

3.3 Homoclinic bifurcation

Deadline: 29 Nov 23:59



(4 points)

See exercise 8.4.3 and 8.4.12 in Strogatz

Consider the dynamical system

$$\mu = 2x$$

$$\begin{aligned}\dot{x} &= \mu x + y - x^2 = 0 \\ \dot{y} &= -x + \mu y + 2x^2, = 0\end{aligned}$$

where μ is a dimensionless parameter.

$$\mu x + y - x^2 = -x + \mu y + 2x^2$$

$\mu < \mu_c$ verschwindet FP
 $\mu > \mu_c$ gesamt FP

- a) Using a numerical method of your choice, find the value $\mu = \mu_c$ where the system undergoes a homoclinic bifurcation. Give your result with two significant digits.

μ

A A A

- b) Plot the phase portraits that occur for the cases $\mu < 0$, $\mu = 0$, $0 < \mu < \mu_c$, $\mu = \mu_c$ and $\mu > \mu_c$, marking and labelling fixed points, closed orbits, limit cycles and homoclinic orbits. Use a numerical solver, for example NDSolve[] in Mathematica (using StreamPlot[] will not give enough resolution for this task). [Upload the portraits as .png images or as .pdf](#).

In order to find out how the period of a closed orbit scales as a homoclinic bifurcation is approached, it is useful to first estimate the time it takes for an orbit to pass a saddle point. To estimate the time to pass a generic saddle, consider the linearised dynamics

$$\begin{aligned}\dot{x} &= ux \\ \dot{y} &= sy\end{aligned}$$

where u and s are the eigenvalues of the unstable and stable directions respectively, i.e. $u > 0$ and $s < 0$.

Now, let a trajectory start from the point

$$(x(0), y(0)) = (\gamma, 1),$$

$$\gamma = 0.01$$

where $\gamma > 0$ is small.

- c) Find an analytical expression for the time t_1 to escape from the saddle to $x(t_1) = 1$. [Answer in term of \$\gamma\$ and \$u\$, even if OpenTA does not specify that.](#)

(in terms of gamma, u)

A A A

- d) Find an analytical expression for u suitable for the system in Eq. (1).

(in terms of mu)

A A A

The time of the periodic orbit, T_μ , just below the homoclinic bifurcation where $\mu < \mu_c$ and $|\mu - \mu_c| \ll 1$ is well approximated by the time it takes to pass the saddle point, i.e. it depends only on u and γ . Hence, to find T_μ we first need to investigate how γ depends on $|\mu - \mu_c|$ for $|\mu - \mu_c| \ll 1$.

Numerically find this dependence. It should be given by the scaling law

$$\gamma \sim A |\mu - \mu_c|^a,$$

for some constants a and A . Here \sim denotes asymptotic equivalence, meaning that the expression $A \sim |\mu - \mu_c|^a$ is approached in the limit of $\mu \rightarrow \mu_c$.

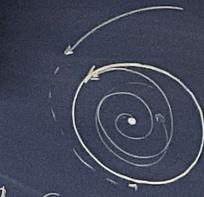
- e) Give your estimate for a with one digit accuracy.

precision = .1

A A A

- f) First, numerically evaluate the period time of the periodic orbit and plot it against $\mu - \mu_c$. Second, from the estimate in e), together with the results of c) and d), you should be able to find an estimate of the period time, T_μ , as a function of $|\mu - \mu_c|$. Plot this estimate in the same figure as the numerically evaluated period time. To show that the scaling for small $|\mu - \mu_c|$ comes out correctly, you may need to multiply T_μ by a constant to make the curves overlap for small $|\mu - \mu_c|$. [Upload the figure as a .png image or a .pdf](#).

3.2 Hopf b.f.



a) Compare! find ω

b) find $f(x,y)$, $g(x,y)$ Comparison!

$$\begin{aligned}\dot{x} &= -\omega y - f(x,y) \\ \dot{y} &= \omega x + g(x,y)\end{aligned}$$

higher order nonlinear

c) $a > 0 \rightarrow \text{stab}$

$D[f(x,y), (x_0, y_0)]^2 < 0 \rightarrow \text{instab}$

d) Phase portraits

Numerical solution not stable

3.3 Homoclinic bif.

a) find μ_c (where the HC.bif. occurs)

b) phase portraits for

$$\begin{cases} \mu < 0 \\ \mu = 0 \\ \mu < \mu_c \\ \mu = \mu_c \\ \mu > \mu_c \end{cases}$$



$$\begin{cases} \dot{x} = u x \\ \dot{y} = s y \end{cases}$$

unstable dir
stable dir

c) $(x(0), y(0)) = (x_0, 1)$

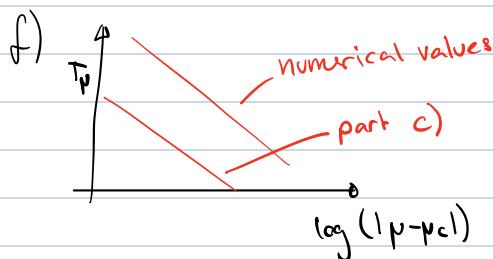
$x(1) = 1$

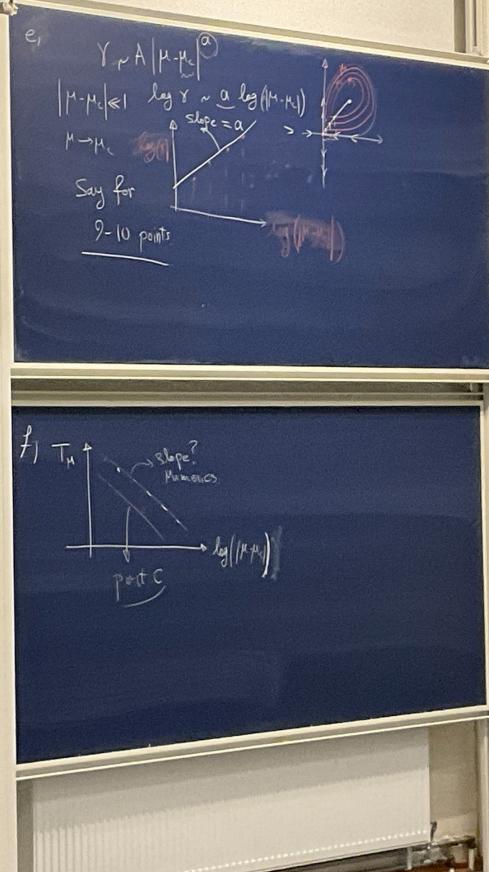
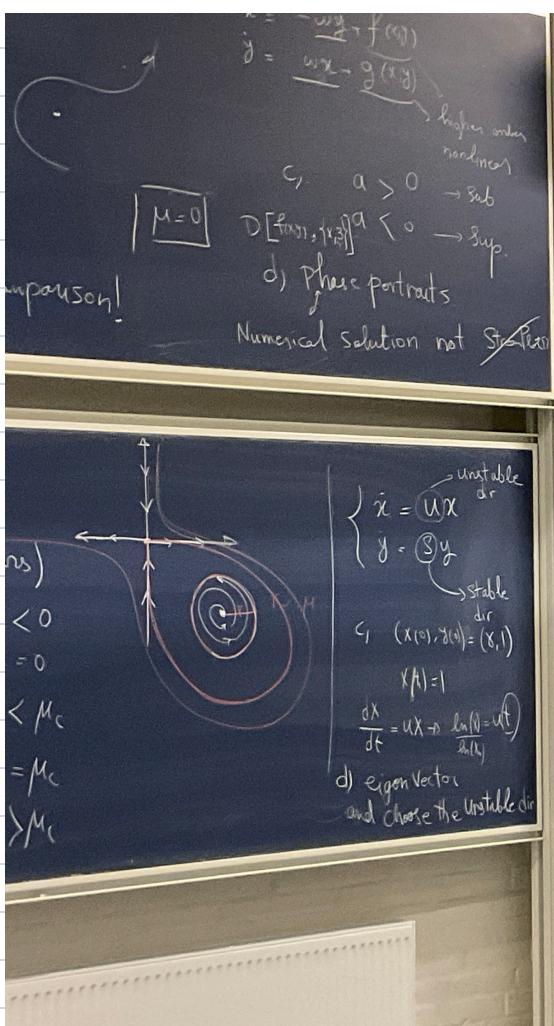
$\frac{dx}{dt} = ux \rightarrow \frac{x(1)}{x(0)} = u \cdot 1 = v \cdot 1$

d) eigenvector
and choose the unstable dir

e) $\gamma \sim A \cdot |\nu - \nu_c|^\alpha$ $\nu \rightarrow \nu_c$ $|\nu - \nu_c| \ll 1$

$$\log(\gamma) = a \cdot \log(A|\nu - \nu_c|)$$





Compute A :

$$A = \begin{pmatrix} \frac{\partial \dot{x}}{\partial x} & \frac{\partial \dot{x}}{\partial y} \\ \frac{\partial \dot{y}}{\partial x} & \frac{\partial \dot{y}}{\partial y} \end{pmatrix} = \begin{pmatrix} \mu - 2x & 1 \\ -1 + 4x & \mu \end{pmatrix}$$

Check FP's:

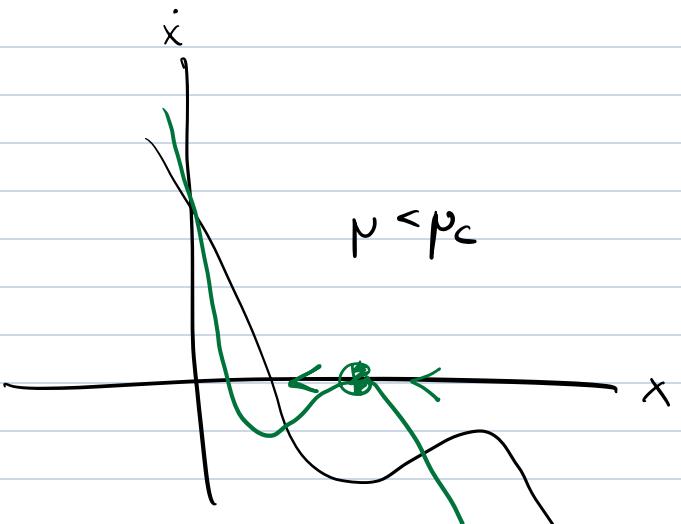
$$C = \mu x + y - x^2$$

$$x^2 = \mu x + y$$

$$C = -x + \mu y + 2x^2$$

$$-2x^2 + x = \mu y$$

$$-2(\mu x + y)^2 + x = \mu y$$



$$\nu(x,y)$$

$$\nu = \nu_c$$

$$(\nu - 2x) \nu$$

$$\nu^2 - 2\nu x = 0$$

$$\nu (\nu - 2x) = 0$$

$$a=1 \quad b=-2x \quad c=0$$

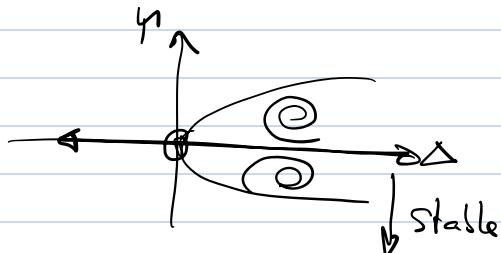
$$\nu = 0$$

$$\nu_c = 2x$$

$$b^2 - 4ac = 0$$

$$4x^2 = 0$$

$$\dot{x} =$$



put ν_c in $\det(A)$ and check if = 0

$$A = \begin{pmatrix} \nu - 2x & 1 \\ -1 + 4x & \nu \end{pmatrix} \rightarrow \begin{pmatrix} 2x - 2x & 1 \\ -1 + 4x & 2x \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ -1 + 4x & 2x \end{pmatrix}$$

$$\nu = 2x$$

$$\Delta = ad - bc = 0 - ((-1+4x)1)$$

$$= 1 - 4x$$

$$1 = 4x$$
$$x = 1/4$$

$$\nu = 2x \rightarrow \frac{1}{2}$$

FP $[0, c]$

$$x^* \Rightarrow \nu = \frac{x^2 - y}{x}$$

$$y^* \Rightarrow \nu = \frac{x - 2x^2}{y}$$

$$\frac{x^2 - y}{x} = \frac{x - 2x^2}{y} \quad || \cdot x, \cdot y$$

$$y(x^2 - y) = x(x - 2x^2)$$

$$yx^2 - y^2 = x^2 - 2x^3$$

$$x^2(y - \frac{y^2}{x^2}) = x^2(1 - 2x)$$

$$y - \frac{y^2}{x^2} = 1 - 2x$$

a.) Find FP:

$$\dot{x} = px + y - x^2 \stackrel{!}{=} 0 \quad (\text{I})$$

$$y = -x + py + 2x^2 \stackrel{!}{=} 0 \quad (\text{II})$$

$$FP_1 = [0, 0]$$

for FP_2 :

$$(\text{II}) \Rightarrow y = \frac{x - 2x^2}{p}$$

put in (I)

$$0 = x \cdot p + \frac{x - 2x^2}{p} - x^2 \parallel \cdot p$$

$$0 = x \cdot p^2 + x - 2x^2 - x^2 p$$

$$x = -xp^2 + 2x^2 + x^2 p$$

$$x - 2x^2 = -xp^2 + x^2 p$$

$$x(1-2x) = x(xp - p^2)$$

$$1-2x = xp - p^2$$

$$1+p^2 = xp + 2x$$

$$1+p^2 = x(p+2)$$

$$x^* = \frac{1+p^2}{p+2}$$

$$y^* = \frac{x - 2x^2}{p} = \frac{x(1-2x)}{p}$$
$$= \frac{1}{p} \cdot \left(\frac{1+p^2}{p+2} \right) \left(1 - \frac{2+2p^2}{p+2} \right)$$

$$FP_2 = [x^*, y^*]$$

$$\int \dot{x} = \int ux \quad \text{with initial cond}$$

$$\int_y^1 ux dx = \int_0^{t_1} ux dt$$

c)

$$\dot{x} = \mu x + y - x^2$$

$$\dot{y} = -x + \mu y + 2x^2$$

↓ linearise

$$\dot{x} = ux$$

$$\frac{dx}{dt} = ux$$

$$\dot{y} = sy$$

find the time t_1 to escape from the saddle to $x(t_1) = 1$!

Init conditions:

$$x(0) = \mu$$

$$y(0) = 1$$

Separation of Variable

$$\frac{dx}{dt} = u \cdot x$$

$$\frac{1}{x} dx = u \cdot dt \quad || \int$$

$$\int \frac{1}{x} dx = \int u \cdot dt$$

$$\ln|x| = u \cdot t + C$$

$$\text{Put in init conditions: } x(0) = g \rightarrow \ln|g| = C$$

$$\ln|x| = v \cdot t + \ln|g|$$

$$x = g \cdot e^{(v \cdot t)}$$

$$\text{init cond } x(t_1) = 1$$

$$1 = g \cdot e^{(v \cdot t_1)}$$

solve for t_1 :

$$t_1 = \frac{\ln(1/g)}{v}$$

$$d) \quad \begin{aligned} \dot{x} &= \mu x + y - x^2 \\ \dot{y} &= -x + \mu y + 2x^2 \end{aligned} \quad \rightarrow A = \begin{pmatrix} \mu - 2x & 1 \\ -1 + 4x & \mu \end{pmatrix}$$

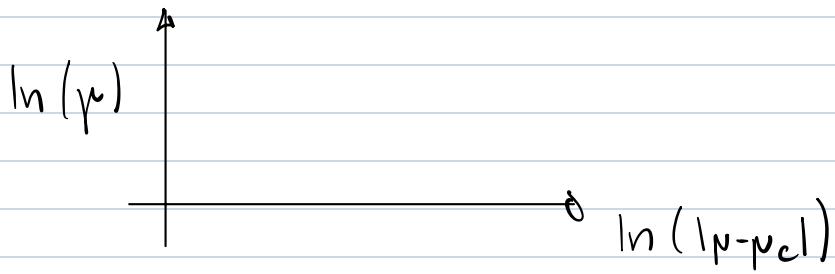
$$A = \begin{pmatrix} \mu - 2x & 1 \\ -1 + 4x & \mu \end{pmatrix} \quad \text{now } x^* = \frac{1 + \mu^2}{\mu + 2}$$

Substitute EigVal [A] /o $x \rightarrow \frac{1 + \mu^2}{\mu + 2}$

e) To find T_p first find $\gamma(\lvert \mu - \mu_c \rvert)$ for $\lvert \mu - \mu_c \rvert \ll 1$

$$\gamma \sim A \cdot \lvert \mu - \mu_c \rvert^\alpha$$

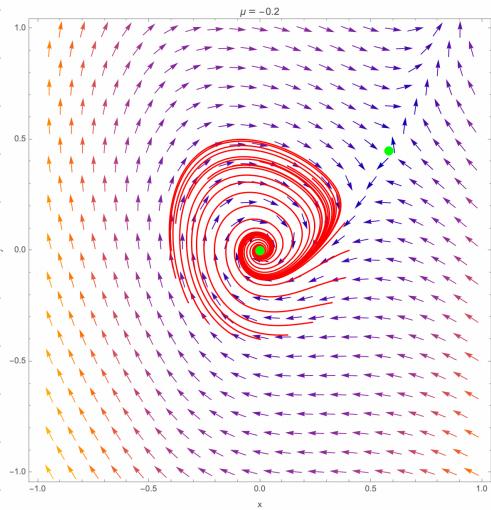
$$\gamma = \frac{1 + \mu^2}{\mu + 2}$$



$$\log(\gamma(\mu)) = a \cdot \log(\lvert \mu - \mu_c \rvert) + \log(A)$$

$$\log(\gamma(\mu)) = a \cdot \log(\text{mabs})$$

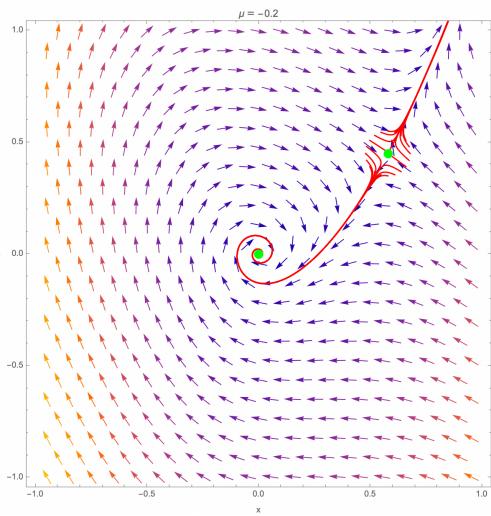
$$\mu = -0.2$$



Starting very close to FP_1 .

The trajectory spirals into the stable

$$\text{FP}_1 @ \{0, 0\}.$$



When starting the trajectories around FP_2

they either spiral into the stable FP_1 or

escape towards NorthEast, with a way

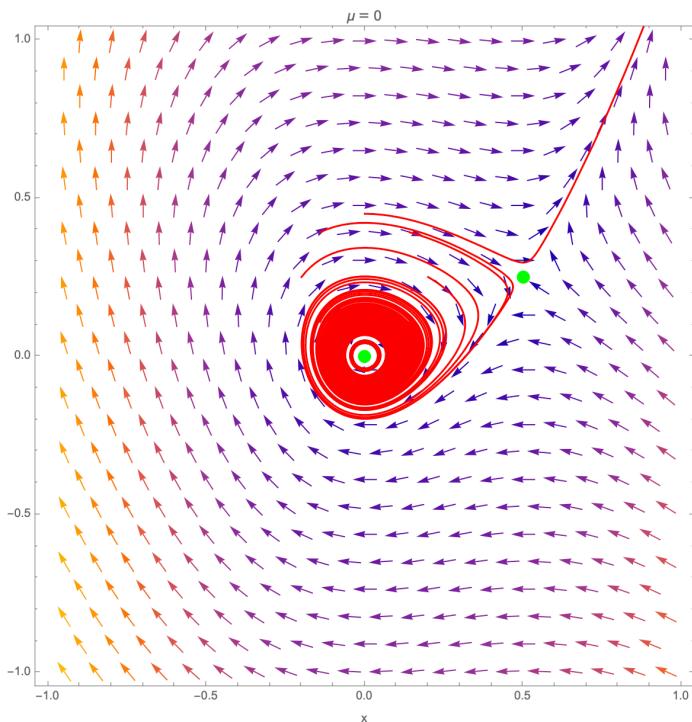
higher velocity than the ones going into FP_1 .

FP_2 seems to be a saddle point, since attracting

in one direction, and repelling in the other (Eigenvectors)

So stable FP_1 at $\{0, 0\}$ and a saddle node $\text{FP}_2 (\mu)$.

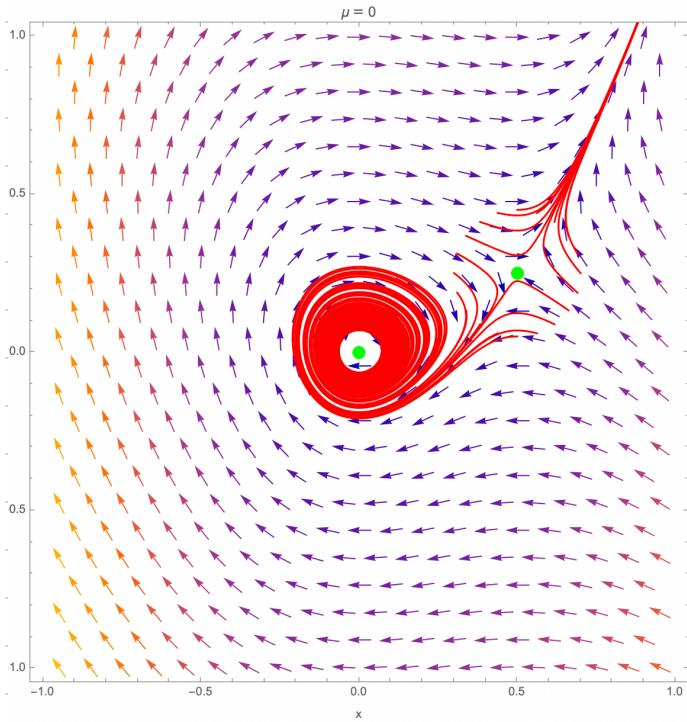
$\nu = 0$



Trajectories starting close around FP_1 ,

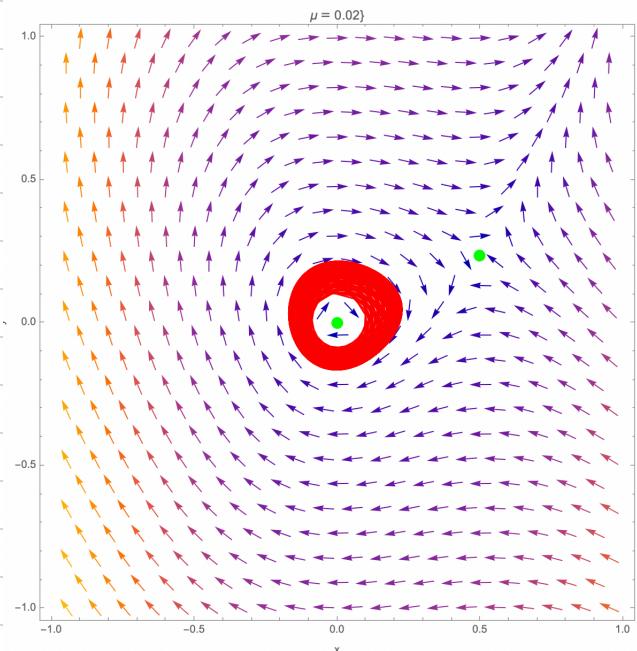
spiral into FP_1 . FP_1 stable spiral.

into FP_1 the trajectories are very slow.

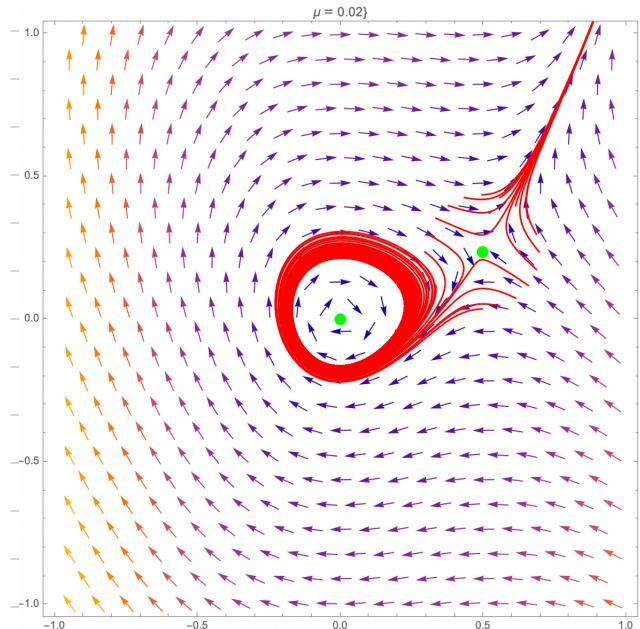


FP_2 is again as in $\nu = -0, 2$ a saddle point

$$\mu = 0.02$$

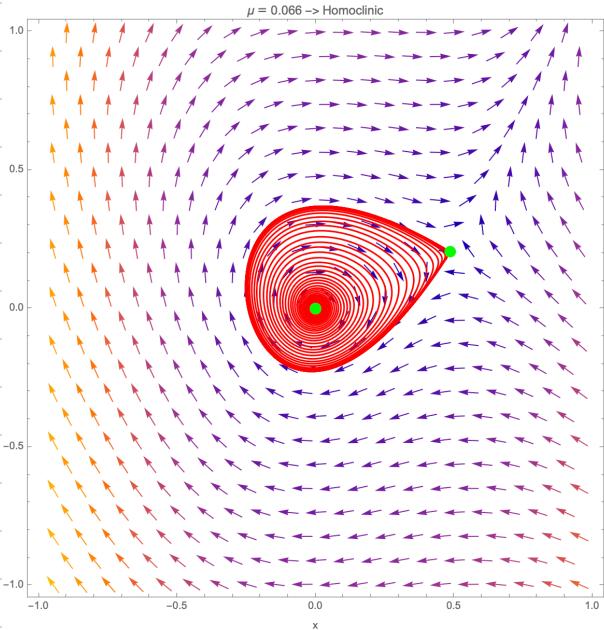


Trj. starting close around FP_1
are repelled from the FP_1 , hence
 FP_1 seems unstable. They are trapped
inside the "egg" shape, limit cycle.



When starting around FP_2 , the traj
are attracted either to limit cycle or
escape towards NorthEast. FP_2 saddle
point.

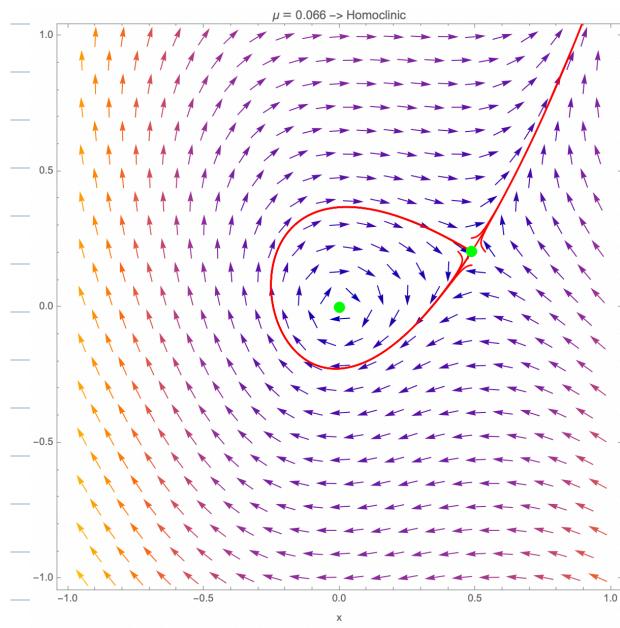
$$\mu = \mu_c$$



Starting traj. close around FP_1

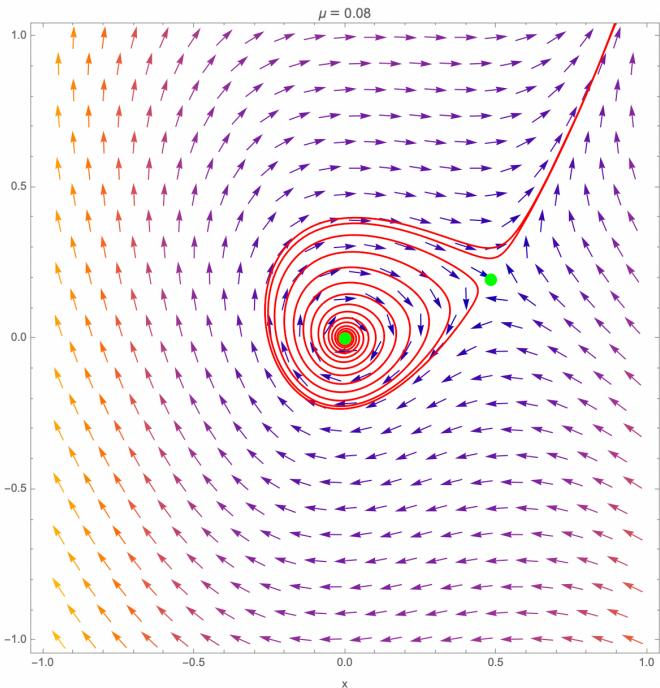
the get trapped by homoclinic orbit.

FP_1 unstable spiral



Starting just at the FP_1 one sees that
the trajectories escape the FP and
come into it again.

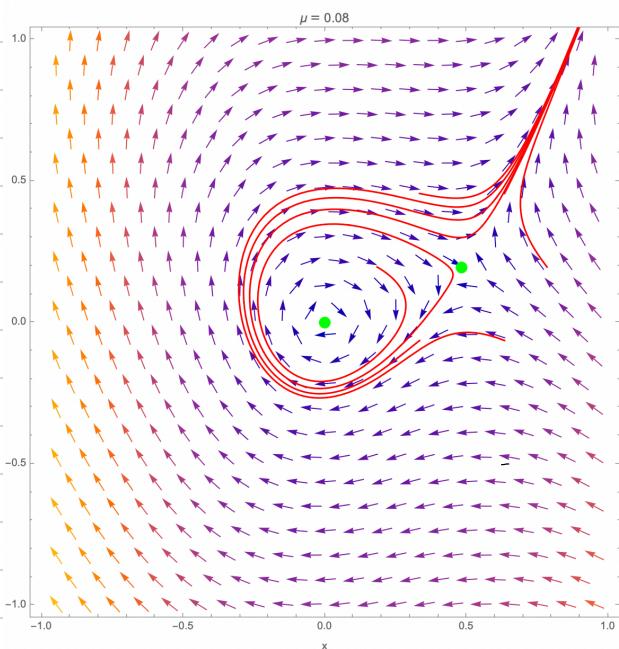
$$\mu = 0.08$$



Starting traj. close to FP_1

the escape from FP_1 . So around

FP_1 unstable spiral.



FP_2 saddle point.