

## LoRa Boat Monitor

Voltage: 12V (reverse polarity protected, 10 ... 35V DC)

Current: 0.1A (0.15A with relay on)

Power: 1.2W

Frequency: 868MHz

Transmission power: 100mW

Antenna:  $\lambda / 4$ , 5dBi, SWR 1.50, 868MHz, SMA

LoRa channel: EU868 dynamic 0 ... 7 or fixed 0 ... 7 (adjustable via return channel)

US915 / AU915 dynamic 8 ... 15 or fixed 8 ... 15 (adjustable via return channel)

Spreading factor: SF7 ... SF12 (adjustable via return channel)

Send interval: every 300s (5min)

Telegram length: 40 bytes (12 measured values)

GPS: 50 channels, -161dBm, 1Hz, max.2.5m resolution, fix = flashing LED

Float switch: closed = 0, open = 1

Temp sensor: -55 ... + 125 ° C, moisture-proof

Relay: 12V / 3A (adjustable via return channel with time limit)

5V output: 2A, short-circuit proof, **Attention! Do not connect 12V**

## Buttons and LEDs LoRa Modul

PRG: programming (without function)

RST: Reset the software, also triggers a telegram transmission and resets the counter

LED orange: charge status of the Lipo battery (without function, may light up or flicker)

LED white: status of the relay (on: relay active, off: relay inactive)

USB: programming and debug messages, 8N1, 115200Bd

## Conector

	Alarm +12V	Alarm GND	Level sensor 2 signal, 0-180 Ohm	Level sensor 2 GND 0-180 Ohm	DS18B20 Temp sensor, +5V	DS18B20 Temp sensor, 1Wire	DS18B20 Temp sensor, GND
<b>top</b>	<b>AL</b>	<b>AL</b>	<b>TA2</b>	<b>GND</b>	<b>+5V</b>	<b>1W</b>	<b>GND</b>
<b>bottom</b>	<b>+12V</b>	<b>GND</b>	<b>TA1</b>	<b>GND</b>	<b>NC</b>	<b>C</b>	<b>NO</b>
	Power +12V	Power GND	Level sensor 1 signal, 0-180 Ohm	Level sensor 1 GND	Relay Normaly Close	Relay Center	Relais Normaly Open

AL: Potential-free digital alarm input (0V high / 12V low) Float switch, door contact, etc.

TA1 / 2: Tank sensor input 0-180 Ohm

**Caution! Do not connect 12V**

1W: 1Wire data line for external temperature sensor DS18B20 (0 ... 3.3V) Temperature monitoring for battery

**Caution! Do not connect 12V**

Relay: Potential-free changeover switch for 12 ... 24V / 3A

## Display values

A: Alarm input [1 = 0V, 0 = 12V]

C: Telegram counter 0...n

D: Dewpoint [°C]

dT: Send interval [s]

H: rel. Humidity [%]

L: Level value 1 [%]

L2: Level value 2 [%]

P: Air pressure [mbar]

R: State Relay

T: Temperature [°C] (BME280)

T2: Temperature extern [°C] (DS18B20)

X: GPS Longitude [° dez]

Y: GPS Latitude [° dez]

## Decoding Payload

```
var counter = ((bytes[1] << 8) | bytes[0]);  
var temperature = (((bytes[3] << 8) | bytes[2]) / 100) - 50;  
var pressure = ((bytes[5] << 8) | bytes[4]) / 10;  
var humidity = ((bytes[7] << 8) | bytes[6]) / 100;  
var dewpoint = (((bytes[9] << 8) | bytes[8]) / 100) - 50;  
var voltage = ((bytes[11] << 8) | bytes[10]) / 100;  
var tempbattery = (((bytes[13] << 8) | bytes[12]) / 100) - 50;  
var longitude = ((bytes[15] << 8) | bytes[14]) + ((bytes[17] << 8) | bytes[16]) / 10000;  
var latitude = ((bytes[19] << 8) | bytes[18]) + ((bytes[21] << 8) | bytes[20]) / 10000;  
var level1 = ((bytes[23] << 8) | bytes[22]) / 100;  
var level2 = ((bytes[25] << 8) | bytes[24]) / 100;
```

## Coding Return Channel

The following settings can be made with 3 bytes via the LoRa return channel:

- Byte 0 Change relay state with time function
- Byte 1 Setting of the LoRa spreading factor
- Byte 2 Setting of the transmission interval

The values for the spreading factor and transmission interval are permanently saved in the EEPROM and are power off save.

## Meaning

The settings must be entered as hexadecimal values for TTN. It is not necessary that all bytes are transmitted. The relay status can also be changed with just one byte.

Byte 0: 0x00...0xFF (0=off, 1...255 \* 5 min)

Byte 1: 0x07...0x0A (7...10 = SF7...SF10)

Byte 2: 0x01...0xFF (1...255 \* 30s)

## Sample:

0x02 0x0A 0x0A

\_\_\_\_\_ |\_\_\_\_\_ Send interval 300s  
\_\_\_\_\_ |\_\_\_\_\_ Spreading faktor SF10  
\_\_\_\_\_ |\_\_\_\_\_ Relay on for 10 min

0x00                      Relay off

0x00 0x07                Relay off, SF7

The values for Downlink can be entered in the TTN console under Device. Port 1 should be used and the data should be sent with confirmation. The return channel data is only received by the LoRa boat monitor for 2 seconds after the LoRa measured values have been sent out. Depending on the connection quality and the transmission interval setting, it can take several hours until the information is received by the LoRa boat monitor. The relay switch-on time must be selected carefully, as it may not be possible to switch the relay off again for a short time.

**DOWNLINK**

**Scheduling**  

replacefirstlast

**FPort**  

1

**Confirmed**

**Payload**  

bytesfields

00 0A 0A

3 bytes

Send