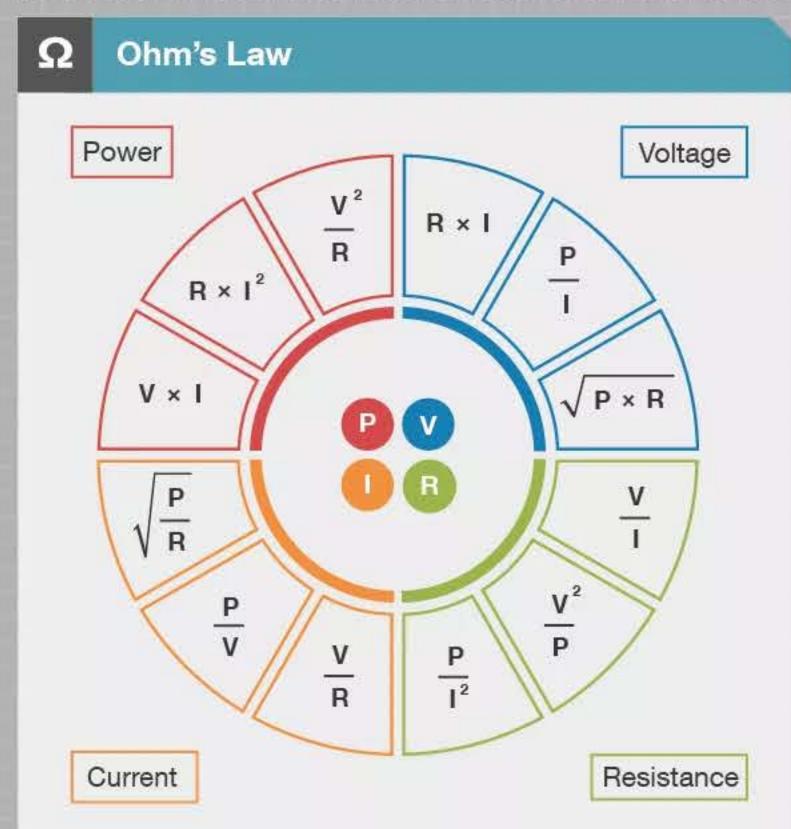
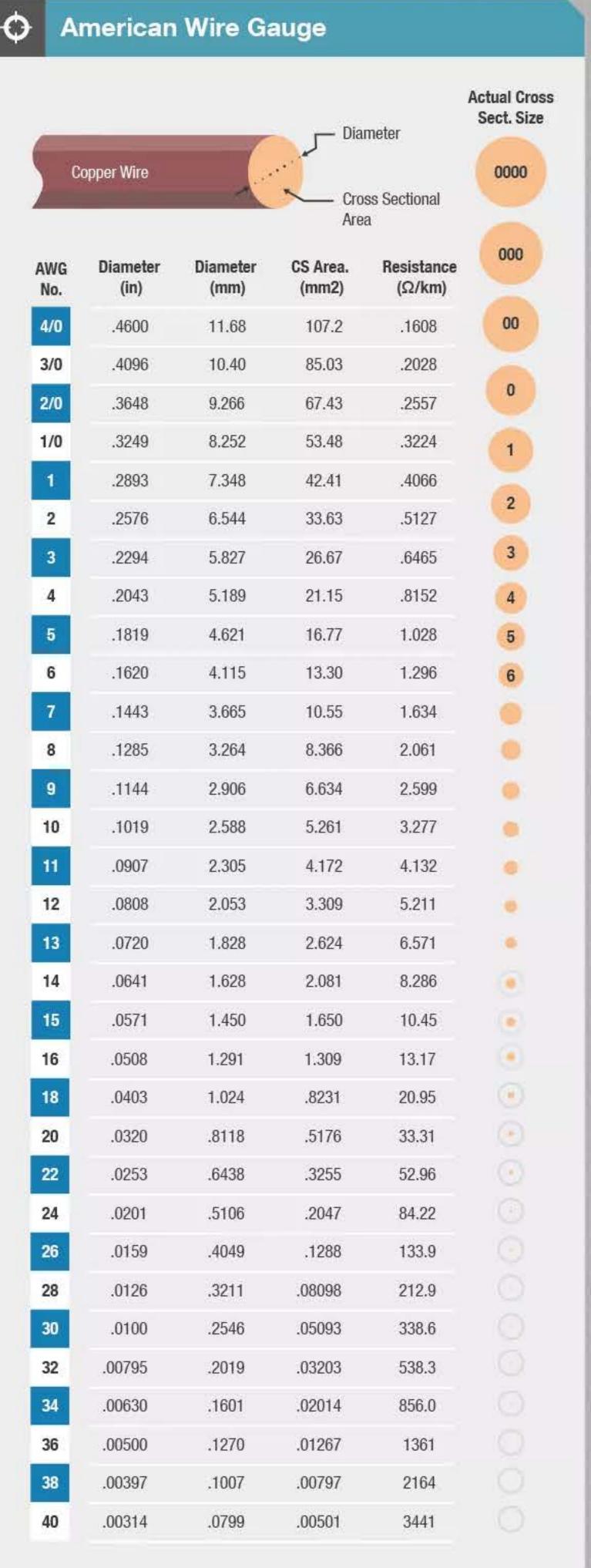


**ELECTRONICS CHEAT SHEET POSTER** 

Your quick reference companion in learning, referencing and debugging your electronics projects





Other Stuffs

References

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Engineer's Mini-Notebook by Forrest Mims III,

Joseph Ricafort

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dangerousprototypes.com blog.ricardoarturocabral.com

Books:

Thanks to the

Contributors

Richard Crowley

Michael Lebon

Max McMullen

Joseph Johnson

Compiled and

Illustrated by:

Let's Keep in Touch!

any means you prefer:

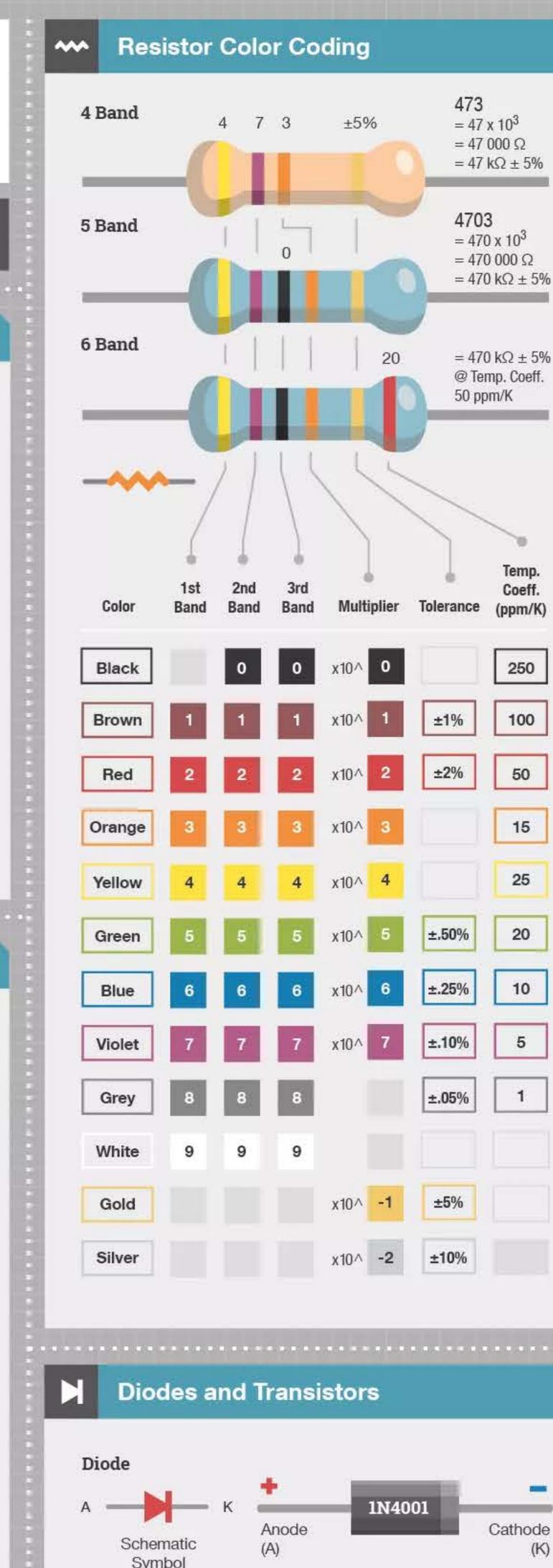
You can drop me some message at

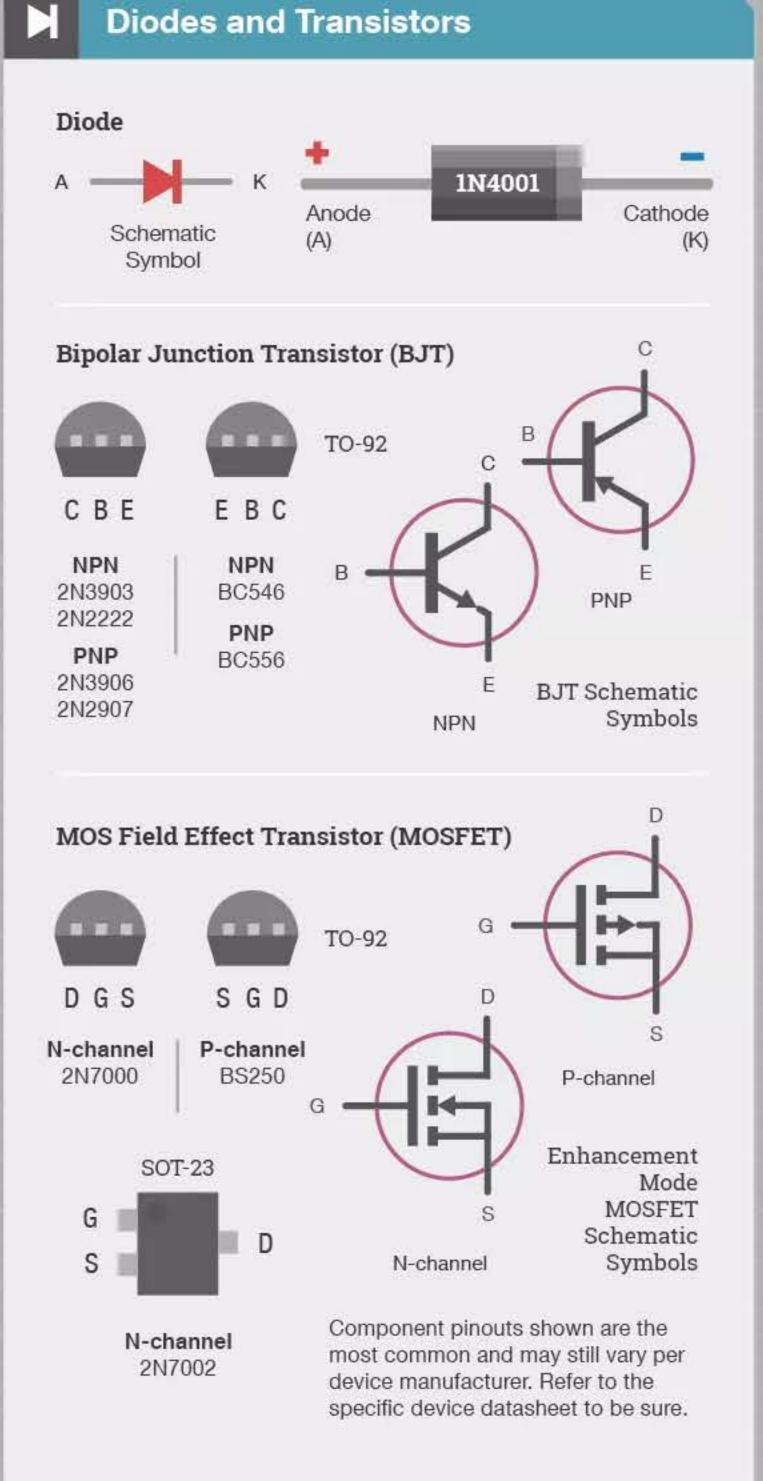
Andrew Goulah

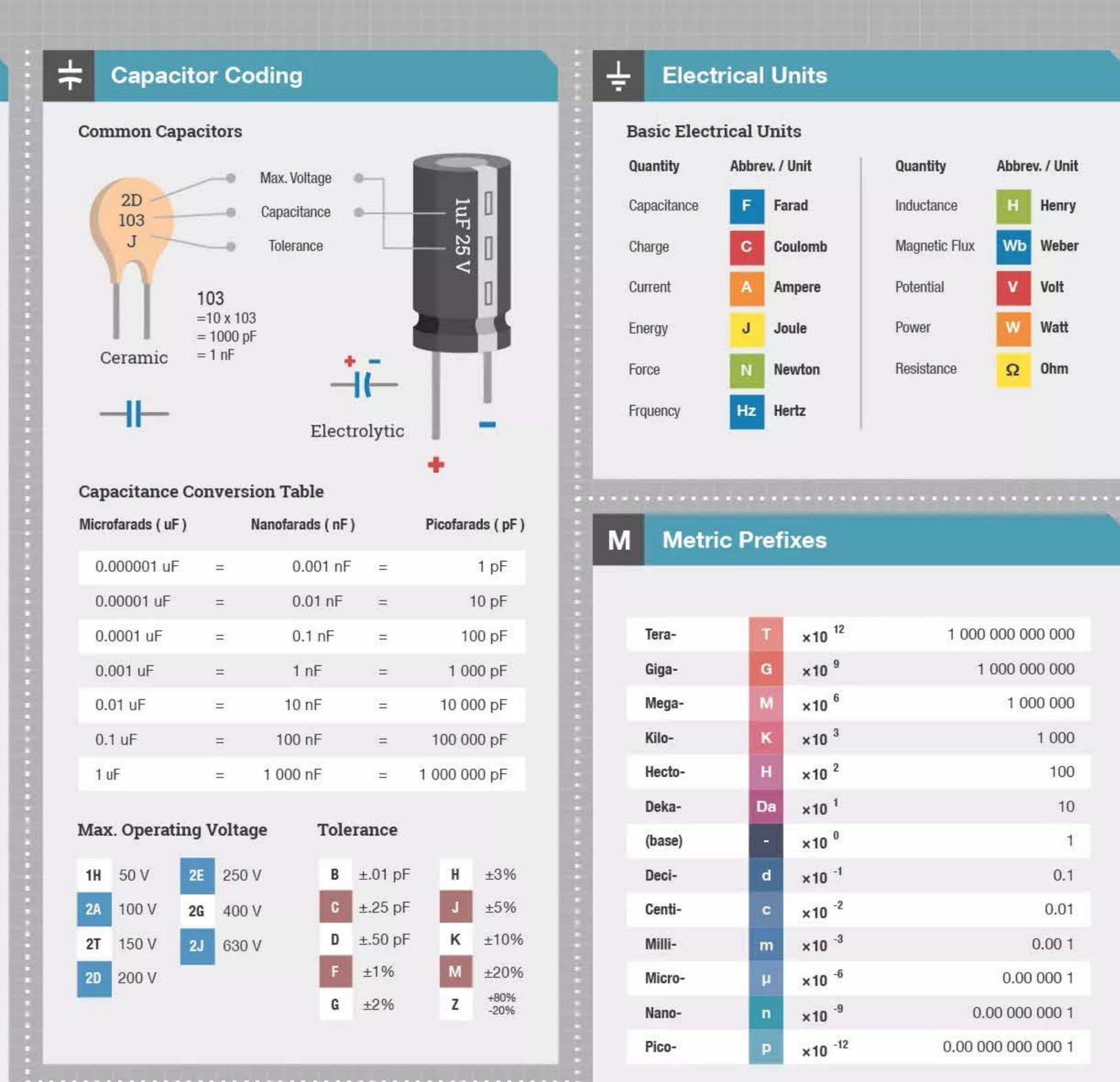
Jean François Dupuis

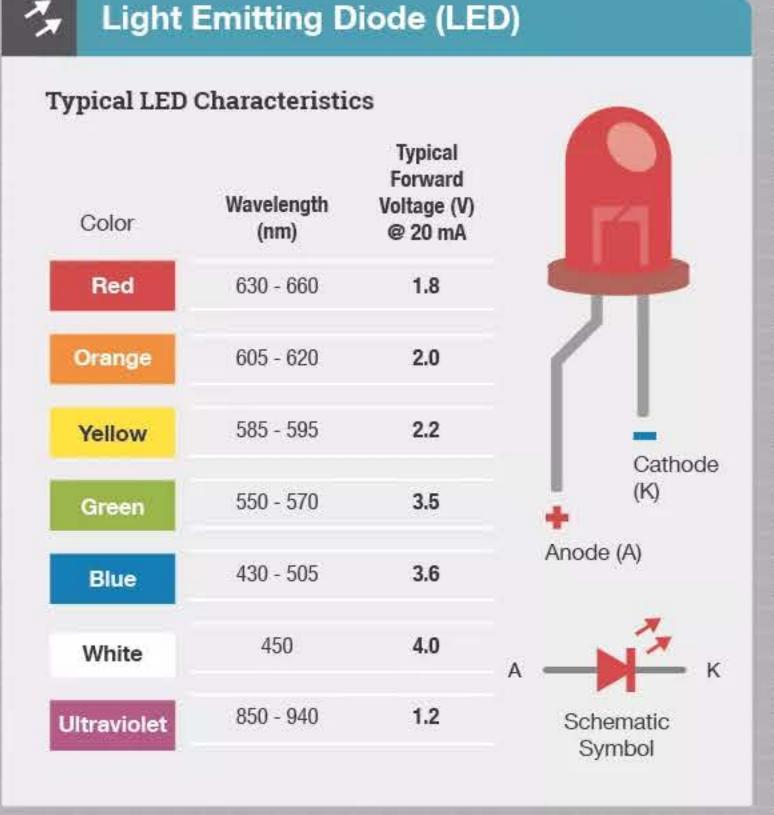
Cate Cannon

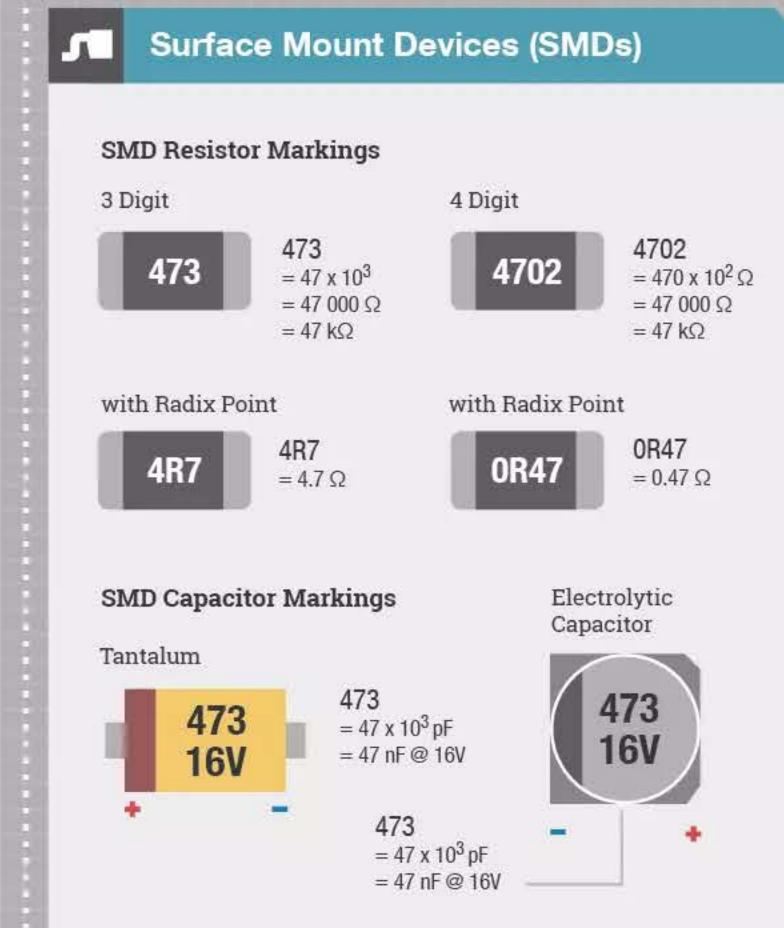
John Quinn

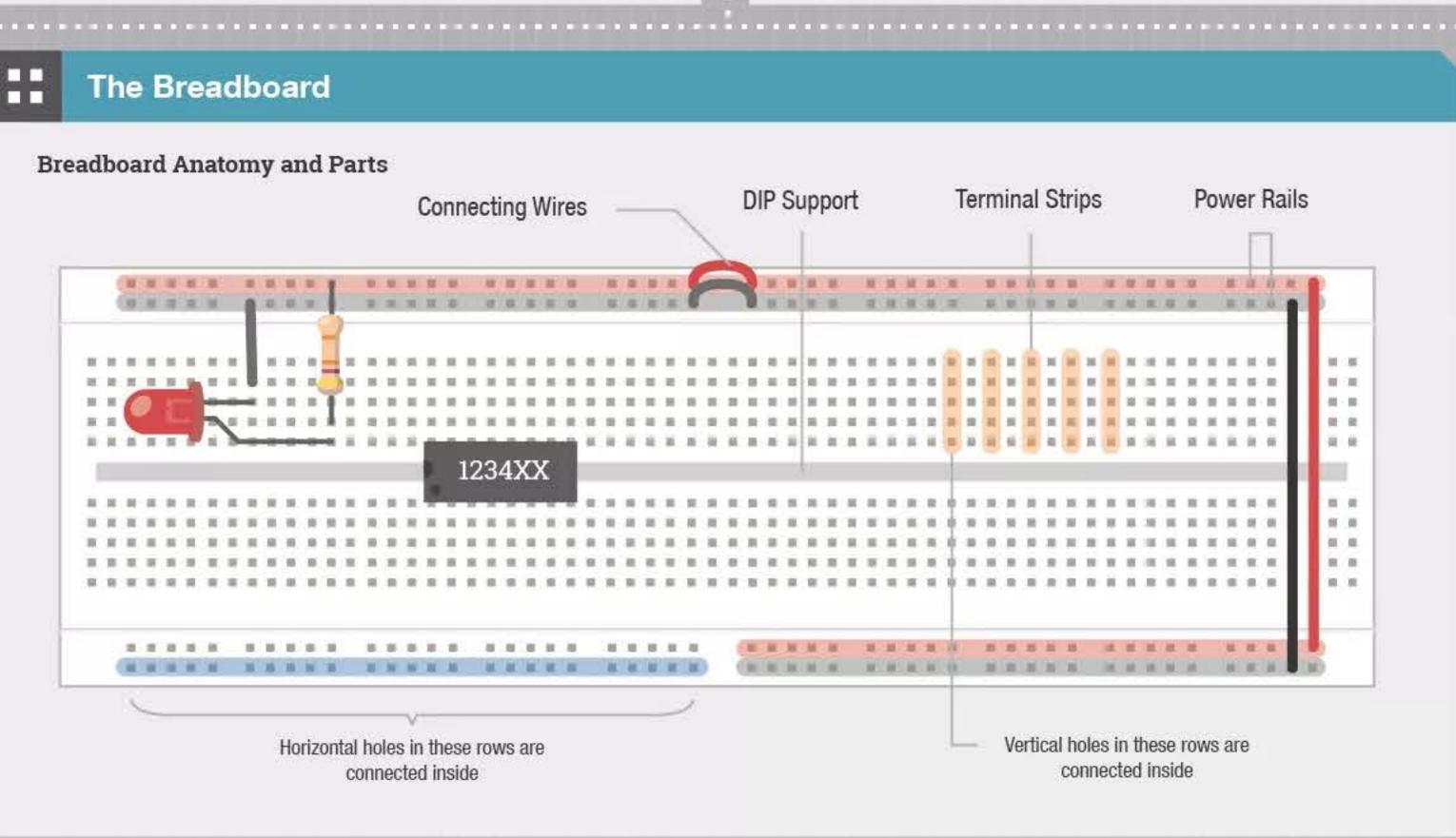


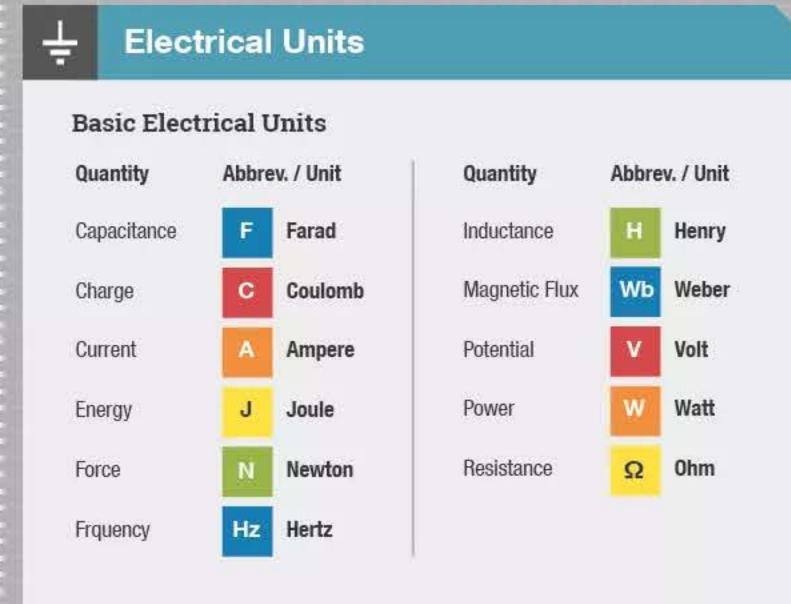




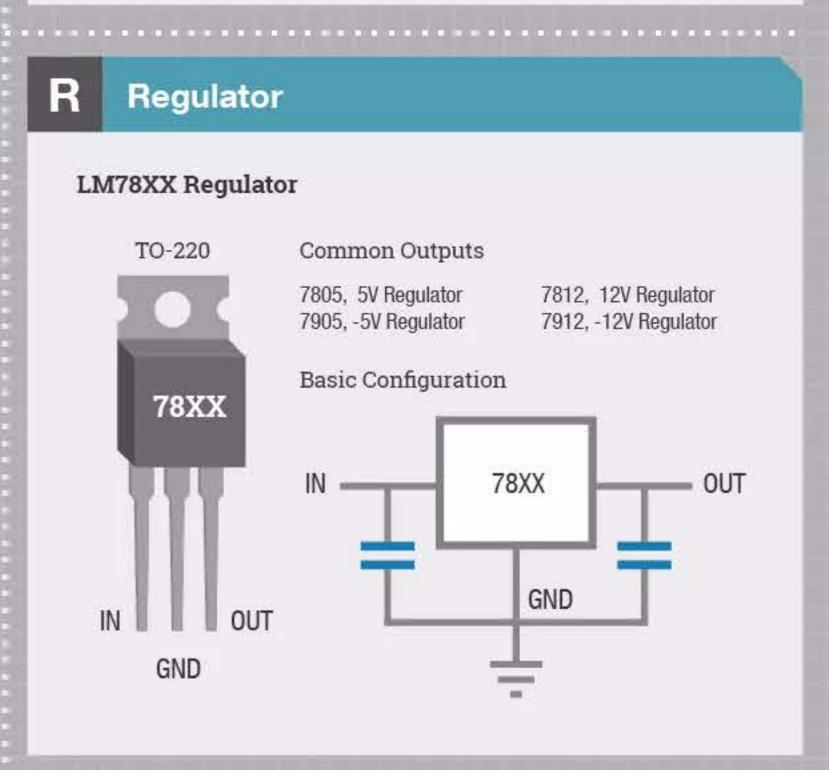


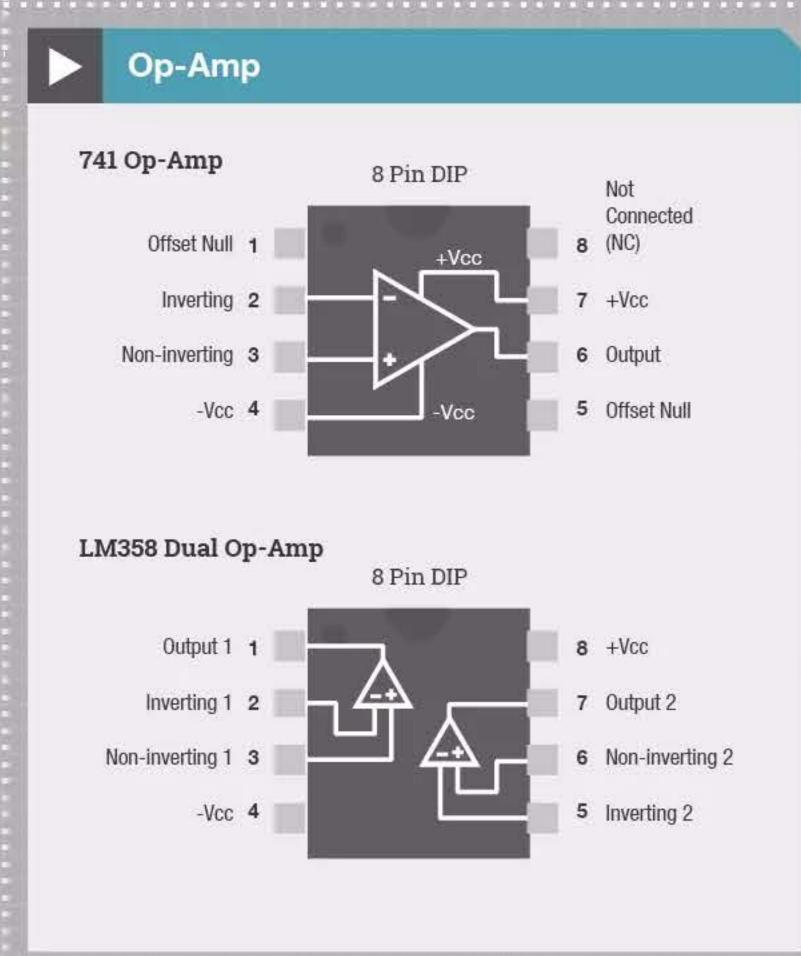






Tera-	Ţ	×10 <sup>12</sup>	1 000 000 000 000
Giga-	G	×10 9	1 000 000 000
Mega-	M	×10 6	1 000 000
Kilo-	K	×10 <sup>3</sup>	1 000
Hecto-	н	×10 <sup>2</sup>	100
Deka-	Da	×10 1	10
(base)	=	×10 0	1
Deci-	d	×10 <sup>-1</sup>	0.1
Centi-	c	×10 <sup>-2</sup>	0.01
Milli-	m	×10 <sup>-3</sup>	0.00 1
Micro-	μ	×10 <sup>-6</sup>	0.00 000 1
Nano-	n	×10 <sup>-9</sup>	0.00 000 000 1
Pico-	р	×10 <sup>-12</sup>	0.00 000 000 000 1







PRINTFUL

# Arduino Programming Cheat Sheet

Primary source: Arduino Language Reference http://arduino.cc/en/Reference/

# Structure & Flow

```
Basic Program Structure
void setup() {
  // Runs once when sketch starts
void loop() {
  // Runs repeatedly
Control Structures
if (x < 5) { ... } else { ... }
while (x < 5) { ... }
for (int i = 0; i < 10; i++) { ... }
        // Exit a loop immediately
continue; // Go to next iteration
switch (var) {
  case 1:
    break;
  case 2:
    break;
  default:
    * * *
          // x must match return type
          // For void return type
return;
Function Definitions
<ret. type> <name>(<params>) { ... }
e.g. int double(int x) {return x*2;}
```

# Operators

### General Operators

```
assignment
              - subtract
                 divide
   multiply
   modulo
              != not equal to
   equal to
   less than > greater than
  less than or equal to
   greater than or equal to
              or
&& and
   not
```

```
Compound Operators
++ increment
   decrement
   compound addition
   compound subtraction
*= compound multiplication
/= compound division
&= compound bitwise and
```

### Bitwise Operators

= compound bitwise or

```
& bitwise and
                    bitwise or
                 ∼ bitwise not
   bitwise xor
<< shift left
                 >> shift right
```

### Pointer Access

& reference: get a pointer dereference: follow a pointer

# Variables, Arrays, and Data

Data Types					
	false				
char -128	- 127, 'a' '\$' etc.				
unsigned char 0	- 255				
byte 0	- 255				
<b>int</b> -32768	- 32767				
unsigned int 0	- 65535				
word 0	- 65535				
long -2147483648	- 2147483647				
unsigned long 0	- 4294967295				
<b>float</b> -3.4028e+38	- 3.4028e+38				
double currently same as float					
void i.e., no ret	urn value				
Strings					
char str1[8] =					
{'A','r','d','u','i','n','o','\0'};					
// Includes \0 null termination					
char str2[8] =					
{'A','r','d','u','i','n','o'};					
// Compiler adds null termination					
<pre>char str3[] = "Arduino";</pre>					
<pre>char str4[8] = "Arduino";</pre>					
200 MANA					

### Numeric Constants

123	decimal	
<b>0b</b> 01111011	binary	
<b>0</b> 173	octal - base 8	
<b>0x</b> 7B	hexadecimal - base 16	
123 <b>U</b>	force unsigned	
123L	force long	
123 <b>UL</b>	force unsigned long	
123.0	force floating point	
1.23 <b>e</b> 6	1.23*10^6 = 1230000	
Qualifiers		
static	persists between call:	

in RAM (nice for ISR) volatile read-only const

```
PROGMEM
            in flash
Arrays
int myPins[] = \{2, 4, 8, 3, 6\};
int myInts[6]; // Array of 6 ints
myInts[0] = 42; // Assigning first
                 // index of myInts
myInts[6] = 12; // ERROR! Indexes
                 // are 0 though 5
```

### Built-in Functions

```
Pin Input/Output
                                       min(x, y)
Digital I/O - pins 0-13 A0-A5
 pinMode(pin,
                                       sin(rad)
    [INPUT, OUTPUT, INPUT_PULLUP])
                                       sqrt(x)
 int digitalread(pin)
  digitalWrite(pin, [HIGH, LOW])
Analog In - pins A0-A5
  int analogRead(pin)
  analogReference(
    [DEFAULT, INTERNAL, EXTERNAL])
                                      long random(min, max)
PWM Out - pins 3 5 6 9 10 11
  analogWrite(pin, value)
Advanced I/O
tone(pin, freq_Hz)
tone(pin, freq_Hz, duration_ms)
noTone(pin)
shiftOut(dataPin, clockPin,
  [MSBFIRST, LSBFIRST], value)
unsigned long pulseIn(pin,
 [HIGH, LOW])
Time
unsigned long millis()
  // Overflows at 50 days
```

### unsigned long micros() // Overflows at 70 minutes delay(msec) delayMicroseconds(usec)

```
Math
            max(x, y)
                        abs(x)
            cos(rad)
                       tan(rad)
            pow(base, exponent)
constrain(x, minval, maxval)
map(val, fromL, fromH, toL, toH)
```

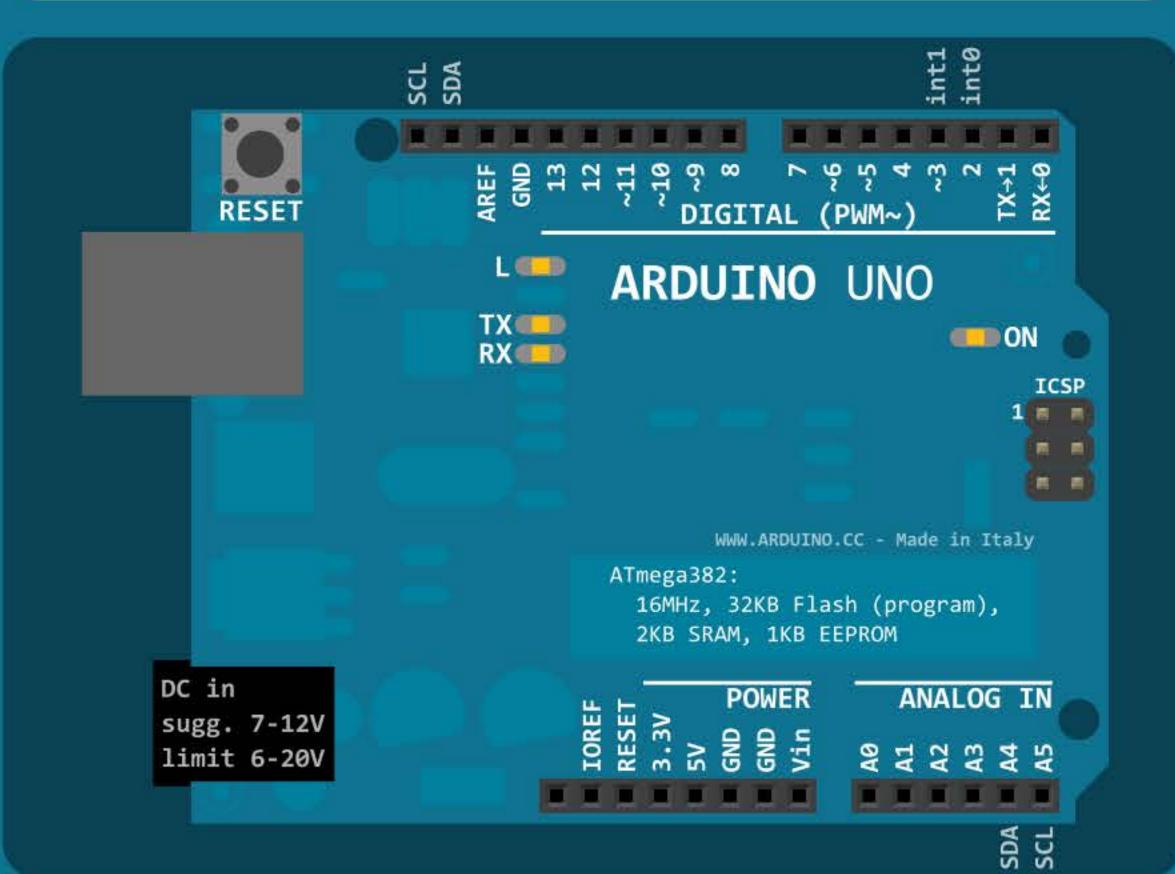
### Random Numbers randomSeed(seed) // long or int long random(max) // 0 to max-1

```
Bits and Bytes
lowByte(x)
             highByte(x)
bitRead(x, bitn)
bitWrite(x, bitn, bit)
bitSet(x, bitn)
bitClear(x, bitn)
bit(bitn) // bitn: 0=LSB 7=MSB
```

# Type Conversions

<pre>char(val)</pre>	<pre>byte(val)</pre>
<pre>int(val)</pre>	<pre>word(val)</pre>
<pre>long(val)</pre>	<pre>float(val)</pre>

External Interrupts attachInterrupt(interrupt, func, [LOW, CHANGE, RISING, FALLING]) detachInterrupt(interrupt) interrupts() noInterrupts()



## Libraries

Serial - comm. with PC or via RX/TX

```
begin(long speed) // Up to 115200
end()
int available() // #bytes available
           // -1 if none available
int read()
            // Read w/o removing
int peek()
flush()
print(data)
               println(data)
              write(char * string)
write(byte)
write(byte * data, size)
SerialEvent() // Called if data rdy
SoftwareSerial.h - comm. on any pin
SoftwareSerial(rxPin, txPin)
begin(long speed) // Up to 115200
             // Only 1 can listen
listen()
isListening() // at a time.
read, peek, print, println, write
 // Equivalent to Serial library
EEPROM.h - access non-volatile memory
byte read(addr)
write(addr, byte)
EEPROM[index] // Access as array
Servo.h - control servo motors
attach(pin, [min_uS, max_uS])
write(angle) // 0 to 180
writeMicroseconds(uS)
   // 1000-2000; 1500 is midpoint
int read() // 0 to 180
bool attached()
detach()
Wire.h - I<sup>2</sup>C communication
begin()
           // Join a master
begin(addr) // Join a slave @ addr
requestFrom(address, count)
beginTransmission(addr) // Step 1
send(byte)
                       // Step 2
send(char * string)
send(byte * data, size)
endTransmission()
                       // Step 3
int available() // #bytes available
byte receive() // Get next byte
onReceive(handler)
onRequest(handler)
```



by Mark Liffiton

### Adapted from:

- Original: Gavin Smith
- SVG version: Frederic Dufourg
- Arduino board drawing: Fritzing.org