## 1 An analytical solution for two oscillator problem

We wish to construct an analytical solution for a decoupled two-oscillator system. We start by finding two separate solutions to one-oscillator systems and then use them to construct the solution to the two-oscillator case. Consider the Schrödinger equation

$$\dot{\psi} = -iH(t)\psi, \quad \psi(0) = \psi_0. \tag{1}$$

Solution 1: Suppose the Hamiltonian is given by

$$H(t) = H_1(t) = f(t)(a + a^{\dagger}), \quad a + a^{\dagger} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, \quad f(t) = \frac{1}{4}(1 - \cos(\omega t))$$
 (2)

An analytical solution is given by

$$\psi_1(t) = \begin{bmatrix} \cos(\phi(t)) \\ -i\sin(\phi(t)) \end{bmatrix}, \qquad \phi(t) = \frac{1}{4}(t - \frac{1}{\omega}\sin(\omega t))$$
 (3)

Check:

$$\dot{\psi}_1 = \frac{1}{4} (1 - \cos(\omega t)) \begin{bmatrix} -\sin(\phi) \\ -i\cos(\phi) \end{bmatrix} \tag{4}$$

$$-iH_1\psi_1 = \frac{-i}{4}(1 - \cos(\omega t)) \begin{bmatrix} 0 & 1\\ 1 & 0 \end{bmatrix} \begin{bmatrix} \cos(\phi)\\ -i\sin(\phi) \end{bmatrix} = \frac{1}{4}(1 - \cos(\omega t)) \begin{bmatrix} -\sin(\phi)\\ -i\cos(\phi) \end{bmatrix}$$
 (5)

**Solution 2**: Suppose the Hamiltonian is given by

$$H(t) = H_2(t) = ig(t)(a - a^{\dagger}), \quad a - a^{\dagger} = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}, \quad g(t) = \frac{1}{4}(1 - \sin(\omega t))$$
 (6)

An analytical solution is given by

$$\psi_2(t) = \begin{bmatrix} \cos(\theta(t)) \\ -\sin(\theta(t)) \end{bmatrix}, \qquad \theta(t) = \frac{1}{4}(t + \frac{1}{\omega}\cos(\omega t) - 1)$$
 (7)

Check:

$$\dot{\psi}_2 = \frac{1}{4} (1 - \sin(\omega t)) \begin{bmatrix} -\sin(\theta) \\ -\cos(\theta) \end{bmatrix}$$
 (8)

$$-iH_2\psi_1 = \frac{1}{4}(1-\sin(\omega t))\begin{bmatrix} 0 & 1\\ -1 & 0 \end{bmatrix}\begin{bmatrix} \cos(\theta)\\ -\sin(\theta) \end{bmatrix} = \frac{1}{4}(1-\sin(\omega t))\begin{bmatrix} -\sin(\theta)\\ -\cos(\theta) \end{bmatrix}$$
(9)

Constructing the two-oscillator solution: We now show that the solutions 1 and 2 can be used to solve eq (1) for the two-oscillator system given that  $\psi = \psi_1 \otimes \psi_2$  and the

Hamiltonian is described as  $H(t) = H_1(t) \otimes I_2 + I_2 \otimes H_2(t)$  where  $I_2$  is the 2 × 2 identity matrix.

$$\dot{\psi} = \dot{\psi}_1 \otimes \psi_2 + \psi_1 \otimes \dot{\psi}_2 = -i(H_1\psi_1 \otimes \psi_2 + \psi_1 \otimes H_2\psi_2) \tag{10}$$

$$H_{1}\psi_{1} \otimes \psi_{2} = f(t) \begin{bmatrix} -i\sin(\phi) \\ \cos(\phi) \end{bmatrix} \otimes \begin{bmatrix} \cos(\theta) \\ -\sin(\theta) \end{bmatrix} = f(t) \begin{bmatrix} -i\sin(\phi)\cos(\theta) \\ i\sin(\phi)\sin(\theta) \\ \cos(\phi)\cos(\theta) \\ -\cos(\phi)\sin(\theta) \end{bmatrix}$$

$$\psi_{1} \otimes H_{2}\psi_{2} = g(t) \begin{bmatrix} \cos(\phi) \\ -i\sin(\phi) \end{bmatrix} \otimes \begin{bmatrix} -i\sin(\theta) \\ -i\cos(\theta) \end{bmatrix} = -g(t) \begin{bmatrix} i\cos(\phi)\sin(\theta) \\ i\cos(\phi)\cos(\theta) \\ \sin(\phi)\sin(\theta) \\ \sin(\phi)\sin(\theta) \\ \sin(\phi)\cos(\theta) \end{bmatrix}$$
(11)

$$\psi_{1} \otimes H_{2} \psi_{2} = g(t) \begin{bmatrix} \cos(\phi) \\ -i\sin(\phi) \end{bmatrix} \otimes \begin{bmatrix} -i\sin(\theta) \\ -i\cos(\theta) \end{bmatrix} = -g(t) \begin{vmatrix} i\cos(\phi)\sin(\theta) \\ i\cos(\phi)\cos(\theta) \\ \sin(\phi)\sin(\theta) \\ \sin(\phi)\cos(\theta) \end{vmatrix}$$
(12)

where we have substituted solutions 1 and 2 in the second equality of (10). Now looking at the right hand side:

$$-iH\psi = -i \begin{bmatrix} 0 & ig(t) & f(t) & 0 \\ -ig(t) & 0 & 0 & f(t) \\ f(t) & 0 & 0 & ig(t) \\ 0 & f(t) & -ig(t) & 0 \end{bmatrix} \begin{bmatrix} \cos(\phi)\cos(\theta) \\ -\cos(\phi)\sin(\theta) \\ -i\sin(\phi)\cos(\theta) \\ i\sin(\phi)\sin(\theta) \end{bmatrix}$$
(13)

it holds that  $-i(H_1\psi_1\otimes\psi_2+\psi_1\otimes H_2\psi_2)=-i(H_1\otimes I_2+I_2\otimes H_2)(\psi_1\otimes\psi_2)$  and therefore  $\dot{\psi} = -iH\psi.$ 

**Density Matrix:** From here we can construct the corresponding density matrix

$$\rho(t) = \psi(t)\psi^{\dagger}(t), \quad \psi = \begin{bmatrix} \cos(\phi)\cos(\theta) \\ -\cos(\phi)\sin(\theta) \\ -i\sin(\phi)\cos(\theta) \\ i\sin(\phi)\sin(\theta) \end{bmatrix}$$
(14)

$$\rho(t) = \begin{bmatrix}
\cos(\phi)\cos(\theta) \\
-\cos(\phi)\sin(\theta) \\
-i\sin(\phi)\cos(\theta) \\
i\sin(\phi)\sin(\theta)
\end{bmatrix} [\cos(\phi)\cos(\theta), -\cos(\phi)\sin(\theta), i\sin(\phi)\cos(\theta), -i\sin(\phi)\sin(\theta)]$$

$$= \begin{bmatrix}
\cos^{2}(\phi)\cos^{2}(\theta) & * & * & * \\
* & \cos^{2}(\phi)\sin^{2}(\theta) & * & * \\
* & * & \sin^{2}(\phi)\cos^{2}(\theta) & * \\
* & * & \sin^{2}(\phi)\sin^{2}(\theta)
\end{bmatrix} (15)$$