

# Electrical Circuits Analysis

Phasor Analysis Revision

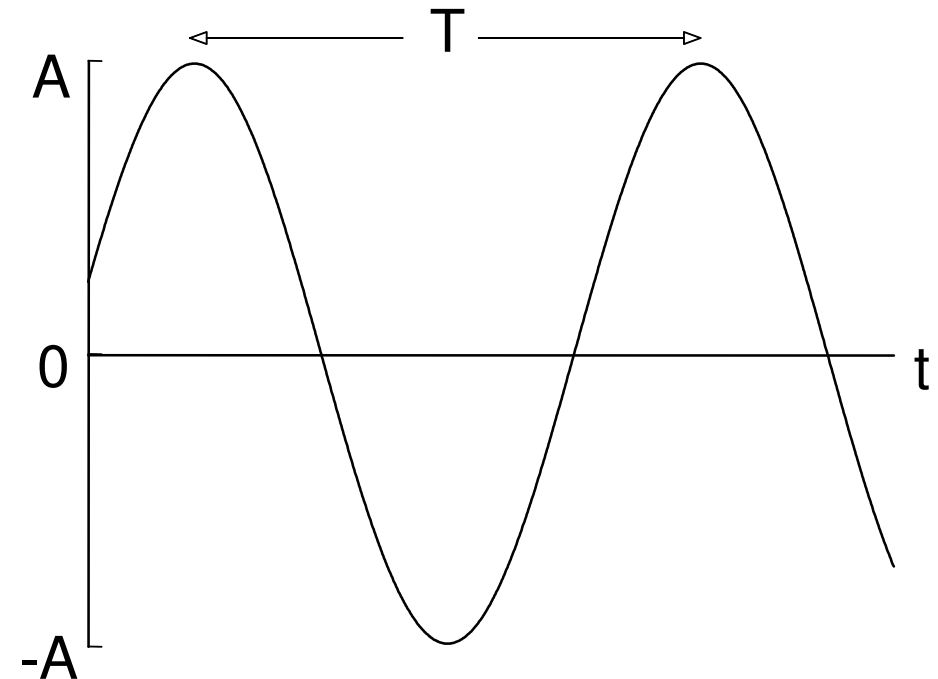
# Sinusoids

A sinusoidal function is given by the equation  $A \sin(\omega t + \phi)$

$A$  is the amplitude

$\phi$  is the phase angle (rad)

$\omega$  is the angular frequency (rad/s)



- The frequency,  $f$ , is given in cycles per second or Hertz (Hz), where  $\omega = 2\pi f$
- The period,  $T$ , is the time taken for the waveform to complete a full cycle, where  $T = 2\pi/\omega = 1/f$

# Root Mean Square (rms)

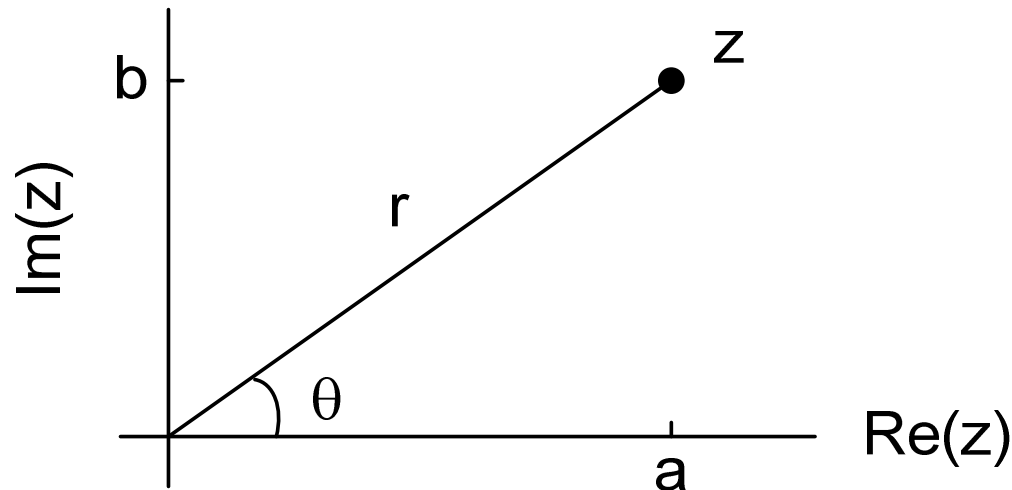
- To find the root mean square of a function, first square it, find the mean (average) of the result, and finally take the square root
- Considering the sinusoid  $A \sin \omega t$

$$\begin{aligned}\sqrt{\frac{1}{2\pi/\omega} \int_0^{2\pi/\omega} A^2 \sin^2 \omega t \, dt} &= \sqrt{\frac{A^2 \omega}{4\pi} \int_0^{2\pi/\omega} (1 - \cos 2\omega t) \, dt} \\ &= \sqrt{\frac{A^2 \omega}{4\pi} \left[ t - \frac{1}{2\omega} \sin 2\omega t \right]_0^{2\pi/\omega}} = \sqrt{\frac{A^2}{2}} = \frac{A}{\sqrt{2}} \text{ (rms value)}\end{aligned}$$

- *Electrical* engineers measure sinewave amplitude using *rms* values: *electronic* engineers use the *peak* value of the sinewave

# Complex Numbers

- A complex number  $\mathbf{z}$  can be written in rectangular form  $a + jb$
- $a$  is the real part of  $\mathbf{z}$ , denoted  $\text{Re}(\mathbf{z})$
- $b$  is the imaginary part of  $\mathbf{z}$ , denoted  $\text{Im}(\mathbf{z})$
- $\bar{\mathbf{z}}$  is the complex conjugate of  $\mathbf{z}$ , equals  $a - jb$



By elementary trigonometry,

$$\text{Re}(\mathbf{z}) = a = r \cos \theta$$

$$\text{Im}(\mathbf{z}) = b = r \sin \theta$$

# Complex Numbers

- $\mathbf{z}$  can be written as  $r \cos \theta + j r \sin \theta = r e^{j\theta}$  (polar form)
- $\bar{\mathbf{z}}$ , the complex conjugate of  $\mathbf{z}$ , equals  $r e^{-j\theta}$
- We can convert between rectangular and polar forms as,

$$a = r \cos \theta \qquad b = r \sin \theta$$

$$r = \sqrt{a^2 + b^2} \qquad \theta = \tan^{-1} b/a$$

- $\tan^{-1}$  function will only give a result between  $-\pi/2$  and  $\pi/2$

# Complex Arithmetic

If  $\mathbf{z}_1 = a + j b$  and  $\mathbf{z}_2 = c + j d$

$$\mathbf{z}_1 + \mathbf{z}_2 = a + c + j (b + d)$$

$$\mathbf{z}_1 - \mathbf{z}_2 = a - c + j (b - d)$$

$$\mathbf{z}_1 \mathbf{z}_2 = (a + j b) (c + j d) = ac - bd + j (ad + bc)$$

$$\frac{\mathbf{z}_1}{\mathbf{z}_2} = \frac{a + j b}{c + j d} = \frac{a + j b}{c + j d} \times \frac{c - j d}{c - j d} = \frac{ac + bd}{c^2 + d^2} + j \frac{bc - ad}{c^2 + d^2}$$

If  $\mathbf{z}_1 = r_1 e^{j\theta_1}$  and  $\mathbf{z}_2 = r_2 e^{j\theta_2}$

$$\mathbf{z}_1 \mathbf{z}_2 = r_1 e^{j\theta_1} r_2 e^{j\theta_2} = r_1 r_2 e^{j(\theta_1 + \theta_2)}$$

$$\frac{\mathbf{z}_1}{\mathbf{z}_2} = \frac{r_1 e^{j\theta_1}}{r_2 e^{j\theta_2}} = \frac{r_1}{r_2} e^{j(\theta_1 - \theta_2)}$$

# Impedance and Admittance

- *Impedance*,  $\mathbf{Z}$ , is the phasor domain equivalent of resistance
- The impedance of a capacitor  $C$  is  $1/j\omega C$ , while the impedance of an inductor  $L$  is  $j\omega L$ , where  $\omega$  is the supply frequency (rad/s)

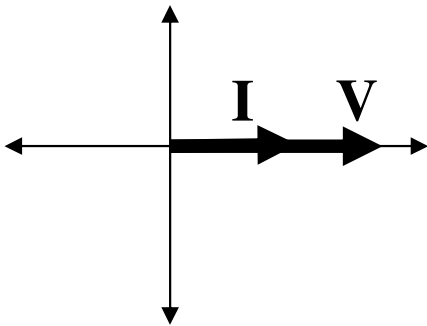
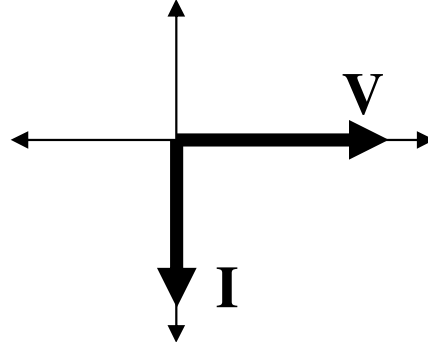
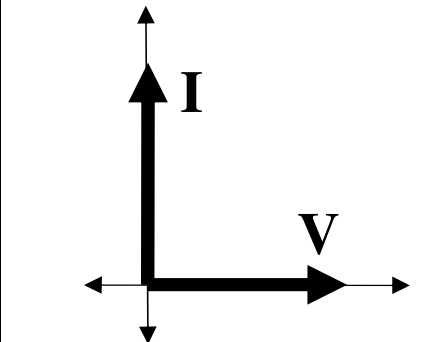
$$\mathbf{I} = j\omega C \mathbf{V} \quad \text{or} \quad \mathbf{V} = \frac{1}{j\omega C} \mathbf{I} \quad \mathbf{V} = j\omega L \mathbf{I} \quad \text{or} \quad \mathbf{I} = \frac{1}{j\omega L} \mathbf{V}$$

- The reciprocal of impedance,  $\mathbf{Y}$ , is called *admittance*

$$\mathbf{Z} = \frac{\mathbf{V}}{\mathbf{I}} = R + jX \quad \text{and} \quad \mathbf{Y} = \frac{1}{\mathbf{Z}} = G + jB$$

where  $X$  and  $B$  are the *reactance* and *susceptance*

# Phasor Domain

	Resistor	Inductor	Capacitor
Time domain	$v = R i$	$v(t) = L \frac{di(t)}{dt}$	$i(t) = C \frac{dv(t)}{dt}$
Phasor domain	$\mathbf{V} = R \mathbf{I}$	$\mathbf{V} = j\omega L \mathbf{I}$	$\mathbf{I} = j\omega C \mathbf{V}$
		<i>Current through inductor is said to lag the voltage</i>	<i>Current through capacitor is said to lead the voltage</i>
Phasor diagram CIVIL mnemonic			



# Impedances in Series & Parallel

- $\mathbf{Z}_1$  and  $\mathbf{Z}_2$  connected in series are equivalent to a single impedance ( $\mathbf{Z}_1 + \mathbf{Z}_2$ )

$$\mathbf{Z} = \mathbf{Z}_1 + \mathbf{Z}_2$$

$$R + jX = (R_1 + jX_1) + (R_2 + jX_2)$$

- $\mathbf{Z}_1$  and  $\mathbf{Z}_2$  connected in parallel are equivalent to a single impedance,  $\mathbf{Z}$ , such that

$$\frac{1}{\mathbf{Z}} = \frac{1}{\mathbf{Z}_1} + \frac{1}{\mathbf{Z}_2}$$

$$\frac{1}{R + jX} = \frac{1}{R_1 + jX_1} + \frac{1}{R_2 + jX_2}$$

# Average Power

- If the voltage and current for a circuit element are

$$v(t) = V_m \sin(\omega t + \phi_v) \text{ and } i(t) = I_m \sin(\omega t + \phi_i)$$

where  $V_m$  and  $I_m$  are the peak values of the sinewaves

→ the associated power at time instant  $t$  is

$$\begin{aligned} p(t) &= v(t) i(t) = V_m I_m \sin(\omega t + \phi_v) \sin(\omega t + \phi_i) \\ &= (V_m I_m / 2) [\cos(\phi_v - \phi_i) - \cos(2\omega t + \phi_v + \phi_i)] \end{aligned}$$

- The *average* power follows as

$$P = \frac{1}{2} V_m I_m \cos(\phi_v - \phi_i)$$

- $\cos(\phi_v - \phi_i)$  is called the *power factor*

# Phasor Representation

- The rms value of the sinusoid  $V_m \sin(\omega t + \theta_v)$  is  $V_{\text{rms}} = V_m / \sqrt{2}$
- Average power

$$= \frac{1}{2} V_m I_m \cos(\phi_v - \phi_i) = V_{\text{rms}} I_{\text{rms}} \cos(\phi_v - \phi_i)$$

- For a resistor,  $\mathbf{V} = R \mathbf{I}$

$$\Rightarrow \theta_v = \theta_i \rightarrow P = V_{\text{rms}} I_{\text{rms}} = V_{\text{rms}}^2 / R = I_{\text{rms}}^2 R$$

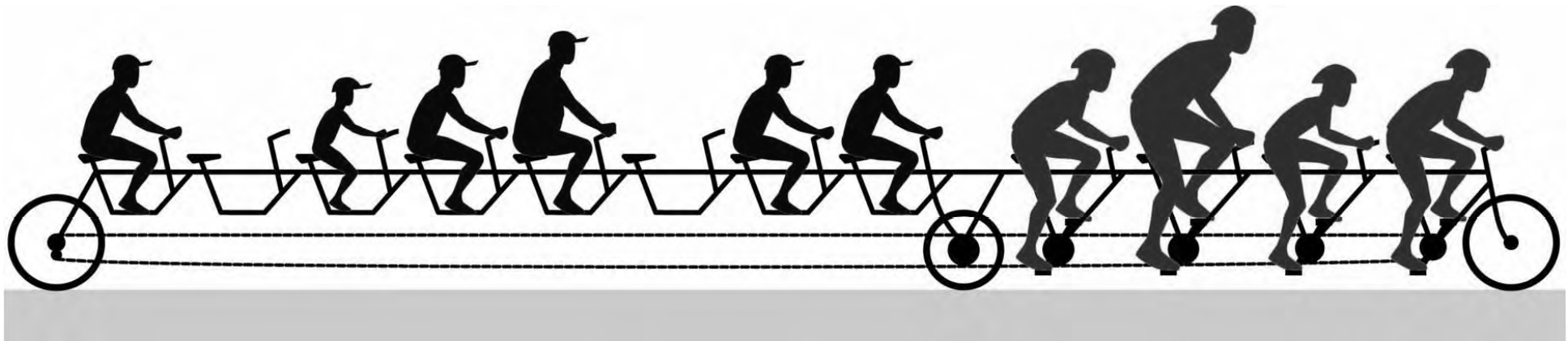
- For an inductor,  $\mathbf{V} = j \omega L \mathbf{I}$

$$\Rightarrow (\theta_v - \theta_i) = 90^\circ \rightarrow P = 0$$

- For a capacitor,  $\mathbf{V} = \mathbf{I} / j \omega C$

$$\Rightarrow (\theta_v - \theta_i) = -90^\circ \rightarrow P = 0$$

# Reactive Power analogy



Riders at the back  
are passengers

*Loads*

Riders at the front  
*drive* the bike

*Power stations*

# Reactive Power analogy

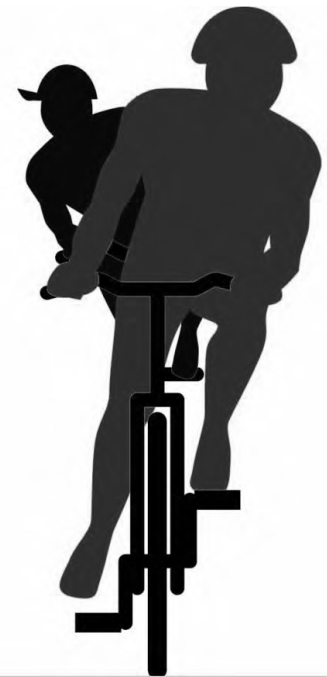


Effort required to drive bike is unaffected  
... BUT bike might fall over  
(A *reactive* load)

Riders at front must compensate  
(reactive generation)

Peddalling becomes more difficult  
(reduced capability)

Bicycle drag increases (more losses)



# Reactive Power

- Reactive power refers to the energy storage part of a load
- Reactive power is exchanged *back and forth* between inductive and capacitive parts of a *reactive load* (one containing inductors and capacitors) during each ac cycle
- Inductors store energy in their magnetic field while capacitors store energy in their electric field
- There is no net transfer of energy – no work is done
- Loads are generally made up of two components
  - Energy dissipated (active power)
  - Energy stored (reactive power)

# Active, Reactive & Apparent Power

- The *average (active) power*,  $P$ , is given as

$$P = V_{\text{rms}} \times I_{\text{rms}} \cos \theta \quad \text{W}$$

- The *reactive power*,  $Q$ , is then given as

$$Q = V_{\text{rms}} \times I_{\text{rms}} \sin \theta \quad \text{VAr}$$

- The *apparent power*,  $S$ , is given as

$$S = V_{\text{rms}} \times I_{\text{rms}} \quad \text{VA}$$

$$|S| = \sqrt{P^2 + Q^2}, \quad S = P + jQ$$

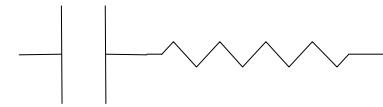
- Equipment ratings are expressed in terms of their apparent power (kVA / MVA) loading

# Power Triangles

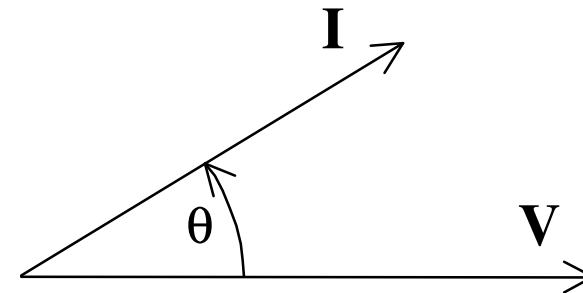
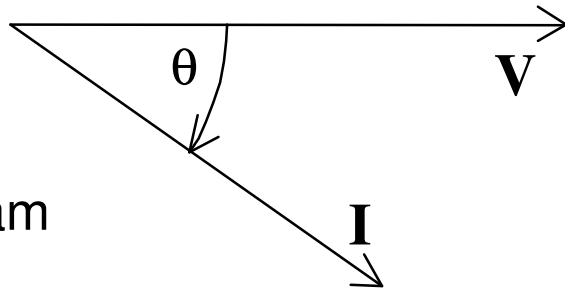
Lagging (inductive) load

Leading (capacitive) load

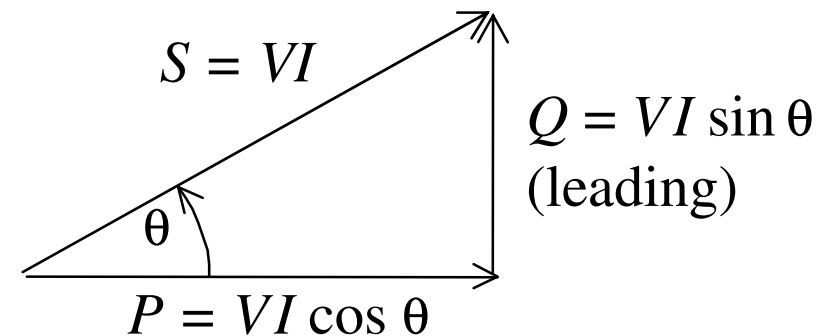
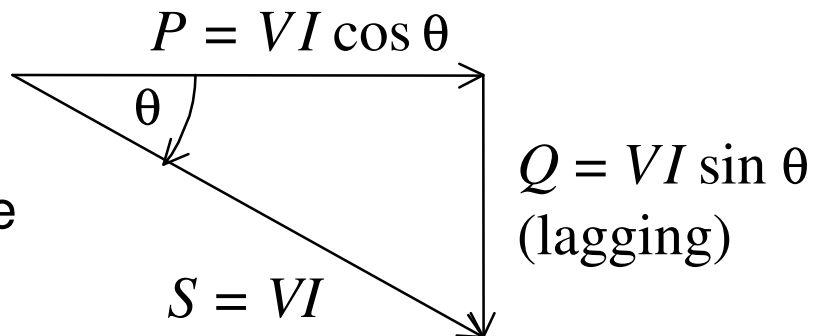
Circuit element



Phasor diagram



Power triangle





# Example

Determine the currents flowing in the following circuit

