

Mean Field Games:  
Numerical Methods and  
Applications in Machine Learning  
Part 6: Deep Learning for MFG PDEs

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<https://mlauriere.github.io/teaching/MFG-PKU-6.pdf>

Peking University  
Summer School on Applied Mathematics  
July 26 – August 6, 2021

# RECAP

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## 1. Deep Galerkin Method for MFG PDEs

- Warm-up: ODE
- Solving MFG PDE system
- Link with Generative Adversarial Networks

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## Numerical Illustration

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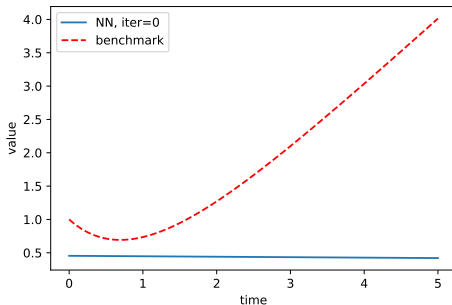
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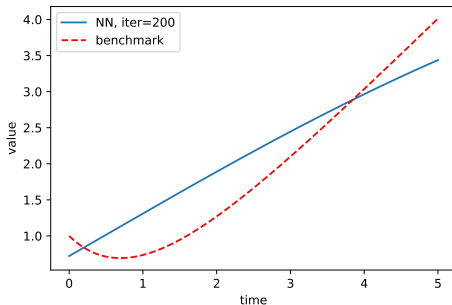
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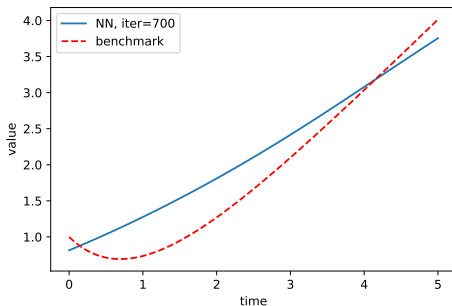
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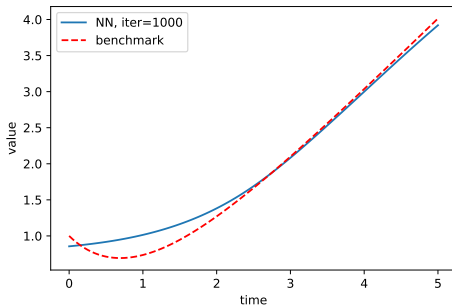
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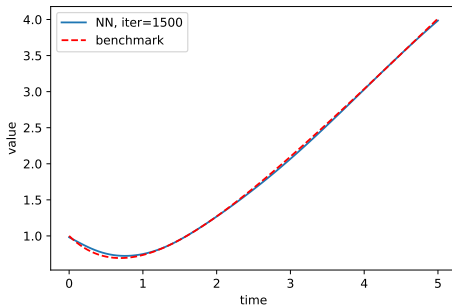
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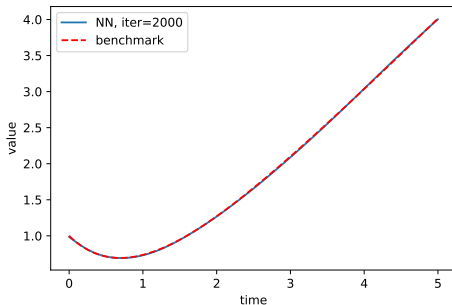
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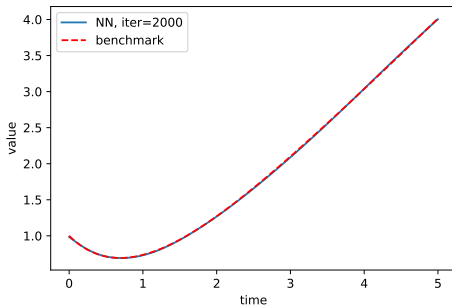
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**Deep Galerkin Method (DGM)**, proposed by [Sirignano, Spiliopoulos]<sup>1</sup>

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- Use SGD
- Remarks on the implementation:
  - ▶ Choice of distribution
  - ▶ Boundary conditions
  - ▶ Higher order derivatives computation

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- Let  $\vec{x} = (t, x)$  be the input
- Architecture:  $L + 1$  hidden layers ( $\odot$  denotes element-wise multiplication):

$$\begin{aligned}S^1 &= \sigma(W^1 \vec{x} + b^1), \\Z^\ell &= \sigma(U^{z,\ell} \vec{x} + W^{z,\ell} S^\ell + b^{z,\ell}), \quad \ell = 1, \dots, L, \\G^\ell &= \sigma(U^{g,\ell} \vec{x} + W^{g,\ell} S^1 + b^{g,\ell}), \quad \ell = 1, \dots, L, \\R^\ell &= \sigma(U^{r,\ell} \vec{x} + W^{r,\ell} S^\ell + b^{r,\ell}), \quad \ell = 1, \dots, L, \\H^\ell &= \sigma(U^{h,\ell} \vec{x} + W^{h,\ell} (S^\ell \odot R^\ell) + b^{h,\ell}), \quad \ell = 1, \dots, L, \\S^{\ell+1} &= (1 - G^\ell) \odot H^\ell + Z^\ell \odot S^\ell, \quad \ell = 1, \dots, L, \\f(t, x; \theta) &= WS^{L+1} + b,\end{aligned}$$

- The parameters are

$$\theta = \left\{ W^1, b^1, \left( U^{\alpha,\ell}, W^{\alpha,\ell}, b^{\alpha,\ell} \right)_{\ell=1, \dots, L, \alpha \in \{z, g, r, h\}}, W, b \right\}.$$

- The number of units in each layer is  $M$  and  $\sigma : \mathbb{R}^M \rightarrow \mathbb{R}^M$  is an element-wise nonlinearity:

$$\sigma(z) = \left( \phi(z_1), \phi(z_2), \dots, \phi(z_M) \right),$$

where  $\phi : \mathbb{R} \rightarrow \mathbb{R}$  is a nonlinear activation function.



Reminder:  $(m, u)$  solving, on  $[0, T] \times \mathbb{T}^d$ ,

$$\begin{cases} 0 = -\frac{\partial u}{\partial t}(t, x) - \nu \Delta u(t, x) + H(x, m(t, \cdot), \nabla u(t, x)) \\ 0 = \frac{\partial m}{\partial t}(t, x) - \nu \Delta m(t, x) - \operatorname{div}(m(t, \cdot) \partial_p H(\cdot, m(t), \nabla u(t, \cdot))) (x) \\ u(T, x) = g(x, m(T, \cdot)), \quad m(0, x) = m_0(x) \end{cases}$$

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See [\[Lasry, Lions'07; BFY'13, Chapter 7\]](#)

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Analogous PDE systems for MFC problems

# Numerical Illustration 1: Ergodic Example with Explicit Solution

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## Example (of MFC) with explicit solution on $\mathbb{T}^d$ ( $d = 10$ )

Following [Almulla *et al.*'17], take

$$f(x, m, v) = \frac{1}{2}|v|^2 + \tilde{f}(x) + \ln(m(x)),$$

with  $\tilde{f}(x) = 2\pi^2 \left[ -\sum_{i=1}^d c \sin(2\pi x_i) + \sum_{i=1}^d |c \cos(2\pi x_i)|^2 \right] - 2 \sum_{i=1}^d c \sin(2\pi x_i)$ ,

then the solution is given by  $u(x) = c \sum_{i=1}^d \sin(2\pi x_i)$  and  $m(x) = e^{2u(x)} / \int e^{2u}$

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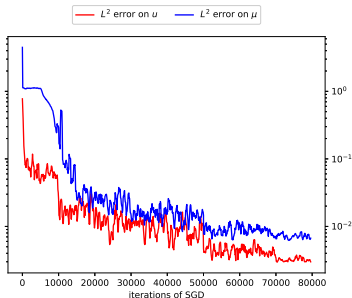
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**Error** vs SGD iterations (see [\[Carmona, L.'21\]](#)):



Relative  $L^2$  error on  $u$  and  $m$

## Numerical Illustration 2: Ergodic Example without Explicit Solution

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**Example (of MFG) without explicit solution on  $\mathbb{T}^d$  ( $d = 30$ )**

Inspired by [Achdou, Capuzzo-Dolcetta'11], take

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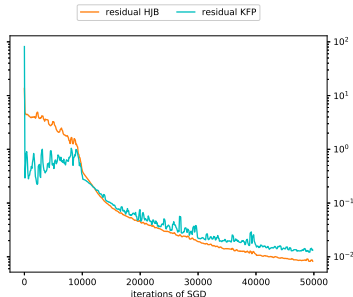
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**PDE residuals** vs SGD iterations (see [\[Carmona, L'21\]](#)):



$L^2$  norm of residuals for HJB and KFP

## Numerical Illustration 3: Crowd Trading

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Model of crowd trading [Cardaliaguet, Lehalle]:

$$\begin{cases} dS_t^{\bar{v}} = \gamma \bar{v}_t dt + \sigma dW_t & \text{(price)} \\ dQ_t^v = v_t dt & \text{(player's inventory)} \\ dX_t^{v, \bar{v}} = -v_t (S_t^{\bar{v}} + \kappa v_t) dt & \text{(player's wealth)} \end{cases}$$

**Objective:** given  $(\bar{v}_t)_t$ , maximize

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**Ansatz** [Cartea, Jaimungal]:  $V(t, x, s, q) = x + qsu(t, q)$ ,  $\hat{v}_t(q) = \frac{\partial_q u(t, q)}{2\kappa}$

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**Mean field term:** at equilibrium

$$\bar{v}_t = \int \hat{v}_t(q) \hat{m}(t, dq) = \int \frac{\partial_q \hat{u}(t, q)}{2\kappa} \hat{m}(t, dq),$$

where  $\hat{m}$  solves the KFP equation:

$$m(0, \cdot) = m_0, \quad \partial_t m + \partial_q \left( m \frac{\partial_q \hat{u}(t, q)}{2\kappa} \right) = 0$$

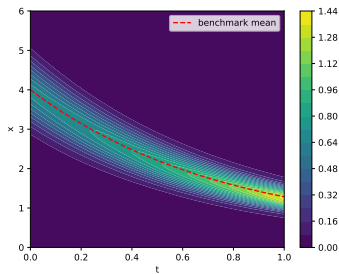
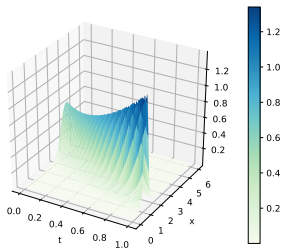
Reduced forward-backward PDE system:

$$\left\{ \begin{array}{l} 0 = -\partial_t u(t, q) + \phi q^2 - \frac{|\partial_q u(t, q)|^2}{4\kappa} = \gamma \bar{\nu}_t q \\ 0 = \partial_t m(t, q) + \partial_q \left( m(t, q) \frac{\partial_q u(t, q)}{2\kappa} \right) \\ \bar{\nu}_t = \int \frac{\partial_q u(t, q)}{2\kappa} m(t, q) dq \\ m(0, \cdot) = m_0, u(T, q) = -Aq^2. \end{array} \right.$$

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Numerical results obtained with DGM & comparison with ODE solution:

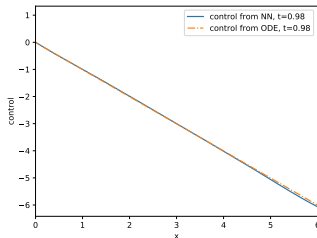
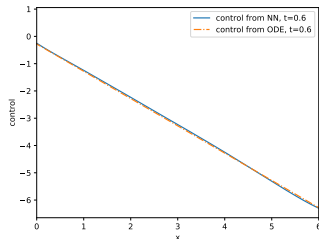
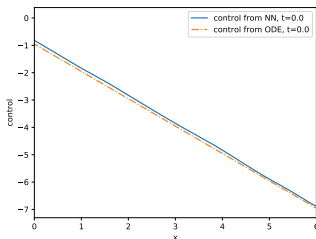
Evolution of  $m$ :



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Evolution of equilibrium control  $\hat{v}$ :



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# Examples

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## Examples

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thispersondoesnotexist.com



thiscatdoesnotexist.com



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[Karras *et al.*'20]: Karras, T., Laine, S., Aittala, M., Hellsten, J., Lehtinen, J., & Aila, T. (2020). Analyzing and improving the image quality of stylegan. In *Proceedings of the IEEE/CVF Conference on Computer Vision and Pattern Recognition* (pp. 8110-8119).

**Generative Adversarial Nets** [Goodfellow *et al.*'14]:

**Setup:** data space  $\mathcal{X}$  (e.g. images of fixed size); *unknown* data distribution  $p_{data}$

**Goal:** be able to generate samples according  $p_{data}$

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**Idea:** learn  $G : \mathcal{Z} \rightarrow \mathcal{X}$  such that  $p_z \circ G^{-1} \approx p_{data}$

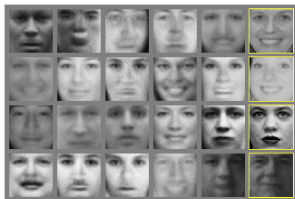
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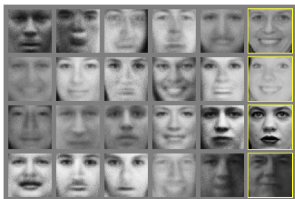
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NVIDIA'19

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Related work: [Domingo-Enrich *et al.*, NeurIPS'20; Onken *et al.*'20]















