

# CTL Syntax

Assume a set *Atom* of atom propositions.

$$\begin{aligned}\phi ::= & p \mid \neg\phi \mid \phi \wedge \phi \mid \phi \vee \phi \mid \phi \rightarrow \phi \\ & \mid \mathbf{AX} \phi \mid \mathbf{EX} \phi \mid \mathbf{AF} \phi \mid \mathbf{EF} \phi \mid \mathbf{AG} \phi \mid \mathbf{EG} \phi \\ & \mid \mathbf{A}[\phi \mathbf{U} \phi] \mid \mathbf{E}[\phi \mathbf{U} \phi]\end{aligned}$$

where  $p \in \textit{Atom}$ .

Each temporal connective is a pair of a *path quantifier*:

**A** — for all paths

**E** — there exists a path

and an LTL-like temporal operator **X**, **F**, **G**, **U**.

Precedence (high-to-low): (**AX**, **EX**, **AF**, **EF**, **AG**, **EG**,  $\neg$ ), ( $\wedge$ ,  $\vee$ ),  $\rightarrow$

# CTL Semantics 1: Transition Systems and Paths

(This is the same as for LTL)

## Definition (Transition System)

A transition system  $\mathcal{M} = \langle S, \rightarrow, L \rangle$  consists of:

$S$	a finite set of states
$\rightarrow \subseteq S \times S$	transition relation
$L : S \rightarrow \mathcal{P}(Atom)$	a labelling function

such that  $\forall s_1 \in S. \exists s_2 \in S. s_1 \rightarrow s_2$

## Definition (Path)

A path  $\pi$  in a transition system  $\mathcal{M} = \langle S, \rightarrow, L \rangle$  is an infinite sequence of states  $s_0, s_1, \dots$  such that  $\forall i \geq 0. s_i \rightarrow s_{i+1}$ .

Paths are written as:  $\pi = s_0 \rightarrow s_1 \rightarrow s_2 \rightarrow \dots$

## CTL Semantics 2: Satisfaction Relation

**Satisfaction** relation  $\mathcal{M}, s \models \phi$  read as

*state  $s$  in model  $\mathcal{M}$  satisfies CTL formula  $\phi$*

We often leave  $\mathcal{M}$  implicit.

The propositional connectives:

$$s \models \top$$

$$s \not\models \perp$$

$$s \models p \quad \text{iff} \quad p \in L(s)$$

$$s \models \neg\phi \quad \text{iff} \quad s \not\models \phi$$

$$s \models \phi \wedge \psi \quad \text{iff} \quad s \models \phi \text{ and } s \models \psi$$

$$s \models \phi \vee \psi \quad \text{iff} \quad s \models \phi \text{ or } s \models \psi$$

$$s \models \phi \rightarrow \psi \quad \text{iff} \quad s \models \phi \text{ implies } s \models \psi$$

## CTL Semantics 2: Satisfaction Relation

The temporal connectives, assuming path  $\pi = s_0 \rightarrow s_1 \rightarrow s_2 \rightarrow \dots$ ,

$$s \models \mathbf{AX} \phi \quad \text{iff} \quad \forall \pi \text{ s.t. } s_0 = s. s_1 \models \phi$$

$$s \models \mathbf{EX} \phi \quad \text{iff} \quad \exists \pi \text{ s.t. } s_0 = s. s_1 \models \phi$$

$$s \models \mathbf{AG} \phi \quad \text{iff} \quad \forall \pi \text{ s.t. } s_0 = s. \forall i. s_i \models \phi$$

$$s \models \mathbf{EG} \phi \quad \text{iff} \quad \exists \pi \text{ s.t. } s_0 = s. \forall i. s_i \models \phi$$

$$s \models \mathbf{AF} \phi \quad \text{iff} \quad \forall \pi \text{ s.t. } s_0 = s. \exists i. s_i \models \phi$$

$$s \models \mathbf{EF} \phi \quad \text{iff} \quad \exists \pi \text{ s.t. } s_0 = s. \exists i. s_i \models \phi$$

$$s \models \mathbf{A}[\phi \mathbf{U} \psi] \quad \text{iff} \quad \forall \pi \text{ s.t. } s_0 = s.$$

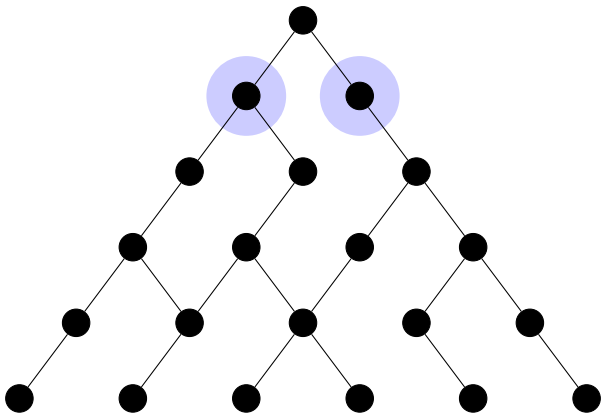
$$\exists i. s_i \models \psi \text{ and } \forall j < i. s_j \models \phi$$

$$s \models \mathbf{E}[\phi \mathbf{U} \psi] \quad \text{iff} \quad \exists \pi \text{ s.t. } s_0 = s.$$

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Note: The semantics for **AX** and **EX** is given differently in H&R.

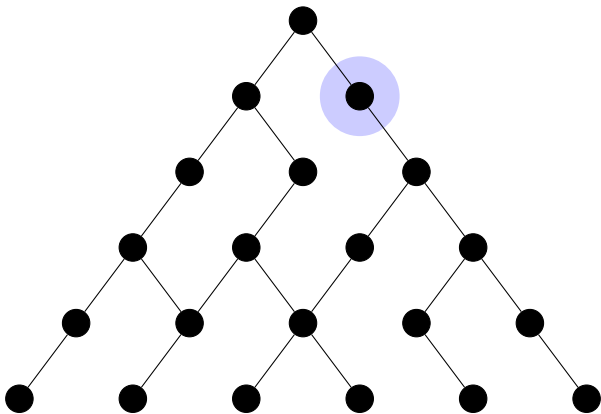
## CTL in Pictures



$AX \phi$

For *every* next state,  $\phi$  holds.

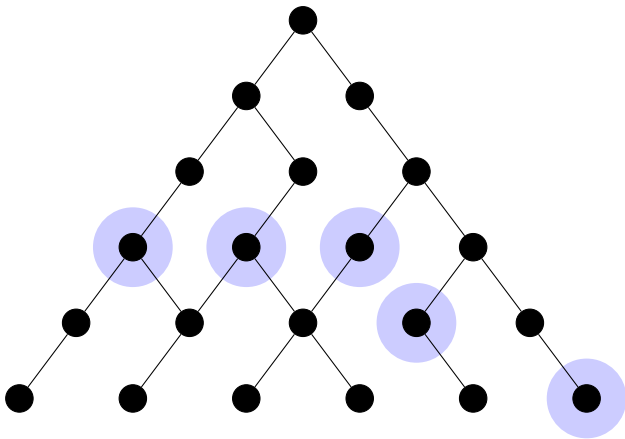
## CTL in Pictures



$\text{EX } \phi$

There *exists* a next state where  $\phi$  holds.

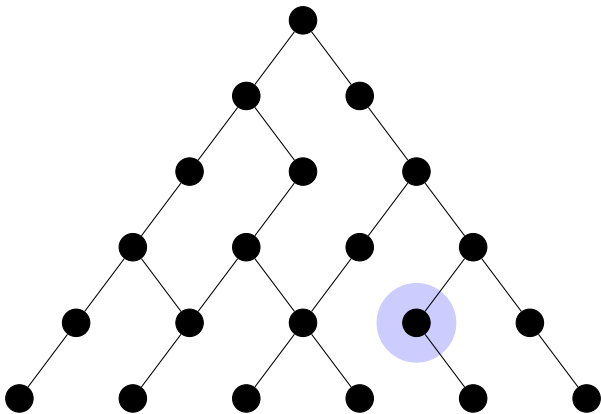
## CTL in Pictures



$AF \phi$

For all paths, there exists a future state where  $\phi$  holds.

## CTL in Pictures

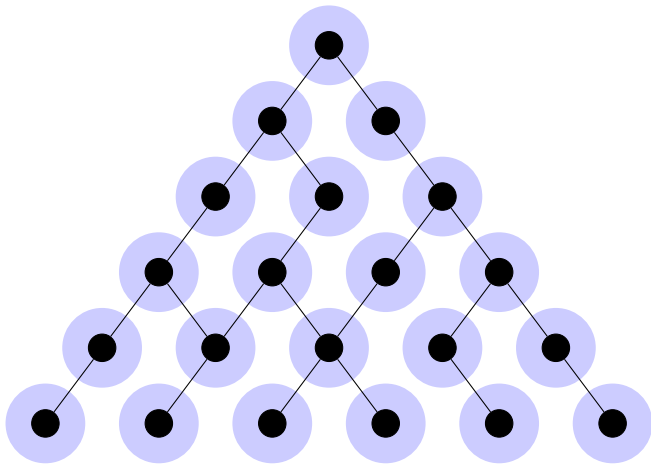


$\text{EF } \phi$

There exists a path with a future state where  $\phi$  holds.



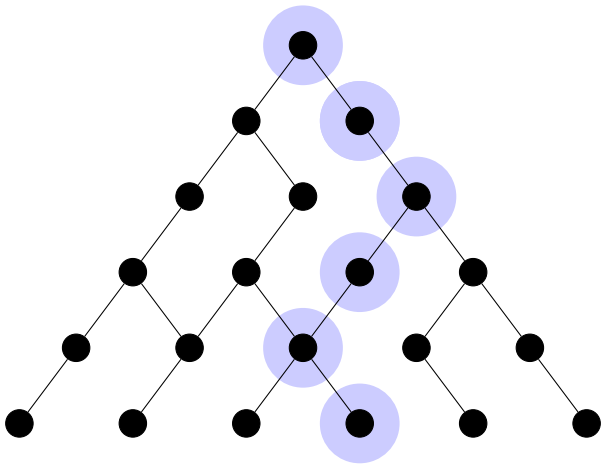
## CTL in Pictures



$\text{AG } \phi$

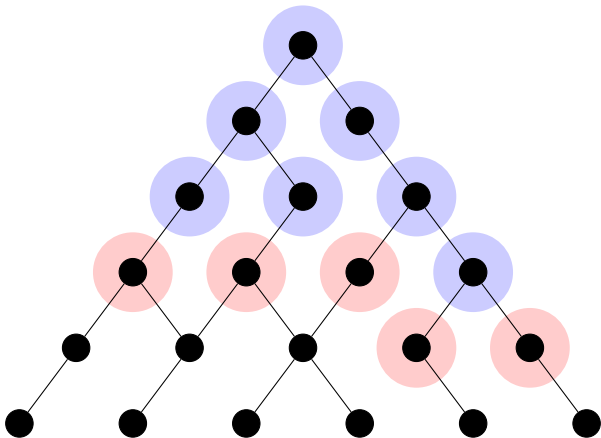
For all paths, for all states along them,  $\phi$  holds.

## CTL in Pictures

EG  $\phi$ 

There exists a path such that, for all states along it,  $\phi$  holds.

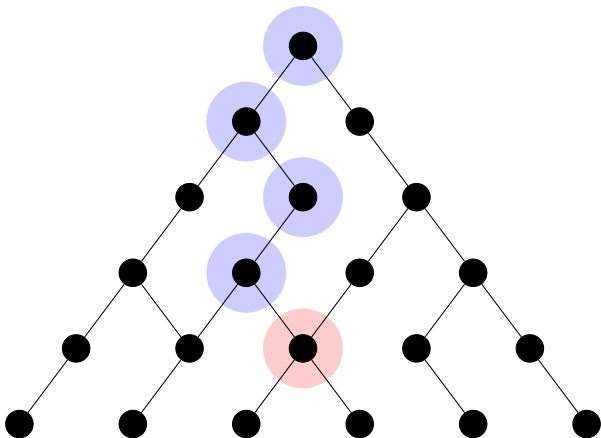
## CTL in Pictures



$$A[\phi U \psi]$$

For all paths,  $\psi$  eventually holds, and  $\phi$  holds at all states earlier.

## CTL in Pictures



$$E[\phi U \psi]$$

There exists a path where  $\psi$  eventually holds, and  $\phi$  holds at all states earlier.

# Examples of CTL formulas (and their possible readings)

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- ▶  $\text{EF } \phi$   
*it is possible to get to a state where  $\phi$  is true*
- ▶  $\text{AG AF enabled}$   
*A certain process is enabled infinitely often on every computation path*
- ▶  $\text{AG (requested} \rightarrow \text{AF acknowledged)}$   
*for any state, if a request occurs, then it will eventually be acknowledged*
- ▶  $\text{AG } (\phi \rightarrow \text{E}[\phi \text{ U } \psi])$   
*for any state, if  $\phi$  holds, then there is a future where  $\psi$  eventually holds, and  $\phi$  holds for all points in between*
- ▶  $\text{AG } (\phi \rightarrow \text{EG } \psi)$   
*for any state, if  $\phi$  holds then there is a future where  $\psi$  always holds*
- ▶  $\text{EF AG } \phi$   
*there exists a possible state in the future, from where  $\phi$  is always true*

# CTL Equivalences

de Morgan dualities for the temporal connectives:

$$\neg \mathbf{EX} \phi \equiv \mathbf{AX} \neg \phi$$

$$\neg \mathbf{EF} \phi \equiv \mathbf{AG} \neg \phi$$

$$\neg \mathbf{EG} \phi \equiv \mathbf{AF} \neg \phi$$

Also have

$$\mathbf{AF} \phi \equiv \mathbf{A}[\top \mathbf{U} \phi]$$

$$\mathbf{EF} \phi \equiv \mathbf{E}[\top \mathbf{U} \phi]$$

$$\mathbf{A}[\phi \mathbf{U} \psi] \equiv \neg(\mathbf{E}[\neg \psi \mathbf{U} (\neg \phi \wedge \neg \psi)] \vee \mathbf{EG} \neg \psi)$$

From these, one can show that the sets  $\{\mathbf{AU}, \mathbf{EU}, \mathbf{EX}\}$  and  $\{\mathbf{EU}, \mathbf{EG}, \mathbf{EX}\}$  are both adequate sets of temporal connectives.