

Integration - Volume (Region under, or above)

Volume under $y = f(x)$ over R is $\int_a^b f(x) dx$

Volume above $y = g(x)$ over R is $\int_a^b [f(x) - g(x)] dx$

$$\begin{aligned} U_1(t) - U_2(t) &= \left(\frac{t}{2} + \frac{t^2}{2} \right) \int_0^t (x-2)(y-2) dx \\ &= \left(\frac{t}{2} + \frac{t^2}{2} \right) \int_0^t (x-2)(t-x) dx = \left(\frac{t}{2} + \frac{t^2}{2} \right) \frac{1}{2}(x-2)(t-x) \Big|_0^t \\ &= \left(\frac{t}{2} + \frac{t^2}{2} \right) \frac{1}{2}(t-2)(t-2) = \frac{1}{2}(t-2)^2(t+2) \end{aligned}$$

$$U_1(t) - U_2(t) = \left(\frac{t}{2} + \frac{t^2}{2} \right) \int_0^t (x-2)(y-2) dx$$

$$= \left(\frac{t}{2} + \frac{t^2}{2} \right) \int_0^t (x-2) dx = \left(\frac{t}{2} + \frac{t^2}{2} \right) \frac{1}{2}(x-2) \Big|_0^t = \frac{1}{2}(t-2)^2(t+2)$$

$\rightarrow t$ is increasing w.r.t.

$$(x,y) \text{ s.t. } y = \text{sq}(t), t_1 = \text{Int}(U_1(t)) = \frac{1}{2}(t-2)^2(t+2)$$

DEFINITION Integrals

Example: $\int_0^1 (x^2 + 2x) dx$ \rightarrow x for function $f(x) = x^2 + 2x$

$$\int_0^1 (x^2 + 2x) dx = \int_0^1 (x^2 + 2x) dx = \left[\frac{x^3}{3} + 2x^2 \right]_0^1 = \frac{1}{3} + 2 = \frac{7}{3}$$

$\Rightarrow \int_0^1 (x^2 + 2x) dx = \frac{7}{3} + 2 = \frac{13}{3}$

$$\int_0^1 g(y) dy = \int_0^1 \left(\frac{g(x)}{x} + 2x^2 \right) dx = \int_0^1 \left(\frac{g(x)}{x} + 2x^2 \right) dx =$$

$$\rightarrow \frac{1}{2}(x^2) \Big|_0^1 + \frac{1}{2}(2x^3) \Big|_0^1$$

$$I_1 = \int_0^1 \left(\frac{g(x)}{x} \right) dx ; I_2 = \int_0^1 \left(2x^2 \right) dx$$

Two Definitions of Riemann Integral, then the Intermediate Value Theorem

$$I_1 = \int_0^1 \left(\frac{g(x)}{x} \right) dx \text{ or } I_2 = \int_0^1 \left(2x^2 \right) dx \text{ EMT}$$

Int. Val. Theorem: If f is continuous on $[a,b]$, then there exists $c \in (a,b)$ such that $f(c) = \text{Int}(f)$.

$$\text{Int}(f) = \lim_{n \rightarrow \infty} \sum_{i=1}^n f(x_i^*) \Delta x_i$$

$$\text{Int}(f) = \lim_{n \rightarrow \infty} \sum_{i=1}^n f(x_i^*) \Delta x_i = \lim_{n \rightarrow \infty} \sum_{i=1}^n f(x_i^*) \Delta x_i$$

$$\rightarrow f(x^*) \text{ is constant in } [a,b] \rightarrow f(x^*) = \text{constant}$$

$$\text{Int}(f) = f(x^*) \Delta x = f(x^*) (b-a) \rightarrow f(x^*) = \text{constant}$$

Two functions are continuous on R , then the difference is also

$f(x) = \int_a^x g(t) dt$ \rightarrow $f(x)$ is continuous on $[a,b]$

$\text{Int}(f) = \int_a^b f(x) dx = \int_a^b \left(\int_a^x g(t) dt \right) dx = \int_a^b g(t) dt$

$$\rightarrow \int_a^b g(t) dt = \int_a^b f(x) dx = \text{constant}$$

$$\text{Int}(f) = f(b) - f(a) = \text{constant}$$

Two functions are continuous on R , then the difference is also

$f(x) = \int_a^x h(t) dt$ \rightarrow $f(x)$ is continuous on $[a,b]$

$\text{Int}(f) = \int_a^b f(x) dx = \int_a^b \left(\int_a^x h(t) dt \right) dx = \int_a^b h(t) dt$

$$\rightarrow \int_a^b h(t) dt = \int_a^b f(x) dx = \text{constant}$$

If $A \in M_n(\mathbb{R})$ is symmetric,

then exists

A is symmetric matrix
 $M_n(\mathbb{R})$ the linear map
 $\rightarrow Ax \in \mathbb{R}^n$ has
 $t = A$, so $t = f^*$
 is in O.N.B $B = (v_1, \dots, v_n)$

s.t. $[f]_{B,B}$ is diagonal.

If $P = (v_1 | \dots | v_n) \in M_n(\mathbb{R})$

then P is an orthogonal matrix

$$P^T [f]_{B,B} P = [f]_{B,B}$$

$$P^T A P \quad \text{D diagonal}$$

$$A = P D P^T \quad \text{factorization of } A$$

* If $A \in M_n(\mathbb{R})$ is symmetric,

then exists an orthogonal

$P \in M_n(\mathbb{R})$ and a diagonal

$D \in M_n(\mathbb{R})$ s.t.

$$A = P D P^T$$

If $A \in M_n(\mathbb{R})$ s.t. $A = P D P^T$
 with D diagonal and P orthogonal,

$$\text{then } A^T = (P D P^T)^T = P^T D^T P^T$$

$$= P D P^T = A \quad \text{so } A \text{ is symm.}$$

(singular value decomposition)

then (SVD factorization)

If $A \in M_n(\mathbb{R})$, then there

exist matrices $U, V \in O(n)$

and a diagonal matrix $D \in M_n(\mathbb{R})$

$$\text{s.t. } A = U D V^T$$

$$D = \begin{pmatrix} \lambda_1 & & 0 \\ 0 & \ddots & \\ 0 & & \lambda_n \end{pmatrix} \quad \text{the } \lambda_i \text{ are called singular values for } A$$

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* If $A \in M_n(\mathbb{R})$ is symmetric,

then exists an orthogonal

$P \in M_n(\mathbb{R})$ and a diagonal

$D \in M_n(\mathbb{R})$ s.t.

$$A = P D P^T$$

$$\overbrace{n=3} \cdot P = (v_1 | v_2 | v_3) \quad D = \begin{pmatrix} \lambda_1 & & \\ & \lambda_2 & \\ & & \lambda_3 \end{pmatrix}$$

$$A = P D P^T = (v_1 | v_2 | v_3) \begin{pmatrix} \lambda_1 & & \\ & \lambda_2 & \\ & & \lambda_3 \end{pmatrix} \left(\frac{v_1^T}{\|v_1\|^2} \right)$$

$$= (v_1 | v_2 | v_3) \left[\begin{pmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_2 & 0 \\ 0 & 0 & \lambda_3 \end{pmatrix} + \begin{pmatrix} 0 & \lambda_1 & 0 \\ \lambda_1 & 0 & 0 \\ 0 & 0 & \lambda_3 \end{pmatrix} + \begin{pmatrix} 0 & 0 & \lambda_3 \\ 0 & 0 & \lambda_1 \\ 0 & \lambda_1 & 0 \end{pmatrix} \right] \left(\frac{v_1^T}{\|v_1\|^2} \right)$$

$$= (v_1 | v_2 | v_3) \left(\begin{pmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_2 & 0 \\ 0 & 0 & \lambda_3 \end{pmatrix} + \frac{v_1^T}{\|v_1\|^2} v_1 v_1^T \right) + \dots$$

$$= \lambda_1 \underbrace{v_1 v_1^T}_{w_1^T} + \lambda_2 \underbrace{v_2 v_2^T}_{w_2^T} + \lambda_3 \underbrace{v_3 v_3^T}_{w_3^T}$$

$$w_1^T \quad w_2^T \quad w_3^T$$

If $v \in \mathbb{R}^n \setminus \{0\}$, then $v \cdot v^T$

has rank 1, and every

rank 1 matrix of that form

$$v_1 \quad v_2 \quad v_3$$