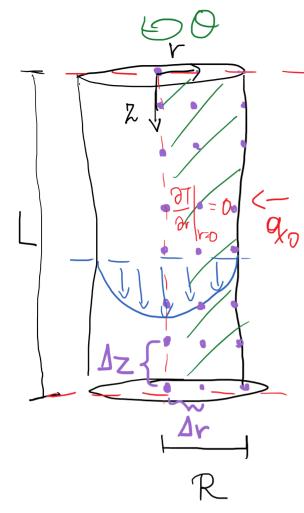
IIQ2003 - Python S3.2.2 - SOR - discretización dominio*



$$T(r,z=0) = T_1$$

Suprestos

* Estado estacionaria

* Simetria angular -> T=T(r,z)

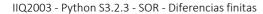
· Prop. termofísicos constantes

· Fluso C.D. en la entrader

$$\frac{\partial T}{\partial z}(r,z=L)=0$$

•
$$\Delta r = \frac{R}{N_R}$$
; $\Delta z = \frac{L}{N_Z}$

Nati nodos en R Nati nodos en 2



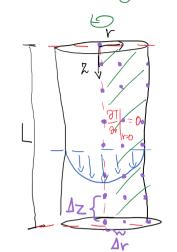
$$k\frac{\partial^{2}T}{\partial r^{2}} + k\frac{\partial^{2}T}{\partial z^{2}} + \underbrace{\frac{k}{r}\frac{\partial T}{\partial r}}_{\text{LC}} - \underbrace{\rho\hat{c}_{p}v_{max}}_{\text{max}} \left(1 - \left(\frac{r}{R}\right)^{2}\right)\frac{\partial T}{\partial z} = 0$$

 $k \frac{3^27}{2r^2} |_{i,j} k \left(\frac{T_{c-1,j}-2T_{i,j}+T_{i+1,j}}{\Delta r^2} \right)$

 $k\frac{\partial^2 T}{\partial z^2} \approx \frac{k(T_{i,j-1}-2T_{i,j}+T_{i,j+1})}{4z^2}$

ال 0 دوا/		1	•	•
i=2	×		×	•
i=3	•	(•	•
<u>i</u> =	•	•	•	•
)=1	J=2	J - 3	4

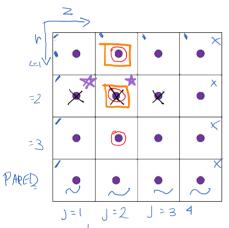
$V_{i} = i\Delta v$; $Z_{i} = J\Delta z$ Donde $\Delta v = R$; $\Delta z = L$ M_{z-1} Q



$$\frac{k}{r} \frac{\partial T}{\partial r} \approx \frac{k}{r_{i,j}} \frac{T_{i-1,j} - T_{i,j}}{\Delta r}$$

$$\mathbb{D}\left(1-\frac{r}{R}\right)^{2}\frac{\partial T}{\partial z} \approx \mathbb{D}\left(1-\left(\frac{r_{i,j}}{R}\right)^{2}\right) = \frac{T_{i,j-1}-T_{i,j}}{\Delta z}$$

$$r = (i-1)\Delta v$$
, $r = (j-1)\Delta z$



$$\begin{array}{ccc}
 & \times & i & \alpha_{0}i & T_{1,j=1} = T_{1} \\
 & \times & i & CB2 & T_{2,j} - T_{1,j} = I_{2,j} \\
 & & & \Delta r
\end{array}$$

$$\frac{\partial}{\partial r}|_{r=0,z} = 0$$

$$\Rightarrow \frac{\partial T}{\partial z}|_{r,z=L} = 0$$

$$\Rightarrow T_{i}, \forall j = T_{i}, \forall j + 1$$

$$\sim k \frac{\partial T}{\partial r}|_{r=R^{2}} = q_{0} \qquad CBA) : \frac{T_{NR+1,j} - T_{NR,j}}{K}$$