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Customer Solutions

Phone: 0 905 / 624 90 00
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Plant designation	FMCP-3P-4CMMP-CPXE
Customer order no.	6800099354
Festo order number	5221134280
Material / Project no	23455210 / FMCP Master Drawig : 3 Phase , 4 CMMP , CPXE

2.9.4



Customer	
Name	FESTO CORPORATION
Plant	Customer plant
Street	5300 Explorer Dr,
Code postal: / location	L4W 5G4 Mississauga, ON

Type of project	37B1F6LX
Responsible for project	Zaid Faraj
Project name	MASTER-FMCP-1PH-4CMMP
Created	19.11.2021 / CA0ZF
Edit	13.07.2022 / ca0zfa
Approved	/
Revision 1	13.07.2022 / ca0zfa

Number of pages 65

FESTO assumes no warranty and liability for any changes to this documentation made by the customer. The circuit diagrams were created on the EPLAN Electric P8 and EPLAN Fluid CAE systems. Changes may only be made using the CAE systems and the original parameters.

Summarized parts list

Quantity	Order number	Type number	Designation	Σ Length [m]	Manufacturer
1	194E-A32-1753	194E	IEC Load Switch, Base/DIN Rail Mounting	0	Allen-Bradley (NFPA Data)
1	194L-G3394	194L	Shaft Extension	0	Allen-Bradley (NFPA Data)
1	194L-HE6G-175	194L	Handle for Front/Base Mounting, 64 x 64mm	0	Allen-Bradley (NFPA Data)
1	35A1804U	35A1804U	Cable 4 x 18AWG	0	AWP
1	216771	M22-L-W	Voyant lumineux, plat, blanc.	0	Eaton
3	550311	NEBM-M23G8-E-10-Q9N-LE8	Motor cable	30	Festo
3	550319	NEBM-M12W8-E-10-N-S1G15	Encoder cable	30	Festo
1	8150834	NEBM-M23G15-EH-10-Q7N-S1LEG21-CS		10	Festo
6	AT-C5-3BU-10PK		3FT Cat5e UTP 24AWG Ethernet Network	0	Festo
4	1622902	CMMP-AS-C5-3A-M0	Motor controller	0	Festo
3	550138	EMMS-AS-140-L-HS-RMB	Servo motor	0	Festo
1	5242219	EMMT-AS-60-L-HS-RMB	Servo motor	0	Festo
1	4252744	CPX-E-CEC-M1-EP	control unit	0	Festo
1	58812	8 port unmanaged switch	Xelity 8TX	0	Murrelektronik
1	9000-41068-0400000	MICO Basic 8.4	MICO BASIC 8.4 electronic circuit protection 8 CHANNELS	0	Murrelektronik
1	85442	85442	EMPARRO POWER SUPPLY 1-PHASE,	0	Murrelektronik
1	3000-33113-3020060	MIRO SAFE+ T 2 24	MIRO SAFE+ T 2 24 24 VAC/DC - 3 N/O contact / 2 N/O contact delayed	0	Murrelektronik
1	4000-73000-0010000	4000-73000-0010000	Connector (special)	0	Murrelektronik
4	2761622	SUBCON 25/M-SH	D-SUB bus connector	0	Phoenix Contact
1	3238124	SK.3238124	TopTherm fan-and-filter units	0	Rittal
38	2434340000	AMC 2.5	motor connection terminal	0	Weidmueller
1	BR1C06UC	BR1C06UC	Branch Rated Circuit Breaker - 6A	0	Weidmueller
4	BR1C15UC	BR1C15UC	Branch Rated Circuit Breaker - 15A	0	Weidmueller
1	1791010000	ZDK 2.5-2PE	Multi-tier modular terminal	0	Weidmueller
3	1791030000	ZDK 2.5-2V	Multi-tier modular terminal	0	Weidmueller

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Item parts list

Reference identification Placement	Quantity	Order number Type number	Designation	X-length Length [m]	Manufacturer	Identcode 1 Identcode 2
CB0120 =A1+O1&EFS/1.1	1	BR1C06UC BR1C06UC	Branch Rated Circuit Breaker - 6A		Weidmueller	
CB0130 =A1+O1&EFS/1.2	1	BR1C15UC BR1C15UC	Branch Rated Circuit Breaker - 15A		Weidmueller	
CB0140 =A1+O1&EFS/1.3	1	BR1C15UC BR1C15UC	Branch Rated Circuit Breaker - 15A		Weidmueller	
CB0150 =A1+O1&EFS/1.4	1	BR1C15UC BR1C15UC	Branch Rated Circuit Breaker - 15A		Weidmueller	
CB0160 =A1+O1&EFS/1.5	1	BR1C15UC BR1C15UC	Branch Rated Circuit Breaker - 15A		Weidmueller	
-CBL0510 =A1+O1&EFS/5.1	1	35A1804U 35A1804U	Cable 4 x 18AWG		AWP	
CBL2210 =A1+O1&EFS/22.0	1	550311 NEBM-M23G8-E-10-Q9N-LE8	Motor cable	10 m	Festo	
CBL2230 =A1+O1&EFS/22.3	1	550319 NEBM-M12W8-E-10-N-S1G15	Encoder cable	10 m	Festo	
CBL2610 =A1+O1&EFS/26.0	1	550311 NEBM-M23G8-E-10-Q9N-LE8	Motor cable	10 m	Festo	
CBL2630 =A1+O1&EFS/26.3	1	550319 NEBM-M12W8-E-10-N-S1G15	Encoder cable	10 m	Festo	
CBL3010 =A1+O1&EFS/30.0	1	550311 NEBM-M23G8-E-10-Q9N-LE8	Motor cable	10 m	Festo	
CBL3030 =A1+O1&EFS/30.3	1	550319 NEBM-M12W8-E-10-N-S1G15	Encoder cable	10 m	Festo	
CBL3410 =A1+O1&EFS/34.0	1	8150834 NEBM-M23G15-EH-10-Q7N-S1LEG21-CS		10 m	Festo	
CBL5010 =A1+O1&EFS/50.0	1	AT-C5-3BU-10PK	3FT Cat5e UTP 24AWG Ethernet Network		Festo	
-CBL5020 =A1+O1&EFS/50.2	1	AT-C5-3BU-10PK	3FT Cat5e UTP 24AWG Ethernet Network		Festo	

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Item parts list

Reference identification Placement	Quantity	Order number Type number	Designation	X-length Length [m]	Manufacturer	Identcode 1 Identcode 2
-CBL5030 =A1+O1&EFS/50.3	1	AT-C5-3BU-10PK	3FT Cat5e UTP 24AWG Ethernet Network		Festo	
-CBL5040 =A1+O1&EFS/50.4	1	AT-C5-3BU-10PK	3FT Cat5e UTP 24AWG Ethernet Network		Festo	
-CBL5050 =A1+O1&EFS/50.5	1	AT-C5-3BU-10PK	3FT Cat5e UTP 24AWG Ethernet Network		Festo	
-CBL5080 =A1+O1&EFS/11.4	1	AT-C5-3BU-10PK	3FT Cat5e UTP 24AWG Ethernet Network		Festo	
CMMP-AS-1 =A1+O1&EFS/21.0	1	1622902 CMMP-AS-C5-3A-M0	Motor controller		Festo	
CMMP-AS-2 =A1+O1&EFS/25.0	1	1622902 CMMP-AS-C5-3A-M0	Motor controller		Festo	
CMMP-AS-3 =A1+O1&EFS/29.0	1	1622902 CMMP-AS-C5-3A-M0	Motor controller		Festo	
CMMP-AS-4 =A1+O1&EFS/33.0	1	1622902 CMMP-AS-C5-3A-M0	Motor controller		Festo	
CON2300 =A1+O1&EFS/23.0	1	2761622 SUBCON 25/M-SH	D-SUB bus connector		Phoenix Contact	
CON2700 =A1+O1&EFS/27.0	1	2761622 SUBCON 25/M-SH	D-SUB bus connector		Phoenix Contact	
CON3100 =A1+O1&EFS/31.0	1	2761622 SUBCON 25/M-SH	D-SUB bus connector		Phoenix Contact	
CON3500 =A1+O1&EFS/35.0	1	2761622 SUBCON 25/M-SH	D-SUB bus connector		Phoenix Contact	
-DS0110 =A1+O1&EFS/1.1	1	194E-A32-1753 194E	IEC Load Switch, Base/DIN Rail Mounting		Allen-Bradley (NFPA Data)	
-DS0110 =A1+O1&EFS/1.1	1	194L-G3394 194L	Shaft Extension		Allen-Bradley (NFPA Data)	
-DS0110 =A1+O1&EFS/1.1	1	194L-HE6G-175 194L	Handle for Front/Base Mounting, 64 x 64mm		Allen-Bradley (NFPA Data)	

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Item parts list

Reference identification Placement	Quantity	Order number Type number	Designation	X-length Length [m]	Manufacturer	Identcode 1 Identcode 2
ETH5000 =A1+O1&EFS/50.0	1	58812 8 port unmanaged switch	Xelity 8TX		Murrelektronik	
FAN5530 =A1+O1&EFS/55.3	1	3238124 SK.3238124	TopTherm fan-and-filter units		Rittal	
FU0220 =A1+O1&EFS/2.3	1	9000-41068-0400000 MICO Basic 8.4	MICO BASIC 8.4 electronic circuit protection 8 CHANNELS		Murrelektronik	
-LT1 =A1+O1&EFS/2.2	1	216771 M22-L-W	Voyant lumineux, plat, blanc.		Eaton	
MOT1 =A1+O1&EFS/22.0	1	550138 EMMS-AS-140-L-HS-RMB	Servo motor		Festo	
MOT2 =A1+O1&EFS/26.0	1	550138 EMMS-AS-140-L-HS-RMB	Servo motor		Festo	
MOT3 =A1+O1&EFS/30.0	1	550138 EMMS-AS-140-L-HS-RMB	Servo motor		Festo	
MOT4 =A1+O1&EFS/34.0	1	5242219 EMMT-AS-60-L-HS-RMB	Servo motor		Festo	
PLC1102 =A1+O1&EFS/11.1	1	4252744 CPX-E-CEC-M1-EP	control unit		Festo	
-PSU211 =A1+O1&EFS/2.0	1	85442 85442	EMPARRO POWER SUPPLY 1-PHASE,		Murrelektronik	
-SR0510 =A1+O1&EFS/5.0	1	3000-33113-3020060 MIRO SAFE+ T 2 24	MIRO SAFE+ T 2 24 VAC/DC - 3 N/O contact / 2 N/O contact delayed		Murrelektronik	
-XF5080 =A1+O1&EFS/11.4	1	4000-73000-0010000 4000-73000-0010000	Connector (special)		Murrelektronik	

Technical notes

Voltage and frequency, as well as the setting points for motor protection and time relays must be checked prior to commissioning.

All terminal screws must be tightened prior to commissioning and during maintenance work

Keep doors closed at all times, as dust and moisture may cause malfunctioning.

The specified cable cross sections are minimum cross section for copper, without taking into account:

a.) Cable lengths and the resulting voltage drops. (Permissible voltage drop for motors according to VDE 0530 5%* Un)

b.) Type of cable installation and permissible ambient temperature (Installation type reduction factor 0,8 / amb. temp. 20° C)

In the event that operating voltages deviate from the assumed values listed above, correspondingly larger cross-sections must be selected.

(e.g. with increased voltage drop, increased ambient temp., unsuitable type of cable installation, high wiring density)

Sizing of cables is the responsibility of the customer

Air supply:

This controller is designed for a state-of-the-art (ISO 8573-A:2010) compressed air network

We require compressed air that is unlubricated, free of residual oil (residual oil from compressors max. 0.1mg/m³ for "HEES fluids, biodegradable oils" or max. 5mg/m³ for mineral oils permissible) and appropriately dried

A filter should remove solid contamination from the compressed air. (ISO 8573-A:2010)

Class:

7:4:4 --> 40µm Filter

Technical data

Reference identification =A1+O1

IP-degree of protection UL Type 1

Ambient temperature +5°C - +35°C

Humidity max. 50%

FLA Rating

CMMP-AS-C15-11A-P3-M3 13A

CMMP-AS-C5-11A-P3-M3 5.5A

Power Supply 0.55

FLA = (3x13) + (2x5.5) + 0.55 = 50.55 A

Sizing of disconnect switch as per UL508A standards section 30.2.2 : 63.18 A

Amacities of Main supply conductor as per UL508 standard table 28.1 : 8AWG

Pneumatics

Max. system pressure na

Working pressure na

Supply air connection Tube mm externally calibrated

Working ports according to circuit diagram

Special feature

No single-core marking

no hose designation

Wire colours used:

Power circuit: Black (BK)

Power circuit (permanent voltage): Yellow (YE)

Neutral conductor: Blue (BU)

Protective conductor: Green/yellow (GNYE)

Control circuit AC: Red (RD)

Control circuit DC (+): Dark blue (DBU)

Control circuit DC (-): Dark blue (DBU)

excepted circuits: Orange (OG)

Standards used:

NFPA 79 Electrical Standard for Industrial Machinery

UL 508A STANDARD FOR SAFETY Industrial Control Panels

EN 60204-1:2018 Safety of machinery - Electrical equipment of machines – Part 1: General requirements

EN ISO 4414:2010 Pneumatic fluid power - General rules and safety requirements for systems and their components

Hose used

PUN-H-.....-BL --> Control cabinet

PUN-H-.....-SW --> Control cabinet outside

PUN-H-...-NT --> Condensate drain

PUN-.....-BL --> M5-Series



5300 Explorer Drive , Mississauga, Ontario
Tel: 1-877-GO-FESTO Fax: 1-877-FX-FESTO
CONTROL PANEL

Part # / Project # : FMCP Master Drawig : 3 Phase , 4 CMMP , CPXE

Prod. Order / Serial #: CA_CS.2178969-A 1330719396

Year of Mfg.: 2021

Main Voltage 480 VAC FLA 50.5 A

Largest Motor: 7.8 A

Fault Rating: 5 KVA Control Voltage: 24V DC

Panel type: Type 1

Operating Pressure na

Level 4

Level 3

Level 2

Level 1



Level No.



Terminal No.

0	1	2	3	4	5	6	7	8	9
---	---	---	---	---	---	---	---	---	---

REV.	DESCRIPTION	DATE
------	-------------	------

ITEM NO.	PART NUMBER	DESCRIPTION	QTY.
1	FMCP Front ASSY	Enclosure	1
2	DS1 / 194E-A32-1753	Disconnect Switch	1
3	FU0220 / MURR.9000-41068-0400000	Smart Fuse	1
4	PSU211 / MURR.85442	Power Supply	1
5	BR1C6UC	Circuit Breaker 6A	1
6	BR1C15UC	Circuit Breaker 15A	4
7	RIT.3238124	Fan	1
8	AMC 2.5	Terminal Bank 1	12
9	MURR.58812	Ethernet Switch	1
10	AMC 2.5	Terminal Bank 2	12
11	1622902	Motor Controller	4

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		DRAWN	ca0zfa	2021-12-07	5300 Explorer Drive, Mississauga ON L4W 5G4 TEL: (905) 624-4600	
		UNLESS OTHERWISE SPECIFIED:			FILE NAME:	FMCP-UR_ASSY_CMMP
		DIMENSIONS ARE IN MILLIMETERS			TITLE:	
MATERIAL	TOLERANCES: x ±1 x.x ±0.1 x.xx ±0.01 ANGLES ±1°			DWG. NO.		REV
FINISH				-		
DO NOT SCALE DRAWING				SCALE: 1:7	SHEET 1 OF 1	

&MTB/1				8				7				6				5				4				3				2				1				&EFA/1			
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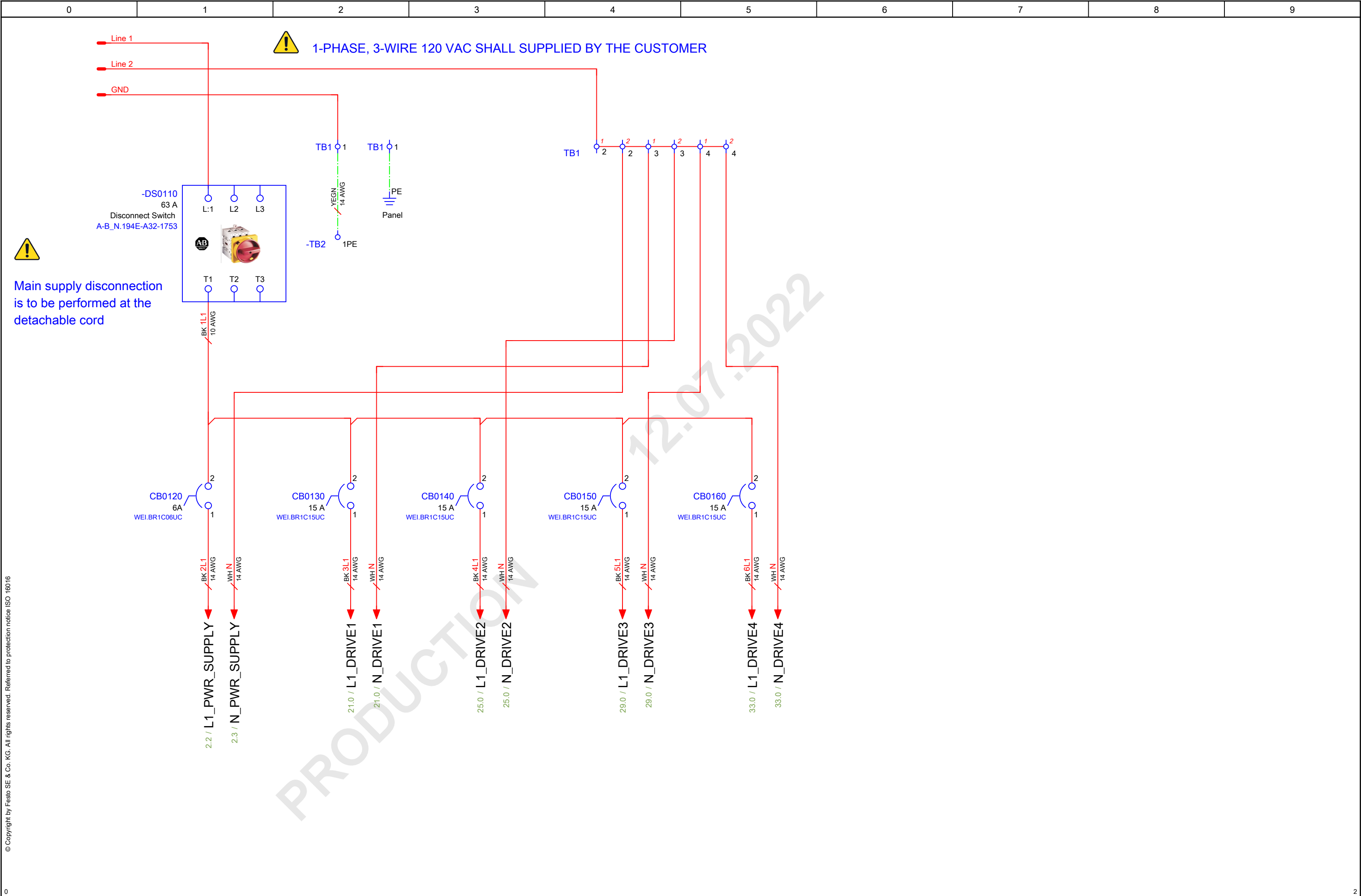
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00A.	12.07.2022	ca0zfa	Date	19.11.2021	CA0ZF A
	12.07.2022	ca0zfa	Edit by	12.07.2022	ca0zfa
			Appr.		
Modification	Date	Name	Standard	DIRECTIVE 2014/35/EU	

FESTO CORPORATION
FMCP-3P-4CMMP-CPXE

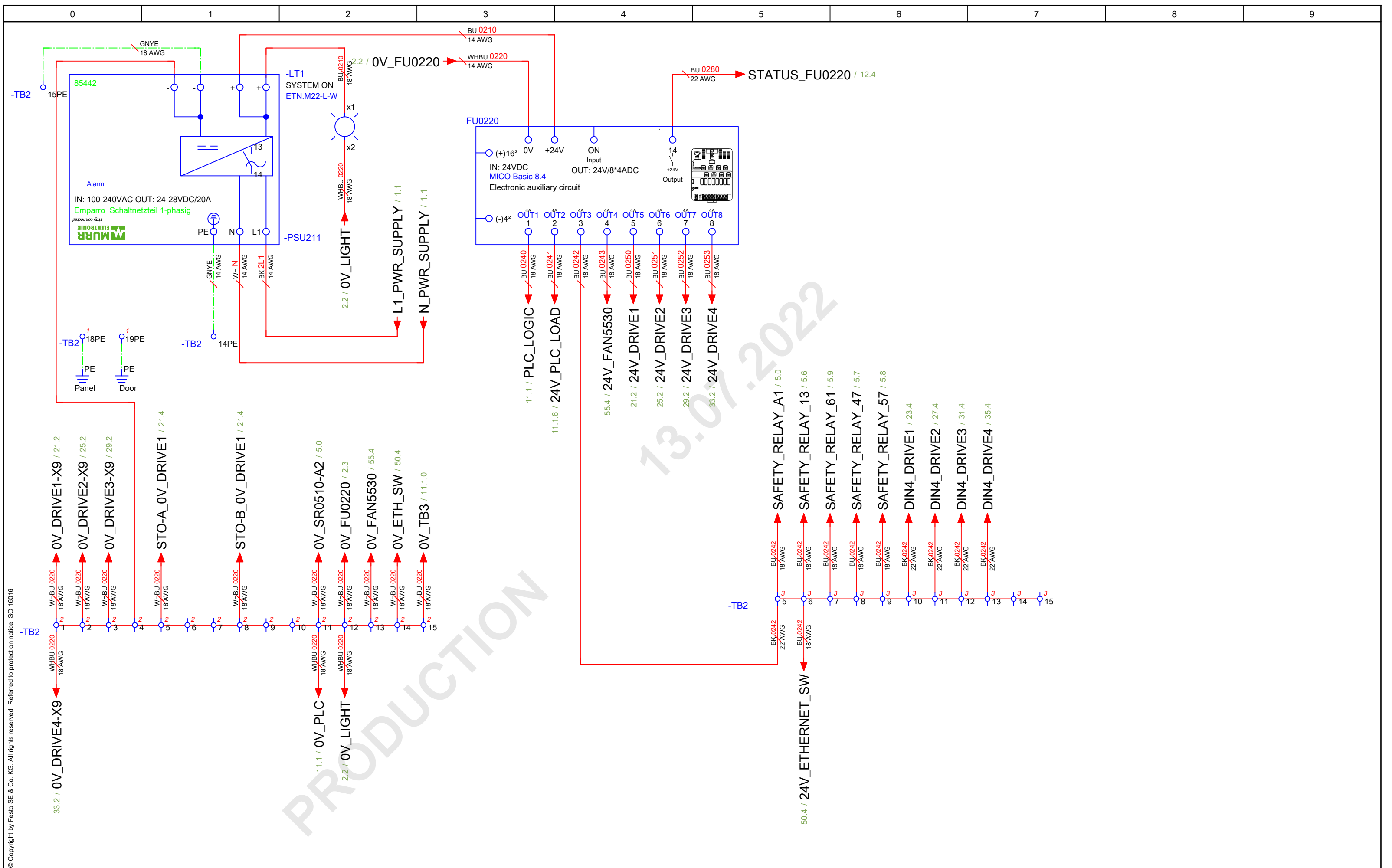
Control cabinet construction

EN &MTL	
Material no.:	23455210
Project no.: FMCP Master Drawig : 3 Phase , 4 CMMP , CPXE	
Productionorder: 001330719396	
Pg.	1
Pg.	1

13.07.2022



Project status		xxx			FESTO CORPORATION		MAIN AC	EN		&EFS			
00A.	12.07.2022	ca0zfa	Date	19.11.2021				CA0ZFA	Material no.:	23455210	=	A1	
1	01.02.2022	ca0zfa	Edit by	12.07.2022				ca0zfa			+	O1	
			Appr.										
Modification	Date	Name	Standard	DIRECTIVE 2014/35/EU									
					FMCP-3P-4CMMP-CPXE			Project no.:		FMCP Master Drawig : 3 Phase , 4 CMMP , CPXE		Pg.	1
								Productionorder:		001330719396		Pg.	60



Time setting (see Fig. 3 and 4)



DIP switch settings:

- The DIP switches are located underneath the front cover of the safety-monitoring module (see Fig. 3 and 4).
- Both DIP switches SW 1 (channel 1) and SW 2 (channel 2) must be set identically.
- The DIP switches can be set when the operating voltage is on; however, in order for the setting to be saved in the MIRO SAFE+ T 2 24, the voltage supply must be interrupted for approx. 3 seconds.
- The functionality of the setting must be checked.



Fig. 3



DIP switch setting	Drop-out delay	DIP switch setting	Drop-out delay
	<0,1 s		5.0 s
	0.5 s		8.5 s
	1.0 s		10.0 s
	1.5 s		12.0 s
	2.0 s		15.0 s
	2.5 s		20.0 s
	3.0 s		25.0 s
	4.0 s		30.0 s

PANEL WILL BE SHIPPED WITH THE SETTING MARKED ABOVE

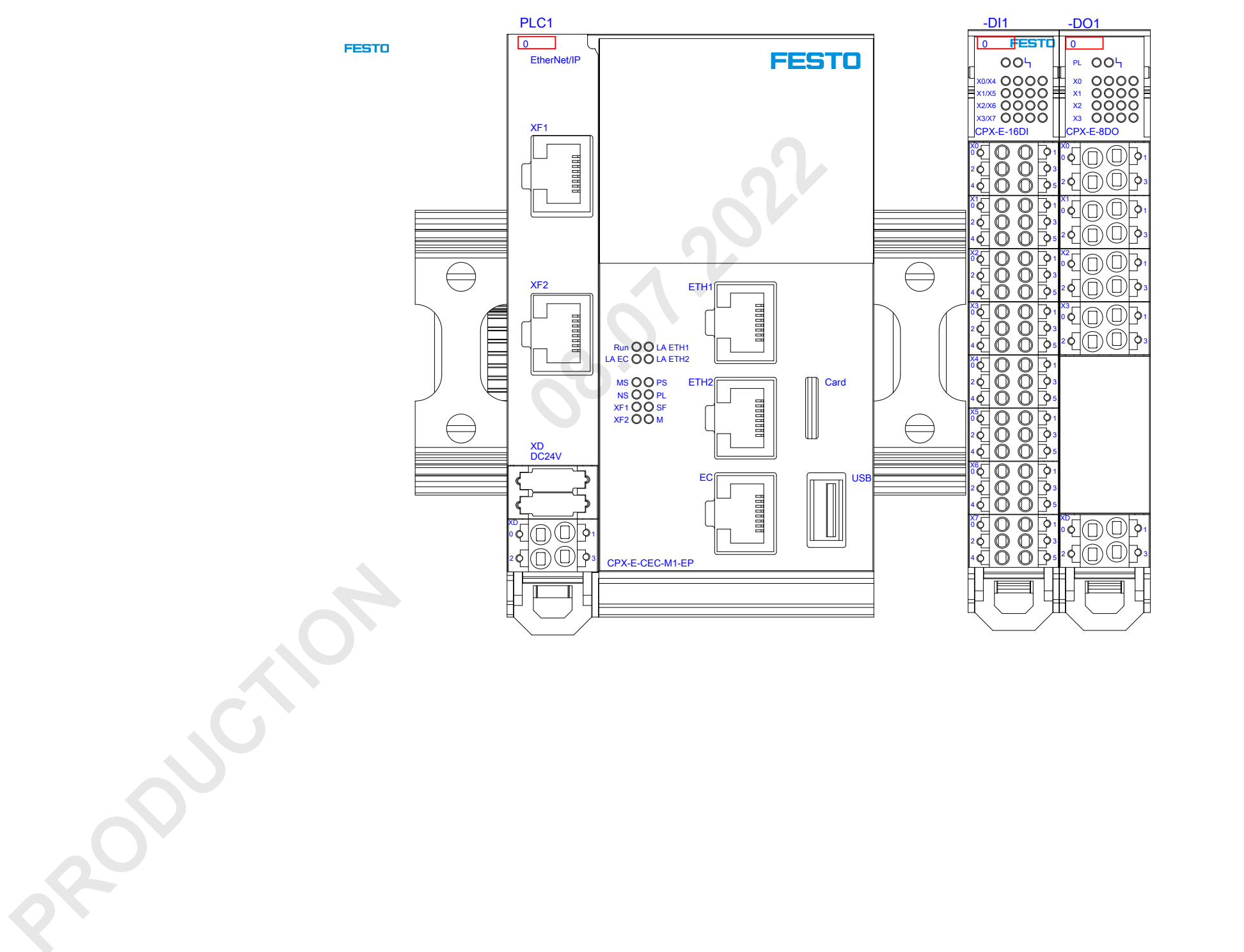
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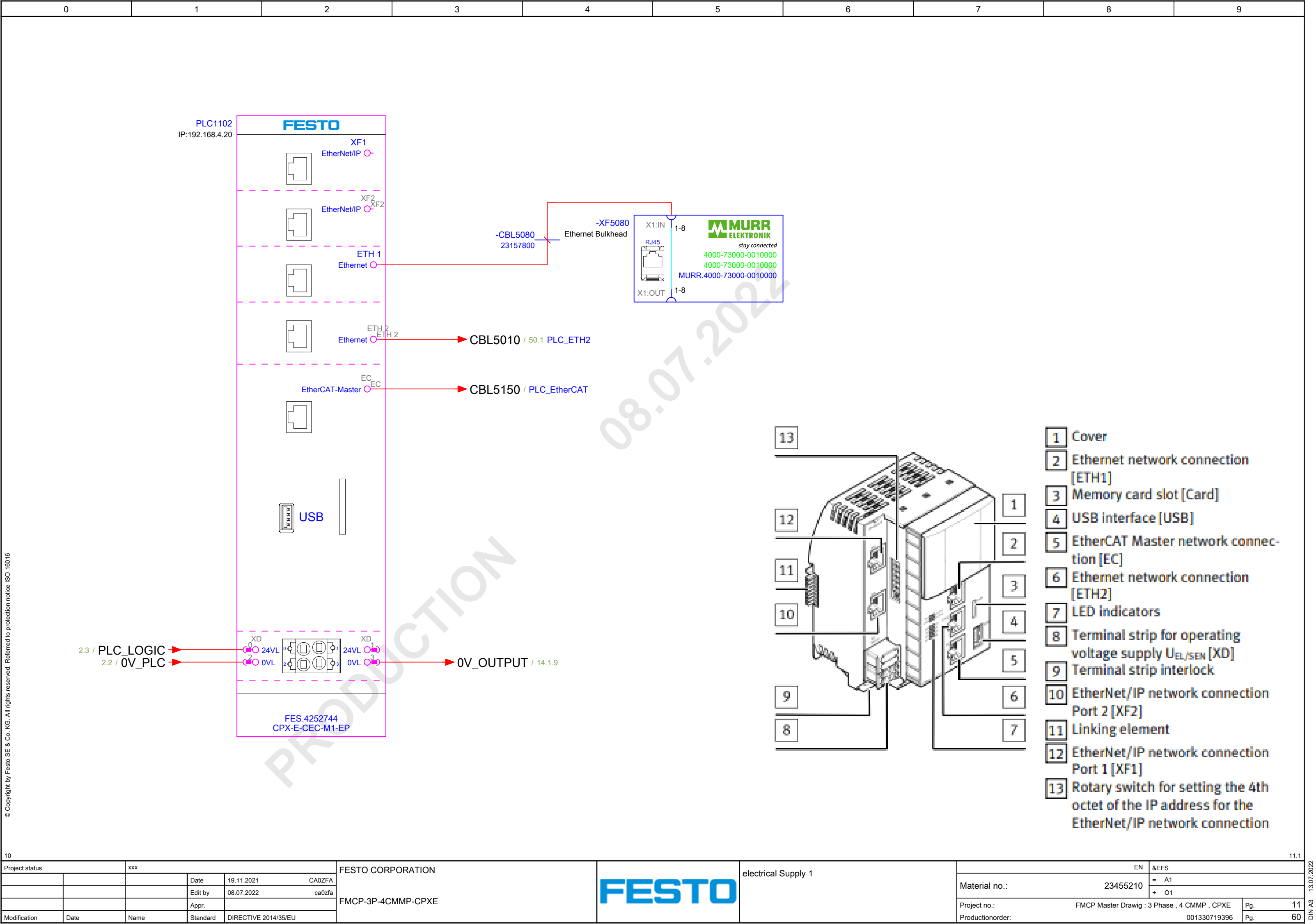
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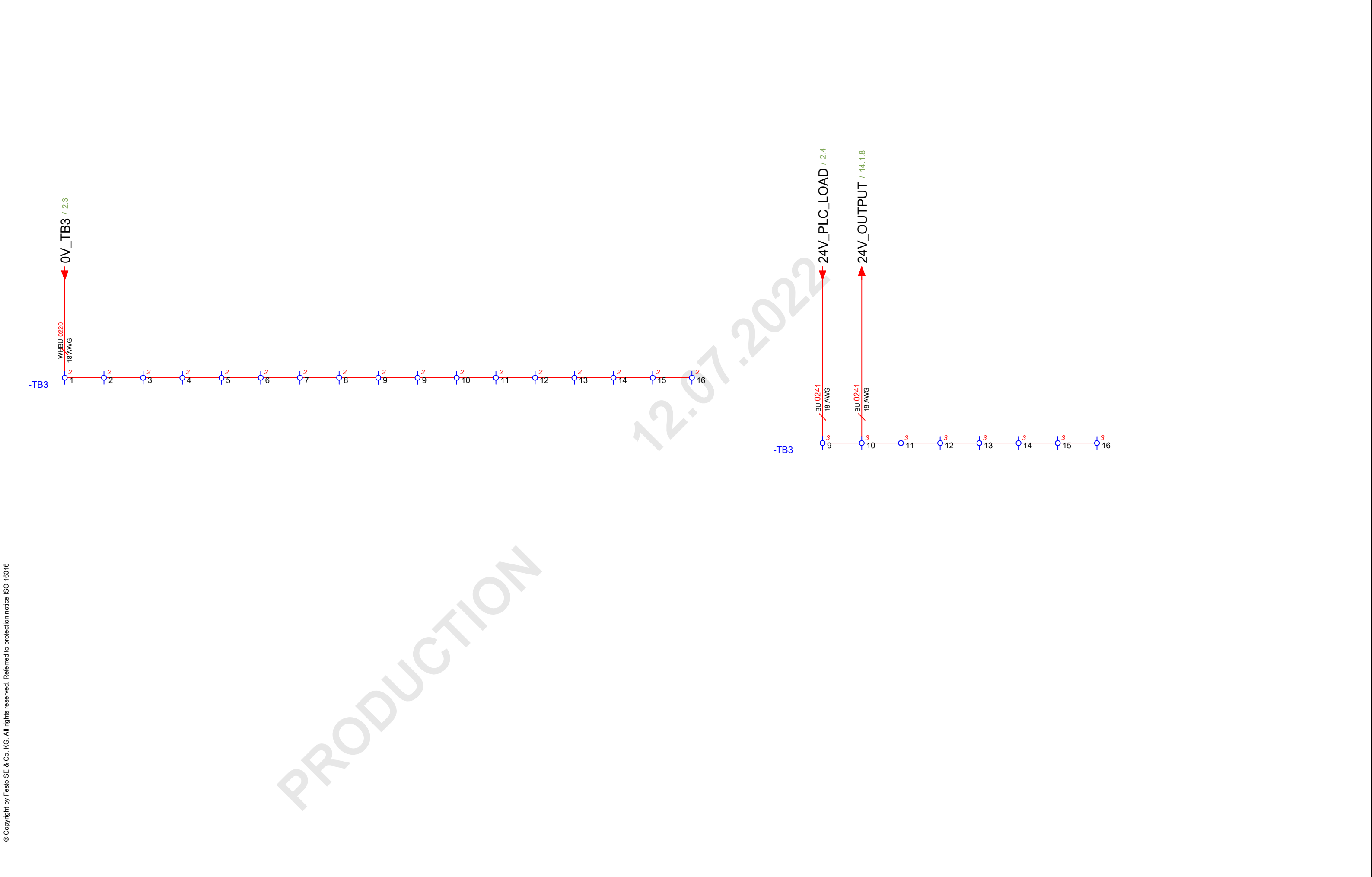
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Project status		xxx			FESTO CORPORATION		Panel - layout	EN &EFS	
		Date	19.11.2021	CA0ZF				Material no.: 23455210	= A1
		Edit by	08.07.2022	ca0zfa					+ O1
		Appr.							
								Project no.: FMCP Master Drawig : 3 Phase , 4 CMMP , CPXE	Pg. 10
Modification	Date	Name	Standard	DIRECTIVE 2014/35/EU	FMCP-3P-4CMMP-CPXE			Productionorder: 001330719396	Pg. 60

DIN A3 13.07.2022

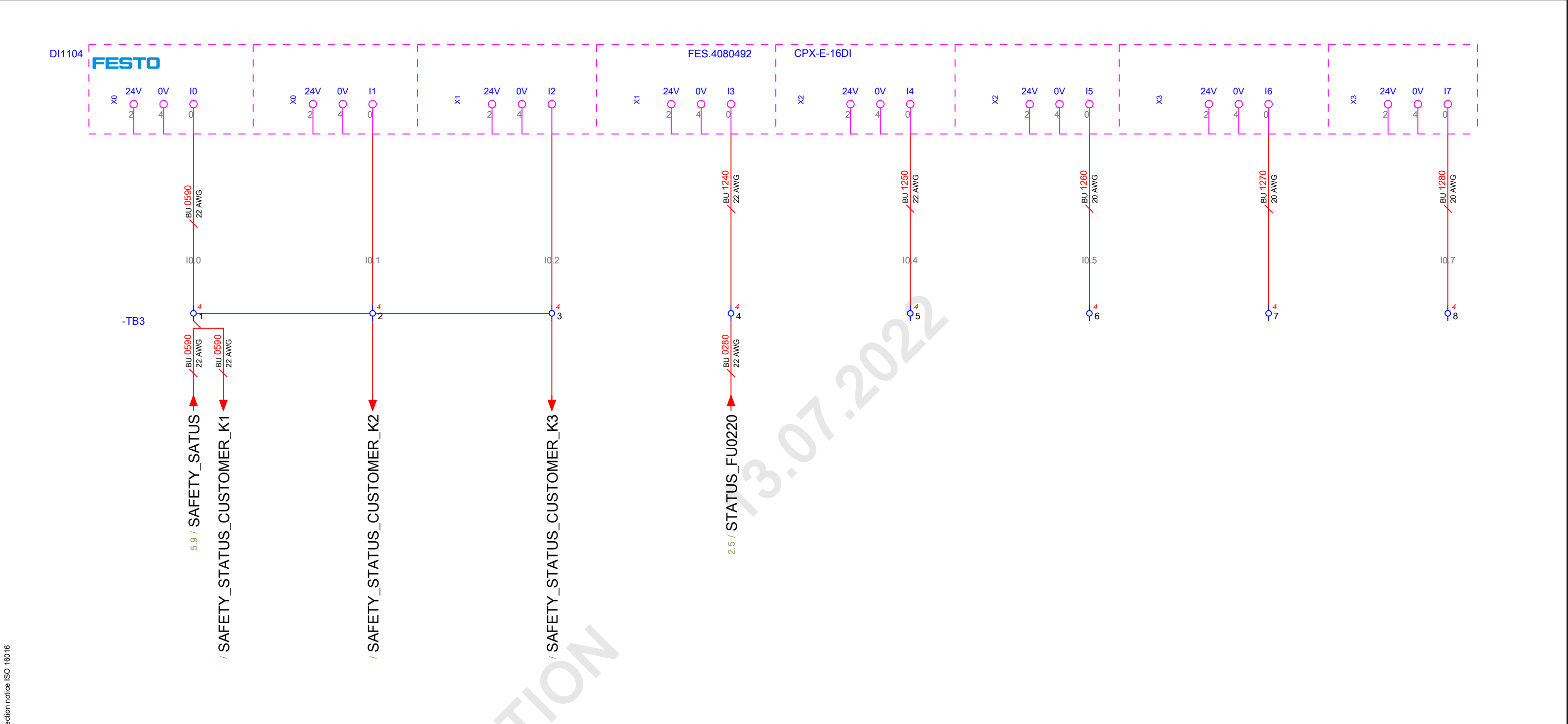








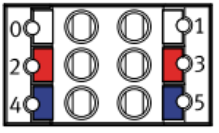
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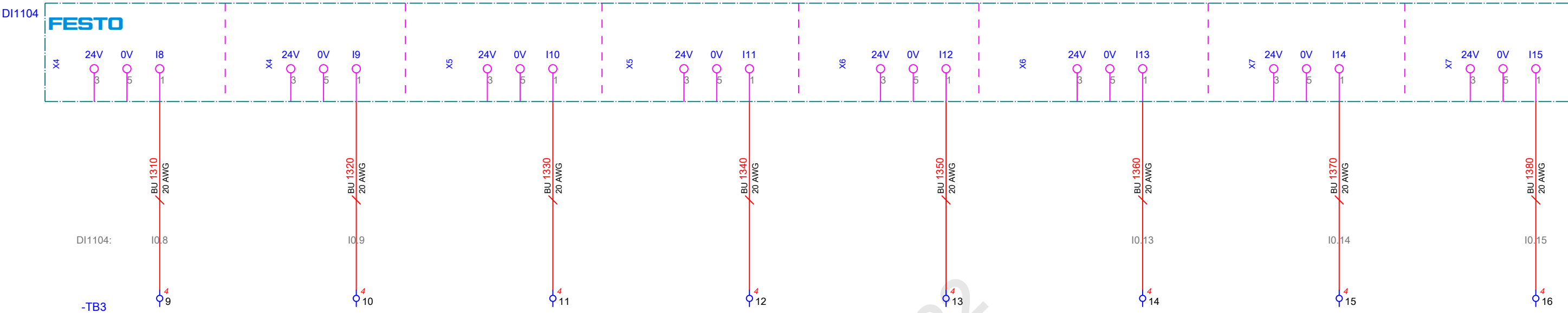
11					12																							
Project status		xxx			FESTO CORPORATION										External 24V and 0V Distribution Terminals					EN		&EFS						
00A.	12.07.2022	ca0zfa	Date	19.11.2021																CA0ZF	Material no.:		23455210			= A1		
			Edit by	12.07.2022																ca0zfa						+ O1		
			Appr.																									
Modification	Date	Name	Standard	DIRECTIVE 2014/35/EU																								
					FMCP-3P-4CMMP-CPXE										Project no.:					FMCP Master Drawig : 3 Phase , 4 CMMP , CPXE					Pg.		11.1	
															Productionorder:					001330719396					Pg.		60	



- 
 - The first three digital inputs are reserved for customer safety staus.
 - In case individual safety status signals are required for K1, K2 and K3:
 - Remove the jumper between terminal 1, 2 and 3 level (4).
 - Labels wires as required
- 

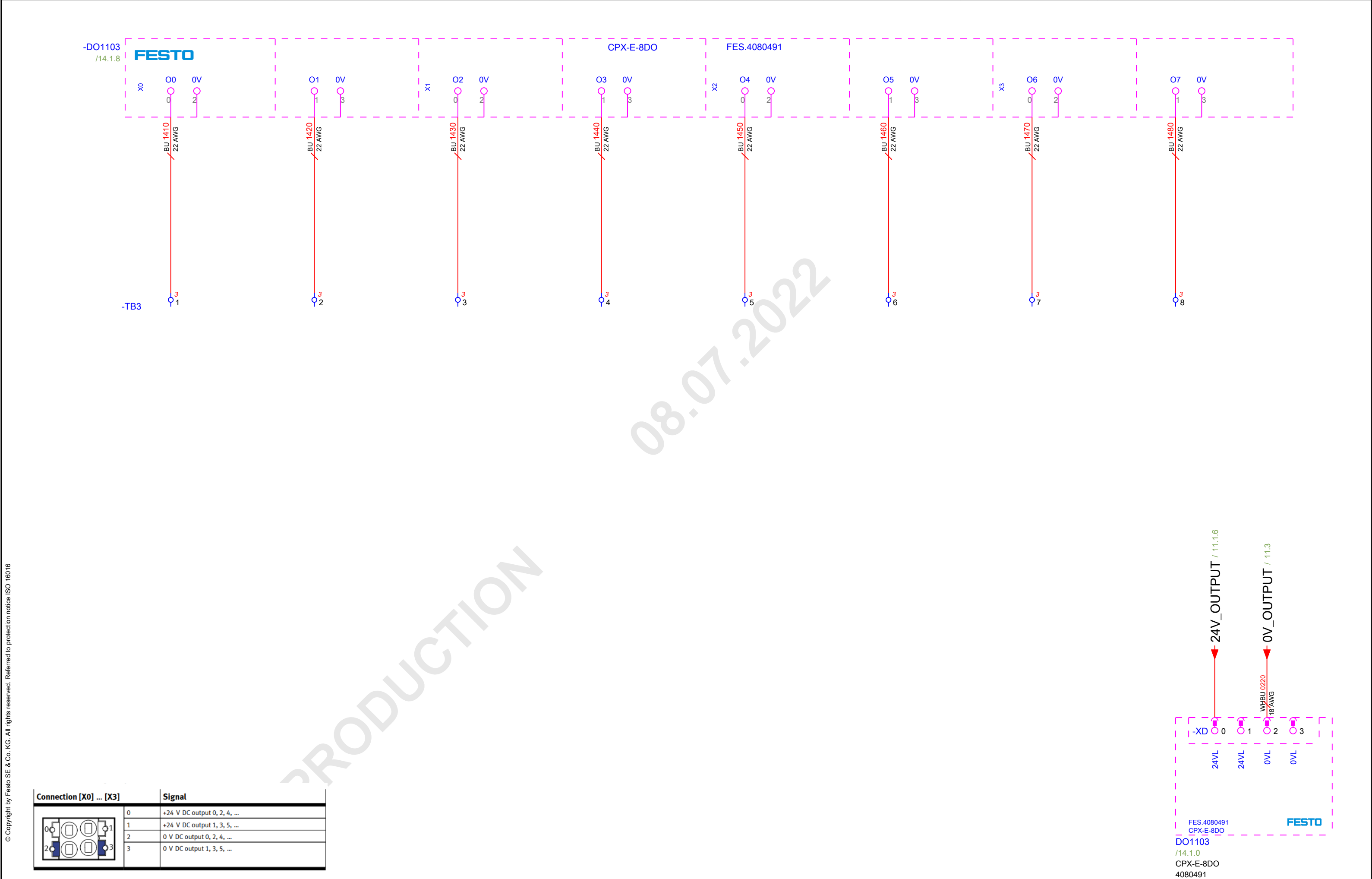
Input 4 and 5 are reserved for Mico Fuse status. These are optional and can be used differently if fuse status are not required .

Connection [X0] ... [X7]	Signal
	
0	Input 0, 2, 4, ...
1	Input 1, 3, 5, ...
2	+24 V DC input 0, 2, 4, ...
3	+24 V DC input 1, 3, 5, ...
4	0 V DC input 0, 2, 4, ...
5	0 V DC input 1, 3, 5, ...

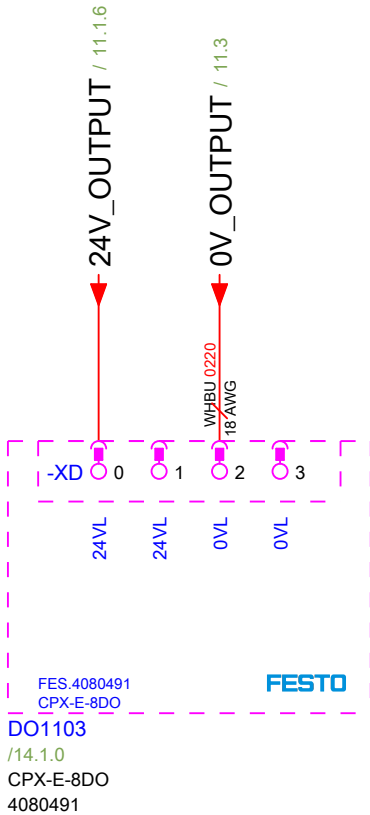


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12												14.1																				
Project status			xxx			FESTO CORPORATION FMCP-3P-4CMMP-CPXE												CPX-E-16DI						EN			&EFS					
																								Material no.:			23455210			= A1		
			Date																					19.11.2021			CA0ZFA					
			Edit by																					08.07.2022			ca0zfa					
			Appr.																													
Modification		Date		Name		Standard		DIRECTIVE 2014/35/EU						FMCP Master Drawig : 3 Phase , 4 CMMP , CPXE						Pg. 13												
												001330719396												Pg. 60								

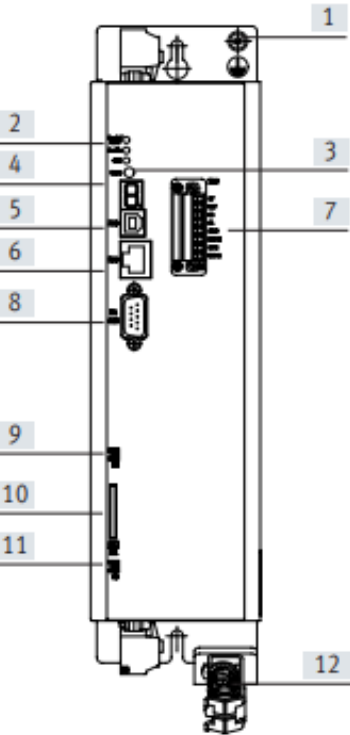


Connection [X0] ... [X3]	Signal
	0 +24 V DC output 0, 2, 4, ...
	1 +24 V DC output 1, 3, 5, ...
	2 0 V DC output 0, 2, 4, ...
	3 0 V DC output 1, 3, 5, ...



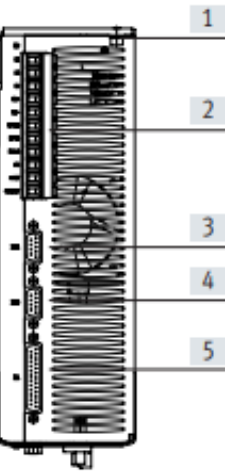
View of motor controller

CMMP-AS-...-M0



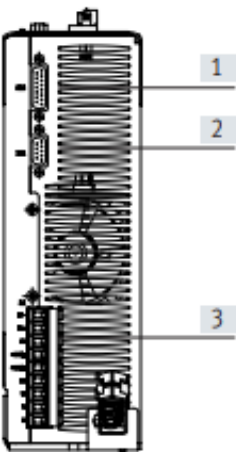
- [1] PE connection
- [2] LEDs
- [3] Reset button
- [4] Seven-segment display
- [5] X19 USB interface
- [6] X18 Ethernet interface
- [7] X40 digital I/O interface for controlling the STO function
- [8] X4 CANopen interface
- [9] Activation of CANopen terminating resistor
- [10] SD/MMC card slot
- [11] Activation of firmware download
- [12] Shield connection

From above



- [1] PE connection
- [2] X9 power supply
- [3] X11 incremental encoder inter-
face (output)
- [4] X10 incremental encoder inter-
face (input)
- [5] X1 I/O interface

From underneath



- [1] X2B encoder connection
- [2] X2A resolver connection
- [3] X6 motor connection

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[X6]1	Pin no.	Designation	Value	Specification
	1	Br-	0 V brake	Holding brake (motor), signal level dependent on switching status, high-side/low-side switch
	2	BR+	24 V brake	
	3	PE	PE	Cable shield for the holding brake and the temperature sensor (with Festo cables: n.c.)
	4	-MTdig	GND	Motor temperature sensor, N/C contact, N/O contact, PTC, KTY ...
	5	+MTdig	+3.3 V 5 mA	
	6	PE	PE	Protective earth conductor from the motor
	7	W	Technical data → Tab. A.9	Connection of the three motor phases
	8	V		
	9	U		

1) Representation of the plug on the device of the motor controller CMMP-AS-...-3A-M0

[X2B]	Pin no.	Designation	Value	Specification
	1	MT+	+3.3 V R _i = 2 kΩ	Temperature sensor, motor temperature, N/C contact, PTC, KTY ...
	9	U_SENS+	5 V ... 12 V	Sensor cable for the encoder supply
	2	U_SENS-	R _i ≈ 1 kΩ	
	10	US	5 V/12 V ±10% I _{max} = 300 mA	Operating voltage for high-resolution incremental encoder
	3	GND	0V	Reference potential for encoder supply and motor temperature sensor
	11	–		
	4	–		
	12	DATA	5 V _{SS} R _i ≈ 120 Ω	Bidirectional RS485 data cable (differential)
	5	DATA#		
	13	SCLK	5 V _{SS} R _i ≈ 120 Ω	RS485 clock output (differential)
	6	SCLK#		
	14	COS_Z0 1)	1 V _{SS} ±10% R _i ≈ 120 Ω	COSINE tracking signal (differential) from high-resolution incremental encoder
	7	COS_Z0 1)#		
	15	SIN_Z0 1)	1 V _{SS} ±10% R _i ≈ 120 Ω	SINE tracking signal (differential) from high-resolution incremental encoder
	8	SIN_Z0 1)#		

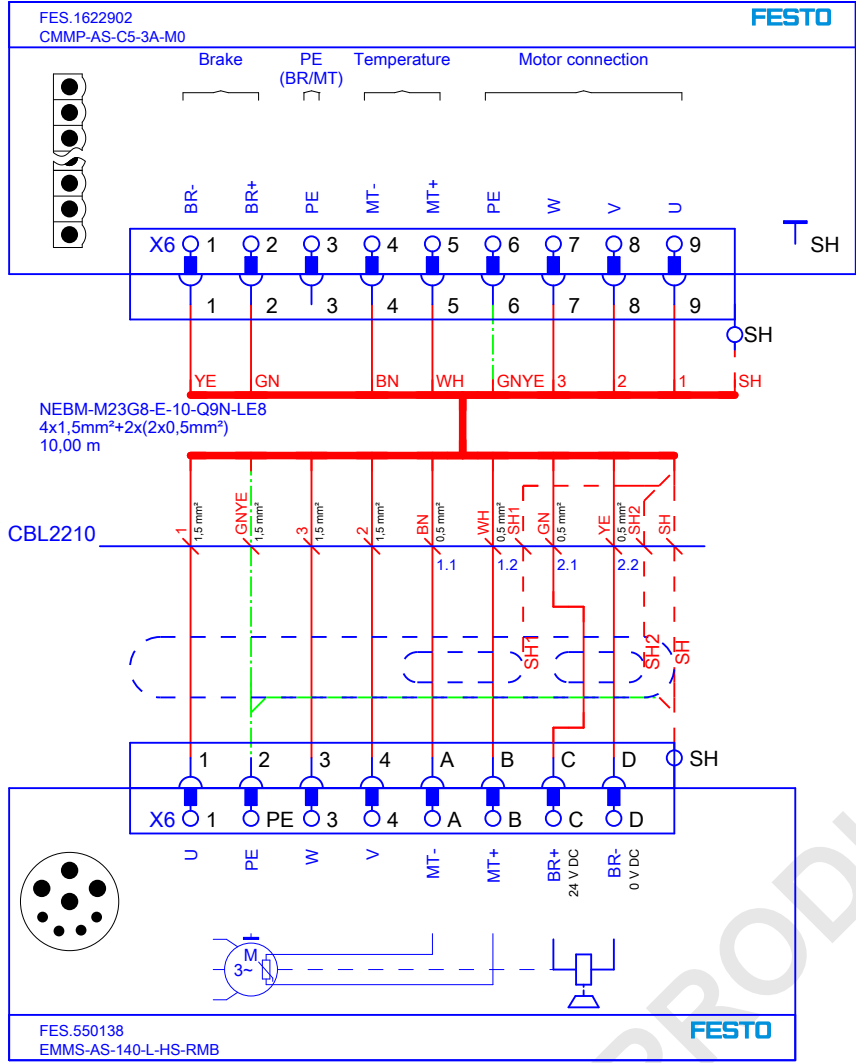
1) Heidenhain encoder: A=SIN_Z0; B=COS_Z0

Pin assienment: Incremental encoder with serial interface. e.e. EnDat – optional

Pin assignment [X2A]				
[X2A]	Pin no.	Designation	Value	Specification
	1	S2	3.5 V _{eff} 5-10 kHz R _i > 5 kΩ	SINE tracking signal, differential
	6	S4		
	2	S1	3.5 V _{eff} 5-10 kHz R _i > 5 kΩ	COSINE tracking signal, differential
	7	S3		
	3	AGND	0V	Screening for signal pairs (inner screening)
	8	MT-	GND	Reference potential for temperature sensor
	4	R1	7 V _{eff} 5-10 kHz I _A ≤ 150 mA _{eff}	Carrier signal for resolver
	9	R2	GND	
	5	MT+	+3.3 V R _i = 2 kΩ	Temperature sensor, motor temperature, N/C contact, PTC, KTY ...

/21.0

CMMP-AS-1

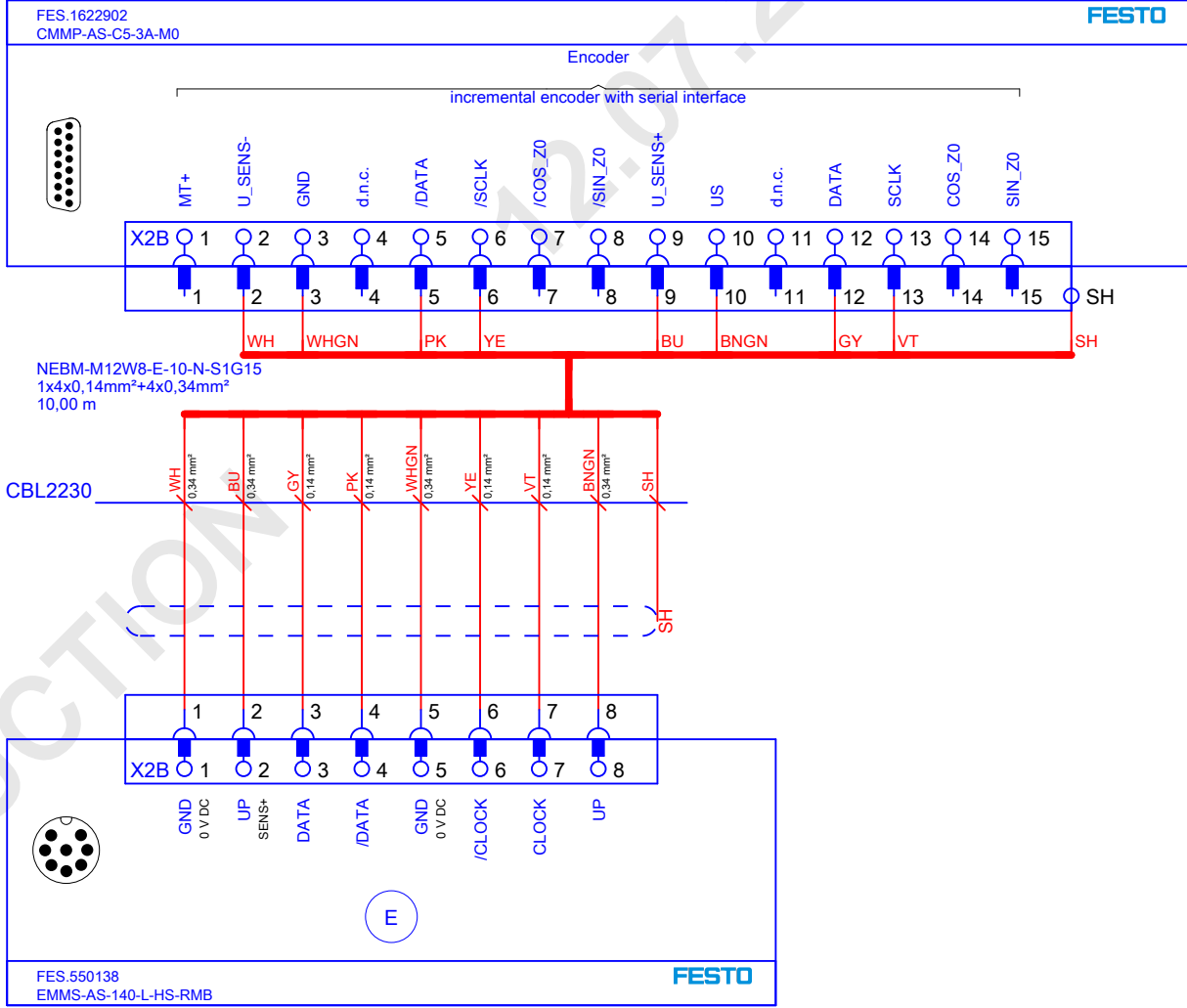


MOT1

/22.3

/21.0

CMMP-AS-1

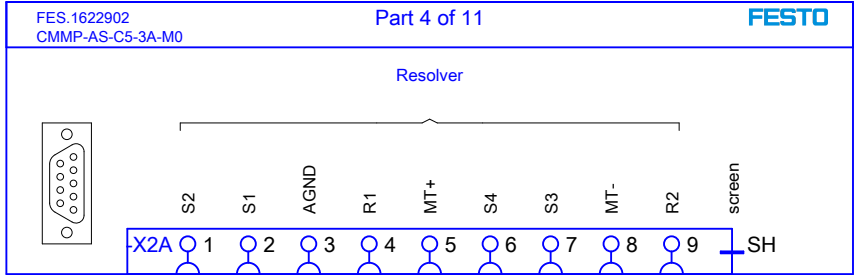


MOT1

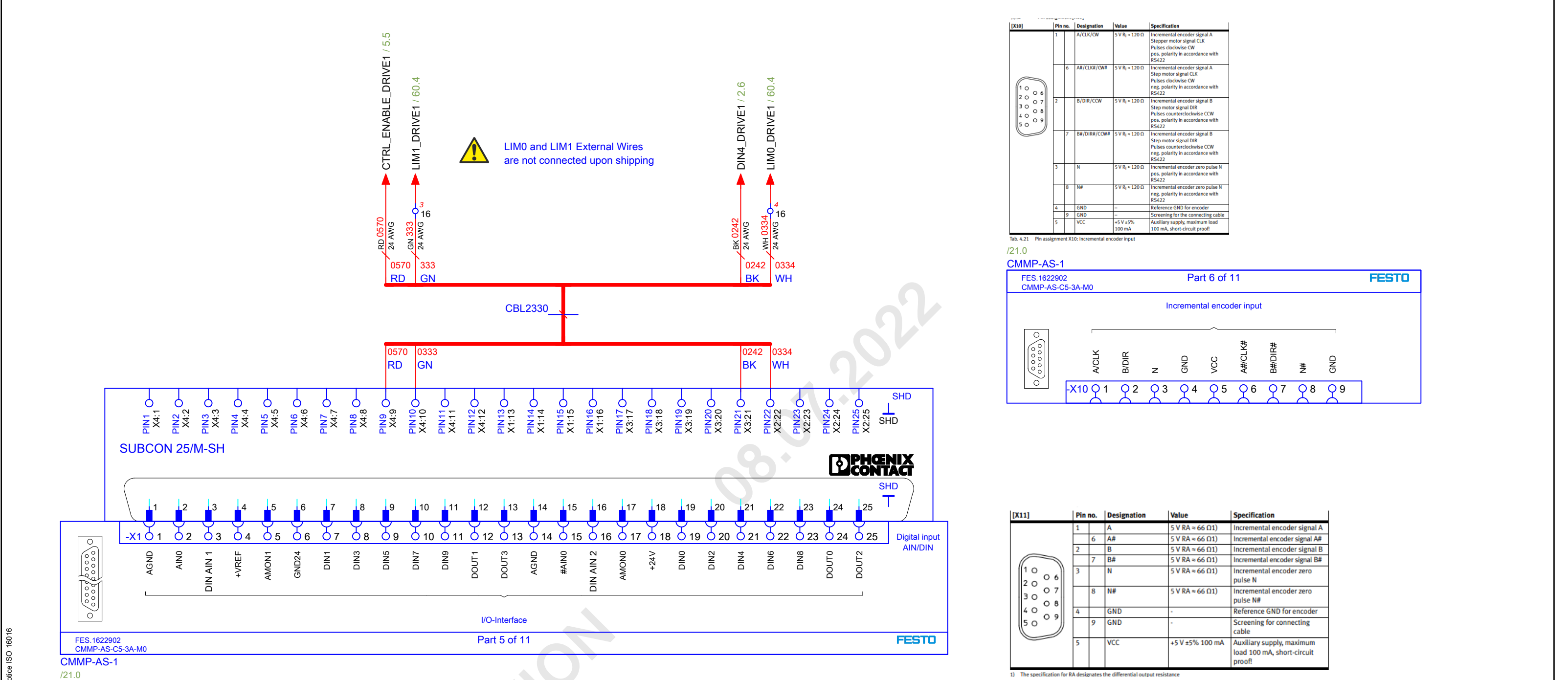
/22.0

/21.0

CMMP-AS-1



Servo shown in this page to show connection example only



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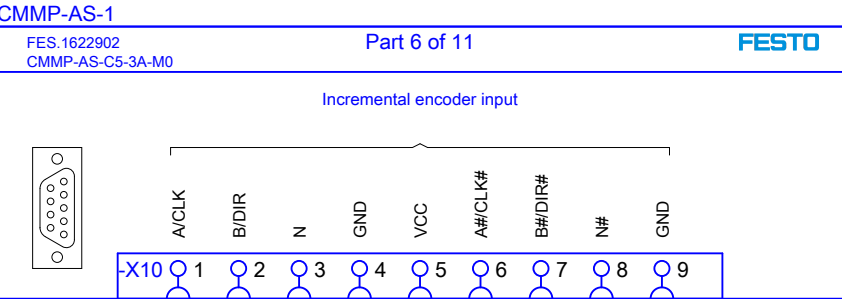
[X1]	Pin no.	Designation	Specification
	13	DOUT3	Output freely parameterisable, optionally parameterisable as DIN11
	25	DOUT2	Output freely parameterisable, optionally parameterisable as DIN10
	12	DOUT1	Output freely parameterisable
	24	DOUT0	Controller ready, output permanently assigned
	11	DIN 9	Fieldbus data profile (CiA 402, FHPP), input freely parameterisable
	23	DIN 8	Fieldbus activation communication, input freely parameterisable
	10	DIN7	Limit switch 1 (blocks n < 0), input permanently assigned
	22	DIN6	Limit switch 0 (blocks n > 0), input permanently assigned
	9	DIN5	Controller enable, input permanently assigned
	21	DIN4	End stage enable, input permanently assigned
	8	DIN 3	Fieldbus offset node number bit 3, input freely parameterisable
	20	DIN 2	Fieldbus offset node number bit 2, input freely parameterisable
	7	DIN 1	Fieldbus offset node number bit 1, input freely parameterisable
	19	DIN 0	Fieldbus offset node number bit 0, input freely parameterisable
	6	GND24	Reference potential for digital I/Os
	18	+24 V	24 V output
	5	AOUT1	Analogue output freely parameterisable
	17	AOUT0	Analogue output freely parameterisable
	4	+VREF	Reference output for setpoint potentiometer
	16	DIN13	Fieldbus transmission rate bit 1, optionally parameterisable as AIN2 ¹⁾
	3	DIN12	Fieldbus transmission rate bit 0, optionally parameterisable as AIN1 ¹⁾
	15	#AIN0	Setpoint input 0, differential analogue input
	2	AIN0	
	14	AGND	Reference potential for analogue signals
	1	AGND	Screening for analogue signals, AGND

1) Configuration with FCT. Observe not → Abschnitt 4.3.3.

[X10]	Pin no.	Designation	Value	Specification
	1	A/CLK/CW	5 V R _i = 120 Ω	Incremental encoder signal A Stepper motor signal CLK Pulses clockwise CW pos. polarity in accordance with RS422
	6	A#/CLK#/CW#	5 V R _i = 120 Ω	Incremental encoder signal A Step motor signal CLK Pulses clockwise CW neg. polarity in accordance with RS422
	2	B/DIR/CCW	5 V R _i = 120 Ω	Incremental encoder signal B Step motor signal DIR Pulses counterclockwise CCW pos. polarity in accordance with RS422
	7	B#/DIR#/CCW#	5 V R _i = 120 Ω	Incremental encoder signal B Step motor signal DIR Pulses counterclockwise CCW neg. polarity in accordance with RS422
	3	N	5 V R _i = 120 Ω	Incremental encoder zero pulse N pos. polarity in accordance with RS422
	8	N#	5 V R _i = 120 Ω	Incremental encoder zero pulse N neg. polarity in accordance with RS422
	4	GND	-	Reference GND for encoder
	9	GND	-	Screening for the connecting cable
	5	VCC	+5 V ±5% 100 mA	Auxiliary supply, maximum load 100 mA, short-circuit proof!

Tab. 4.21 Pin assignment X10: Incremental encoder input

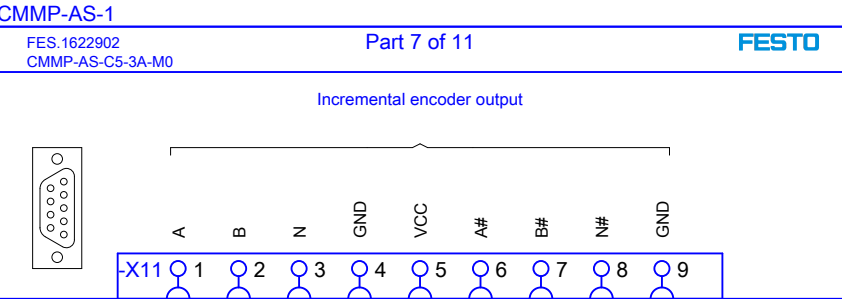
/21.0



[X11]	Pin no.	Designation	Value	Specification
	1	A	5 V R _A = 66 Ω1)	Incremental encoder signal A
	6	A#	5 V R _A = 66 Ω1)	Incremental encoder signal A#
	2	B	5 V R _A = 66 Ω1)	Incremental encoder signal B
	7	B#	5 V R _A = 66 Ω1)	Incremental encoder signal B#
	3	N	5 V R _A = 66 Ω1)	Incremental encoder zero pulse N
	8	N#	5 V R _A = 66 Ω1)	Incremental encoder zero pulse N#
	4	GND	-	Reference GND for encoder
	9	GND	-	Screening for connecting cable
	5	VCC	+5 V ±5% 100 mA	Auxiliary supply, maximum load 100 mA, short-circuit proof!

1) The specification for RA designates the differential output resistance

/21.0



Project status	xxx	Date	19.11.2021	CA0ZFA
		Edit by	08.07.2022	ca0zfa
		Appr.		
Modification	Date	Name	Standard	DIRECTIVE 2014/35/EU

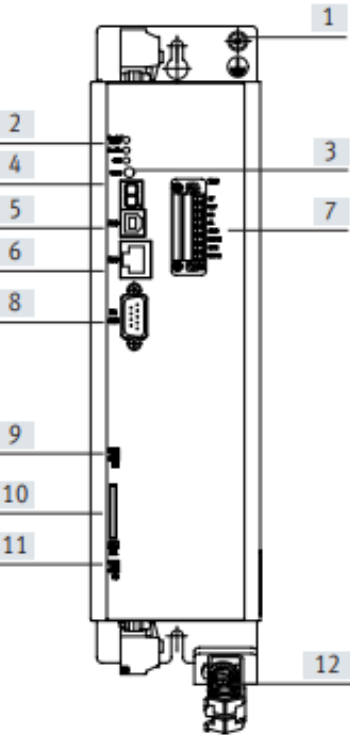
FESTO CORPORATION
FMCP-3P-4CMMP-CPXE



CMMP-AS-1:X1,X10,X11

EN	&EFS
Material no.:	23455210
Project no.:	FMCP Master Drawig : 3 Phase , 4 CMMP , CPXE
Productionorder:	001330719396

View of motor controller
CMMP-AS-...-M0



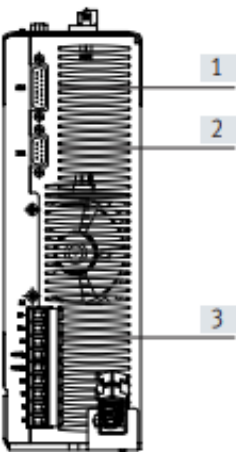
- [1] PE connection
- [2] LEDs
- [3] Reset button
- [4] Seven-segment display
- [5] X19 USB interface
- [6] X18 Ethernet interface
- [7] X40 digital I/O interface for controlling the STO function
- [8] X4 CANopen interface
- [9] Activation of CANopen terminating resistor
- [10] SD/MMC card slot
- [11] Activation of firmware download
- [12] Shield connection

From above



- [1] PE connection
- [2] X9 power supply
- [3] X11 incremental encoder interface (output)
- [4] X10 incremental encoder interface (input)
- [5] X1 I/O interface

From underneath

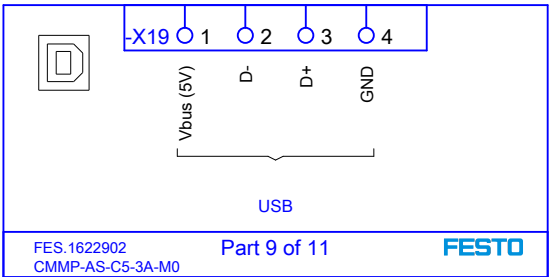
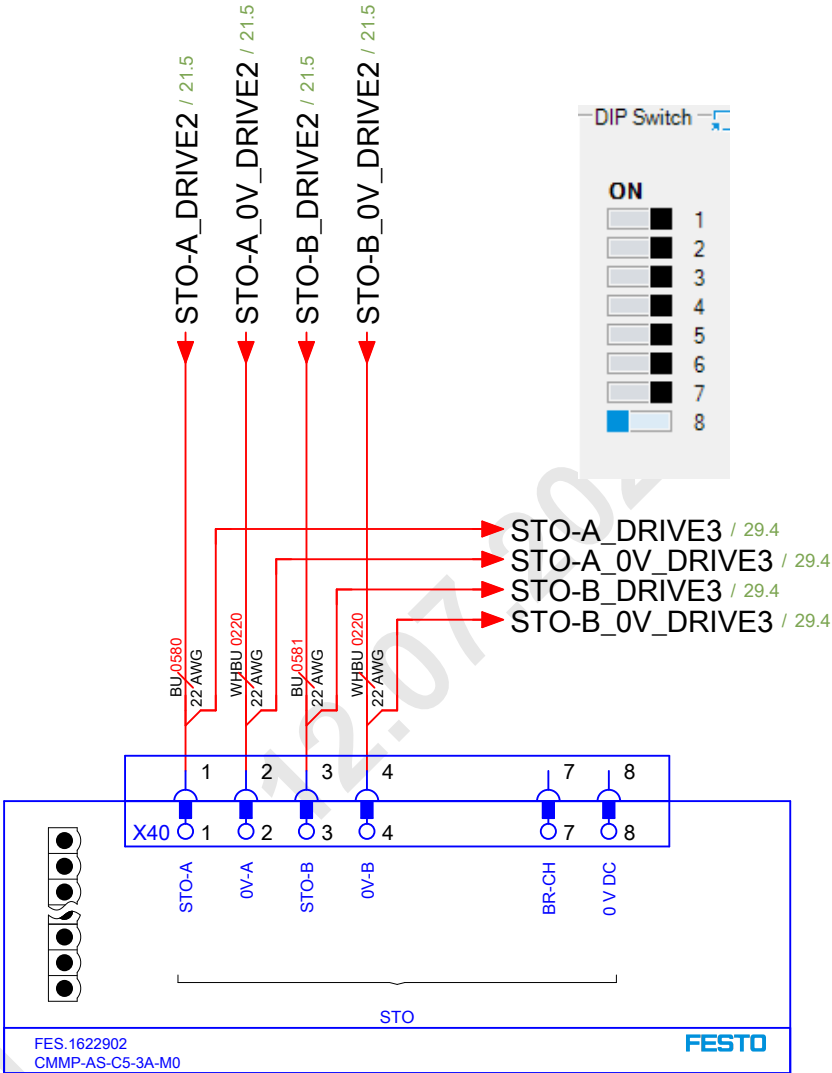
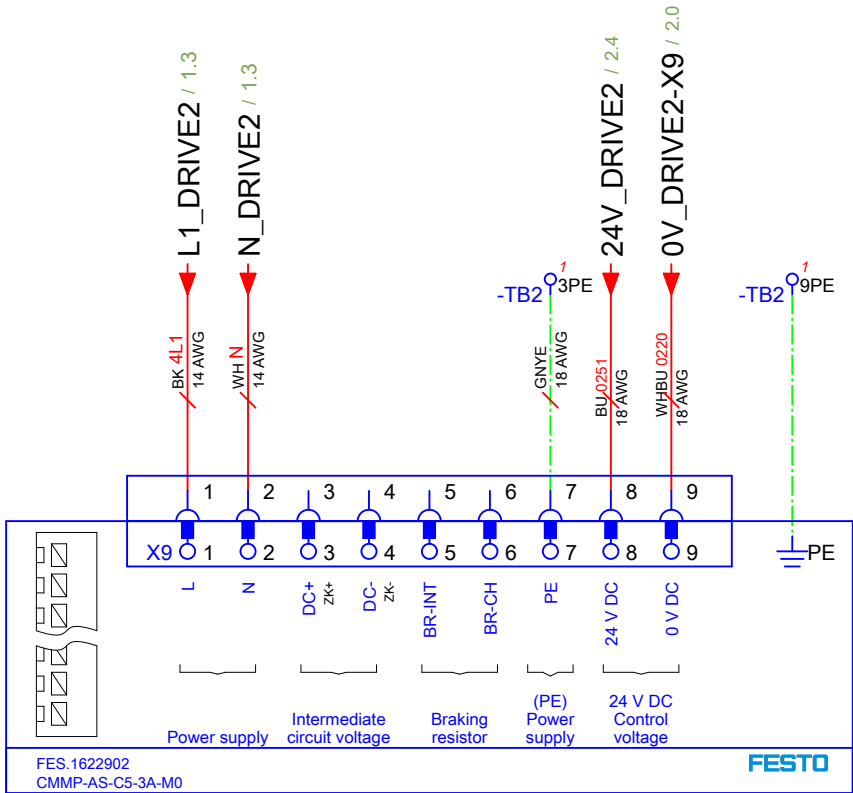


- [1] X2B encoder connection
- [2] X2A resolver connection
- [3] X6 motor connection

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/25.3
/25.6
/26.0
/26.3
/26.7
/27.0
/27.6
/27.6
/50.2



Note : Pin 5 (C1) and Pin 6 (C2) of Connector X40 are shown on the safety page.

4.8.2 Pin assignment [X9] – single-phase				
[X9]1	Pin no.	Designation	Value	Specification
	1	L	100 ... 230 V AC	Mains phase
	2	N	±10% 50 ... 60 Hz	Mains neutral conductor (reference potential)
	3	ZK+	60 ... 380 V DC	Alternative supply: Positive intermediate circuit voltage
	4	ZK-	GND_ZK	Alternative supply: Negative intermediate circuit voltage
	5	BR-INT	< 460 V DC	Internal braking resistor connection (bridge after BR-CH when using the internal resistor).
	6	BR-CH	< 460 V DC	Brake chopper connection for – internal braking resistor toward BR-INT – or – – external braking resistor against ZK+
	7	PE	PE	Connection for protective conductor from the mains
	8	+24 V	+24 V DC ±20%	Supply for control section, holding brake and I/O
	9	GND24 V	GND24 V DC	Reference potential for supply 0V

1) Representation of the contact strip on the motor controller CMMP-AS-...-3A-M0

[X40]1	Pin no.	Designation	Value	Specification
	8	0 V	0 V	Reference potential for auxiliary power supply.
	7	24 V	+24 V DC	Output for auxiliary power supply (24 V DC logic supply of the motor controller brought out).
	6	C2	–	Feedback contact for the status "STO" on an external controller.
	5	C1	–	Feedback contact for the status "STO" on an external controller.
	4	0V-B	0V	Reference potential for STO-B.
	3	STO-B	0 V / 24 V	Control port B for the function STO.
	2	0V-A	0 V	Reference potential for STO-A.
	1	STO-A	0V / 24V	Control port A for the function STO.

[X6]1	Pin no.	Designation	Value	Specification
	1	Br-	0 V brake	Holding brake (motor), signal level dependent on switching status, high-side/low-side switch
	2	BR+	24 V brake	
	3	PE	PE	Cable shield for the holding brake and the temperature sensor (with Festo cables: n.c.)
	4	-MTdig	GND	Motor temperature sensor, N/C contact, N/O contact, PTC, KTY ...
	5	+MTdig	+3.3 V 5 mA	
	6	PE	PE	Protective earth conductor from the motor
	7	W	Technical data → Tab. A.9	Connection of the three motor phases
	8	V		
	9	U		

1) Representation of the plug on the device of the motor controller CMMP-AS-...-3A-M0

[X2B]	Pin no.	Designation	Value	Specification
	1	MT+	+3.3 V R _i = 2 kΩ	Temperature sensor, motor temperature, N/C contact, PTC, KTY ...
	9	U_SENS+	5 V ... 12 V	Sensor cable for the encoder supply
	2	U_SENS-	R _i ≈ 1 kΩ	
	10	US	5 V/12 V ±10% I _{max} = 300 mA	Operating voltage for high-resolution incremental encoder
	3	GND	0V	Reference potential for encoder supply and motor temperature sensor
	11	–		
	4	–		
	12	DATA	5 V _{SS}	Bidirectional RS485 data cable (differential)
	5	DATA#	R _i ≈ 120 Ω	
	13	SCLK	5 V _{SS}	RS485 clock output (differential)
	6	SCLK#	R _i ≈ 120 Ω	
	14	COS_Z0 1)	1 V _{SS} ±10% R _i ≈ 120 Ω	COSINE tracking signal (differential) from high-resolution incremental encoder
	7	COS_Z0 1)#		
	15	SIN_Z0 1)	1 V _{SS} ±10% R _i ≈ 120 Ω	SINE tracking signal (differential) from high-resolution incremental encoder
	8	SIN_Z0 1)#		

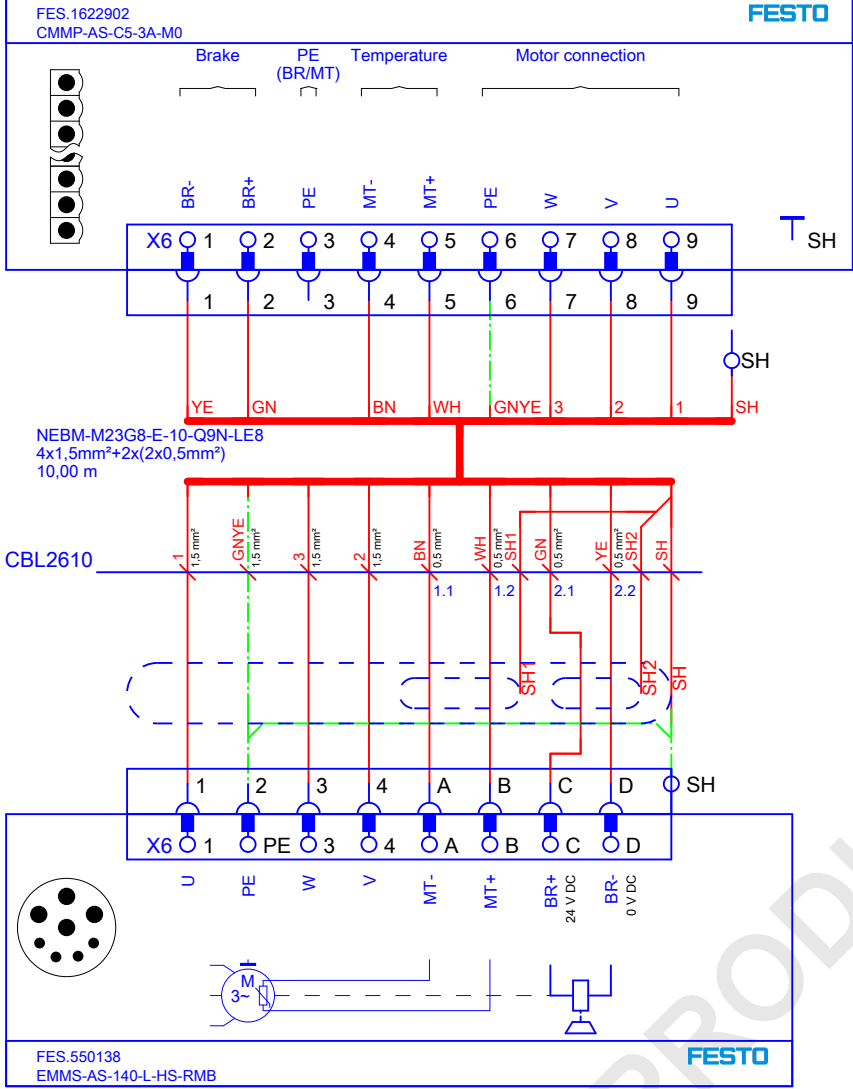
1) Heidenhain encoder: A=SIN_Z0; B=COS_Z0

Pin assienment: Incremental encoder with serial interface. e.e. EnDat – optional

Pin assignment [X2A]				
[X2A]	Pin no.	Designation	Value	Specification
	1	S2	3.5 V _{eff} 5-10 kHz R _i > 5 kΩ	SINE tracking signal, differential
	6	S4		
	2	S1	3.5 V _{eff} 5-10 kHz R _i > 5 kΩ	COSINE tracking signal, differential
	7	S3		
	3	AGND	0V	Screening for signal pairs (inner screening)
	8	MT-	GND	Reference potential for temperature sensor
	4	R1	7 V _{eff} 5-10 kHz I _A ≤ 150 mA _{eff}	Carrier signal for resolver
	9	R2	GND	
	5	MT+	+3.3 V R _i = 2 kΩ	Temperature sensor, motor temperature, N/C contact, PTC, KTY ...

/25.0

CMMP-AS-2

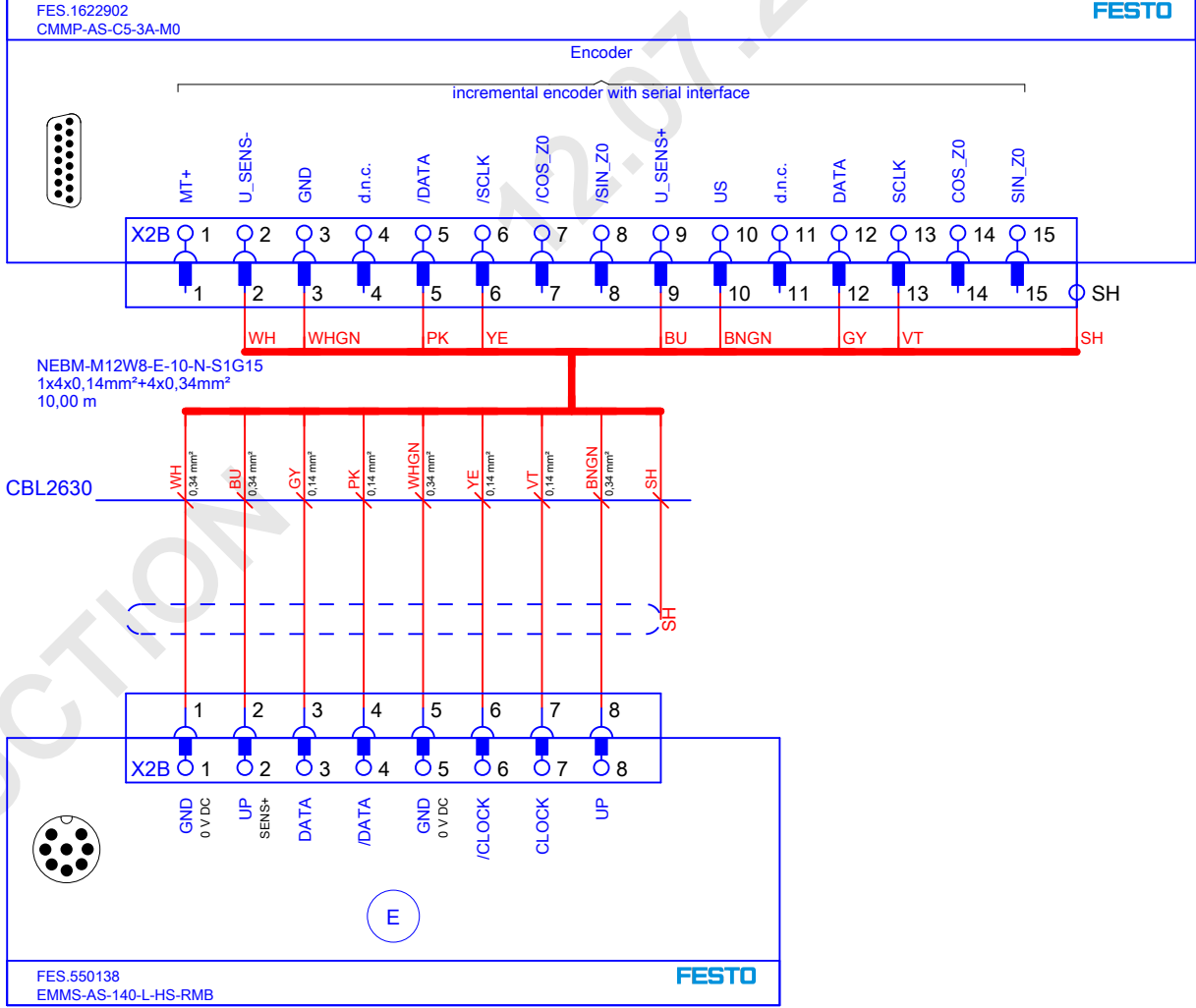


MOT2

/26.3

/25.0

CMMP-AS-2

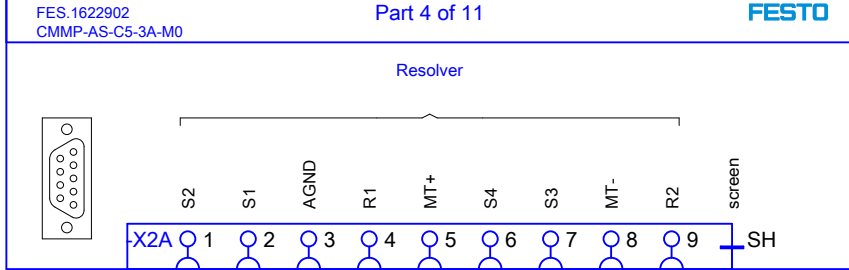


MOT2

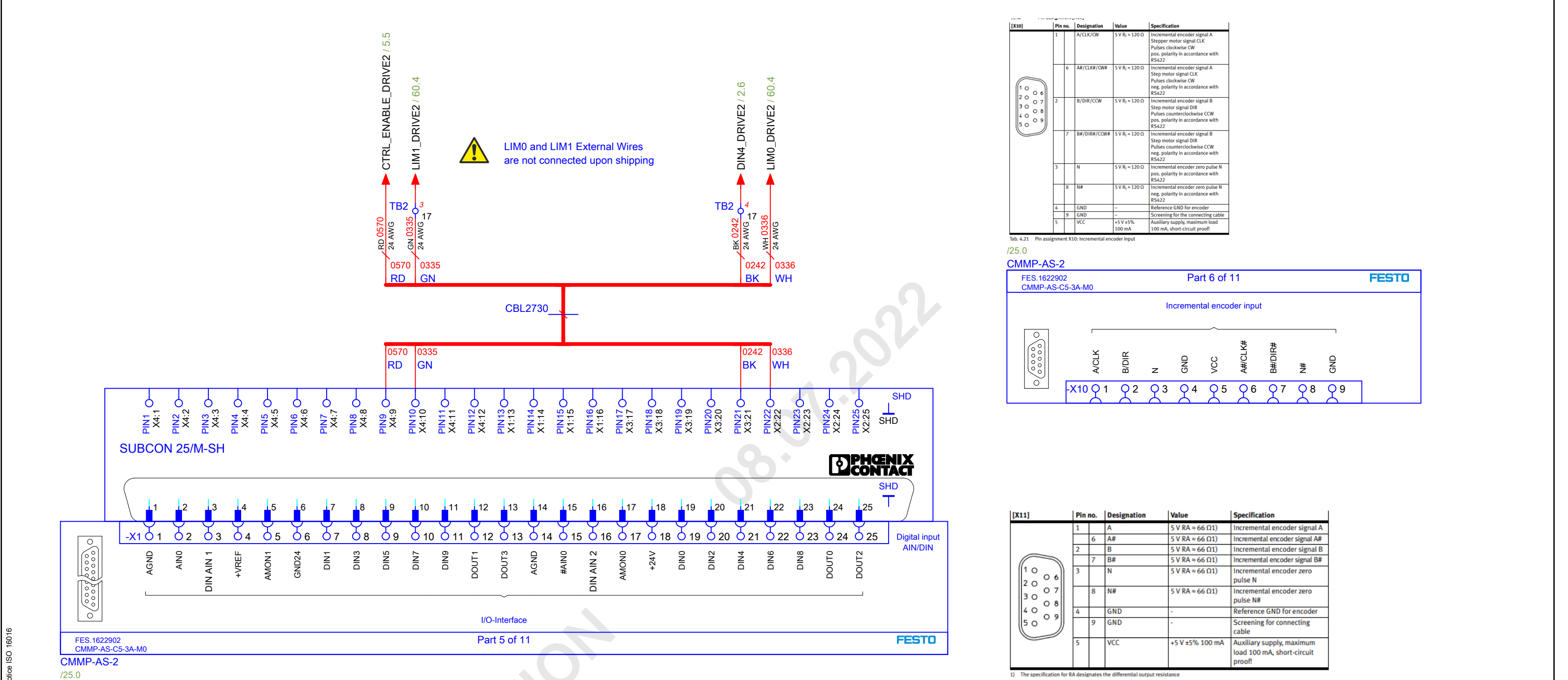
/26.0

/25.0

CMMP-AS-2



Servo shown in this page to show connection example only



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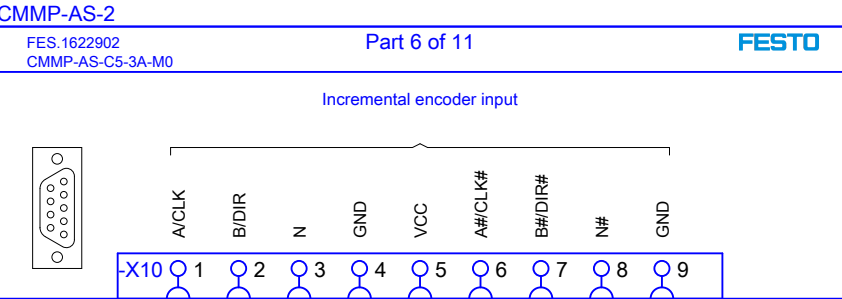
[X1]	Pin no.	Designation	Specification
	13	DOUT3	Output freely parameterisable, optionally parameterisable as DIN11
	25	DOUT2	Output freely parameterisable, optionally parameterisable as DIN10
	12	DOUT1	Output freely parameterisable
	24	DOUT0	Controller ready, output permanently assigned
	11	DIN 9	Fieldbus data profile (CiA 402, FHPP), input freely parameterisable
	23	DIN 8	Fieldbus activation communication, input freely parameterisable
	10	DIN7	Limit switch 1 (blocks n < 0), input permanently assigned
	22	DIN6	Limit switch 0 (blocks n > 0), input permanently assigned
	9	DIN5	Controller enable, input permanently assigned
	21	DIN4	End stage enable, input permanently assigned
	8	DIN 3	Fieldbus offset node number bit 3, input freely parameterisable
	20	DIN 2	Fieldbus offset node number bit 2, input freely parameterisable
	7	DIN 1	Fieldbus offset node number bit 1, input freely parameterisable
	19	DIN 0	Fieldbus offset node number bit 0, input freely parameterisable
	6	GND24	Reference potential for digital I/Os
	18	+24 V	24 V output
	5	AOUT1	Analogue output freely parameterisable
	17	AOUT0	Analogue output freely parameterisable
	4	+VREF	Reference output for setpoint potentiometer
	16	DIN13	Fieldbus transmission rate bit 1, optionally parameterisable as AIN2 ¹⁾
	3	DIN12	Fieldbus transmission rate bit 0, optionally parameterisable as AIN1 ¹⁾
	15	#AIN0	Setpoint input 0, differential analogue input
	2	AIN0	
	14	AGND	Reference potential for analogue signals
	1	AGND	Screening for analogue signals, AGND

1) Configuration with FCT. Observe not → Abschnitt 4.3.3.

[X10]	Pin no.	Designation	Value	Specification
	1	A/CLK/CW	5 V R _i = 120 Ω	Incremental encoder signal A Stepper motor signal CLK Pulses clockwise CW pos. polarity in accordance with RS422
	6	A#/CLK#/CW#	5 V R _i = 120 Ω	Incremental encoder signal A Step motor signal CLK Pulses clockwise CW neg. polarity in accordance with RS422
	2	B/DIR/CCW	5 V R _i = 120 Ω	Incremental encoder signal B Step motor signal DIR Pulses counterclockwise CCW pos. polarity in accordance with RS422
	7	B#/DIR#/CCW#	5 V R _i = 120 Ω	Incremental encoder signal B Step motor signal DIR Pulses counterclockwise CCW neg. polarity in accordance with RS422
	3	N	5 V R _i = 120 Ω	Incremental encoder zero pulse N pos. polarity in accordance with RS422
	8	N#	5 V R _i = 120 Ω	Incremental encoder zero pulse N neg. polarity in accordance with RS422
	4	GND	-	Reference GND for encoder
	9	GND	-	Screening for the connecting cable
	5	VCC	+5 V ±5% 100 mA	Auxiliary supply, maximum load 100 mA, short-circuit proof!

Tab. 4.21 Pin assignment X10: Incremental encoder input

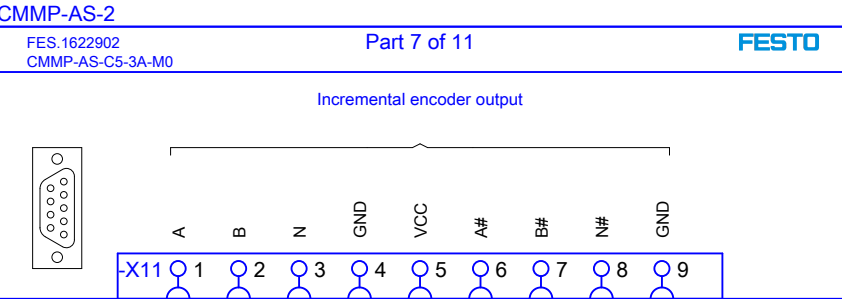
/25.0



[X11]	Pin no.	Designation	Value	Specification
	1	A	5 V R _A = 66 Ω1)	Incremental encoder signal A
	6	A#	5 V R _A = 66 Ω1)	Incremental encoder signal A#
	2	B	5 V R _A = 66 Ω1)	Incremental encoder signal B
	7	B#	5 V R _A = 66 Ω1)	Incremental encoder signal B#
	3	N	5 V R _A = 66 Ω1)	Incremental encoder zero pulse N
	8	N#	5 V R _A = 66 Ω1)	Incremental encoder zero pulse N#
	4	GND	-	Reference GND for encoder
	9	GND	-	Screening for connecting cable
	5	VCC	+5 V ±5% 100 mA	Auxiliary supply, maximum load 100 mA, short-circuit proof!

1) The specification for RA designates the differential output resistance

/25.0



Project status	xxx	Date	19.11.2021	CA0ZFA
		Edit by	08.07.2022	ca0zfa
		Appr.		
Modification	Date	Name	Standard	DIRECTIVE 2014/35/EU

FESTO CORPORATION
FMCP-3P-4CMMP-CPXE

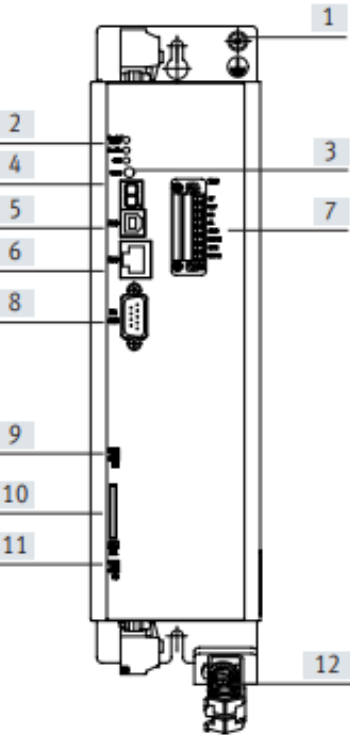


CMMP-AS-2:X1,X10,X11

EN	&EFS
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Project no.:	FMCP Master Drawig : 3 Phase , 4 CMMP , CPXE
Productionorder:	001330719396
Pg.	27
Pg.	60

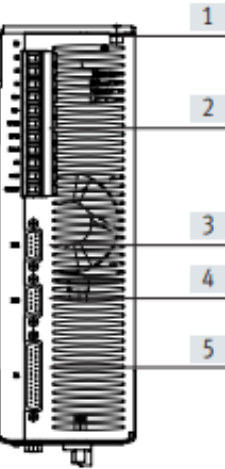
View of motor controller

CMMP-AS-...-M0



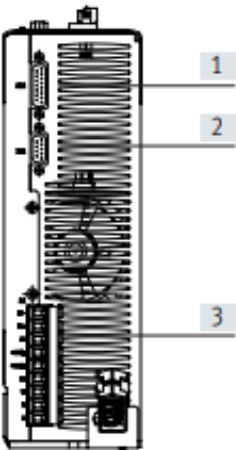
- [1] PE connection
- [2] LEDs
- [3] Reset button
- [4] Seven-segment display
- [5] X19 USB interface
- [6] X18 Ethernet interface
- [7] X40 digital I/O interface for controlling the STO function
- [8] X4 CANopen interface
- [9] Activation of CANopen terminating resistor
- [10] SD/MMC card slot
- [11] Activation of firmware download
- [12] Shield connection

From above



- [1] PE connection
- [2] X9 power supply
- [3] X11 incremental encoder inter-
face (output)
- [4] X10 incremental encoder inter-
face (input)
- [5] X1 I/O interface

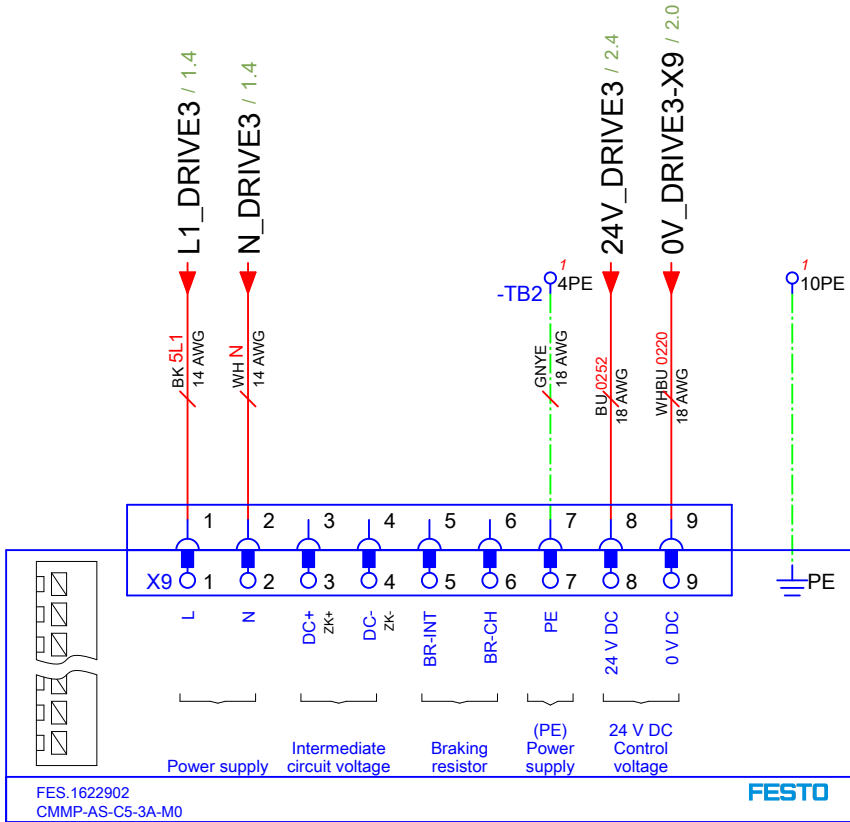
From underneath



- [1] X2B encoder connection
- [2] X2A resolver connection
- [3] X6 motor connection

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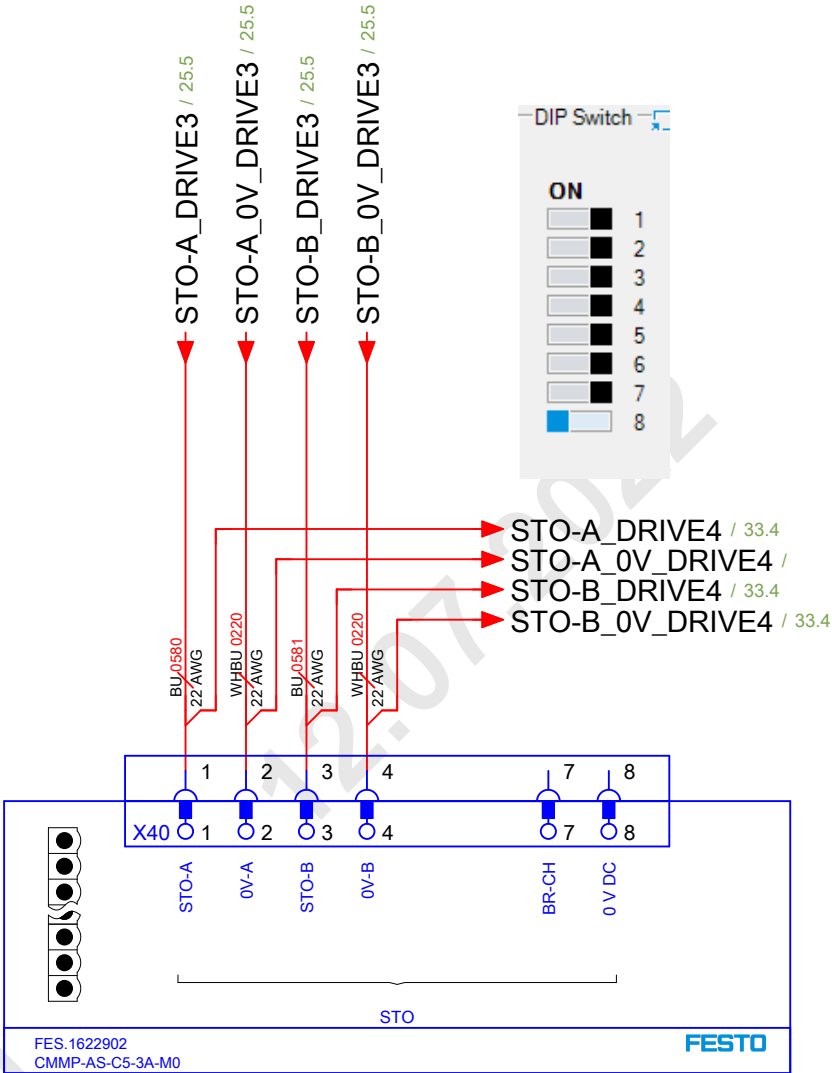
/29.3
/29.6
/30.0
/30.3
/31.0
/31.6
/31.6
/50.4



CMMP-AS-3

4.8.2 Pin assignment [X9] – single-phase				
[X9]1	Pin no.	Designation	Value	Specification
	1	L	100 ... 230 V AC	Mains phase
	2	N	±10% 50 ... 60 Hz	Mains neutral conductor (reference potential)
	3	ZK+	60 ... 380 V DC	Alternative supply: Positive intermediate circuit voltage
	4	ZK-	GND_ZK	Alternative supply: Negative intermediate circuit voltage
	5	BR-INT	< 460 V DC	Internal braking resistor connection (bridge after BR-CH when using the internal resistor).
	6	BR-CH	< 460 V DC	Brake chopper connection for – internal braking resistor toward BR-INT – or – – external braking resistor against ZK+
	7	PE	PE	Connection for protective conductor from the mains
	8	+24 V	+24 V DC ±20%	Supply for control section, holding brake and I/O
	9	GND24 V	GND24 V DC	Reference potential for supply 0V

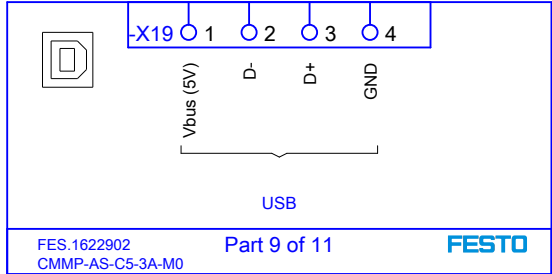
1) Representation of the contact strip on the motor controller CMMP-AS-...3A-M0



CMMP-AS-3

[X40]1	Pin no.	Designation	Value	Specification
	8	0 V	0 V	Reference potential for auxiliary power supply.
	7	24 V	+24 V DC	Output for auxiliary power supply (24 V DC logic supply of the motor controller brought out).
	6	C2	–	Feedback contact for the status "STO" on an external controller.
	5	C1	–	Feedback contact for the status "STO" on an external controller.
	4	0V-B	0V	Reference potential for STO-B.
	3	STO-B	0 V / 24 V	Control port B for the function STO.
	2	0V-A	0V	Reference potential for STO-A.
	1	STO-A	0V / 24V	Control port A for the function STO.

Note : Pin 5 (C 1) and Pin 6 (C 2) of Connector X40 are shown on the safety page.



CMMP-AS-3

Project status		xxx		
00A.	12.07.2022	ca0zfa	Date	19.11.2021 CA0ZFA
			Edit by	12.07.2022 ca0zfa
			Appr.	
Modification	Date	Name	Standard	DIRECTIVE 2014/35/EU

FESTO CORPORATION

FMCP-3P-4CMMP-CPXE

FESTO

CMMP-AS-3:X9,X40,X19

EN		&EFS	
Material no.:		23455210	
Project no.:		FMCP Master Drawig : 3 Phase , 4 CMMP , CPXE	
Productionorder:		001330719396	
Pg.		29	
Pg.		60	

[X6]1	Pin no.	Designation	Value	Specification
	1	Br-	0 V brake	Holding brake (motor), signal level dependent on switching status, high-side/low-side switch
	2	BR+	24 V brake	
	3	PE	PE	Cable shield for the holding brake and the temperature sensor (with Festo cables: n.c.)
	4	-MTdig	GND	Motor temperature sensor, N/C contact, N/O contact, PTC, KTY ...
	5	+MTdig	+3.3 V 5 mA	
	6	PE	PE	Protective earth conductor from the motor
	7	W	Technical data → Tab. A.9	Connection of the three motor phases
	8	V		
	9	U		

1) Representation of the plug on the device of the motor controller CMMP-AS-...-3A-M0

[X2B]	Pin no.	Designation	Value	Specification
	1	MT+	+3.3 V R _i = 2 kΩ	Temperature sensor, motor temperature, N/C contact, PTC, KTY ...
	9	U_SENS+	5 V ... 12 V	Sensor cable for the encoder supply
	2	U_SENS-	R _i ≈ 1 kΩ	
	10	US	5 V/12 V ±10% I _{max} = 300 mA	Operating voltage for high-resolution incremental encoder
	3	GND	0V	Reference potential for encoder supply and motor temperature sensor
	11	–		
	4	–		
	12	DATA	5 V _{SS} R _i ≈ 120 Ω	Bidirectional RS485 data cable (differential)
	5	DATA#		
	13	SCLK	5 V _{SS} R _i ≈ 120 Ω	RS485 clock output (differential)
	6	SCLK#		
	14	COS_Z0 1)	1 V _{SS} ±10% R _i ≈ 120 Ω	COSINE tracking signal (differential) from high-resolution incremental encoder
	7	COS_Z0 1)#		
	15	SIN_Z0 1)	1 V _{SS} ±10% R _i ≈ 120 Ω	SINE tracking signal (differential) from high-resolution incremental encoder
	8	SIN_Z0 1)#		

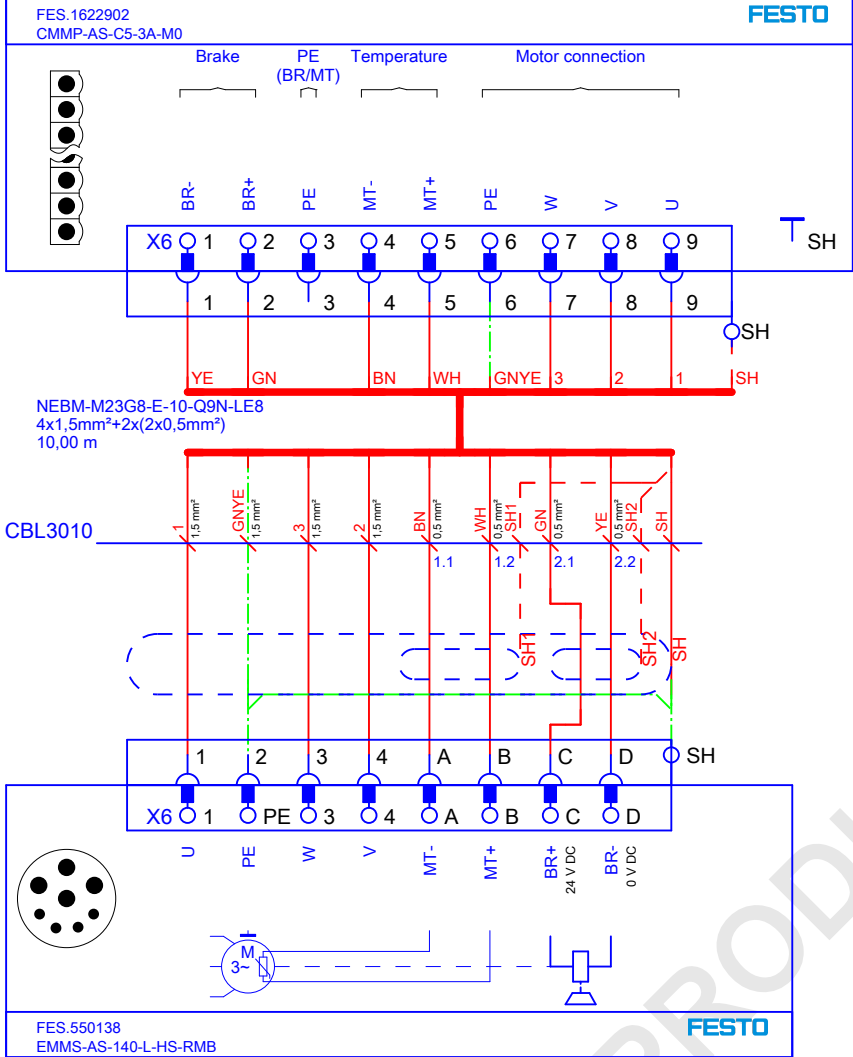
1) Heidenhain encoder: A=SIN_Z0; B=COS_Z0

Pin assienment: Incremental encoder with serial interface. e.e. EnDat – optional

Pin assignment [X2A]				
[X2A]	Pin no.	Designation	Value	Specification
	1	S2	3.5 V _{eff} 5-10 kHz R _i > 5 kΩ	SINE tracking signal, differential
	6	S4		
	2	S1	3.5 V _{eff} 5-10 kHz R _i > 5 kΩ	COSINE tracking signal, differential
	7	S3		
	3	AGND	0V	Screening for signal pairs (inner screening)
	8	MT-	GND	Reference potential for temperature sensor
	4	R1	7 V _{eff} 5-10 kHz I _A ≤ 150 mA _{eff}	Carrier signal for resolver
	9	R2	GND	
	5	MT+	+3.3 V R _i = 2 kΩ	Temperature sensor, motor temperature, N/C contact, PTC, KTY ...

/29.0

CMMP-AS-3

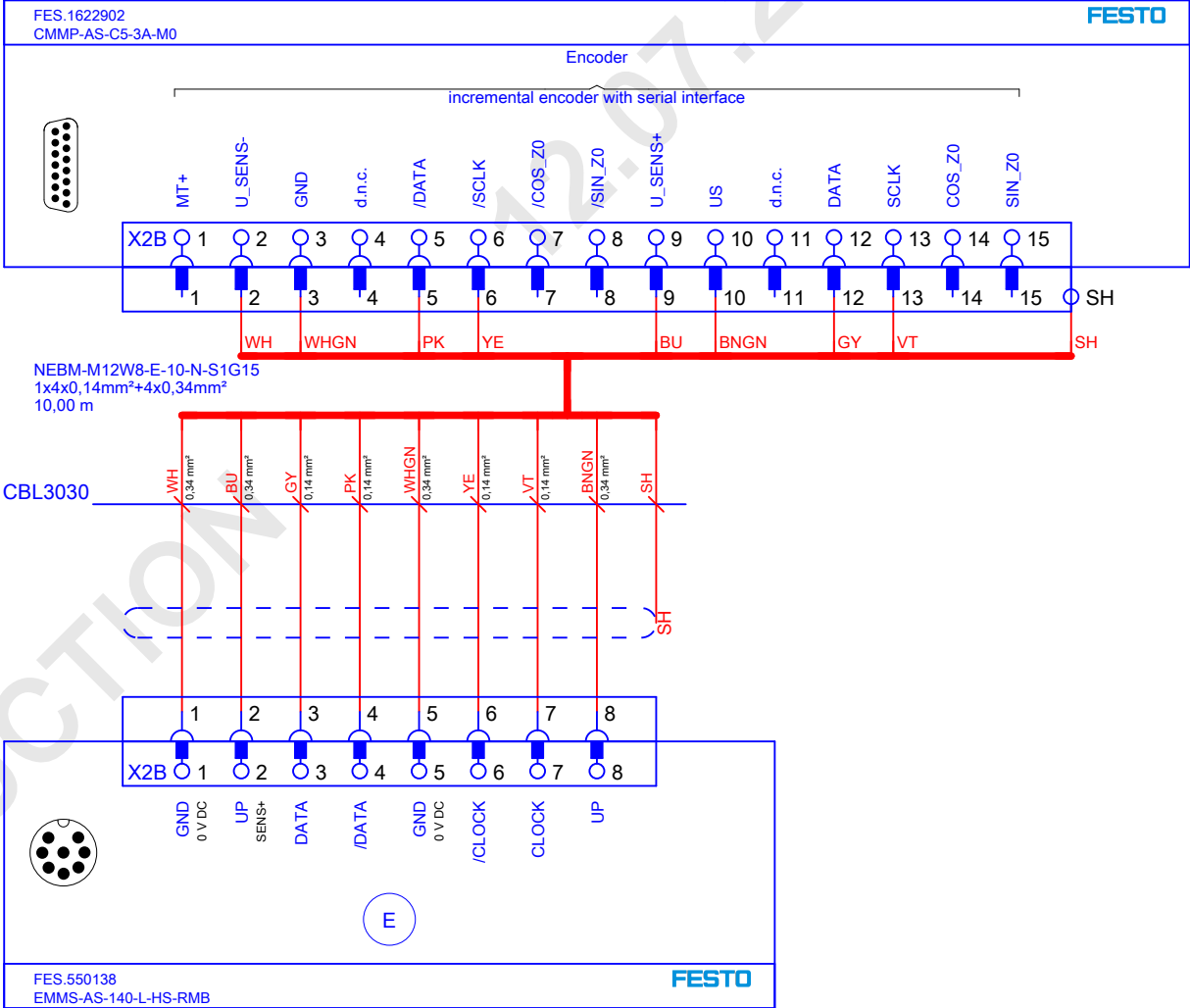


MOT3

/30.3

/29.0

CMMP-AS-3

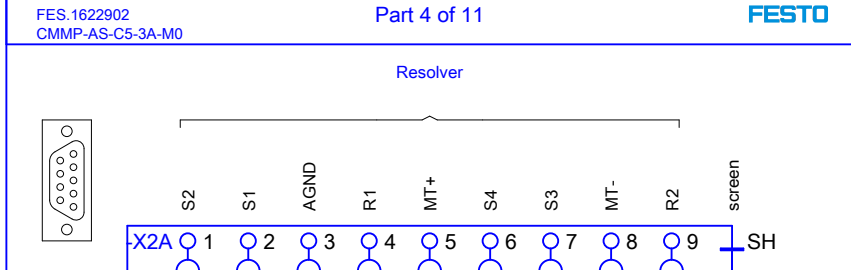


MOT3

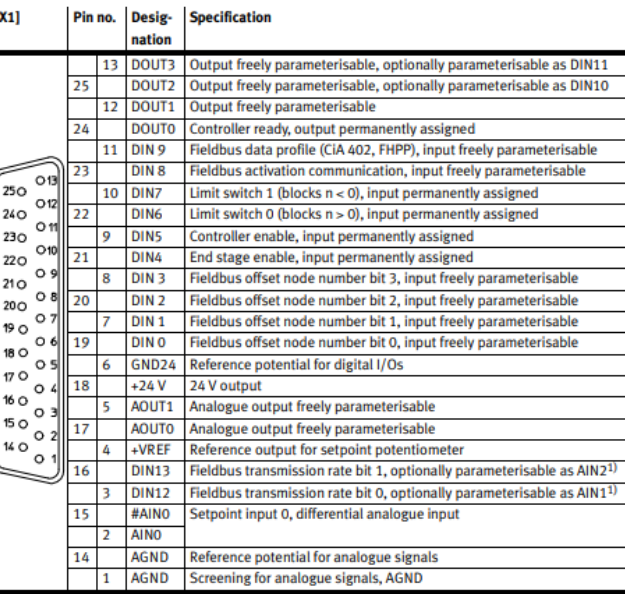
/30.0

/21.0

CMMP-AS-1



Servo shown in this page to show connection example only



Tab. 4.21 Pin assignment X10: Incremental encoder input

1) The specification for RA designates the differential output resistance

Incremental encoder output

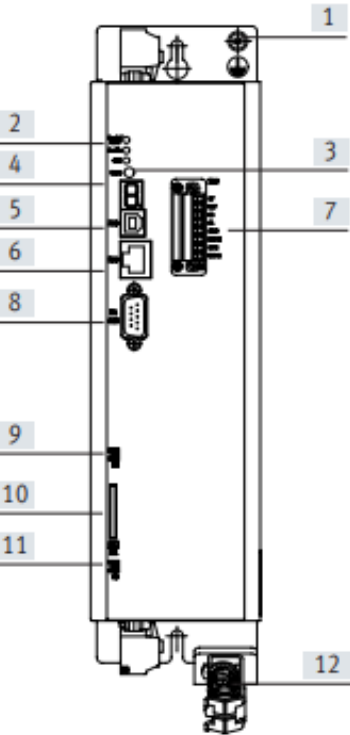
The diagram shows the wiring for the incremental encoder output. A bracket indicates that pins 1 through 8 are connected to the encoder output signals. The signals are labeled as follows:

- A
- B
- Z
- GND
- VCC
- A#
- B#
- Z#
- GND

The physical connector is shown on the left, and the corresponding pin numbers (1-8) are shown below the signal labels. Pin 1 is labeled -X11.

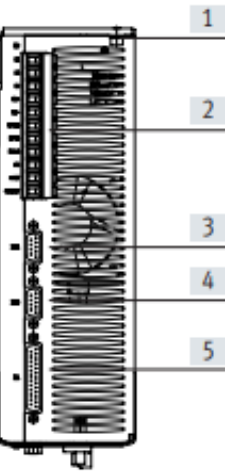
View of motor controller

CMMP-AS-...-M0



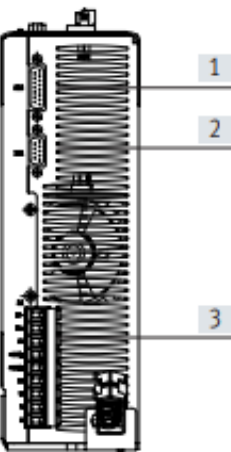
- [1] PE connection
- [2] LEDs
- [3] Reset button
- [4] Seven-segment display
- [5] X19 USB interface
- [6] X18 Ethernet interface
- [7] X40 digital I/O interface for controlling the STO function
- [8] X4 CANopen interface
- [9] Activation of CANopen terminating resistor
- [10] SD/MMC card slot
- [11] Activation of firmware download
- [12] Shield connection

From above



- [1] PE connection
- [2] X9 power supply
- [3] X11 incremental encoder interface (output)
- [4] X10 incremental encoder interface (input)
- [5] X1 I/O interface

From underneath



- [1] X2B encoder connection
- [2] X2A resolver connection
- [3] X6 motor connection

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/33.3

/33.6

/34.0

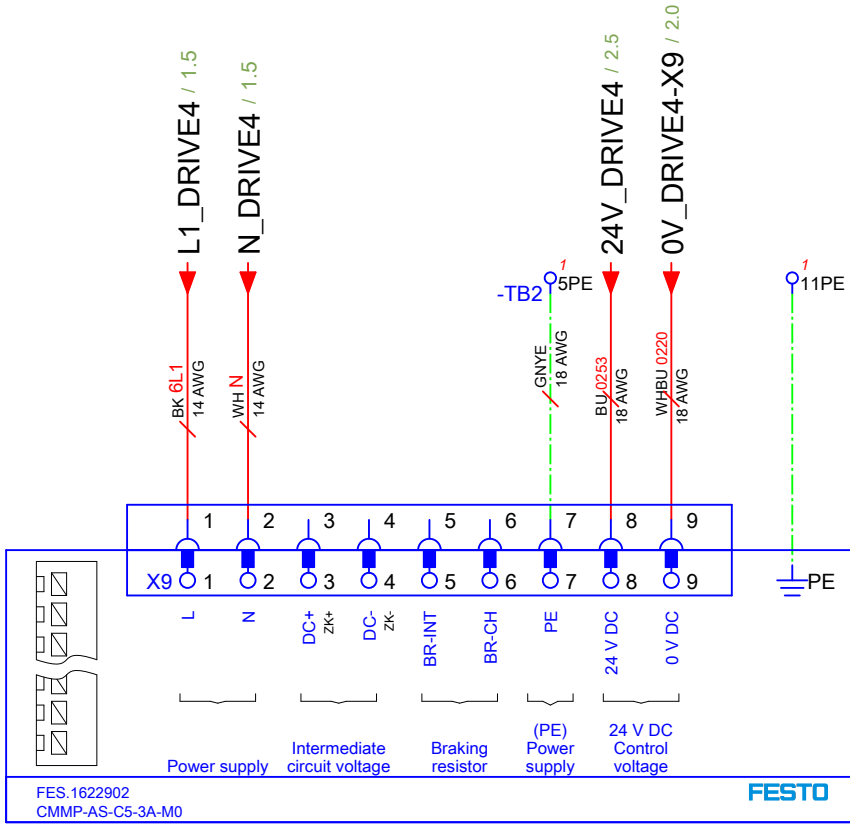
/34.3

/34.7

/35.6

/35.6

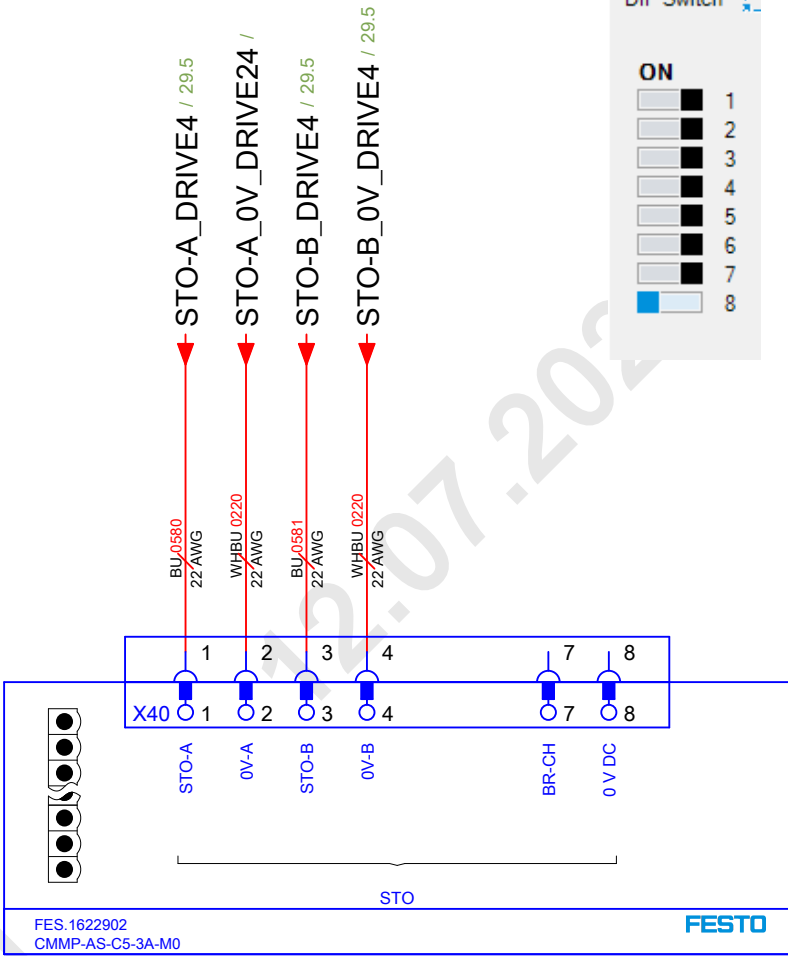
/50.5



CMMP-AS-4

4.8.2 Pin assignment [X9] – single-phase				
[X9]1	Pin no.	Designation	Value	Specification
	1	L	100 ... 230 V AC	Mains phase
	2	N	±10% 50 ... 60 Hz	Mains neutral conductor (reference potential)
	3	ZK+	60 ... 380 V DC	Alternative supply: Positive intermediate circuit voltage
	4	ZK-	GND_ZK	Alternative supply: Negative intermediate circuit voltage
	5	BR-INT	< 460 V DC	Internal braking resistor connection (bridge after BR-CH when using the internal resistor).
	6	BR-CH	< 460 V DC	Brake chopper connection for – internal braking resistor toward BR-INT – or – – external braking resistor against ZK+
	7	PE	PE	Connection for protective conductor from the mains
	8	+24 V	+24 V DC ±20%	Supply for control section, holding brake and I/O
	9	GND24 V	GND24 V DC	Reference potential for supply 0V

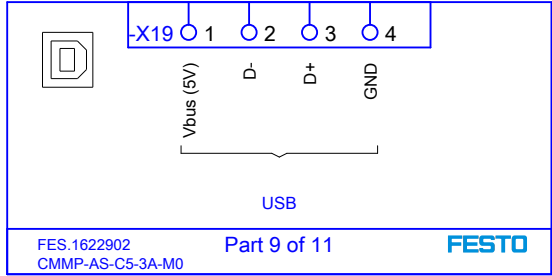
1) Representation of the contact strip on the motor controller CMMP-AS-...-3A-M0



CMMP-AS-4

[X40]1	Pin no.	Designation	Value	Specification
	8	0 V	0 V	Reference potential for auxiliary power supply.
	7	24 V	+24 V DC	Output for auxiliary power supply (24 V DC logic supply of the motor controller brought out).
	6	C2	–	Feedback contact for the status "STO" on an external controller.
	5	C1	–	Feedback contact for the status "STO" on an external controller.
	4	0V-B	0V	Reference potential for STO-B.
	3	STO-B	0 V / 24 V	Control port B for the function STO.
	2	0V-A	0 V	Reference potential for STO-A.
	1	STO-A	0V / 24V	Control port A for the function STO.

Note : Pin 5 (C 1) and Pin 6 (C 2) of Connector X40 are shown on the safety page.



CMMP-AS-4

Project status		xxx		
00A.	12.07.2022	ca0zfa	Date	19.11.2021 CA0ZFA
			Edit by	12.07.2022 ca0zfa
			Appr.	
Modification	Date	Name	Standard	DIRECTIVE 2014/35/EU

FESTO CORPORATION

FMCP-3P-4CMMP-CPXE

FESTO

CMMP-AS-4:X9,X40,X19

EN		&EFS	
Material no.:		23455210	= A1
			+ O1
Project no.:		FMCP Master Drawig : 3 Phase , 4 CMMP , CPXE	
Productionorder:		001330719396	
		Pg.	33
		Pg.	60

[X6]1)	Pin no.	Designation	Value	Specification
	1	Br-	0 V brake	Holding brake (motor), signal level dependent on switching status, high-side/low-side switch
	2	BR+	24 V brake	
	3	PE	PE	Cable shield for the holding brake and the temperature sensor (with Festo cables: n.c.)
	4	-MTdig	GND	Motor temperature sensor, N/C contact, N/O contact, PTC, KTY ...
	5	+MTdig	+3.3 V 5 mA	
	6	PE	PE	Protective earth conductor from the motor
	7	W	Technical data → Tab. A.9	Connection of the three motor phases
	8	V		
	9	U		

1) Representation of the plug on the device of the motor controller CMMP-AS-...-3A-M0

[X2B]	Pin no.	Designation	Value	Specification
	1	MT+	+3.3 V R _i = 2 kΩ	Temperature sensor, motor temperature, N/C contact, PTC, KTY ...
	9	U_SENS+	5 V ... 12 V	Sensor cable for the encoder supply
	2	U_SENS-	R _i ≈ 1 kΩ	
	10	US	5 V/12 V ±10% I _{max} = 300 mA	Operating voltage for high-resolution incremental encoder
	3	GND	0V	Reference potential for encoder supply and motor temperature sensor
	11	–		
	4	–		
	12	DATA	5 V _{SS}	Bidirectional RS485 data cable (differential)
	5	DATA#	R _i ≈ 120 Ω	
	13	SCLK	5 V _{SS}	RS485 clock output (differential)
	6	SCLK#	R _i ≈ 120 Ω	
	14	COS_Z0 1)	1 V _{SS} ±10%	COSINE tracking signal (differential) from high-resolution incremental encoder
	7	COS_Z0 1)#	R _i ≈ 120 Ω	
	15	SIN_Z0 1)	1 V _{SS} ±10%	SINE tracking signal (differential) from high-resolution incremental encoder
	8	SIN_Z0 1)#	R _i ≈ 120 Ω	

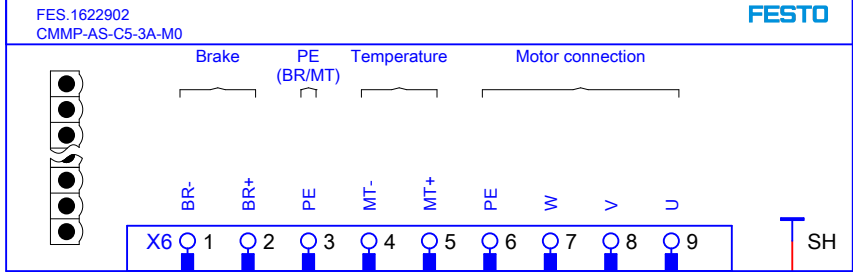
1) Heidenhain encoder: A=SIN_Z0; B=COS_Z0

Pin assienment: Incremental encoder with serial interface. e.e. EnDat – optional

Pin assignment [X2A]				
[X2A]	Pin no.	Designation	Value	Specification
	1	S2	3.5 V _{eff} 5-10 kHz	SINE tracking signal, differential
	6	S4	R _i > 5 kΩ	
	2	S1	3.5 V _{eff} 5-10 kHz	COSINE tracking signal, differential
	7	S3	R _i > 5 kΩ	
	3	AGND	0V	Screening for signal pairs (inner screening)
	8	MT-	GND	Reference potential for temperature sensor
	4	R1	7 V _{eff} 5-10 kHz I _A ≤ 150 mA _{eff}	Carrier signal for resolver
	9	R2	GND	
	5	MT+	+3.3 V R _i = 2 kΩ	Temperature sensor, motor temperature, N/C contact, PTC, KTY ...

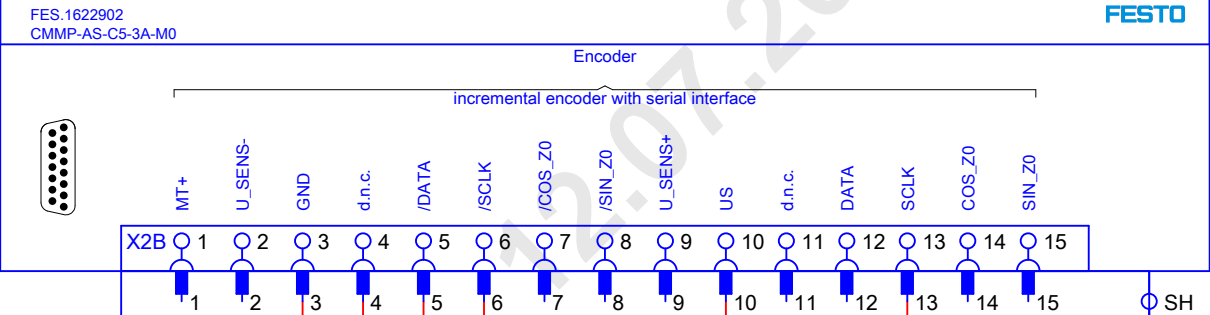
/33.0

CMMP-AS-4



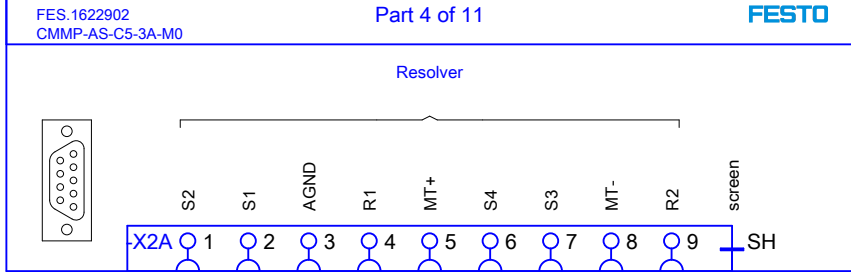
/33.0

CMMP-AS-4



/33.0

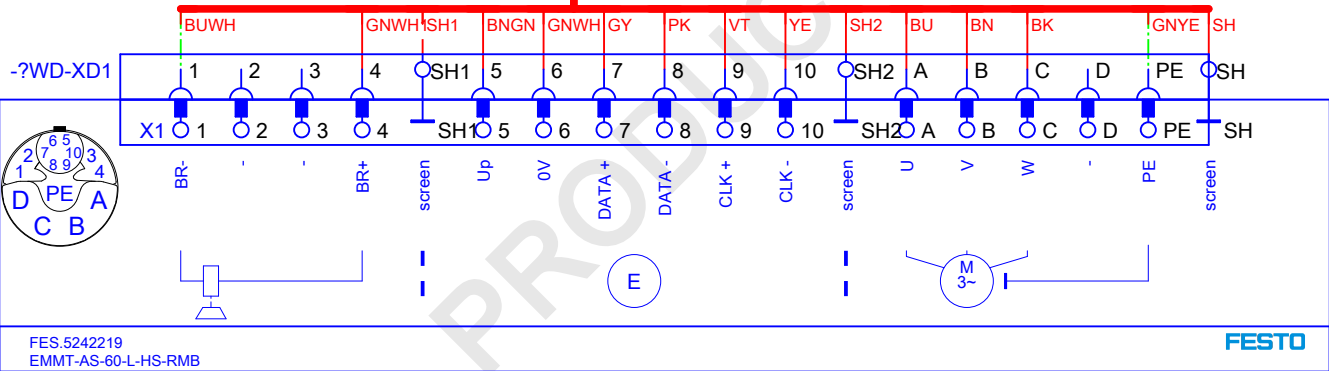
CMMP-AS-4



CBL3410

/34.6

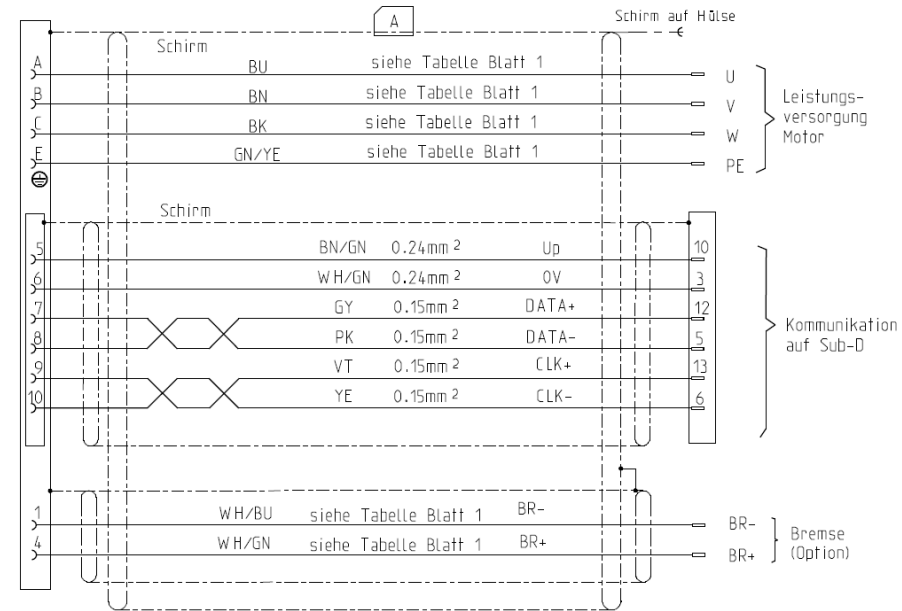
FES.8150834



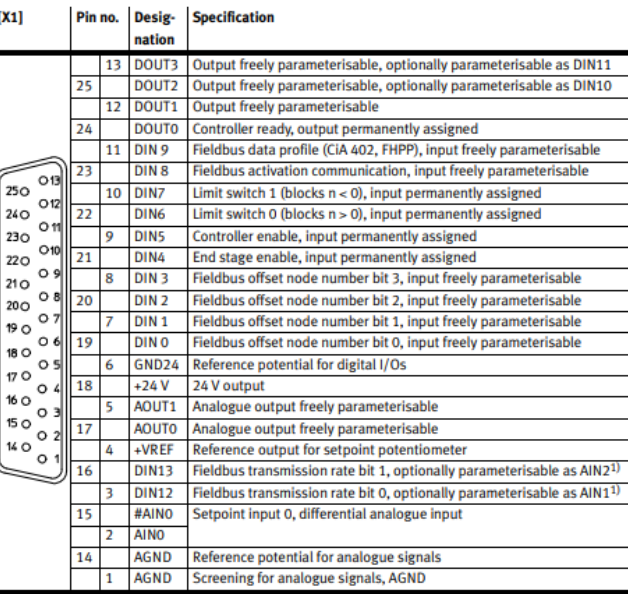
MOT4

MOTORSEITE

CONTROLLERSEITE

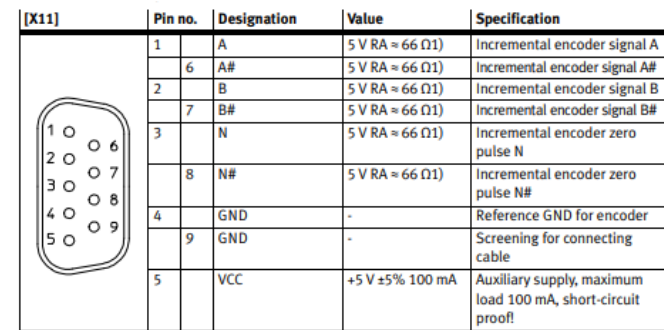


Servo shown in this page to show connection example only



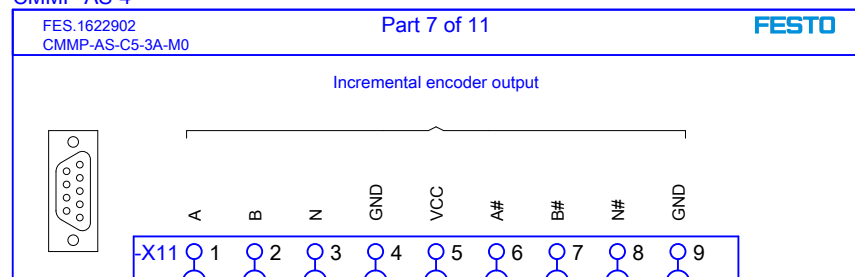
Tab. 4.21 Pin assignment X10: Incremental encoder input

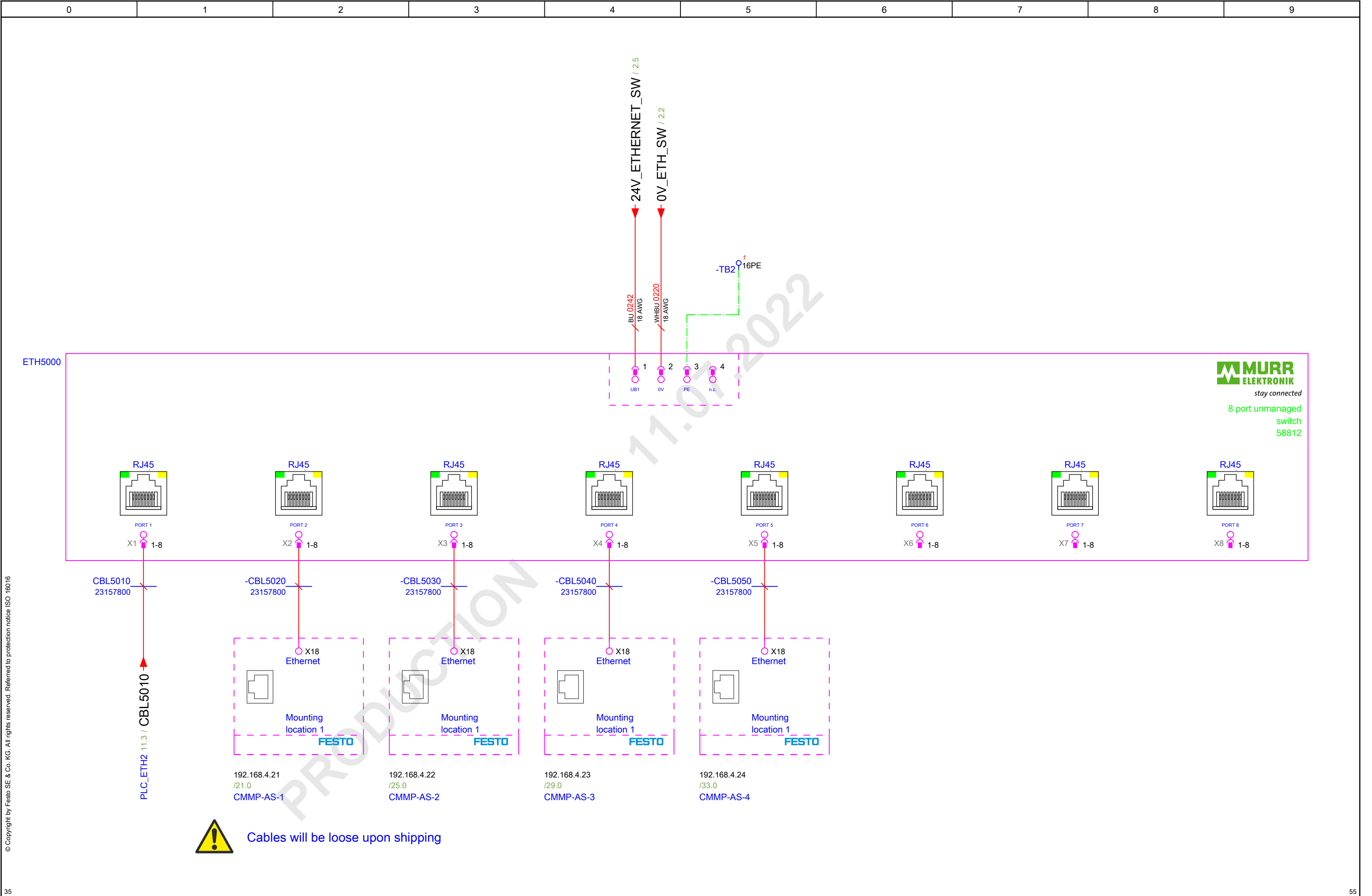
CMMP-AS-4



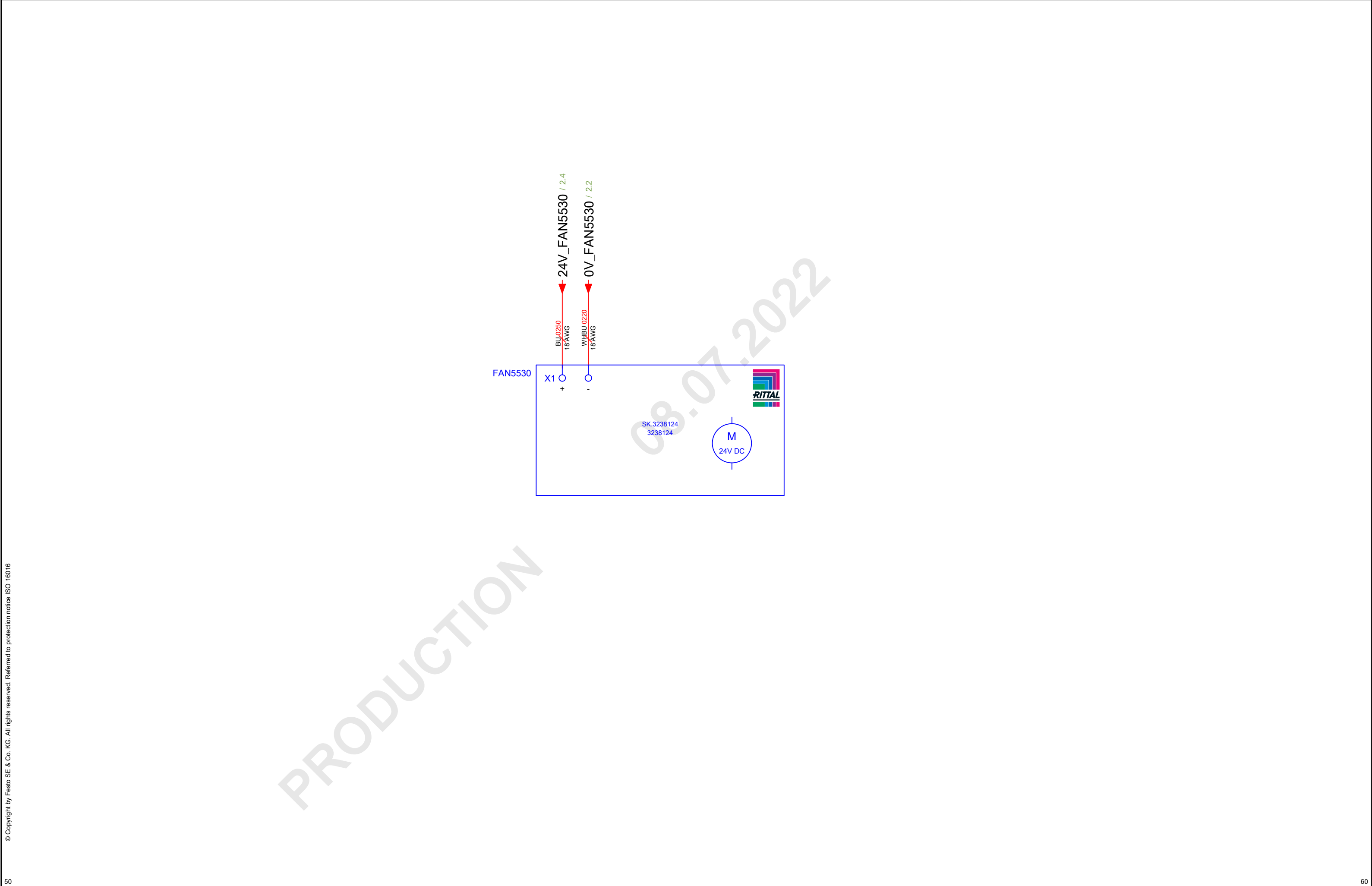
- 1) The specification for RA designates the differential output resistance

CMMP-AS-4





35		55	
Project status		xxx	
		Date	19.11.2021 CA0ZFA
		Edit by	11.07.2022 ca0zfa
		Appr.	
Modification	Date	Name	Standard DIRECTIVE 2014/35/EU
		FESTO CORPORATION	
		FMCP-3P-4CMMP-CPXE	
		Ethernet Switch Connection	
		EN &EFS	
		Material no.: 23455210 = A1	
		+ O1	
		Project no.: FMCP Master Drawig : 3 Phase , 4 CMMP , CPXE	Pg. 50
		Productionorder: 001330719396	Pg. 60



Terminal diagram

Type number	Manufacturer	Connection design / -number	14 AWG									Cable name	external Terminal strip =A1+O1-TB1										Cable name								Connection design / -number	Page / column
													Target designation	Connection	Level	Terminal	Connection internal	Jumper	Connection	Target designation												
ZDK 2.5-2PE	WEI		YEGN									-TB2	1PE:7	2	1	1PE:7	1	1	I											&EFS/1.2		
												-DS0110-L3	PE	4	2		1	3	I											&EFS/1.2		
ZDK 2.5-2V	WEI														2	1	2	1	●											&EFS/1.4		
		N	WH									-PSU211	N	4	2	2	3	3	I											&EFS/1.4		
ZDK 2.5-2V	WEI	N	WH											2	2	1	3	1	●											&EFS/1.4		
		N	WH											2	4	2	3	3	I											&EFS/1.4		
ZDK 2.5-2V	WEI	N	WH											2	2	1	4	1	●											&EFS/1.5		
		N	WH											2	4	2	4	3	I											&EFS/1.5		

1

2.1

DIN A3 13.07.2022

Terminal diagram

Type number	Manufacturer	Connection design / -number												Cable name	Terminal strip =A1+O1-TB2										Cable name									Connection design / -number	Page / column
															external	Target designation	Connection	Level	Terminal	Connection external	Jumper	Connection	Target designation	internal											
AMC 2.5	WEI													-CMMP-AS-3	X9:PE	7	1	10PE															&EFS/29.2		
																6	2	10	1														&EFS/2.2		
																5	3	10	2														&EFS/2.6		
		0550	BU											-PB2	41	4	4	10	3									BU	0550				&EFS/5.1		
AMC 2.5	WEI													-CMMP-AS-4	X9:PE	7	1	11PE															&EFS/33.2		
		0220		WHBU										-PLC1102	XD:2	6	2	11	1								WHBU		0220				&EFS/2.2		
																5	3	11	2									BK	0242				&EFS/2.6		
														-PB2	42	4	4	11	3														&EFS/5.1		
		0220		WHBU										-LT1	x2	6	2	12	1								WHBU		0220				&EFS/2.2		
																5	3	12	2														&EFS/2.6		
		0560	BU											-PB2	21	4	4	12	3									BU	0560				&EFS/5.1		
AMC 2.5	WEI															7	1	13PE																	
																6	2	13	1								WHBU		0220				&EFS/2.2		
																5	3	13	2														&EFS/2.7		
														-PB2	22	4	4	13	3														&EFS/5.1		
AMC 2.5	WEI				GNYE									-PSU211	PE	7	1	14PE															&EFS/2.1		
																6	2	14	1								WHBU		0220				&EFS/2.2		
																5	3	14	2														&EFS/2.7		
		0541	BU											-SR0510	X1	4	4	14	3														&EFS/5.3		
AMC 2.5	WEI				GNYE									-PSU211	-1	7	1	15PE															&EFS/2.0		
																6	2	15	1								WHBU		0220				&EFS/2.3		
																5	3	15	2														&EFS/2.7		
														-S1	11	4	4	15	3									BU	0542				&EFS/5.3		
AMC 2.5	WEI													-ETH5000	3	7	1	16PE															&EFS/50.5		
																6	2	16	1														&EFS/5.5		
																5	3	16	2														&EFS/23.2		
																4	4	16	3														&EFS/23.4		
AMC 2.5	WEI															7	1	17PE																	
																6	2	17	1														&EFS/5.5		
																5	3	17	2														&EFS/27.2		
		0242	BK											-TB2	11:2	4	4	17	3														&EFS/27.4		
AMC 2.5	WEI														PE	7	1	18PE															&EFS/2.0		
																6	2	18	1														&EFS/5.5		
																5	3	18	2														&EFS/31.2		
																4	4	18	3														&EFS/31.4		
AMC 2.5	WEI														PE	7	1	19PE															&EFS/2.0		

Terminal diagram

Type number	Manufacturer	Connection design / -number										Cable name	external					Terminal strip =A1+O1-TB2					internal					Cable name	-CBL3530							Connection design / -number	Page / column
													Target designation	Connection	Terminal Level Connection external	Terminal Internal Connection internal	Jumper	Connection	Target designation	Cable type					20 AWG												
																6	2	1:2	19	1	●	X4:9	-CON3500	RD									0570	&EFS/5.5			
																5	3		19	2		X4:10	-CON3500	GN									0339	&EFS/35.2			
																4	4		19	3		X2:22	-CON3500	WH									0340	&EFS/35.4			
AMC 2.5	WEI															7	1		20PE																		
																6	2		20	1	●													&EFS/5.6			
																5	3		20	2																	
																4	4			3																	
AMC 2.5	WEI															7	1		21PE																		
																6	2		21	1	●													&EFS/5.6			
																5	3		21	2																	
																4	4		21	3																	
AMC 2.5	WEI															7	1		22PE																		
																6	2		22	1	●	14	-SR0510							BU		0570	&EFS/5.6				
																5	3		22	2																	
																4	4		22	3																	

Terminal diagram

Type number	Manufacturer	Connection design / -number	22 AWG									Cable name	external					Terminal strip =A1+O1-TB3					internal					Cable name						Connection design / -number	Page / column																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																										
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Terminal diagram

Type number	Manufacturer	Connection design / -number										Cable name	external						Terminal strip =A1+O1-TB3						internal						Cable name							20 AWG	18 AWG	Connection design / -number	Page / column																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																									

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