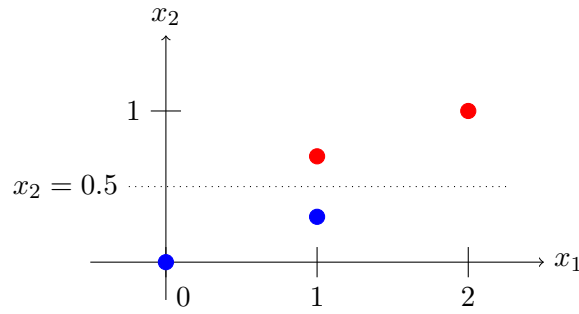


# Introduction to Machine Learning

## Problem Solutions: Support Vector Machines

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1. (a) The best way to do this is first draw a scatter plot of the four points as shown in the figure below where the red circles represent  $y = 1$  and the blue circles are for the class  $y = -1$ .



We see that we can separate the points with the classifier,

$$\hat{y} = \begin{cases} 1 & \text{if } x_2 > 0.5 \\ -1 & \text{if } x_2 < 0.5. \end{cases}$$

We then rewrite the classifier as,

$$\hat{y} = \begin{cases} 1 & \text{if } z > 0, \\ -1 & \text{if } z < 0, \end{cases} \quad z = b + w_1x_1 + w_2x_2 < 0,$$

where  $b = -0.5$ ,  $w_1 = 0$  and  $w_2 = 1$ .

- (b) Let

$$z_i = b + w_1x_{i1} + w_2x_{i2} = -0.5 + x_{i2}.$$

We evaluate  $z_i$  and  $y_iz_i$  for each sample:

$x_{i1}$	0	1	1	2
$x_{i2}$	0	0.3	0.7	1
$y_i$	-1	-1	1	1
$z_i$	-0.5	-0.2	0.2	0.5
$y_iz_i$	0.5	0.2	0.2	0.5

Since we require  $z_iz_i \geq \gamma$  for all  $i$ , the largest value of  $\gamma$  we can take is  $\gamma = 0.2$ .

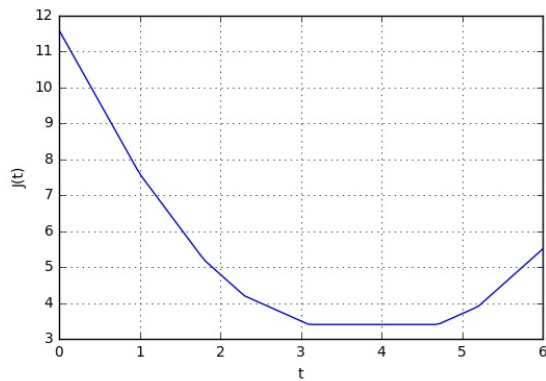


Figure 1: The objective function  $J(t)$

(c) The margin is

$$m = \frac{\gamma}{\|\mathbf{w}\|} = \frac{0.2}{\sqrt{0+1}} = 0.2.$$

(d) The points on the margin are the ones where  $z_i y_i = \gamma$ . These are  $(1, 0.3)$  and  $(1, 0.7)$ .

2. (a) You can compute and plot  $J(t)$  with the following code. The figure is shown in Fig. 1.

```
x = np.array([0,1.3,2.1,2.8,4.2,5.7])
y = np.array([-1,-1,-1,1,-1,1])
tvals = np.linspace(0,6,100)
J = []
for t in tvals:
    z = x-t
    Jt = np.sum(np.maximum(0,1-y*z))
    J.append(Jt)
J = np.array(J)

plt.plot(tvals, J)
plt.xlabel('t')
plt.ylabel('J(t)')
plt.grid()
plt.savefig('Jt.jpg')
```

(b) From Fig. 1, we see that  $t = 4$  is a minimizer. In fact,  $J(t)$  is flat around the minima, so other values of  $t$  close to  $t = 4$  would also minimize the function.

(c) We can compute the slack variables by the python code:

```
t = 4
z = x-t
eps = np.maximum(0, 1-y*z)
eps
```

```
>>> array([ 0. ,  0. ,  0. ,  2.2,  1.2,  0. ])
```

- (d) We see that  $\epsilon_i > 1$  for samples  $i = 3, 4$  so both of these samples will be misclassified (and violate the margin).

3. Consider an image recognition problem, where an image  $\mathbf{X}$  and filter  $\mathbf{W}$  are  $4 \times 4$  matrices:

$$\mathbf{X} = \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix}, \quad \mathbf{W} = \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}.$$

- (a) Going down the columns of  $\mathbf{X}$  and  $\mathbf{W}$ , the vectors are:

$$\begin{aligned} \mathbf{x} &= [0, 0, 0, 0, 0, 0, 0, 0, 0, 1, 1, 1, 0, 0, 0, 0] \\ \mathbf{w} &= [0, 0, 0, 0, 0, 1, 1, 0, 0, 1, 1, 0, 0, 0, 0, 0] \end{aligned}$$

- (b) The inner product will be

$$z = \mathbf{w}^T \mathbf{x} = \sum_{i=1}^{16} x_i w_i.$$

Since  $x_i$  and  $w_i = 0$  or  $1$ ,  $x_i w_i = 1$  only on the pixels where  $x_i = w_i = 1$ . Hence  $z = \mathbf{w}^T \mathbf{x}$  is the number of pixels where two images overlap. Thus, we have  $z = 2$ .

- (c) If  $\mathbf{X}$  is shifted to the right we have

$$\mathbf{X}_{\text{right}} = \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix}.$$

This has no overlap with  $\mathbf{W}$ , so  $z = \mathbf{w}^T \mathbf{x}_{\text{right}} = 0$ .

- (d) If  $\mathbf{X}$  is shifted to the left we have

$$\mathbf{X}_{\text{left}} = \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix}.$$

This overlaps with two pixels in  $\mathbf{W}$ . Hence,  $z = \mathbf{w}^T \mathbf{x}_{\text{left}} = 2$ .

- (e) The python commands are `x = Xmat.ravel()` and `Xmat = x.reshape([4,4])`.

4. (a) You can use the python code below. Note the use of `meshgrid` command. The matrix `xpmat` has rows equal to `xp[j]` and `xmat` has columns equal to `x[i]`, Therefore, the matrix `dist` has elements `dist[i,j] = (x[i]-xp[j])**2`, which are the squared distances need to compute  $z$ .

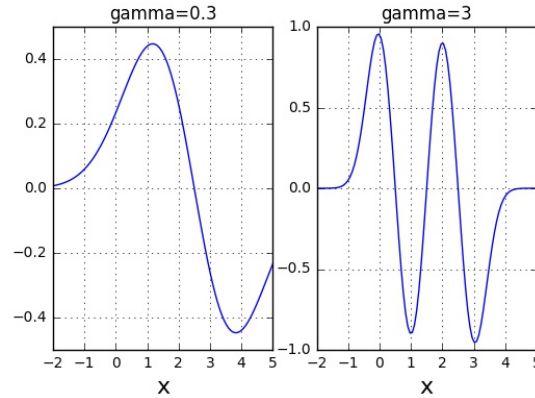


Figure 2: The function  $z$  in Problems 4(a) and (b)

```
x = np.array([0,1,2,3])
y = np.array([1,-1,1,-1])

def plot_zrbf(x,y,a,gam):
    xp = np.linspace(-2,5,100)
    xpmat,xmat = np.meshgrid(xp,x)
    dist = (xpmat-xmat)**2
    z = (y*a).dot(np.exp(-gam*dist))
    plt.plot(xp,z)
    plt.grid()
    plt.xlabel('x', fontsize=16)

plt.subplot(1,2,1)
a = np.array([0,0,1,1])
plot_zrbf(x,y,a,gam=0.3)
plt.title('gamma=0.3')

plt.subplot(1,2,2)
a = np.array([1,1,1,1])
plot_zrbf(x,y,a,gam=3)
plt.title('gamma=3')

plt.savefig('rbf.png')
```

The result function  $z$  is plotted in the left of Fig. 2.

- (b) The function  $z$  for  $\gamma = 3$  is plotted in the right of Fig. 2.
- (c) The classifier takes  $\hat{y}_i = \text{sign}(z_i)$ . The resulting values are shown in the table below. We see that the classifier in part (b) makes no errors. Since it uses a higher  $\gamma$  it is able to fit the data better.

$x_i$	0	1	2	3
$y_i$	1	-1	1	-1
$\hat{y}_i = \text{sign}(z_i)$ for (a)	1	1	1	-1
$\hat{y}_i = \text{sign}(z_i)$ for (b)	1	-1	1	-1