Software Engineering Project

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Outline

- Tools and resources
- Methodology
- ullet C++ implementation
- Matlab implementation



Tools and resources

IDE

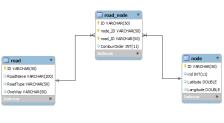
- Qt 5.1 with OpenGL
- Matlab 2013Ra

Group meetings and coordination

- Trello
- Git and Bitbucket

Database

- MySQL Server 5.6
- PostgreSQL



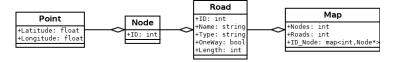






C++ Implementation

Main Structure:



- Loaded in memory through QMYSQL Driver
- Displayed using GL_STRIPES of OpenGL
- Creation of a map of ID_Node* because of the complexity
 - Avoiding Queries
 - Avoiding double loops



C++: Dijkstra's algorithm

- Other kind of algorithms:
 - Bellman-Ford and SPFA
 - Jonhson's algorithm
 - Floyd-Warshall algorithm
 - Dijkstra's algorithm
- Why? Performs better with non negative values
- How it works?
 - **1** Initialize D to 0 in the diagonal and ∞ in non connected nodes
 - 2 Suppose that a = x (current node)
 - Oheck all adjacent nodes of a except the ones that are marked
 - **4** If $(D_i > D_a + d(a, v_i))$ then, $D_i = D_a + d(a, v_i)$
 - Marked as completed the node a
 - We take as next current node the smaller in D
 - Go back to step 3 until there are nodes not marked



C++: Adjacency Matrix

• Sparse Matrix of the Euclidean distance between nodes (Eigen library)

0	3	0	0	0	
22	0	0	0	17	
7	5	0	1	0	
0	0	0	0	0	
0	0	14	0	8	

Results measured under Debug mode and dependent on the performance of each processor

Values:	22	7	3	5	14	1	17	8
InnerIndices:	1	2	0	2	4	2	1	4

Table 1: Sum up of the benefits of Sparse matrices

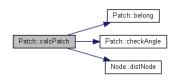
	Matrix	Sparse
Num. nodes	$\simeq 84.10^{6}$	$\simeq 16.10^{3}$
Memory	\simeq 336 MB	≃64 KB + Zero vector
Time	>30 sec	<1 sec
Dijkstra	>30 sec	<3 sec



Route path

- Functions:
 - Path calculation
 - Distance and time
 - Export
- General case:

Same road \rightarrow NO \rightarrow Angle < 180 \rightarrow Right Same road \rightarrow NO \rightarrow Angle > 180 \rightarrow Left Same road \rightarrow YES \rightarrow Distance



 $\label{eq:Figure:Functions} \mbox{Figure: Functions involved in the route path calculation}$

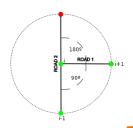


Figure : Example of road intersection

Heuristics



Normalization and displaying



Selecting a route



Matlab implementation

Getting the data

- PostgreSQL database
- Queries were made only once.
- Created objects can be saved in .MAT files
- No need to recreate object on each program start



Matlab implementation

Data Structure

- Objects of 4 classes were constructed.
- No pointers in Matlab.
- Solution: handle classes.



Figure : Simplified diagram of relationship of a classes

Matlab implementation

The shortest path

- Dijkstra's algorithm
- Determine the window on which the closest nodes and projections will be searched.
- Find the closest node on determined window.
- Find the closest projection (if possible) on the same window.
- Update the adjacency matrix according shortest distance.

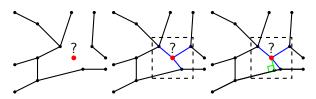
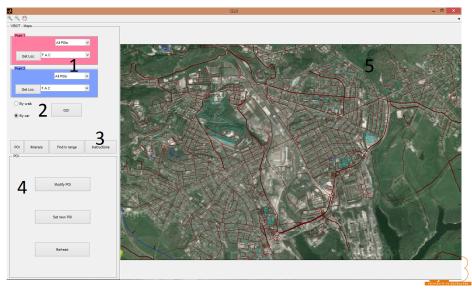


Figure: Finding the shortest point/projection for the random point on window domain

Graphical User Interface (GUI)



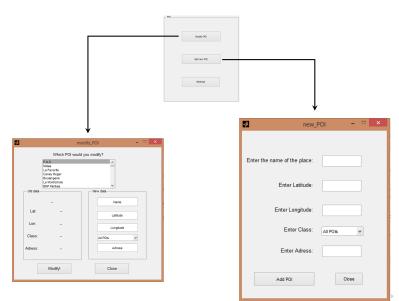
Insertion of points

- Point from a list
- Filter by class
- Get Location from the map
- Walk / Car
- GO!





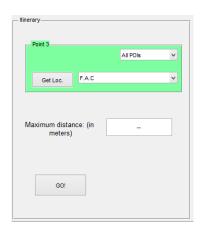
Manipulating Points of interest





Itinerary

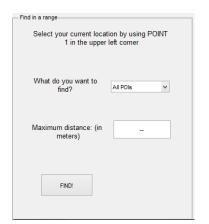
- Adding a third point
- Getting and storing the distance
- How it works
- Cost of time





Find in a Range

- Using Point 1 data
- Selection of classes
- Distance
- Slow process





Generation of the instructions

- Generating instructions from shortest path
- Setting a scroll bar
- Exporting this data
- Default text when missing data





Conclusions



Thank you for attention!



Questions?

