The adjoint method and the trace objective function

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The state equation

The state equation for $\Psi^{lpha}_j \in \mathbb{C}^N$ is

$$\dot{\Psi}_{j}^{\alpha}+iH(t,\alpha)\Psi_{j}^{\alpha}=0,\quad 0\leq t\leq \mathcal{T},\quad \Psi_{j}^{\alpha}(0)=\mathbf{e}_{j},$$

where the Hamiltonian matrix is $H(t, \alpha) = H_0 + p(t, \alpha)H_1 = H^*$ and \mathbf{e}_i is the j^{th} unit base vector.

The real-valued function $p(t, \alpha)$ depends on the control parameters

$$\boldsymbol{\alpha} = [\alpha_1, \alpha_2, \dots, \alpha_D]^T.$$

The quantity $\Phi_{jk}^{\alpha} = \partial \Psi_{j}^{\alpha}/\partial \alpha_{k}$ satisfies

$$\dot{\Phi}^{\alpha}_{jk} + iH(t,\alpha)\Phi^{\alpha}_{jk} = -i\frac{\partial H(t,\alpha)}{\partial \alpha_k}\Psi^{\alpha}_j, \quad \Phi^{\alpha}_{jk}(0) = 0,$$

for $0 \le t \le T$.

The objective functional

Desired target gate after time T,

$$\Psi^{t}(T) := [\mathbf{d}_{1}, \mathbf{d}_{2}, \dots, \mathbf{d}_{N}] =: G_{t}, \ G_{t}^{*} G_{t} = I.$$

The control parameters lpha result in the state

$$\mathbf{\Psi}^{\alpha}(t) = [\Psi^{\alpha}_1(t), \Psi^{\alpha}_2(t), \dots, \Psi^{\alpha}_{N}(t)] = \mathcal{G}_{\alpha}(t).$$

The distance between $G_{\alpha}(t)$ and G_t , in a weighted norm, with a weight function $0 \le w(t) \le 1$, w(0) = 0, w(T) = 1,

$$g_2(\mathbf{\Psi}^{\alpha}) = \int_0^T w(\tau) \left(1 - \frac{1}{N^2} S(\tau) \bar{S}(\tau)\right) d\tau.$$

The gate fidelity is measured using the Frobenius matrix scalar product,

$$S(au) = \sum_{j=1}^N \langle \Psi_j^lpha(au), \mathbf{d}_j
angle.$$

The gradient of the objective functional

$$\begin{split} \frac{\partial g_2}{\partial \alpha_k} &= -\frac{2}{N^2} \mathrm{Re} \int_0^T w(\tau) \frac{\partial S(\tau)}{\partial \alpha_k} \bar{S}(\tau) \, d\tau \\ &= -\frac{2}{N^2} \mathrm{Re} \int_0^T w(\tau) \sum_{j=1}^N \left\langle \frac{\partial \Psi_j^{\alpha}(\tau)}{\partial \alpha_k}, \mathbf{d}_j \right\rangle \bar{S}(\tau) \, d\tau \\ &= -\frac{2}{N^2} \mathrm{Re} \sum_{j=1}^N \int_0^T w(\tau) \left\langle \frac{\partial \Psi_j^{\alpha}(\tau)}{\partial \alpha_k}, \bar{S}(\tau) \mathbf{d}_j \right\rangle \, d\tau \\ &= -\frac{2}{N^2} \mathrm{Re} \sum_{j=1}^N \int_0^T \left\langle \Phi_{jk}(\tau), w(\tau) \bar{S}(\tau) \mathbf{d}_j \right\rangle \, d\tau \end{split}$$

where $\Phi_{jk} = \partial \Psi_i^{\alpha}/\partial \alpha_k$ and k = 1, 2, ..., D.

The state and adjoint equations

Let $\Phi_{jk} = \partial \Psi^{\alpha}_{j}/\partial \alpha_{k}$. It satisfies the state equation

$$\dot{\Phi}_{jk}+iH\Phi_{jk}=\mathbf{f}_{jk}(t),\quad \Phi_{jk}(0)=0,$$

where $\mathbf{f}_{jk}(t) = -i(\partial H/\partial \alpha_k)\Psi_j^{\alpha}$. The adjoint equation is

$$-\dot{\lambda}_j - iH\lambda_j = \mathbf{h}_j(t), \quad \lambda_j(T) = 0.$$

where we choose

$$\mathbf{h}_j(t) = w(t)\bar{S}(t)\mathbf{d}_j, \quad j = 1, 2, \dots, N.$$

Note that the adjoint equation satisfies terminal conditions and is solved backwards in time, $T \ge t \ge 0$.

The adjoint relation

By integration by parts in time and using the initial and terminal conditions, it is straighforward to derive the adjoint relation,

$$\int_0^T \langle \Phi_{jk}(au), \mathbf{h}_j(au)
angle \, d au = \int_0^T \langle \mathbf{f}_{jk}(au), oldsymbol{\lambda}_j(au)
angle \, d au.$$

By combining the above results,

$$\frac{\partial g_2}{\partial \alpha_k} = -\frac{2}{N^2} \operatorname{Re} \sum_{j=1}^N \int_0^T \langle \Phi_{jk}(\tau), \mathbf{h}_j(\tau) \rangle d\tau$$

$$= +\frac{2}{N^2} \operatorname{Re} \sum_{j=1}^N \int_0^T \langle i \left(\frac{\partial H}{\partial \alpha_k} \right) \Psi_j^{\alpha}(\tau), \lambda_j(\tau) \rangle d\tau.$$

Without adjoint: solve N state equations for Ψ_j^α and ND state equations for Φ_{jk} ; total solves: =(D+1)NWith adjoint: solve N state equations for Ψ_j^α and N adjoint equations for λ_j ; ; total solves: =2N