

Last time:

Gaussian elimination is an algorithm with three operations:

- multiply rows with real #s
- add rows to other (below)
- swap the rows

ex: $x_1 + x_2 + x_3 + x_4 + x_5 = 0$
 $2x_1 + x_2 - x_3 + 3x_4 - x_5 = 0$
 $x_2 + 3x_3 + x_4 - 3x_5 = 0$

homogeneous system

↓ $-2 \cdot R_1 + R_2 \rightarrow R_2$

$$\left(\begin{array}{ccccc|c} 1 & 1 & 1 & 1 & 1 & 0 \\ -1 & -3 & 1 & -3 & -1 & 0 \\ 1 & 3 & 1 & -3 & -1 & 0 \end{array} \right)$$

→ $R_2 + R_3 \rightarrow R_3$

$$\left(\begin{array}{ccccc|c} 1 & 1 & 1 & 1 & 1 & 0 \\ 0 & -1 & -3 & 1 & -3 & 0 \\ 0 & 0 & 0 & 2 & -6 & 0 \end{array} \right)$$

the row reduced echelon form

Up to here : forward elimination

Pivot: the 1st nonzero entry of a row

The corresponding system:

$$x_1 + x_2 + x_3 + x_4 + x_5 = 0$$

$$-x_2 - 3x_3 + x_4 - 3x_5 = 0$$

$$2x_4 - 6x_5 = 0$$

free variables

$$R3: x_4 = 3x_5$$

$$R2: x_2 = -3x_3 + x_4 - 3x_5 \\ = -3x_3 + 3x_5 - 3x_5 = -3x_3$$

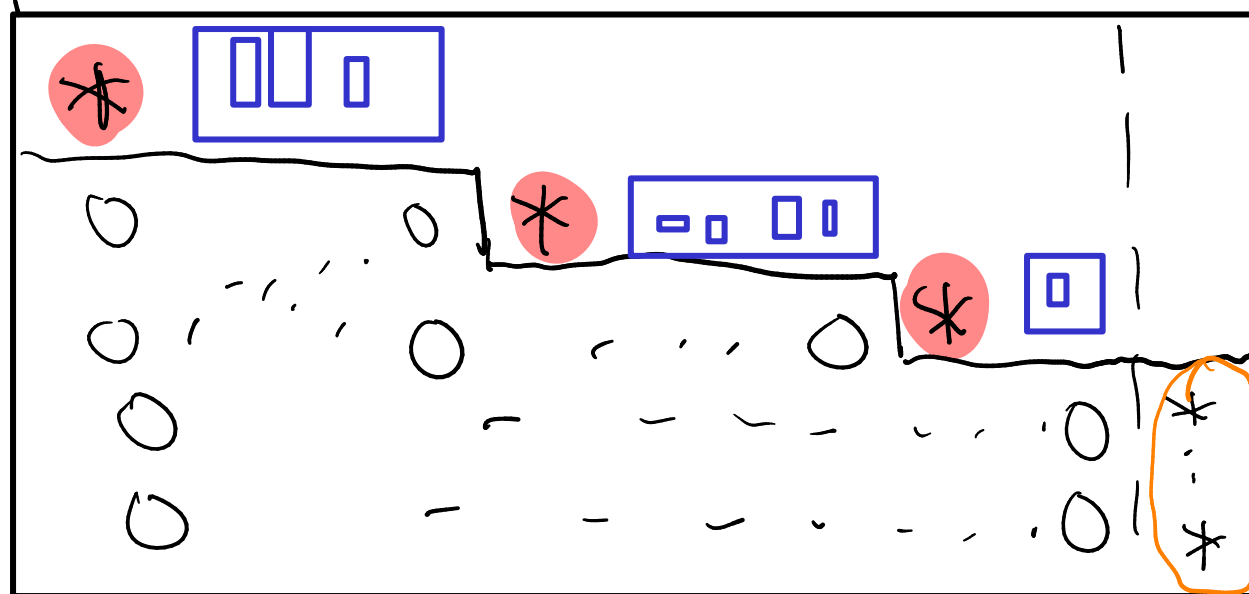
$$R1: x_1 = -x_2 - x_3 - x_4 - x_5 \\ = +3x_3 - x_3 - 3x_5 - x_5 \\ = 2x_3 - 4x_5$$

backward substitution

$$\text{Soln set} = \{x_3, x_5 \in \mathbb{R};$$

$$\left. \begin{aligned} x_4 &= 3x_5, x_2 = -3x_3, \\ x_1 &= 2x_3 - 4x_5 \end{aligned} \right\}$$

Summary: By forward elimination we come to the row reduced echelon form:



if nonzero then
INCONSISTENCY

The pivot variables are dependent on the nonpivot variables: the ones in the blue boxes are free.

Remark. Of course you're free to choose which variables are free. However numbers must match:

dependent ones \approx # of pivots

The choice we made above is the most reasonable.

Today: some algebra

Let V be a set, with two operations:

- $+$: $u, v \in V \leadsto u + v \in V$
- given $k \in \mathbb{R}$, $u \in V$: $ku \in V$.

We require they satisfy:

$$(k, l \in \mathbb{R}; u, v, w \in V)$$

G1: $u + (v + w) = (u + v) + w$: associativity

G2: There is some $a \in V$ which satisfies

$$a + u = u = u + a \quad \forall u.$$

a is called the ~~identity~~^{zero} element for $+$ & is denoted by $0 \in V$.

G3: $\forall u$, there's some v such that
 $u + v = 0 = v + u$.
 \downarrow inverse or opposite of u .

G4: $u + v = v + u$: commutativity

$$\boxed{S1}: k(lu) = (k \cdot l)u$$

$$\boxed{S2}: (k + l)u = ku + lu$$

$$\boxed{S3}: \underset{\in \mathbb{R}}{0} u = \underset{\in \mathbb{R}}{0} \in V.$$

If $(V, +, \cdot)$ satisfies $G1-G4$, $S1-S3$ then it's called a vector space. Its elements are called vectors.

The 2nd operation is called scalar product.

ex: Take $V = \mathbb{R}^n$, $n \geq 1$, $u = \begin{pmatrix} u_1 \\ u_2 \\ u_3 \end{pmatrix}$, $v = \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix}$

Define

$$u + v \stackrel{\text{def}}{=} \begin{pmatrix} u_1 + v_1 \\ u_2 + v_2 \\ u_3 + v_3 \end{pmatrix}, \quad ku \stackrel{\text{def}}{=} \begin{pmatrix} ku_1 \\ ku_2 \\ ku_3 \end{pmatrix}.$$

Then we get a vector space.
(HW: check $G1-G4$, $S1-S3$ hold!)

ex: A **matrix** is a grid of integers

$$A = \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1q} \\ a_{21} & a_{22} & \dots & \vdots \\ \vdots & \vdots & \ddots & \vdots \\ a_{p1} & a_{p2} & \dots & a_{pq} \end{pmatrix} \text{ is a } p \text{ by } q \text{ matrix.}$$

$p \times q$ \hookrightarrow # of rows
 a_{p2} \hookrightarrow an entry
 $p \times q$ \hookrightarrow # of columns

Define, for A, B $p \times q$ matrices,

$A + B$ as follows:

$$(A + B)_{ij} \stackrel{\text{def}}{=} a_{ij} + b_{ij}$$

kA as follows:

$$(kA)_{ij} \stackrel{\text{def}}{=} k \cdot a_{ij}.$$

Claim: The set of all $p \times q$ matrices
[with these operations is a vector space]

Let's check:

G2: the zero element for this $+$ is the zero matrix; $\begin{pmatrix} 0 & 0 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & 0 \end{pmatrix}_{p \times q}$

G3: The opposite of $A = (a_{ij})_{p \times q}^{p \times q}$ is $(-a_{ij})_{p \times q}$.

G1-G4, S1-S3 are satisfied.

ex: $F =$ set of all cont fncs

$[0, 1] \rightarrow \mathbb{R}$, with standard

$f + g$, kf operations, is
a vector space.

Multiplying matrices

Let $A_{p \times q}$ & $B_{q \times r}$ be two matrices.

ex: $\begin{pmatrix} 1 & 1 & 1 \\ 1 & 2 & 3 \end{pmatrix}_{2 \times 3} \cdot \begin{pmatrix} -1 & 0 \\ 0 & 2 \\ 1 & 3 \end{pmatrix}_{3 \times 2}$

defn $\begin{pmatrix} 1 \cdot (-1) + 1 \cdot 0 + 1 \cdot 1 & 1 \cdot 0 + 1 \cdot 2 + 1 \cdot 3 \\ 1 \cdot (-1) + 2 \cdot 0 + 3 \cdot 1 & 1 \cdot 0 + 2 \cdot 2 + 3 \cdot 3 \end{pmatrix}_{2 \times 2}$

$= \begin{pmatrix} 0 & 5 \\ 2 & 13 \end{pmatrix}_{2 \times 2}$

defn: Given $A_{p \times q}$ & $B_{q \times r}$, $A \cdot B$ is a $p \times r$ matrix given as:

$$(A \cdot B)_{ij} = \sum_{k=1}^q a_{ik} \cdot b_{kj}$$

Rmks. • You cannot multiply any pair of matrices!

- Let $A_{1 \times p}$ (a row vector)
& $B_{p \times 1}$ (a column vector)

$$A \cdot B = a_1 b_1 + \dots + a_p b_p \quad \left. \begin{array}{l} a_{1 \times 1} \\ \text{matrix} \end{array} \right\}$$

\downarrow \rightarrow $(a_1, \dots, a_p) \cdot \begin{pmatrix} b_1 \\ \vdots \\ b_p \end{pmatrix}$ (dot product in MATH102)

- $A_{p \times 1}, B_{1 \times q} : A \cdot B$ is $p \times q$.
- Is this operation associative?
That is, does it satisfy $\forall 1$?

ex: $\underbrace{(A_{p \times q} \cdot B_{q \times s})}_{\text{not even defined!}} \cdot C_{s \times t}$

claim: Using appropriate sizes, multiplication is associative.