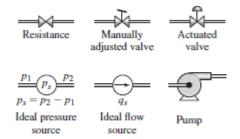
## **Control y Sistemas**

# Trabajo práctico: Modelado de sistemas hidráulicos

## Referencias de símbolos



Realice los siguientes ejercicios en Simscape.

1)

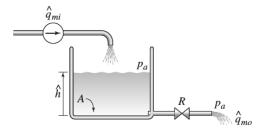
## **EXAMPLE 7.4.3**

Liquid-Level System with a Flow Source

### **■ Problem**

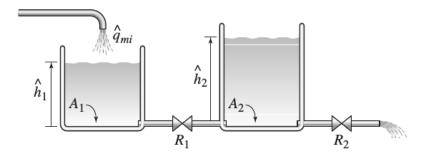
The cylindrical tank shown in Figure 7.4.3 has a bottom area A. The total mass inflow rate from the flow source is  $\hat{q}_{mi}(t)$ , a given function of time. The total mass outflow rate  $\hat{q}_{mo}$  is not given and must be determined. The outlet resistance R is the linearized resistance about the reference condition  $(h_r, q_{mir})$ . Develop a model of h, the deviation of the liquid height from the constant reference height  $h_r$ , where  $\hat{h} = h_r + h$ .

**Figure 7.4.3** A liquid-level system with a flow source.



2)

7.23 (a) Develop a model of the two liquid heights in the system shown in Figure P7.23. The inflow rate  $q_{mi}(t)$  is a mass flow rate. (b) Using the values  $R_1 = R$ ,  $R_2 = 3R$ ,  $A_1 = A$ , and  $A_2 = 4A$ , find the transfer function  $H_2(s)/Q_{mi}(s)$ .



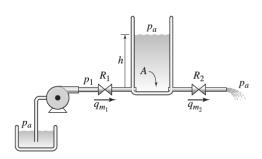
3)

### **EXAMPLE 7.4.10**

A Liquid-Level System with a Pump

#### **■ Problem**

Figure 7.4.12 shows a liquid-level system with a pump input and a drain whose linear resistance is  $R_2$ . The inlet from the pump to the tank has a linear resistance  $R_1$ . The resistances were linearized about the reference height h = hr. Obtain a linearized model of the liquid height h.



**Figure 7.4.12** A liquid-level system with a pump.

7.28 In Figure P7.28 the piston of area A is connected to the axle of the cylinder of radius R, mass m, and inertia I about its center. Develop a dynamic model of the axle's translation x, with the pressures  $p_1$  and  $p_2$  as the inputs.

