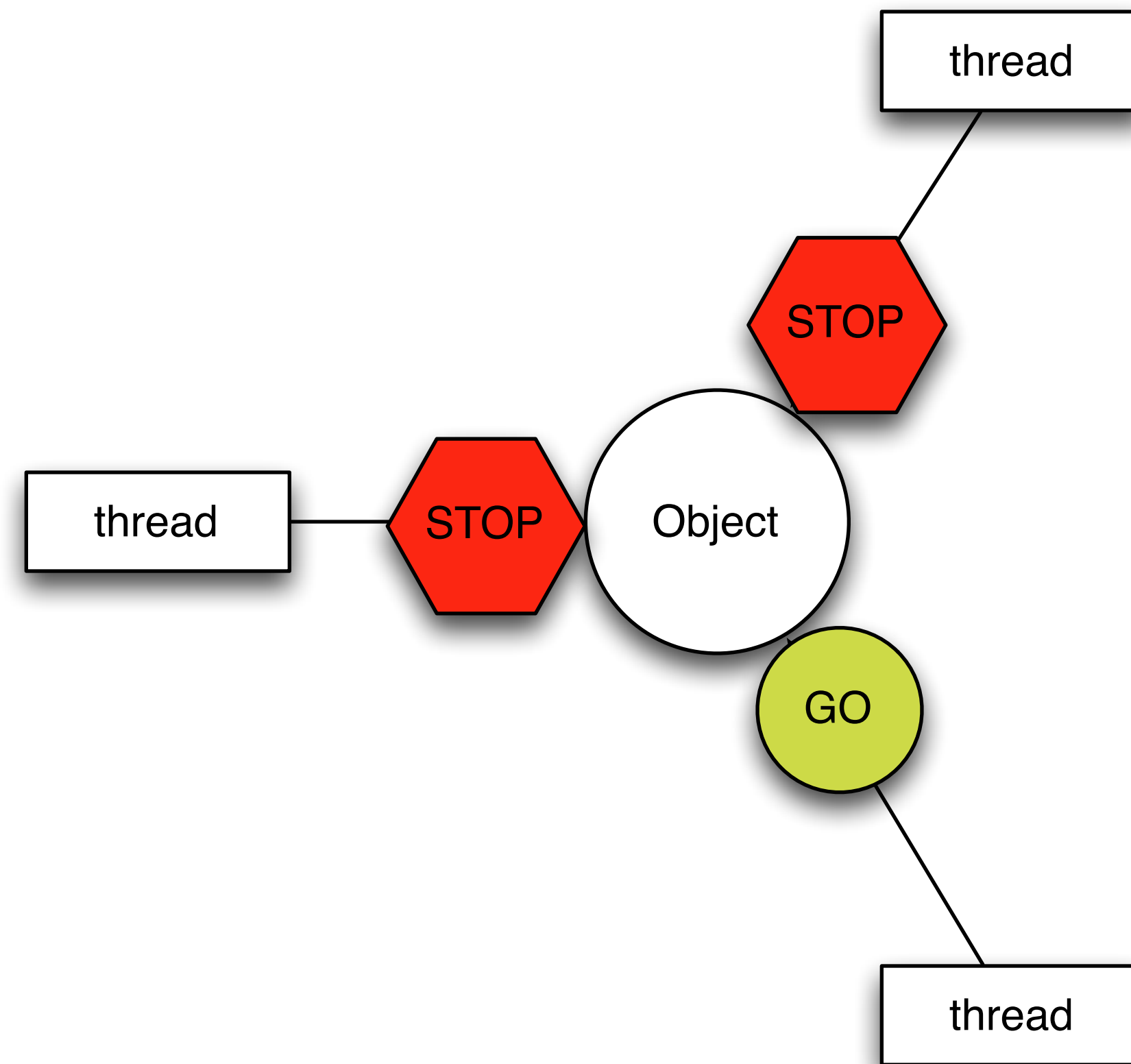
Why No Raw Synchronization Primitives?



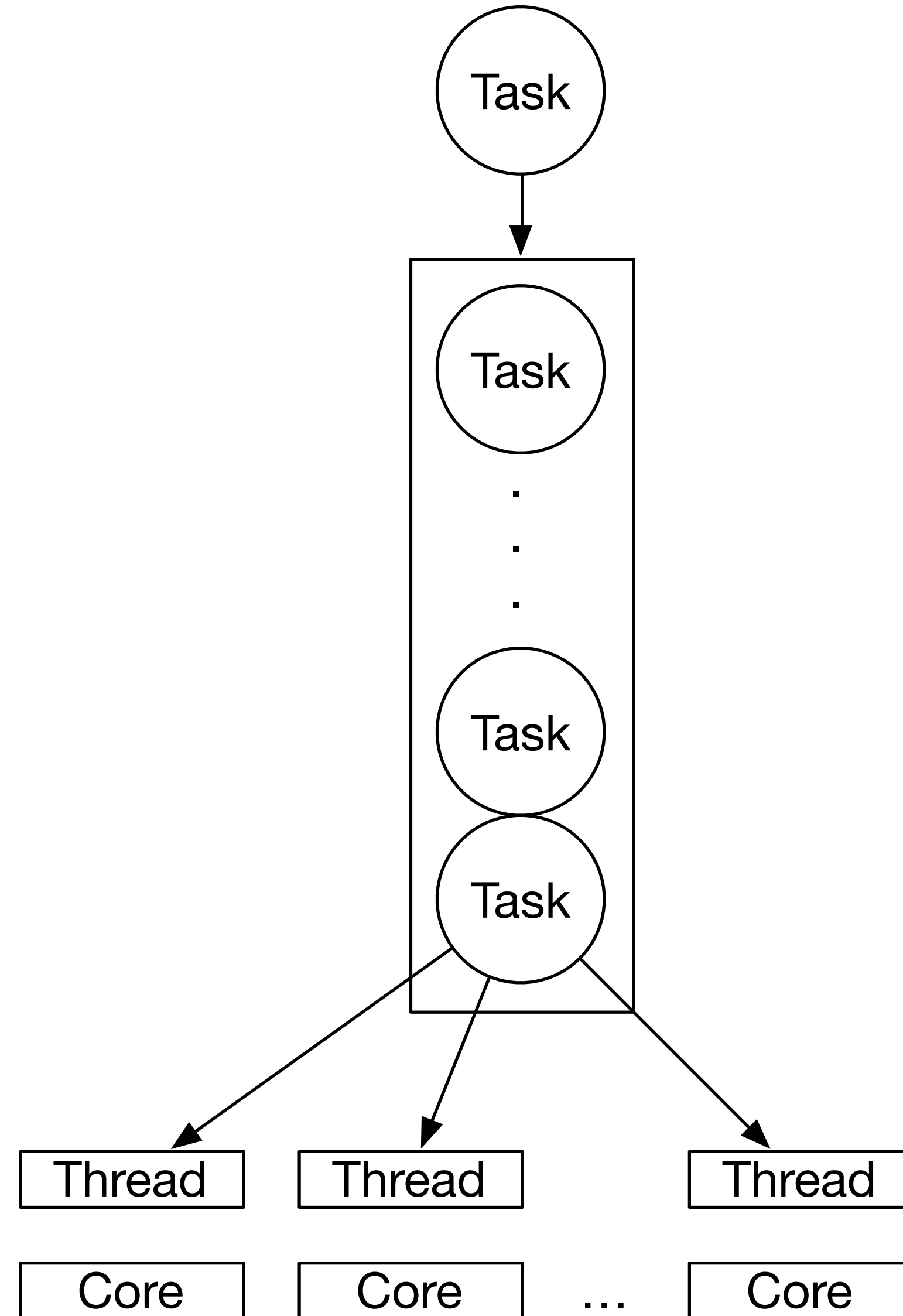
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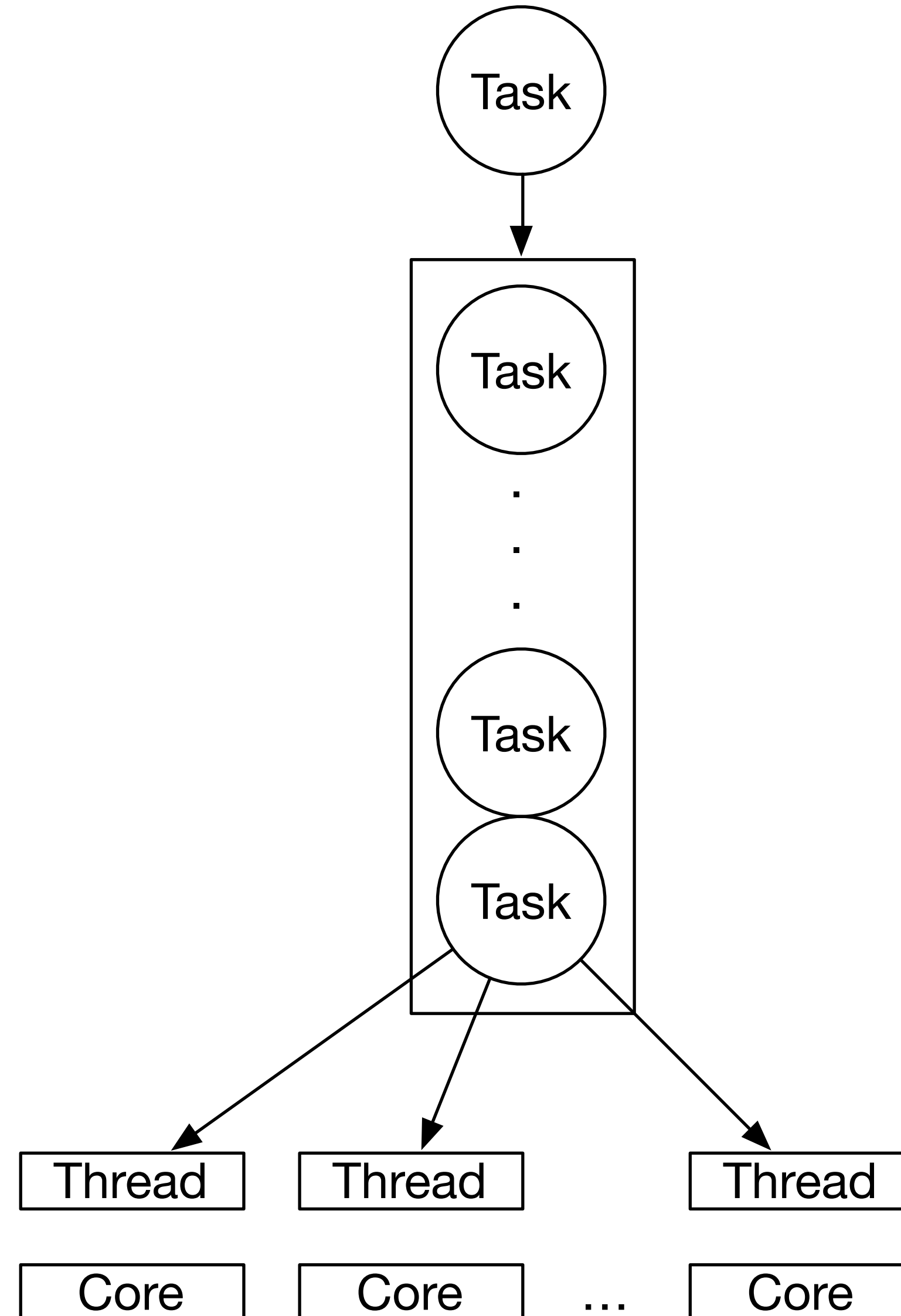
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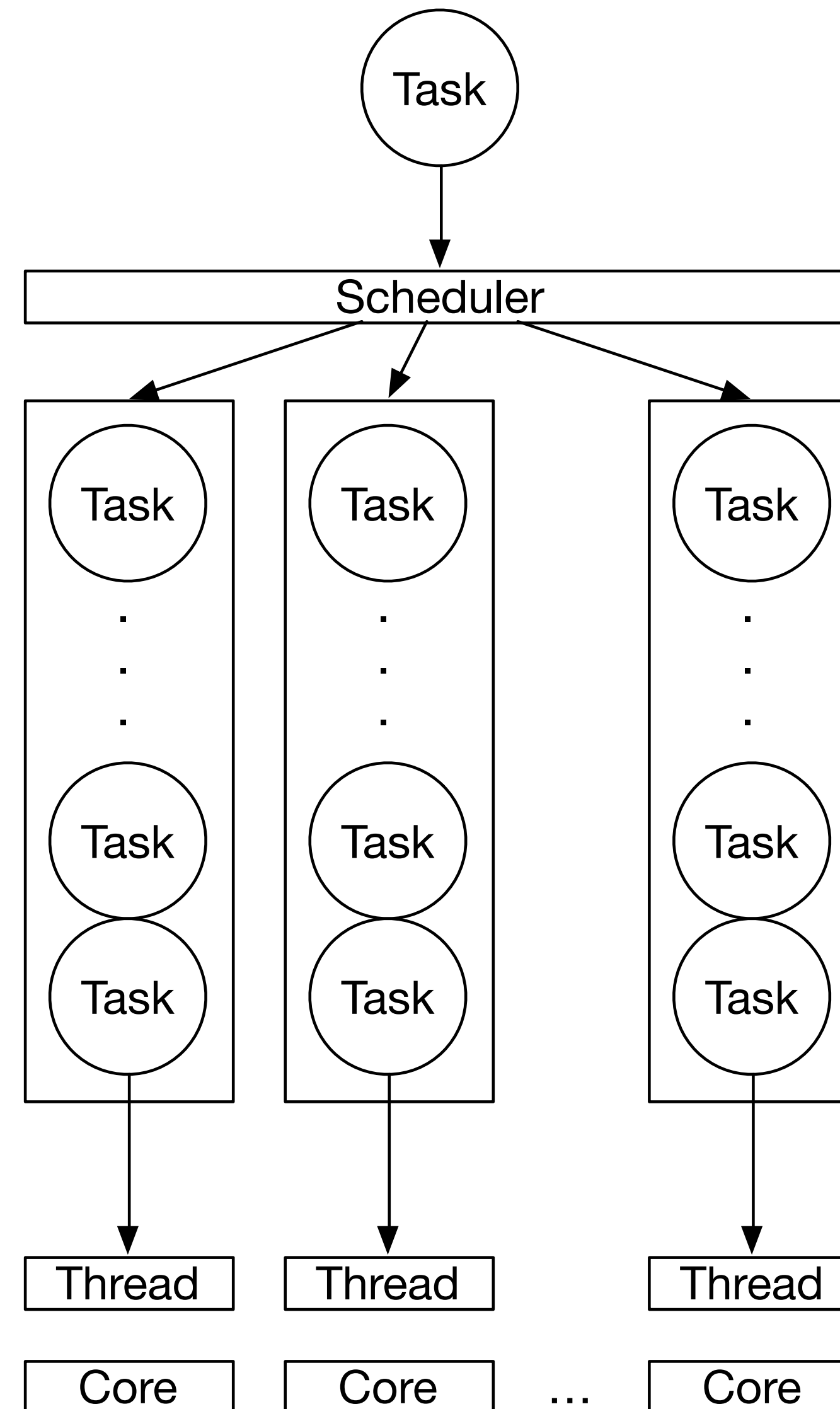
Building a Task System



Building a Task System



Building a Task System



Building a Task System

```
class task_system {
    const unsigned          _count{thread::hardware_concurrency()};
    vector<thread>          _threads;
    vector<notification_queue> _q{_count};
    atomic<unsigned>        _index{0};

    void run(unsigned i) {
        while (true) {
            function<void()> f;
            if (!_q[i].pop(f)) break;
            f();
        }
    }

public:
    task_system() {}

    ~task_system() {
        for (auto& e : _q) e.done();
        for (auto& e : _threads) e.join();
    }

    template <typename F>
    void async_(F&& f) {
        auto i = _index++;
        _q[i % _count].push(forward<F>(f));
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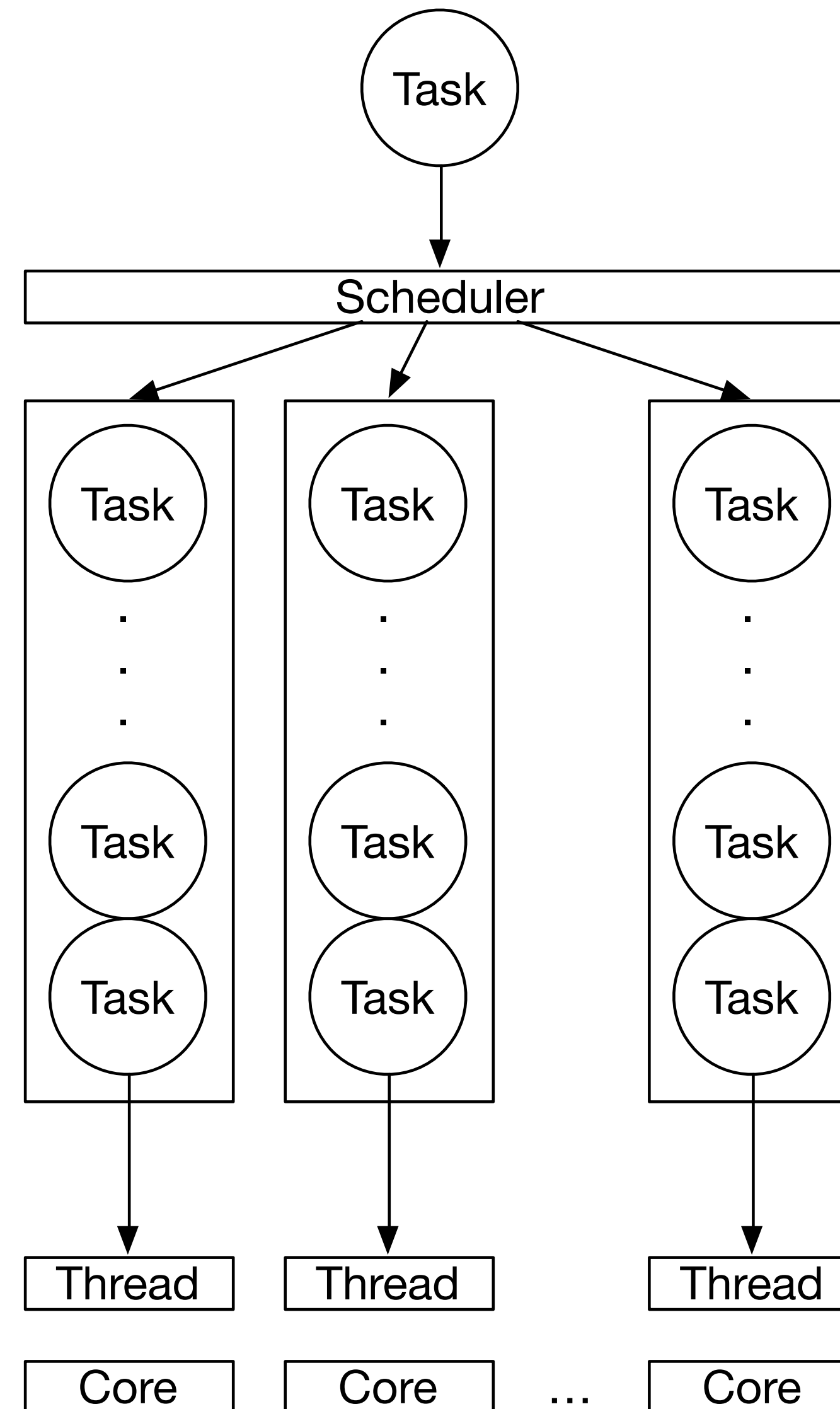
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    }

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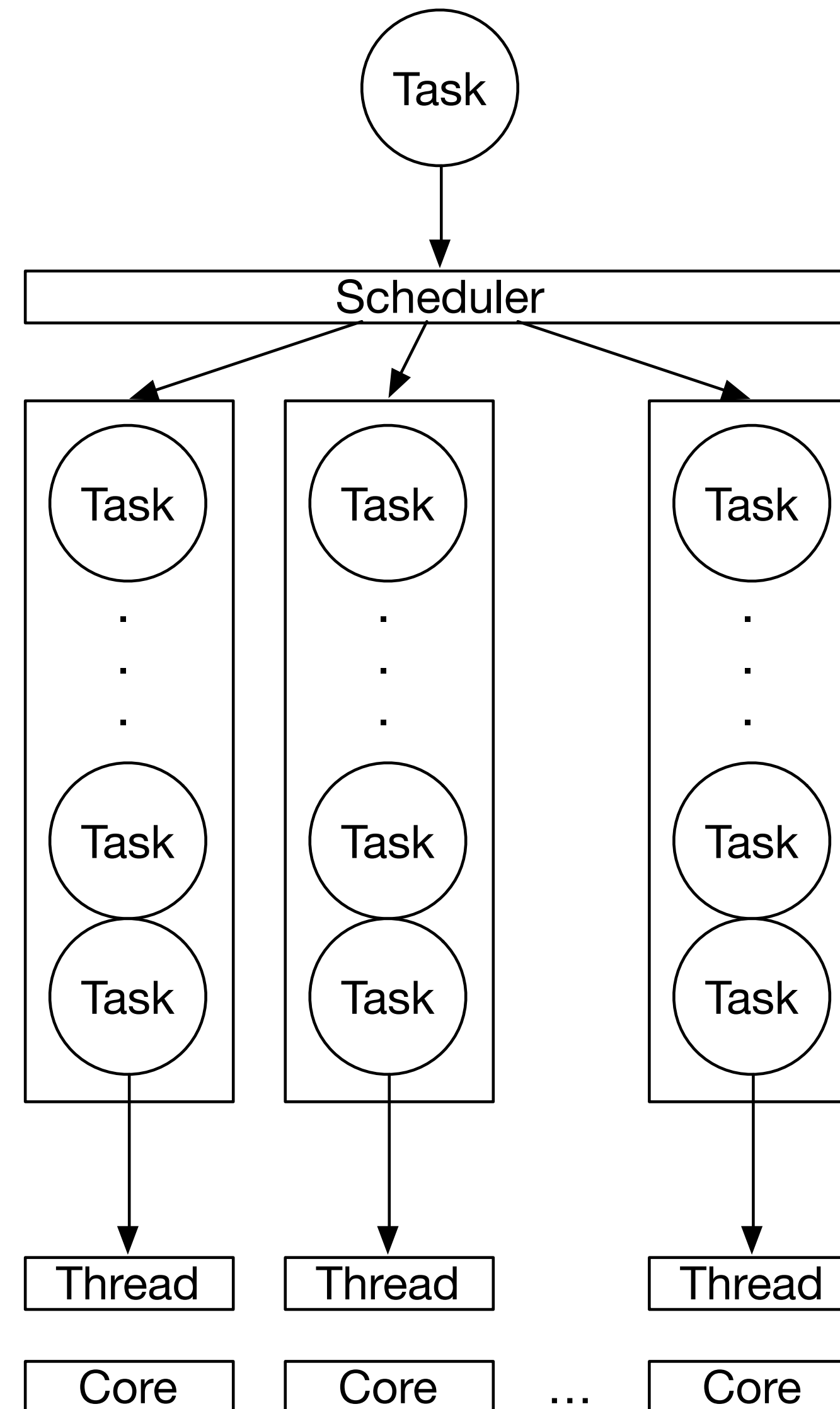
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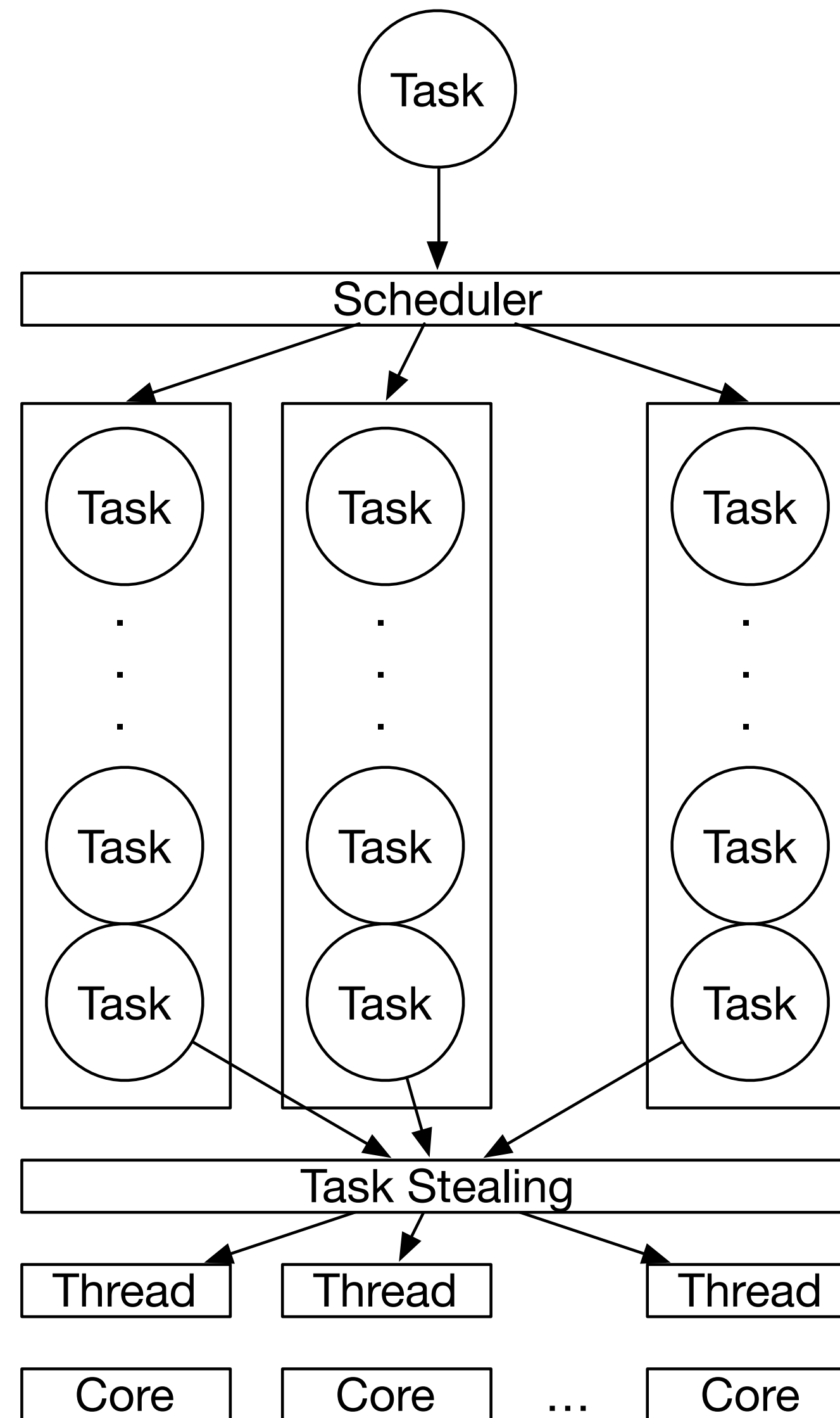
Building a Task System



Building a Task System



Building a Task System



Building a Task System

```
class notification_queue {
    deque<function<void()>> _q;
    bool _done{false};
    mutex _mutex;
    condition_variable _ready;

public:
    bool try_pop(function<void()>& x) {
        lock_t lock{_mutex, try_to_lock};
        if (!lock || _q.empty()) return false;
        x = move(_q.front());
        _q.pop_front();
        return true;
    }

    template<typename F>
    bool try_push(F&& f) {
        {
            lock_t lock{_mutex, try_to_lock};
            if (!lock) return false;
            _q.emplace_back(forward<F>(f));
        }
        _ready.notify_one();
        return true;
    }

    void done() {
        {
            unique lock<mutex> lock{ mutex};

```

Building a Task System

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    condition_variable _ready;

public:
    bool try_pop(function<void()>& x) {
        lock_t lock{_mutex, try_to_lock};
        if (!lock || _q.empty()) return false;
        x = move(_q.front());
        _q.pop_front();
        return true;
    }

    template<typename F>
    bool try_push(F&& f) {
        {
            lock_t lock{_mutex, try_to_lock};
            if (!lock) return false;
            _q.emplace_back(forward<F>(f));
        }
        _ready.notify_one();
        return true;
    }

    void done() {
        {
            unique lock<mutex> lock{ mutex};

```

Building a Task System

```
class notification_queue {
    deque<function<void()>> _q;
    bool _done{false};
    mutex _mutex;
    condition_variable _ready;

public:
    bool try_pop(function<void()>& x) {
        lock_t lock{_mutex, try_to_lock};
        if (!lock || _q.empty()) return false;
        x = move(_q.front());
        _q.pop_front();
        return true;
    }

    template<typename F>
    bool try_push(F&& f) {
        {
            lock_t lock{_mutex, try_to_lock};
            if (!lock) return false;
            _q.emplace_back(forward<F>(f));
        }
        _ready.notify_one();
        return true;
    }

    void done() {
        {
            unique lock<mutex> lock{ mutex};

```

Building a Task System

```
void run(unsigned i) {  
    while (true) {  
        function<void()> f;  
  
        for (unsigned n = 0; n != _count; ++n) {  
            if (_q[(i + n) % _count].try_pop(f)) break;  
        }  
        if (!f && !_q[i].pop(f)) break;  
  
        f();  
    }  
}  
  
public:  
    task_system() { ... }  
  
    ~task_system() { ... }  
  
    template <typename F>  
    void async_(F&& f) {  
        auto i = _index++;  
  
        for (unsigned n = 0; n != _count * K; ++n) {  
            if (_q[(i + n) % _count].try_push(forward<F>(f))) return;  
        }  
  
        _q[i % _count].push(forward<F>(f));  
    }  
};
```

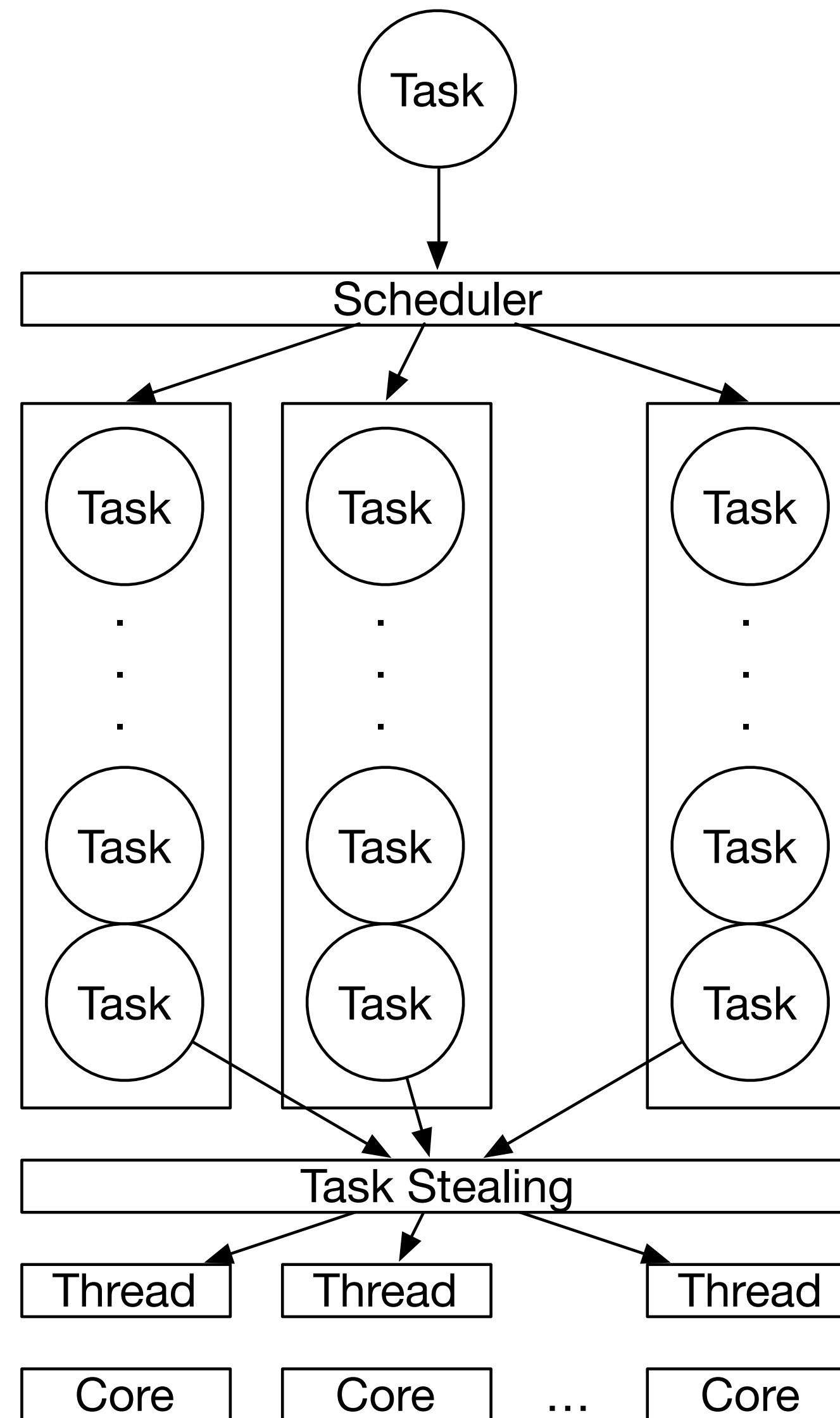

Building a Task System

```
void run(unsigned i) {  
    while (true) {  
        function<void()> f;  
  
        for (unsigned n = 0; n != _count; ++n) {  
            if (_q[(i + n) % _count].try_pop(f)) break;  
        }  
        if (!f && !_q[i].pop(f)) break;  
  
        f();  
    }  
}  
  
public:  
    task_system() { ... }  
  
    ~task_system() { ... }  
  
    template <typename F>  
    void async_(F&& f) {  
        auto i = _index++;  
  
        for (unsigned n = 0; n != _count * K; ++n) {  
            if (_q[(i + n) % _count].try_push(forward<F>(f))) return;  
        }  
  
        _q[i % _count].push(forward<F>(f));  
    }  
};
```

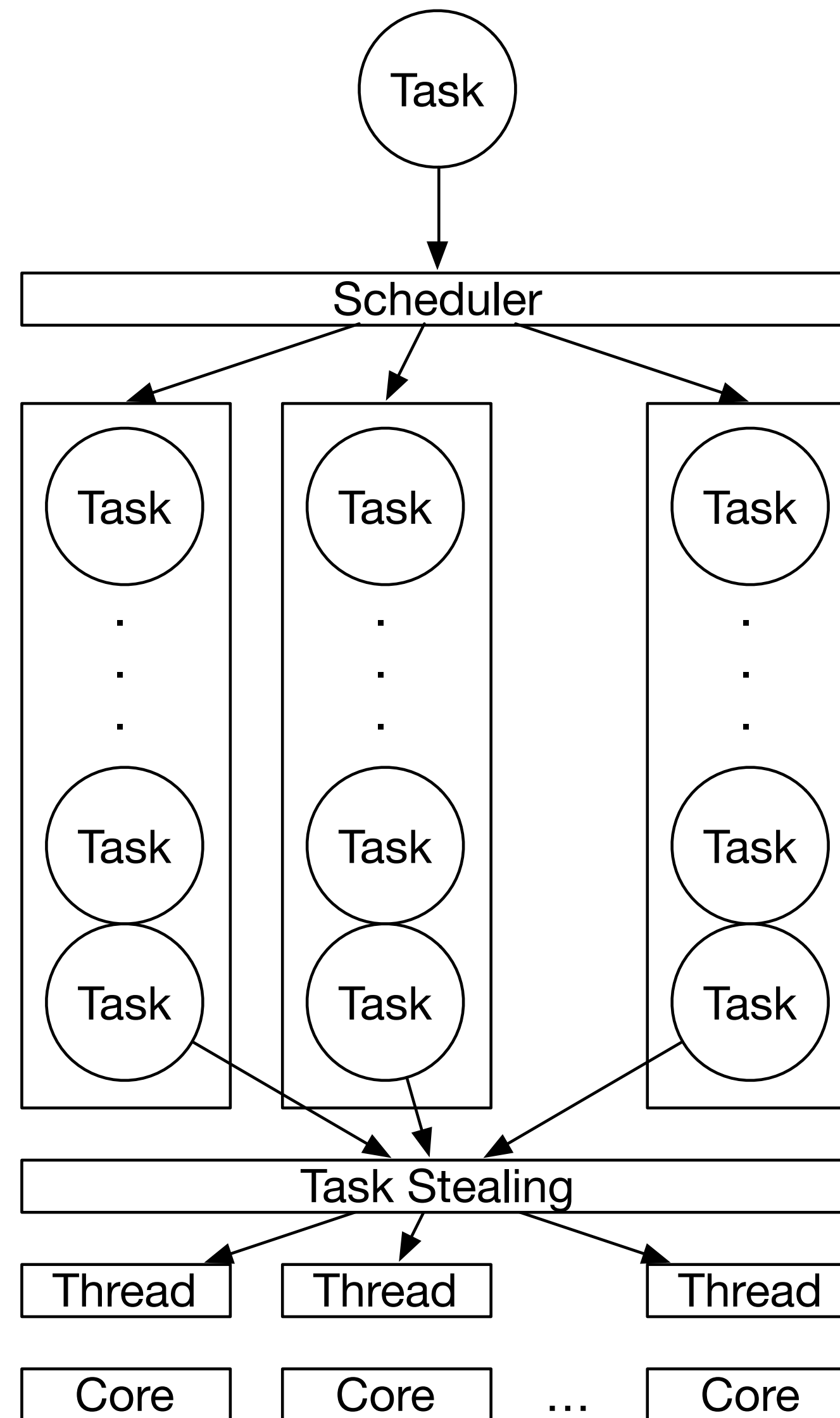
Building a Task System

```
void run(unsigned i) {  
    while (true) {  
        function<void()> f;  
  
        for (unsigned n = 0; n != _count; ++n) {  
            if (_q[(i + n) % _count].try_pop(f)) break;  
        }  
        if (!f && !_q[i].pop(f)) break;  
  
        f();  
    }  
}  
  
public:  
    task_system() { ... }  
  
    ~task_system() { ... }  
  
    template <typename F>  
    void async_(F&& f) {  
        auto i = _index++;  
  
        for (unsigned n = 0; n != _count * K; ++n) {  
            if (_q[(i + n) % _count].try_push(forward<F>(f))) return;  
        }  
  
        _q[i % _count].push(forward<F>(f));  
    }  
};
```

Building a Task System



Building a Task System



- Compared to Apple's Grand Central Dispatch (libdispatch)



- Compared to Apple's Grand Central Dispatch (libdispatch)



C++14 compatible async with libdispatch

```
#include <functional>
#include <future>
#include <type_traits>

#include <dispatch/dispatch.h>

namespace stlab {

template <class Function, class... Args>
auto async(Function&& f, Args&&... args )
{
    using result_type = std::result_of_t<std::decay_t<Function>(std::decay_t<Args>...)>;
    using packaged_type = std::packaged_task<result_type>;

    auto p = new packaged_type(std::bind(std::forward<Function>(f), std::forward<Args>(args)...));
    auto result = p->get_future();

    dispatch_async_f(dispatch_get_global_queue(DISPATCH_QUEUE_PRIORITY_DEFAULT, 0),
        p, [](void* f_) {
            packaged_type* f = static_cast<packaged_type*>(f_);
            (*f)();
            delete f;
        });

    return result;
}

} // namespace stlab
```


- Written with ASIO (Boost 1.62.0)

```
class task_system {  
    io_service          _service;  
    vector<thread>      _threads;  
    unique_ptr<io_service::work> _work{make_unique<io_service::work>(_service)};  
  
public:  
    task_system() {  
        for (unsigned n = 0; n != thread::hardware_concurrency(); ++n) {  
            _threads.emplace_back( [&]{  
                _service.run();  
            });  
        }  
    }  
  
    ~task_system() {  
        _work.reset();  
        for (auto& e : _threads) e.join();  
    }  
  
    template <typename F>  
    void async_(F&& f) {  
        _service.post(forward<F>(f));  
    }  
};
```



- Written with ASIO (Boost 1.62.0)

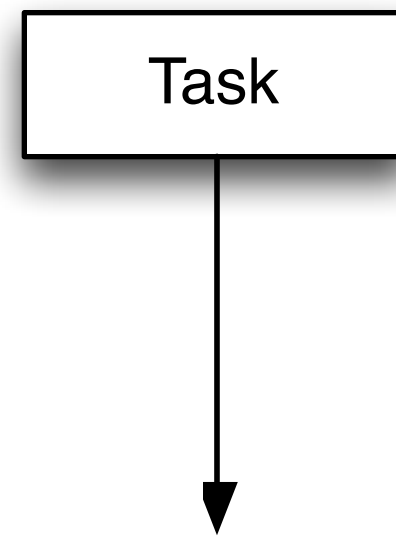
```
class task_system {  
    io_service          _service;  
    vector<thread>      _threads;  
    unique_ptr<io_service::work> _work{make_unique<io_service::work>(_service)};  
  
public:  
    task_system() {  
        for (unsigned n = 0; n != thread::hardware_concurrency(); ++n) {  
            _threads.emplace_back( [&]{  
                _service.run();  
            });  
        }  
    }  
  
    ~task_system() {  
        _work.reset();  
        for (auto& e : _threads) e.join();  
    }  
  
    template <typename F>  
    void async_(F&& f) {  
        _service.post(forward<F>(f));  
    }  
};
```



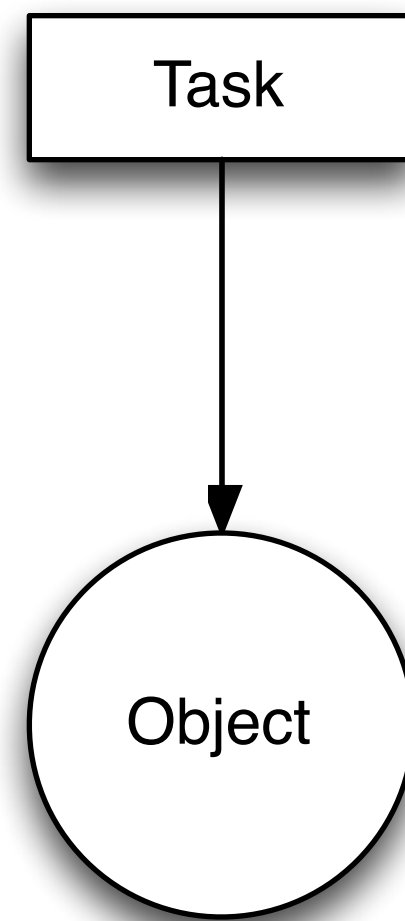
No Raw Synchronization Primitives



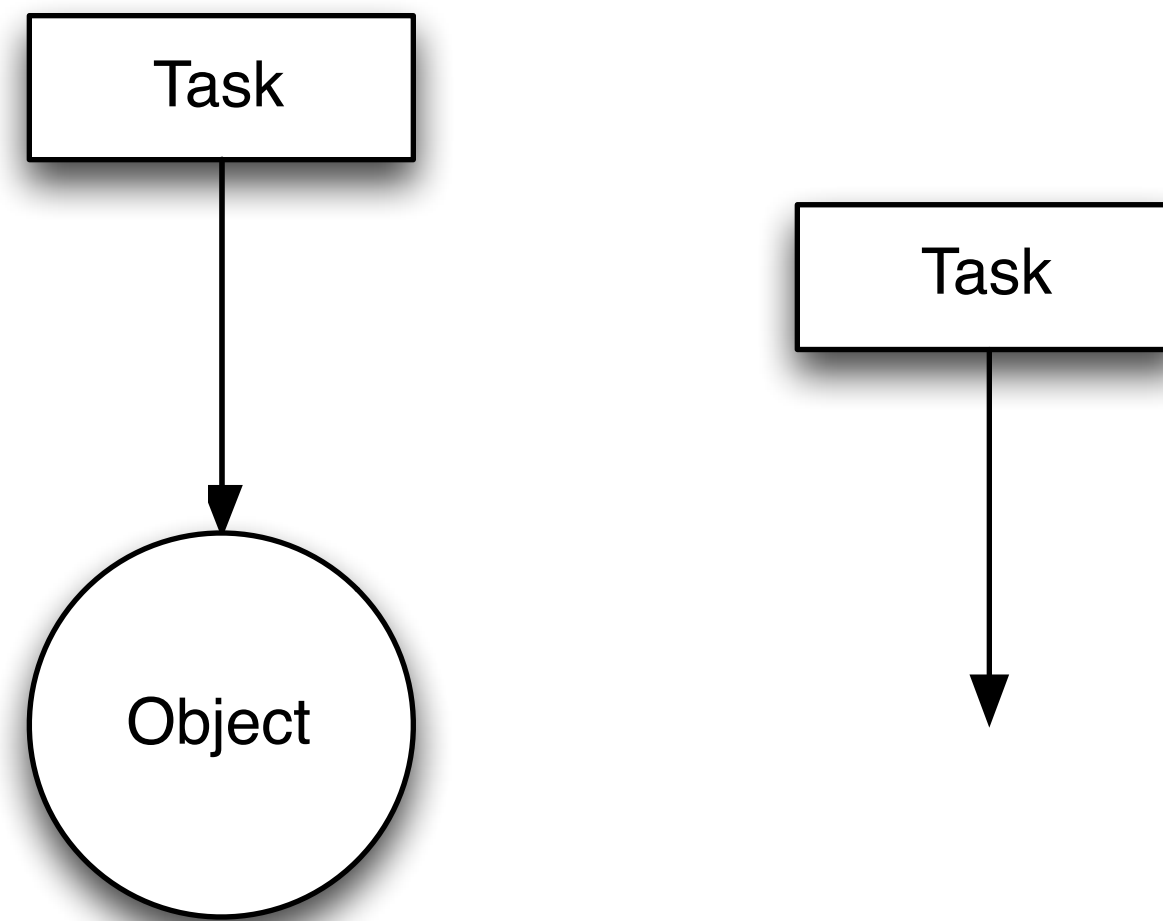
No Raw Synchronization Primitives



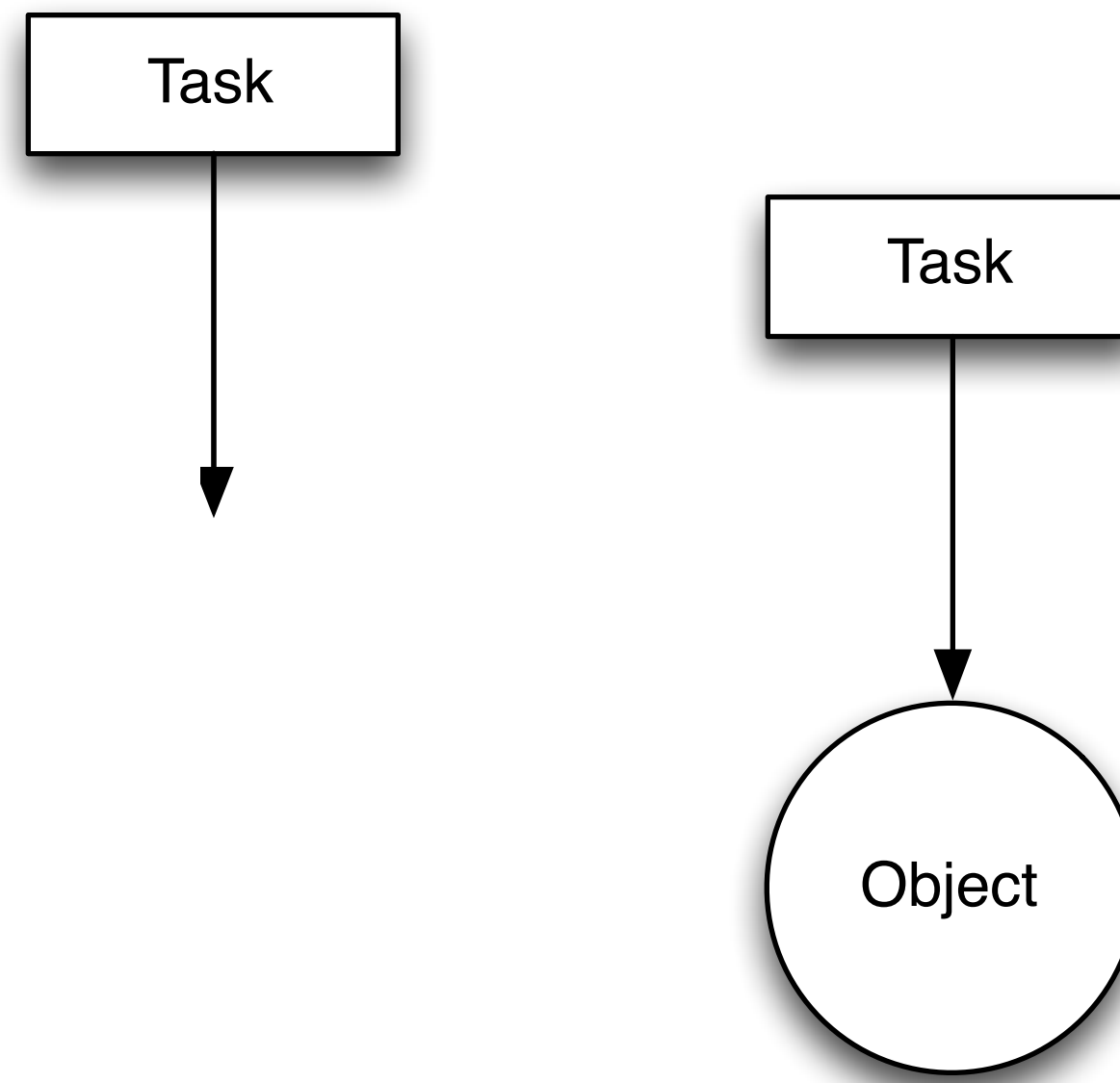
No Raw Synchronization Primitives



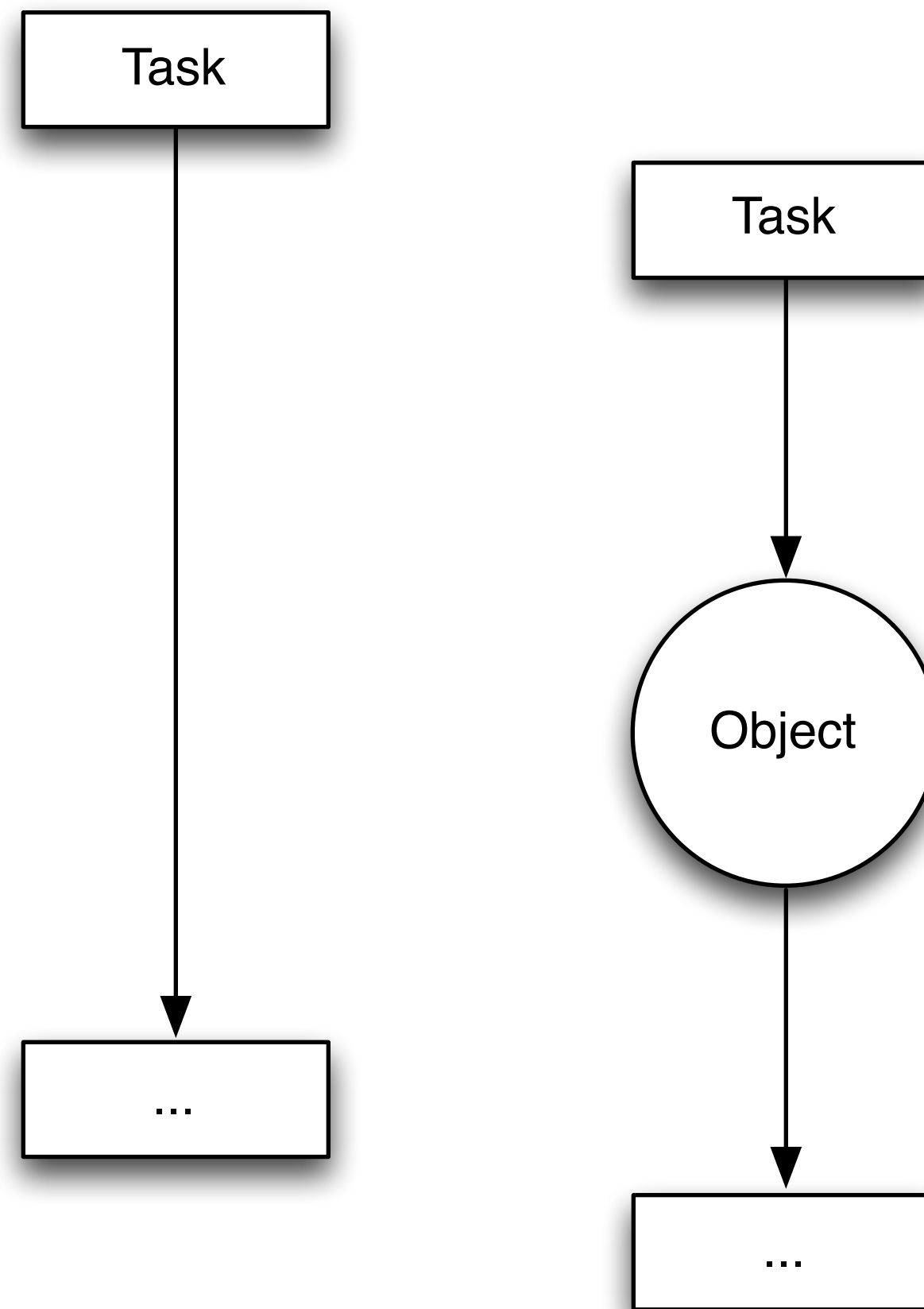
No Raw Synchronization Primitives



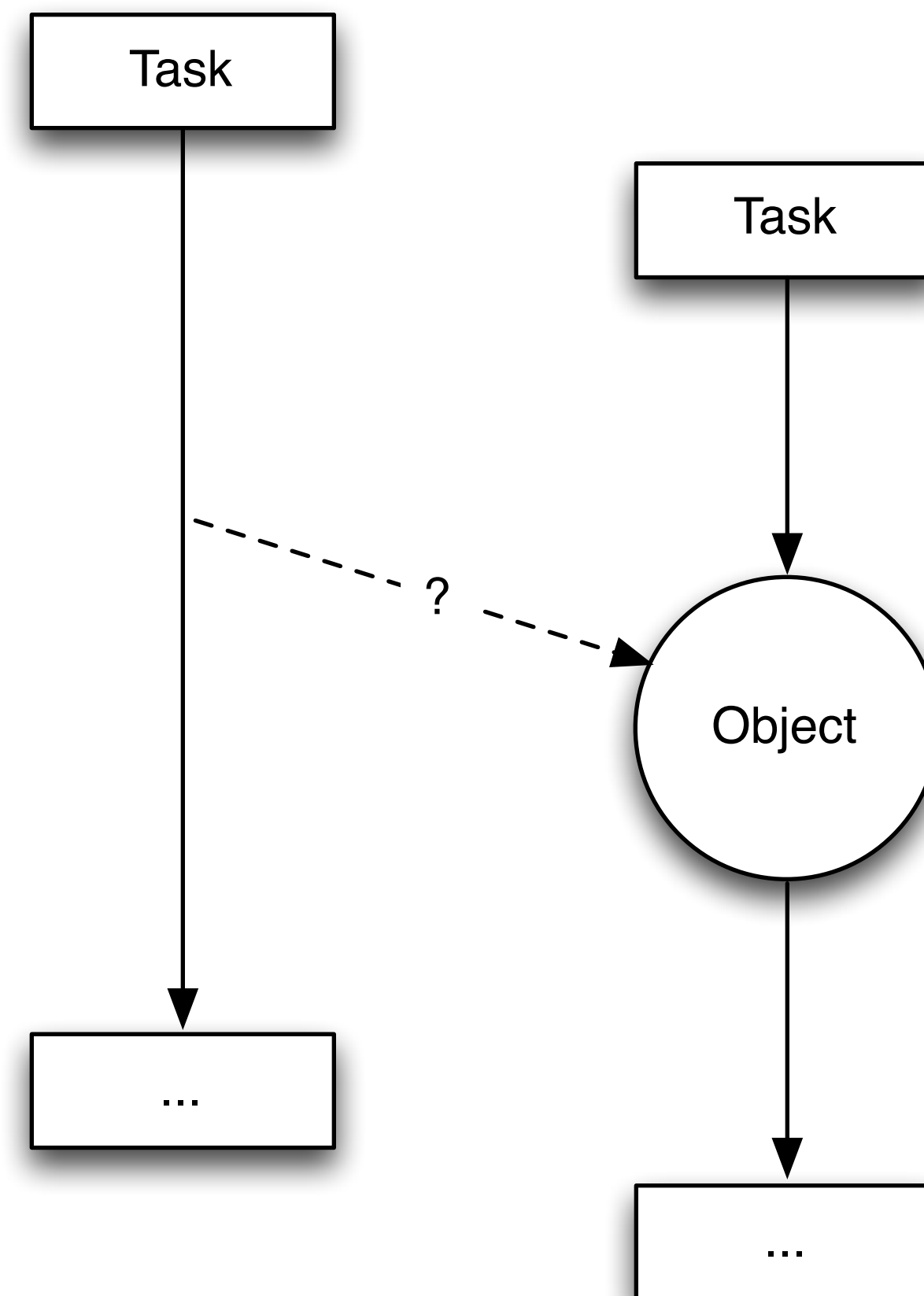
No Raw Synchronization Primitives



No Raw Synchronization Primitives



No Raw Synchronization Primitives



```
future<cpp_int> x = async([]{ return fibonacci<cpp_int>(1'000'000); });  
  
// Do Something  
  
cout << x.get() << endl;
```

```
future<cpp_int> x = async([]{ return fibonacci<cpp_int>(1'000'000); });  
  
// Do Something  
  
cout << x.get() << endl;
```

- Fibonacci is often used as an example for parallel algorithms
 - Please stop...

Public Service Announcement - How to Write Fibonacci

```
template <typename T, typename N, typename Op>
T power(T x, N n, Op op)
{
    if (n == 0) return identity_element(op);

    while ((n & 1) != 0) {
        n >>= 1;
        x = op(x, x);
    }

    T result = x;
    n >>= 1;
    while (n != 0) {
        x = op(x, x);
        if ((n & 1) != 0) result = op(result, x);
        n >>= 1;
    }
    return result;
}
```

Public Service Announcement - How to Write Fibonacci

```
template <typename T, typename N, typename Op>
T power(T x, N n, Op op)
{
    if (n == 0) return identity_element(op);

    while ((n & 1) != 0) {
        n >>= 1;
        x = op(x, x);
    }

    T result = x;
    n >>= 1;
    while (n != 0) {
        x = op(x, x);
        if ((n & 1) != 0) result = op(result, x);
        n >>= 1;
    }
    return result;
}
```

Egyptian Multiplication (Russian Peasant Algorithm)

See “From Mathematics to Generic Programming” - Alex Stepanov and Dan Rose

Public Service Announcement - How to Write Fibonacci

```
template <typename N>
struct multiply_2x2 {
    array<N, 4> operator()(const array<N, 4>& x, const array<N, 4>& y)
    {
        return { x[0] * y[0] + x[1] * y[2], x[0] * y[1] + x[1] * y[3],
                 x[2] * y[0] + x[3] * y[2], x[2] * y[1] + x[3] * y[3] };
    }
};
```

```
template <typename N>
array<N, 4> identity_element(const multiply_2x2<N>&) { return { N(1), N(0), N(0), N(1) }; }
```

```
template <typename R, typename N>
R fibonacci(N n) {
    if (n == 0) return R(0);
    return power(array<R, 4>{ 1, 1, 1, 0 }, N(n - 1), multiply_2x2<R>())[0];
}
```


Public Service Announcement - How to Write Fibonacci

```
template <typename N>
struct multiply_2x2 {
    array<N, 4> operator()(const array<N, 4>& x, const array<N, 4>& y)
    {
        return { x[0] * y[0] + x[1] * y[2], x[0] * y[1] + x[1] * y[3],
                 x[2] * y[0] + x[3] * y[2], x[2] * y[1] + x[3] * y[3] };
    }
};
```

```
template <typename N>
array<N, 4> identity_element(const multiply_2x2<N>&) { return { N(1), N(0), N(0), N(1) }; }
```

```
template <typename R, typename N>
R fibonacci(N n) {
    if (n == 0) return R(0);
    return power(array<R, 4>{ 1, 1, 1, 0 }, N(n - 1), multiply_2x2<R>())[0];
}
```

$$\begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix}^n = \begin{bmatrix} F_{n+1} & F_n \\ F_n & F_{n-1} \end{bmatrix}$$

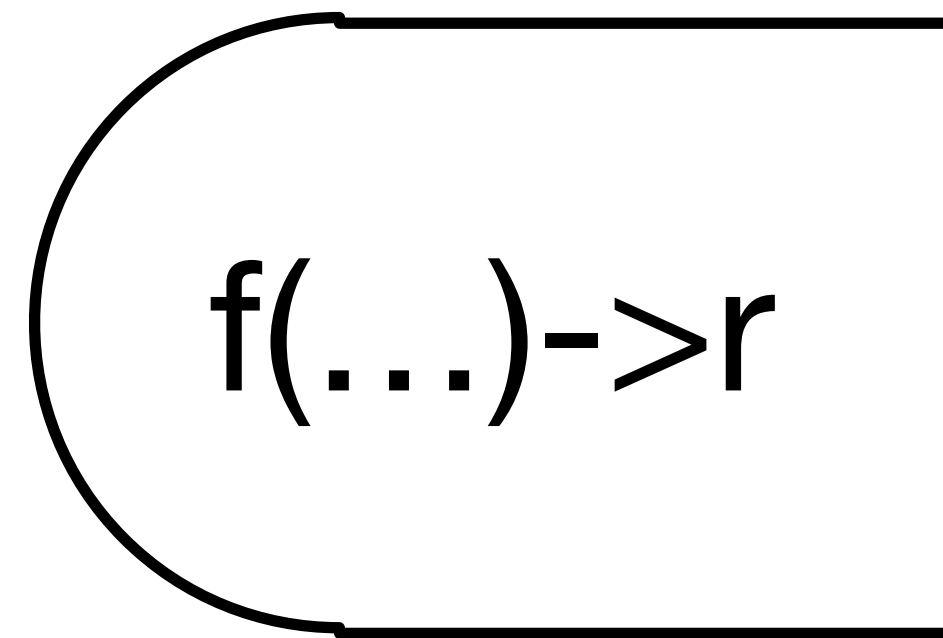
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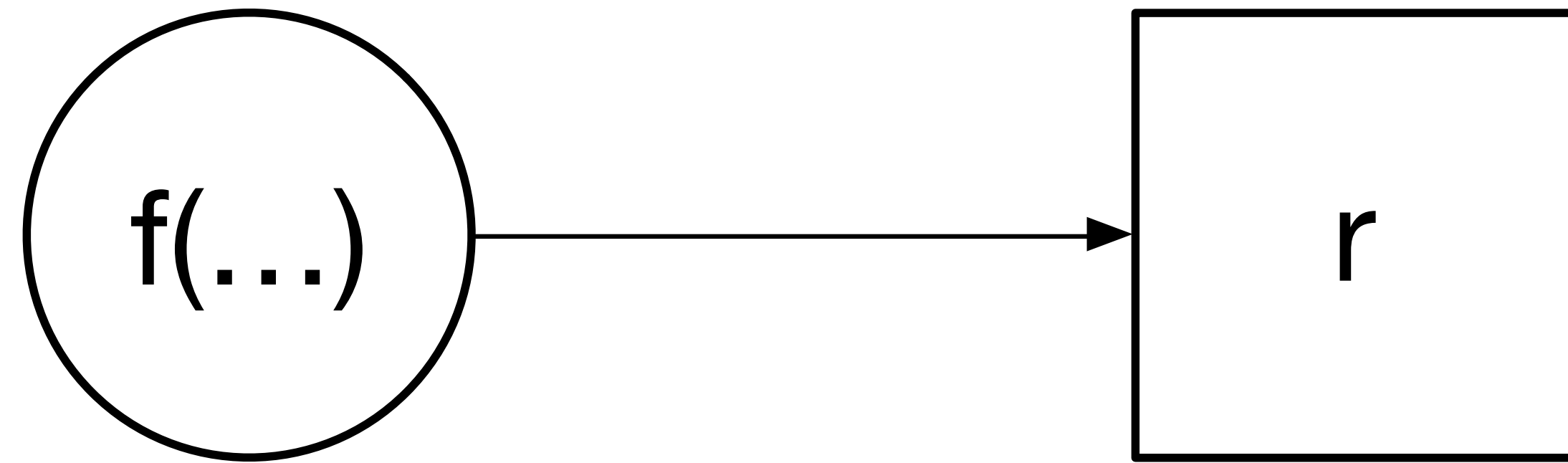
Figures

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04582256143224299859780683239696543855523783781413866750792868372058020433472254190336846843017198934115689
96526838242546875

0.72s to calculate
208,988 digits

```
future<cpp_int> x = async([]{ return fibonacci<cpp_int>(1'000'000); });  
  
// Do Something  
  
cout << x.get() << endl;
```





- Futures allow minimal code transformations to express dependencies

Exception Marshalling

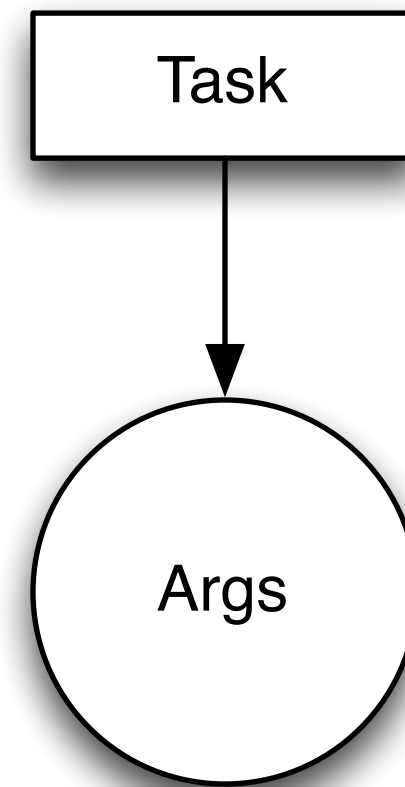
```
future<cpp_int> x = async([]{  
    throw runtime_error("failure");  
    return fibonacci<cpp_int>(1'000'000);  
});  
  
// Do Something  
  
try {  
    cout << x.get() << endl;  
} catch (const runtime_error& error) {  
    cout << error.what() << endl;  
}
```

Exception Marshalling

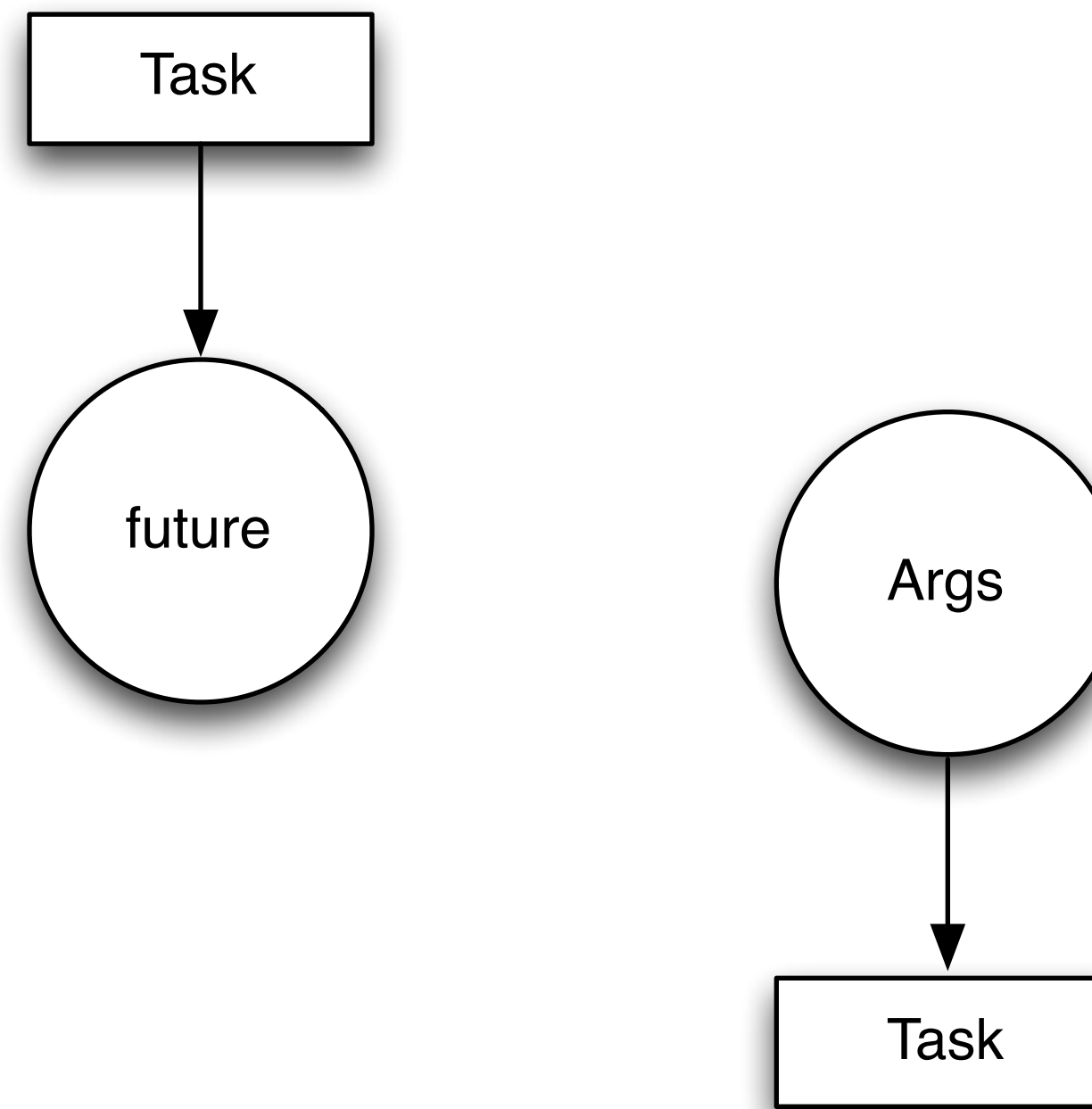
```
future<cpp_int> x = async([]{  
    throw runtime_error("failure");  
    return fibonacci<cpp_int>(1'000'000);  
});  
  
// Do Something  
  
try {  
    cout << x.get() << endl;  
} catch (const runtime_error& error) {  
    cout << error.what() << endl;  
}
```

failure

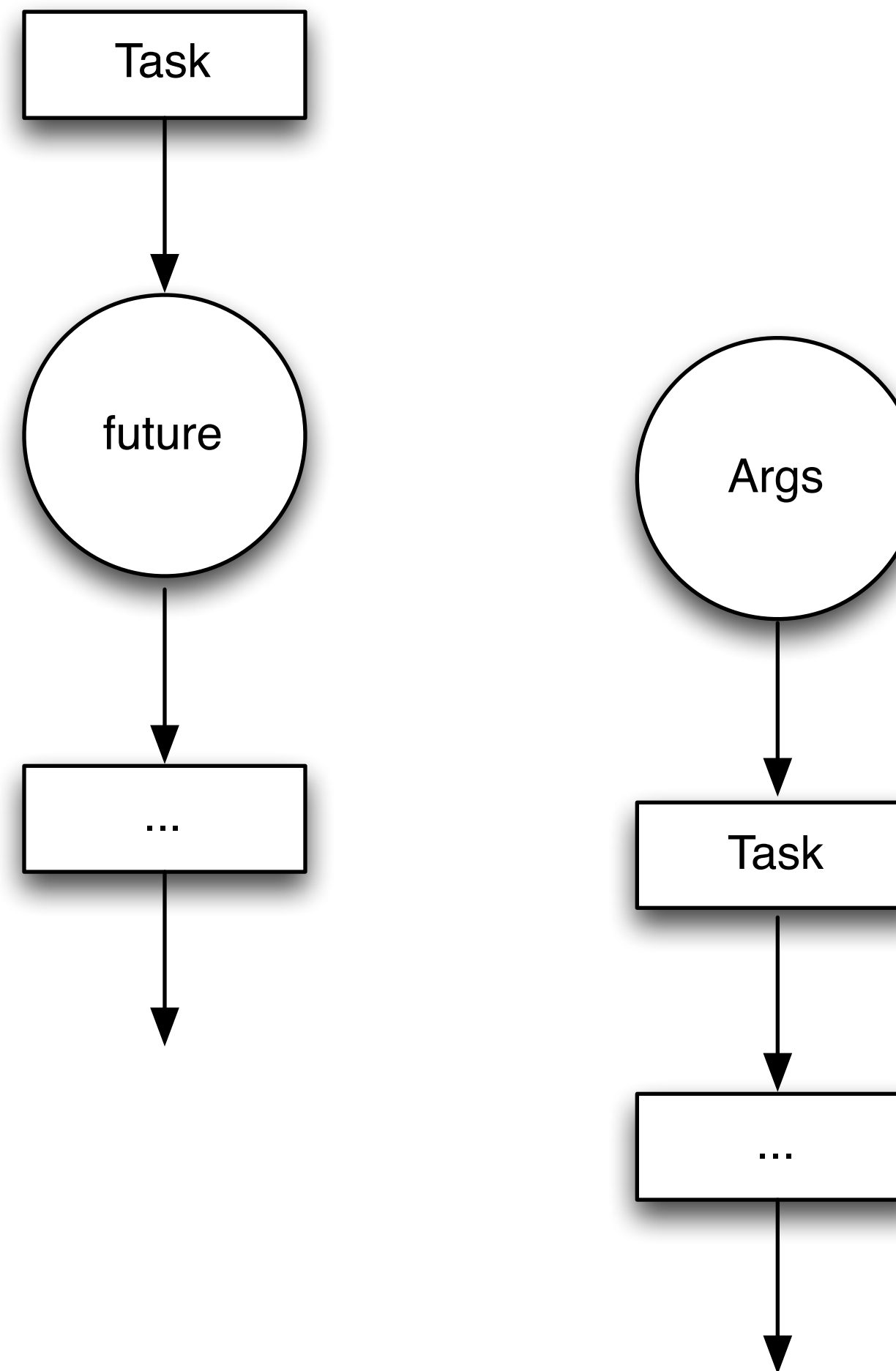
No Raw Synchronization Primitives



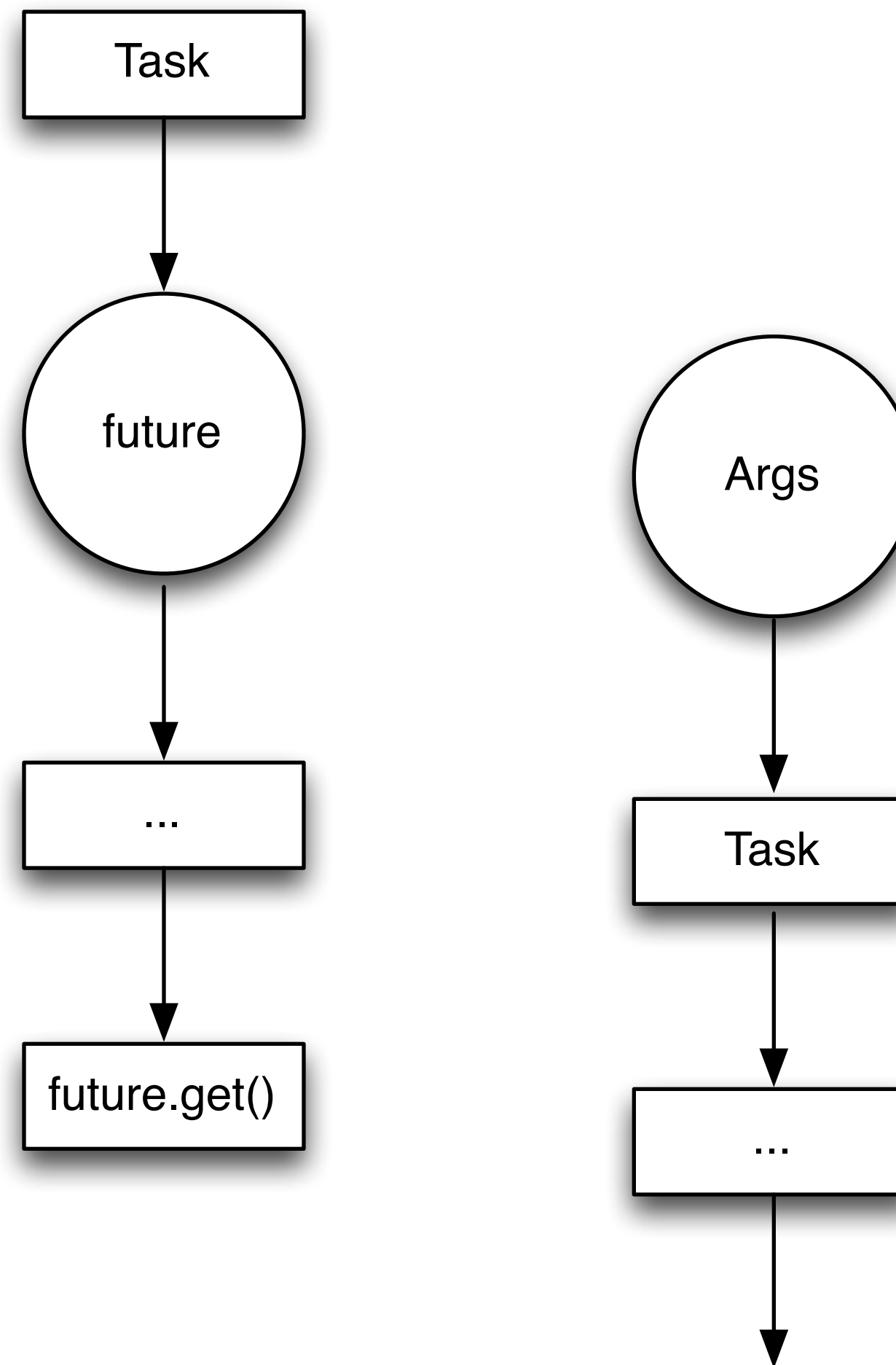
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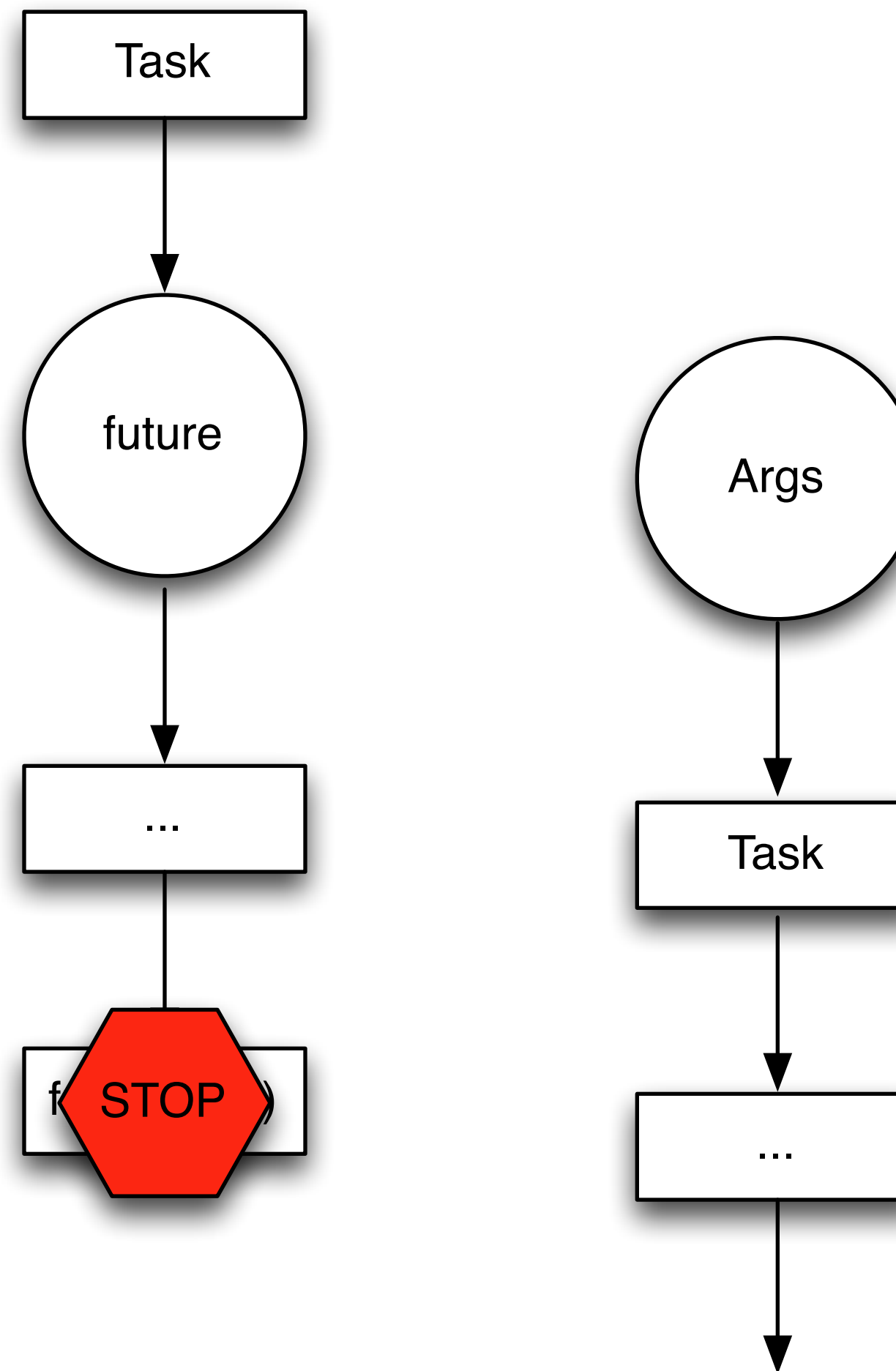
No Raw Synchronization Primitives



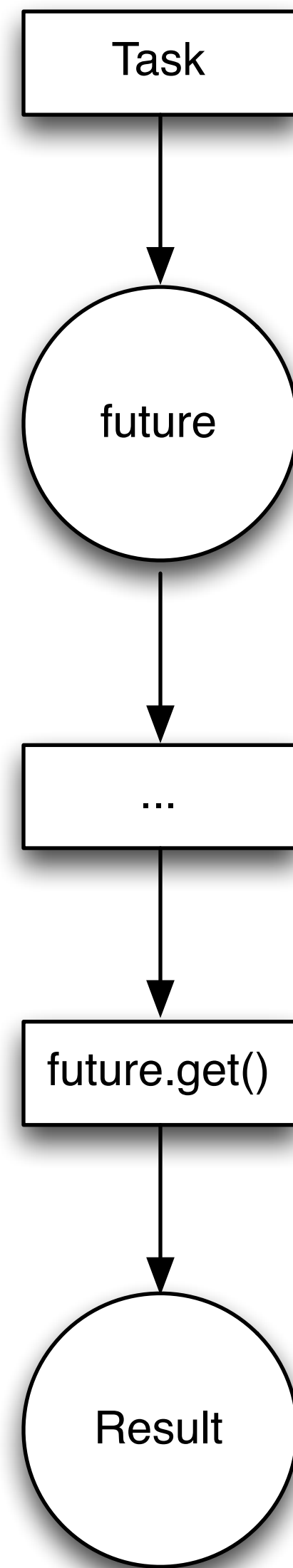
No Raw Synchronization Primitives



No Raw Synchronization Primitives

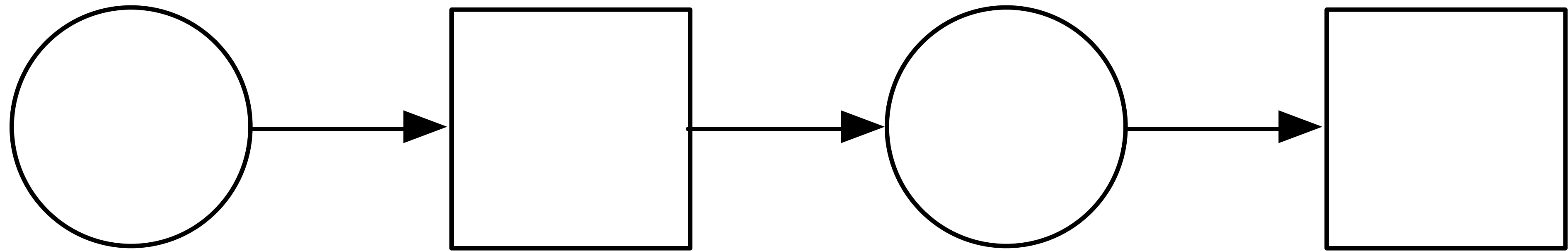


No Raw Synchronization Primitives



Futures: What year is this?

- C++14 futures lack:
 - Continuations - `.then()`
 - Joins - `when_all()`
 - Split
 - Cancellation
 - Progress Monitoring (Except Ready)
- And C++14 futures don't compose (easily) to add these features



- Blocking on `std::future.get()` has two problems
 - One thread resource is consumed, increasing contention
 - Possibly causing a deadlock in our tasking system!
 - Any subsequent non-dependent calculations on the task are also blocked
- C++14 doesn't have continuations
 - GCD has serialized queues and groups
 - PPL has chained tasks
 - TBB has flow graphs
 - TS Concurrency will have `.then()`
 - Boost futures have them now

Futures: Continuations

```
future<cpp_int> x = async([]{ return fibonacci<cpp_int>(1'000); });  
future<void> y = x.then([](future<cpp_int> x){ cout << x.get() << endl; });  
// Do something  
y.wait();
```

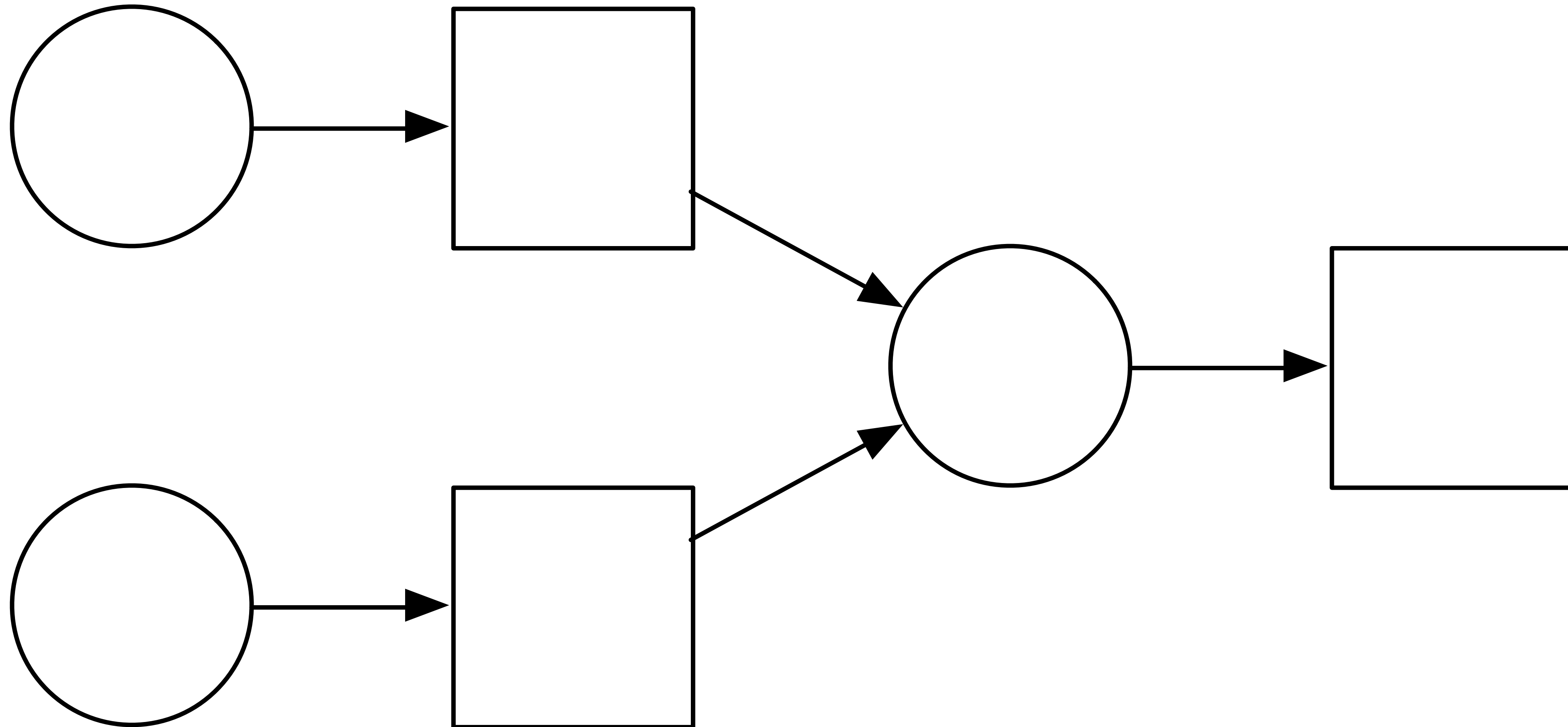
Futures: Continuations

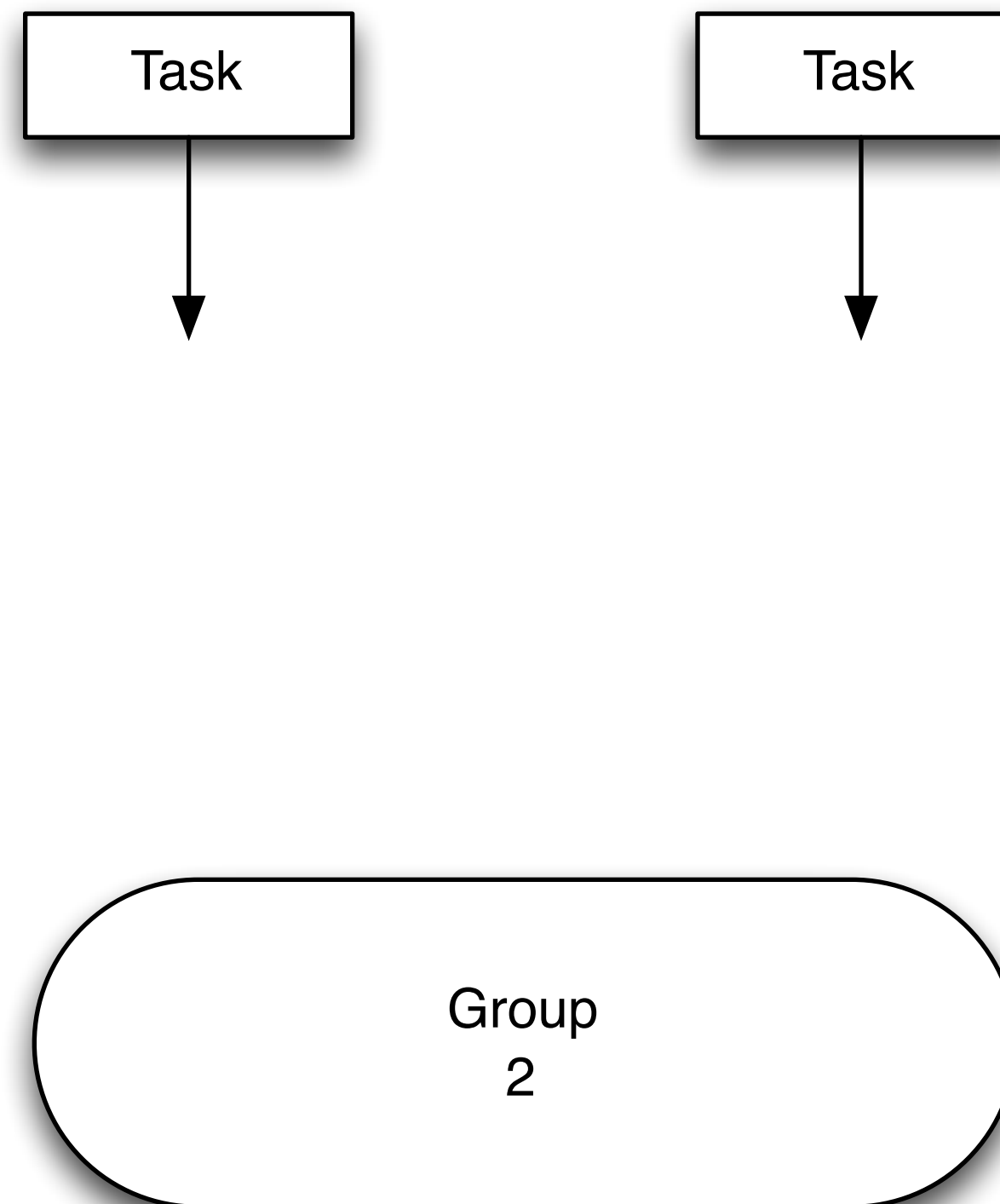
```
future<cpp_int> x = async([]{ return fibonacci<cpp_int>(1'000); });  
  
future<void> y = x.then([](future<cpp_int> x){ cout << x.get() << endl; });  
  
// Do something  
  
y.wait();
```

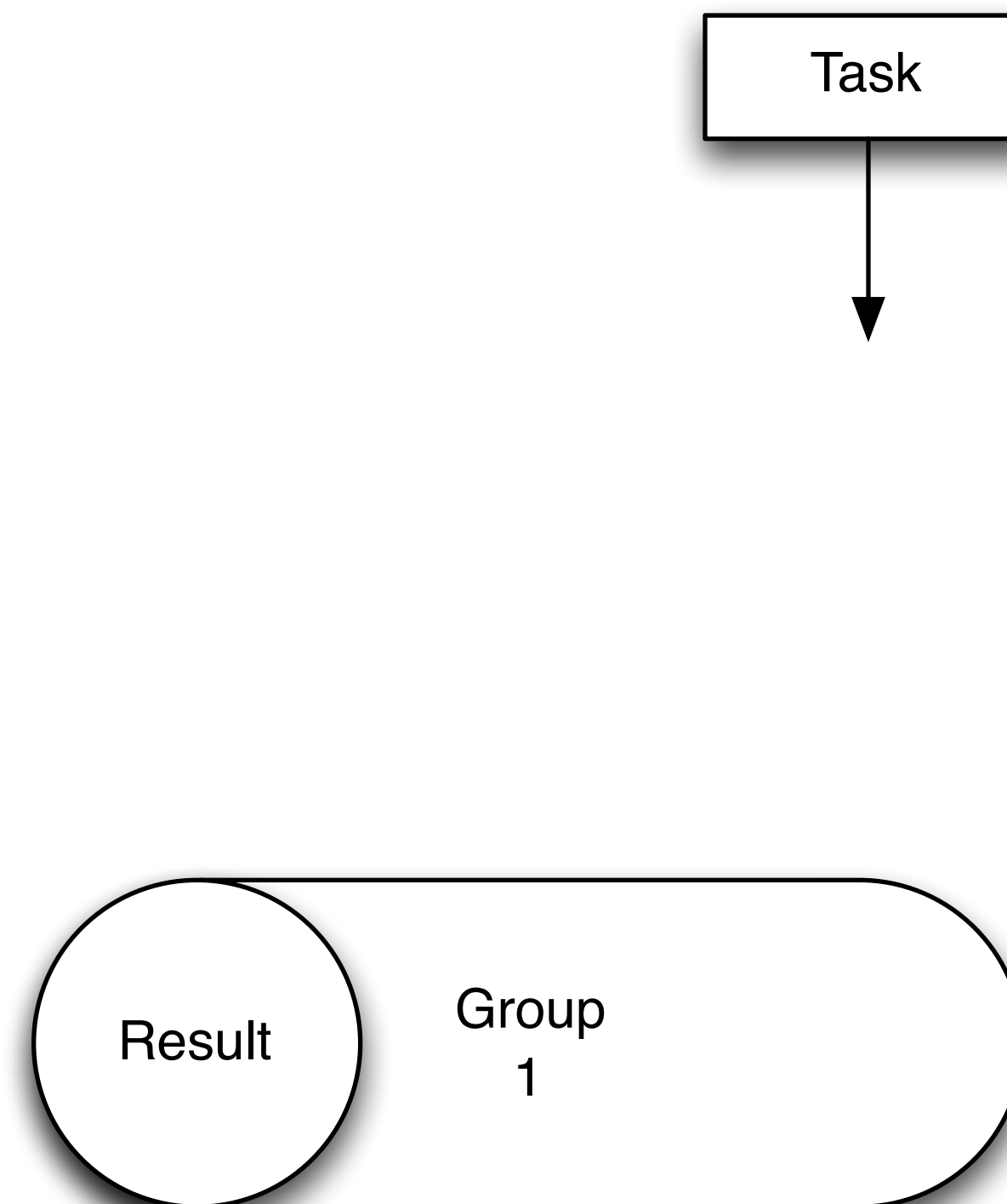
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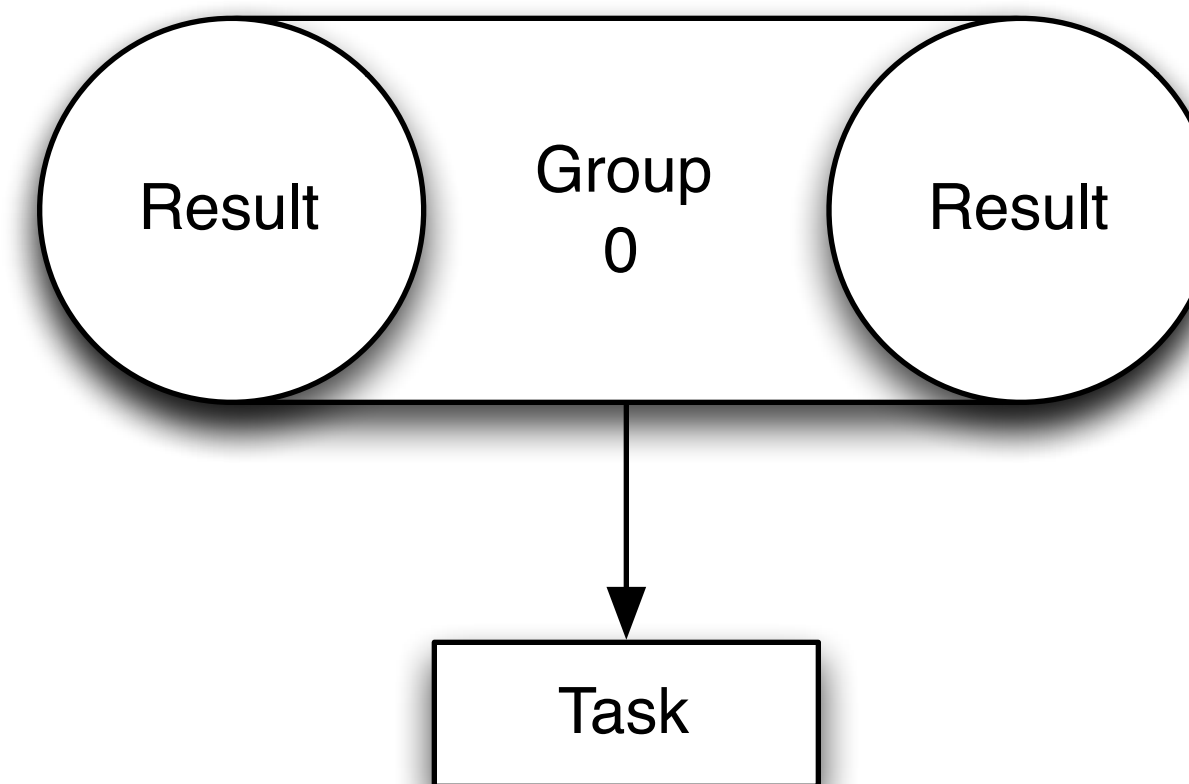
Futures vs Completion Handlers

- Completion handlers are callbacks, they must be known prior to the call
 - No need to synchronize between invoking and setting the continuation
- Futures allow setting the continuation after the sending call is in flight
 - Simpler to compose
 - Require synchronization between invoking and setting the continuation









Futures: Continuations

```
auto x = async([]{ return fibonacci<cpp_int>(1'000'000); });
auto y = async([]{ return fibonacci<cpp_int>(2'000'000); });

auto z = when_all(std::move(x), std::move(y)).then([](auto f){
    auto t = f.get();
    return cpp_int(get<0>(t).get() * get<1>(t).get());
});

cout << z.get() << endl;
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Futures: Continuations

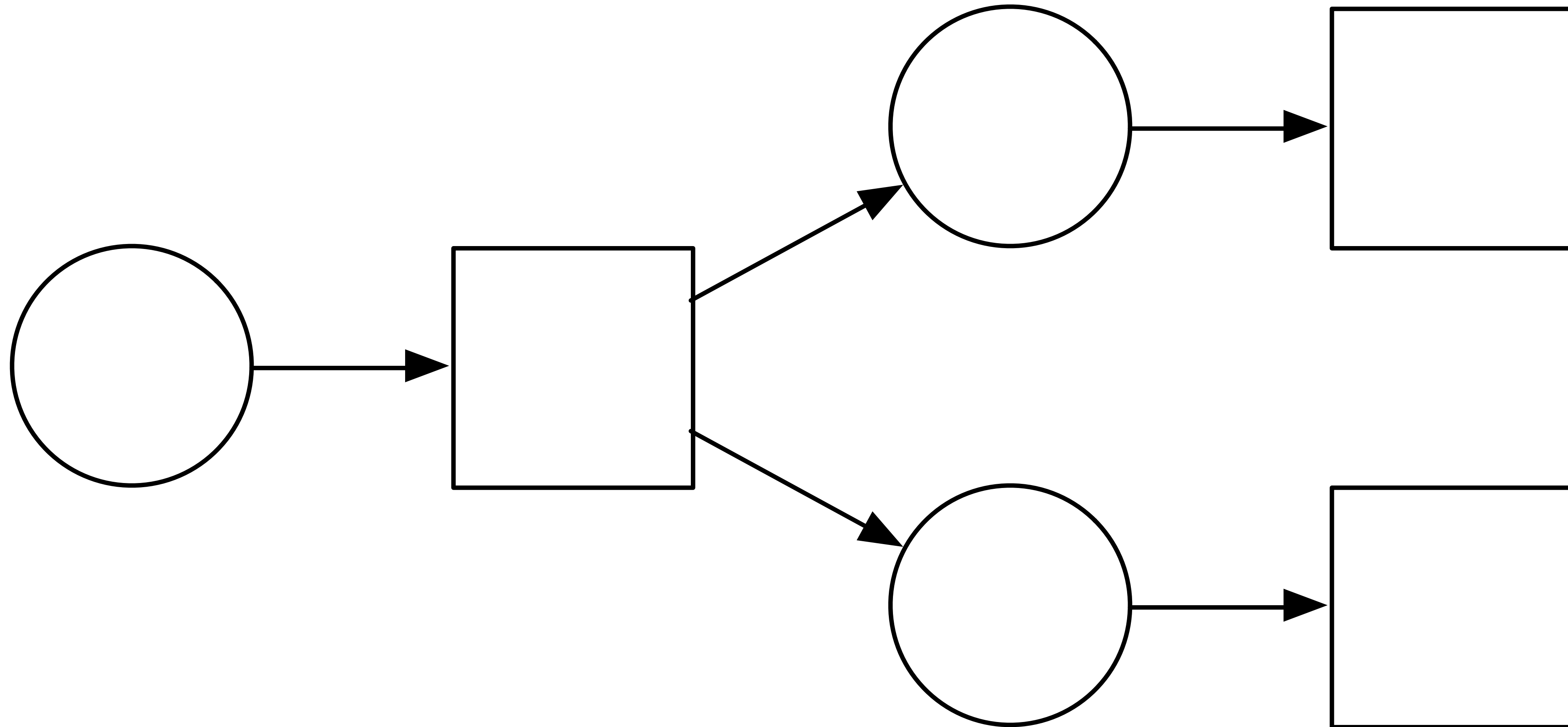
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});

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```

f is a future tuple of futures

result is 626,964 digits



Futures: Continuations

```
future<cpp_int> x = async([]{ return fibonacci<cpp_int>(100); });  
  
future<cpp_int> y = x.then([](future<cpp_int> x){ return cpp_int(x.get() * 2); });  
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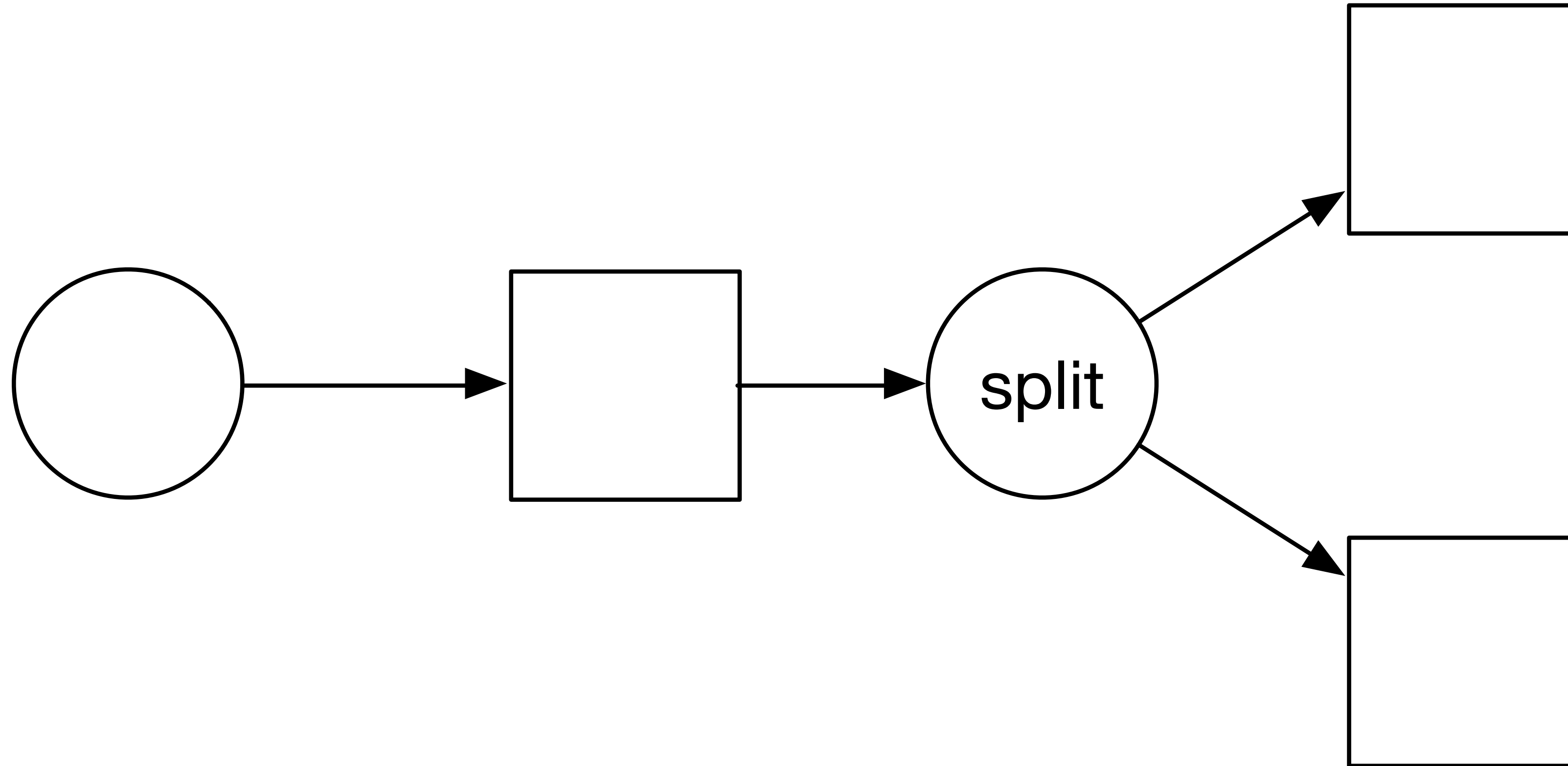
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```

Thread 1: signal SIGABRT

Assertion failed: (px != 0), function operator->, file shared_ptr.hpp, line 648.

- Desired behavior
 - A future should behave as a *regular* type - a token for the actual value
 - `shared_futures` let me “copy” them around and do multiple `get()` operations
 - But not multiple continuations

- We can write a pseudo-copy, `split()`.



Futures: Continuations

```
future<cpp_int> x = async([]{ return fibonacci<cpp_int>(100); });
```

```
future<cpp_int> y = split(x).then([](future<cpp_int> x){ return cpp_int(x.get() * 2); });  
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**708449696358523830150
23614989878617461005**

- Promise is the sending side of a future
- Promises are packaged with a function to form a packaged task
 - Packaged tasks handle the exception marshalling through a promise

Promise

```
promise<int> x;  
future<int> y = x.get_future();  
  
x.set_value(42);  
cout << y.get() << endl;
```

Promise

```
promise<int> x;  
future<int> y = x.get_future();  
  
x.set_value(42);  
cout << y.get() << endl;
```

42

Futures: Split

```
template <typename T>
auto split(future<T>& x) {

    auto tmp = std::move(x);

    promise<T> p;
    x = p.get_future(); // replace x with new future

    return tmp.then([_p = move(p)](auto _tmp) mutable {
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        _p.set_value(value); // assign to new "x" future
        return value; // return value through future result
    });
}
```

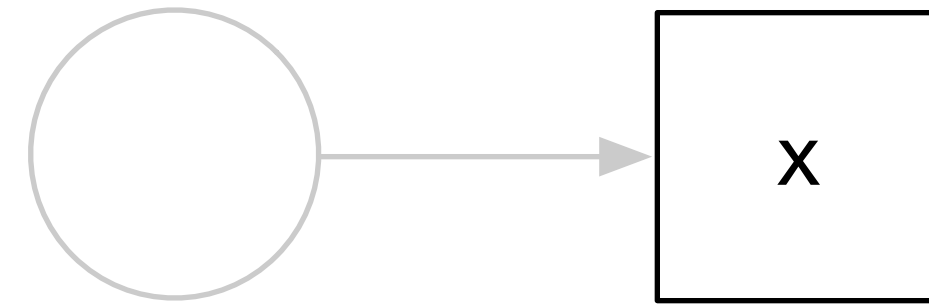
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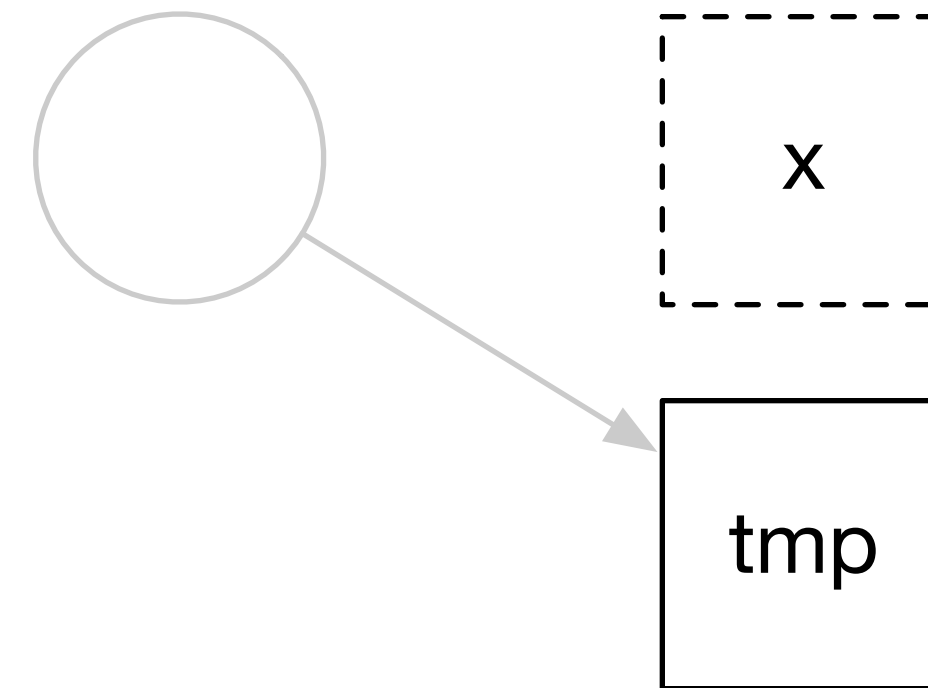


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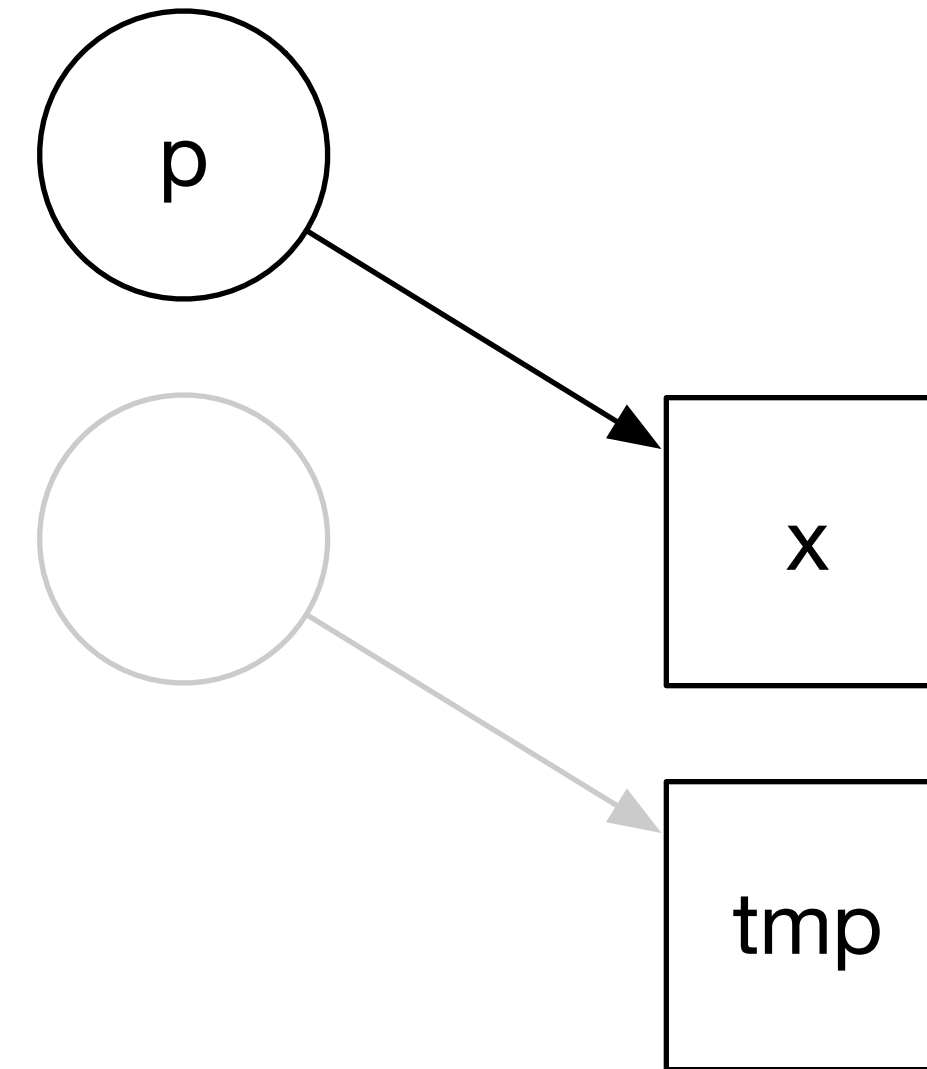


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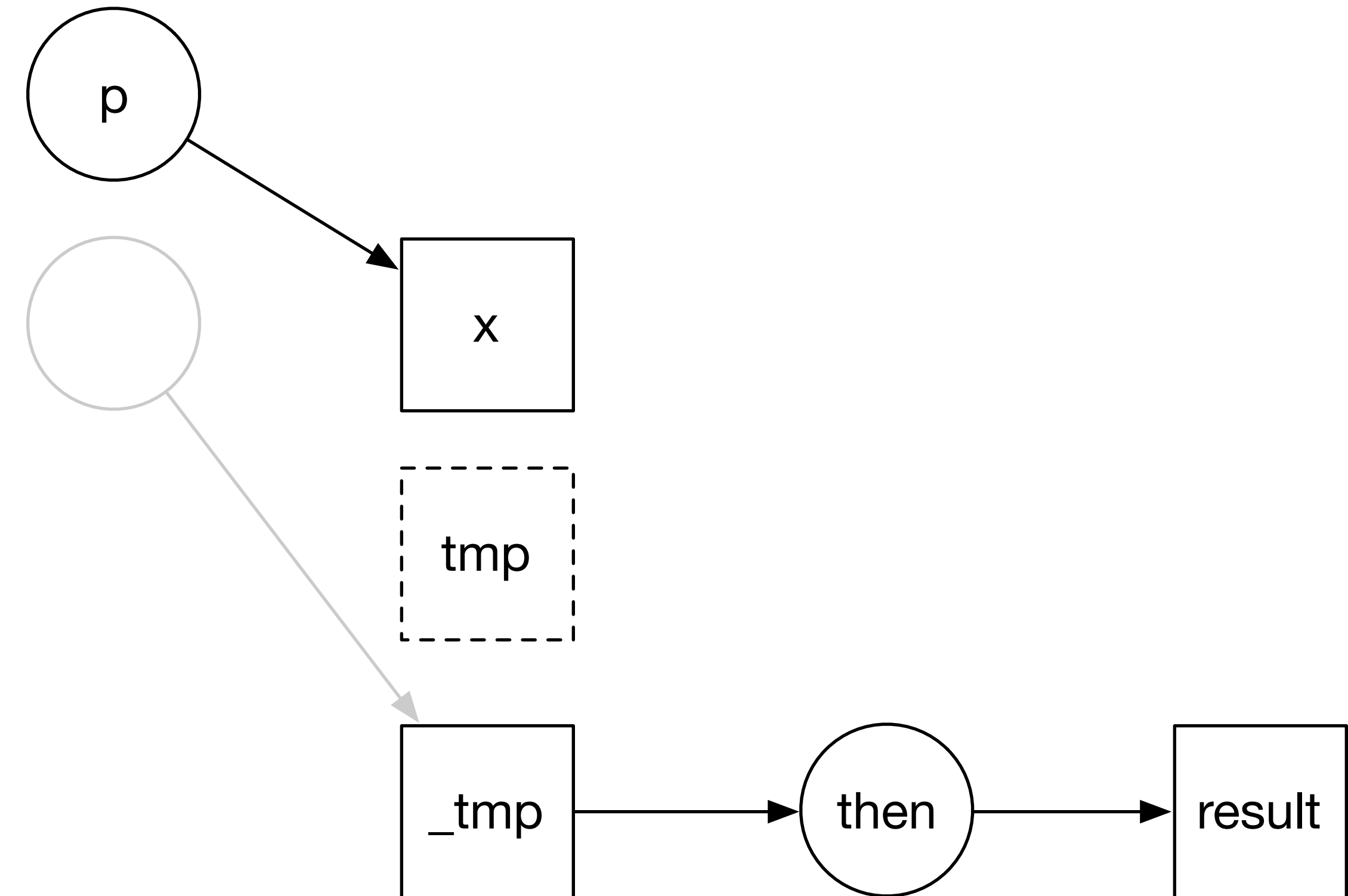


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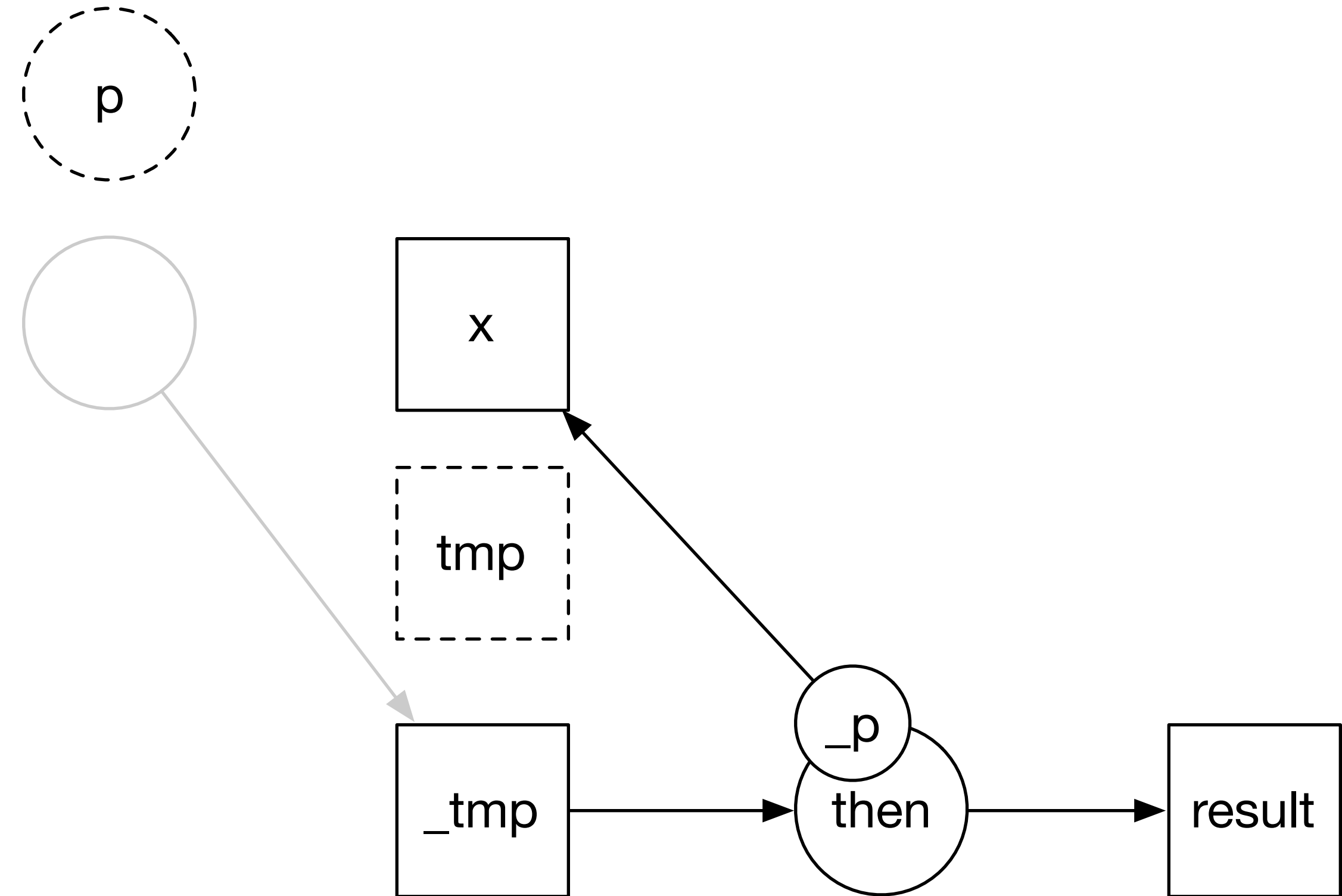
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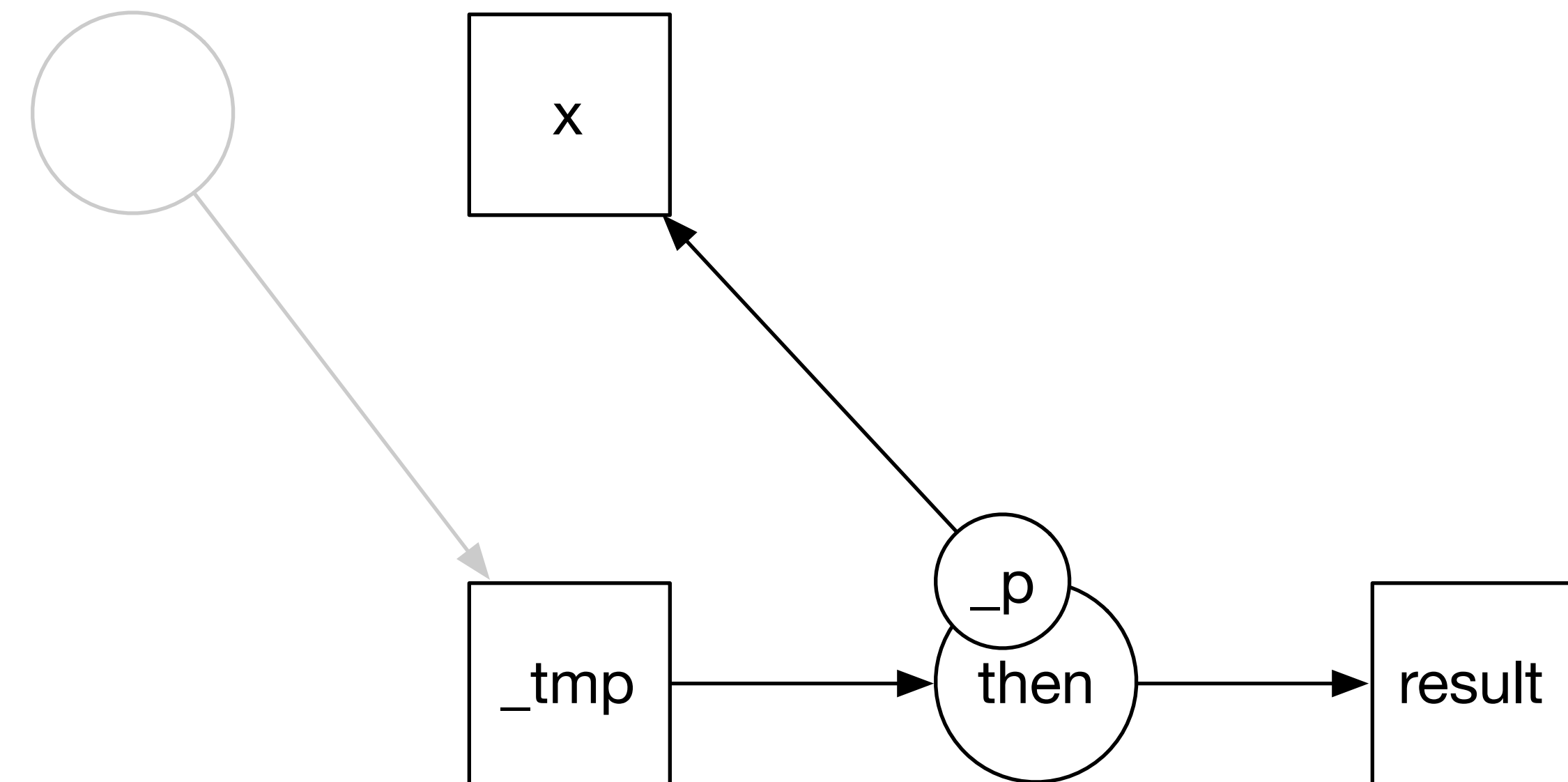
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        if (_tmp.has_exception()) {
            auto error = _tmp.get_exception_ptr();
            _p.set_exception(error);
            rethrow_exception(error);
        }

        auto value = _tmp.get();
        _p.set_value(value); // assign to new "x" future
        return value; // return value through future result
    });
}
```

Futures: Continuations

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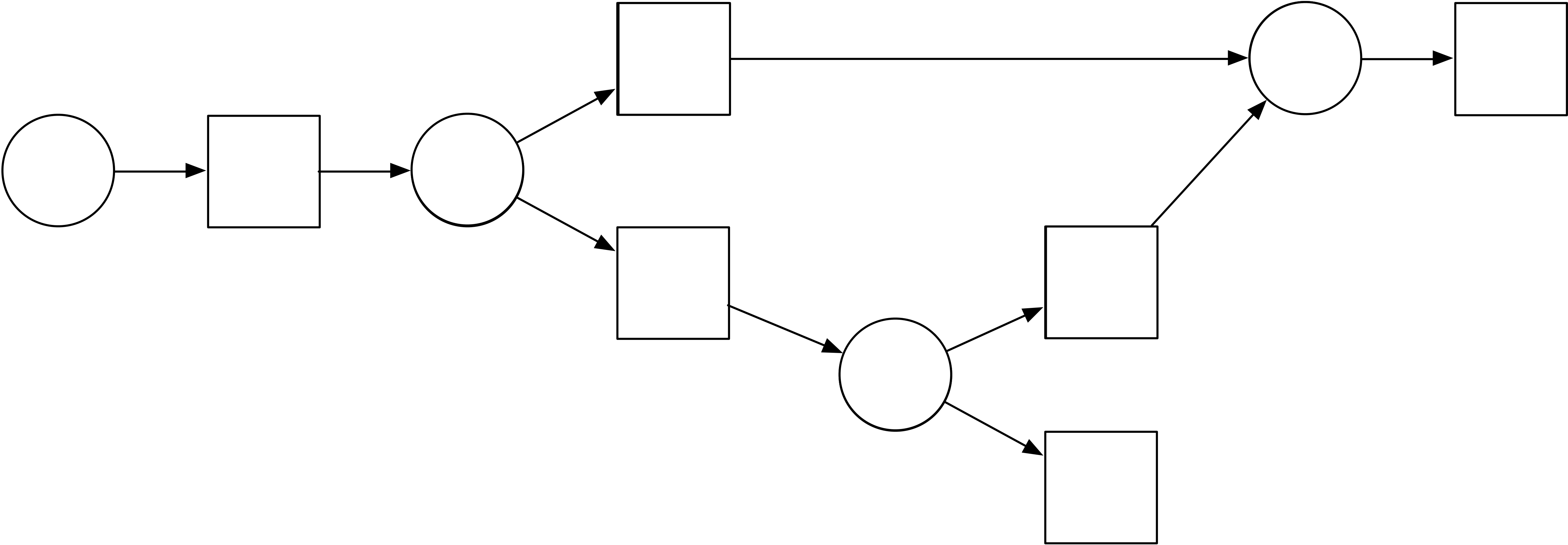
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    cout << get<0>(t).get() << endl;
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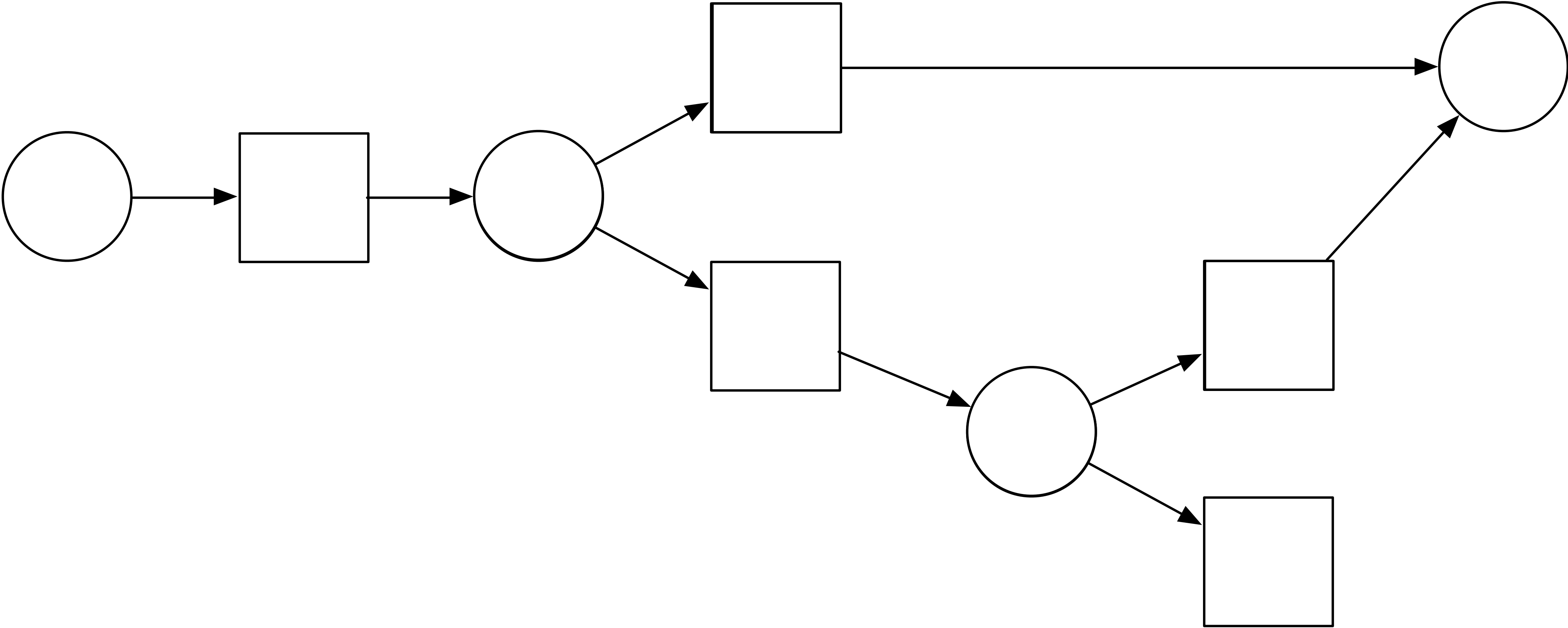
done.wait();
```

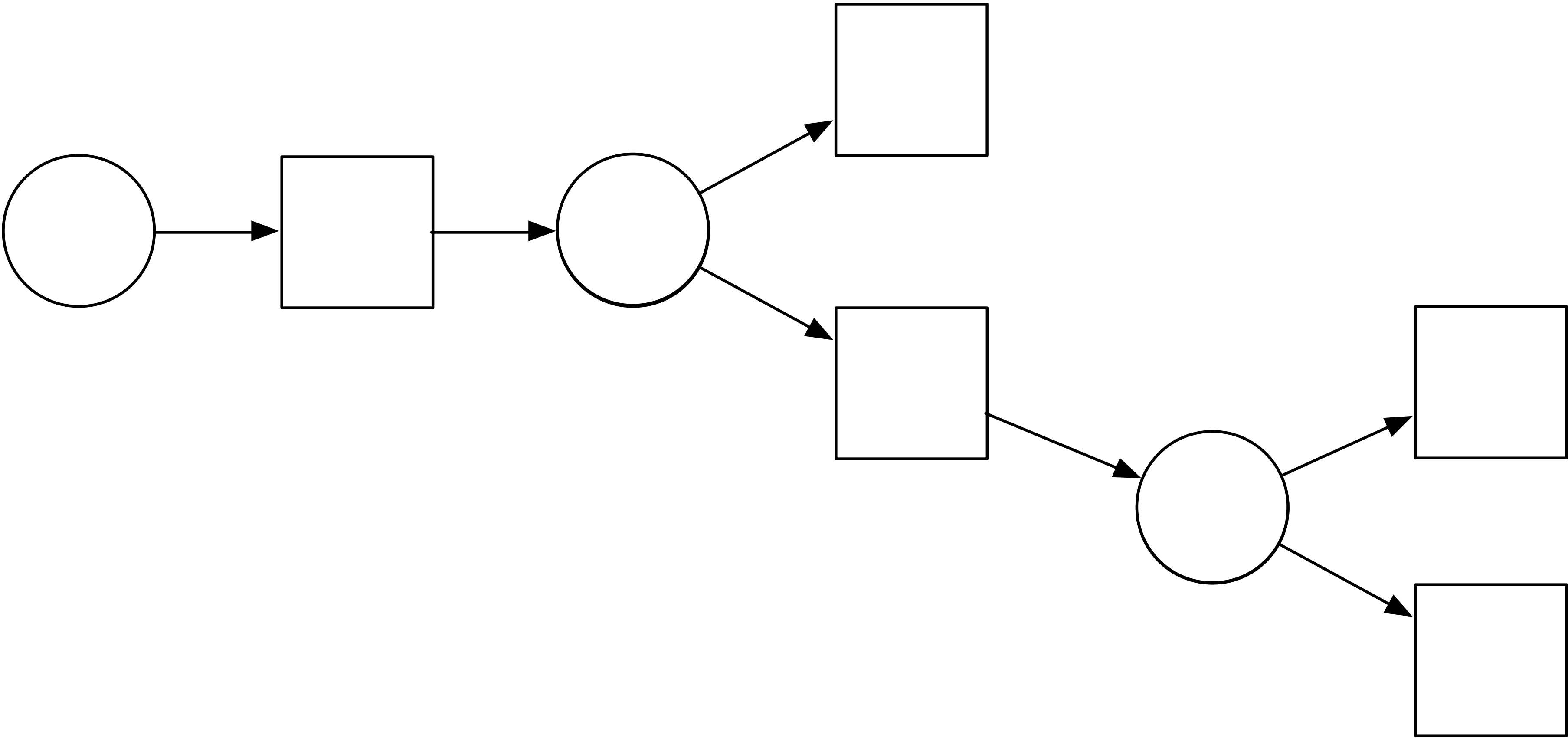
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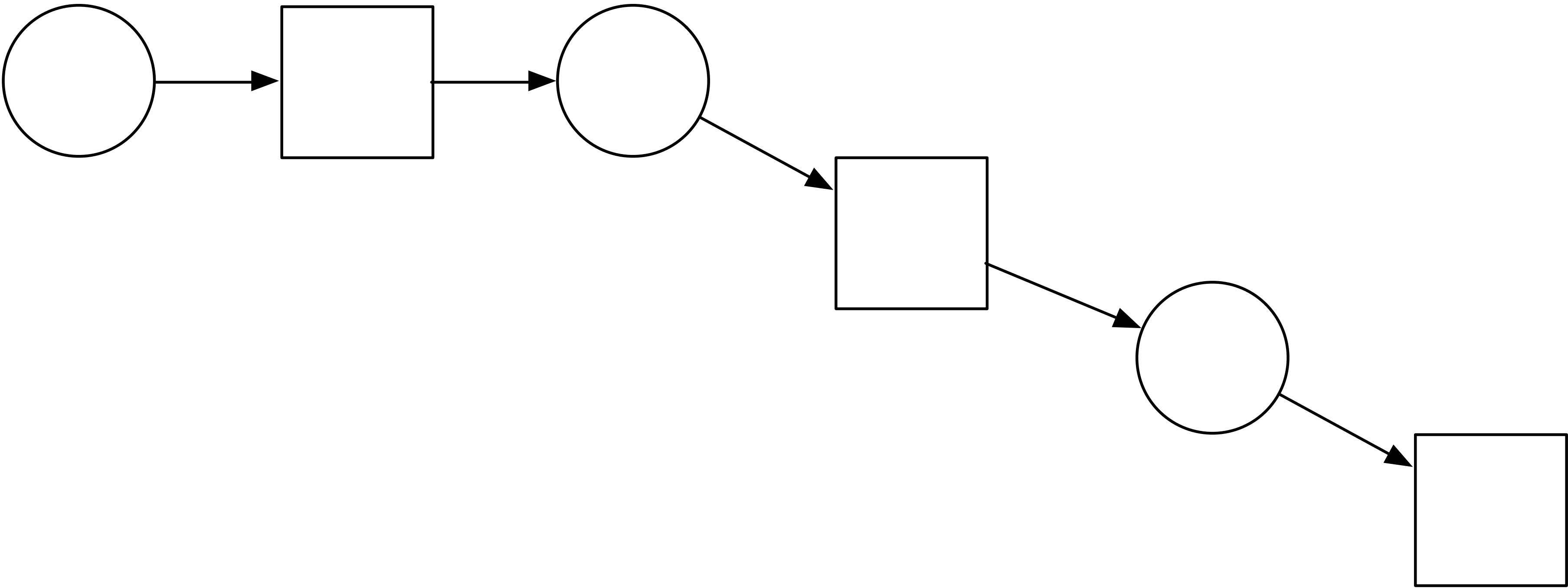

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 - The associated task that has not started, should not execute (NOP)
 - The resource held by that task should be released
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- When the (last) future destructs
 - The associated task that has not started, should not execute (NOP)
 - The resource held by that task should be released
 - Since that task may hold futures for other tasks, the system unravels
- I do not know of a good way to compose such cancellation with current futures
 - Except to create something more complex than re-implementing futures



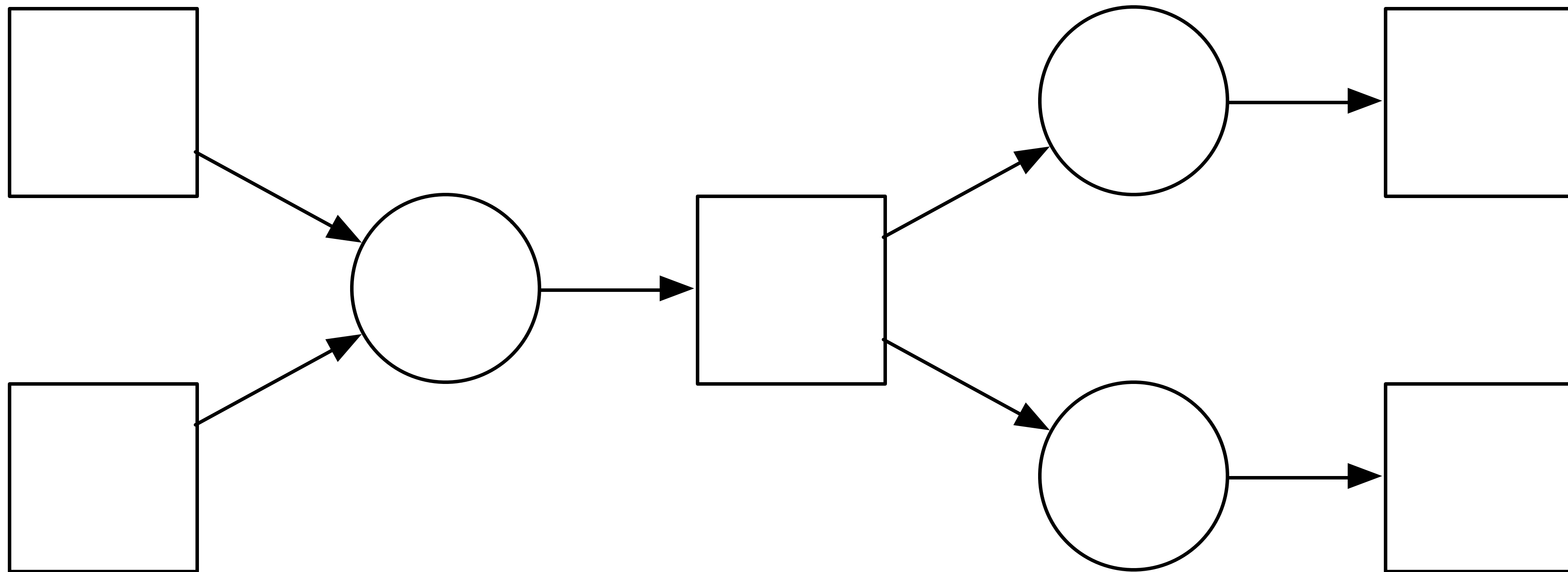






Channels

What if we persist the graph?



What if we persist the graph?

- Allow multiple invocations of the tasks by setting the source values
- Each change triggers a notification to the sink values
 - This is a reactive programming model and futures are known as *behaviors* or *channels*

- Each operation does not have to be a 1:1 mapping of input to output
- Coroutines are one way to write n:m functions

```
channel<int> send;

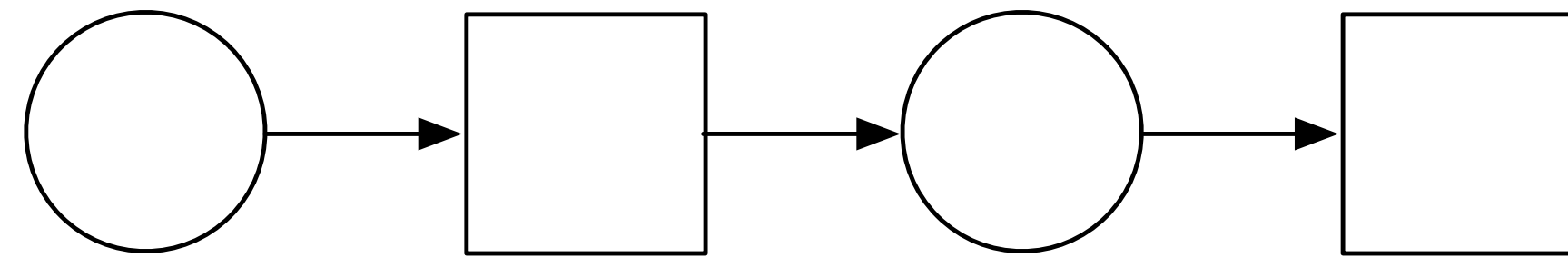
auto hold = send
| [](const receiver<int>& r) {
    int sum = 0;
    while(auto v = co_await r) {
        sum += v.get();
    }
    return sum;
}
| [](int x){ cout << x << '\n'; };

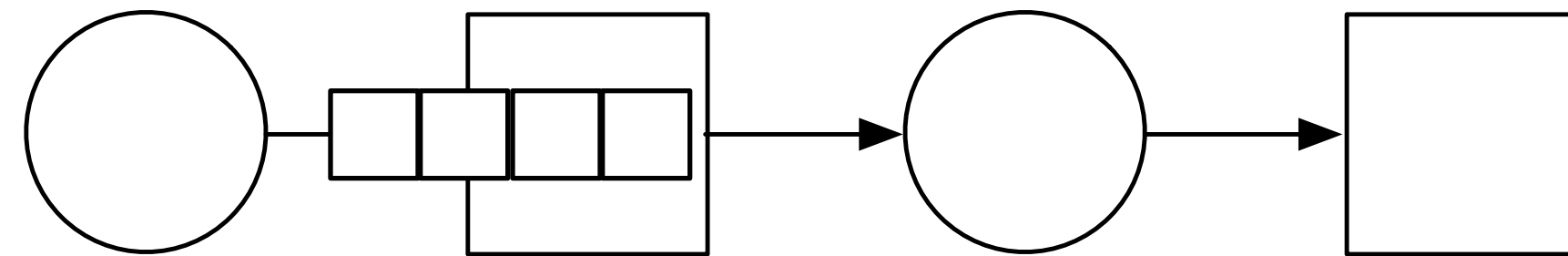
send(1);
send(2);
send(3);
send.close();
```

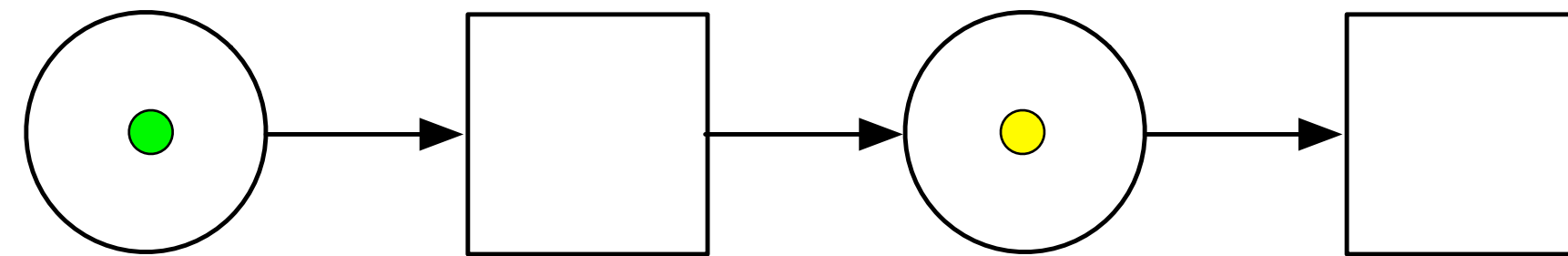
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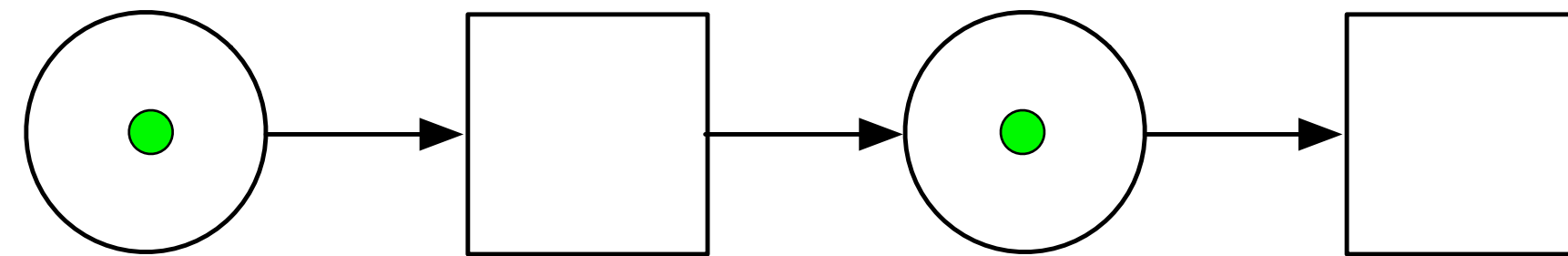
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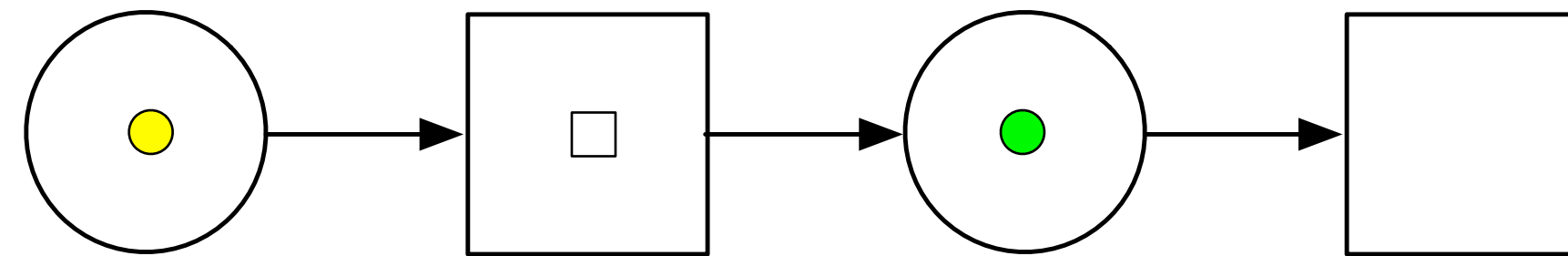
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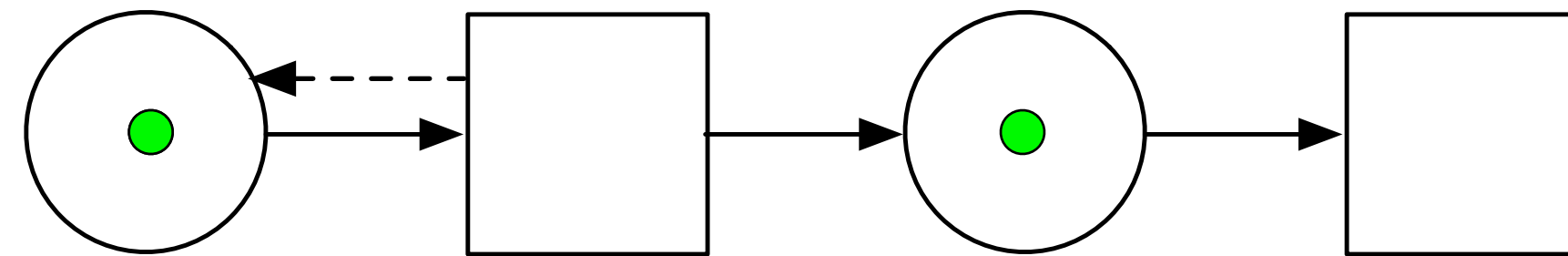



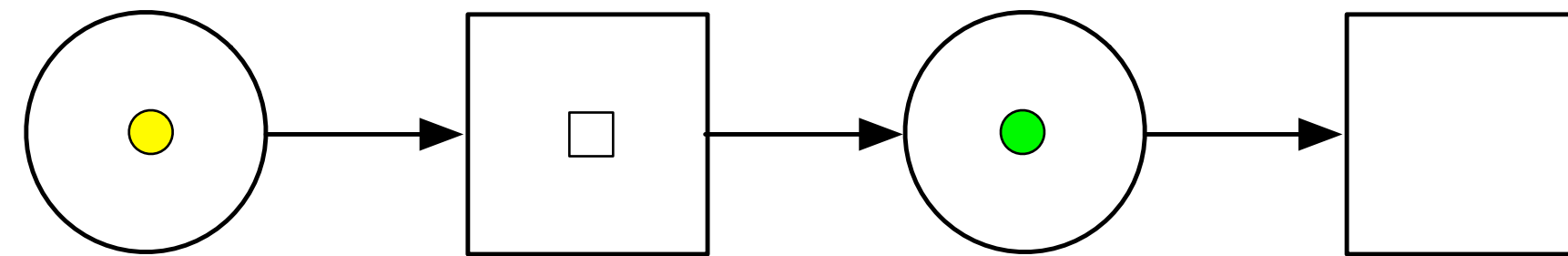






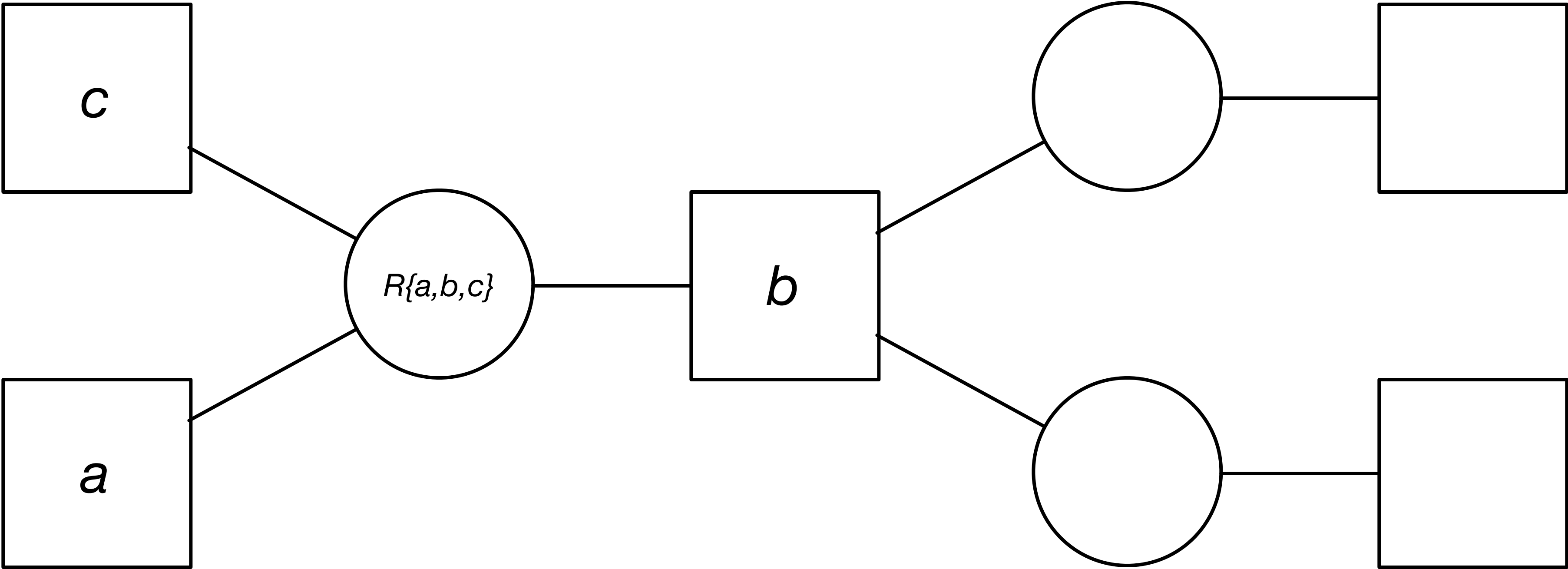






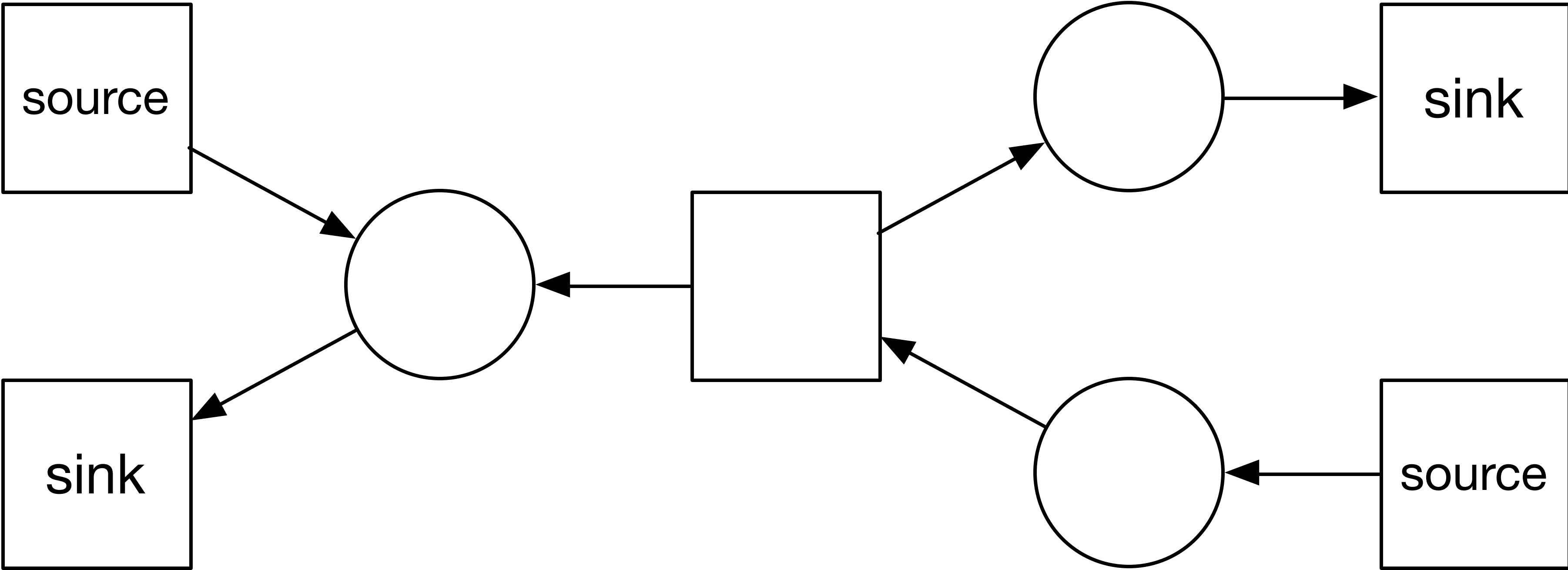
Property Models

How do the graphs change during execution?



A function is a directed relationship

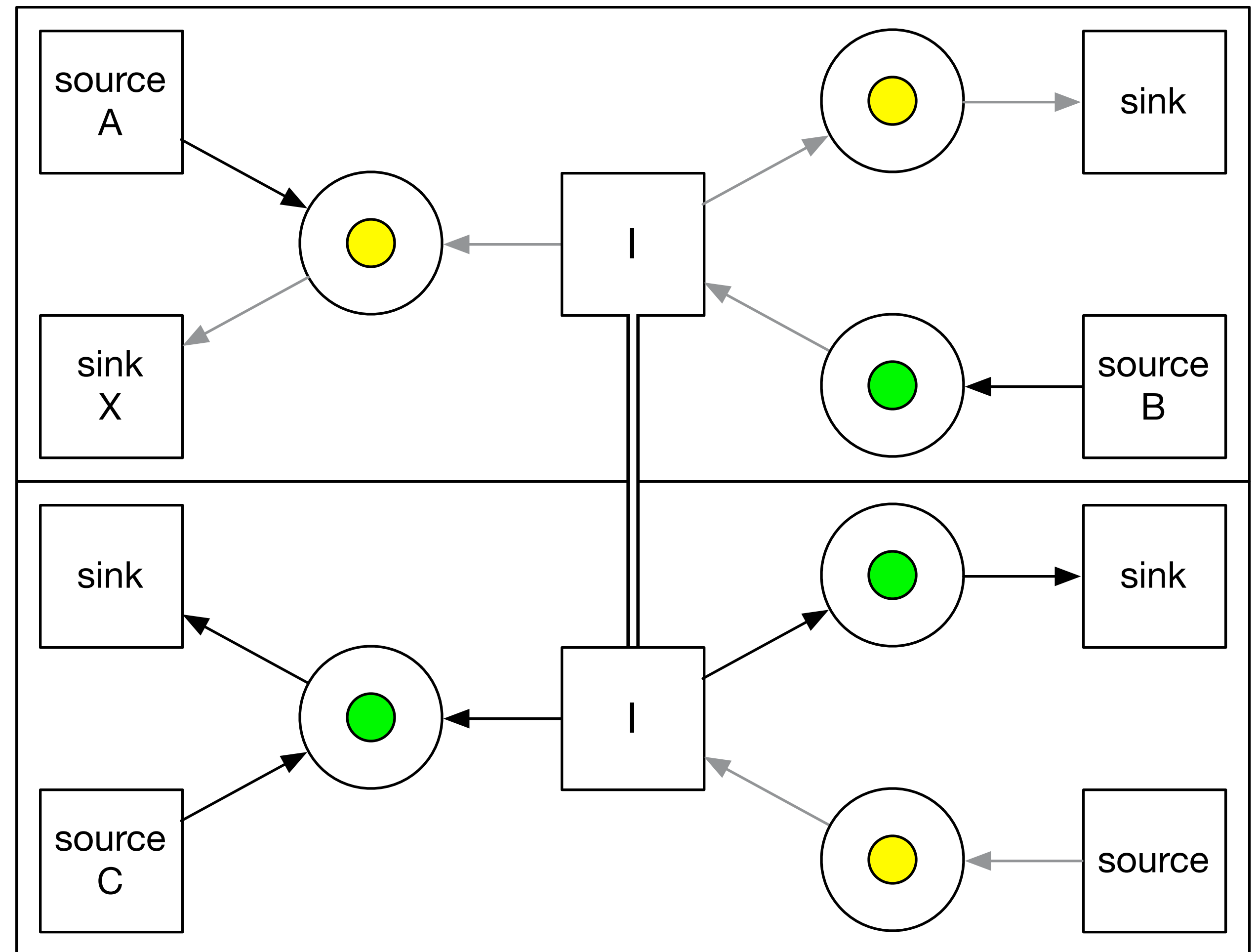
- We can remove the arrows by providing a package of functions to represent the relationship
 - $a = b * c$
 $b = a / c$
 $c = a / b$
 - This forms a type of constraint system called a *property model*
 - Flow is determined by value, or *cell*, priority
 - Relationships can be conditional, so long as predicate can be determined regardless of flow
- Cells can only have one in-edge for a given flow or the system is over constrained

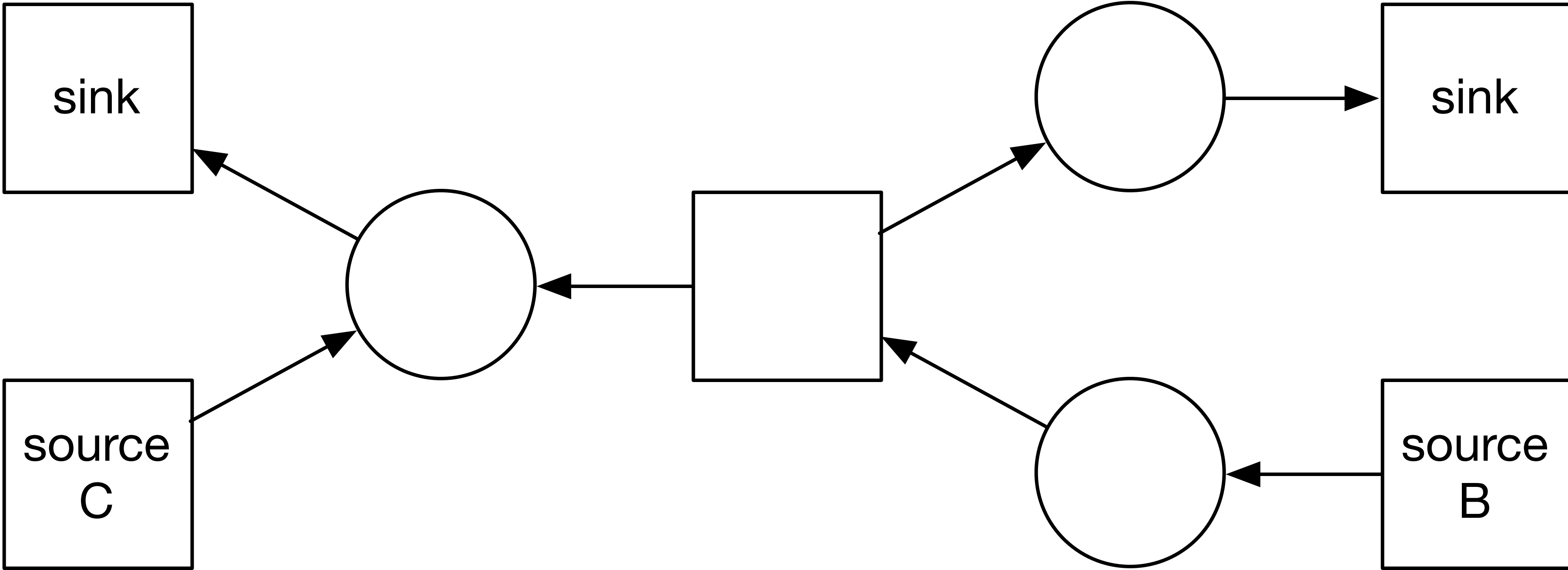


- Reflowing a property model doesn't require all relationships to be resolved
 - The task representing them can still be executing concurrently
- This creates a single dependency graph that is appended to for each new flow and is pruned and *unravels* as tasks are complete

Property Model

- Value set in source A then B
- Operation connected to B is high latency
- Value is set in source C causing reflow
 - Sink X is no longer needed, pending operation is canceled
 - Source A is discarded
 - Intermediate value I is shared between flows, once determined
- Final values determined by source B (via I) and source C





- Very useful for UI behavior
- Significant information is in the graph
 - Source / Derived values form a partition set
 - Easily model checked
 - Equal result regardless of source order
 - Form an operational transform, useful for collaborative editing
 - A value is *implied* by the current state it only has in in-edge
 - Source values determine *intent*
 - Values disconnected from result (sink) are *don't care*

- Perhaps representing such systems *as if* it where imperative code is not the correct approach
- Instead the a graph description can be compiled and statically validated
- Slides and code from talk:
- <http://sean-parent.stlab.cc/papers-and-presentations>
- Experimental future library:
- <https://github.com/stlab/libraries/tree/develop>

No raw synchronization primitives

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Communicating Sequential Tasks

No raw synchronization primitives

Communicating Sequential Tasks

Better Code



Adobe