

Project: "490. The Maze" - LC - Breadth-First Traversal

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1. INTRODUCTION

- Breadth-First Search (BFS) is an algorithm for traversing or searching tree or graph data structures.
- It starts at a selected node (often at the root in the case of trees, or some arbitrary node for graphs).
- It explores all of the neighbor nodes at the present depth prior to moving on to nodes at the next depth level.

2. DESIGN

2.1. Without Wheel (Legged Robot)

A 5x5 grid representing a maze. The grid is labeled with letters A through J. The starting point is at C, and the goal is at R. The grid is as follows:

A	B		C	O
D	E	F	G	H
I	R	U		K
		L		
M	N	P	Q	J

Breadth-First Traversal - 1 legged robots move in a Hotel - 1 non wheeled

Step 1	Step 2	Step 3	Step 4	Step 5	Step 6
visited: O	visited: O, C, H	V → O, C, H, G	V → O, C, H, G, F	V → O, C, H, G, F, U	V → O, C, H, G, F, U, D, B, R
Queue:	Queue: C, H	Q → H, G	Q → G, K	Q → K, F	Q → F
Print: O	print: O, C, H	P → O, C	P → O, C, H, G	P → O, C, H, G, F	P → O, C, H, G, F, U, D, B, R
Step 7	Step 8	Step 9			
V → O, C, H, G, F, U, D, B, R	V → O, C, H, G, F, U, D, B, R	V → O, C, H, G, F, U, D, B, R	→ Add R to the Queue		
Q → EU	Q → U, D, B, R	Q → U, D, B, R	→ Mark R as visited		
P → O, C, H, G, K, F	P → O, C, H, G, K, F	P → O, C, H, G, K, F			

2.2. With Wheel (Self-driving Car)

BFT \rightarrow wheeled

1) Visited \rightarrow O

Queue -

Print - O

2. Visited - O C K

Queue - C K

Print - O

3. Visited - O C K G

Queue - K G

Print - O C

4. Visited - O C K G

Queue - G

Print - O C K

5. V \rightarrow O C K G

Q \rightarrow

P \rightarrow O C K G

6. V \rightarrow O C K G D

Q \rightarrow D

P \rightarrow

7) V \rightarrow O C K G D A I

Q \rightarrow A I

P \rightarrow O C K G D

8) V \rightarrow O C K G D A I B

Q \rightarrow I B

P \rightarrow O C K G D A

9) V \rightarrow O C K G D A I B U

Q \rightarrow B U

P \rightarrow O C K G D A I

Add R to the queue as
it is already visited

3. IMPLEMENTATION

```
Users > fevenbelay > Desktop > FevDesktop > SFBU-Semester2 > Practical algorithm > BFS-maze.py > ...
1  from collections import deque
2  class Solution:
3      def hasPath(self, maze, start, destination):
4          m, n = len(maze), len(maze[0])
5          visited = set()
6          queue = deque([start[0], start[1]])
7
8          while queue:
9              x, y = queue.popleft()
10             if (x, y) == (destination[0], destination[1]):
11                 return True
12
13             if (x, y) in visited:
14                 continue
15             visited.add((x, y))
16
17             for dx, dy in [(0, 1), (0, -1), (1, 0), (-1, 0)]:
18                 nx, ny = x + dx, y + dy
19                 while 0 <= nx < m and 0 <= ny < n and maze[nx][ny] == 0:
20                     nx += dx
21                     ny += dy
22                 nx -= dx
23                 ny -= dy
24                 if (nx, ny) not in visited:
25                     queue.append((nx, ny))
26
27             return False
28
```

4. TEST

```
29 # Test the function
30 maze = [[0,0,1,0,0], [0,0,0,0,0], [0,0,0,1,0], [1,1,0,1,1], [0,0,0,0,0]]
31 start = [0, 4]
32 destination = [4, 4]
33 sol = Solution()
34 print(sol.hasPath(maze, start, destination))
35
36 maze = [[0,0,1,0,0], [0,0,0,0,0], [0,0,0,1,0], [1,1,0,1,1], [0,0,0,0,0]]
37 start = [0, 4]
38 destination = [3,2]
39 sol = Solution()
40 print(sol.hasPath(maze, start, destination))
41
42 maze = [[0,0,0,0,0], [1,1,0,0,1], [0,0,0,0,0], [0,1,0,0,1], [0,1,0,0,0]]
43 start = [4,3]
44 destination = [0,1]
45 sol = Solution()
46 print(sol.hasPath(maze, start, destination))
```



PROBLEMS DEBUG CONSOLE TERMINAL

```
/usr/bin/python3 "/Users/fevenbelay/Desktop/FevDesktop/SFBU-Semester2/Practical algorithm/BFS-maze.py"
● (base) fevenbelay@Feven-MacBook-Air ~ % /usr/bin/python3 "/Users/fevenbelay/Desktop/FevDesktop/SFBU-Semester2/Practical algorithm/BFS-maze.py"
True
False
False
○ (base) fevenbelay@Feven-MacBook-Air ~ %
```

5. ENHANCEMENT IDEAS

1. Space-Efficient Data Structures: Using more space-efficient data structures for the queue and visited set, such as compressed bit vectors, can significantly reduce the memory footprint of BFS.
2. Parallel BFS: BFS can be parallelized by processing multiple nodes at the same level concurrently, using parallel computing resources.
3. Sparse BFS: For sparse graphs, an adjacency list can be more efficient than an adjacency matrix, reducing the time complexity of checking for neighboring nodes from $O(V)$ to $O(\deg(v))$, where V is the number of vertices and $\deg(v)$ is the degree of a vertex.
4. Dynamic BFS: For graphs that change over time (dynamic graphs), maintaining BFS trees and updating them incrementally can be more efficient than re-computing the BFS from scratch after every change.
5. External BFS: For extremely large graphs that do not fit into memory, employing external memory algorithms can allow BFS to run on graphs stored on disk.

6. CONCLUSION

- This approach is ideal for mazes because it can find the shortest path without getting trapped in dead ends or visiting any part of the maze unnecessarily.
- Each position is visited at most once, ensuring the process is efficient and terminates once it either finds the destination or exhausts all possible paths.