* Srpints
  + Sprint0
    - Analysis
  + Sprint1
    - Kb
    - Robot free moves
  + Sprint2
    - Onecellforward
    - Onerotateforward
    - Test robot steps move
    - Kb for robot position
  + Sprint3
    - Explorer
    - Missionresolver
    - Kb for object position
  + Srpint4
    - Reconition for map bound
    - Reconition for map object on bound side
    - Reconition for table