

# Ausarbeitung eines Konzepts für Ergonomische Arbeitsplätze einer Montagelinie

Studienarbeit im Rahmen des AWP  
“Problemlösungen in der Praxis”

Vorgelegt von:

Felix Dick

Matrikelnummer: 22111369

Betreuer:

Dipl.sc.pol.Univ., M.Sys.Eng. Roman Tizki

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## **1    Startup with ANDI-tool and Loopback**

This chapter introduces the initial setup and basic testing procedures.

### **1.1    Introduction to the ANDI-tool**

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### **1.2    Loopback Test Procedure**

1. Step 1: Connect the hardware.
2. Step 2: Configure the software.
3. Step 3: Run the test and observe results.

Example of citing a source [1].

## **2    Build up a communication path over MediaGateway - simple connection and VLAN**

This section details the establishment of a communication path.

### **2.1    Simple Connection Setup**

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### **2.2    VLAN Configuration**

Placeholder for text...

A figure example:

Figure 1: Network diagram of the MediaGateway setup.

## **3    Integration into a network structure**

This chapter covers the integration of the setup into a larger network.

### **3.1    Network Architecture Overview**

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### **3.2    Integration Steps and Challenges**

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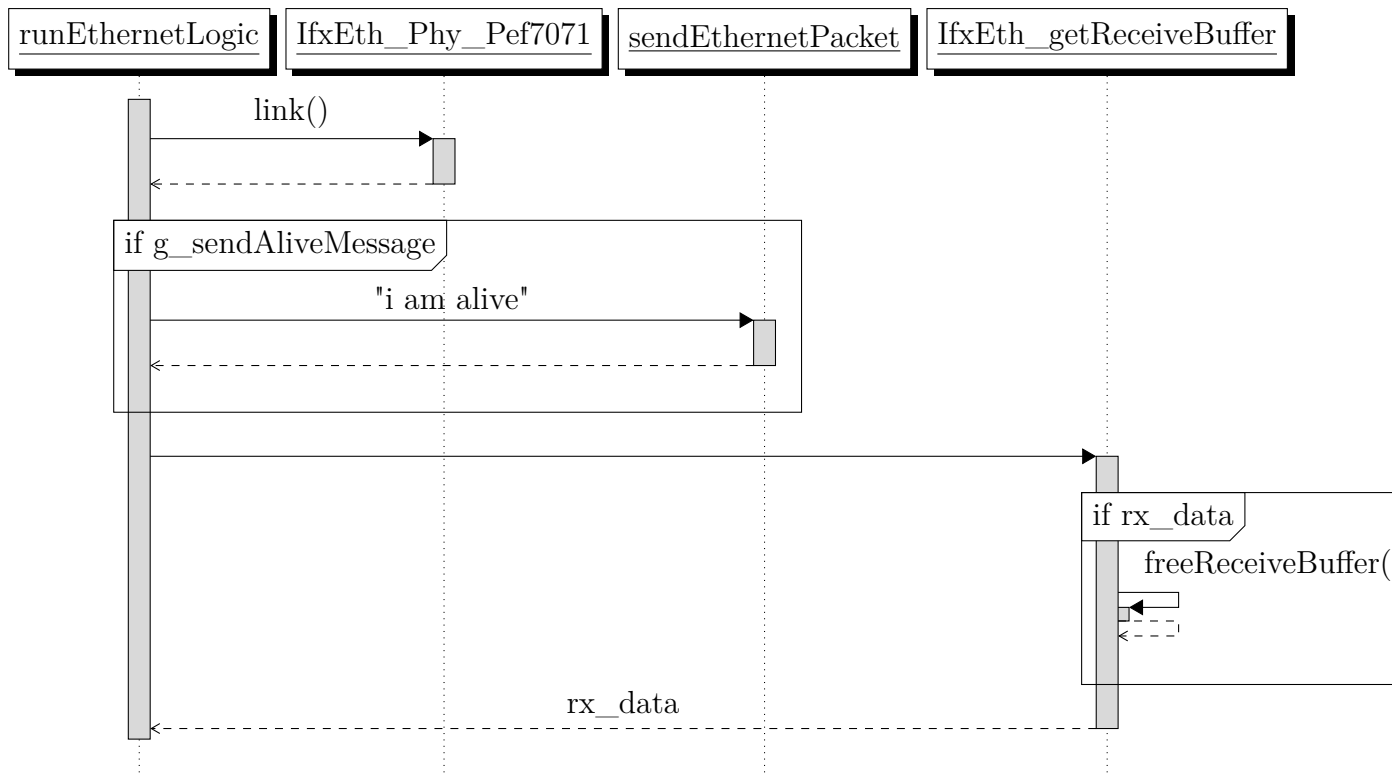


Figure 2: Ethernet Rx/Tx Logic

## 4 CAN-Ethernet-Gateway on Infineon AURIX TC297

This chapter focuses on the implementation of a CAN-Ethernet gateway.

### 4.1 Hardware Overview: Infineon AURIX TC297

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### 4.2 Software Implementation

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#### 4.2.1 C Code Example

Here is an example of how to include a C code snippet.

```

1 #include <stdio.h>
2
3 // Define CAN message structure
4 typedef struct {
5     unsigned int id;
6     unsigned char data[8];
7     unsigned char dlc; // Data Length Code
8 } CAN_Message;
9
10 /*
11  * @brief Sends a CAN message.
12  * @param msg Pointer to the CAN_Message to be sent.
13  */
  
```

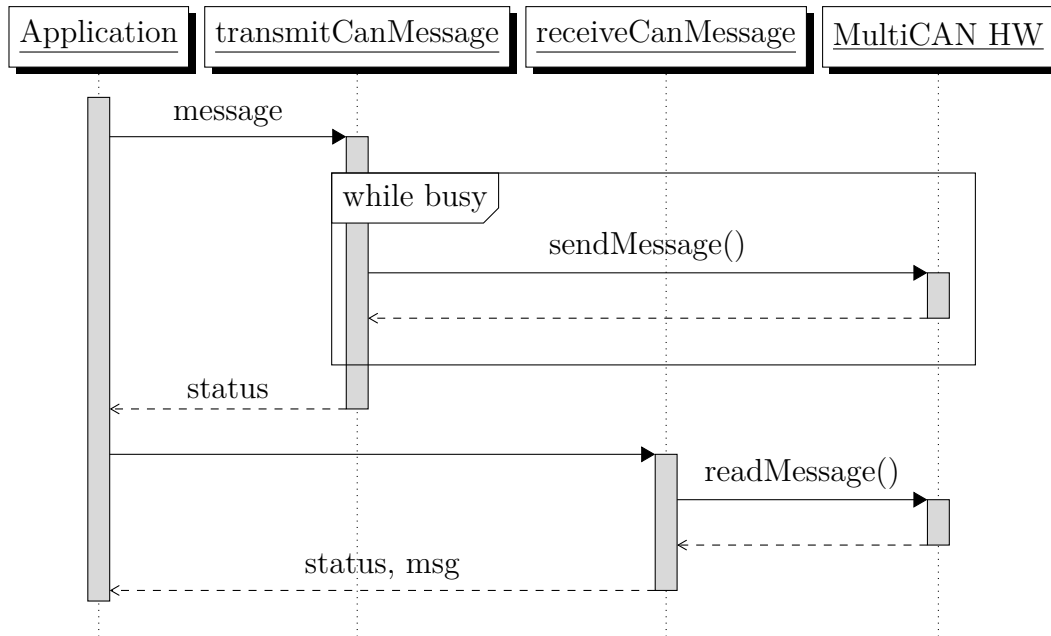


Figure 3: CAN Rx/Tx Logic

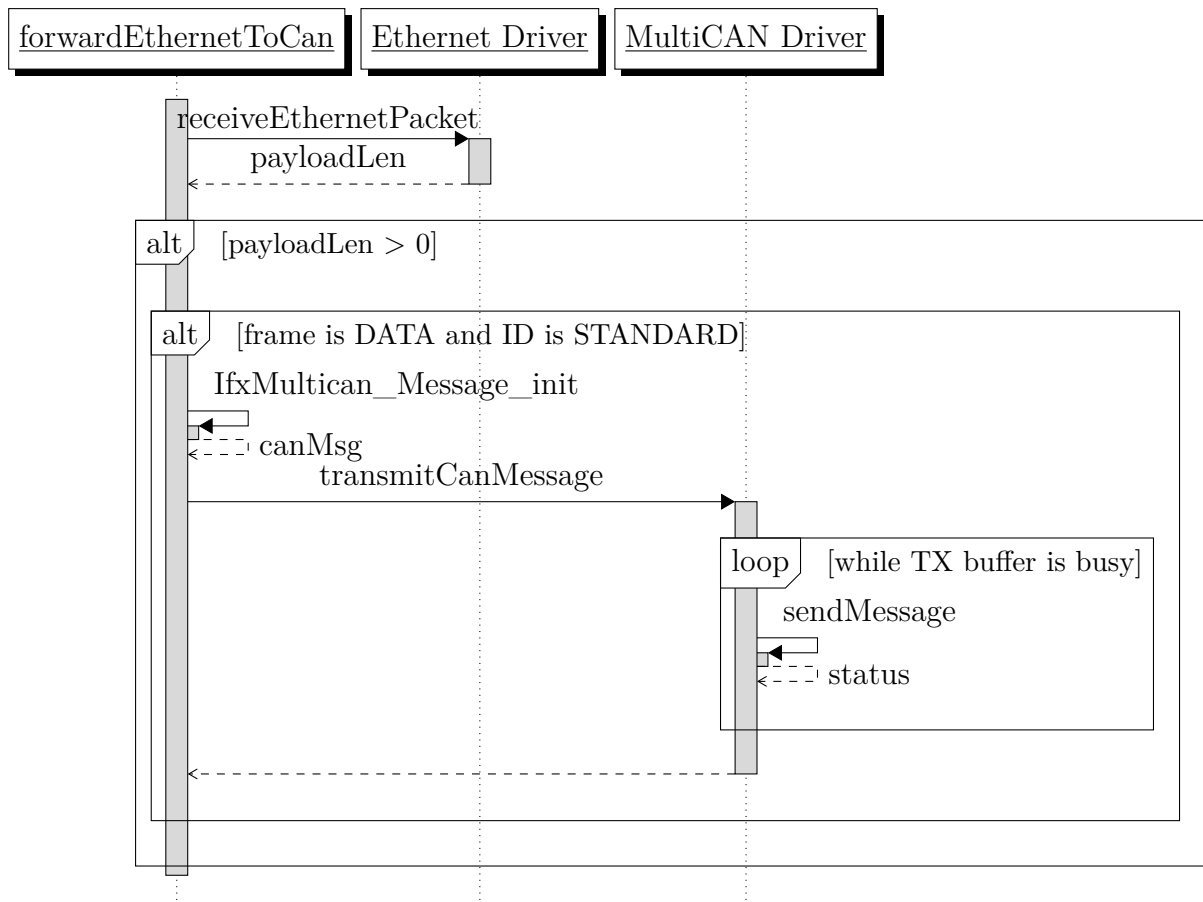


Figure 4: Ethernet to CAN Message Forwarding

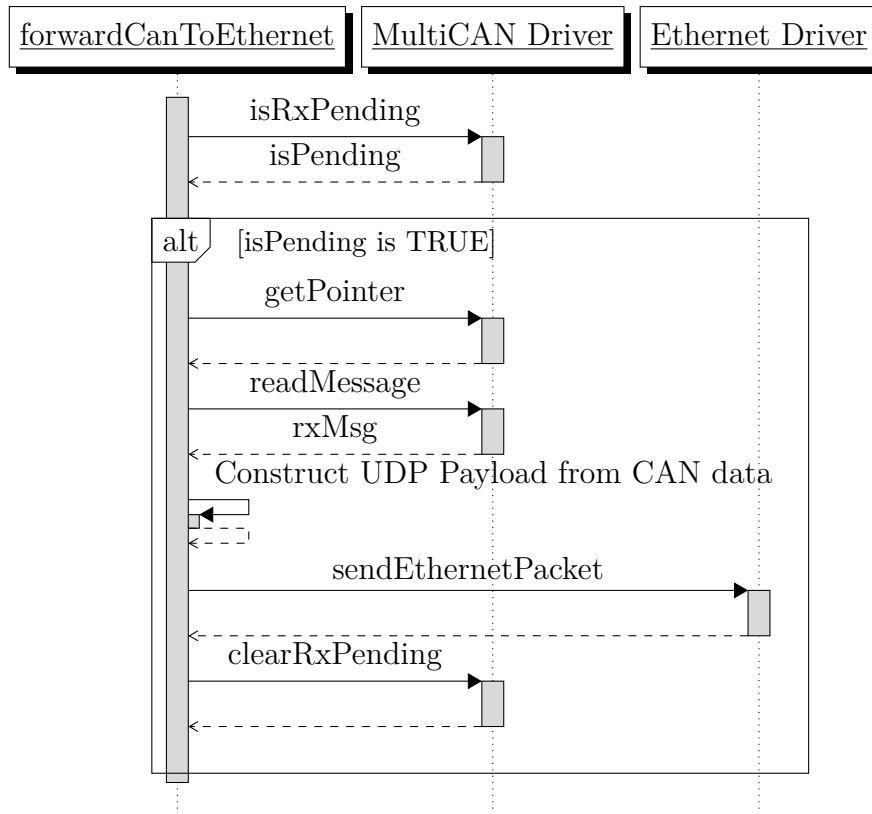


Figure 5: CAN to Ethernet Message Forwarding

```

14 void send_can_message(const CAN_Message* msg) {
15     // Placeholder for actual hardware driver call
16     printf("Sending CAN message with ID: 0x%X\n", msg->id);
17     // ... implementation details for hardware registers ...
18 }
19
20 int main() {
21     CAN_Message my_message;
22     my_message.id = 0x123;
23     my_message.dlc = 8;
24     for (int i = 0; i < my_message.dlc; ++i) {
25         my_message.data[i] = i;
26     }
27
28     send_can_message(&my_message);
29
30     return 0;
31 }
  
```

Listing 1: Example of a simple CAN message sending function.

## REFERENCES

### References

- [1] J. Doe, *Advanced Networking Protocols*. New York, NY: Tech Publishing, 2023.