ECE/CS 498 DSU/DSG Spring 2020 In-Class Activity 6

NetID:

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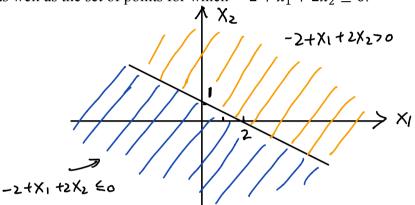
The purpose of the in-class activity is for you to:

- (i) Review concepts related to SVM and neural networks
- (ii) Work out steps in backpropagation for optimization of a neural network

Support Vector Machine

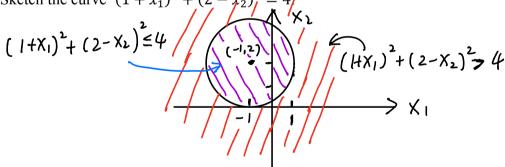
1. Linear decision boundary

Sketch the hyperplane $-2 + x_1 + 2x_2 = 0$. Indicate the set of points for which $-2 + x_1 + 2x_2 > 0$, as well as the set of points for which $-2 + x_1 + 2x_2 \le 0$.



2. Non-linear decision boundary

a) Sketch the curve $(1 + x_1)^2 + (2 - x_2)^2 = 4$



- b) On your sketch, indicate the region for which $(1 + x_1)^2 + (2 x_2)^2 > 4$, as well as the region for which $(1 + x_1)^2 + (2 x_2)^2 \le 4$.
- c) Suppose that a classifier assigns an observation (x_1, x_2) to the blue class if $(1 + x_1)^2 + (2 x_2)^2 > 4$, and to the red class otherwise. To what class is the observation (0,0) classified? (-1,1)?

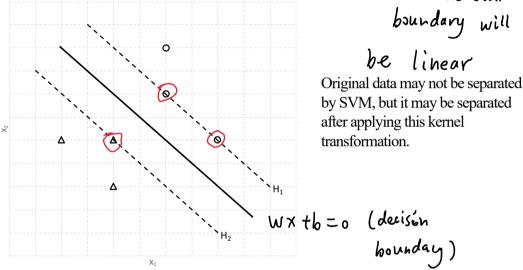
$$(-1,1) \rightarrow \text{red class}$$

d) The decision boundary equation in c) is not linear in terms of an input $x = (x_1, x_2)$ since it has x_1^2 and x_2^2 terms. However, suppose that we instead consider $\mathbf{x} = (x_1,$ x_1^2 , x_2 , x_2^2). This might be the case after applying a kernel transformation to the dataset. Is the decision boundary equation linear then? What might be a reason for

applying this kernel transformation? after sin plificath: $(1+x_1)^2 + (2-x_2)^2 = 4 \implies 1+2x_1+x_1^2 - 4x_2+x_2^2 = 0$ $\phi(x) = [1, x_1, x_2, x_1^2, x_2^2] \in K[x_i, x_j] = [tx_1 + x_2 + x_1^2 + x_2^2 + x_1x_2] \in K[x_i, x_j] = [tx_1 + x_2 + x_1^2 + x_1x_2] \in K[x_i, x_j] = [tx_1 + x_2 + x_1^2 + x_1x_2] \in K[x_i, x_j] = [tx_1 + x_2 + x_1^2 + x_1x_2] \in K[x_i, x_j] = [tx_1 + x_2 + x_1^2 + x_1x_2] \in K[x_i, x_j] = [tx_1 + x_2 + x_1^2 + x_1x_2] \in K[x_i, x_j] = [tx_1 + x_2 + x_1^2 + x_1x_2] \in K[x_i, x_j] = [tx_1 + x_2 + x_1^2 + x_1x_2] \in K[x_i, x_j] = [tx_1 + x_2 + x_1^2 + x_1x_2] \in K[x_i, x_j] = [tx_1 + x_1 + x_2 + x_1^2 + x_1x_2] \in K[x_i, x_j] = [tx_1 + x_1 + x_2 + x_1^2 + x_1x_2] \in K[x_i, x_j] = [tx_1 + x_1 + x_2 + x_1^2 + x_1x_2] \in K[x_i, x_j] = [tx_1 + x_1 + x_2 + x_1^2 + x_1x_2] \in K[x_i, x_j] = [tx_1 + x_1 + x_2 + x_1x_2] \in K[x_i, x_j] = [tx_1 + x_1 + x_2 + x_1x_2] \in K[x_i, x_j] = [tx_1 + x_1 + x_2 + x_1x_2] \in K[x_i, x_j] = [tx_1 + x_1 + x_2 + x_1x_2] \in K[x_i, x_j] = [tx_1 + x_1 + x_2 + x_1x_2] \in K[x_i, x_j] = [tx_1 + x_1 + x_2 + x_1x_2] \in K[x_i, x_j] = [tx_1 + x_1 + x_2 + x_1x_2] \in K[x_i, x_j] = [tx_1 + x_1 + x_2 + x_1x_2] \in K[x_i, x_j] = [tx_1 + x_1 + x_2 + x_1x_2] \in K[x_i, x_j] = [tx_1 + x_1 + x_2 + x_1x_2] \in K[x_i, x_j] = [tx_1 + x_1 + x_2 + x_1x_2] \in K[x_i, x_j] = [tx_1 + x_1 + x_2 + x_1x_2] \in K[x_i, x_j] = [tx_1 + x_1 + x_2 + x_1x_2] = [tx_1 + x_1 + x_1x_2] = [tx_1 + x_1x_$

3. Hard margin SVM Suppose we are learning a hard margin SVM with two real-valued features x_1, x_2 and

binary label $y \in \{-1, +1\}$ (represented by \triangle and \bigcirc , respectively). The training data is \neg pictured in the figure below. Our linear classifier takes the form $\mathbf{w} \cdot \mathbf{x} + b = 0$. boundary will



- a) According to the maximum margin principle, identify the support vectors, and sketch the decision boundary of the trained SVM. The red-circled points are the support vetors.
- b) Suppose hyperplane H_1 takes the form $\mathbf{w} \cdot \mathbf{x} + b = 1$, write down the equations for H_2 . H2: w·x+b=-1
- c) The constraints for linear hard margin SVM can be written as $y_i(\mathbf{w} \cdot \mathbf{x}_i + b) \ge 1$, $\forall i \in \{1, ..., N\}$. Explain why. This equation can be interpreted as any given point in the space is at least I away from the hyperplane and the training set are seperated 100% correct J
 - d) What condition do the data points have to satisfy such that a feasible w exists? requirement of the hard All data points are classified correctly Margin SVM

e) Calculate the distance between H_1 and H_2 .

Margin distance =
$$\frac{\vec{w}^T \vec{x} + b + \vec{1} - (\vec{w}^T \vec{x} + b - \vec{1})}{||\vec{w}||} = \frac{2}{||\vec{w}||}$$

f) Based on your answer to the above questions, write down the optimization problem whose solution is hard margin SVM.

$$\max \frac{2}{||\vec{w}||} \Rightarrow \min ||\vec{w}|| \Rightarrow \min \frac{||\vec{w}||^2}{2}$$

\Rightarrow \text{argmin}_{\vec{w}} \frac{1}{2} ||\vec{w}||^2 \text{ such that } 1 \leq y_i (\vec{w}^T \vec{x}_i + b) \, \forall i \in \{1, \ldots, N\}

g) For the following data points $x_1 = (1, 2, 3)$, $x_2 = (4, 1, 2)$, $x_3 = (-1, 2, -1)$ corresponding to class $y_1 = +1$, $y_2 = +1$, $y_3 = -1$, one of the following w, b gives the correct SVM decision boundary ($w \cdot x + b = 0$). Which one is it? Show your work.

A.
$$w = [0.3, 0, 0.4]', b = -0.4$$
B. $w = [0.2, 0, 0.4]', b = -0.4$
C. $w = [0.1, 0, 0.4]', b = -0.4$
For y1: 1.1
For y2: 1.6
For y3: 1.1

D.
$$w = [0.4, 0, 0.2]', b = -0.4$$

B is the correct SVM decision boundary. For y2: 1. 2000000000000002

C.

В.

For y1: 0.90000000000000002

For y2: 0.8000000000000002

For y3: 0.9

D.

For y1: 0.6

For y2: 1.6

For y3: 1.0

Compare the objective for A and B

A: 0.125

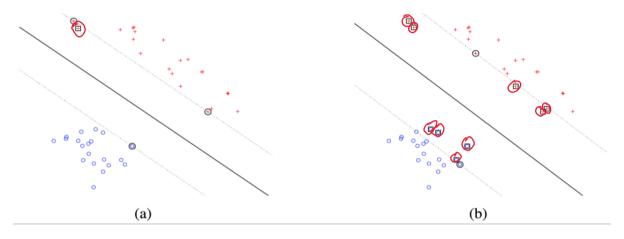
B: 0.100000000000000002

4. Soft margin SVM

Recall the program for solving the soft margin SVM:

$$\min_{\mathbf{w}, \ \xi_{I} \ge 0} \frac{1}{2} ||\mathbf{w}||^{2} + C \sum_{i}^{N} \xi_{i} \qquad s.t. \quad 1 - \xi_{i} \le y_{i}(\mathbf{w}^{T} \mathbf{x}_{i} + b) \quad \forall i \in \{1, \dots, N\}$$

We have plotted the SVM solutions for a training dataset in Figure (a) and (b) corresponding to two values of C:



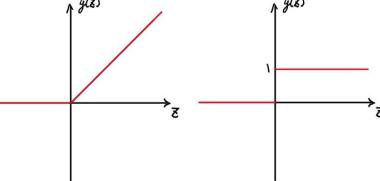
- a) Indicate non-zero ξ_i s on both plots (a) and (b). The red-circled points are those non-zero ξ_i s.
- b) Which figure corresponds to a larger value of C? Explain why. Figure (a) corresponds to a larger value of C, because the amount of allowed slack is smaller in (a) than that in (b). With a larger C, the amount of allowed slack should be smaller.

The unconstrained form of the above optimization problem is given as:

$$\min_{\mathbf{w}, \mathbf{b}} \frac{1}{2} ||\mathbf{w}||^2 + C \sum_{i=1}^{N} \max\{0, 1 - y_i(\mathbf{w}^T \mathbf{x}_i + b)\}$$

c) Draw the function $g(z) = \max\{0, z\}$ for scalar variable z. What is the derivative $\frac{dg(z)}{dz}$? Draw the derivative.





d) Compute the gradient of this unconstrained program w.r.t w. [Hint: Think of z in part (c) as $1 - y_i(w^Tx_i + b)$, you can express max in terms of an indicator function]

$$\Rightarrow C\vec{w} + \sum_{i=1}^{M} -y_i \vec{x_i}$$
, where $x_i \in \{x_1, x_2, \dots, x_M\}$ satisfy $1 - y_i (\vec{w}^T \vec{x_i} + b) > 0$

e) Suppose you are training your SVM using gradient descent and the gradient derived in (d), the original gradient is $\mathbf{w} = [2,2]'$, b = -1. The first iteration we trained on data point $\mathbf{x_1} = (1,1)$, $\mathbf{y_1} = 1$; the second iteration we trained on data point $\mathbf{x_2} = (-1,-1)$, $\mathbf{y_2} = -1$, $\lambda = 1$, assuming both C and learning-rate to be 1 calculate the gradient after these two iterations.

$$\therefore 1 - y_1(\vec{w}^T \vec{x}_1 + b) = -2 < 0$$

$$\therefore \nabla \vec{w} = \begin{bmatrix} 2 \\ 2 \end{bmatrix}$$

$$\therefore \vec{w}_1 = \vec{w} - 1 \times \nabla \vec{w} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\therefore 1 - y_2(\vec{w}^T \vec{x}_2 + b) = 0$$

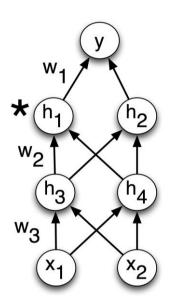
$$\therefore \nabla \vec{w} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} + \vec{x}_2$$

$$\therefore \vec{w}_2 = \vec{w}_1 - 1 \times \nabla \vec{w} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

Neural Networks

1. Partial derivatives

Consider the network shown in the figure below. All the hidden units use the ReLU- $h_i(z_i) = \max\{z_i, 0\}$. We are trying to minimize a cost function C which depends only on the activation of the output unit y. The unit h_1 (marked with a *) receives an input of $z_i = -1$ on a training iteration, so its output is 0. Based only on this information, which of the following weight derivatives are guaranteed to be 0 for this training case? Write YES or NO for each. Justify your answers informally. (Hint: don't work through the backprop computations. Instead think about what the partial derivatives really mean.)



a)
$$\frac{\partial C}{\partial w_1}$$
 NO

b)
$$\frac{\partial C}{\partial w_2}$$
 YES

c)
$$\frac{\partial C}{\partial w_3}$$
 YES

$$z_i = -1$$

 $h'_1(z_i) = 0$, according to problem 4.(c) in SVM

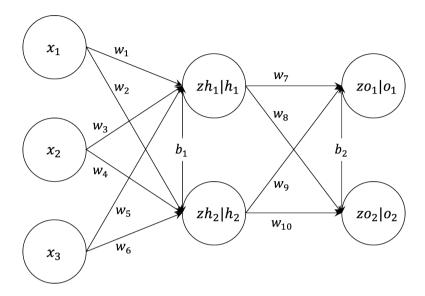
 \therefore any weight derivative including $\frac{dh_1(z_i)}{z_i}$ should be 0

 \therefore based on the network, $\frac{\partial C}{\partial w_2}$ and $\frac{\partial C}{\partial w_3}$ includes $\frac{dh_1(z_i)}{z_i}$

 $\therefore \frac{\partial C}{\partial w_2}$ and $\frac{\partial C}{\partial w_3}$ are gauranteed to be 0 while the value of $\frac{\partial C}{\partial w_1}$ is not sure

2. Backpropagation

The neural network considered in this question has three input neurons, one hidden layer with two neurons, and one output layer with two neurons. b_1 and b_2 are bias terms.



a) Suppose $zh_1 = w_1x_1 + w_3x_2 + w_5x_3 + b_1$, $h_1 = \text{sigmoid}(zh_1)$, and similar relationships hold for the other neurons in the hidden/output layer. Assume the current parameters of the networks $w_1, w_2, w_3, w_4, w_5, w_6, w_7, w_8, w_9, w_{10} = 0.1, 0.2, 0.3, 0.4, 0.5, 0.6, 0.7, 0.8, 0.9, 0.1, <math>b_1, b_2 = 0.5, 0.5$. Given input $x_1, x_2, x_3 = 1, 4, 5$, use forward propagation to find out the value of h_1, o_1 . You can think of writing a Python program.

```
In [4]:
              def sigmoid(x):
                  return 1/(1 + np. exp(-x))
              x = np. array([1, 4, 5])
              w_h = np. array([[.1, .2],
                                [.3, .4],
                                [.5, .6]
              w_o = np. array([[.7, .9],
                                [.8,.1]
              b_1 = np. array([.5, .5])
              b_2 = np. array([.5, .5])
              zh = np. dot(x, w_h) + b_1
              zo = np. dot(zh, w_o) + b_2
              print('h1\n', sigmoid(zh[0]))
              print('o1\n', sigmoid(zo[0]))
              h1
               0.9866130821723351
              01
               0.9995694429186754
```

b) Let t_1, t_2 represent the true labels. Define the sum of squared loss $E = \frac{1}{2}((o_1 - t_1)^2 + (o_2 - t_2)^2)$. Write down the partial derivatives $\frac{\partial E}{\partial w_1}, \frac{\partial E}{\partial b_2}, \frac{\partial E}{\partial w_1}$

according to the chain rule. Example for
$$\frac{\partial E}{\partial w_{10}}$$
, $\frac{\partial E}{\partial w_2}$ is given below.

$$\frac{\partial E}{\partial w_{10}} = \frac{\partial E}{\partial o_{2}} \frac{\partial o_{2}}{\partial z_{02}} \frac{\partial z_{02}}{\partial z_{02}} \frac{\partial z_{02}}{\partial w_{10}}$$

$$\frac{\partial E}{\partial w_{2}} = \frac{\partial E}{\partial o_{2}} \frac{\partial o_{2}}{\partial z_{02}} \frac{\partial z_{02}}{\partial h_{2}} \frac{\partial h_{2}}{\partial z_{02}} \frac{\partial z_{02}}{\partial w_{2}} \frac{\partial z_{02}}{\partial w_{2}} \frac{\partial z_{02}}{\partial v_{2}} \frac{\partial z_{02}}{\partial v_{2$$

For $\frac{\partial E}{\partial w_2}$, look at the two paths which lead from w_2 to E. Backpropagation includes both the paths in the calculation.

$$\frac{\partial E}{\partial w_7} = \frac{\partial E}{\partial o_1} \frac{\partial o_1}{\partial zo_1} \frac{\partial zo_1}{\partial w_7}$$

$$\frac{\partial E}{\partial b_2} = \frac{\partial E}{\partial o_1} \frac{\partial o_1}{\partial zo_1} \frac{\partial zo_1}{\partial b_2} + \frac{\partial E}{\partial o_2} \frac{\partial o_2}{\partial zo_2} \frac{\partial zo_2}{\partial b_2}$$

$$\frac{\partial E}{\partial w_1} = \frac{\partial E}{\partial o_1} \frac{\partial o_1}{\partial z o_1} \frac{\partial z o_1}{\partial h_1} \frac{\partial h_1}{\partial z h_1} \frac{\partial z h_1}{\partial w_1} + \frac{\partial E}{\partial o_2} \frac{\partial o_2}{\partial z o_2} \frac{\partial z o_2}{\partial h_1} \frac{\partial h_1}{\partial z h_1} \frac{\partial z h_1}{\partial w_1}$$

Suppose $t_1, t_2 = 0.1, 0.05$, learning rate $\alpha = 0.01$. Calculate the updated w_7, b_2, w_1 after one iteration of backpropagation. Use $h_2 = 1$, $o_2 = 0.8$.

$$\therefore \frac{\partial E}{\partial o_1} = o_1 - t_1 = 0.89956944, \ \frac{\partial E}{\partial o_2} = o_2 - t_2 = 0.75$$

$$\therefore \frac{\partial o_1}{\partial z o_1} = o_1(1 - o_1) = 0.00043037, \ \frac{\partial o_2}{\partial z o_2} = o_2(1 - o_2) = 0.16$$

$$\because \frac{\partial zo_1}{\partial w_7} = h_1 = 0.98661308, \ \frac{\partial zo_1}{\partial b_2} = 1, \ \frac{\partial zo_2}{\partial b_2} = 1$$

$$\therefore \frac{\partial zo_1}{\partial h_1} = w_7 = 0.7, \ \frac{\partial zo_2}{\partial h_1} = w_8 = 0.8$$

$$\therefore \frac{\partial h_1}{\partial z h_1} = h_1 (1 - h_1) = 0.013207710, \ \frac{\partial z h_1}{\partial w_1} = x_1 = 1$$

3. Neural Network Playground (for you to explore)

https://developers.google.com/machine-learning/crash-course/introduction-to-neural-networks/playground-exercises : $\frac{\partial E}{\partial w_2} = 0.00038196$, $\frac{\partial E}{\partial b_2} = 0.12038715$, $\frac{\partial E}{\partial w_1} = 0.00127152$

$$w_7^+ = w_7 - \alpha \times \frac{\partial E}{\partial w_7} = 0.69999618$$

$$\therefore b_2^+ = b_2 - \alpha \times \frac{\partial E}{\partial b_2} = 0.49879613$$

$$\therefore w_1^+ = w_1 - \alpha \times \frac{\partial E}{\partial w_1} = 0.09998728$$