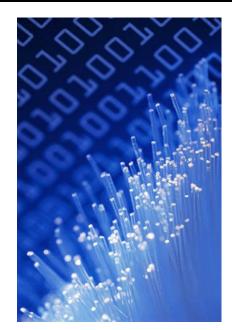
CMSC 124, 1st Semester, AY 2009-10



#### **Discussion**

Remember, we have 2 kinds of data types, which are:

- Primitive Data Types
- Composite Data Types

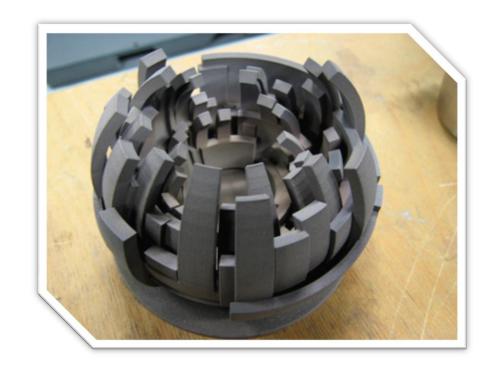


### **Data Objects**

- Data objects represent container for data values.
- They are memory spaces where data values may be stored and later retrieved.

## **Two Types of Data Objects**

- 1. Programmer-Defined
- **Eg:** Variables, constants
- 2. System-Defined
- **Eg:** Data objects maintained by the virtual computer.



## Attributes of Data Objects

# 1. Value Type

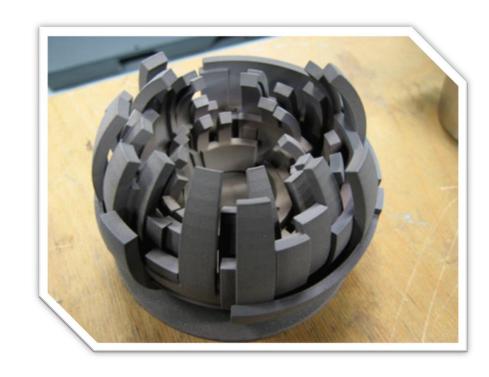
 Types of values that the data object may contain.

#### 2. Size

 The amount of storage needed to store the values in the data object.

#### 3. Lifetime

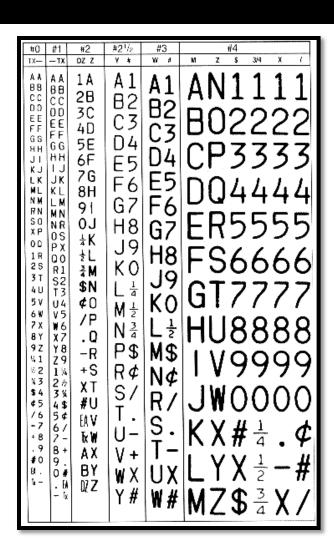
How long the data object exists.



#### Data Values and Value Types

#### **Value**

- Anything that may be evaluated, stored, passed as a argument to a procedure, returned by a function, or may be a component of a data structure.
- The one that is placed on the data object.
- The values may be grouped into types.



### Data Values and Value Types

## Value Type

A value type is just a set of values.

### The Types of Values

#### 1. Primitive Type

- One whose value is atomic and therefore cannot be decomposed.
- **Eg:** Characters, Integers, Booleans

## 2. Composite Type

- One whose values are composed or structured from simpler values.
- **Eg:** Records, Arrays, Sets, Strings\*



### 3. Recursive Type

It is defined in terms of itself.

## **Data Types**

- Data types are class of data objects **PLUS** set of operations for creating and manipulating them.
- Primitive data types may be <u>combined</u> to form a composite data type.
- Certain PL's provide facilities for the programmer to <u>define</u> <u>new composite</u> data types.



## Illustration on Data Objects

# Data Object

A location in the computer memory with the name **A**.

A:

#### Data Value

A bit pattern used by the translator whenever the number 17 is used in the program.

10001

Bound Variable

Data object is bound to the value 17

**A**:

0000 0000 0001 0001

#### Primitive Data Types

#### 1. Numeric Data Type

Includes integer and real number types.

#### • In C:

```
short int i
long int k
unsigned int u
float x
double y
```

 In PL/I and ADA, it allows the number of digits in the decimal representation to be specified.

```
DECLARE PAY FIXED DECIMAL (7,2)
```

#### In COBOL:

ROOT PICTURE 99999V99

#### Primitive Data Types

## 2. Subrange Type

 This is introduced to save on storage and for better type checking.

#### Consider this:

A variable having a value in the subrange 1..100

#### **SOMETHING TO PONDER:**

- ✓ How do you save storage space?
- ✓ How is type checking facilitated?

### • **Eg**:

age = 1..120, define as integer

#### What can you say about?

- $\checkmark$  age = 130
- $\checkmark$  age = 0
- $\checkmark$  age = age 1

### Primitive Data Types

### 3. Enumeration Type

 It is common to have a variable that can take on one of a small set of values.

### In Pascal: (Example)

```
rank: (instructor,
assistant_professor,
associate_professor,
professor)
```

status: (single, married, widowed)

#### • In C:

```
enum days {mon, tue,...sun}
week;
enum days week1, week2;
```



### Primitive Data Types

- 4. Boolean (or Truth Value) Type
- A data type having one of the two possible values (true or false).
- **Eg:** Declaring a variable RESPONSE.
  - ✓ In PL/I:

LOGICAL RESPONSE

✓ In Pascal:

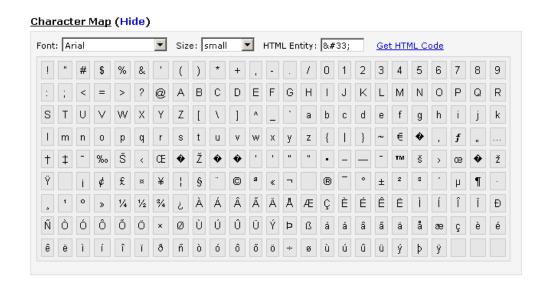
RESPONSE: boolean;

✓ In Java:

boolean RESPONSE;

### 5. Character Type

 Characters are stored as numeric coding, wherein the most popular scheme is ASCII.



### Primitive Data Types

## 6. String Type

- Natural extension of character types is the string type.
- Languages such as SNOBOL,
   PL/I, FORTRAN, BASIC allow a
   string to be manipulated as one
   unit.
   (Primitive Data Type)
- While others, like APL, Pascal, C, ADA, consider a string as a <u>linear</u> <u>array of characters</u>. (Composite Data Type)

#### Eg:

✓ In PL/I:

DCL NAME CHAR (25)

## ✓ In Pascal:

name: array[1..25] of
char;

#### **SOMETHING TO PONDER:**

What's the matter if a string is implemented as PDT or CDT?

## The Concept of Binding

## **Binding**

- Association such as between an attribute and an entity, and an operation and a symbol.
- The time when binding takes place is called the binding time.
- Eg:
  - Variable to type
  - Variable to value
  - Symbol to operation.



### Classes of Binding

# 1. Execution Time (Runtime)

- a. On entry to a procedure or block.
  - Formal to actual parameters.
  - Formal parameters to particular storage locations.
- b. At arbitrary points during execution.
  - Variables to values.



## Classes of Binding

# 2. Translation Time (Compile Time)

## a. Chosen by the programmer.

- Variable types, names.
- Statement structures.

# b. Chosen by the translator.

- Relative location of a data object.
- How arrays are stored.



### Classes of Binding

# 3. Language Design (Definition) Time

- Bindings set by the designer of the programmer.
- Program structures, possible statement forms, data structure types.
- **Eg:** Possible types of a variable in every programming language.



### Classes of Binding

# 4. Language Implementation Time

- Brought about by the differences in hardware where PL's are implemented.
- Possible range of values may be dictated by the PL.
- Details associated with the representation of numbers and arithmetic operations.



# Illustration on Binding

```
int count;
...
count = count + 926;
```

#### **Considerations**

- Set of possible type for count =
- Type of count =
- Set of possible values of count =
- Value of count =
- Set of possible meanings for the operator symbol + =
- Meaning of the operator symbol + =
- Internal representation of the literal 926

## **Binding Types**

Before a variable can be referenced in a program, it must be bound to a data type.

## 1. Static Binding

- Types are specified through declarations.
- Explicit Declaration
   In C: int j;
- Implicit Declaration
   In FORTRAN, variables with names that start with I,J,K,L,M,N are said to be integer types.

## 2. Dynamic Binding

- The type is not specified by the declaration statement.
- Variable is bound to a type when it is assigned a value in an assignment statement.
- Eg:

```
$grade = "mataas"
$grade = 100;
```

#### **Declaration**

**Declaration** is the part of the program where the programmer communicates to the language translator information on the numbers and types of data objects needed during program execution.

# **Purposes of a Declaration**

- 1. Choice of storage representation
- 2. Storage management
- 3. Generic operations
- Type checking



## Type Checking

- Type checking is done to ensure that an operation is provided with the correct types.
- Consider this: A:=B+C;
  - The types for operands B and C must be those allowed for the operands of addition.
- It is done almost everywhere in a program.



## Type Checking

## 1. Static Type Checking

- Type checking is done during compilation.
- A lot of information is needed in order to do checks at compile time.
  - This is the reason why most data objects are declared.

## 2. Dynamic Type Checking

- Type checking is done during execution time.
- Performed immediately before the execution of a particular operation.
- Usually slows down the execution of the program.

# Type Checking

Type checking is dependent on whether the language is:

### 1. Statically Typed

- Every variable and parameter has a fixed type that is chosen by the programmer.
- The type of each expression can be deduced and each operation can be type-checked at compile time.

# 2. Dynamically Typed

- Only the values have fixed types.
- A variable may have no designated type and may take on values of different types at different stages of execution.

# Strong Typing

A PL is **strongly typed** if type errors are always detected whether at compile time or at run time.

#### **NOT STRONGLY TYPED**

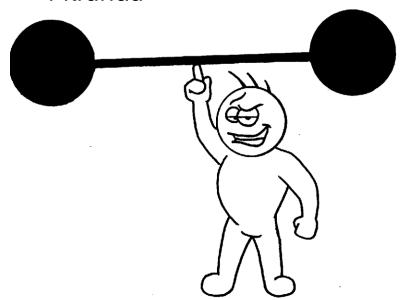
- FORTRAN-77
- MODULA 2

#### **NEARLY STRONGLY TYPED**

- ADA
- Pascal

#### **PURE STRONGLY TYPED**

- ML
- Miranda



# Type Equivalence

- When two data objects are involved in one operation, this issue arises.
- When two data objects are identical in types, then there is no problem.
- But, we often encounter operations involving nonidentical data objects but closely related.
- "Are they compatible?"



## Type Equivalence

#### 1. Structural Equivalence

- They have the same logical structure.
- However, it is not always easy to decide the logical equivalence of 2 data types.

#### **Pascal Declaration**

```
type rangetype1 = 1..120;
type rangetype2 = 1..120;
var age1:rangetype1;
var age2:rangetype2;
```

## **Assignment Statement**

```
age1 := age2;
```

### Type Equivalence

#### 2. Named Equivalence

• Look at the example. ☺

#### **ADA Declaration**

```
TYPE meter IS NEW integer;
TYPE yard IS NEW integer;
m, n: meter;
y: yard;
```

#### **Assignment Statements**

```
m := n;
- LEGAL
y := m;
- ILLEGAL
```

# Type Conversion and Coercion

- When the operands of an operation have types that are not exactly the same, either a type mismatch error occurs or some type conversion has to be done.
- Type conversion is an operation that converts a data object of one type and produces the corresponding data object in another type.
- It has two types:

### 1. Narrowing Conversion

- Converts the object type with a certain storage reqm't to the one with lesser storage reqm't.
- **Eg:** real -> int

### 2. Widening Conversion

- Storage reqm't of the original type is lesser than the converted type.
- Eg: int -> real

## Type Conversion and Coercion

 Type conversion may be done implicitly (coercion) or explicitly.

#### Coercion

- Way by which a data object of a certain type is changed to the correct type.
- Usually carried out by compiler or virtual computer.

• **Eg:** Consider the following Pascal expression.

$$x := n * 26;$$

- ✓ Assume x is real and n is integer.
- ✓ The type n is coerced to be real.
- ✓ This illustrates implicit integerto-real conversion in Pascal.

#### Initialization

- Uninitialized variables may contain "garbage" and when used, may cause errors.
- Most PLs provide for initialization immediately after declaration (allocation of storage).



#### Prelude

## **Composite Data Type**

Data type whose values are composed or structured from simpler values.

MATHEMATICAL CONCEPT	COMPOSITE DATA TYPE
Cartesian Product	Records, Tuples
Disjoint Unions	Variants, Unions
Mappings	Arrays, Functions
Power Sets	Sets
Recursive Types	Dynamic Data Structure

#### Cartesian Product

- The Cartesian product of two sets S and T, denoted by S x T.
  - \* "The set of all ordered pairs, such that the first value of the pair is chosen from the set S and the second value from the other set T."

#### In General:

The Cartesian product  $S_1 \times S_2 \times ... \times S_n$  stands for the set of n-tuples, such that the first component of the n-tuple comes from  $S_1$ , the second  $S_2$ , so on...

#### Cartesian Product

Eg: Pascal

```
type date = record
    d: 1..31;
    m: (Jan, Feb, Mar, Apr, May, Jun, Jul, Aug, Sep,
    oct, Nov, Dec);
    y: 1900..3000
end
```

How do we define date using Cartesian product notation?

#### Cartesian Product

Another Eg: C

```
struct date {
    int day;
    int month;
    int year;
    char dow;
} today
```

How do we define date using Cartesian product notation?

```
✓ date = int x int x int x char
```

# **Disjoint Unions**

- The disjoint unions of two sets S and T, denoted by S + T.
  - \* "The set of values in which each value is chosen from either set S or set T."
- In General:
  - $S_1 + S_2 + ... + S_n$  stands for the set in which each value is chosen from one of  $S_1$ ,  $S_2$ , ..., or  $S_n$

### Disjoint Unions

Eg: Variant records in Pascal

How do we define employeetype using disjoint unions notation?

```
✓ employeetype = integer x char x integer x
  ((real x integer) + (real x integer x integer))
```

#### **Disjoint Unions**

- Eg: Unions in C
  - ✓ A union is a variable which may hold (at diff. times) objects of different sizes and types

```
union number {
    short shortnumber;
    long longnumber;
    double floatnumber;
} anumber;
```

- ✓ Defines a union called number and an instance anumber
- ✓ To access: anumber.longnumber

### Mappings

- A mapping f maps every value x in set S to a value y in set T: f:S->T
- Examples:
  - **❖** Array
    - ✓ mapping: (index set) -> (component set)
  - Function Abstraction
    - ✓ mapping: (parameter) -> (returned value)



### Mappings

• **Eg: Pascal** amikind = array[1..161] of boolean

How do we define amikind using mappings notation?

```
amikind = \{1, 2, 3, ..., 161\} \rightarrow \{true, false\}
```

Mappings: More Examples

```
function odd (n: integer):boolean;
 begin
      odd := (n \mod 2=1)
 end;
  • Set S: integer
  • Set T: boolean
  • Notation: odd = integer -> boolean
function gcd (m, n: integer):integer;
 begin
      if n = 0 then qcd := m
     else qcd := qcd (n, m mod n)
 end;
  • Set S: integer x integer
  • Set T: integer
  • Notation: gcd = integer x integer -> integer
```

#### **Powersets**

- The set of all subsets of S is called the powerset of S.
- **Operations:** (defined in set theory)
  - Membership test
  - Inclusion test
  - Union
  - Intersection
- Pascal and ML support set type.
- Eg: Pascal

```
type color = red, yellow, blue;
mix = set of color;
// mix = powerset of color
```



#### **Recursive Types**

- A recursive type is one whose values are composed from values of the same type.
  - Defined in terms of itself.

#### In General:

The set of values of a recursive type T, will be defined by a recursive equation of the form T = ... T ...



#### **Recursive Types**

Eg: List Type in ML Notation:

```
Integer-list = Unit + (Integer x Integer-list)
```

#### In ML:

```
datatype intlist = nil | cons of int * intlist
```

#### Sample Values:

```
nil
cons(11, nil)
cons(1, cons(2, cons(3, cons(4, nil))))
```

#### QUIZ Number N(?) – Get 1/4

 Show the set of values of each of the following Pascal types using formal notations.



QUIZ Number N(?) – Get ¼ - Answer

#### **Formal Set Notation**

```
cmscsubj = {CMSC 124, CMSC 150, CMSC 100, CMSC 128}
numgrade = {1.0, 1.25, 1.5, ...., 3.0, 5.0}

studrec = {CMSC 124, CMSC 150, CMSC 100, CMSC 128} x
boolean x {1.0, 1.25, 1.5, ...., 3.0, 5.0}

OR

{CMSC 124, CMSC 150, CMSC 100, CMSC 128} x
{true, false} x {1.0, 1.25, 1.5, ...., 3.0, 5.0}

sreinrecord = {1, 2, ... 161} -> {CMSC 124, CMSC 150, CMSC 100, CMSC 128} x {true, false} x {true, false} x {1.0, 1.25, 1.5, ...., 3.0, 5.0}
```

#### Specification of Composite Data Types

#### The Properties

- 1. Number of Components
  - Consider: Fixed size or variable size?
  - Fixed size signifies invariant number of components.
    - ✓ Eg: Pascal arrays and records
  - Variable size signifies dynamically changing number of components.
    - ✓ Eg: ML's list types, Java's array list

#### Specification of Composite Data Types

#### The Properties

- 2. Type of Each Component
  - Consider: Homogenous or heterogenous?
  - Homogenous requires all components are of the same type.
    - ✓ Eg: Arrays, Strings\*
  - Heterogeneous allows components of different types.
    - ✓ Eg: Records, Variant records

### Specification of Composite Data Types

### **The Properties**

- 3. Name to be Used in Selecting the Component
  - Dependent on the syntax adopted by the language.

#### 4. Maximum Number of Components

- Dictated whether dynamic or static?
- For dynamic structures: Usually no limitation on size.
- For static structures: Programmer usually sets the size.

#### 5. Organization of Components

Dependent on the type of each component.

### Operations on Composite Data Types

#### 1. Selection Operation

- Operation to access components of the composite structure.
- Issue: Random versus Sequential?

#### 2. Whole Structure Operations

- Take the whole structure as argument.
- **Eg:** Equality test of strings, Union, Intersection of sets

### 3. Insertion/Deletion of Components

- Actually relevant only to dynamic composite structures.
- Ponder: How about static composite structures?

#### 4. Creation/Destruction of Data Objects

- Supported by most PL's
- Again, dependent whether structure is static or dynamic.

Review: Given these Pascal types, use formal set notations to show the set of values of each.

```
{define a gendertype and civiltype}
type gendertype = (male, female);
type civiltype = (single, married);
{define another type called person, which is a record
   containing ... }
type person = record
   name: array[1..3] of string;
   gender: gendertype;
  age: integer;
   case civilstat: civiltype of
      single: (num fiance: integer);
      married: (spouse: string;
                num offspring: integer);
```

end;

**Review:** Given these Pascal types, use formal set notations to show the set of values of each.

#### **Answers:**

```
gendertype = {male, female}
civiltype = {single, married}
```



```
S<sub>1 (name)</sub> = {1,2,3} -> string
S<sub>2 (gender)</sub> = {male, female}
S<sub>3 (age)</sub> = integer
S<sub>4 (civilstat)</sub> = integer + (string x integer)
```

```
person = ({1,2,3}->string) x {male, female} x integer x (integer + (string x integer))
```

**Review:** Given these Pascal types, use formal set notations to show the set of values of each.

```
{function used in checking if a person is a zombie ©}
function is_a_zombie(p: person, x:integer):
  boolean;
begin
  if p.age > 70 then
    is_a_zombie := true
  else
    is_a_zombie := false;
end;
```



**Review:** Given these Pascal types, use formal set notations to show the set of values of each.

#### **Answers:**

```
$ = person x integer
    = ({1,2,3}->string) x {male, female} x
    integer x (integer + (string x integer))
    x integer
```



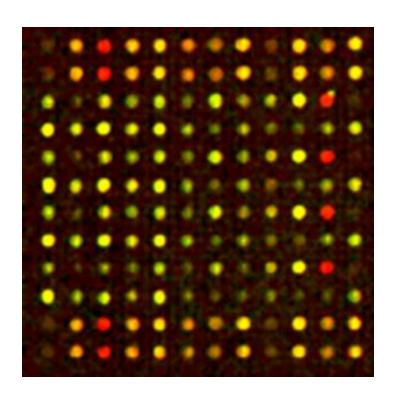
**T** = boolean or {true, false}

```
is_a_zombie = ( ({1,2,3}->string) x {male, female} x integer x
  (integer + (string x integer)) x integer ) -> {true, false}
```

#### Implementation: Arrays

An **array** is an ordered sequence of identical objects.

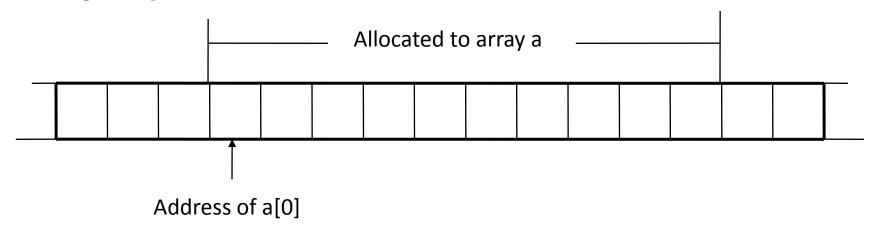
- ✓ **Static arrays**Index set is fixed at compile time.
- ✓ **Dynamic arrays**Index set is fixed on creation of the array during execution.
- ✓ Flexible arrays
  Index set is not fixed at all.



1D Arrays

### **One Dimensional Arrays**

> Storage Representation

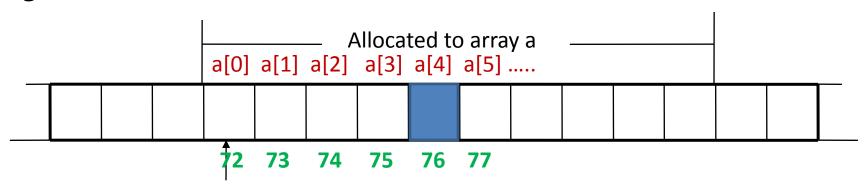


- Accessing Elements (a[i])
  - 1. Load address of **a[0]** to register **r**
  - 2. Add i to register **r**
  - 3. Get the content of memory whose address is in **r**

### 1D Arrays

### **One Dimensional Arrays (Plain)**

> Eg: Access a[4]



Address of a[0]

- Accessing Elements (a[i])
  - 1. Load address of **a[0]** to register **r.**
  - 2. Add i to register r.
  - 3. Get the content of memory whose address is in **r**.

$$i = 4$$

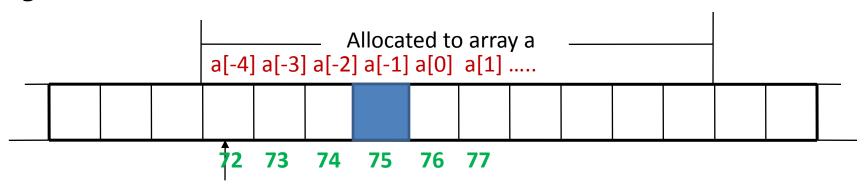
$$1. r = 72$$

$$2. r = 72 + 4 = 76$$

### 1D Arrays

### One Dimensional Arrays (without Subscript Checking)

> Eg: Access a[-1]



Address of a[-4]

### > Accessing Elements (a[i])

- 1. Load address of **a[-4]** to register **r**
- 2. Add i to register r
- 3. Subtract -4 from register r
- 4. Get the content of memory whose address is in **r**

1. 
$$r = 72$$

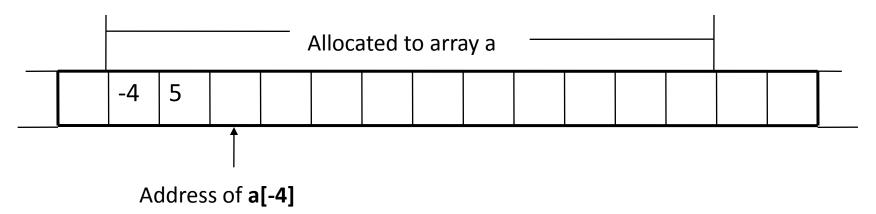
2. 
$$r = 72 + -1 = 71$$

3. 
$$r = 71 - (-4) = 75$$

1D Arrays

### One Dimensional Arrays (with Subscript Checking)

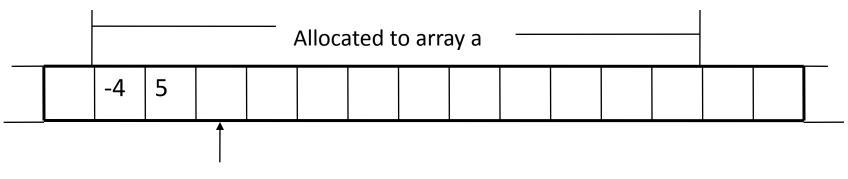
> Storage Representation



- The lower and upper bounds of the indices of the array should be made available during runtime.
- One way is to store these bound in the memory, together with the components of the array.
- Above example shows a:array[-4..5] of integer.

1D Arrays

### One Dimensional Arrays (with Subscript Checking)



Address of a[-4]

- > Accessing Elements (element a[i])
  - 1. Load address of **a[-4]** to register **r1**
  - Load i to register r2
  - 3. Is **r2** < the content of **r1-2** then error subscript out of range
  - 4. Is **r2** > the content of **r1-1** then error subscript out of range
  - 5. Add **r2** to **r1**
  - 6. Subtract -4 from register r1

N-Dimensional Arrays

### **Two Ways**

- Indirect Access via Pre-Calculated Vectors of Addresses
- Multiplicative Subscript Calculation



Indirect Access via Pre-Calculated Vectors of Addresses

### **Two Dimensional Arrays**

#### > Storage Allocation

Array  $m_1 \times m_2$  will require  $m_1 * m_2$  storage locations for the components and  $m_1$  storage locations for the pointers.

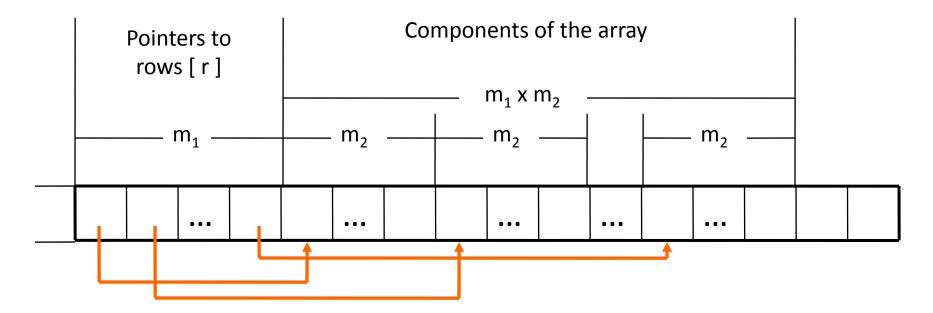
Pointers to rows [r]				Components of the array											
m <sub>1</sub>				$m_1 \times m_2$ $m_2$											
		•••			•••			•••		•••		•••			

### Indirect Access: Two Dimensional Arrays

#### Pointer Initialization

Let  $\mathbf{b}$  – address of the first storage location of the array  $\mathbf{v_1}$  – address of the first storage location of the first row

for i:=0 to 
$$m_1-1$$
 do  $r[i] := v_1 + m_2*i$ ;

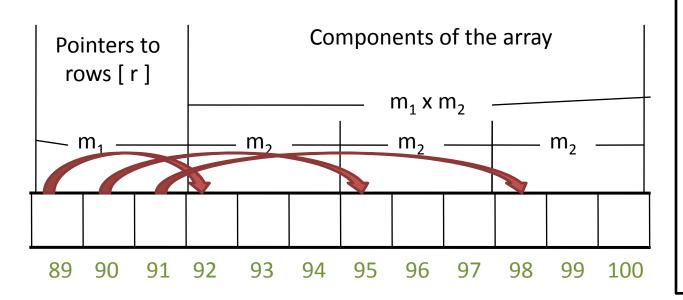


#### Indirect Access: Two Dimensional Arrays

### Eg: Initialize 3 x 3 array

Let  $\mathbf{b}$  – address of the first storage location of the array  $\mathbf{v_1}$  – address of the first storage location of the first row

for i:=0 to 
$$m_1-1$$
 do  $r[i] := v_1 + m_2*i$ ;



$$b = 89$$

$$v_1 = 92$$

$$m_1 = 3$$

$$m_2 = 3$$

$$r[0] = 92+3*0$$

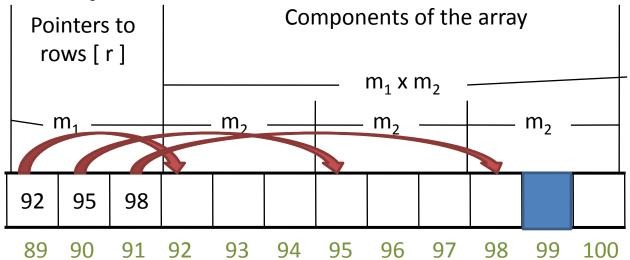
$$= 92$$

$$r[1] = 92+3*1$$

$$= 95$$

#### Indirect Access: Two Dimensional Arrays

#### Example: Access a[2,1]



#### Accessing Elements (element a[i, j])

- 1. Load address of the first memory allocated to the array to register **r** --- **b**
- 2. Add i to register **r**
- 3. Get the content of memory address is in **r** and store it to **r**
- 4. Add **j** to **r**
- 5. Get the content of the memory whose address is in  $\bf r$

get content

(at 99)

Indirect Access via Pre-Calculated Vectors of Addresses

### **N - Dimensional Arrays**

Consider an n-dimensional array

where

$$m_i = hi_i - lo_i + 1, 1 \le i \le n$$
  
 $lo_i = 0, 1 \le i \le n$ 

**b** = address of the first storage location allocated for array **a** 

Indirect Access: N-Dimensional Arrays

### **N - Dimensional Arrays**

> Storage Allocation

SPACES FOR THE VECTOR OF ADDRESSES	SPACES FOR THE COMPONENTS OF ARRAYS
$m_1$ $m_1 * m_2$ $m_1 * m_2 * m_3$  $m_1 * m_2 * m_3 * m_{n-1}$	m <sub>1</sub> * m <sub>2</sub> * m <sub>3</sub> * m <sub>n</sub>

#### **TRY THIS!**

Compute total number of spaces for a 3 x 3 x 3 array.

• The total number of cells needed for an n-dimensional array is

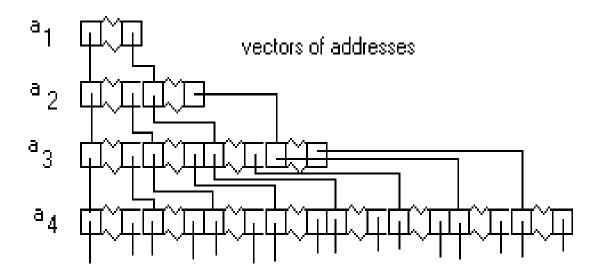
$$m_1 + (m_1 * m_2) + (m_1 * m_2 * m_3) + ... + (m_1 * m_2 * m_3 * .. * m_n)$$

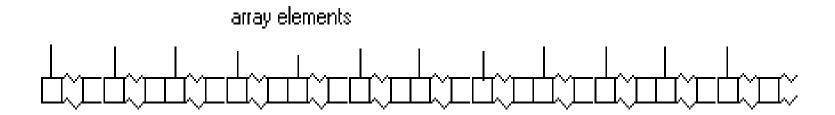
#### Indirect Access: N-Dimensional Arrays

#### > Pointer Initialization

```
v_1 = b + m_1
v_2 = b + m_1 + (m_1 * m_2)
v_3 = b + m_1 + (m_1 * m_2) + (m_1 * m_2 * m_3)
v_{n-1} = b + m_1 + (m_1 * m_2) + (m_1 * m_2 * m_3) + (m_1 * m_2 * m_3 * ... * m_{n-1})
for i:=0 to m_1-1 do r_1[i] := v_1 + m_2 * i;
for i:=0 to m_1*m_2-1 do r_2[i]:=v_2+m_3*i;
for i:=0 to m_1*m_2*m_3-1 do r_3[i]:=v_3+m_4*i;
for i:=0 to m_1 * m_2 * m_3 * ... * m_n do r_{n-1}[i] := v_{n-1} + m_n * i;
```

Indirect Access: N-Dimensional Arrays





### Indirect Access: N-Dimensional Arrays

### > Accessing Elements

For simplicity, we will access an element in a 3-dimensional array which is **a[i, j, k]**.

- 1. Get the first memory allocated to the arrays **b**
- 2. Go to storage location **b+i**
- 3. Get the contents of  $\mathbf{b} + \mathbf{i}$  and add  $\mathbf{j}$  to this
- 4. Go to the resulting address and get its content and add  ${f k}$
- 5. Get the content of this last address. The content of this is the value of **a[i, j, k]**

#### **Indirect Access: Analysis**

- √ Fast component access
- ✓ Large memory requirement
- ✓ Overhead of the initialization process
- ✓ Ideal for machines with high memory capacity
- ✓ In pass by value, the whole array including its vectors of addresses have to be copied to the called procedure. The initialization process have to be redone.

#### Multiplicative Subscript Calculation

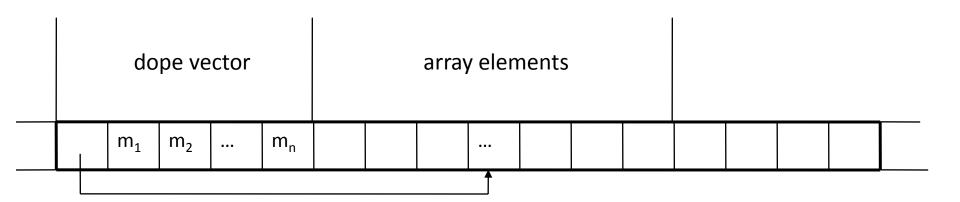
- ✓ Transforms an  $\mathbf{m_1} \times \mathbf{m_2} \times \mathbf{m_3} \times ... \times \mathbf{m_n}$  array into an equivalent one dimensional array with  $\mathbf{m_1} * \mathbf{m_2} * \mathbf{m_3} * ... * \mathbf{m_n}$  elements.
- ✓ Instead of using n indices to access an element, they are used to calculate the one index that tells the position of the element to be accessed in the equivalent one-dimensional array.

```
address of a[i_1, i_2, i_3,...,i_n] = address of a[0, 0, 0, ..., 0] + (...(((((i_1*m_2) + i_2)*m_3) + i_3)*m_4)+i_4...*m_n)+i_n
```

- ✓ A requirement in the use of the formula is to know the values of these terms at runtime.
  - address of a[0,0,0...,0] = b
  - $m_i$ , 2 <= i <= n

#### Multiplicative Subscript Calculation

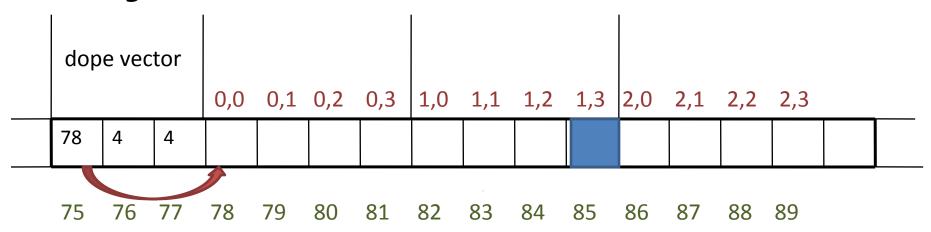
✓ We use here a storage called a dope vector.



#### Multiplicative Subscript Calculation

#### 2 - Dimensional Arrays

- > **Eg.** Consider a 4 x 4 array. Access a[1,3]
- > Storage Allocation



> Accessing element a[i, j]

$$b + (i * m_2) + j$$

> Accessing element a[1, 3]

$$78 + (1 * 4) + 3 = 85$$

#### Multiplicative Subscript Calculation

#### N - Dimensional Arrays

Consider an n-dimensional array a[lo<sub>1</sub>..hi<sub>1</sub>,lo<sub>2</sub>..hi<sub>2</sub>,...,lo<sub>n</sub>..hi<sub>n</sub>] where

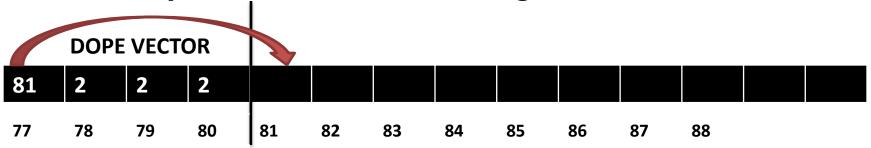
$$m_i = hi_i - lo_i + 1$$
,  $1 < i < n$   
 $lo_i = 0$ ,  $1 < i < n$  (assumption)

- Storage Allocation
  Allocating for the offset a[0,0,...,0], dope vector and the components of the array
- Accessing Elements

```
address of a[i_1, i_2, i_3, ..., i_n] = address of <math>a[0, 0, 0, ..., 0] + (...(((((i_1*m_2) + i_2)*m_3) + i_3)*m_4)+i_4...*m_n)+i_n
```

Multiplicative Subscript Calculation: N-Dimensional Arrays

> Given this particular allocated storage



- 1. Get 1/4.
- 2. What are the dimensions of the array?  $(m_1, m_2, m_3)$
- 3. What is **b**?
- 4. Show the <u>complete</u> computation to access **a[0,1,1]**.

```
address of a[i_1, i_2, i_3,...,i_n] = address of a[0, 0, 0, ..., 0] + (...(((((i_1*m_2) + i_2)*m_3) + i_3)*m_4)+i_4...*m_n)+i_n
```

Multiplicative Subscript Calculation: N-Dimensional Arrays

### > Given this particular allocated storage



#### Access a[0, 1, 1]

$$i_1 = 0$$
 $i_2 = 1$ 
 $i_3 = 1$ 
 $m_1 = 2$ 
 $m_2 = 2$ 
 $m_3 = 2$ 

n=3

**b**= 81

#### Multiplicative Subscript Calculation: Analysis

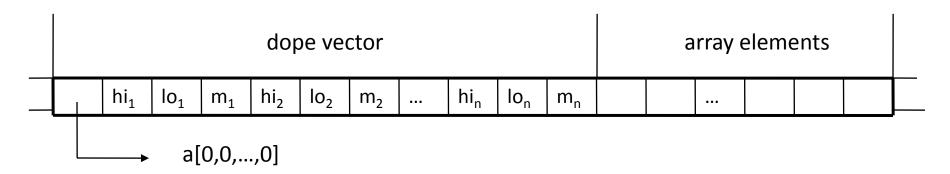
- ✓ Requires much less storage than indirect access via precalculated addresses.
- ✓ Initialization does not require expensive loops.
- ✓ But requires extensive computation of the address of an element at run time.

#### Subscript Checking

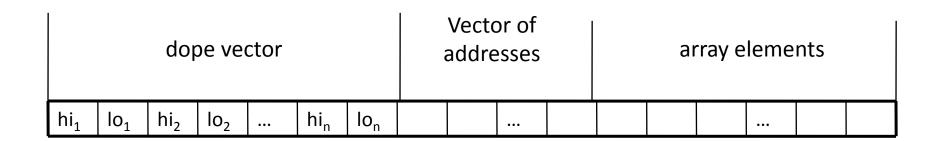
- ✓ Usually carried out at run-time.
- ✓ Usual procedure for doing this is through the dope vector.
- ✓ It is expensive to perform subscript checking.
- ✓ Most languages allow subscript checking for programmers to save hours from debugging errors in arrays.



#### Subscript Checking



#### Dope vector for multiplicative subscript calculation



Dope vector for indirect access via pre-calculated addresses

- ✓ A record structure is composed of a fixed number of components that can be of different types.
- ✓ Indices in records, called record offsets, are of fixed size.

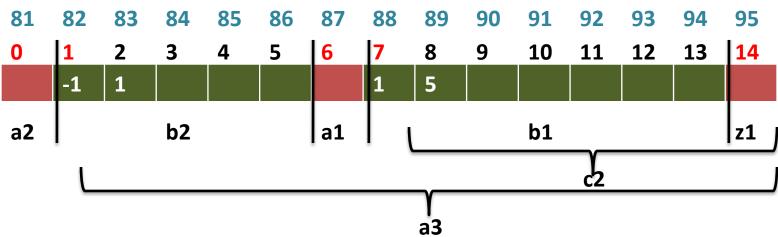


```
r3 = record
       a3: r2;
       z1: integer;
   end
   var id: r3;
a1
```

```
In Pascal,
                                             r3 = record
type r1 = record
                                                a3: r2;
      a1: integer;
                                                z1: integer;
      b1: array[1..5] of char;
                                             end
end;
                                OFFSET
type r2 = record
                                             var id: r3;
     a2: char;
     b2: array[-1..1] of real;
     c2: r1;
end;
                                                     8
             0
                                      5
                                                               10
                                                                    11
                                                                         12
                                                                              13
                      1
                                                     5
             a2
                            b2
                                           a1
                                                               b1
```

```
In Pascal,
                                            r3 = record
                                                                       OFFSET
type r1 = record
                                                a3: r2;
      a1: integer;
                                                z1: integer;
                                                                         14
      b1: array[1..5] of char;
                                            end
end;
type r2 = record
                                            var id: r3;
     a2: char;
     b2: array[-1..1] of real;
     c2: r1;
end;
                                                                                  14
             0
                                                          9
                                                               10
                                                                    11
                                                                         12
                                                                              13
             a2
                            b2
                                           a1
                                                                                   z1
                                                               b1
```

#### Implementation: Records



#### **Accessing Elements**

- 1. Load the address of first memory allocated to id to register r.
- 2. Add offset of a3 to r.
- 3. Add offset of c2 to r.
- 4. Get the content of the memory whose address is in r.

#### **Eg: id.a3.c2**

- 1. r = 81
- 2. r = 81 + 0 = 81
- 3. r = 81 + 7 = 88
- 4. get\_content(at 88)

Implementation: Records

#### **Take Note:**

 $\checkmark$  **r** = Address of the first storage location allocated to the record.

```
\sqrt{r} = r + component offset
```

- ✓ If component is an array
  - r = r + offset of the array
  - The rest is done like in arrays

#### Implementation: Variant Records

- ✓ Variant records are records with one or more variants.
- ✓ Part of a record may assume different number of components and different types of components.
- √ Storage Representation
  - w/ dynamic type checking
  - w/o dynamic type checking

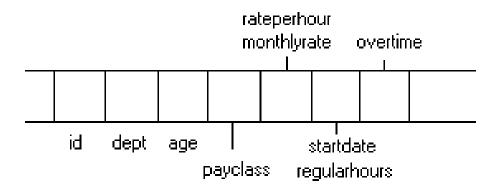


Implementation: Variant Records

```
Declaration
                                                 RECORD OFFSET
type paytype = (salaried, hourly)
type employeetype = record
id: integer;
dept: char;
age: integer;
case payclass: paytype of
        salaried: (monthlyrate: real;
                         startdate: integer);
        hourly: (rateperhour: real;
                         regularhours: integer;
                         overtime: integer);
end
     end
var employee: employeetype;
```

Implementation: Variant Records (with Dynamic Type Checking)

#### **Storage Representation**



# Accessing Elements Eg. employee.startdate

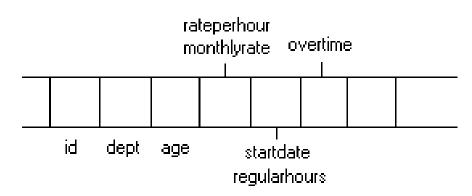
- 1. Load address of the first cell allocated to record employee (r).
- 2. Make a copy of that address.
- 3. Load value of tag field.
- 4. = salaried.
- 5. True, jump to @1.
- 6. False.
- 7. Call error handler.
- 8. Quit.
- 9. @1:Load employee.startdate.

Implementation: Variant Records (without Dynamic Type Checking)

```
Declaration
                                                 RECORD OFFSET
type paytype = (salaried, hourly)
type employeetype = record
id: integer;
dept: char;
age: integer;
case payclass: paytype of
        salaried: (monthlyrate: real;
                         startdate: integer);
        hourly: (rateperhour: real;
                         regularhours: integer;
                         overtime: integer);
end
     end
var employee: employeetype;
```

Implementation: Variant Records (without Dynamic Type Checking)

#### **Storage Representation**



# Accessing Elements Eg. employee.startdate

- 1. Load the address of the first cell allocated to employee to register r.
- 2. Add offset of startdate (that is 4) to r.
- 3. Get the content of the memory whose address is in r.

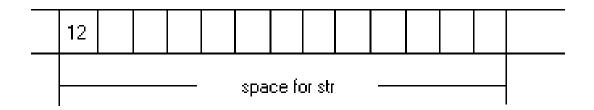
#### Implementation: Strings

- ✓ A string is a sequence of characters.
- ✓ Can be treated as:
  - Primitive data type with the built-in functions
  - Array of chars
  - List of chars



#### Implementation: Strings

- ✓ In ADA, a string is simply a string of characters.
- ✓ To declare an array in ADA:
  - str :String(1..12);



• str: String := "Hello World!" -> str: String(12)

```
12 H e I I o w o r I d !
```

#### Implementation: Sets

✓ Defines the set of values that is a powerset of the base type.

```
✓ In Pascal,
  type <identifier> = set of <base type>
  where <base type> must be a scalar type or a subrange type.

  type onedigitset = set of 0..9;
      colorset = set of (blue, yellow, red);

  var d: onedigitset;
      c: colorset;
```

#### Implementation: Sets

- > The Key: Characteristic Function c(s).
  - An array of logical values (0 or 1) whose **ith** component specifies the presence or absence of the **ith** value in the set.

### > Eg:

```
var d : onedigitset;
The representation of d = [1,3,5,7,9] is c(s) = [0,1,0,1,0,1,0,1]
```

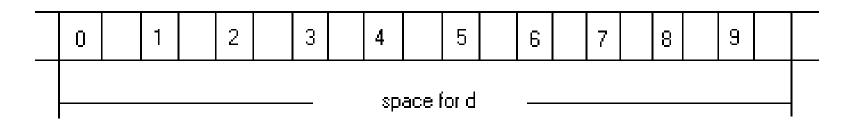
```
REMEMBER!
```

```
type onedigitset = set of 0..9;
```

#### Implementation: Sets

### > Implementation

- Individual values of the set must be known at run time.
- Hence, there is a need to store the individual values of the base type.
- > Storage Representation of var d : onedigitset



#### > Accessing Elements

Similar to accessing a one-dimensional array.

Practice: Show the storage representation of a

# Sample 1. Use multiplicative subscript calculation (without subscript checking)

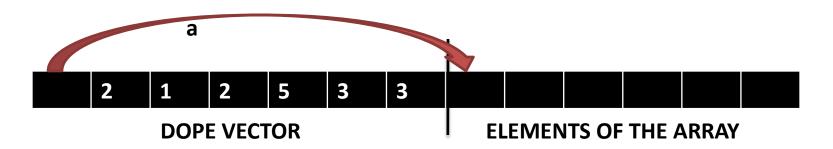
```
program arrayaccess;
var a: array[1..2, 3..5] of integer
begin
    a[1,3] := 100;
end.
```



Practice: Show the storage representation of a

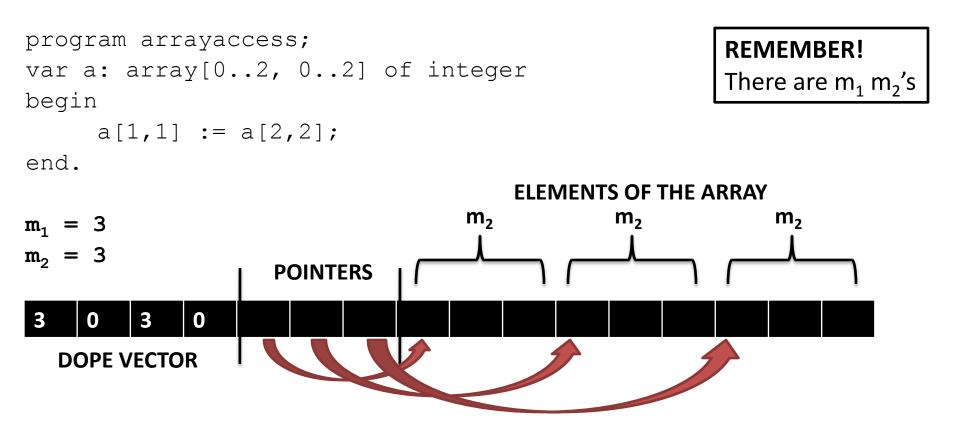
# Sample 2. Use multiplicative subscript calculation (with subscript checking)

```
program arrayaccess;
var a: array[1..2, 3..5] of integer
begin
    a[1,3] := 100;
end.
```



Practice: Show the storage representation of a

### Sample 3. Use indirect access (with subscript checking)

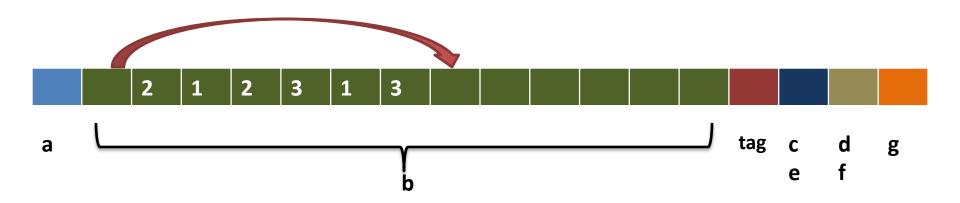


Practice: Show the storage representation of r

### Sample 4. Use MSC and dynamic TC.

Practice: Show the storage representation of r

#### Sample 4. Use MSC and dynamic TC.



#### **EXERCISES @ Home:**

- Now, use **indirect access (with subscript checking)** and still dynamic type checking to show r's storage representation.
- Btw, try experimenting in defining your own structures and showing their corresponding storage representations; and tracing in accessing elements. ©