Mean Field Games: Numerical Methods and Applications in Machine Learning

Part 6: Deep Learning for MFG PDEs

Mathieu LAURIÈRE

https://mlauriere.github.io/teaching/MFG-PKU-6.pdf

Peking University
Summer School on Applied Mathematics
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RECAP

Outline

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Solving ODEs with Neural Networks

- Look for $\varphi : \mathbb{R} \ni x \mapsto \varphi(x) \in \mathbb{R}$ s.t.

$$F(x, \varphi(x), \varphi'(x), \dots) = 0, \qquad x \in [a, b]$$

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- Use SGD

Numerical Illustration

Application to the ODE:

$$F(x, \varphi(x), \varphi'(x)) = \varphi'(x) - (x - \varphi(x))$$

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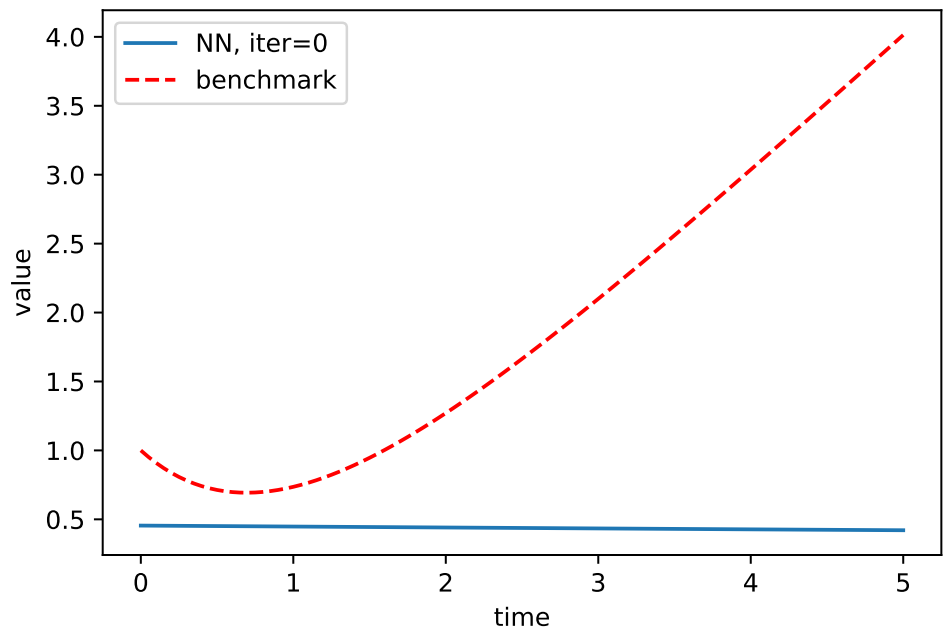

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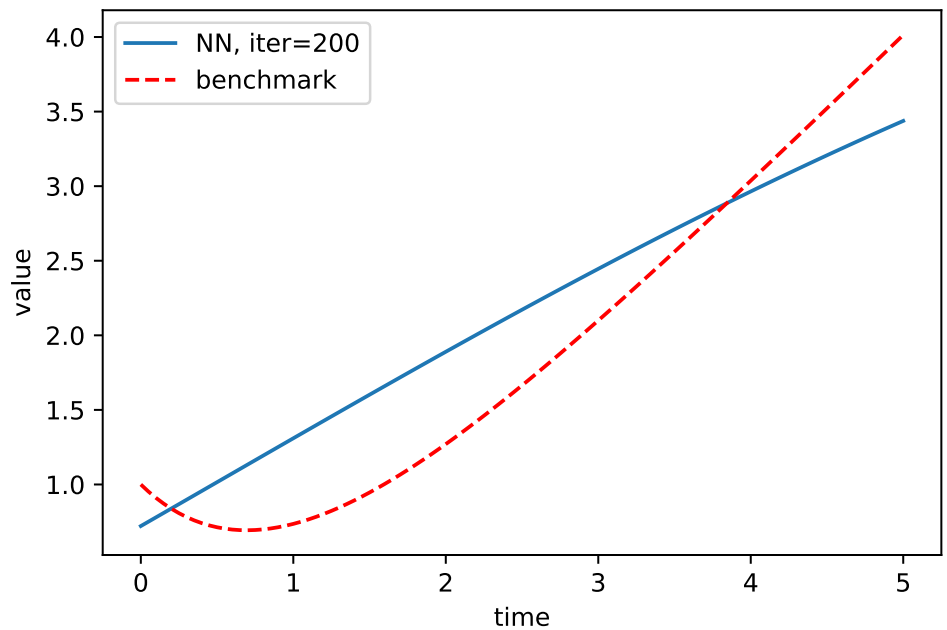

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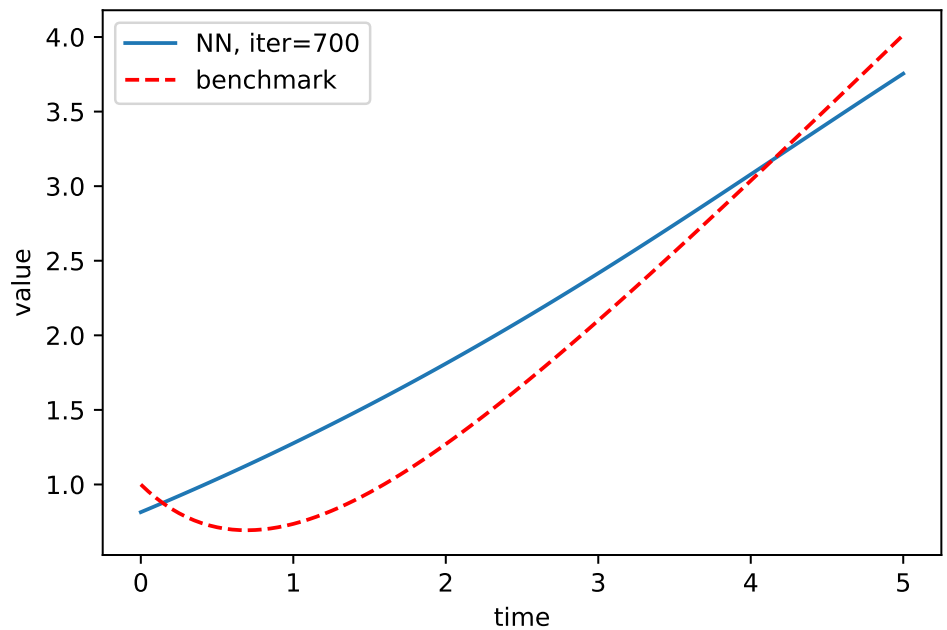

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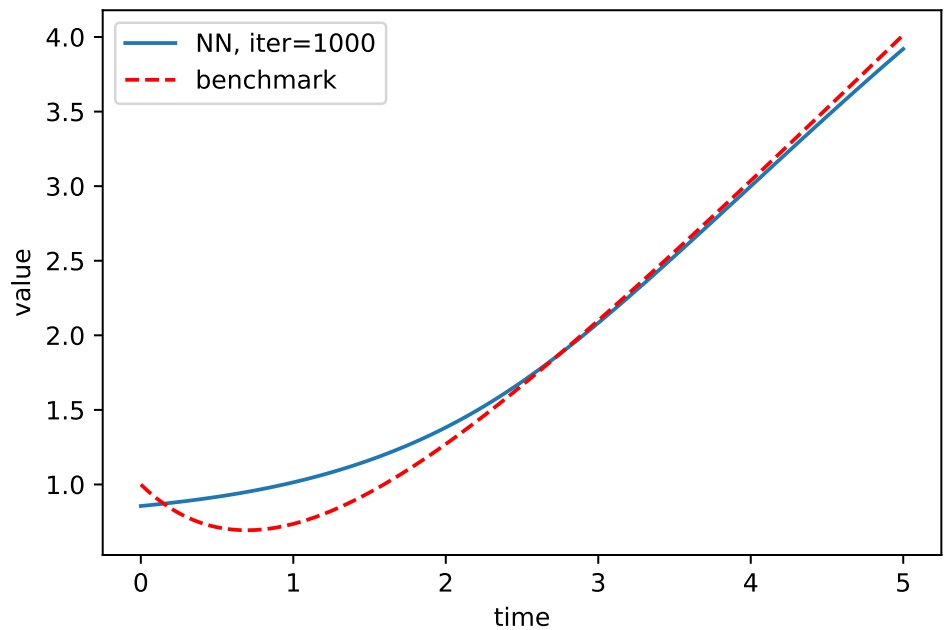

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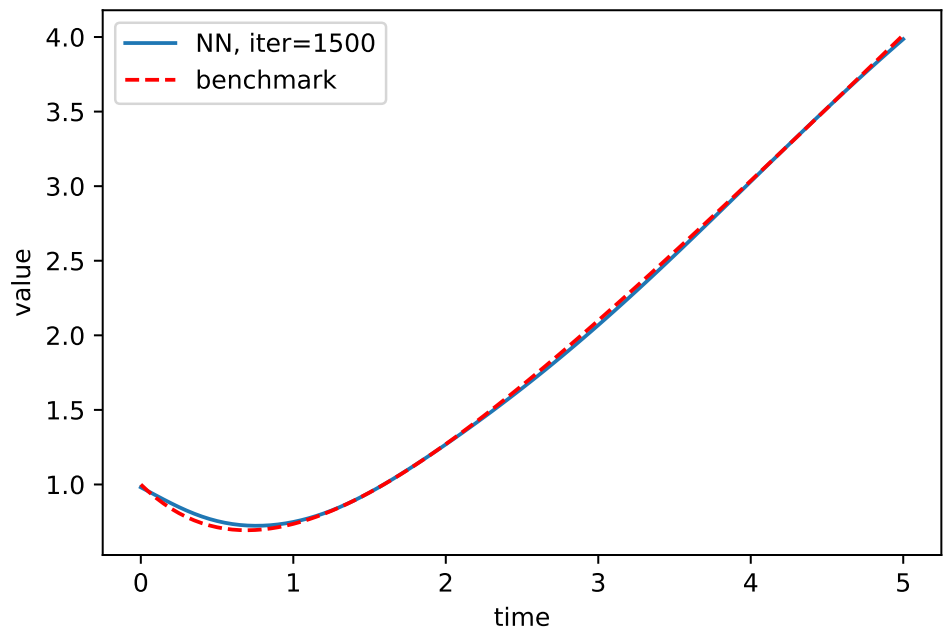

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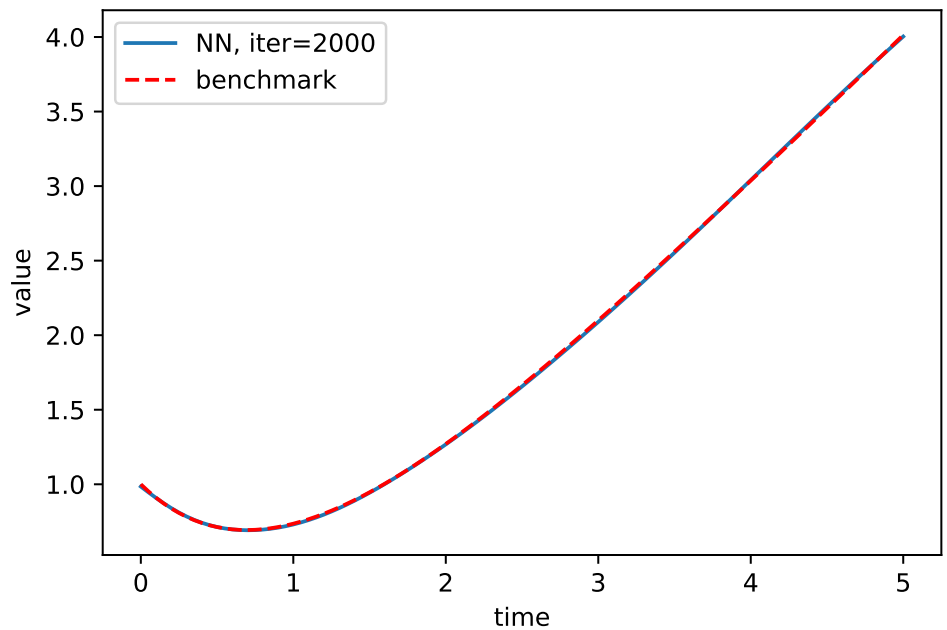

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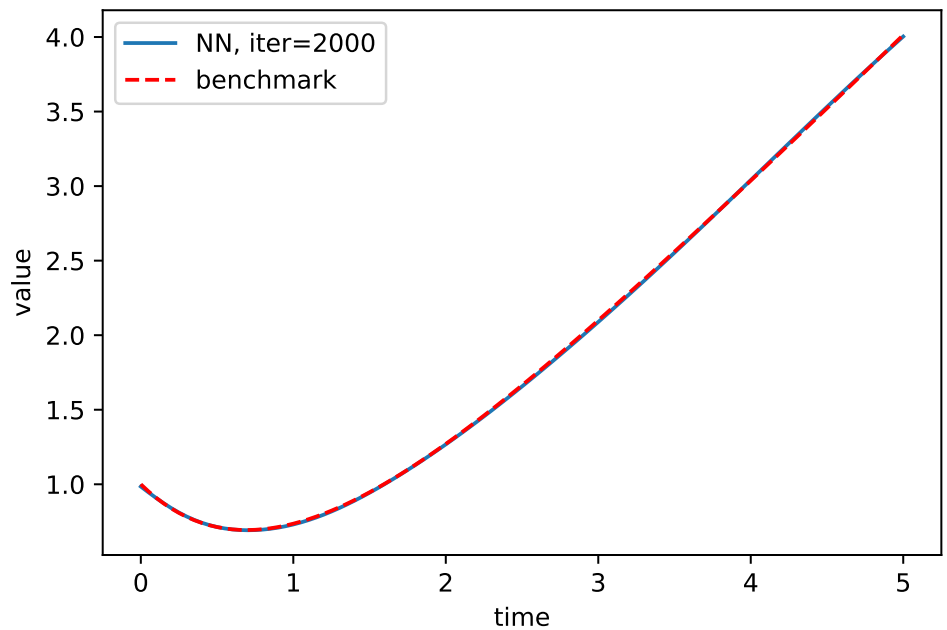

https://colab.research.google.com/drive/1LHuV1oE6eyO6AQgw3joQjow_uozQWSTw?usp=sharing

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Deep Galerkin Method (DGM), proposed by [Sirignano, Spiliopoulos][1]

- Look for $\varphi : \mathbb{R}^d \ni x \mapsto \varphi(x) \in \mathbb{R}$ s.t.

$$F(x, \varphi(x), D\varphi(x), D^2\varphi(x), \dots) = 0, \qquad x \in Q$$

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- Remarks on the implementation:
  - Choice of distribution
  - Boundary conditions
  - Higher order derivatives computation

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DGM Architecture

- Let $\vec{x} = (t, x)$ be the input
- Architecture: $L + 1$ hidden layers ($\odot$ denotes element-wise multiplication):

$$\begin{aligned}
S^1 &= \sigma(W^1 \vec{x} + b^1), \\
Z^\ell &= \sigma(U^{z,\ell} \vec{x} + W^{z,\ell} S^\ell + b^{z,\ell}), \quad \ell = 1, \ldots, L, \\
G^\ell &= \sigma(U^{g,\ell} \vec{x} + W^{g,\ell} S^1 + b^{g,\ell}), \quad \ell = 1, \ldots, L, \\
R^\ell &= \sigma(U^{r,\ell} \vec{x} + W^{r,\ell} S^\ell + b^{r,\ell}), \quad \ell = 1, \ldots, L, \\
H^\ell &= \sigma(U^{h,\ell} \vec{x} + W^{h,\ell} (S^\ell \odot R^\ell) + b^{h,\ell}), \quad \ell = 1, \ldots, L, \\
S^{\ell+1} &= (1 - G^\ell) \odot H^\ell + Z^\ell \odot S^\ell, \quad \ell = 1, \ldots, L, \\
f(t, x; \theta) &= W S^{L+1} + b,
\end{aligned}$$

- The parameters are

$$\theta = \left\{ W^1, b^1, \left(U^{\alpha,\ell}, W^{\alpha,\ell}, b^{\alpha,\ell} \right)_{\ell = 1 \ldots, L, \alpha \in \{z,g,r,h\}}, W, b \right\}.$$

- The number of units in each layer is M and $\sigma : \mathbb{R}^M \to \mathbb{R}^M$ is an element-wise nonlinearity:

$$\sigma(z) = \Big(\phi(z_1), \phi(z_2), \ldots, \phi(z_M) \Big),$$

where $\phi : \mathbb{R} \to \mathbb{R}$ is a nonlinear activation function.

MFG PDE system

Reminder: (m, u) solving, on $[0, T] \times \mathbb{T}^d$,

$$\begin{cases} 0 = -\dfrac{\partial u}{\partial t}(t,x) - \nu \Delta u(t,x) + H(x, m(t,\cdot), \nabla u(t,x)) \\ 0 = \dfrac{\partial m}{\partial t}(t,x) - \nu \Delta m(t,x) - \operatorname{div}\left(m(t,\cdot) \partial_p H(\cdot, m(t), \nabla u(t,\cdot))\right)(x) \\ u(T,x) = g(x, m(T,\cdot)), \qquad m(0,x) = m_0(x) \end{cases}$$

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Or ergodic version: (m, u, λ) on $\mathbb{T}^d$

$$\begin{cases} 0 = -\nu \Delta u(x) + H(x, m(\cdot), \nabla u(x)) + \lambda \\ 0 = -\nu \Delta m(x) - \operatorname{div}\left(m(\cdot) \partial_p H(\cdot, m, \nabla u(\cdot))\right)(x) \\ \displaystyle\int u(x) dx = 0, \qquad \int m(x) dx = 1, m > 0 \end{cases}$$

See [Lasry, Lions'07; BFY'13, Chapter 7]

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Analogous PDE systems for MFC problems

Numerical Illustration 1: Ergodic Example with Explicit Solution

Example (of MFC) with explicit solution on $\mathbb{T}^d$ ($d = 10$)
Following [Almulla *et al.*'17], take

$$f(x, m, v) = \frac{1}{2}|v|^2 + \tilde{f}(x) + \ln(m(x)),$$

with $\tilde{f}(x) = 2\pi^2 \left[-\sum_{i=1}^d c \sin(2\pi x_i) + \sum_{i=1}^d |c \cos(2\pi x_i)|^2 \right] - 2\sum_{i=1}^d c \sin(2\pi x_i)$,
then the solution is given by $u(x) = c\sum_{i=1}^d \sin(2\pi x_i)$ and $m(x) = e^{2u(x)} / \int e^{2u}$

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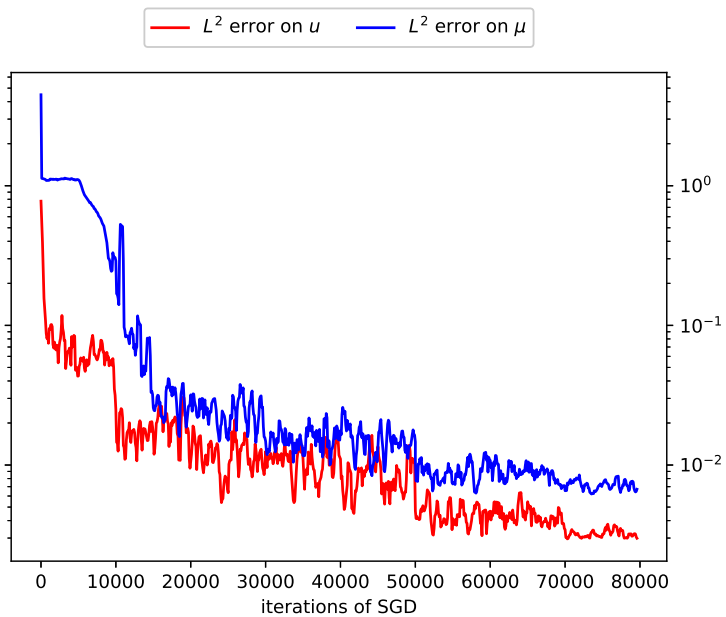
Error vs SGD iterations (see [Carmona, L.'21]):



Relative L^2 error on u and m

Numerical Illustration 2: Ergodic Example without Explicit Solution

Example (of MFG) without explicit solution on $\mathbb{T}^d$ ($d = 30$)
Inspired by [Achdou, Capuzzo-Dolcetta'11], take

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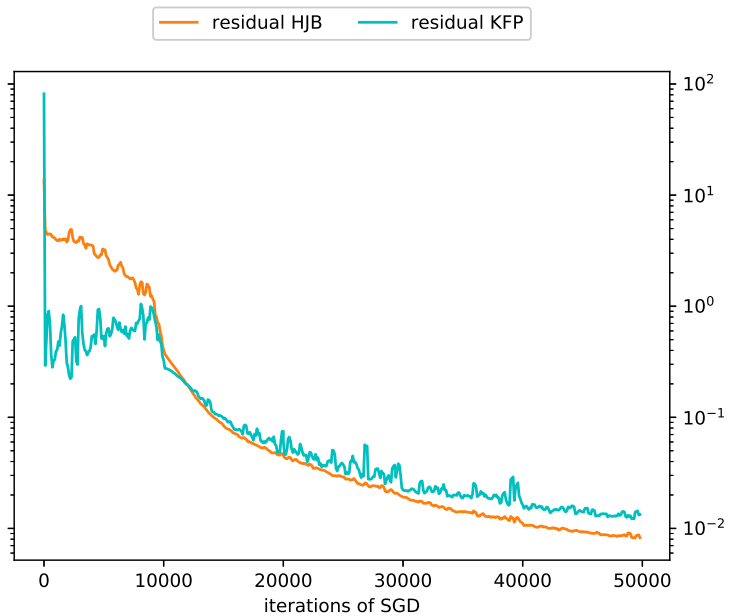
PDE residuals vs SGD iterations (see [Carmona, L.'21]):



L^2 norm of residuals for HJB and KFP

Numerical Illustration 3: Crowd Trading

Model of crowd trading [Cardaliaguet, Lehalle]:

$$\begin{cases} dS_t^{\bar{\nu}} = \gamma \bar{\nu}_t dt + \sigma dW_t & \text{(price)} \\ dQ_t^{v} = v_t dt & \text{(player's inventory)} \\ dX_t^{v,\bar{\nu}} = -v_t (S_t^{\bar{\nu}} + \kappa v_t) dt & \text{(player's wealth)} \end{cases}$$

Objective: given $(\bar{\nu}_t)_t$, maximize

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Mean field term: at equilibrium

$$\bar\nu_t = \int \hat v_t(q) \hat m(t, dq) = \int \frac{\partial_q \hat u(t,q)}{2\kappa} \hat m(t, dq),$$

where $\hat m$ solves the KFP equation:

$$m(0,\cdot) = m_0, \qquad \partial_t m + \partial_q \left(m \frac{\partial_q \hat u(t,q)}{2\kappa} \right) = 0$$

Numerical Illustration 3: Crowd Trading

Reduced forward-backward PDE system:

$$\begin{cases} 0 = -\partial_t u(t,q) + \phi q^2 - \dfrac{|\partial_q u(t,q)|^2}{4\kappa} = \gamma \bar{\nu}_t q \\ 0 = \partial_t m(t,q) + \partial_q \left(m(t,q) \dfrac{\partial_q u(t,q)}{2\kappa} \right) \\ \bar{\nu}_t = \displaystyle\int \frac{\partial_q u(t,q)}{2\kappa} m(t,q) dq \\ m(0,\cdot) = m_0, u(T,q) = -Aq^2. \end{cases}$$

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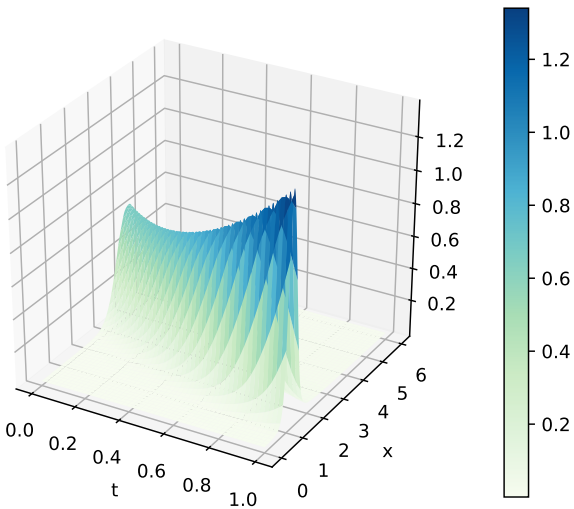
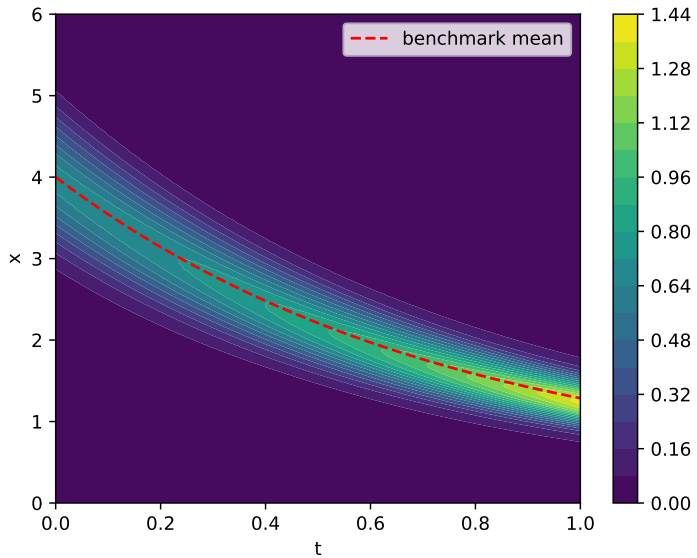
Numerical results obtained with DGM & comparison with ODE solution:

Evolution of m:





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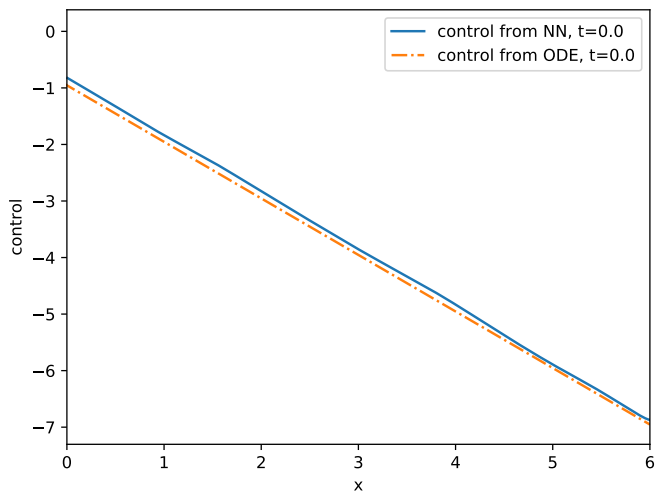
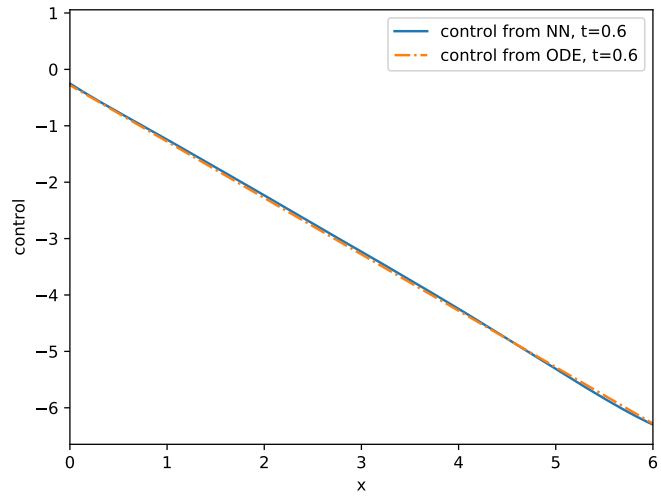
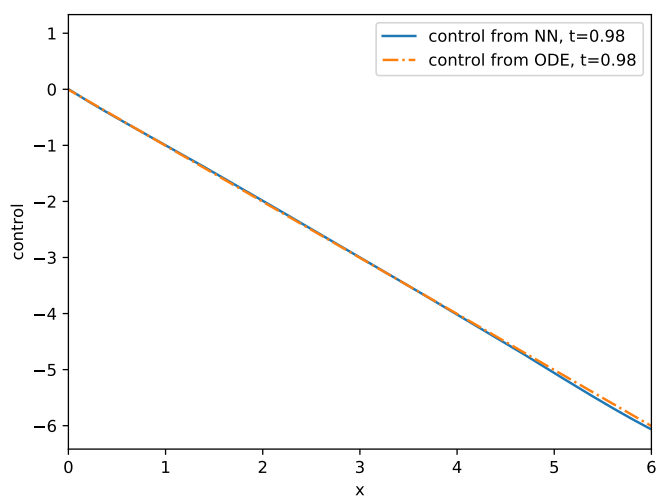
Evolution of equilibrium control $\hat{v}$:







Outline

Examples

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`thispersondoesnotexist.com`

`thiscatdoesnotexist.com`

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[Karras *et al.*'20]: Karras, T., Laine, S., Aittala, M., Hellsten, J., Lehtinen, J., & Aila, T. (2020). Analyzing and improving the image quality of stylegan. In *Proceedings of the IEEE/CVF Conference on Computer Vision and Pattern Recognition* (pp. 8110-8119).

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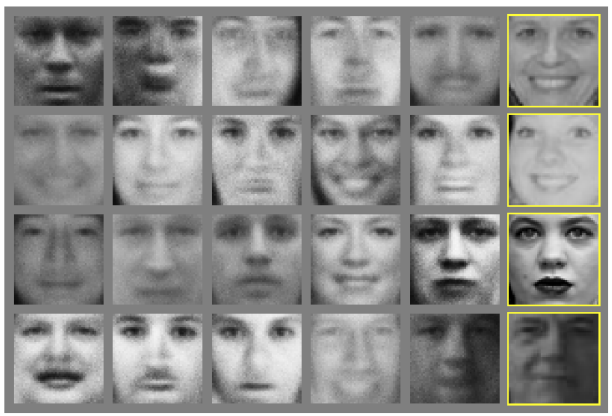

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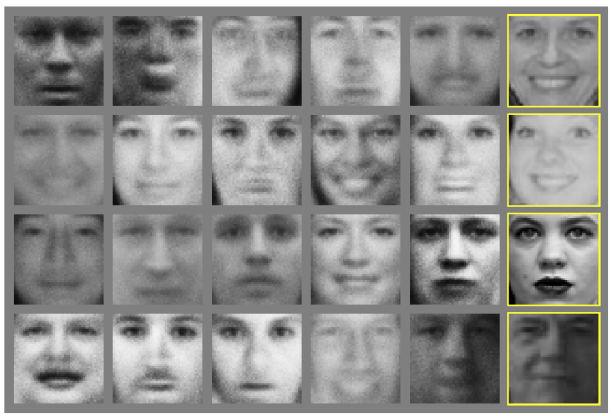

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NVIDIA'19

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GANs & MFGs

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Variational MFG: $\inf_{u:[0,T]\times\mathbb{R}^d \to \mathbb{R}} \quad \sup_{m:[0,T]\times\mathbb{R}^d \to \mathbb{R}} \Phi(m,u)$, where

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Related work: [Domingo-Enrich *et al.*, NeurIPS'20; Onken *et al.*'20]