

# 1 GroBdd

## 1.1 Initial definition of GroBdd

A GroBdd is very similar to an actual ROBDD, the two main differences being that (1) it represents a vector of Boolean functions with a finite number of variables possibly of different arity and (2) on every edge there is a transformation (the "output inverter" is an example of such transformations").

A Reduced Ordered Binary Decision Diagram is a directed acyclic graph  $(V \cup T, \Psi \cup E)$  representing a vector of Boolean functions  $F = (f_1, \dots, f_k)$ . Nodes are partitioned into two sets: the set of internal nodes  $V$  and the set of terminal nodes  $T$ . Every internal node  $v \in V$  has two outgoing edges respectively denoted  $if0$  and  $if1$ . Every internal node  $v \in V$  has a field *index* which represents a unique identifier associated to each node. Arcs are partitioned into two sets: the set of root arcs  $\Psi$  and the set of internal arcs  $E$ . There is exactly  $k$  root arcs, a root arc is denoted  $\Psi_i$  with  $0 \leq i < k$ , informally,  $\Psi_i$  is the root of the GroBdd representing  $f_i$ . Every arc has a transformation descriptor field  $\gamma$  and a destination node denoted *node*.

We denote  $\rho(\gamma) : \mathbb{F}_n \rightarrow \mathbb{F}_m$  the semantic interpretation of the transformation descriptor  $\gamma$ . We define  $\phi(node)$  the semantic of the node *node* and  $\psi(arc)$  the semantic of the arc *arc* as follow:

- $\forall i, f_i = \psi(\Psi_i)$
- $\forall arc \in \Psi \cup E, \psi(arc) = \rho(arc.\gamma)(\phi(arc.node))$
- $\forall node \in V, \phi(node) = \psi(node.if0) \star \psi(node.if1)$

We assume the function  $\phi$  defined on all terminals  $T$  (we always assume, all terminal to have a different interpretation through  $\phi$ ).

## 1.2 Transformation Descriptor Set (TDS)

We denote  $\mathbb{Y}$  the set of all transformation descriptor. We assume defined  $\rho$  the semantical interpretation of transformation descriptors,  $\forall \gamma, \exists n, m \in \mathbb{N}, \rho(\gamma) \in \mathbb{F}_n \rightarrow \mathbb{F}_m$  (with  $n \leq m$ ). In this section, we make the list of properties that the TDS must ensure to be correct.

### 1.2.1 Canonical

$$\forall \gamma, \gamma' \in \mathbb{Y}, (\gamma = \gamma') \Leftrightarrow (\rho(\gamma) = \rho(\gamma'))$$

We denote  $\mathbb{Y}_{n,m} = \{\gamma \in \mathbb{Y} \mid \rho(\gamma) \in \mathbb{F}_n \rightarrow \mathbb{F}_m\}$ , and  $\mathbb{Y}_{n,*} = \bigcup_{m \leq n} \mathbb{Y}_{n,m}$  and  $\mathbb{Y}_{*,m} = \bigcup_{n \geq m} \mathbb{Y}_{n,m}$ .

### 1.2.2 Separable

$$\begin{aligned} \forall \gamma \in \mathbb{Y}_{n,m}, \exists! \Delta_\gamma \in \mathbb{B}^m \rightarrow \mathbb{B}^n, \nabla_\gamma \in \mathbb{B}^m \rightarrow \mathbb{B} \rightarrow \mathbb{B}, \\ \forall f \in \mathbb{F}_n, \forall x \in \mathbb{B}^m, \rho(\gamma)(f)(x) = \nabla(x, f(\Delta_\gamma)) \end{aligned}$$

This constraint allows any transformation to be represented as circuit which can be wrapped around the function. This constraint enforces transformations to be local. The function  $\Delta$  is called the pre-process, and the function  $\nabla$  is called the post-process.

### 1.2.3 Composable (definition of $\mathbb{C}$ )

$$\forall \gamma \in \mathbb{Y}_{n,m}, \gamma' \in \mathbb{Y}_{m,l}, \exists \gamma'' \in \mathbb{Y}_{n,l}, \rho(\gamma') \circ \rho(\gamma) = \rho(\gamma'')$$

This constraint enforces  $\mathbb{Y}_{n,n}$  to be stable by composition. Furthermore, it exists an algorithm  $\mathbb{C} : \mathbb{Y}_{n,m} \rightarrow \mathbb{Y}_{m,l} \rightarrow \mathbb{Y}_{n,l}$ , such that:

$$\forall \gamma \in \mathbb{Y}_{n,m}, \gamma' \in \mathbb{Y}_{m,l}, \rho(\gamma') \circ \rho(\gamma) = \rho(\mathbb{C}(\gamma, \gamma'))$$

For convenience, we denote  $\gamma' \circ \gamma = \mathbb{C}(\gamma, \gamma')$ .

### 1.2.4 Decomposable (definition of $\mathbb{A}$ and $\mathbb{S}$ )

For all  $n \in \mathbb{N}$ , we define  $A_n = \mathbb{Y}_{n,n}$  the set of asymmetric transformations. For all  $n, m \in \mathbb{N}$ , it exists  $S_{n,m} \subset \mathbb{Y}_{n,m}$  a set of transformations such that  $\forall \gamma \in \mathbb{Y}_{n,m}, \exists a \in A_m, \exists! s \in S_{n,m}, \gamma = a \circ s$ . The set  $S_{n,m}$  is called the set of symmetric transformation.

#### definition : S-free

A Boolean function  $f \in \mathbb{F}_m$  is said S-free, iff

$$\forall s \in S_{n,m}, \forall g \in \mathbb{F}_n, f = \rho(s)(g) \Rightarrow \rho(s) = Id$$

#### constraint : S-uniqueness

$$\forall f \in \mathbb{F}_n, f' \in \mathbb{F}_{n'}, s \in S_{n,m}, s' \in S_{n',m}, \rho(s)(f) = \rho(s')(f') \Rightarrow (s = s') \wedge (f = f')$$

#### definition : A-equivalent

Two Boolean functions  $f, g \in \mathbb{F}_n$  are said A-equivalent, iff  $\exists a \in A_n, f = \rho(a)(g)$ . This relation is an equivalence relation (i.e. reflexive, symmetric, transitive) denote  $\sim_A$ .

#### definition : A-invariant free

A Boolean function  $f \in \mathbb{F}_n$  is said A-invariant free, iff  $\forall a, a' \in A_n, \rho(a)(f) \neq \rho(a')(f)$ .

#### constraint : S-free implies A-invariant free

For all function  $f$ , if  $f$  is S-free, then  $f$  is A-invariant free.

#### definition : A-reduced set of function

Let  $X = \{x_1, x_2, \dots, x_n\}$  be a set of Boolean functions. The set  $X$  is said A-reduced iff  $\forall x_i, x_j \in X, (x_i \sim_A x_j) \Rightarrow (x_i = x_j)$ .

#### definition : $\mathbb{I}_n$

For all  $n \in \mathbb{N}$ , we denote  $\mathbb{I}_n$  the set of identifiers corresponding to node representing functions of arity  $n$ .

**definition :  $\mathbb{Y}$ -node**

A  $\mathbb{Y}$ -node $_{l,m,n}$  is a quadruple  $(\gamma_0, I_0, \gamma_1, I_1) \in \mathbb{Y}_{l,n} \times \mathbb{I}_l \times \mathbb{Y}_{m,n} \times \mathbb{I}_m$ . Let  $v$  be a  $\mathbb{Y}$ -node, we denote  $v.\gamma_0$  (respectively  $v.I_0$ ,  $v.\gamma_1$  and  $v.I_1$ ) the first (respectively second, third and fourth) component of  $v$ .

- For all  $\mathbb{Y}$ -node  $v$ , we always assume that functions  $\phi(v.I_0)$  and  $\phi(v.I_1)$  are  $\mathbf{S}$ -free.
- We always assume the set  $X = \{\phi(v.I_0) \mid v \in \mathbb{Y}\text{-node}\} \cup \{\phi(v.I_1) \mid v \in \mathbb{Y}\text{-node}\}$  to be  $\mathbf{A}$ -reduced

We extend the definition of  $\phi$ , with : for all  $\mathbb{Y}$ -node  $v$ ,  $\phi(v) = \rho(v.\gamma_0)(\phi(v.I_0)) \star \rho(v.\gamma_1)(\phi(v.I_1))$ .

**constraint : terminal nodes are  $\mathbf{S}$ -free and  $\mathbf{A}$ -reduced (definition of  $\mathbf{E}_0$ )** For all terminal node  $t \in T$ ,  $t$  is  $\mathbf{S}$ -free. Furthermore, the set  $\{\phi(t) \mid t \in T\}$  is  $\mathbf{A}$ -reduced. Moreover, we define the function  $\mathbf{E}_0$  such  $\forall b \in \mathbb{F}_0, \exists \gamma \in \mathbb{Y}_{0,0}, \exists t \in T, \mathbf{E}_0(b) = \{\gamma = \gamma, node = I_t\}$  and  $\psi(\mathbf{E}_0(b)) = b$ .

### 1.2.5 Buildable (definition of $\mathbf{B}$ )

Let  $X$  be a function, we denote  $I_X$  the identifier of an hypothetical node whose semantic interpretation is  $X$ .

We define  $\mathbf{B}$  an algorithm over  $\mathbb{Y}$  which respect the signature:

$$\begin{array}{lcl} 1 & \mathbf{B} : & \mathbb{Y}_{n_0,m} \times \mathbb{I}_{n_0} \longrightarrow \mathbb{Y}_{n_1,m} \times \mathbb{I}_{n_1} \longrightarrow \\ 2 & & | \text{ ConsNode } \mathbb{Y}_{n',m} \times (\mathbb{Y}_{n_x,n'} \times \mathbb{I}_{n_x}) \times (\mathbb{Y}_{n_y,n'} \times \mathbb{I}_{n_y}) \\ 3 & & | \text{ Merge } \mathbb{Y}_{n_z,m} \times \mathbb{I}_{n_z} \end{array}$$

(with  $x, y, z \in \{0, 1\}$ )

Furthermore, for all  $(\gamma_g, I_g, \gamma_h, I_h) \in \mathbb{Y}_{n_0,m} \times \mathbb{I}_{n_0} \times \mathbb{Y}_{n_1,m} \times \mathbb{I}_{n_1}$ ,

$$\mathbf{B}(\gamma_g, I_g, \gamma_h, I_h) = \mathbf{ConsNode}(\gamma, (\gamma', I_X), (\gamma'', I_Y)) \Rightarrow f = \rho(\gamma)(\rho(\gamma')(X) \star \rho(\gamma'')(Y))$$

$$\mathbf{B}(\gamma_g, I_g, \gamma_h, I_h) = \mathbf{Merge}(\gamma''', I_Z) \Rightarrow f = \rho(\gamma''')(Z)$$

(with  $X, Y, Z \in \{g, h\}$  and  $f = \rho(\gamma_g)(g) \star \rho(\gamma_h)(h)$ )

**definition : a node is  $\mathbf{B}$ -stable**

Let  $G$  be a GroBdd, we denote  $v$  an internal node of  $G$ . We denote  $\gamma_0 = v.if0.\gamma$ ,  $I_0 = v.if0.node$ ,  $\gamma_1 = v.if1.\gamma$  and  $I_1 = v.if1.node$ . The node  $v$  is said  $\mathbf{B}$ -stable iff  $\mathbf{B}(\gamma_0, I_0, \gamma_1, I_1) = \mathbf{ConsNode}(Id, (\gamma_0, I_0), (\gamma_1, I_1))$ .

**constraint :  $\mathbf{B}$  is  $\mathbf{B}$ -stable**

$$\begin{aligned} \forall \gamma_f, I_f, \gamma_g, I_g, \mathbf{B}(\gamma_f, I_f, \gamma_g, I_g) &= \mathbf{ConsNode}(\gamma, (\gamma_0, I_0), (\gamma_1, I_1)) \\ &\Rightarrow \mathbf{B}(\gamma_0, I_0, \gamma_1, I_1) = \mathbf{ConsNode}(Id, (\gamma_0, I_0), (\gamma_1, I_1)) \end{aligned}$$

Informally, when  $\mathbf{B}$  returns a node, this node is  $\mathbf{B}$ -stable.

**constraint :  $\mathbb{Y}$ -node are  $\mathbf{B}$ -stable**

1. We assume all  $\mathbb{Y}$ -node  $v$  to be  $\mathbf{B}$ -stable

$$\mathbf{B}(v.\gamma_0, v.I_0, v.\gamma_1, v.I_1) = \mathbf{ConsNode}(Id, (v.\gamma_0, v.I_0), (v.\gamma_1, v.I_1))$$

**constraint : B is S-free preserving**

The algorithm B is said S-free preserving iff for all  $\mathbb{Y}$ -node  $v$ ,  $\phi(v)$  is S-free.

**constraint : B is A-reduction preserving**

The algorithm B is said A-reduction preserving iff

$$\forall v, w \in \mathbb{Y}\text{-node}, \phi(v) \sim_A \phi(w) \Rightarrow v = w$$

**1.3 Reduction Rules**

We define a GroBdd model as the triple  $(\mathbb{Y}, \mathbb{C}, \mathbb{B})$ . A valid model must satisfy all the previously mentioned constraints.

In addition to the previous constraints, we define two reduction rules:

1. The syntactical reduction : all sub-graphs are different up to graph-isomorphism (i.e. all identical sub-graphs are merged)
2. The local semantic reduction : all internal node  $v \in V$  is B-stable.
3. All node has at least one incoming arc. A GroBdd is said reduced if it satisfies the reduction rules.

In this section we prove:

1. For all vector of Boolean function  $F$  it exists a reduced GroBdd  $G$  representing it.
2. A reduced GroBdd  $G$  is semi-canonical, defined as :
  - (a) For all node  $v \in V$ ,  $\phi(v)$  is S-free.
  - (b) The set  $X = \{\phi(v_1), \dots, \phi(v_N)\}$  representing the set of the semantic interpretation of the set of internal nodes  $V$  is A-reduced.
  - (c)  $\forall (\gamma, I, \gamma', I') \in (\mathbb{Y}_{n,m} \times \mathbb{I}_n)^2, \psi(\{\gamma = \gamma, node = I\}) = \psi(\{\gamma = \gamma', node = I'\}) \Rightarrow (\gamma, I) = (\gamma', I')$  (with  $I$  and  $I'$  being indexes of nodes in  $G$ ).
3. Between two reduced GroBdd  $G$  and  $G'$  representing the same vector of Boolean functions  $F$ , it exists a one-to-one mapping  $\sigma : V \longrightarrow V'$  such that  $\forall v, v' \in V \times V', \sigma(v) = v' \Rightarrow (\exists a \in A_*, \phi(v) = \rho(a)(\phi(v')))$ .

**1.3.1 Additional procedures****The Cons procedure**

We define the **Cons** procedure as follow. Let  $G$  be a GroBdd and  $F$  be its vector of root arcs of size  $k$ .

Let  $i$  and  $j$  be indexes of this vector. We denote  $\gamma_i = \Psi_i.\gamma$ ,  $\gamma_j = \Psi_j.\gamma$  and  $I_i = \Psi_i.node$ ,  $I_j = \Psi_j.node$ .

- If  $\mathbb{B}(\gamma_g, I_g, \gamma_h, I_h) = \text{ConsNode}(\gamma, (\gamma', I_X), (\gamma'', I_Y))$ . We define the node  $N = \{if0 = \{\gamma = \gamma', node = I_X\}, if1 = \{\gamma = \gamma'', nodes = I_Y\}\}$ .
  - If the node  $N$  already exists in  $G$ , we retrieve its identifier  $I$ , we define  $G'$  as a copy of  $G$  with a new root arc  $\Psi_k = \{\gamma = \gamma, node = I\}$

- Otherwise, we define  $G'$  as a copy of  $G$  with add  $N$  to the list of nodes of  $G'$  and create it a new identifier  $I$ , we add a new root arc  $\Psi_k = \{\gamma = \gamma, node = I\}$ .
- Otherwise,  $B(\gamma_g, I_g, \gamma_h, I_h) = \text{Merge}(\gamma, I_Z)$ . We define  $G'$  as a copy of  $G$  with a new root arc  $\Psi_k = \{\gamma = \gamma''', node = I_Z\}$ .

#### The Remove procedure

We define the **Remove** procedure as follow. Let  $G$  be a GroBdd and  $F$  be its vector of root arc of size  $k$ .

Let  $i$  be an index of this vector We define  $G'$  as a copy of  $G$  with its vector of root arc  $F' = (\Psi_1, \dots, \Psi_{i-1}, \Psi_{i+1}, \dots, \Psi_n)$ . In an iterative process, we remove nodes which have no incoming arc, until all nodes have at least one incoming arc (in order to satisfy the third reduction rule). As  $G'$  is a subset of  $G$ , thus,  $G'$  satisfies the first and second reduction rule.

#### The Reduction procedure

Let  $G$  be a GroBdd and  $F$  be its vector of root arcs  $F$ . Using an iterative process, we remove nodes which have no incoming arc, until all nodes have at least one incoming arc (satisfying the third reduction rules). The **Reduction** procedure consist in going through the GroBdd  $G$  (starting with nodes with the smallest depth), applying the **Cons** procedure on each node creating a new GroBdd  $G'$ . The GroBdd  $G'$  is by construction equivalent to  $G$ , however, the GroBdd  $G'$  satisfies all three reduction rules.

#### The Merge procedure

We define the **Merge** procedure as follow. Let  $G$  and  $G'$  be two GroBdds (based on the same GroBdd model). We define  $G''$  a GroBdd which is the union of both GroBdd. We define  $F'' = (\Psi_1, \dots, \Psi_n, \Psi'_1, \dots, \Psi'_n)$ . Due to possible conflicts on identifiers, we re-generate identifiers of the nodes in  $G''$ . Finally, we apply the **Reduction** procedure on  $G''$ .

### 1.3.2 Existence

We inductively define the procedure **E** with:

- $\forall b \in \mathbb{F}_0, E(b) = E_0(b)$
- Let  $f$  be a Boolean function of arity  $n$  (with  $n \geq 1$ ). Let  $G$  be a GroBdd representing functions  $f_0$  (the negative restriction of  $f$  according to its first variable) and  $f_1$  (the positive restriction of  $f$  according to its first variable.) by using the procedure **E** on  $f_0$  and  $f_1$ . Let  $G'$  be the output of the **Cons** procedure on  $G$ , in order to create  $f = f_0 \star f_1$  (expansion theorem).  
 $E(f) = G'$  The GroBdd  $G'$  satisfies the reduction rules:
  - If no node is created, the proof is straightforward.
  - If a node is created, this node is syntactically unique by definition of **Cons** and is B-stable (as B is B-stable)

By construction, the procedure **E** (generalized to accept a vector of function as input) returns a GroBdd satisfying the reduction rules.

### 1.3.3 Semi-Canonical

Let  $G$  be a reduced GroBdd.

**S-free and A-reduced** For all node  $v \in V$ , we denote  $h(v) = \max(h(v.if0.node), h(v.if1.node))$  with  $\forall t \in T, h(t) = 0$ . For all  $n \in \mathbb{N}$ , we define  $V_n = \{v \in V \mid h(v) \leq n\}$ . For all  $n \in \mathbb{N}$ , we define the recurrence hypothesis  $H(n)$  :

- For all  $v \in V_n$ ,  $\phi(v)$  is S-free.
- The set of Boolean function  $X = \{\phi(v) \mid v \in V_n\}$  is A-reduced.

**Initialization** We prove  $H(0)$  using the constraints that (1) terminals are S-free and (2) the set of terminal nodes is A-reduced.

**Induction** Let  $n \in \mathbb{N}$ , we assume  $\forall k \leq n, H(k)$ . Let  $v$  be a node of depth  $n+1$ , thus the depth of  $v.if0.node$  and  $v.if1.node$  is lower than  $n$  (we can apply the recurrence hypothesis). Therefore, the quadruple  $\bar{v} = (v.if0.\gamma, v.if0.node, v.if1.\gamma, v.if1.node)$  is a  $\mathbb{Y}$ -node. Thus, using the constraints that B is S-free preserving, we prove that  $\phi(v) = \phi(\bar{v})$  is S-free. Let  $v'$  be a node of depth  $k \leq n+1$ , we can prove that the quadruple  $\bar{v}' = (v'.if0.\gamma, v'.if0.node, v'.if1.\gamma, v'.if1.node)$  is a  $\mathbb{Y}$ -node. Therefore, we can use the constraint that B is A-reduction preserving to prove that  $\phi(\bar{v}) \sim_A \phi(\bar{v}') \Rightarrow \phi(\bar{v}) = \phi(\bar{v}')$ . However,  $\phi(v) = \phi(\bar{v})$  and  $\phi(v') = \phi(\bar{v}')$ . Thus,  $\forall v, v' \in V_{n+1}, \phi(v) \sim_A \phi(v') \Rightarrow \phi(v) = \phi(v')$ . Thus, the set of Boolean function  $X = \{\phi(v) \mid v \in V_{n+1}\}$  is A-reduced. Therefore  $(\text{land}_{k \leq n} H(k) \Rightarrow H(n+1))$ .

Using the strong recurrence theorem, we prove that  $\forall n \in \mathbb{N}, H(n)$ . Therefore proving properties (2.a) "all nodes are S-free" and (2.b) "the set  $X = \{\phi(v_1), \dots, \phi(v_N)\}$  is A-reduced".

**Semantic Reduction** We prove the property " $\forall (\gamma, I, \gamma', I') \in (\mathbb{Y}_{n,m} \times \mathbb{I}_n)^2, \psi(\{\gamma = \gamma, node = I\}) = \psi(\{\gamma = \gamma', node = I'\}) \Rightarrow (\gamma, I) = (\gamma', I')$  (with  $I$  and  $I'$  being indexes of nodes in  $G$ )" by induction on  $n \in \mathbb{N}$  the arity of  $f = \psi(\{\gamma = \gamma, node = I\})$ .

**Initialization** The induction property holds for  $n = 0$ :

Let  $f \in \mathbb{F}_0$ , we assume it exists a quadruple  $(\gamma, I, \gamma', I') \in (\mathbb{Y}_{n,m} \times \mathbb{I}_n)^2$  such that  $f = \psi(\{\gamma = \gamma, node = I\}) = \psi(\{\gamma = \gamma', node = I'\})$ . We decompose  $\gamma$  and  $\gamma'$  to their symmetric and asymmetric components:  $\gamma = s \circ a$  and  $\gamma' = s' \circ a'$ . Using the S-uniqueness constraint, on  $f = \rho(s)(\rho(a)(\phi(I))) = \rho(s')(\rho(a')(\phi(I')))$ , we have  $s = s'$  and  $\rho(a)(\phi(I)) = \rho(a')(\phi(I'))$ . Therefore,  $\phi(I) \sim_A \phi(I')$ , however, we proved that the set of the semantic interpretations of the nodes is A-reduced, thus  $\phi(I) = \phi(I')$ . However, the only node representing function of arity 0 are terminal nodes, therefore  $I = I'$ .

**Induction** Let  $k \in \mathbb{N}$ , we assume the induction property holds for all  $n \leq k$ , let prove it holds for  $n = k+1$ . Let  $f$  be a Boolean function, we assume it exists a quadruple  $(\gamma, I, \gamma', I') \in (\mathbb{Y}_{n,m} \times \mathbb{I}_n)^2$  such that  $f = \psi(\{\gamma = \gamma, node = I\}) = \psi(\{\gamma = \gamma', node = I'\})$ . We decompose  $\gamma$  and  $\gamma'$  to their symmetric and asymmetric components:  $\gamma = s \circ a$  and  $\gamma' = s' \circ a'$ . Using the

S-uniqueness constraint, on  $f = \rho(s)(\rho(a)(\phi(I))) = \rho(s')(\rho(a')(\phi(I')))$ , we have  $s = s'$  and  $\rho(a)(\phi(I)) = \rho(a')(\phi(I'))$ . Therefore,  $\phi(I) \sim_A \phi(I')$ , however, we proved that the set of the semantic interpretations of the nodes is A-reduced, thus  $\phi(I) = \phi(I')$ . Using the induction hypothesis (as  $\phi(I)$  as an arity strictly smaller than  $k + 1$ , thus smaller than  $k$ ), we deduce that  $I = I'$ .

Therefore, applying the strong induction theorem, we prove the property (2.c).

#### 1.3.4 Canonical modulo graph-isomorphism and A-equivalence

In order to prove that "Between two reduced GroBdd  $G$  and  $G'$  representing the same vector of Boolean functions  $F$ , it exists a one-to-one mapping  $\sigma : V \longrightarrow V'$  such that  $\forall v, v' \in V \times V', \sigma(v) = v' \Rightarrow (\exists a \in A_*, \phi(v) = \rho(a)(\phi(v'))$ ", we start by (1) proving that within the **Merge** procedure, each node is replace by an A-equivalent one then (2) using the **Merge** procedure without re-generating the identifiers of the nodes of  $G$  and using the property (2.c), we prove that the nodes of  $G'$  collapse on the nodes of  $G$  during the **Reduction** procedure, providing a one-to-one mapping. Details of this proof are cumbersome and not of great interest