

DiDi Rescheduling

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Abstract—This thesis explores a car rescheduling solution based on the data set provided by DiDi.

I. INTRODUCTION

Since the shared economy stepped into our life, it has been common to choose DiDi taxi as one of the means of the daily transportation. Therefore it is of great significance for DiDi to explore an efficient method to schedule the cars for the purpose of saving more time while making more income.

The main results and contributions of this report are summarized as follows:

- **Initially modeling**
- **Reframing**
- **Resolution and optimization.**
- **Summary.**

II. INITIALLY MODELING

(i) Assumption

Provided with datasets of the *GPS path* and *order information* of DiDi taxi in Chengdu on a certain day, we firstly come up with an idea about **clustering**, which can be illustrated in Fig.1. On such a heat map, the region in the big red circle can be designated as **busy**, while that in the yellow circle can be regarded as a **vacant** region.

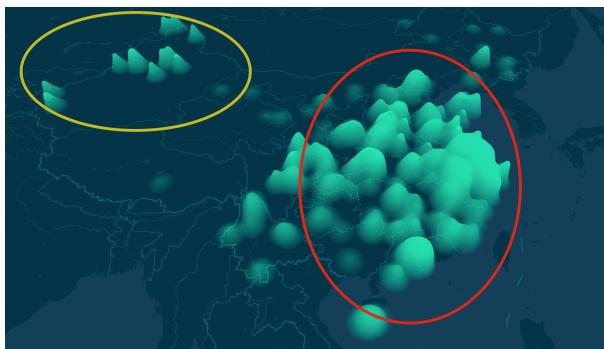


Fig. 1. The assumed heat map

In our assumption, if we plot the start point and the end point of each car in the *order dataset* on the map, the heat distribution should be like Fig.1. Then, from the backend of DiDi, a message can be sent to the drivers in the red region, which may say, would you like to go to region yellow where cars may be needed?

(ii) Data visualization

After we plotting all the GPS points from *order dataset*, things are not going as we like. The visualization result is shown below.



Fig. 2. The real heat map (2D)

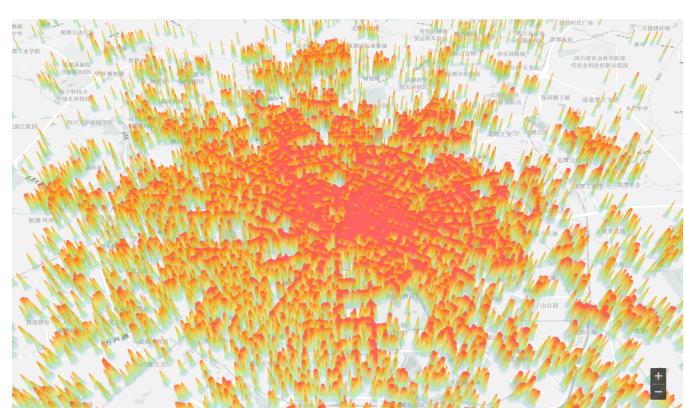


Fig. 3. The real heat map (3D)

It is not much obvious that the gathered clusters scattered over the whole city, rather, the density of the center is reasonably high, but the radiation seems to be uniformly distributed. Therefore our previous assumption is **trivial** and **should be reframed**.

III. REFRAMING

(i) Reframed assumption

Although the previous assumption is really frustrating as it seems, it enlightens us to think about the regions. Since we

cannot reach the conclusion that the *orders* have some kind of tendency to cluster together, we reframed our assumption based on the views of those DiDi drivers, that is, what if it is not the density of orders but the preferred region of the drivers that matters.

(ii) Visualization again

Following this intuition, we then plot the *GPS route point* for each driver to see what is going on with the *GPS path database*. For each driver, we set the *Driver IDs* as the control variable. Then for each *Driver ID*, we record every *route point* of every *Order ID*. Finally, the map with all the *route points* of every driver should be able to generate the **active zones** of every single one of those drivers. Part of the processed data is shown below in Fig.4.

Fig. 4. drivers with their route points

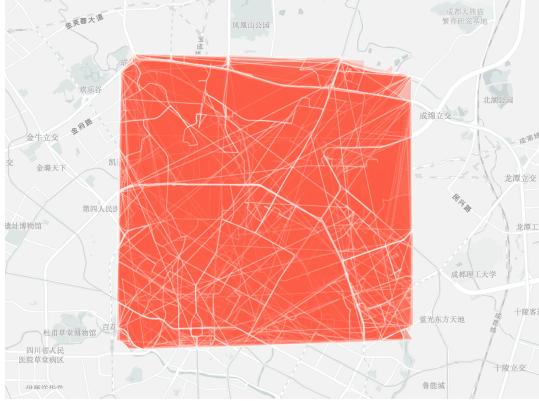


Fig. 5. preferred regions of all the drivers

As we can see in Fig.5, it is totally a mess because the large database elicit a situation where all of those regions overlap and the API cannot provide us so many colors to clarify different preferred regions of different *DriverIDs*. To make it much more lucid, we choose 7 regions from it and recolor them as Fig.6 below.



Fig. 6. preferred regions of 7 drivers

Fig.6 above shows that different drivers indeed have different routes. We may basically attribute the fact that the active zone differs from driver to driver to several reasons, their homes, their familiarity of the region, etc. From the view of the customers, we simply want to get to the location comfortably and especially quickly. Hence, the familiarity of the regions is quite important. Since those regions are both familiar and the active zones of those drivers, we simply defined those colored regions as **preferred regions** for each driver.

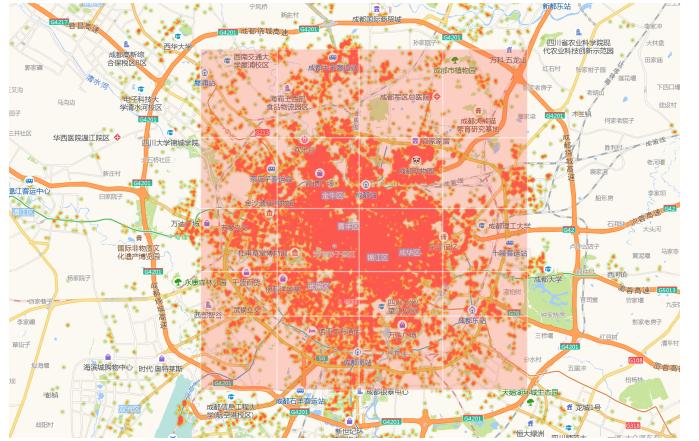


Fig. 7. heat map with a rectangle

Back to the previous heat map(Fig.2), we roughly overlay a rectangle onto it to make most of the heat points inside (we choose a rectangle rather a circle to make the prototype model simple), as illustrated in Fig.7. The big rectangle is divided into 5×4 sub-rectangles. And when Fig.6 and Fig.7 are combined together, as Fig.8, it can be found that one single driver' **preferred region** intersect with one or several sub-rectangles. For example, the blue **preferred region** mainly intersects sub-rectangles in (2,2), (2,3), (3,2).

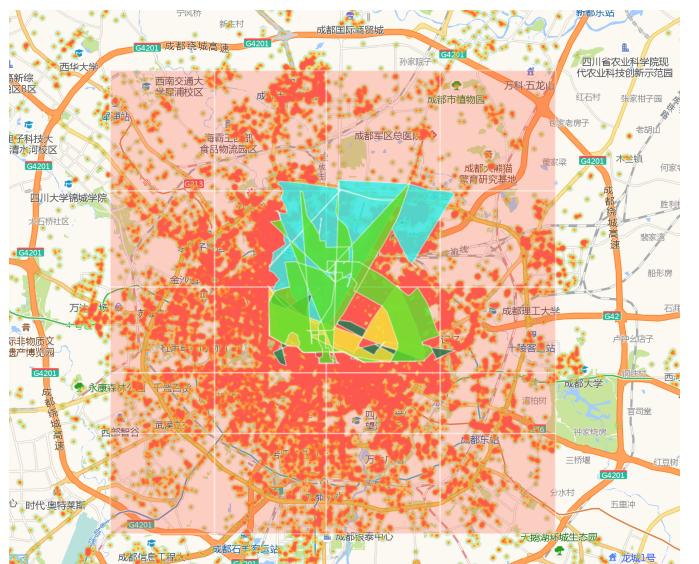


Fig. 8. preferred regions of 7 drivers plus the heat map and the rectangle

IV. RESOLUTION AND OPTIMIZATION

(i) Algorithm

According to Fig.8, the numbers of cars in each sub-rectangle can be obtained, which can be regarded as the **historical number of needed cars**. Suppose we can acquire the **real-time number of cars** in each sub-rectangle, then we can know whether the sub-rectangle needs the car or has more cars.

We implement two priority queues. **Priority queue I** is for the sub-rectangles which need cars and **Priority queue II** is for the sub-rectangles which have more cars. Then we decide each sub-rectangle belongs to which priority queue, and insert it into one of these two priority queue.

Every ten seconds, we pop the sub-rectangle with the highest priority. Firstly, it should be determined whether these two sub-rectangles are far. If so, we pop one more sub-rectangle from **priority queue II** and push the first popped sub-rectangle from **priority queue II** back to it. Such a loop lasts until 2 close enough(may need a threshold here) sub-rectangles are found.

The sub-rectangle from **Priority queue I** is designated as **target**, while that from **Priority queue II** is designated as **source**. The next step is to find all the cars in the **source**, if there is a car whose driver's **preferred region** intersects with **target**, a message will be sent to notify the driver, which may say, would you like to go to xxx, you may get more orders there. **The control flow is shown in Fig.9.**

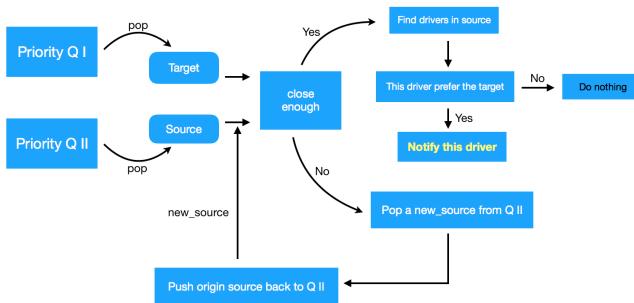


Fig. 9. the car object implementation

And after that, we update these two priority queues.

(ii) Implementation

As for the implementation, the 2 main Objects are shown below in Fig.10 and Fig.11. It should be noted that what we call sub-rectangle is implemented as **class Region** for the further generalization.

```

class Car:
    def __init__(self, available, now_region, preferred_region, name):
        self.available = available
        self.now_region = now_region
        self.preferred_region = preferred_region
        self.name = name
        self.to_go = -1

    def whether_can_go(self, wanted_region):
        if (self.available):
            if (abs(self.now_region-wanted_region)+abs(self.now_region-wanted_region))<=4:
                if (wanted_region in self.preferred_region):
                    if (self.to_go==1):
                        return True
                    else:
                        return False
                else:
                    return False
            else:
                return False
        else:
            return False
  
```

Fig. 10. the car object implementation

```

class Region:
    def __init__(self, predicted_car, region1, now_car=[]):
        self.predicted_car = predicted_car
        self.now_car = now_car
        self.need_car = abs(predicted_car-len(now_car))
        self.region = region1

    def lack_or_more(self):
        if (self.predicted_car<self.now_car):
            return False, len(self.now_car)-self.predicted_car
        else:
            return True, self.predicted_car-len(self.now_car)

    def add_car(self, car):
        self.now_car.append(car)
        self.need_car -= 1
  
```

Fig. 11. the region object implementation

V. SUMMARY

(i) Conclusion

Through our optimized resolution, the scheduling of DiDi cars can be somehow more balanced. The goal of making more income while saving more time is primarily achieved.

(ii) Some Flaws

- In previous part, we adopted rectangles as divided regions, which lacks generalization.
- The execution of our algorithm consists of obtaining and processing the real-time data, which may cost a giant time complexity.

ACKNOWLEDGMENT

During this project, we collaborated and discussed within a group of classmates Fengming Zhu, Yucong Zhang, Weikai Xu, Ziqi Han and Ming Zhong. The data is from DiDi. We also refer to some contents from Gaode API [?].