

EX 5  $p^1$

$$\underline{z} = \begin{pmatrix} x \\ y \end{pmatrix}$$

$$\underline{z}_0 = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\underline{\hat{z}} = \begin{pmatrix} \hat{r} \\ \hat{\phi} \end{pmatrix}$$

$$\underline{v} \sim p_{\underline{v}} \quad \underline{\text{zero mean}} \quad \mathbb{E}(\underline{v}) = \underline{0}$$

$$\underline{\hat{w}} = \underline{w} + \underline{v} = f(\underline{z}) + \underline{v}$$

$$f(\underline{z}) = \begin{pmatrix} \sqrt{x^2 + y^2} \\ \arctan\left(\frac{y}{x}\right) \end{pmatrix}$$

$$\underline{\hat{z}} = f^{-1}(\underline{\hat{w}}) = \begin{pmatrix} \hat{r} \cdot \cos \hat{\phi} \\ \hat{r} \cdot \sin \hat{\phi} \end{pmatrix}$$

(a) find  $p_{\underline{\hat{w}}|\underline{z}} = \int p(\underline{\hat{w}}|\underline{z}, \underline{v}) p(\underline{v}|\underline{z}) d\underline{v}$



$$p(\underline{\hat{w}}|\underline{z}, \underline{v}) = \delta(\underline{\hat{w}} - f(\underline{z}) - \underline{v})$$

both are known  
 $\Rightarrow$  then cond. prob is deterministic

what is  $p_{\underline{\hat{w}}|\underline{w}, \underline{v}} = \frac{p(\underline{\hat{w}}, \underline{w}, \underline{v})}{p(\underline{w}, \underline{v})} \Big|_{\underline{z}=f(\underline{w})} = \frac{p(\underline{\hat{w}}, \underline{v}|\underline{z}) \cdot p(\underline{z})}{p(\underline{v}|\underline{z}) p(\underline{z})}$

$$\underline{\hat{w}} = f(\underline{z}) + \underline{v}$$

$$\text{if } p(\underline{z} > 0)$$

$\rightarrow$  we know pdf of  $\underline{v} = p_{\underline{v}}(\underline{v})$ ,  $\mathbb{E}(\underline{v}) = \underline{0}$

$\Rightarrow$  change of variable formula:

$$\underline{v} = \underline{\hat{w}} - f(\underline{z})$$

$$p_{\underline{\hat{w}}|\underline{z}}(\underline{\hat{w}}|\underline{z}) = \int_{\underline{v} \in \mathcal{V}} p(\underline{\hat{w}}|\underline{z}, \underline{v}) p(\underline{v}|\underline{z}) d\underline{v}$$

$$= \int_{\underline{v} \in \mathcal{V}} \delta(\underbrace{\underline{\hat{w}} - f(\underline{z}) - \underline{v}}_{\underline{v} = \underline{\hat{w}} - f(\underline{z})}) p(\underline{v}|\underline{z}) d\underline{v}$$

$$= p_{\underline{v}|\underline{z}=\underline{z}}(\underline{\hat{w}} - f(\underline{z})|\underline{z})$$

noise can depend on  $\underline{z}$

(b)  $E(\hat{\omega} | z) = ?$

unbiased?

EX 5

$$E_{\hat{\omega}|z}(\hat{\omega}) = \int_{\hat{\omega} \in \hat{\Omega}} \hat{\omega} \cdot p_{\hat{\omega}|z}(\hat{\omega} | z) d\hat{\omega}$$

p2

$$= \int \hat{\omega} p_V(\hat{\omega} - f(z) | z) d\hat{\omega}$$

$$\hat{\omega} = f(z) + v$$

$$= \int (f(z) + v) p_V(v | z) dv$$

= 0 zero mean

$$= \int f(z) p_V(v | z) dv + \int v p_V(v | z) dv$$

$$= \int \frac{p(v, z)}{p(z)} dv = \frac{p(z)}{p(z)} = 1$$

if  $v$  and  $z$  indep.

$$= f(z)$$

$$\text{then } p(v, z) = p(v)p(z)$$

$$\text{and } \int v p(z) p(v) dv \text{ vanishes}$$

otherwise not true...

if  $v$  and  $z$  independent

$$\Rightarrow p(v | z) = p(v)$$

# EX 5 p 3

$$P_{\underline{v}} = P_{v_r} \cdot P_{v_\phi} \quad \text{independent}$$

assume  $\underline{z}$  and  $\underline{v}$  independent

$$\Rightarrow P_{\hat{\underline{w}}|\underline{z}} = P_{\underline{v}}(\hat{\underline{w}} - \underline{f}(\underline{z}))$$

$$E_{\hat{\underline{w}}|\underline{z}}(f^{-1}(\hat{\underline{w}})) = (*)$$

$$f^{-1}(\hat{\underline{w}}) = \begin{pmatrix} \hat{r} \cos \hat{\phi} \\ \hat{r} \sin \hat{\phi} \end{pmatrix}$$

$$P_{\underline{v}} = P_{v_r} \cdot P_{v_\phi}$$

$$P_{\underline{v}}(\hat{\underline{w}} - \underline{f}(\underline{z}))$$

$$(*) = \int_{v_r} \int_{v_\phi} \begin{pmatrix} \hat{r} \cos \hat{\phi} \\ \hat{r} \sin \hat{\phi} \end{pmatrix} P_{v_r} \cdot P_{v_\phi} dv_r dv_\phi$$

$$E_{\hat{\underline{w}}|\underline{z}}(f^{-1}(\hat{\underline{w}})) = \begin{pmatrix} E_{\hat{\underline{w}}|\underline{z}}(\hat{r} \cos \hat{\phi}) \\ E_{\hat{\underline{w}}|\underline{z}}(\hat{r} \sin \hat{\phi}) \end{pmatrix}$$

$$E_{\hat{\underline{w}}|\underline{z}}(\hat{r} \cos \hat{\phi}) = \int_{v_r} \int_{v_\phi} \hat{r} \cos \hat{\phi} P_{v_r} P_{v_\phi} dv_r dv_\phi$$

$$= \int_{v_r} \int_{v_\phi} \hat{r} \cos \hat{\phi} P_{v_r}(v_r) P_{v_\phi}(v_\phi) dv_r dv_\phi$$

$$= \int_{v_r} \int_{v_\phi} (r + v_r) \cos(\phi + v_\phi) P_{v_r}(v_r) P_{v_\phi}(v_\phi) dv_r dv_\phi$$

$$= (*)$$

# EX5 p4

$$\begin{aligned}
 (*) &= \int_{v_r} (x + v_r) p_{v_r}(v_r) dv_r \cdot \int_{v_\varphi} \cos(\varphi + v_\varphi) p_{v_\varphi}(v_\varphi) dv_\varphi \\
 &= \left( x \underbrace{\int_{v_r} p_{v_r}(v_r) dv_r}_{=1} + \underbrace{\int_{v_r} v_r p_{v_r}(v_r) dv_r}_{=0} \right) \cdot \int_{v_\varphi} \cos(\varphi + v_\varphi) p_{v_\varphi}(v_\varphi) dv_\varphi \\
 &= x \cdot \underbrace{\int_{v_\varphi} \cos(\varphi + v_\varphi) p_{v_\varphi}(v_\varphi) dv_\varphi}_{\stackrel{?}{=} \cos \varphi} \quad \text{is it unbiased?}
 \end{aligned}$$

not in general = counterexample...

$$p_{v_\varphi}(v_\varphi) = \begin{cases} \frac{1}{2} & v_\varphi \in [-1, 1] \\ 0 & \text{else} \end{cases}$$

$$\begin{aligned}
 \Rightarrow \int_{-1}^1 \cos(\varphi + v_\varphi) \frac{1}{2} dv_\varphi &= \frac{1}{2} \sin(\varphi + v_\varphi) \Big|_{-1}^1 = \frac{1}{2} \sin(\varphi + 1) \\
 &\quad - \frac{1}{2} \sin(\varphi - 1) \\
 &= \cos \varphi \cdot \sin(1)
 \end{aligned}$$

$$\frac{1}{2} (\sin(x) - \sin(y)) = \cos\left(\frac{x+y}{2}\right) \cdot \sin\left(\frac{x-y}{2}\right) \neq \cos \varphi$$

$$\begin{aligned}
 \frac{1}{2} (\sin(x+1) - \sin(x-1)) &= \cos\left(\frac{x+1+x-1}{2}\right) \sin\left(\frac{x+1-x+1}{2}\right) \\
 &= \cos(x) \cdot \sin(1) \neq \cos(x)
 \end{aligned}$$

same for  $E_{\hat{w}|z}(\hat{x} \cdot \sin \hat{\varphi}) \rightarrow$  not unbiased

(d)  $\{\hat{\omega}_n\}_{n=1}^N$

$$\hat{\Xi}_A = f^{-1} \left( \underbrace{\frac{1}{N} \sum_n \hat{\omega}_n}_{\approx E(\hat{\omega})} \right)$$

$$\begin{aligned} \frac{1}{N} \sum_n \hat{\omega}_n &\approx E(\hat{\omega}) = E(\underline{\omega} + \underline{v}) \\ &= E(\underline{\omega}) + E(\underline{v}) \end{aligned}$$

$\Rightarrow \hat{\Xi}_A$  asymptotically unbiased

$$= \underline{\omega} + \underline{0}$$

if  $E(\underline{v}) = 0$  zero mean

$$\hat{\Xi}_B = \frac{1}{N} \sum_n f^{-1}(\hat{\omega}_n) \approx E(f^{-1}(\hat{\omega}))$$

from (c) BIASED