Nissan Logo Area - Magbutay (FINAL)

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```
[1]: import random import numpy as np import time
```

1 For the Circle

```
[2]: def MC(func, a, b, n):
    f = func
    x = np.random.uniform(a, b, n)
    w = b - a
    return w * sum(f(x))/n
```

```
[3]: def area_circ_segment(x): return np.sqrt(R**2 - x**2) - x**0 * R * np.cos(theta/2)
```

```
[4]: Area_Circle = []
     for i in range(100000):
         # Calculating for the outer radius
         R = 25
         h = 15
         theta = 2 * np.arccos(1-h/R)
         a = -R * np.sin(theta/2)
         b = R * np.sin(theta/2)
         A_outerrad = MC(func=area_circ_segment, a = a, b=b, n=100000)
         # Calculating for the inner radius
         R = 20
         h = 10
         theta = 2 * np.arccos(1 - h/R)
         a = -R * np.sin(theta/2)
         b = R * np.sin(theta/2)
         A_innerrad = MC(func = area_circ_segment, a = a, b = b, n=100000)
```

```
Area_Circle.append(2*(A_outerrad - A_innerrad))
```

```
[5]: mean_Circle = np.mean(Area_Circle)
    sd_Circle = np.std(Area_Circle)
    print(f'Circular portion is determined to be: {mean_Circle}mm^2 with a standard
    →deviation of {sd_Circle}mm^2')
```

Circular portion is determined to be: $499.5052330561189mm^2$ with a standard deviation of $0.705686929886594mm^2$

2 For the rectangle

```
[6]: def PointInRectangle(x,y, Cx, Cy):
    if (x < Cx) and (y < Cy):
        return True
    return False

def approxRectangleArea(Cx, Cy, points):
    x_enclosed = Cx + 0.01
    y_enclosed = Cy + 0.01
    pointsInside = 0
    for i in range(points):
        x = np.random.random() * x_enclosed
        y = np.random.random() * y_enclosed
        if PointInRectangle(x,y,Cx,Cy):
            pointsInside = pointsInside + 1
    return pointsInside / points * (Cx * Cy)</pre>
```

Area of the rectangle is determined to be: $1399.1031879999998mm^2$ with a standard deviation of $0.3510324153921341mm^2$

3 For the whole area