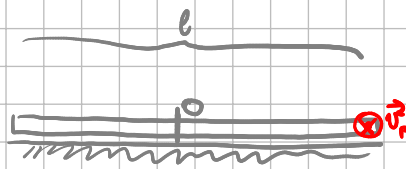


43.3

HP

$$\begin{aligned}
 m &= 1 \text{ kg} \\
 l &= 1 \text{ m} \\
 v_p &= 10 \text{ m/s} \\
 m_p &= 0.1 \text{ kg} \\
 M_{\text{alt}}
 \end{aligned}$$



Th

- 1) ω @ ωt_0
- 2) M_{alt} @ $\omega=0$ dopo 2 giri

$$m_p v_p = (m_p + m) v \rightarrow v = \frac{m_p v_p}{m_p + m}$$

cons. mom ang. $I_{\text{rot}} \omega = \frac{l}{2} (m + m_p) v$

$$\text{con } I_{\text{rot}} = \frac{1}{12} m \frac{1}{4} l^2 + \frac{1}{4} l^2 m_p = \frac{1}{4} l^2 \left(\frac{1}{12} m + m_p \right)$$

$$\Rightarrow \omega = \frac{\frac{1}{2} l (m + m_p) \cdot \frac{m_p v_p}{m_p + m}}{\frac{1}{4} l^2 \left(\frac{1}{12} m + m_p \right)} = \frac{2 m_p v_p}{\left(\frac{1}{12} m + m_p \right) l}$$

$$2) \frac{1}{2} I_{\text{rot}} \omega^2 = M_{\text{alt}} \rightarrow \frac{1}{2} I_{\text{rot}} \omega^2 = M_{\text{alt}} g = M_{\text{alt}} 4\pi$$

$$\Rightarrow M_{\text{alt}} = \frac{\frac{1}{2} \cdot \frac{1}{4} l^2 \left(\frac{1}{12} m + m_p \right)}{4\pi} \cdot \frac{4 m_p^2 v_p^2}{\left(\frac{1}{12} m + m_p \right)^2 l^2} = \frac{m_p^2 v_p^2}{8\pi \left(\frac{1}{12} m + m_p \right)}$$

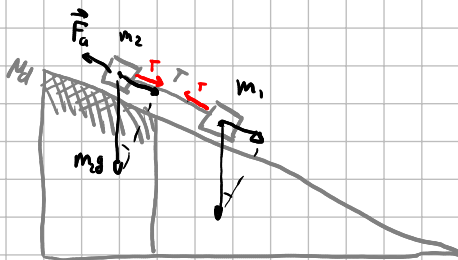
43.2

HP

$$\begin{aligned}
 m_1 &= 3 \text{ kg} \\
 m_2 &= 1 \text{ kg}
 \end{aligned}$$

$$g = \frac{\pi}{6}$$

$$\mu_d = 0.3$$



Th

- 1) a_{m_2}, T
- 2) F e v_{cent}

$$\begin{cases}
 m_2 a = T + m_2 g \sin \theta - m_2 g \cos \theta \mu \\
 m_1 a = m_1 g \sin \theta - T
 \end{cases} \rightarrow a = \frac{m_1 g \sin \theta - T}{m_1}$$

$$m_2 \frac{m_1 g \sin \theta - T}{m_1} = T + m_2 g \sin \theta - m_2 g \cos \theta \mu$$

$$-m_2 g \sin \theta + \frac{m_2 T}{m_1} + T = -m_2 g \sin \theta + m_2 g \cos \theta \mu$$

$$\Rightarrow \frac{m_2 T + m_1 T}{m_1} = m_2 g \cos \theta \mu \Rightarrow T \left(\frac{m_2 + m_1}{m_1} \right) = m_2 g \cos \theta \mu$$

$$\Rightarrow T = \frac{m_2 m_1 g \cos \theta \mu}{m_2 + m_1}$$

$$\Rightarrow a = \frac{m_1 g \sin \theta}{m_1} - \frac{m_2 g \cos \theta \mu}{m_2 + m_1} = g \sin \theta - \frac{m_2}{m_2 + m_1} g \cos \theta \mu = a$$

2) verso l'alto, attrito nel senso opposto $\Rightarrow a' = g \sin \theta + \frac{m_2}{m_2 + m_1} g \cos \theta \mu$

$$F - (m_1 + m_2)a' = 0 \Rightarrow F = (m_1 + m_2) g \sin \theta + m_2 g \cos \theta \mu$$

43.1

H_P

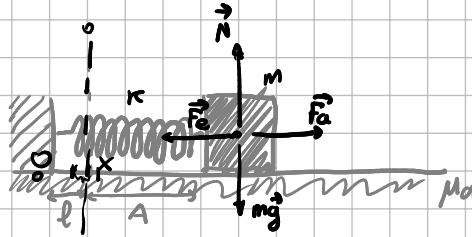
$$\kappa = 19.6 \frac{N}{m}$$

$$l = 40 \text{ cm}$$

$$m = 100 \text{ g}$$

$$\mu_d = 0.5$$

$$A = 30 \text{ cm}$$



metto lo zero in l

$$\frac{1}{2} \kappa A^2 = \mu m g (A - x) + \frac{1}{2} \kappa x^2$$

$$\Rightarrow \frac{1}{2} \kappa A^2 = \mu m g A - \mu m g x + \frac{1}{2} \kappa x^2 \Rightarrow \frac{1}{2} \kappa x^2 - \mu m g x + A \left(\mu m g - \frac{1}{2} \kappa A \right) = 0$$

$$x = \frac{\mu m g \pm \sqrt{(\mu m g)^2 - 2 \kappa A (\mu m g - \frac{1}{2} \kappa A)}}{\kappa} = \begin{cases} 0.3 \\ -0.25 \end{cases} \text{ minore}$$

con lo zero in 0 -0.25 diventa $\boxed{15 \text{ cm}} = b$

$$2) \frac{1}{2} \kappa (l - b)^2 = \frac{1}{2} m v^2 + \mu m g (l - b) \Rightarrow v = \sqrt{\frac{\kappa (l - b)^2 - \mu m g (l - b)}{m}}$$

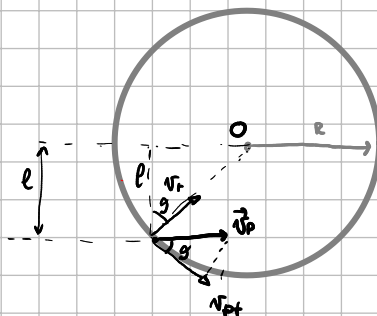
42.3

$$m = 11.0 \text{ kg}$$

$$R = 49.0 \text{ cm}$$

$$m_p = 1.6 \text{ kg}$$

$$v = 2.70 \text{ m/s}$$



$$R \cos \theta = l$$

$$\cos \theta = \frac{l}{R}$$

$$v_{pt} = v_p \cos \theta = v_p \frac{l}{R}$$

T_h

1) W dopo urto

2) $\Delta \vec{P}$

$$t) m_p v_{pt} = (m + m_p) v \rightarrow v = \frac{m_p v_{pt}}{m + m_p} = \frac{m_p v_p}{m + m_p} \frac{l}{R}$$

$$I\omega = L = r \cdot m v \rightarrow \omega = \frac{r m v}{I} = \frac{R(m+m_p)}{R^2(\frac{1}{2}m+m_p)} \cdot \frac{m_p v_p}{m+m_p} \cdot \frac{\ell}{R}$$

$$\begin{aligned} r &= R \\ I &= \frac{1}{2}mR^2 + m_p R^2 \\ m &= m + m_p \end{aligned} \Rightarrow \omega = \frac{m_p v_p}{\frac{1}{2}m + m_p} \cdot \frac{\ell}{R^2}$$

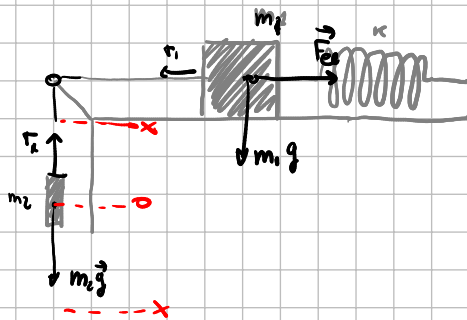
$$\begin{aligned} 2) \Delta P_x: P_{dx} - P_{px} &= (m+m_p)v - m_p v_p = (m+m_p) \frac{m_p v_p}{m+m_p} \frac{\ell}{R} - m_p v_p \\ &= m_p v_p \left(\frac{\ell}{R} - 1 \right) \end{aligned}$$

$$3) m_p v_p = (m+m_p) v_{cm} \rightarrow v_{cm} = \frac{m_p v_p}{m+m_p}$$

42.2

Hp

$$\begin{aligned} m_1 &= 2 \text{ kg} \\ \kappa &= 98 \text{ N/m} \\ m_2 &= 1 \text{ kg} \end{aligned}$$



Th

- 1) x, T
- 2) periodo τ

$$T = m_2 g \rightarrow T - \kappa x = 0 \rightarrow \kappa x = m_2 g \rightarrow x = \frac{m_2 g}{\kappa}$$

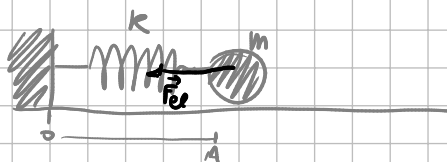
- 2) la molla oscilla attorno alla posizione di equilibrio
 $\Rightarrow S_{max} = 2x$

$$\omega = \sqrt{\frac{\kappa}{m}} \Rightarrow T = \frac{2\pi}{\omega} = 2\pi \sqrt{\frac{m}{\kappa}} = 2\pi \sqrt{\frac{m+m_2}{\kappa}}$$

42.1

Hp

m
 κ
 A



Th

- 1) $P(t)$
- 2) T

$$x(t) = A \sin(\sqrt{\frac{\kappa}{m}} t) \Rightarrow F_{el} = -\kappa A \sin(\sqrt{\frac{\kappa}{m}} t)$$

$$v(t) = \sqrt{\frac{\kappa}{m}} A \cos(\sqrt{\frac{\kappa}{m}} t) \Rightarrow P = Fv = +\kappa A \sin(\sqrt{\frac{\kappa}{m}} t) \cdot \sqrt{\frac{\kappa}{m}} A \cos(\sqrt{\frac{\kappa}{m}} t)$$

$$= -kA^2 \sqrt{\frac{k}{m}} \sin \cdot \cos \cdot$$

$$= \frac{1}{2} kA^2 \sqrt{\frac{k}{m}} \sin(2\sqrt{\frac{k}{m}} t)$$

$$2) T = 2\pi/\omega = 2\pi\sqrt{\frac{m}{k}} \Rightarrow P(T/8) = kA^2 \sqrt{\frac{k}{m}} \sin \frac{\pi}{4} \cos \frac{\pi}{4}$$

$$= kA^2 \sqrt{\frac{k}{m}} \frac{1}{2}$$



$$P_m = \frac{1}{T} \int_0^T \frac{1}{2} kA^2 \sqrt{\frac{k}{m}} \sin(2\sqrt{\frac{k}{m}} t) dt = -\frac{1}{T} \frac{1}{2} kA^2 \sqrt{\frac{k}{m}} \cos(2\sqrt{\frac{k}{m}} t) \cdot \frac{1}{2\sqrt{\frac{k}{m}}}$$

$$\cos(2\sqrt{\frac{k}{m}} \cdot 2\pi\sqrt{\frac{m}{k}}) = 1$$

$$= 0$$

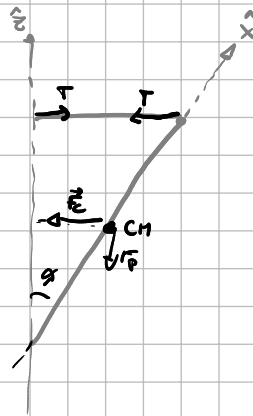
4.3

H_p

l, m, g, ω

$\lambda = cx$

$$dm = \lambda dx = cx dx$$



I_p

1) $C.M.$

2) M_p

3) M_c

$$x_{CM} = \frac{\int_0^l x dm}{\int_0^l dm} = \frac{\int_0^l x^2 c dx}{\int_0^l c x dx} = \frac{\frac{1}{3} l^3 c}{\frac{1}{2} l^2 c} = \frac{2}{3} l$$

$$2) M_p = mg x_{CM} \sin \theta = \frac{2}{3} mgl \sin \theta$$

$$3) a_c = \omega^2 r = \omega^2 x \sin \theta$$

$$F_c = m a_c \Rightarrow dF_c = \omega^2 x \sin \theta dm \Rightarrow dF_c = \omega^2 x \sin \theta c x dx = \omega^2 x^2 c \sin \theta dx$$

$$M_c = F_c \cdot b \cos \theta \Rightarrow dM_c = x \cos \theta \cdot \omega^2 x^2 c \sin \theta dx = \cos \theta \sin \theta \omega^2 c x^3 dx$$

$$\Rightarrow M_c = \frac{1}{4} l^4 \cos \theta \sin \theta \omega^2 c \quad ?$$

41.2

tip

$$m_A = 4.5 \text{ kg}$$

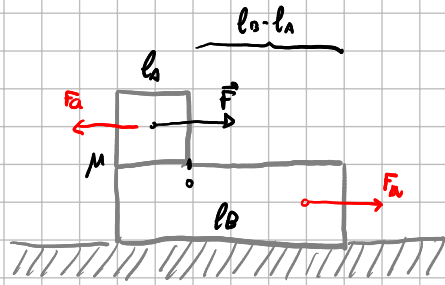
$$m_B = 9.0 \text{ kg}$$

$$l_A = 15 \text{ cm}$$

$$l_B = 30 \text{ cm}$$

$$\mu = 0.2$$

$$F = 22 \text{ N}$$



Th

1) a_A, a_B

2) $l_A = l_B$

3) μ_{\min}

$$1) \begin{cases} m_A a_A = F - F_A \\ m_B a_B = F_A \end{cases} \rightarrow \begin{cases} m_A a_A = F - m_A g \mu \rightarrow a_A = \left(\frac{F}{m_A} - \mu g \right) \\ m_B a_B = m_A g \mu \rightarrow a_B = \frac{m_A}{m_B} \mu g \end{cases}$$

$$2) \begin{aligned} v_A(t) &= \left(\frac{F}{m_A} - \mu g \right) t & \rightarrow & x_A(t) = \frac{1}{2} \left(\frac{F}{m_A} - \mu g \right) t^2 \\ v_B(t) &= \left(\frac{m_A}{m_B} \mu g \right) t & \rightarrow & x_B(t) = \frac{1}{2} \left(\frac{m_A}{m_B} \mu g \right) t^2 \end{aligned}$$

$$s(t) = (x_A - x_B) = \frac{1}{2} \left(\underbrace{\frac{F}{m_A} - \mu g}_{a_A} - \underbrace{\frac{m_A}{m_B} \mu g}_{a_B} \right) t^2$$

$$s(t) = l_B - l_A \Rightarrow \frac{1}{2} \left(\underbrace{\frac{F}{m_A} - \mu g}_{a_A} - \underbrace{\frac{m_A}{m_B} \mu g}_{a_B} \right) t^2$$

$$t = \sqrt{\frac{2(l_B - l_A)}{a_A - a_B}}$$

$$3) a_A = a_B \rightarrow \frac{F}{m_A} - \mu g = \frac{m_A}{m_B} \mu g \Rightarrow \frac{F}{m_A} = \mu \left(g + \frac{m_A}{m_B} g \right) \Rightarrow \mu_{\min} = \frac{F}{m_A g \left(1 + \frac{m_A}{m_B} \right)}$$

$$\mu_{\min} = \frac{F}{m_A g \left(\frac{m_B + m_A}{m_B} \right)} = \frac{F m_B}{m_A g (m_B + m_A)}$$

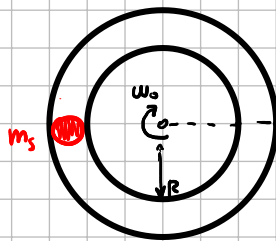
41.1 (?)

40.3

hp

$$m_0 R, \omega_0 \rightarrow v_0 = R \omega_0$$

$$m = \kappa t$$



Th

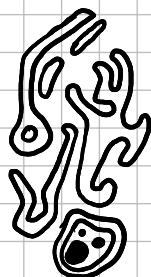
$$\tau @ \omega(\tau) = \frac{1}{2} \omega_0$$

$$[I_{rot} = m_0 R^2 + \kappa t R^2 = R^2 (m_0 + \kappa t)] \quad \text{cons. mom. angulare}$$

$$I_{rot} \omega = R m_{rot} v_0 \rightarrow R^2 (m_0 + \kappa t) \omega = R^2 m_0 \omega_0 \Rightarrow \omega = \frac{m_0 \omega_0}{m_0 + \kappa t}$$

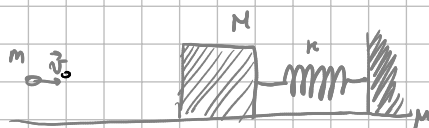
$$\omega(\tau) = \frac{1}{2} \omega_0 \Rightarrow \omega(\tau) = \frac{m_0 \omega_0}{m_0 + \kappa \tau} = \frac{1}{2} \omega_0 \rightarrow 2m_0 = \frac{1}{2} m_0 + \frac{1}{2} \kappa \tau \Rightarrow \tau = \frac{m_0}{\kappa}$$

$$\alpha(t) = \frac{d\omega}{dt} = - \frac{m_0 \omega_0}{(m_0 + \kappa t)^2} \kappa$$



40.2

hp

N
KTh
 δ_{max}

cons. qdm

$$m v_0 = (M + m) v \rightarrow v = \frac{m}{M + m} v_0$$

$$\frac{1}{2} \kappa \delta_{max}^2 + \mu m g \delta_{max} - \frac{1}{2} m v^2 = 0$$

$$\text{con } m = M + m$$

$$\delta = \frac{-\mu m g \pm \sqrt{(\mu m g)^2 + \kappa m v^2}}{\kappa} \quad \checkmark$$

40.1

?

39.3

H_p

m, R, ρ
 $\theta = \frac{\pi}{2}$

$$dm = \rho ds = \rho r d\theta dr$$

$$1) \quad x_{cm} = \frac{\int x dm}{\int dm} = \frac{\int r \cos \theta \cdot \rho r d\theta dr}{\int \rho r d\theta dr} = \frac{\rho \int_0^R r^2 dr \int_0^{\pi/2} \cos \theta d\theta}{\rho \int_0^R r dr \int_0^{\pi/2} d\theta}$$

$$= \frac{\frac{1}{3} R^3}{\frac{1}{2} R^2 \cdot \frac{\pi}{2}} = \frac{4}{3} \cdot \frac{R}{\pi}$$

$$y_{cm} = \frac{4}{3} \frac{R}{\pi}$$

$$\Rightarrow cm. \left(\frac{4}{3} \frac{R}{\pi}, \dots \right)$$

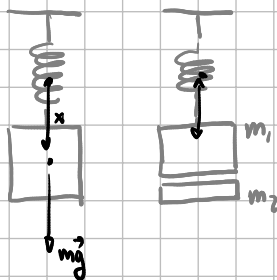
$$2) I_0 = \int r^2 dm = \int r^2 \rho r d\theta dr = \rho \int_0^R r^3 dr \int_0^{\pi/2} d\theta = \frac{4m}{\pi R^2} \cdot \frac{1}{4} R^4 \cdot \frac{\pi}{2} = \frac{1}{2} m R^2$$

$$3) T = 2\pi \sqrt{\frac{I_0}{mg r_{cm}}} = \cancel{2\pi} \sqrt{\frac{\frac{1}{2} m R^2}{m g \frac{4}{3} \frac{R}{\pi}}} = \pi \sqrt{\frac{3}{2} \cdot \frac{R}{g}}$$

39.1

$$m_1 = \frac{2}{3} m$$

$$m_2 = \frac{1}{3} m$$



T_b

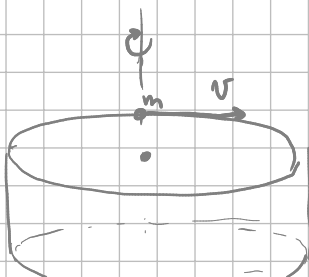
1) a_{max}

$$m_2 g = m_1 a \rightarrow \frac{1}{3} m g = \frac{2}{3} m a \Rightarrow a = \frac{1}{2} g$$

38.3

H_p

$m_c = 0.2 \text{ kg}$
 $R = 0.15 \text{ m}$
 $\omega_0 = 20 \text{ rad/s}$



T_b

1) $\omega @ m_c = m_c - m$

2) ω

$$m = 5g$$

2) cons mom angul

$$I_0 \omega_0 = I_1 \omega_1 \rightarrow \omega_1 = \frac{I_0}{I_1} \omega_0 = \frac{m_c}{m_c - m} \omega_0$$

$$\text{con } \begin{cases} I_0 = \frac{1}{2} m_c R^2 \\ I_1 = \frac{1}{2} (m_c - m) R^2 \end{cases}$$

$$\begin{aligned} \text{e) } W = \Delta E_K &= \frac{1}{2} I_1 \omega_1^2 - \frac{1}{2} I_0 \omega_0^2 = \frac{1}{2} (I_1 \omega_1^2 - I_0 \omega_0^2) = \\ &= \frac{1}{2} \left[\frac{1}{2} (m_c - m) R^2 \left(\frac{m_c^2}{(m_c - m)^2} \omega_0^2 \right) - \frac{1}{2} m_c R^2 \omega_0^2 \right] \\ &= \frac{1}{4} R^2 m_c \omega_0^2 \left(\frac{m_c}{m_c - m} - 1 \right) \\ &= \frac{1}{4} R^2 m_c \omega_0^2 \cdot \frac{m}{m_c - m} \end{aligned}$$

38.1

HP

$$m, v = 30 \text{ m/s}$$

$$\begin{aligned} m_1 &= \frac{2}{3} m \\ m_2 &= \frac{1}{3} m \end{aligned}$$

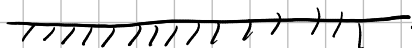
$$\vec{v}_1, \vec{v}_2 \dots v(t_k)$$

$$\vec{v}$$

IB

$$1) v_2$$

$$2) \tau @ y(t) = 0$$



$$\text{CINA } \frac{1}{2} m v^2 = m g h \Rightarrow h = \frac{1}{2} \frac{v^2}{g}$$

$$\text{META } \frac{1}{2} m v^2 = \frac{1}{2} m v_{\text{meta}}^2 + m g h \rightarrow v_{\text{meta}}^2 = \frac{1}{2} (v^2 - g h) \rightarrow v_{\text{meta}} = \sqrt{v^2 - g h}$$

$$\Rightarrow v_{\text{meta}} = \sqrt{v^2 - \frac{1}{2} v^2} = \frac{1}{\sqrt{2}} v = v'$$

Cons qdm

$$\begin{cases} (m_1 + m_2) v' = m_1 v_1 + m_2 v_2 \end{cases}$$

$$\begin{cases} \frac{1}{2} (m_1 + m_2) v'^2 = \frac{1}{2} m_1 v_1^2 + \frac{1}{2} m_2 v_2^2 \end{cases}$$

$$\begin{cases} m_1 v_1 + m_2 v_2 = a \end{cases}$$

$$\begin{cases} m_1 v_1^2 + m_2 v_2^2 = a v' \end{cases}$$

$$\rightarrow v_1 = \frac{a - m_2 v_2}{m_1}$$

$$\rightarrow m_1 \left(\frac{a^2 - 2am_2 v_2 + m_2^2 v_2^2}{m_1^2} \right) + m_2 v_2^2 = a v'$$

$$\frac{a^2}{m_1} - \frac{2am_2}{m_1} v_2 + \frac{m_2^2}{m_1} v_2^2 + m_2 v_2^2 - a v' = 0$$

$$v_2^2 \left(\frac{m_2^2}{m_1} + m_2 \right) - \left(\frac{2am_2}{m_1} \right) v_2 + \frac{a^2}{m_1} - a v' = 0$$

$$v_2 = \frac{\frac{2am_2}{m_1} \pm \sqrt{\left(\frac{2am_2}{m_1} \right)^2 - 4 \left(\frac{m_2^2}{m_1} + m_2 \right) \left(\frac{a^2}{m_1} - a v' \right)}}{2 \left(\frac{m_2^2}{m_1} + m_2 \right)}$$

$$2) \quad v_2(t) = v_2 - g t$$

$$y_1(t) = v_2 t - \frac{1}{2} g t^2 \rightarrow y_2(t) = 0 \rightarrow \frac{1}{2} g t^2 - v_2 t = 0 \rightarrow t = \frac{2v_2}{g}$$

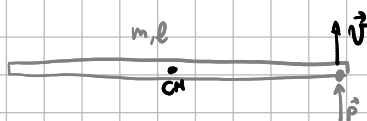
37.2

Hp

$$l = 10 \text{ m}$$

$$m = 3.3 \text{ kg}$$

$$P = 5.6 \text{ N s}$$



Th

- 1) v_{cm}
- 2) ω
- 3) E_{kin}

$$1) \text{ Cons qdm: } P = m v_{cm} \rightarrow v_{cm} = \frac{P}{m}$$

$$2) \text{ Cons mom ang: } I \omega = \frac{1}{2} l P \rightarrow \omega = \frac{\frac{1}{2} l P}{\frac{1}{12} m l^2} = \frac{6P}{m l}$$

$$3) \quad E_{kin} = E_{trans} + E_{rot} = \frac{1}{2} m v_{cm}^2 + \frac{1}{2} I \omega^2$$

$$= \frac{1}{2} m \frac{P^2}{m^2} + \frac{1}{2} \frac{1}{12} m l^2 \cdot \frac{36 P^2}{m^2 l^2} = \frac{1}{3} \frac{P^2}{m} + \frac{3}{2} \frac{P^2}{m} = \frac{11}{6} \frac{P^2}{m}$$

37.1

Hp

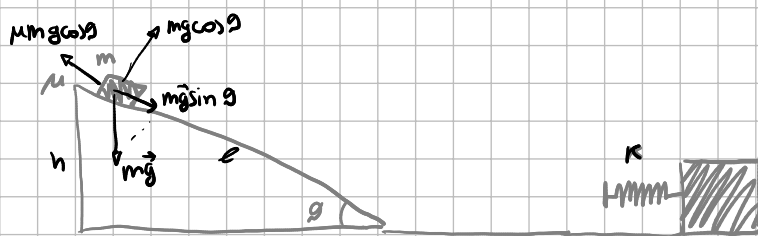
$$m = 0.5 \text{ kg}$$

$$h = 2 \text{ m}$$

$$\theta = 30^\circ$$

$$\mu = 0.2$$

$$k = 4 \cdot 10^3 \text{ N/m}$$



Th

- 1) W_{alt}
- 2) δ_{max}
- 3) $\delta' @ N=0$

$$l \sin \theta = h \rightarrow l = \frac{h}{\sin \theta} = 2h$$

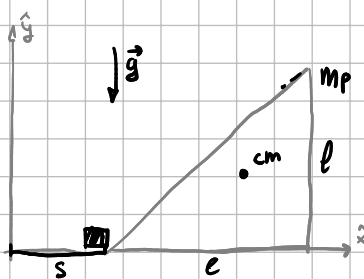
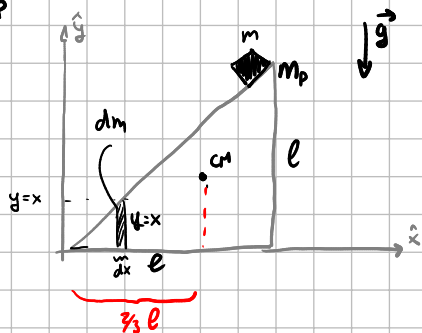
$$2) \Rightarrow W_{att} = \mu mg \cos \theta \cdot 2h$$

$$2) mgh = \mu mg \cos \theta \cdot 2h + \frac{1}{2} k \delta^2 \rightarrow \delta = \sqrt{\frac{2(mgh - \mu mg \cos \theta \cdot 2h)}{k}}$$

$$3) \delta = \sqrt{\frac{2mgh}{k}}$$

36.2

HP



Th

- 1) x_{cm}
- 2) s
- 3) v_x @ blocco a $y=0$

$$1) x_{cm} = \frac{\int x dm}{\int dm} \quad \text{con } dm = \rho ds = \rho x dx \rightarrow x_{cm} = \frac{\rho \int_0^l x^2 dx}{\rho \int_0^l x dx} = \frac{\frac{1}{3} l^3}{\frac{1}{2} l^2} = \frac{2}{3} l$$

2) conservare qdm sui 2 assi

$$x: m v = (m + m_p) v_{cm} \Rightarrow v_{cm} = \frac{m v}{m + m_p}$$

$$\boxed{v_x = \frac{l}{t}} \quad \boxed{v_{cm} = \frac{s}{t}} \Rightarrow \frac{s}{t} = \frac{m}{m + m_p} \frac{l}{t} \Rightarrow s = \frac{m}{m + m_p} l$$

$$y: m v_y = 0$$

$$3) mgl = \frac{1}{2} m v^2 + \frac{1}{2} (m + m_p) v_{cm}^2 \rightarrow \left[v_{cm} = \frac{m v}{m + m_p} \right], \left[v = v_x \sqrt{2} \right]$$

$$mgl = \cancel{m} v_x^2 + (\cancel{m + m_p}) \frac{m^2 v_x^2}{(m + m_p)^2}$$

$$\rightarrow v_x^2 \left(1 + \frac{m}{m + m_p} \right) = gl \Rightarrow v_x = \sqrt{\frac{gl(m + m_p)}{2m + m_p}}$$

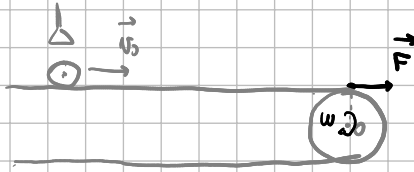
?

36.1

HP

$$\frac{dm}{dt} = 310 \frac{\text{kg}}{\text{s}} = r$$

$$v_0 = 3.40 \text{ m/s}$$



Ih

1) $F @ v_{\text{cost}}$

2) P

v costante se $a=0$

$$\rightarrow F = \frac{dP}{dt} = \frac{dm}{dt} v + \frac{dv}{dt} m$$

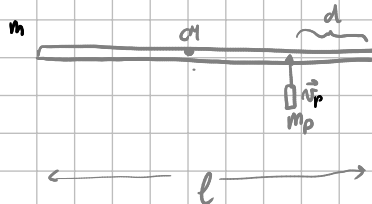
impongo $\frac{dv}{dt} = 0 \Rightarrow F = \frac{dm}{dt} v = r v$

$$P = \frac{95}{100} F v = 0.95 r v^2$$

35.2

HP

m, l, d
 m_p, v_p



Ih

1) $m_p @ v_p = 0$

(m, l, d)

cons qdm e energia

$$\begin{cases} m_p v_p = m v_{cm} \\ \frac{1}{2} m_p v_p^2 = \frac{1}{2} m v_{cm}^2 + \frac{1}{2} I \omega^2 \end{cases}$$

cons. mom ang.

$$\left(\frac{l}{2} - d\right) m_p v_p = I \omega$$

$$\begin{cases} m_p v_p = m v_{cm} \\ \frac{1}{2} m_p v_p^2 = \frac{1}{2} m v_{cm}^2 + \frac{1}{2} I \omega^2 \end{cases} \rightarrow \boxed{v_{cm} = \frac{m_p v_p}{m}}$$

$$\hookrightarrow \frac{1}{2} m_p v_p^2 = \frac{1}{2} m \frac{m_p^2 v_p^2}{m^2} + \frac{1}{24} I \omega^2$$

Trovo ω da $\left(\frac{l}{2} - d\right) m_p v_p = I \omega \rightarrow \boxed{\omega = \frac{\left(\frac{l}{2} - d\right) m_p v_p}{I}}$

$$\frac{1}{2} m_p v_p^2 = \frac{1}{2} \frac{m_p^2 v_p^2}{m} + \frac{1}{2} \frac{(\frac{\ell}{2} - d)^2 m_p^2 v_p^2}{I^2}$$

$$m_p v_p^2 = \frac{m_p^2 v_p^2}{m} + \frac{12(\frac{\ell}{2} - d)^2 m_p^2 v_p^2}{\ell^2 m}$$



Perché ho $(\frac{\ell}{2} - d)^2$ al posto di d !

$$1 = \left(\frac{1}{m} + \frac{12(\frac{\ell}{2} - d)^2}{\ell^2 m} \right) m_p \Rightarrow m_p = \left(\frac{\ell^2 + 12(\frac{\ell}{2} - d)^2}{\ell^2 m} \right) =$$

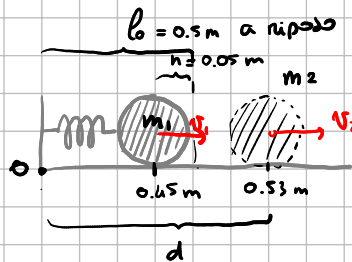
35.1

Hp

$$m_1 = 1 \text{ kg}$$

$$l_0 = 50 \text{ cm}$$

$$m_2 = 3m_1$$



Th

1) δ_{\max} post urto

$$\rightarrow \frac{1}{2} k h^2 = \frac{1}{2} m_1 v_1^2 + \frac{1}{2} k (d - l_0)^2 \rightarrow \text{da qui ricavo } v_1$$

$$\frac{1}{2} m_1 v_1^2 = \frac{1}{2} k (h^2 - (d - l_0)^2) \Rightarrow v_1^2 = \frac{k}{m_1} [h^2 - (d - l_0)^2]$$

$$\begin{cases} m_1 v_1 = m_2 v_2 + m_1 v_1' \\ \frac{1}{2} m_1 v_1^2 = \frac{1}{2} m_2 v_2^2 + \frac{1}{2} m_1 v_1'^2 \end{cases} \rightarrow \begin{cases} m_1 v_1 = 3m_1 v_2 + m_1 v_1' \\ m_1 v_1^2 = 3m_1 v_2^2 + m_1 v_1'^2 \end{cases} \rightarrow \begin{cases} v_1 = 3v_2 + v_1' \\ v_1^2 = 3v_2^2 + v_1'^2 \end{cases} \rightarrow v_2 = \frac{v_1 - v_1'}{3}$$

$$v_1^2 = 3 \frac{v_1^2 + v_1'^2 - 2v_1 v_1'}{3} + v_1'^2 \rightarrow v_1^2 = \frac{1}{3} v_1^2 + \frac{1}{3} v_1'^2 - \frac{2}{3} v_1 v_1' + v_1'^2$$

$$\frac{2}{3} v_1^2 = \frac{2}{3} v_1'^2 - \frac{2}{3} v_1 v_1' \rightarrow v_1^2 = 2v_1'^2 - v_1 v_1'$$

$$2v_1'^2 - v_1 v_1' - v_1^2 = 0 \rightarrow v_1' = \frac{v_1 \pm \sqrt{v_1^2 + 8v_1'^2}}{4} = \frac{v_1 \pm 3v_1}{4}$$

$$\begin{aligned} & \rightarrow v_1' = v_1 \\ & \rightarrow v_1' = -\frac{1}{2} v_1 = v \end{aligned}$$

$$\Rightarrow \frac{1}{2} k (d - l_0)^2 + \frac{1}{2} \frac{m_1}{k} v^2 = \frac{1}{2} k \delta^2$$

$$\delta^2 = (d-l_0)^2 + \frac{m}{\cancel{\kappa}} \frac{1}{4} \cdot \frac{\cancel{\kappa}}{m_1} [h^2 - (d-l_0)^2]$$

$$\delta^2 = (d-l_0)^2 + \frac{1}{4}h^2 - \frac{1}{4}(d-l_0)^2 = \frac{1}{4}h^2 + \frac{3}{4}(d-l_0)^2$$

$$\delta = \sqrt{\frac{1}{4}h^2 + \frac{3}{4}(d-l_0)^2}$$

34.2

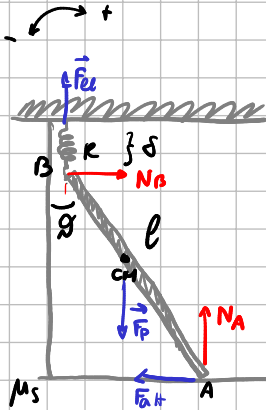
HP

$$m = 1 \text{ kg}$$

$$\kappa = 4 \text{ N/m}$$

$$\delta = 2 \text{ m}$$

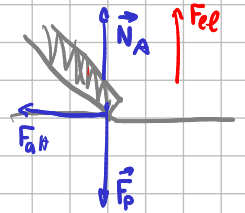
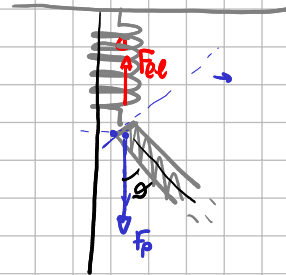
$$\vartheta = 63.5^\circ$$



IB

$$1) N_A, N_B$$

$$\begin{cases} x: N_B - F_{AH} = 0 \rightarrow N_B = F_A \\ y: N_A - F_P + F_E = 0 \rightarrow N_A = F_P - F_E \end{cases}$$



$$M: \sum N = N_B \cancel{\ell} \cos \vartheta + F_E \cancel{\ell} \sin \vartheta - F_P \frac{\cancel{\ell}}{2} \sin \vartheta + F_{AH} \cancel{\ell} \cos \vartheta - N_A \cancel{\ell} \sin \vartheta = 0$$

$$N_B \cos \vartheta + \kappa \delta \sin \vartheta - \frac{mg}{2} \sin \vartheta + N_B \cos \vartheta - mg \sin \vartheta + \kappa \delta \sin \vartheta = 0$$

$$2N_B \cos \vartheta = \frac{2mg \sin \vartheta}{2} - 2\kappa \delta \sin \vartheta \Rightarrow N_B = \left(\frac{mg}{2} - \kappa \delta \right) \tan \vartheta$$

33.2

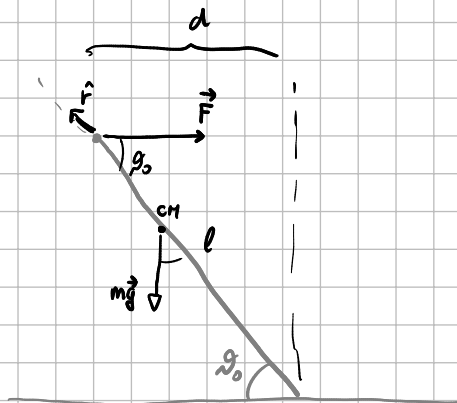
HP

$$m = 1 \text{ kg}$$

$$\ell = 80 \text{ cm}$$

$$\lambda = \kappa \sqrt{r}$$

$$\vartheta_0 = 40^\circ$$



IB

$$1) F$$

$$2) W @ F = 2F$$

$$\omega \vartheta = \frac{\pi}{2} - \vartheta_0$$

$$1) r_{CM} = \frac{\int r dm}{\int dm}$$

$$\omega \vartheta \quad dm = \kappa \sqrt{r} dr$$

$$\Rightarrow = \frac{\int r \kappa r^{1/2} dr}{\int \kappa r^{1/2} dr} = \frac{\int_0^\ell r^{3/2} dr}{\int_0^\ell r^{1/2} dr} = \frac{\frac{2}{5} \ell^{5/2}}{\frac{2}{3} \ell^{3/2}}$$

$$= \frac{3}{5} \ell$$

Per equilibrio: $mg \frac{3}{5} \ell \cos \theta - F \ell \sin \theta \rightarrow F = \frac{3}{5} mg \frac{\cos \theta}{\sin \theta}$

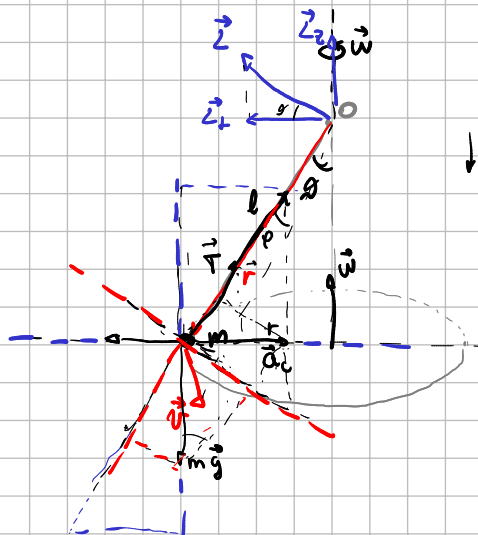
2) $W = 2F\ell = \frac{6}{5} mg \frac{\cos \theta}{\sin \theta} \ell \cos \theta$

33.1

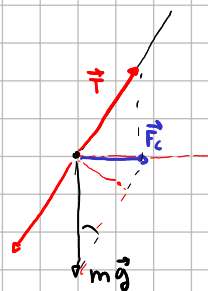
H_P

m
l
g
θ

$$L_z = \ell m v$$



$\frac{T}{h}$
 L_z



$$\begin{cases} T \cos \theta = mg \\ T \sin \theta = m \frac{v^2}{r} \end{cases} \Rightarrow v = \sqrt{\frac{lg \sin^2 \theta}{\cos \theta}}$$

$$\begin{cases} mg \cos \theta = T \\ m \frac{v^2}{r} \cos \theta = mg \sin \theta \end{cases} \rightarrow v^2 \cos \theta = lg \sin^2 \theta \Rightarrow v = \sqrt{lg \frac{\sin^2 \theta}{\cos \theta}}$$

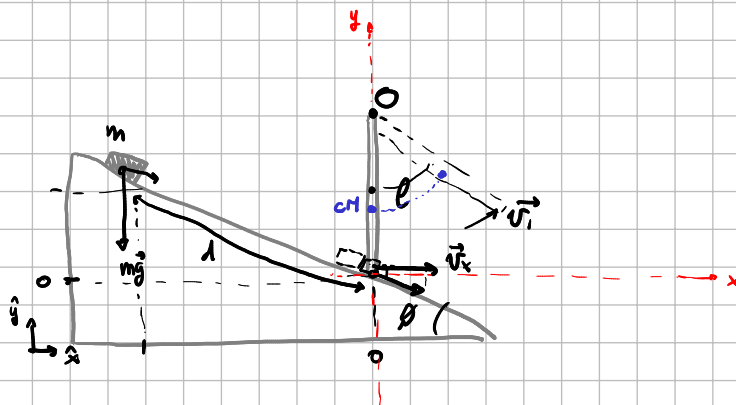
$$L_z = \ell m \sqrt{lg \frac{\sin^2 \theta}{\cos \theta}} = \sqrt{\ell^3 m^2 g \frac{\sin^2 \theta}{\cos \theta}}$$

33.2

H_P

$m_a = 3m$
 ℓ

m



$\frac{T}{h}$
e) \vec{F}_{cm} minima e dopo l'angolo

1) $x_{cm} = 0$

$$y_{cm} = \frac{\frac{1}{2} 3m}{4m} = \frac{3}{8} \ell$$

2) m arriva a velocità v : $mgd \sin \theta = \frac{1}{2} m v^2 \Rightarrow v = \sqrt{2gd \sin \theta}$

la componente x di v : $v_x = \sqrt{2gd \sin \theta} \cos \theta$

cons. qdm: $m v_x = (m+3m) v_i \Rightarrow v_i = \frac{1}{4} \sqrt{2gd \sin \theta} \cos \theta$

cons mom ang: $I \omega = (m+3m) v_i \ell \rightarrow \omega = \frac{4m \cdot \frac{1}{4} \sqrt{2gd \sin \theta} \cos \theta \ell}{m \ell^2 + m \ell^2}$

$$\omega = \frac{\sqrt{2gd \sin \theta} \cos \theta}{2\ell}$$

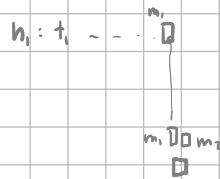
cons eh: $\frac{1}{2} I \omega^2 = mgh \rightarrow h = \frac{\frac{1}{2} (2m\ell^2) \omega^2}{4mg}$

32.1

Hp

v_0 , $m_1 = m_2 = m$

$t_1 \rightarrow m_1: h_1$



I_h

$h_2 \in m_2$ in t_2

$$(m_1 + m_2) v_0 = m_1 v_1 + m_2 v_2 \rightarrow 2m v_0 = m v_1 + m v_2 \rightarrow 2v_0 = v_1 + v_2$$

$$\rightarrow v_2 = 2v_0 - v_1$$

m_1 e m_2 partono con velocità v_1 e v_2 t.c. $v_2 = 2v_0 - v_1$
 \Rightarrow an velocità $\boxed{v_1}$ e $\boxed{2v_0 - v_1}$

$y_1(t) = v_1 t - \frac{1}{2} g t^2$

an $v_1(t) = v_1 - g t$

$y_2(t) = (2v_0 - v_1) t - \frac{1}{2} g t^2$

$y_1(t_1) = v_1 t_1 - \frac{1}{2} g t_1^2 = h_1 \Rightarrow \boxed{v_1 = \frac{h_1}{t_1} + \frac{1}{2} g t_1}$

$y_2(t_1) = (2v_0 - \frac{h_1}{t_1} + \frac{1}{2} g t_1) t_1 - \frac{1}{2} g t_1^2$

$= 2v_0 t_1 - h_1$

?

31.2

Hip

$$m_0, R, \omega_0$$

$$m = \kappa e^{t/c}$$

$$1) m_c(t) = m_0 + \kappa e^{t/c}$$

cons mom ang.

$$I_0 \omega_0 = I_1 \omega_1 \rightarrow \frac{1}{2} m_0 R^2 \omega_0 = \frac{1}{2} (m_0 + \kappa e^{t/c}) R^2 \omega(t)$$

$$\Rightarrow \omega(t) = \frac{m_0 \omega_0}{m_0 + \kappa e^{t/c}} \rightarrow v(t) = \frac{m_0 \omega_0 R}{m_0 + \kappa e^{t/c}}$$

$$2) \omega \text{ cost. se } a=0 = \frac{dv}{dt}$$

Trovo la forza:

$$F = \frac{dp}{dt} = \frac{d}{dt} (m(t) v(t)) = \frac{dm}{dt} v(t) + \frac{dv}{dt} m(t)$$

$$\text{impongo } \frac{dv}{dt} = 0$$

$$\Delta F = \frac{dm}{dt} v(t) = \frac{\kappa}{c} e^{t/c} v(t)$$

$$\Rightarrow P = Fv = \frac{\kappa}{c} e^{t/c} v^2(t)$$

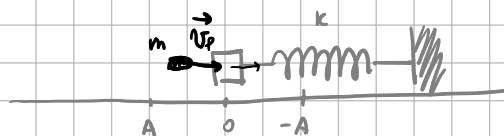
NON È SOLUZIONE

31.1

Hip

$$A, \omega, m$$

$$m_{oj} = m_p, v_p$$



$$x(t) = A \sin(\omega t) \rightarrow v(t) = \omega A \cos(\omega t)$$

$$\text{Nella posiz. la velocità è massima} \rightarrow \boxed{v = \omega A}$$

Ih

$$1) \omega(t)$$

$$2) p \in \omega = \omega t = \omega_0$$

Ih

$$1) v_{cr}$$

$$2) E \text{ dissipata}$$

$$3) A'$$

⇒ Velocità relativa al proiettile: $v = v_p - wA$

Cons. qdm: $m_p(v_p - wA) = (m + m_p)v_{cm}$

⇒ $v_{cm} = \frac{m_p(v_p - wA)}{m + m_p}$

2) Energia dissipata: $\frac{1}{2}m_p v_p^2 + \frac{1}{2}m(wA)^2 = \frac{1}{2}(m + m_p)v_{cm}^2 + E_{oss}$

$E_{oss} = \frac{1}{2}(m_p v_p^2 + m w^2 A^2 - \frac{m_p^2 (v_p - wA)^2}{(m + m_p)^2})$

$= \frac{1}{2}(m_p v_p^2 + m w^2 A^2 - \frac{m_p^2 (v_p - wA)^2}{m + m_p})$

3) Cons. Energia: $\frac{1}{2}(m + m_p)v_{cm}^2 = \frac{1}{2}kA^2$

⇒ $A^2 = \frac{(m + m_p)v_{cm}^2}{k}$

ωn $\omega = \sqrt{\frac{k}{m}} \rightarrow k = \omega^2 m$

⇒ $A = \sqrt{\frac{(m + m_p)v_{cm}^2}{\omega^2(m + m_p)}} = \frac{v_{cm}}{\omega}$

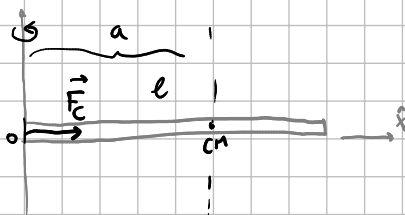
30.1

HP

$\ell, \lambda = c \times$

$dm = \lambda dx = c \times dx$

$\int_0^m dm = \lambda dx = \int_0^\ell c \times dx = \frac{1}{2}c\ell^2 \rightarrow c = \frac{2m}{\ell^2}$



IB

- 1) m
- 2) I_0, I_{cm}
- 3) N @ $\omega \cos t$

$I_0 = \int x^2 dm = \int_0^\ell x^3 c dx = \frac{1}{4}c\ell^4 = \frac{1}{2}m\ell^2$

e) CM: $\frac{\int x dm}{\int dm} = \frac{\int_0^\ell c x^2 dx}{\int_0^\ell c \times dx} = \frac{\frac{1}{3}\ell^3 c}{\frac{1}{2}\ell^2 c} = \frac{2}{3}\ell$

$I_0 = I_{cm} + m_{tot} a^2 \Rightarrow I_{cm} = I_0 - m_{tot} a^2$

$= \frac{1}{2}m\ell^2 - \frac{1}{2}c\ell^2 \frac{4}{9}\ell^2 = \frac{1}{2}m\ell^2 - \frac{1}{2} \frac{2m}{\ell^2} \ell^4 \frac{4}{9}$

$$= \frac{1}{2} m \ell^2 \ominus \frac{4}{9} m \ell^2 = \frac{9-8}{18} m \ell^2 = \frac{1}{18} m \ell^2$$

?

nella soluzione è \oplus

$$3) N = F_c = m \omega^2 \frac{2}{3} \ell$$