

Last time,

□ linear combination; span

□ linear independence of vectors v_1, \dots, v_k

whenever $c_1 v_1 + \dots + c_k v_k = 0$ ($c_i \in \mathbb{R}$)

these c_i 's are forced to be zero.

□ basis of a vector space.

$u_1, \dots, u_n \in V$ is a basis if

- $V = \text{span}(u_1, \dots, u_n)$

- u_1, \dots, u_n are linearly independent.

□ dimension of V is the # of vectors in a basis.

ex. \mathbb{R}^n with $e_1 = \begin{pmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix}$, $e_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix}$, ..., $e_n = \begin{pmatrix} 0 \\ 0 \\ \vdots \\ 0 \\ 1 \end{pmatrix}$

because if for $c_i \in \mathbb{R}$

$c_1 e_1 + \dots + c_n e_n = 0$ then:

$$\begin{pmatrix} c_1 \\ 0 \\ \vdots \\ 0 \end{pmatrix} + \dots + \begin{pmatrix} 0 \\ \vdots \\ 0 \\ c_n \end{pmatrix} = \begin{pmatrix} 0 \\ \vdots \\ 0 \end{pmatrix} \Rightarrow$$

$$c_1 = 0$$

$$c_n = 0$$

Example for today: A 4×6

$$A \xrightarrow{\text{row reduction}} \begin{bmatrix} 1 & -1 & 0 & 2 & 3 & 1 \\ 0 & 0 & 1 & 1 & -1 & 0 \\ 0 & 0 & 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} = U$$

$x_1 \quad x_2 \quad x_3 \quad x_4 \quad x_5 \quad x_6$

Recall

$$(*) \quad F_{4 \times 4} \cdot A = U \quad \& \quad A = F^{-1} \cdot U$$

① $\boxed{\text{null}(A)} = \text{null}(U)$ because

fact 1. If $P = Q \cdot R$ & Q invertible
 [then $\text{null } P = \text{null } R$

$$\text{Now } \text{null}(U) = \{x \in \mathbb{R}^6 \mid Ux = 0\}$$

$$= \left\{ x_5 = -x_6, \quad x_3 = -x_4 - x_6, \quad x_1 = x_2 - 2x_4 + 3x_5 - x_6 \right\}$$

$$= \left\{ \begin{pmatrix} x_1 \\ \vdots \\ x_6 \end{pmatrix} = x_2 \begin{pmatrix} 1 \\ 1 \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} + x_4 \begin{pmatrix} -2 \\ 0 \\ 0 \\ 1 \\ 0 \\ 0 \end{pmatrix} + x_6 \begin{pmatrix} 2 \\ 0 \\ -1 \\ 0 \\ -1 \\ 1 \end{pmatrix} \right\}$$

$= U_2 \quad = U_4 \quad = U_6$

$$= \left\{ x \in \mathbb{R}^6 \mid x = x_2 u_2 + x_4 u_4 + x_6 u_6, \right. \\ \left. x_2, x_4, x_6 \in \mathbb{R} \right\}$$

$$= \text{span}(u_2, u_4, u_6)$$

Moreover u_2, u_4, u_6 are linearly independent: Assume for some

$$c_1, c_2, c_3 \in \mathbb{R} \quad c_1 u_2 + c_2 u_4 + c_3 u_6 = 0$$

$$\text{Then } \begin{cases} c_1 - 2c_2 + 2c_3 = 0 \\ c_1 = 0 \\ -c_2 - c_3 = 0 \\ c_2 = 0 \\ -c_3 = 0 \\ c_3 = 0 \end{cases} \Rightarrow \begin{cases} c_3 = 0 \\ c_2 = 0 \\ c_1 = 0. \end{cases}$$

thm 1. • A basis for $\text{null}(A)$ is the collection of vectors in \mathbb{R}^q found by the above algorithm.

$$\bullet \dim(\text{null}(A_{p \times q})) = \# \text{ of free variables} \\ = q - \# \text{ pivots}$$

The argument above proves also:
fact 2: The following collection is
 linearly independent:

$$\left[\begin{array}{c} 1 \\ 0 \\ \vdots \\ 0 \end{array} \right] \quad \left[\begin{array}{c} * \\ \vdots \\ * \\ 1 \\ 0 \\ \vdots \\ 0 \end{array} \right] \quad \left[\begin{array}{c} * \\ \vdots \\ * \\ 1 \\ 0 \end{array} \right]$$

Blue lines connect the first column to the second, and the second to the third, indicating a sequence of operations.

② $\boxed{\text{col}(A) = ?}$

ex: $\begin{pmatrix} 1 & 2 \\ 1 & 2 \end{pmatrix} \longrightarrow \begin{pmatrix} 1 & 2 \\ 0 & 0 \end{pmatrix}$

$\text{col} = \begin{pmatrix} 1 \\ 1 \end{pmatrix} \neq \text{col} = \text{span} \left(\begin{pmatrix} 1 \\ 0 \end{pmatrix} \right)$

Although $\text{col}(A) \neq \text{col}(U)$ in general,
 they are related as below:
 $\text{col}(U)$ has basis $\begin{pmatrix} 1 \\ 0 \end{pmatrix}$. $\text{col}(A)$ has basis $\begin{pmatrix} 1 \\ 1 \end{pmatrix}$.

$$\text{col}(U) = \text{span} \left(\begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} -1 \\ 0 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 6 \\ 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 2 \\ 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 3 \\ -1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \\ 1 \\ 0 \end{pmatrix} \right)$$

$$= \text{span} \left(\begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 6 \\ 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 3 \\ -1 \\ 1 \\ 0 \end{pmatrix} \right)$$

Moreover by fact 2, these constitute a basis. Hence we proved:

thm 2a. $\dim(\text{col}(U)) = \# \text{ pivots}$.

defn: rank of A is the $\#$ pivots

Then $\dim(\text{col}(U)) = r = \text{rank}(A)$.

What about $\text{col}(A)$?

Recall: $F \cdot A = U$, $A = F^{-1} \cdot U$.

By fact 1, $\text{null}(A) = \text{null}(U)$

i.e.

all possible linear combinations of the columns of A that give $\begin{pmatrix} 0 \\ \vdots \\ 0 \end{pmatrix}$ is the same as all possible linear combos of U that give $\begin{pmatrix} 0 \\ \vdots \\ 0 \end{pmatrix}$.

i.e.

If a nonzero linear comb of columns of U gives 0 then the same nonzero comb of columns of A gives 0 too (and vice versa)

i.e. the linearly indep set of columns of A is exactly the corresponding lin. indep columns of U .

thm 20. • The $\text{col}(A)$ has a basis which is constituted of the columns corresp to the columns of U that are basis for $\text{col}(U)$.

• $\dim(\text{col}(A)) = \dim(\text{col}(U)) = \text{rank}(A)$

In the example:

$\text{col}(U)$ has basis the 1st, 3rd & 5th columns (the ones with pivots)

So $\text{col}(A)$ has basis the 1st, 3rd, 5th columns of A .

$$\textcircled{3} \boxed{\text{row}(A)} = ?$$

= span of rows of A

= span of rows of $U = \text{row}(U)$

↓
because rows of U are lin. combos
of rows of A & vice versa.

An elegant way of saying this:

$F \cdot A = U$ is nothing but taking
linear combinations of rows of A
to produce rows of U .

In our example:

$$\text{row}(U) = \left(\begin{pmatrix} 1 \\ -1 \\ 0 \\ 2 \\ 3 \\ 1 \end{pmatrix}, \begin{pmatrix} 0 \\ 6 \\ 1 \\ 1 \\ -1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 6 \\ 0 \\ 6 \\ 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} \right)$$

\nearrow
 \mathbb{R}^6

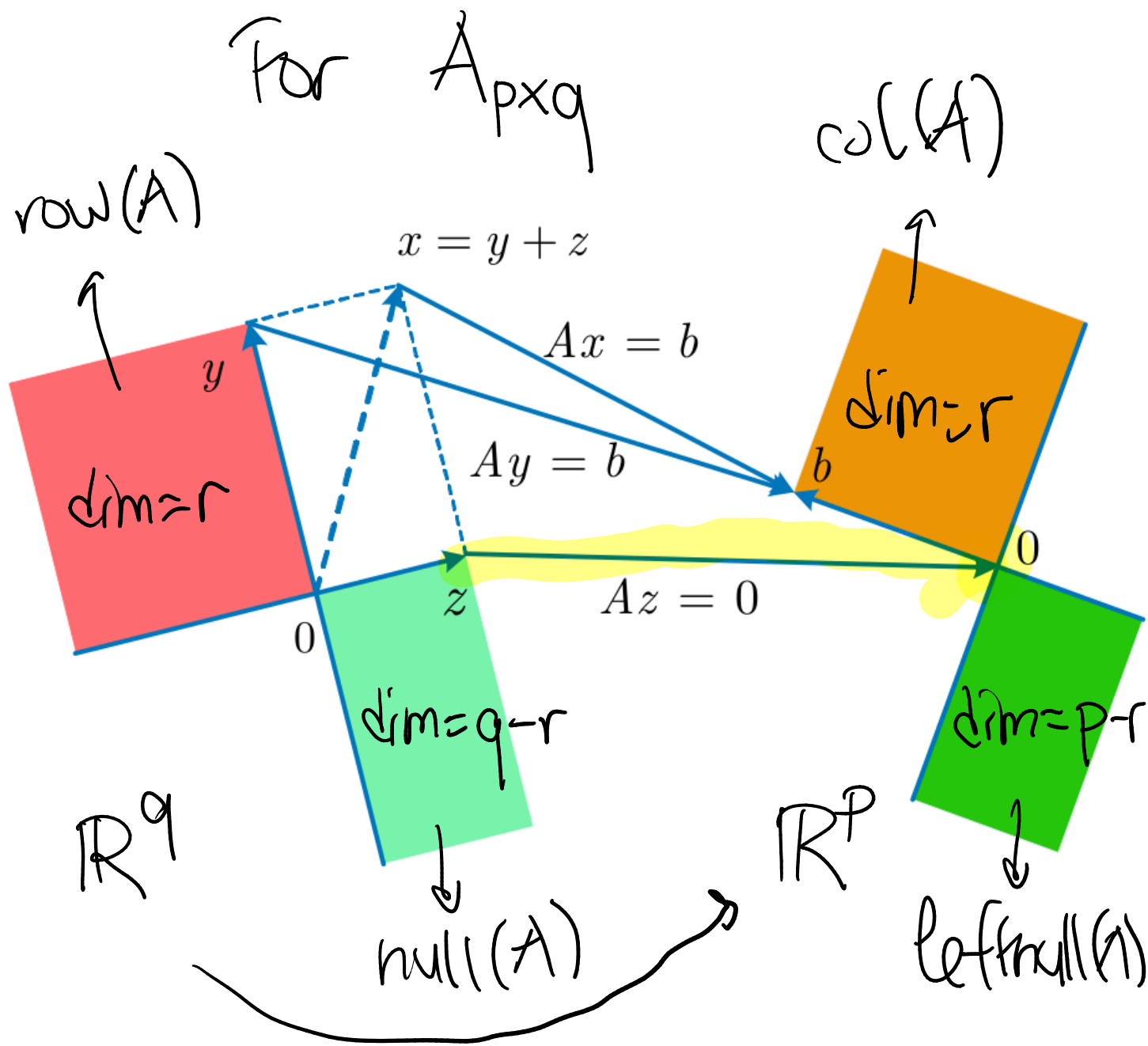
By fact 2, the first 3 rows are linearly independent. This proves:

thm 3 • $\text{row}(A)$ has basis the rows corresponding to the pivots.
• $\dim(\text{row}(A)) = r = \text{rank}(A)$.

Rank-Nullity Theorem (or the Fundamental Thm of Lin. Alg.)

(i) $\text{null}(A), \text{row}(A)$ are subspaces of \mathbb{R}^q with $\dim q-r$ & r respectively.

(ii) $\text{null}(A^T), \text{col}(A) \subset \mathbb{R}^p$ with dimensions $p-r$ & r respectively



Define $f: \mathbb{R}^q \rightarrow \mathbb{R}^p$, $f(x) = Ax$.

Observe: $\text{image}(f) = \text{col}(A)$

We'll see later:

- f sends $\text{row}(A)$ to $\text{col}(A)$ in a 1-1, onto fashion.
- $\text{row}(A)$ is orthogonal to $\text{null}(A)$

Dimension re(ally)-visited.

If there were two bases with different # of vectors then dimension would not be defined. We claim that is impossible.

thm 4. Let $V = \mathbb{R}^3$ be a vector space

& $(u_1, \dots, u_n), (v_1, \dots, v_k)$ be two bases. Then $n = k$ (so that dim. is well-defined).

proof. Suppose $n < k$ &

$$v_j = a_{1j}u_1 + \dots + a_{nj}u_n \text{ for each } j.$$

i.e.

$$\begin{pmatrix} v_1 \\ \vdots \\ v_k \end{pmatrix} = \begin{pmatrix} u_1 \\ \vdots \\ u_n \end{pmatrix} \begin{pmatrix} a_{11} & \dots & a_{k1} \\ \vdots & \ddots & \vdots \\ a_{1n} & \dots & a_{kn} \end{pmatrix}$$

Since $n < k$, $\dim \text{null}(A) = k - \text{rank}(A) \geq k - n > 0$; i.e.

$\text{null}(A) \neq \{0\}$; in particular, there is some $x \in \mathbb{R}^k$ s.t. $\text{RHS} \cdot x = 0$
 $0 \neq$

So $\text{LHS} \cdot x = 0 \Leftrightarrow$ the columns v_1, \dots, v_k are linearly dependent. This is a contradiction. To get rid of that we give up the assumption $n < k$. With similar argument for $n > k$, we get $n = k$.

