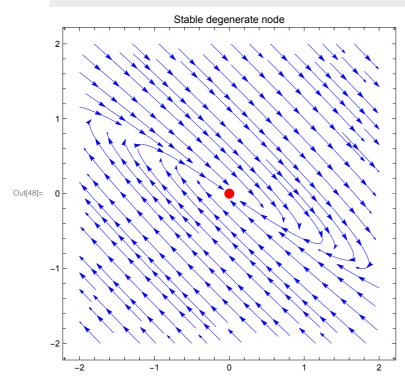
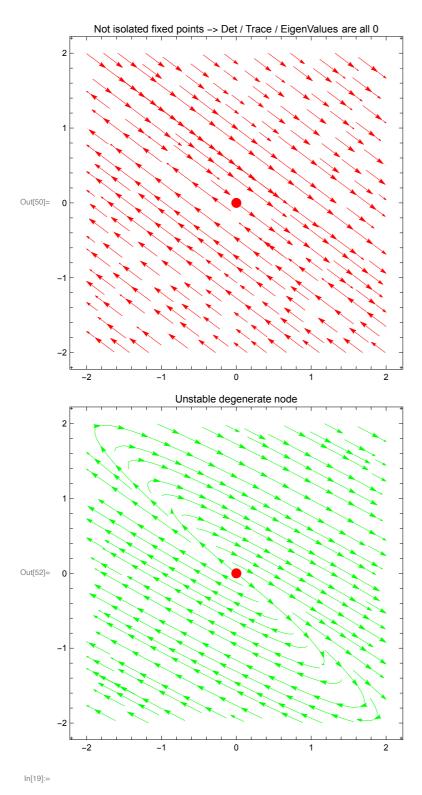
2.1 Degenerate System

a) Plot the trajectories for sigma = {-1,0,1}

```
(*sigma = -1*)
sigma = -1;
p1=StreamPlot[{(sigma + 3)*x +4*y , -(9/4)*x + (sigma-3)y},{x,-2,2},{y,-2,2},
StreamColorFunction→None , StreamStyle→Blue, PlotLabel→"Stable degenerate node", Epilor
sigma = 0;
p2=StreamPlot[{(sigma + 3)*x +4*y , -(9/4)*x + (sigma-3)y},{x,-2,2},{y,-2,2},
StreamColorFunction→None , StreamStyle→Red, PlotLabel→"Not isolated fixed points -> Desigma = 1;
p3=StreamPlot[{(sigma + 3)*x +4*y , -(9/4)*x + (sigma-3)y},{x,-2,2},{y,-2,2},
StreamColorFunction→None , StreamStyle→Green, PlotLabel→"Unstable degenerate node", Epilor
StreamColorFunction→None , StreamSty
```





To determine the stability, check the determinant of A

```
ClearAll["Global`*"]
Clear[sigma]
A = \{\{(sigma+3), 4\}, \{-(9/4), sigma-3\}\};
det = Det[A]//Simplify
trac = sigma + 3 + sigma -3
Parabola = trac^2 - 4 * det
```

```
Out[23]= sigma<sup>2</sup>
Out[24]= 2 sigma
Out[25]= 0
```

One sees that for all values of σ the equation of the parabola = 0. Therefore we always move on that parabola and have a stable σ <0, an unstable degenerate node σ >0 and a center for σ =0. The signs of the the eigenvalues λ determine if the flow is going inwards the stable point or outwards

a)
$$\dot{x} = (\sigma + 3)x + 4y$$

$$\dot{y} = -\frac{7}{4}x + (\sigma - 3)y$$

$$A = \begin{pmatrix} \frac{3x}{3x} & \frac{3x}{3y} \\ \frac{3y}{3x} & \frac{3y}{3y} \end{pmatrix} = \begin{pmatrix} \sigma + 3 & 4 \\ -\frac{9}{4} & \sigma - 3 \end{pmatrix}$$

$$O = 0$$

$$A(0) = \begin{pmatrix} 3 & 4 \\ -\frac{7}{4} & \frac{3}{4} & \frac{3}{4} \end{pmatrix}$$

$$Y = 0$$

$$(\sigma + 3)(\sigma - 3) - (-\frac{9}{4})y$$

$$0 = -9 - (-9) = 0$$

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b) -> eigVal of A

```
In[26]:= Clear[sigma];(*Clears any previous definition of sigma*)
        A = \{\{(sigma + 3), 4\}, \{-(9/4), sigma - 3\}\}
        Eigenvalues[A] // Simplify
Out[27]= \left\{ \left\{ 3 + \text{sigma, 4} \right\}, \left\{ -\frac{9}{4}, -3 + \text{sigma} \right\} \right\}
Out[28]= { sigma, sigma}
```

c) -> eigVec of A

```
In[29]:= Eigenvectors[A]
Out[29]= \left\{ \left\{ -\frac{4}{3}, 1 \right\}, \{0, 0\} \right\}
 In[30]:= \left\{ \left\{ -\frac{4}{3}, 1 \right\}, \{0, 0\} \right\}
           (*Rewrite by hand to norm → other PDF*)
          eigV = \{-4/3, 1\};
          n = Norm[eigV];
          solC = (-1) * eigV / n
Out[30]= \left\{ \left\{ -\frac{4}{3}, 1 \right\}, \{0, 0\} \right\}
Out[33]= \left\{ \frac{4}{5}, -\frac{3}{5} \right\}
```

d) -> A^{-1}

In[34]:= A_inv = Inverse[A] // MatrixForm // Simplify sigma²

e) -> for which sigma is A singular -> det == 0

f) find the direction of the line o the fixed points

$$| |_{138} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28} | |_{28}$$