Probabilistic Graph Models: Factor Graphs

ECE/CS 498 DS U/G

Lecture 21: Factor Graphs

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Announcements

- Course Timeline:
 - Wed 4/8: Factor graphs and belief propagation
 - Mon 4/13: Belief propagation continued
- Discussion section on Friday 4/10
 - Talk through MP 3 for ~15 minutes
 - Office hours with the TA for remaining ~45 min
- Final Project
 - Progress report 2 due Friday April 17 @ 11:59 PM on Compass2G
 - There should be *substantial* progress with projects by this point (i.e. meaningful results, ML/AI models)

Objective: Use real incident data to pre-empt attacks

• Mine patterns of alerts prior to the attack onset in real incidents

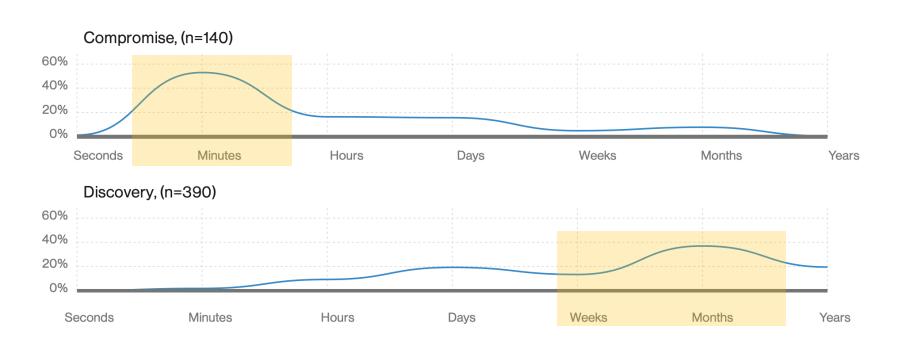
Measure the reliability of these patterns using randomness tests.

• Design pre-emption techniques, to provide attack warning sufficiently in advance to system misuses, to reduce missed incidents and false positives

• Develop a testbed to measure the efficacy of preemptiveness on new attacks that intermingle with legitimate traffic in production network

Challenges: Fast attacks, slow detection

- Challenges:
 - Big data
 - Partial view of attacks
 - Fast attacks, slow detection





62% (23/37) OF HIGH-SEVERITY INCIDENTS WERE CAUGHT IN THE BREACH-PHASE, HAVING ALREADY RESULTED IN SIGNIFICANT DAMAGE – STOLEN CRED.



THE ATTACK MATURE IN FEW MINUTES, WHILE FORENSIC DIAGNOSIS TAKES HOURS OR DAY

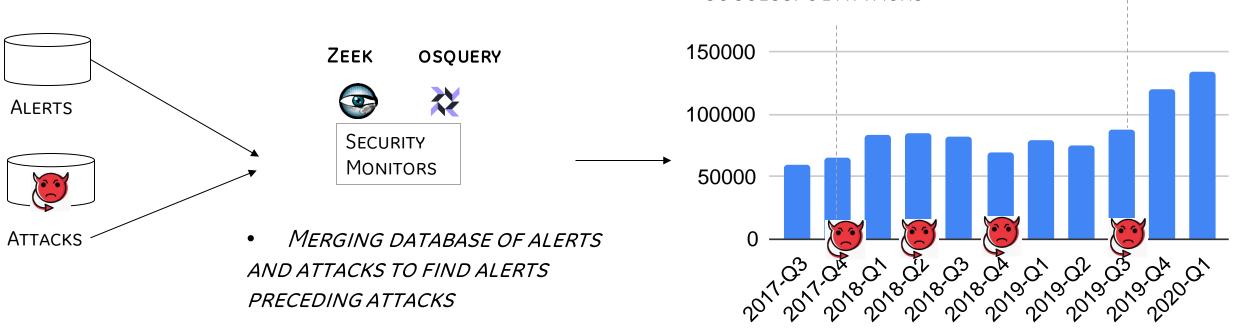
MY GOAL: PREEMPT THE ATTACK IN ADVANCE BEFORE SYSTEM MISUSE.

Challenges: abundant alerts

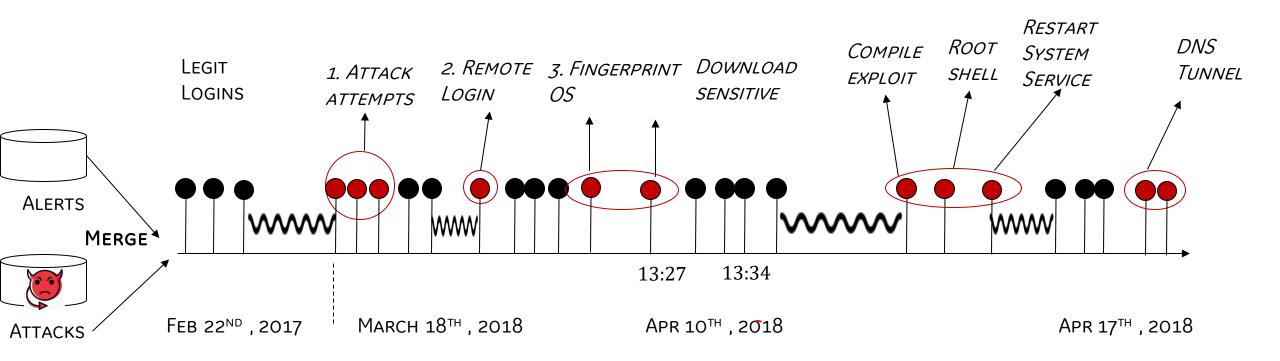
- Challenges:
 - Big data
 - Partial view of attacks
 - Fast attacks, slow detection
 - Many alerts, but few actual attacks

AVG. 80,000 ALERTS/DAY, BUT A FEW SUCCESSFUL ATTACKS/YEAR.

VERY FEW (< 10 ALERTS) PRECEDE SUCCESSFUL ATTACKS



Attack 1. stolen credential attack that has not been discovered in a month



ATTACK STARTS

ATTACK ENDS

- BLACK CIRCLES ARE REGULAR ALERTS IN THE SYSTEM
- RED CIRCLES ARE ACTUAL ATTACK CORRELATED BASED ON A USER'S IP ADDRESS AND/OR USER IDENTIFIER.

WE FOCUS ON ALERTS PRECEDING ATTACKS



- HOW OFTEN PATTERNS OF ALERTS OCCUR IN THE DATA?
- ARE THE PATTERNS RANDOM OR THEY HAVE A CAUSAL EFFECT?
- GIVEN ANY ATTACK, HOW LIKELY WE SEE A PARTICULAR PATTERN TO OCCUR? (CONDITIONAL PROBABILITY)

Reasoning about patterns

- ALERTS OCCUR AS CLUSTERS, GROUPED BY TIME PROXIMITY AND IP ADDRESS
- ALERTS ARE REPEATED AMONG ATTACKS
- Some alerts are found in both legitimate users and attackers, thus are not always reliable (Example: Logging in from a remote site appears in both users traveling and attackers)

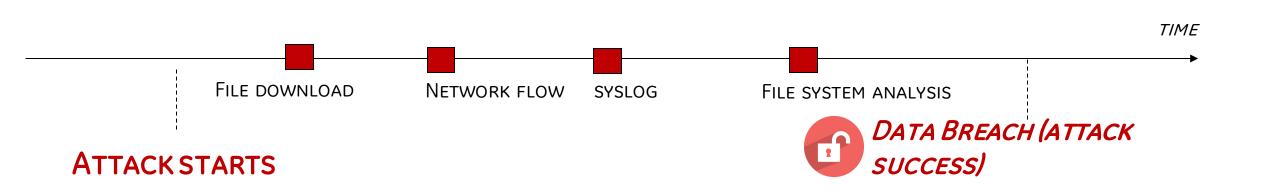


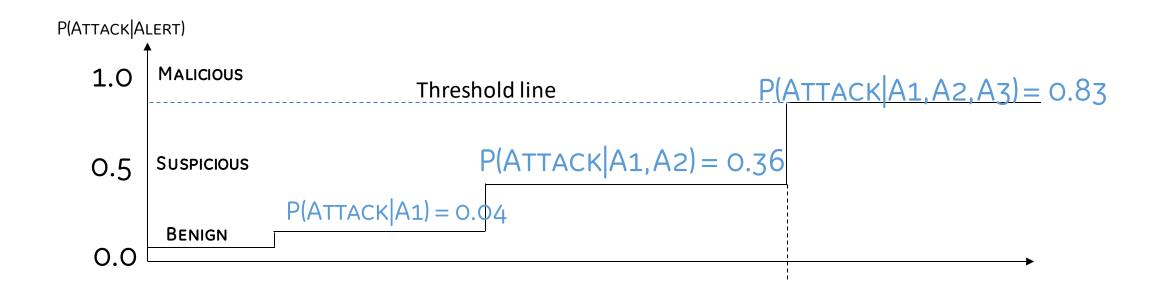
- 1. Show statistical evidence of patterns (conditional probabilities)
- 2. Use randomness testing to validate the predictive power of a pattern
- 3. ENCODE PATTERNS AND PROBABILITIES INTO A DETECTION MODEL (WHICH IS A PROBABILISTIC GRAPHICAL MODEL.)

HOW DOES A SECURITY EXPERT ANALYZE THE ATTACK?

Four data points established from the analysis

- 1. A suspicious source code was downloaded,
- 2. The user login occurred at nearly the same time as the download,
- 3. First time login from IP address 195.aa.bb.cc,
- 4. Additional communication on other ports (FTP)

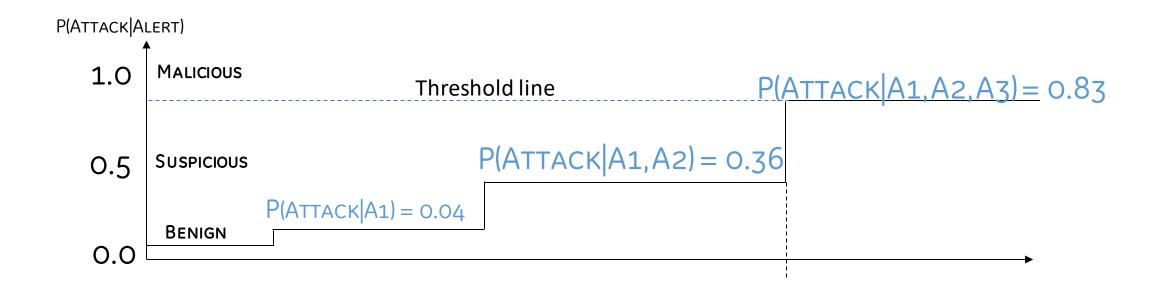




A1. REMOTE LOGIN

A2. OS FINGERPRINTING

A3. Download sensitive files



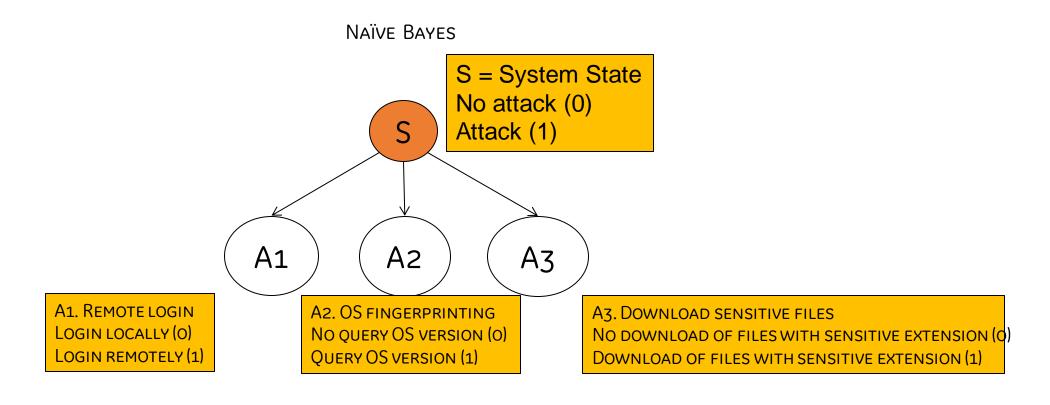
- We can stop the attack at threshold 0.83.
- Neither malicious code would be executed nor data would be extracted
- However, this will have a high false positive (16% or 160 false alarms of attacks per day for 1000 active users)

This example illustrate the idea of building a graphical model, but we need to do better than these numbers, focusing on reducing false positives.

MODELING THE MATURATION OF ATTACK AND SYSTEM STATE

GIVEN THREE ALERT: A1, A2, A3, HOW CAN WE REASON ABOUT THE UNDERLYING SYSTEM STATE?

HOW TO FORMULATE THE SYSTEM STATE AS A FUNCTION OF OBSERVED ALERTS?



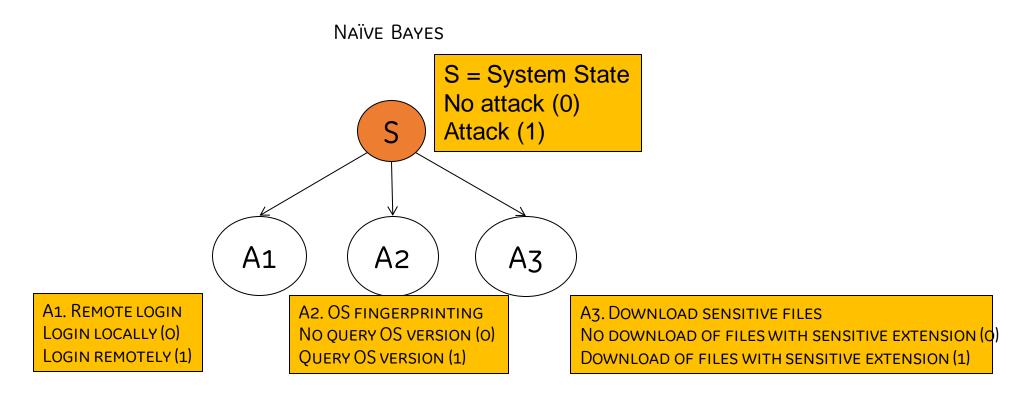
System state S is a binary random variable (0: benign, 1: attack)

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P(S,A1,A2,A3)= P(S)P(A1|S)P(A2|S)P(A3|S) Recall Naive Bayes Classifier

A2: network fingerprinting of web server

$$C^* = \underset{k \in \{1,...,K\}}{\operatorname{argmax}} p(C_k) \prod_{i=1}^{n} p(x_i | C_k)$$

- Given evidence of observed alerts We calculate the hypotheses for (inference)
 - A1 = 1, A2 = 1, A3 = 0

No attack C0:
$$P(C0) \propto P(S = 0) P(A1 = 1|S = 0) P(A2 = 1|S = 0) P(A3 = 0|S = 0)$$

= 0.934 * 0.14 * 0.25 * 0.97 = 0.032

Attack C1:
$$P(C1) \propto P(S = 1) P(A1 = 1|S = 1) P(A2 = 1|S = 1) P(A3 = 0|S = 1)$$

= 0.066 * 0.13 * 0.04 * 0.73 = 0.0002

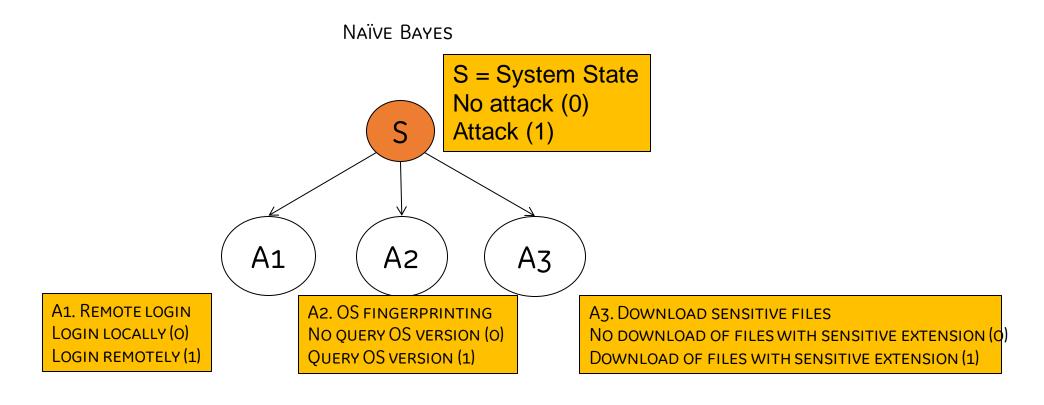
No attack CO	What is the denominator for no attack? We assume 400 users a day. 120 compromised users / 5 years 5*365 - 120 = 1705 days w/o incidents
P(S=0)	0.934
P(A1 = 1 S = 0)	0.14 = (251 – 16) / 1705
P(A2 = 1 S = 0)	0.25 = (422 - 5) / 1705
P(A3 = 0 S = 0)	0.97 = (1705-47) / 1705

Attack C1	
P(S=1)	0.066
P(A1 = 1 S = 1)	0.13 = 16 / 120
P(A2 = 1 S = 1)	0.04 = 5 / 120
P(A3 = 0 S = 1)	0.73 = 88 / 120

MODELING THE MATURATION OF ATTACK AND SYSTEM STATE

INFERENCE TASK:

Given that A1 is True, A2 is True, A3 is False, how likely it is an attack?



The naiveté of this model is the independence assumption.

MODELING THE MATURATION OF ATTACK AND SYSTEM STATE

GIVEN THREE ALERT: A1, A2, A3, HOW CAN WE REASON ABOUT THE UNDERLYING SYSTEM STATE?

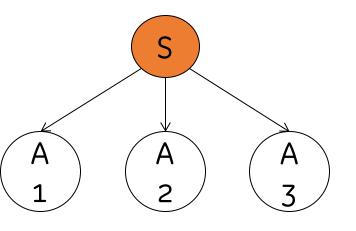
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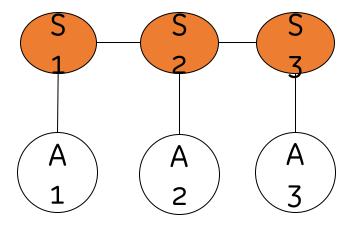
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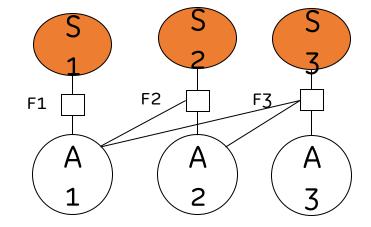
BAYESIAN NETWORK

HIDDEN MARKOV MODEL

FACTOR GRAPH







P(S,A1,A2,A3)= P(S)P(A1|S)P(A2|S)P(A3|S) $P(S_1,S_2,S_3,A_1,A_2,A_3)$ = $P(S_3|S_2) P(S_2|S_1) P(S_1) P(A_1|S) P(A_2|S) P(A_3|S)$

=

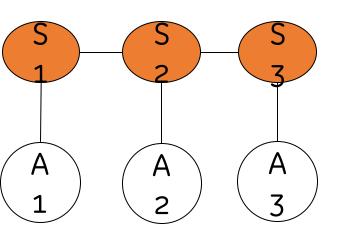
MODELING THE MATURATION OF ATTACK AND SYSTEM STATE AS AN HMM

GIVEN THREE ALERT: A1, A2, A3, HOW CAN WE REASON ABOUT THE UNDERLYING SYSTEM STATE?

HOW TO FORMULATE THE SYSTEM STATE AS A FUNCTION OF OBSERVED ALERTS?

System state S is a binary random variable (0: benign, 1: attack)

HIDDEN MARKOV MODEL



To predict the future, we calculate P(S4|S3=1) based on the transition prob

A1: Remote Login

A2: Fingerprint $S = \{0,1\}$

A3: Download sensitive $A = \{ \text{set of alerts } \exists 1, \exists 2, ..., \exists pha 1, \exists pha 2, ..., \exists pha n \} \}$

OBSERVATION MATRIX

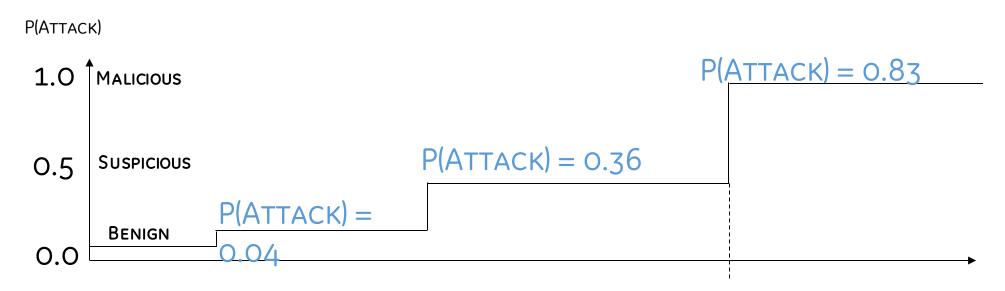
$$(Alert, State) = \begin{pmatrix} P_{A1|Attack} & P_{A1|No \ attack} \\ P_{A2|Attack} & P_{A2|No \ attack} \\ P_{A3|Attack} & P_{A3|No \ attack} \end{pmatrix}$$

TRANSITION MATRIX

$$(State_{t}, State_{t+1}) = \begin{pmatrix} P_{State_{t+1}=1|State_{t}=0} & P_{State_{t+1}=1|State_{t}=1} \\ P_{State_{t+1}=0|State_{t}=0} & P_{State_{t+1}=0|State_{t}=1} \end{pmatrix}$$

$$P(S1,S2,S3,A1,A2,A3)$$

$$= P(S3|S2) \ P(S2|S1) \ P(S1) \ P(A1|S) \ P(A2|S) \ P(A3|S)$$



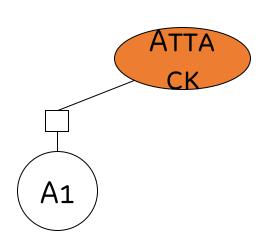
THE QUESTION IS, GIVEN THIS PATTERN, HOW LIKELY IS AN ATTACK IS PROGRESSING?

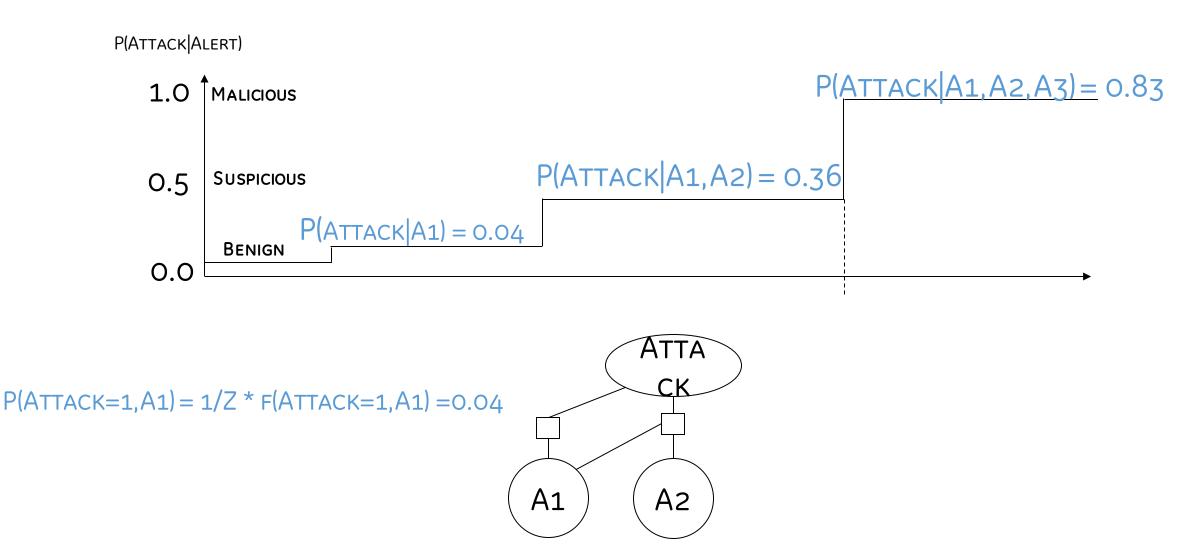
$$P(ATTACK=1) = 1/Z * F(ATTACK=1,A1) = 0.04$$

BASED ON PAST DATA, WE COUNT HOW MANY SUCCESSFUL ATTACKS DOES THIS PATTERN BY ITSELF INDICATE AND HOW MANY TIMES THE PATTERN APPEARS IN THE ENTIRE DATA.

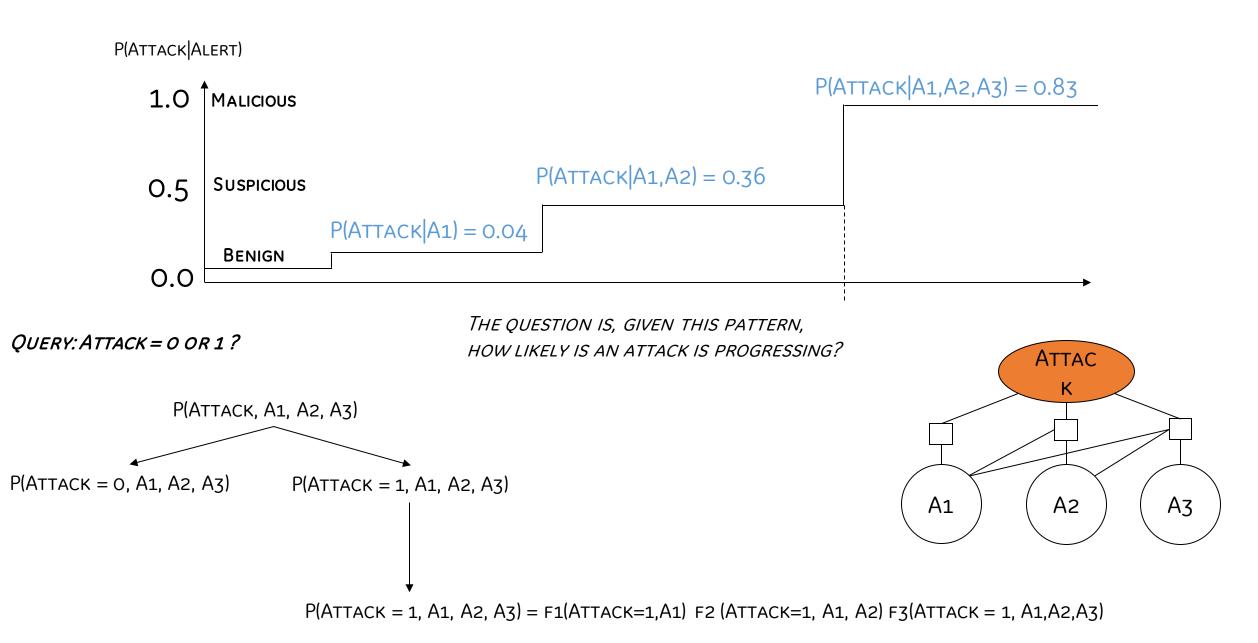
COUNT (ATTACK=1, A1)
COUNT (ATTACK=0, A1)

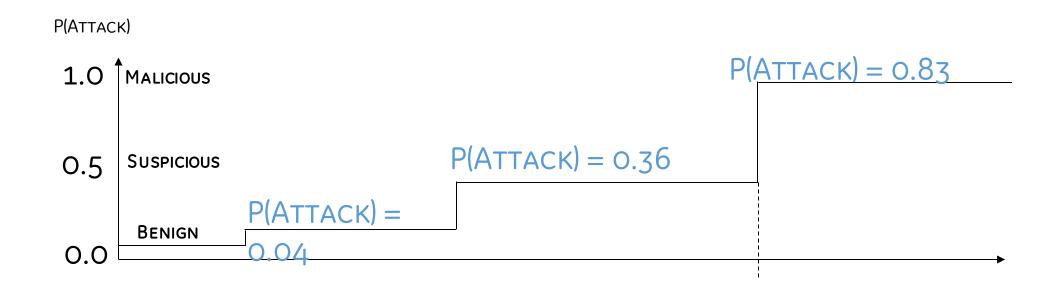
F(ATTACK,A1) = COUNT(ATTACK=1, A1) / (COUNT(ATTACK=0, A1) + COUNT(ATTACK=1,A1))





P(ATTACK|A1,A2) = 1/Z * F(ATTACK,A1) * F(ATTACK,A1,A2) = 0.04 + 0.32 = 0.36

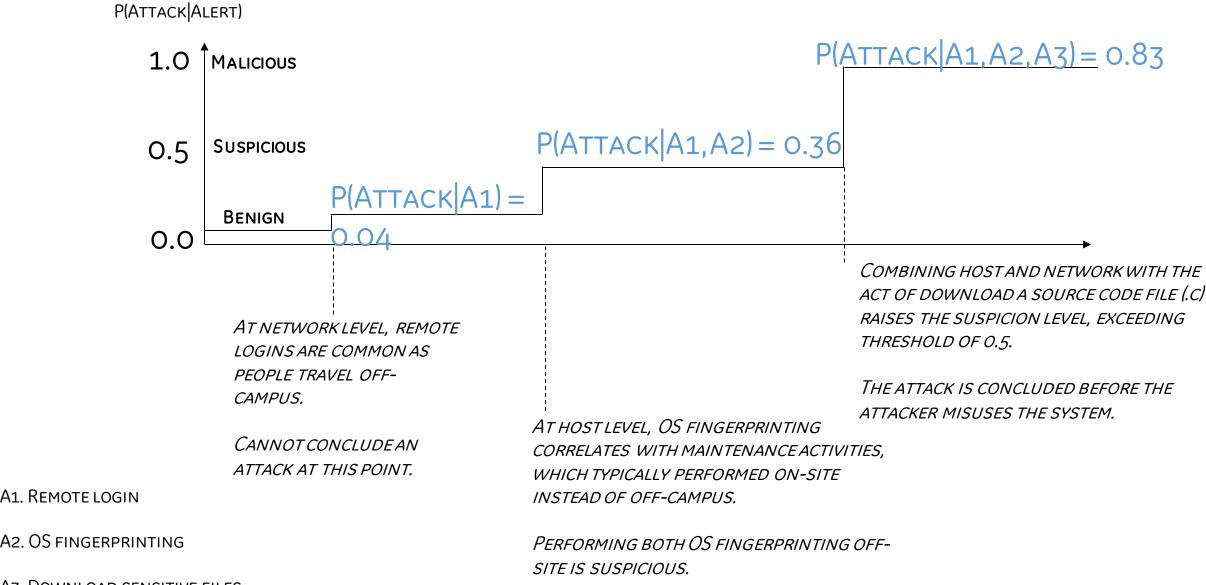




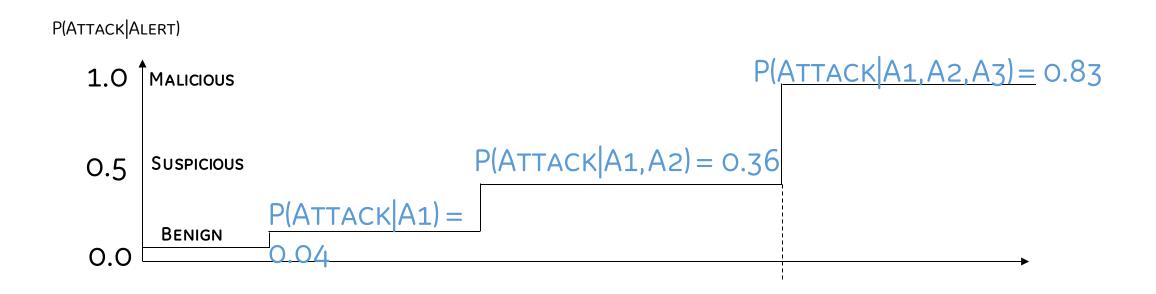
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```



A3. DOWNLOAD SENSITIVE FILES



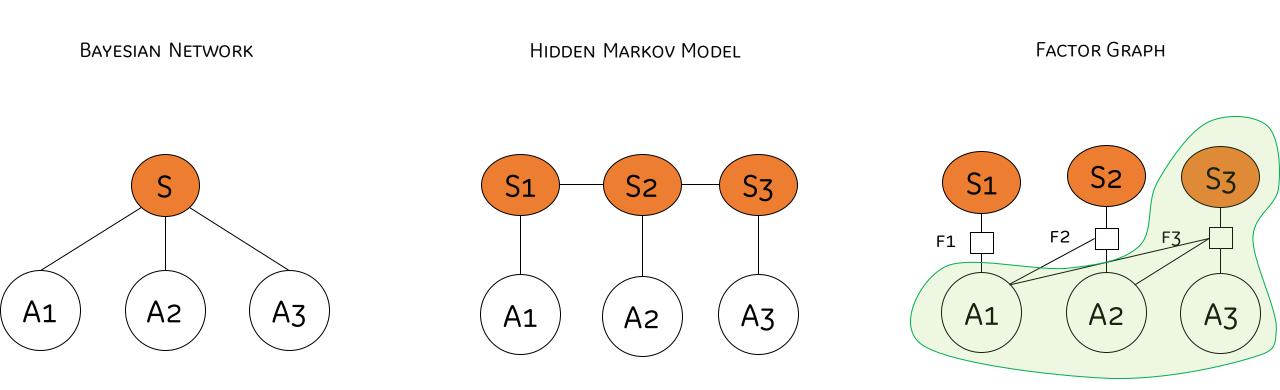
A1. REMOTE LOGIN

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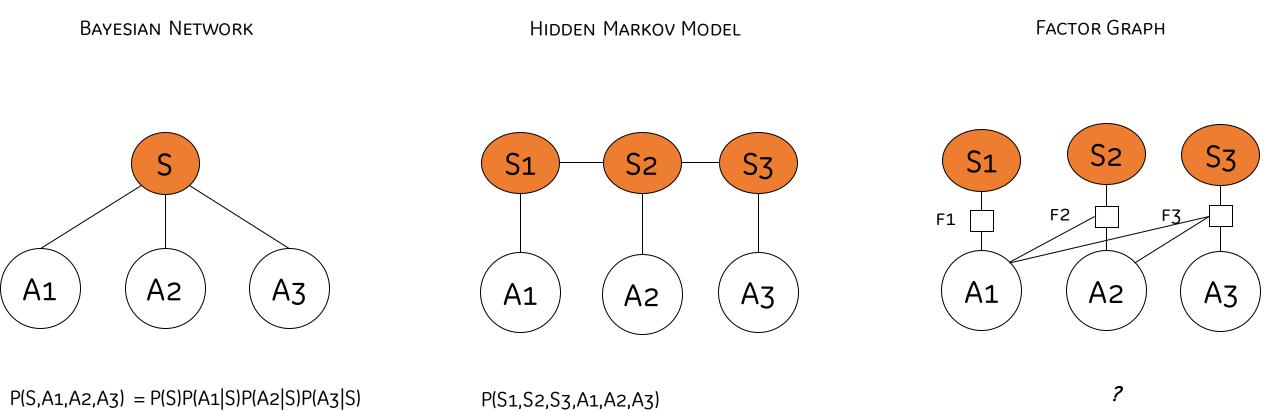
MODELING THE MATURATION OF ATTACK AND SYSTEM STATE

GIVEN THREE EVENTS: A1, A2, A3, HOW CAN WE REASON ABOUT THE UNDERLYING SYSTEM STATE?



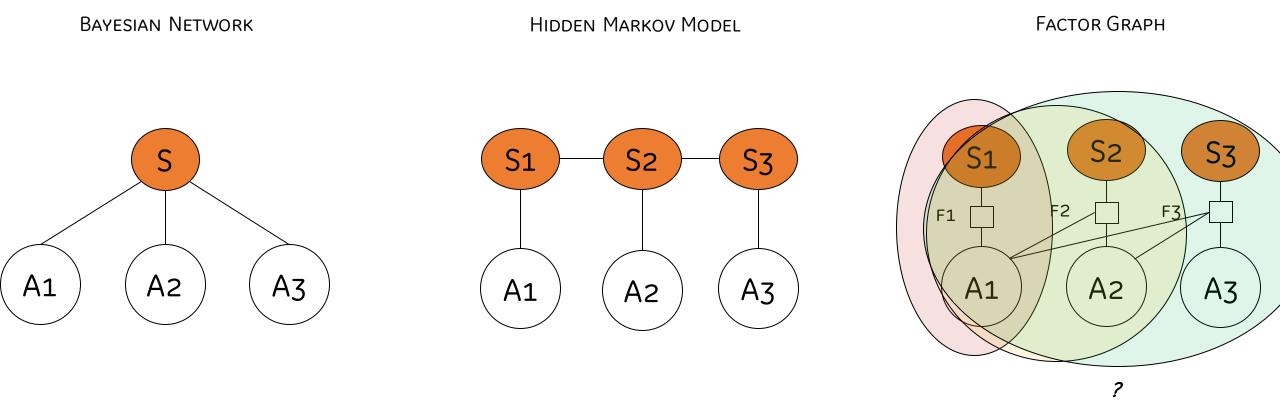
HOW TO FORMULATE THE SYSTEM STATE AS A FUNCTION OF OBSERVED EVENTS?

HOW TO FORMULATE THE SYSTEM STATE AS A FUNCTION OF OBSERVED EVENTS?



 $= P(S_3|S_2) P(S_2|S_1) P(S_1) P(A_1|S) P(A_2|S) P(A_3|S)$

HOW TO FORMULATE THE SYSTEM STATE AS A FUNCTION OF OBSERVED EVENTS?



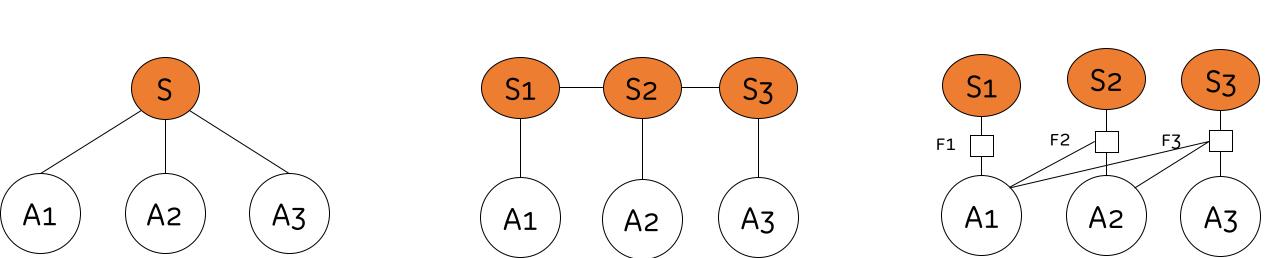
FROM CONDITIONAL INDEPENDENCE TO JOINT DISTRIBUTION FACTORIZATION

BAYESIAN NETWORK

A GRAPH IS SEPARATED INTO CLIQUES: GROUP EVENTS IN WHICH ALL ARE CONNECTED.

TWO CLIQUES ARE CONDITIONAL INDEPENDENT GIVEN ANOTHER CLIQUE C IF WE CAN FIND A PATH FROM A TO

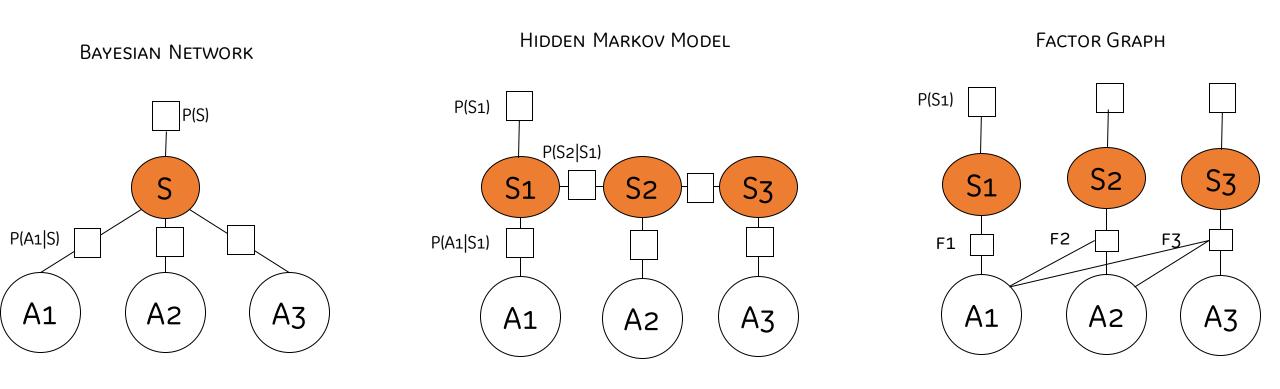
HIDDEN MARKOV MODEL



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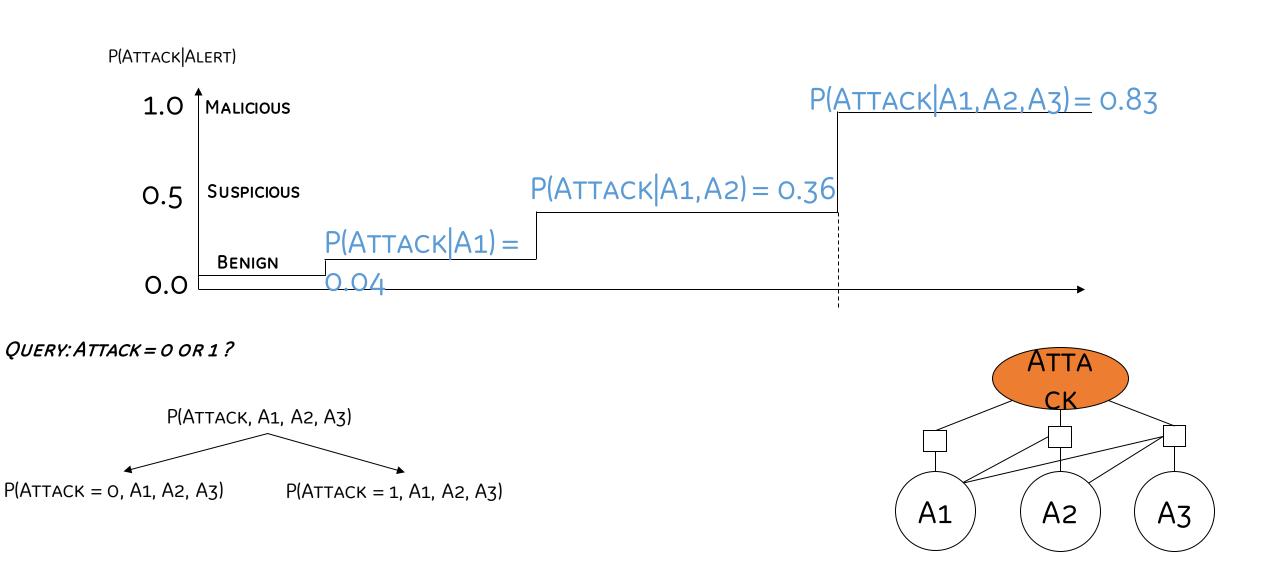
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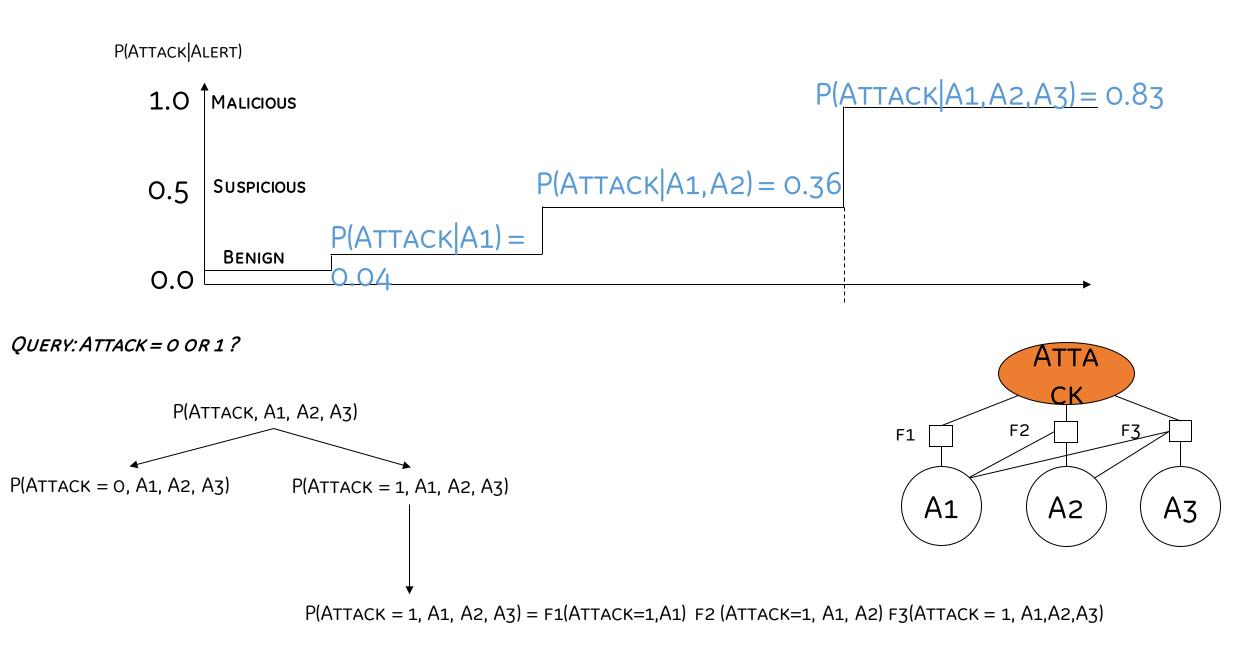
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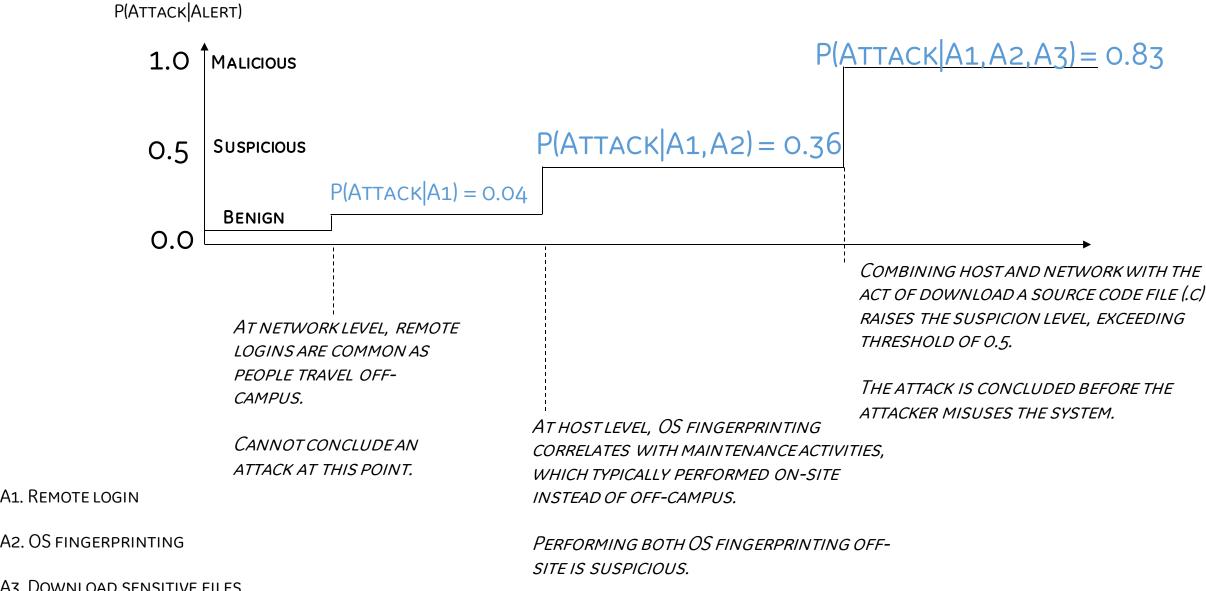


 $P(S,A_1,A_2,A_3)$ = $P(S) P(A_1|S) P(A_2|S) P(A_3|S)$

P(S1,S2,S3,A1,A2,A3) = P(S1) P(A1|S1) P(A2|S2) P(A3|S3) P(S2|S1) P (S3|S2) $P(S_{1},S_{2},S_{3},A_{1},A_{2},A_{3})$ = 1/Z $F_{1}(S_{1},A_{1})$ $F_{2}(S_{2},A_{1},A_{2})$ $F_{3}(S_{3},A_{1},A_{2},A_{3})$

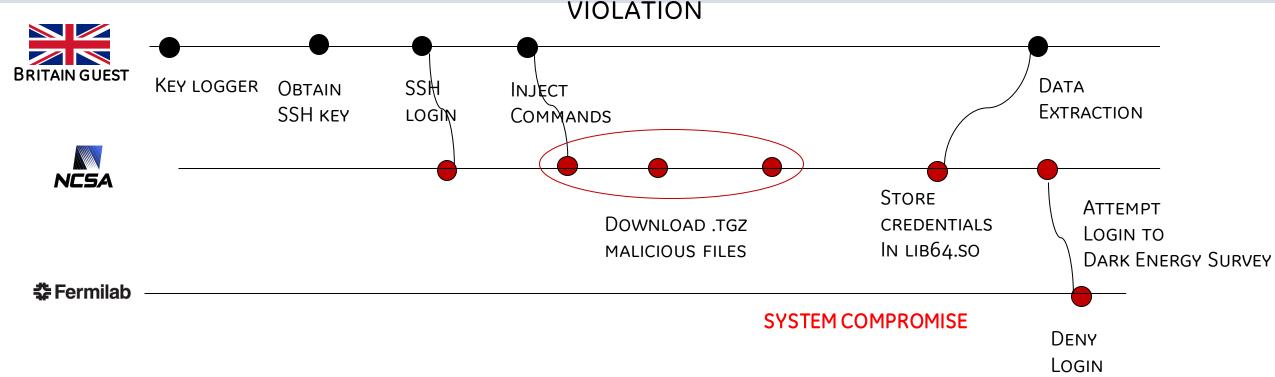






A3. DOWNLOAD SENSITIVE FILES

ATTACK 1: A CREDENTIAL STEALING ATTACK THAT WAS DETECTED AFTER SYSTEM INTEGRITY



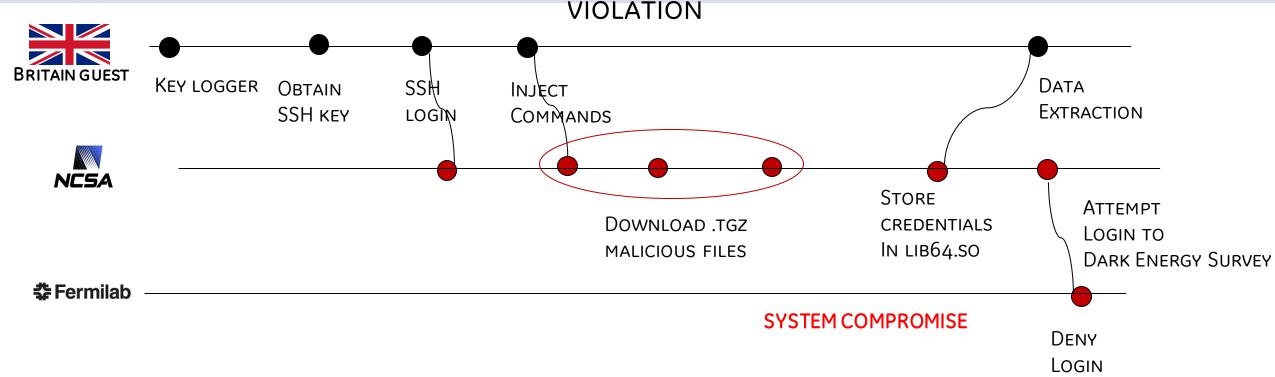
IMPACT. THE ATTACKER

- STAYED IN THE SYSTEM FOR A MONTH
- COLLECTED CREDENTIALS OF THREE SUBSEQUENT LOGINS
- ATTEMPTED (BUT FAILED) TO COMPROMISE THE COMPUTING NODES AT FERMI LAB.

Why did the attack happen? The attack was not preempted because of insufficient evidence (commands were not recorded on the host).

THE SECURITY TEAM ONLY HAD NETWORK TRACES.

ATTACK 1: A CREDENTIAL STEALING ATTACK THAT WAS DETECTED AFTER SYSTEM INTEGRITY



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Analysis of an Example Incident

(Credentials Stealing Category)

• An IDS alert shows successful remote login to a production system, Dark Energy Survey, (141.142.ww.zz) using ssh protocol from many different remote hosts

Date/Time	IP Address
2018-04-10 13:27	113.108.
2018-04-10 13:29	113.108.
2018-04-10 13:33	113.108.
2018-04-10 13:36	113.108.
2018-04-11 05:08	159.226.
2018-04-11 13:59	159.226.
2018-04-12 04:14	62.210.1
2018-04-13 07:02	159.226.
2018-04-13 14:43	159.226.
2018-04-15 05:56	159.226.
2018-04-16 05:05	159.226.
2018-04-16 05:06	159.226.

- The activity is suspect beca
 - The user was not traveling to those countries corresponding to the hosts
 - The user's credentials has been modified, rendering the user unable to login.
- The alerts do not reveal what attacker did on the compromised production host system.

Correlation with network logs

Network flows reveal further download of sensitive files in close time proximity

•	2018-04-10T13:27	181.215.zz.xx:24221/op3.tgz
•	2018-04-10T13:34	181.215.zz.xx:24221/sp.tgz

- These flows are suspect because
 - The downloads are for direct IP address, skipping legitimate domain name resolution (DNS) protocols.
 - The files are downloaded via HTTP protocol (usually port 80), but the server IP addresses are non-standard (24221)
- The server the source was downloaded from not a formal software distribution repository.
- The alert does not reveal what caused the potentially illegal download request

Correlations with host logs

 Further analysis of the host reveal that the OpenSSH server /usr/bin/ssh has been modified.

```
The file, op3.tgz, is the source code for OpenSSH v5.3.pl

A key logger injected into OpenSSH to redirect ssh login credentials to a file, '/usr/lib64/.lib/lib64.so'.
```

These activities are suspect because

The OpenSSH servers never are compiled manually, rather the OpenSSH server must be obtained from official software distribution package during maintenance.

The ".lib" directory is hidden when running standard UNIX list directory (ls) command

The lib64.so file is a text file of stolen credential, but its name masquerades as binary system file.

• Historical commands on the host reveal that the attacker attempted to connect to another iForge computing cluster, but was not successful.

Preempting the above incident

- Four data points established from the analysis
 - Multiple login attempts from remote countries affecting legitimate user logins
 - The user login occurred at nearly the same time as the download of suspicious files from remote servers.
 - SSH binary was compiled manually outside of maintenance window.
 - Failed connection attempts to internal hosts (iForge)

My Research Focus

FAST COMPROMISE

MY GOAL: **PREEMPT INTRUSION BEFORE SYSTEM MISUSE**,

WHILE LEVERAGING A RICH DATASET OF REAL ATTACKS IN AN OPERATIONAL

NETWORK.

SLOW DETECTION

Introduction to Factor Graphs

Hidden Markov Models

Model

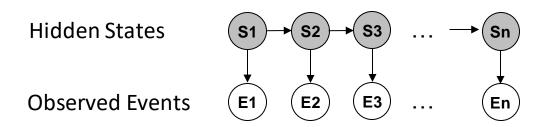
- Set of hidden states $S = \{\sigma_1, ..., \sigma_N\}$
- Set of observable events $\pmb{E} = \{\pmb{\epsilon_1}, ..., \pmb{\epsilon_M}\}$
- Transition probability matrix A
- Observation matrix B
- Initial distribution of hidden states π

Model assumptions

- An observation depends on its hidden state
- A state variable only depends on the immediate previous state (Markov assumption)
- The future observations and the past observations are conditionally independent given the current hidden state

Advantages:

- HMM can model sequential nature of input data (future depends on the past)
- HMM has a linear-chain structure that clearly separates system state and observed events.



A Hidden Markov model on observed events and system states

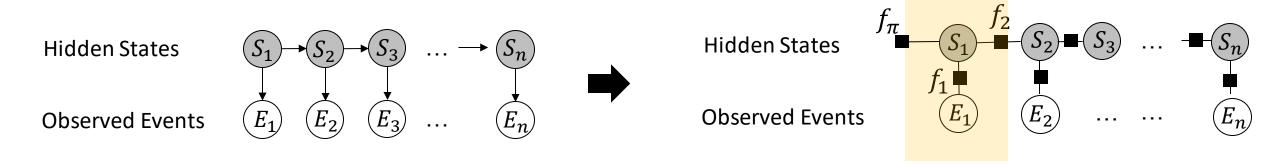
$$P(S_1, ..., S_n, E_1, ..., E_n)$$

$$= P(S_1)P(E_1|S_1) \prod_{i=2}^{n} P(S_i|S_{i-1})P(E_i|S_i)$$

Conversion of a Hidden Markov Model to a Factor Graph

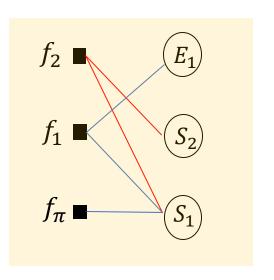
Hidden Markov Model

Factor Graph of the HMM



The above Factor Graph (FG) is a generalization of the Hidden Markov Model

- Boxes (f_{π}, f_1, f_2) represents factor function
- In the above case, it maintains the Markov assumption between states



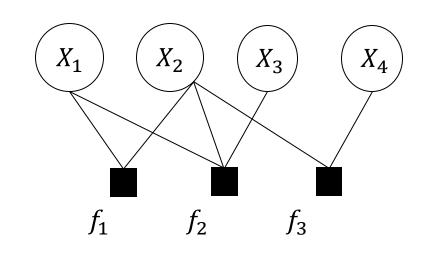
Bipartite graph representation of the FG

Definition of a Factor Graph

A factor graph is a bipartite, undirected graph of random variables and factor functions. [Frey et. al. 01].

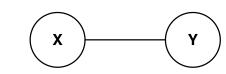
G (graph) = (X,f,E); E denotes the edges

FG can represent both causal and non-causal relations.

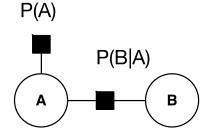




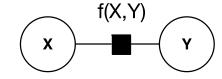
Bayesian Network (BN)



Undirected Graph



Factor Graph equivalent of BN



Factor Graph equivalent of UG

Example Factor function for HMMs

Assume that the state space and observation space are $S = \{\sigma_0, \sigma_1\}$, $E = \{\epsilon_1, \epsilon_2\}$. An example of factor functions is shown.

S	$f_{\pi}(S)$
σ_0	40
σ_1	25

S_t	E_t	$ f_1(S_t, E_t) $
σ_0	ϵ_1	20
σ_0	ϵ_2	15
σ_1	ϵ_1	40
σ_1	ϵ_2	3

S_t	S_{t+1}	$f_2(S_t, S_{t+1})$
σ_0	σ_0	5
σ_0	$\sigma_{\!1}$	1
σ_1	σ_0	10
σ_1	σ_1	15

- Factor values represents the *affinities* between the related variables
 - E.g., $f_1(\sigma_1, \epsilon_1) > f_1(\sigma_0, \epsilon_1)$ implies that σ_1 and ϵ_1 are more compatible than σ_0 and ϵ_1
- Factor functions don't necessarily represent PDs or joint probability distributions
- How are these values found?
 - 1. Given by expert or from domain knowledge
 - 2. Derived from the data (priors)

Definition of Factor functions

Definition:

- Let D be a set of random variables. We define a factor f to be a function from Val(D) to \mathbb{R} . A factor is non-negative if all its values are non-negative.
- The set of variables D is called the scope of the factor f and is denoted as Scope(f).
- $Val(\mathbf{D})$ represents the set of values \mathbf{D} can take.

Example:

A	В	f(A,B)
a_0	b_0	30
a_0	b_1	5
a_1	b_0	1
a_1	b_1	10

$$D = \{A, B\}$$

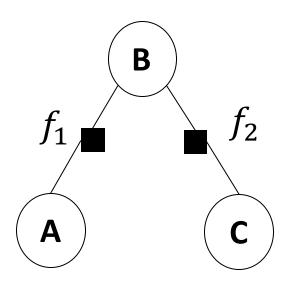
$$Val(\mathbf{D}) = \{(a_0, b_0), (a_0, b_1), (a_1, b_0), (a_1, b_1)\}$$

$$A \in \{a_0, a_1\}$$

$$B \in \{b_0, b_1\}$$

Product of Factor Functions in a Factor Graph

- In HMMs, we derived the joint distribution from the graph representation: $P(S_1, ..., S_n, E_1, ..., E_n) = P(S_1)P(E_1|S_1)\prod P(S_i|S_{i-1})P(E_i|S_i)$
- For a Factor Graph, the joint distribution can be derived from the product of factor functions (given that all factor functions are non-negative)



Example Factor Graph over variables *A*, *B*, *C*.

$$P(A, B, C) = \frac{1}{Z} f_1(A, B) f_2(B, C)$$

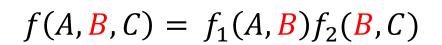
where, the normalization Z is given as

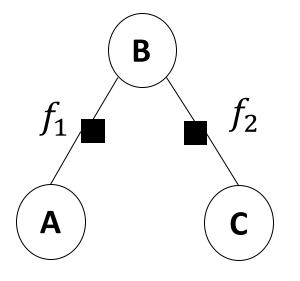
$$Z = \sum_{A,B,C} f(A,B,C) = \sum_{A,B,C} f_1(A,B) f_2(B,C)$$

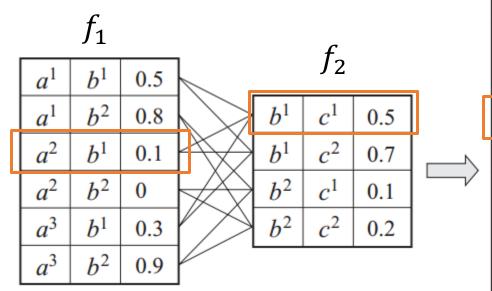
 ${\it Z}$ is also referred to as the *partition function*.

Example of product of factor functions

Two factors f_1 and f_2 are multiplied in a way that "matches up" the common variables







For example, $f(a^2, b^1, c^1) = f_1(a^2, b^1)f_2(b^1, c^1)$

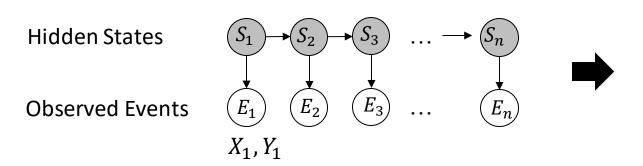
f			
a^1	b^1	c^1	$0.5 \cdot 0.5 = 0.25$
a^1	b^1	c^2	$0.5 \cdot 0.7 = 0.35$
a^1	b^2	c^1	$0.8 \cdot 0.1 = 0.08$
a^1	b^2	c^2	$0.8 \cdot 0.2 = 0.16$
a^2	b^1	c^1	$0.1 \cdot 0.5 = 0.05$
a^2	b^1	c^2	$0.1 \cdot 0.7 = 0.07$
a^2	b^2	c^1	0.0.1 = 0
a^2	b^2	c^2	0.0.2 = 0
a^3	b^1	c^1	$0.3 \cdot 0.5 = 0.15$
a^3	b^1	c^2	$0.3 \cdot 0.7 = 0.21$
a^3	b^2	c^1	$0.9 \cdot 0.1 = 0.09$
a^3	b^2	c^2	$0.9 \cdot 0.2 = 0.18$

Conversion of a Hidden Markov Model to a Factor Graph— Two dimension

Assume that at each time point, two observations are made corresponding to random variables X and Y.

Example: Let |S| = 10, |X| = 10, |Y| = 10

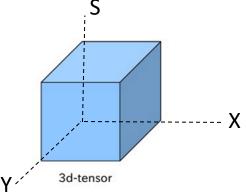
Hidden Markov Model



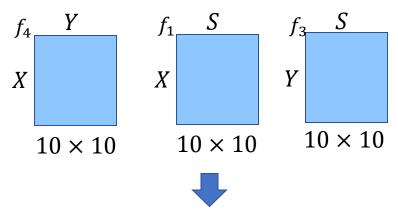
Factor Graph of the HMM 10×10 Hidden States

Observed Events f_3 f_2 f_2 f_3 f_4 f_4

Fewer number of parameters are required are required to specify the given FG.



size of tensor is exponential $10 \times 10 \times 10 = 1000$



size of five matrices $10 + 10 \times 10 + 10 \times 10 + 10 \times 10 + 10 \times 10 = 410$

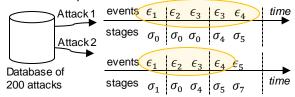
Modeling the credential stealing attack using Factor Graphs - Data

State space of variables

Attack stage: $X = \{\sigma_0, \sigma_1, ..., \sigma_7\}$ (Observed) Events: $E = \{\epsilon_1, ..., \epsilon_5\}$

OFFLINE ANNOTATION ON PAST ATTACKS

a) Annotated events and attack stages in a pair of attacks



b) Event-stage annotation table for the attack pair (Attack 1 and Attack 2)

Event	Attack stage	
$\{\epsilon_1\}$	$\{\sigma_0 \sigma_1\}$	
$\{\epsilon_2\}$	$\{\sigma_0\}$	
$\{\epsilon_3\}$	$\{\sigma_4\}$	
$\{\epsilon_4\}$	$\{\sigma_5\}$	
$\{\epsilon_5\}$	$\{\sigma_7\}$	

 $egin{array}{lll} \epsilon_1 & ext{vulnerability scan} & \sigma_0 & ext{benign} \\ \epsilon_2 & ext{login} & \sigma_1 & ext{discovery} \\ \epsilon_3 & ext{sensitive_uri} & \sigma_4 & ext{privilege escalation} \\ \epsilon_4 & ext{new library} & \sigma_5 & ext{persistence} \\ \end{array}$

Attack Information

- Multi-stage credential stealing attack
- Attack stage $\sigma \in X$ is not observed; however an attack happens in a chain of exploits, thus we have a sequence of events
- Each security event is a known variable ϵ , each takes value from a discrete set of events E
- **Problem statement.** Given a set of security events, infer whether an attack is in progress?
 - Goal is to detect and pre-empt the attack

Model assumptions

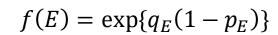
- There are multivariate relationships among the events
- There is no restriction on order of the relationships (can be non-causal or correlation based)
- Markov Model and Bayesian Networks cannot be used in this scenarios
- Factor graphs can be used for modeling highly complex attacks, where the causal relations among the events are not immediately clear.

Modeling the credential stealing attack using Factor Graphs

OFFLINE LEARNING OF **FACTOR FUNCTIONS**

Example patterns, stages, probabilities, and significance learned from the attack pair

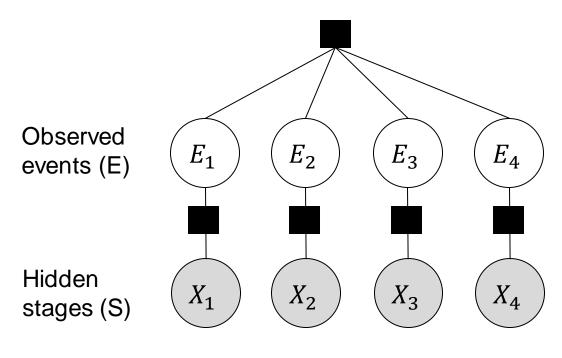
Pattern	Attack stages	Probability in past attacks	Significance (p-value)
$[\epsilon_1, \epsilon_3, \epsilon_4]$	$[\sigma_1,\sigma_4,\sigma_5]$	q_a	p_a
$[\epsilon_1]$	$[\sigma_0 \sigma_1]$	q_b	p_b



A factor function defined on the learned pattern, stages, and its significance

DETECTION OF UNSEEN ATTACKS

Factor Graph



Time step

$$t = 1 \quad t = 2 \quad t = 3$$

Advantages and Disadvantages of Factor Graph

Advantage

• Factor graph subsumes HMMs, Markov Random Fields, Bayesian Networks etc.

Disadvantage

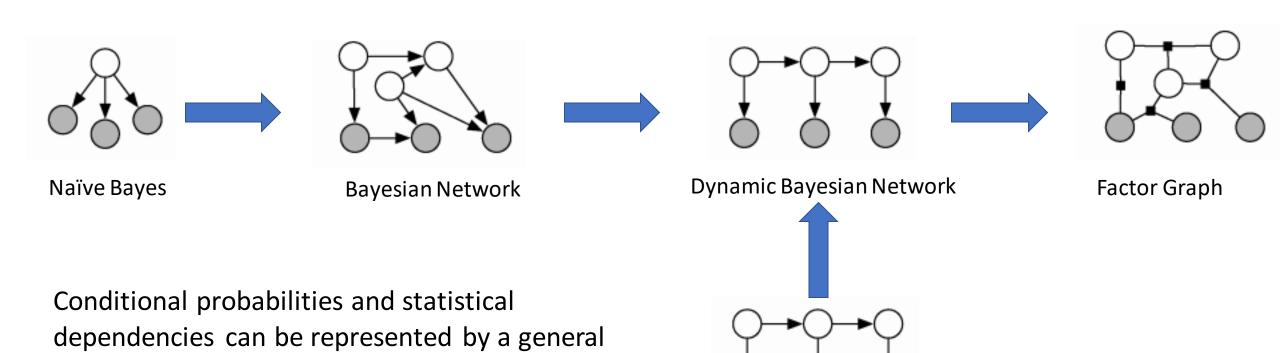
Limitations of probabilistic graphs in general

Comment

• If the problem is well represented by specific models such as Bayesian Networks, HMMs, Naïve Bayes or other graphical models then there is no need to generalize your problem as a factor graphs

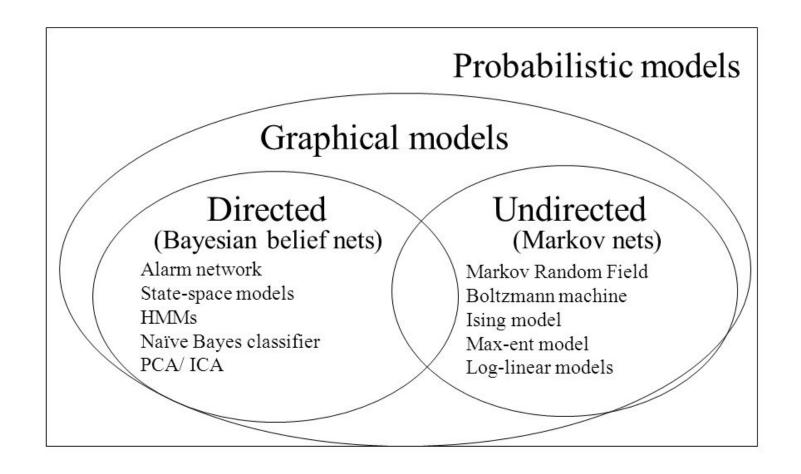
Taxonomy of graphical models

type of graph: Factor Graph



Hidden Markov Model

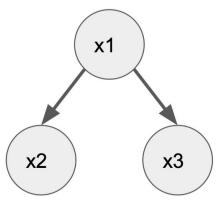
Taxonomy of Graphical Models



Machine Learning, A Probabilistic Perspective, Kevin Murphy, MIT Press

Bayesian Networks vs. Hidden Markov Models vs. Factor Graphs

Bayesian Network

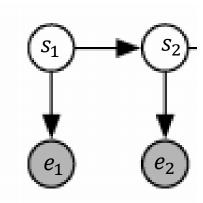


$$p(x_1)p(x_2|x_1)p(x_3|x_1)$$

Product of conditional probabilities

Causal relationships

Hidden Markov Model

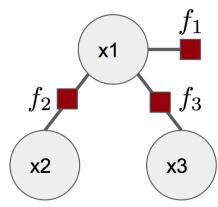


 $p(s_1)p(e_1|s_1)p(s_2|s_1)p(e_2|s_2)$

Product of Temporal dependencies among variable

Temporal and statistical dependencies

Factor Graph



$$\frac{1}{Z}f_1(x_1)f_2(x_2,x_1)f_3(x_1,x_3)$$

Product of dependencies using univariate, bivariate, or multivariate functions

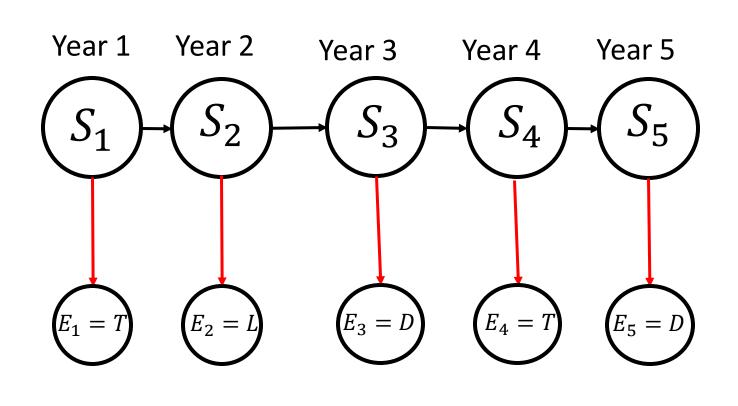
Both types of relations (including prior on a variable)

Practice with Factor Graph

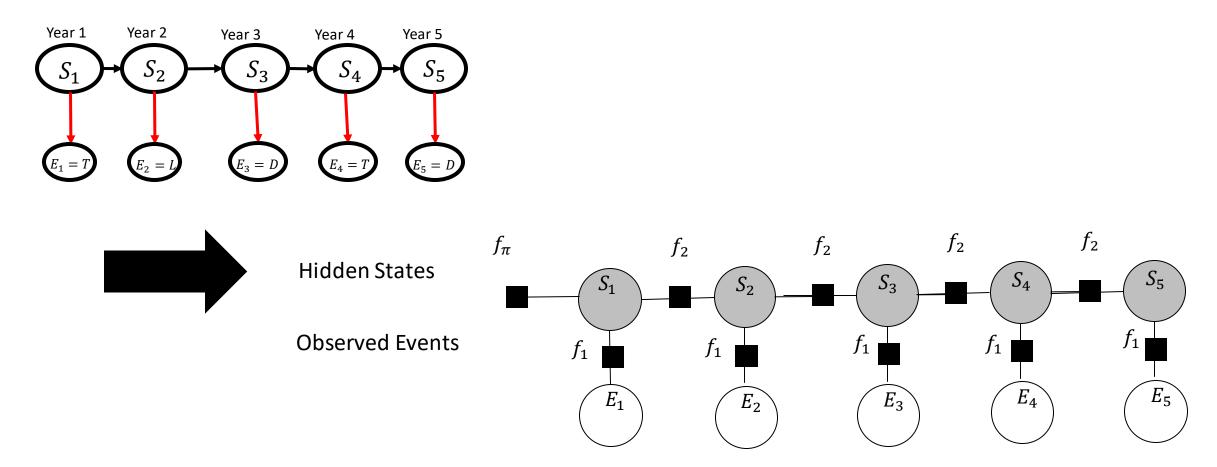
HMM Example - Paleontological Temperature Model

- State space of hidden states: $S = \{H, C\}$
- State space of observations: $E = \{T, D, L\}$
- Transition probability matrix: A
- Observation Matrix: B
- Initial distribution for the hidden states: π

Given by an oracle

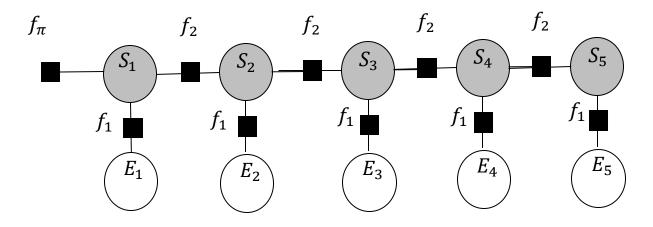


First Step – Drawing Factor Graph from HMM

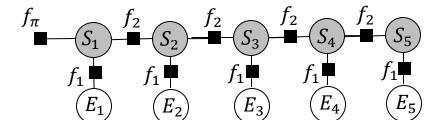


Why are the factor functions...

- Between every pair of states the same?
- Between every pair of state and observation the same?



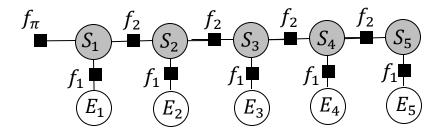
- f_{π} needs to capture the prior probabilities for the states
- f_1 needs to capture the affinity between observations and states
- f_2 needs to capture the affinity between consecutive states



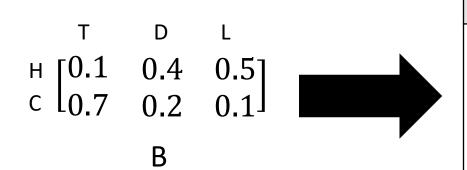
• f_{π} needs to capture the prior probabilities for the states



S_1	$f_{\pi}(S_1)$
Н	0.5
C	0.5

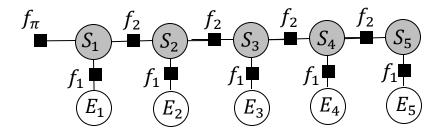


• f_1 needs to capture the affinity between observations and states. (i.e., $P(E_i|S_i)$)



S_i	E_i	$f_1(S_i, E_i)$
Н	T	0.1
	D	0.4
	L	0.5
С	T	0.7
	D	0.2
	L	0.1

Note that the values in this table don't sum to 1 => f_1 is not a joint probability but a conditional probability!



• f_2 needs to capture the affinity between consecutive states. (i.e., $P(S_{i+1}|S_i)$)

 S_{i+1}

H

C

H

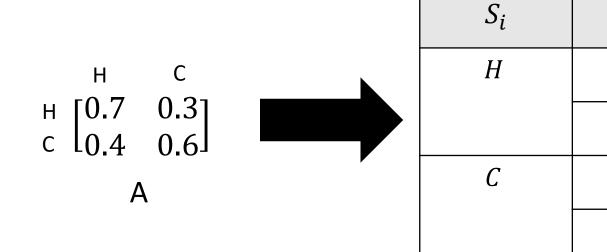
 $f_2(S_i, S_{i+1})$

0.7

0.3

0.4

0.6



Note that the values in this table don't sum to 1 => f_2 not a joint probability but a conditional probability!

After That — Calculating the Joint

