

Matrix Completion and Hawkes Process in Recsys

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Outline



Matrix Completion and Its Applications

Matrix Completion[?][?]
Scalable Demand-Aware Recommendation[?]

Hawkes Process and Its Applications

Hawkes Process
Neural Hawkes Process[?]
CTRec[?]

Q&A

Keywords:

recommendation system \cdot matrix completion \cdot Hawkes process

Motivation



"Dear Amazon, I bought a toilet seat because I needed one. Necessity, not desire. I do not collect them. I am not a toilet seat addict."

1. Matrix Completion

(1). Motivation



Matrix completion is the task of filling in the missing entries of a partially observed matrix.

- · In general, it is NP-hard.
- · But under additional assumptions, it can be solved efficiently.

1. Matrix Completion

(2). Low-rank Matrix Completion



Under low-rank restriction (non-convex, still NP-hard):

$$\begin{aligned} & \underset{X}{\min} & & \operatorname{rank}(X) \\ & \text{s.t.} & & X_{ij} = M_{ij} & (i,j) \in \Omega \end{aligned}$$

Convex relaxation:1

$$\begin{aligned} & \underset{X}{\min} & & ||X||_* \\ & \text{s.t.} & & X_{ij} = M_{ij} & (i,j) \in \Omega \end{aligned}$$

Now this can be solved efficiently.

¹Candès, Emmanuel J., and Benjamin Recht. Exact matrix completion via convex optimization. Foundations of Computational mathematics 9.6 (2009): 717.

2. Scalable Demand-Aware Recommendation²

(1). Motivation



- Item utility = form utility + time utility.
- traditional CF models only considers form utility → tries to incorporate both utilities.

2. Scalable Demand-Aware Recommendation

(2). PU learning for matrix completion³



- Aims to recover the underlying matrix $M \in \mathbb{R}^{m \times n}$.
- Y is a **clean** 0-1 matrix observed from M by thresholding process: $Y_{ij} = \mathbbm{1}\{M_{ij} > \tau\}$ and assume that only a subset of positive entries of Y are observed, denoted as A. But unfortunately, it is impossible to recover M, recover Y instead.
- Label-dependent loss:

$$\begin{split} \hat{X} &= \underset{X:||X||_* \le t}{\text{arg min}} \sum_{i,j} l_{\alpha}(X_{ij}, A_{ij}) \\ &= \underset{X:||X||_* \le t}{\text{arg min}} \alpha \sum_{i,j: A_{ij} = 1} (X_{ij} - 1)^2 + (1 - \alpha) \sum_{i,j: A_{ij} = 0} X_{ij}^2 \end{split}$$

which can be solved very efficiently by optimization methods.

• Recover Y by $\bar{X}_{ij} = \mathbb{1}\{\hat{X}_{ij} > \tau\}$.

³Cho-Jui Hsieh, Nagarajan Natarajan, and Inderjit S. Dhillon. PU learning for matrix completion. In ICML, 2015.

2. Scalable Demand-Aware Recommendation

(3). Loss Functions



Tensor nuclear norm minimization(TNNM) problem:

$$\begin{aligned} \min_{X \in \mathbb{R}^{m \times n \times l}, \mathbf{d} \in \mathbb{R}^{r}_{+}} \eta \sum_{ijk: p_{ijk} = 1} \max[1 - \underbrace{(x_{ijk} - \max(0, d_{c_{j}} - t_{ic_{jk}}))}_{\text{form utility}}, 0]^{2} \\ &+ (1 - \eta) \sum_{ijk: p_{ijk} = 0} x_{ijk}^{2} + \lambda ||X||_{*}^{2} \end{aligned}$$

- $\mathcal{P} \in \{0, 1\}^{m \times n \times l}$ denotes the purchase history.
- $X \in \mathbb{R}^{m \times n \times l}$ denotes the underlying form utility.
- $d \in \mathbb{R}^r_+$ with d_i denoting the underlying duration of category i.
- $\mathcal{T} \in \mathbb{R}^{m \times n \times l}$ where t_{ic_jk} denotes the number of time slots between user i's most recent purchase within item category c_j until time k.
- A binary utility indicator $\mathcal{Y} \in \{0, 1\}^{m \times n \times l}$ with

$$y_{ijk} = \mathbb{1}[x_{ijk} - \max(0, d_{c_i} - t_{ic_ik}) > \tau].$$

3. Hawkes Process⁴

- The Hawkes process is a counting process that models a sequences of 'arrivals' of some type over time and each arrival excites the process.
- Conditional intensity function(CIF) of a counting process N(t) with associated histories $\mathcal{H}(\cdot)$:

$$\lambda^*(t) = \lim_{h \to 0} \frac{\mathbb{E}\{N(t+h) - N(t)|\mathcal{H}(t)\}}{h}$$

· CIF for Hawkes process:

$$\lambda^*(t) = \lambda + \sum_{i:t_i < t} \mu(t-t_i)$$
 background intensity excitation function

Generally, $\mu(\cdot)$ takes the form of $\mu(t) = \alpha e^{-\beta t}$.

⁴Patrick J. Laub, Thomas Taimre, Philip K. Pollett. Hawkes Process. arXiv:1507.02822.

3. Hawkes Process



The log-likelihood of the Hawkes model given observations I is:5

$$l = \left(\sum_{i=1}^{k} \log P(t_i | \mathcal{H}_i)\right) + \log P(t_{k+1} > T | \mathcal{H}_I)$$
$$= \sum_{i=1}^{k} \log \lambda^*(t_i) - \int_0^{t_k} \lambda^*(u) du$$

4. Neural Hawkes Process⁷

(1). Motivation



$$\lambda^*(t) = \lambda + \sum_{i:t_i < t} \mu(t - t_i)$$

- The Hawkes process always assumes that the excitation is ① positive, ② linearly additive over past events, ③ exponentially decaying with time.
- Neural Hawkes process expands the expressivity by generalizing it to 1 both positive and negative, 2 non-linear, 3 waving-curve influences.⁶

⁶Author's answer at zhihu in Chinese.

⁷Hongyuan Mei and Jason M Eisner. *The neural hawkes process: A neurally self-modulating multivariate point process.* In NeurlPS, 2017.

4. Neural Hawkes Process

(2). A simple generalization



Original intensity function (with only self-exciting):

$$\lambda_k(t) = \mu_k + \sum_{h:t_h < t} \alpha_{k_h,k} e^{\left(-\delta_{k_h,k}(t-t_h)\right)}, \quad \mu_k \ge 0, \alpha_{j,k} \ge 0$$

A generalization with self-inhibition:

$$\tilde{\lambda}_{k}(t) = \mu_{k} + \sum_{h:t_{h} < t} \alpha_{k_{h},k} e^{\left(-\delta_{k_{h},k}(t-t_{h})\right)}, \quad \mu_{k} \in \mathbb{R}, \alpha_{j,k} \in \mathbb{R}$$

$$\lambda_{k}(t) = f_{k}\left(\tilde{\lambda}_{k}(t)\right) = s_{k} \log\left(1 + \exp\left(\frac{\tilde{\lambda}_{k}(t)}{s_{k}}\right)\right)$$

where the "softplus" function $f_k(x)$ ensures positive results of the intensity function.

4. Neural Hawkes Process

(3). The neural generalization



$$\lambda_k(t) = f_k \left(\mathbf{w}_k^{\mathsf{T}} \mathbf{h}(t) \right), \qquad \mathbf{h}(t) = \mathsf{cLSTM}(x)$$

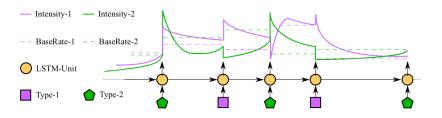


Figure: Drawing an event stream from a neural Hawkes process. Type-1 excites itself but inhibits Type-2. Type-2 excites itself, and excites or inhibits Type-1 according to #(Type-2) is odd or even.

4. More About Hawkes Process and Point Process

(4). References

Papers:



- A Dirichlet Mixture Model of Hawkes Processes for Event Sequence Clustering, NeurlPS'17[?]
- · Learning Granger Causality for Hawkes Processes, ICML'16[?]
- Learning Hawkes Processes from Short Doubly-Censored Event Sequences, ICML'17[?]
- Learning Conditional Generative Models for Temporal Point Processes, AAAI'18[?]
- Wasserstein Learning of Deep Generative Point Process Models, NeurIPS'17[?]
- Time is of the Essence: A Joint Hierarchical RNN and Point Process Model for Time and Item Predictions, WSDM'19[?]

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Group:

· Hongyuan Zha @ Georgia Institute of Technology

(1). Framework: demand-aware Hawkes process



· Conditional intensity function:

$$\lambda_i(t;\theta) = f(\underbrace{\boldsymbol{w}_i^{\mathsf{item}\top} \cdot \boldsymbol{h}(t)}_{\mathsf{short-term}} + \underbrace{\boldsymbol{w}_i^{\mathsf{attri}\top} \cdot \boldsymbol{\vartheta}(t)}_{\mathsf{long-term}} + \underbrace{\boldsymbol{w}_i^{\mathsf{user}\top} \cdot \boldsymbol{u}}_{\mathsf{basic demands}})$$

, where
$$f(x) = \frac{s}{1 + \exp(\frac{-x}{s})}$$
.

- The parameters here $\mathbf{w}_i^{\text{item}}$, $\mathbf{w}_i^{\text{attri}}$, $\mathbf{w}_i^{\text{user}}$, are learnt by neural Hawkes process.
- Then the probability of item i will be purchased at time t:

$$p_i(t;\theta) = \lambda_i(t;\theta) \exp\left(-\int_{t_0}^t \lambda_i(s;\theta)ds\right)$$

• Expectation next purchase time \hat{t}_{next} of item i is:

$$\hat{t}_{\text{next}} = \int_{t_0}^{+\infty} t \cdot p_i(t; \theta) dt$$

⁸Ting Bai, Lixin Zou, Wayne Xin Zhao, etc. CTRec: A Long-Short Demands Evolution Model for Continuous-Time Recommendation. In SIGIR, 2019.

(2). Short-term demands



• Convolutional representation of item i_{t_j} :

$$\mathbf{v}_{t_j} = \operatorname{avg}\left\{\mathbf{i}_{t_j}^{k_1}, \dots, \mathbf{i}_{t_j}^{k_m}\right\}$$

• Then feed all the item vectors $\mathbf{v} = \{v_{t_1}, v_{t_2}, \cdots, v_{t_n}\}$ into a time-aware LSTM to capture the short-term demands:

$$h(t) = LSTM(v)$$

$$\lambda_i(t;\theta) = f(\mathbf{w}_i^{\mathsf{item}\top} \cdot \mathbf{h}(t)) + \mathbf{w}_i^{\mathsf{attri}\top} \cdot \mathbf{y}(t) + \mathbf{w}_i^{\mathsf{user}\top} \cdot \mathbf{u})$$
short-term

(3). Long-term demands



- Let $\mathcal{D} \in \mathbb{R}^{|U| \times |A| \times |A|}$ be the estimated purchase time distance matrix of items for all users.
- · Self-attentive component:

$$\alpha_{t,t_j} = \boldsymbol{h}\left(t_j\right)^{\top} \boldsymbol{i}_t - \lambda \log \left(\max \left\{ \gamma, d^u_{a_t, a_{t_j}} - \Delta^u_{a_t, a_{t_j}} \right\} \right)$$

· Long-term demands:

$$\boldsymbol{\vartheta}_{t} = \sum_{j=1}^{n} \frac{\exp\left(\alpha_{t,t_{j}}\right)}{\sum_{q=1}^{n} \exp\left(\alpha_{t,t_{q}}\right)} \boldsymbol{h}\left(t_{j}\right)$$

$$\lambda_i(t;\theta) = f(\boldsymbol{w}_i^{\mathsf{item}\top} \cdot \boldsymbol{h}(t) + \underbrace{\boldsymbol{w}_i^{\mathsf{attri}\top} \cdot \boldsymbol{\vartheta}_t}_{\mathsf{long-term}} + \boldsymbol{w}_i^{\mathsf{user}\top} \cdot \boldsymbol{u})$$

(4). Loss function



Maximize the log-likelihood of ovserving items in $I_{t_n}^u$, which can be defined as:⁹

$$\begin{split} \ell\left(I_{t_n}^u;\theta\right) &= \sum_{j=1}^n \log \Pr\left(i_{t_j} | I_{t_j}^u, \Delta t_j\right) \\ &= \underbrace{\sum_{j=1}^n \log \lambda_{i_{t_j}}\left(t_j;\theta\right)}_{\text{purchase}} - \underbrace{\sum_{i_{\text{neg} \in I}}^{t_n} \lambda_{i_{\text{neg}}}(t) dt}_{\text{non-purchase}} \\ &= \underbrace{\sum_{i_{\text{neg}} \in I}^n \sum_{j=1}^n \left(\frac{1}{|I|} \log \lambda_{i_{t_j}}\left(t_j;\theta\right) - \int_{t_{j-1}}^{t_j} \lambda_{i_{\text{neg}}}(t) dt\right)}_{\text{non-purchase}} \end{split}$$

⁹Hongyuan Mei and Jason M Eisner. *The neural hawkes process: A neurally self-modulating multivariate point process.* In NeurIPS, 2017.

Q&A Thanks!

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continuous-time LSTM



The continuous-time LSTM is defined as follows:

$$\lambda_k(t) = f_k(\boldsymbol{w}_k^{\mathsf{T}} \boldsymbol{h}(t))$$

$$\mathbf{h}(t) = \mathbf{o}_i \odot (2\sigma(2\mathbf{c}(t)) - 1), \quad \text{for } t \in (t_{i-1}, t_i]$$

$$c(t) \stackrel{\text{def}}{=} \bar{c}_{i+1} + (c_{i+1} - \bar{c}_{i+1}) \exp(-\delta_{i+1}(t - t_i)), \quad \text{for } t \in (t_i, t_{i+1}]$$

Bibliography I

