## QUESTIONNAIRE

## Tell us what do you think about the robot:

	1	2	3	4	5	
fake						natural
machine-like						human-like
unconscious						conscious
artificial						life-like
moving rigidly						moving elegantly
incompetent						competent
ignorant						knowledgeable
irresponsible						responsible
unintelligent						intelligent
foolish						sensible
dead						alive
stagant						lively
mechanical						organic
artificial						lifelike
inert						interactive
apathetic						responsive
	1	2	3	4	5	

Tell us how	did you feel about		robot:	3	4	5	
lislike		).					like
ınflriendly		<u></u>					friendly
ınkind		<u>)</u>					kind
inpleasant		<u></u>					pleasant
ıwful		<u></u>					nice
	1	L	2	3	4	5	
Tell us how y	your emotional st	ate w	vas				
	1	L	2	3	4	5	
nxious		).					relaxed
gitated		<u></u>					calm
uiescent							surprised
	the robot waite	l you ed to	prefer or	consider ear path		-	vigation task? (select
L. Which so	lights etc)				. •		ng velocity, using vigation task? (select
only one)					J	-	·
	the robot waite	ed to	have cle	ear path			
	the robot avoid	led t	he peop	le-obstac	les witho	out any soci	al behaviour

2.	Which social behaviour did you prefer or consider necessary during a navigation task? (select
onl	y one)
	the robot showed social behaviours (e.g. talking, changing velocity, using lights etc)
	the robot avoided the people-obstacles without any social behaviour